
Appendix for "Fine-Tuning Pre-Trained Language Models Effectively by Optimizing Subnetworks Adaptively"

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A Appendix A. Case Study

In Sec.3.3, we have experimentally verified that DPS outperforms various fine-tuning methods. To understand what type of cases DPS predicts more accurately and justify the effectiveness of DPS from another perspective, we conduct case study. Specifically, we fine-tune BERT_{LARGE} on RTE with 10 random restarts and count the overall proportion of easy cases (cases with more than 5 accurate predictions out of 10) and hard cases (cases with more than 5 predictions incorrect out of 10). Figure 1 summarizes the statistics. Compared with various baselines, DPS has the largest proportion of easy cases and the smallest proportion of hard cases. This demonstrates that compared with vanilla fine-tuning, Mixout, and CHILD-TUNING, DPS can better maintain general contextual representation, explore the potential value of data and models, and thus solve difficult cases without affecting the ability to identify easy cases, which is ultimately reflected in the improvement of metrics.

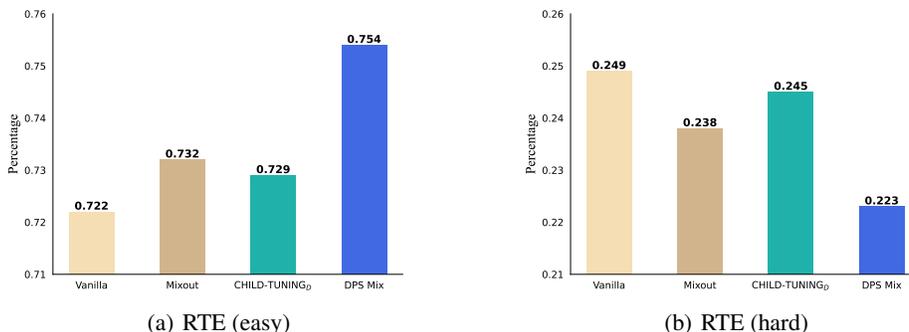


Figure 1: Subfigure.(a) summarizes the percentage of easy cases on various methods; Subfigure.(b) summarizes the percentage of hard cases on various methods.

B Appendix B. GLUE Benchmark Datasets

we conduct experiments on 8 datasets in GLUE benchmark Wang et al. [2019], the dataset statistics for each task are illustrated in Table 1. we also provide a brief description for each dataset:

- RTE**: Binary entailment classification task Bentivogli et al. [2009]
- MRPC**: Semantic similarity Dolan and Brockett [2005]

- STS-B**: Semantic textual similarity Cer et al. [2017]
- CoLA**: Acceptability classification Warstadt et al. [2019]
- SST-2**: Binary sentiment classification Socher et al. [2013]
- QNLI**: Binary question inference classification Rajpurkar et al. [2016]
- QQP**: Binary semantically equivalent classification Shankar Iyer and Csernai. [2017]
- MNLI**: Textual entailment classification Williams et al. [2018]

Dataset	RTE	MRPC	STS-B	CoLA	SST-2	QNLI	QQP	MNLI
Train Examples	2.5k	3.7k	5.7k	8.5k	67k	105k	364k	393k
Dev Examples	277	408	1.5k	1.0k	872	5.5k	40k	4.8k
Metrics	Acc	F1	SCC	MCC	Acc	Acc	Acc	Acc

Table 1: Eight datasets used in this paper form GLUE benchmark. Acc stands for Accuracy, SCC stands for Spearman Correlation Coefficient and MCC stands for Matthews Correlation Coefficient.

C Appendix C. Hyper-parameters and Experimental Details of Different Pre-trained Language Models

In this paper, we investigate the performance of DPS on five distinctive and widely used large-scale pre-trained language models, namely BERT Devlin et al. [2018], RoBERTa Liu et al. [2019], ELECTRA Clark et al. [2020], BART Lewis et al. [2019], and DeBERTa He et al. [2021]. BERT is the first Transformer Vaswani et al. [2017] encoder based pre-trained language model with Mask Language Modeling and Next Sentence Prediction pre-training tasks. RoBERTa is similar to BERT in terms of model architecture but is only pre-trained on the Mask Language Modeling task only, but for longer and on more data. ELECTRA is a BERT-like model trained to distinguish tokens generated by masked language model from tokens drawn from the natural distribution. BART is a sequence-to-sequence model trained as a denoising autoencoder. DeBERTa improves Transformer-based pre-trained model with disentangled attention mechanism and enhanced mask decoder. Table 2 summarizes the hyper-parameters of each model for each dataset. We use AdamW Loshchilov and Hutter [2019] optimizer, clip the gradients with a maximum norm of 1, and the maximum sequence length is set as 128. We use mixed precision training to speed up the experimental process. We conduct all the experiments on a single Tesla-V100 GPU (32G).

Model	Datasets	Batch Size	Learning Rate	Training Epochs/Steps	Warmup Ratio/Steps	LLRD
BERT	all	16	2e-5	3 epochs	10%	-
RoBERTa	RTE	16	2e-5	2036 steps	122 steps	-
	MRPC	16	1e-5	2296 steps	137 steps	-
	STS-B	16	2e-5	3598 steps	214 steps	-
	CoLA	16	1e-5	5336 steps	320 steps	-
ELECTRA	RTE	32	5e-5	10 epochs	10%	0.9
	MRPC	32	5e-5	3 epochs	10%	0.9
	STS-B	32	5e-5	10 epochs	10%	0.9
	CoLA	32	5e-5	3 epochs	10%	0.9
BART	RTE	32	1e-5	3 epochs	10%	-
	MRPC	64	2e-5	3 epochs	10%	-
	STS-B	32	2e-5	3 epochs	10%	-
	CoLA	64	2e-5	3 epochs	10%	-
BEBERTA	RTE	32	1e-5	6 epochs	50 steps	-
	MRPC	32	1e-5	6 epochs	50 steps	-
	STS-B	32	7e-6	4 epochs	100 steps	-
	CoLA	32	7e-6	6 epochs	100 steps	-

Table 2: Fine-tuning hyper-parameters of BERT and its variants as reported in the official repository of each model for best practice. Note that Layer-wise Learning Rate Decay (LLRD) Howard and Ruder [2018] is a method that applies higher learning rates for top layers and lower learning rates for bottom layers. This method is applied by ELECTRA when fine-tuning downstream tasks.

D Appendix D. Experimental Details for Different Fine-tuning Methods

The following is our hyperparameter search space for different fine-tuning regularization methods:

- Mixout** We grid search Mixout probability $p \in \{0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8\}$.
- R3F**: We grid search Noise Types $\in \{\mathcal{N}, \mathcal{U}\}$, $\sigma \in \{1e-5\}$, $\lambda \in \{0.1, 0.5, 1.0, 5.0\}$.
- Re-init**: We grid search $L \in \{1, 2, 3, 4, 5, 6, 7\}$.
- CHILD-TUNING_D**: We grid search CHILD-TUNING_D $p_D \in \{0.1, 0.2, 0.3\}$, and learning rate $lr \in \{2e-5, 4e-5, 6e-5, 8e-5, 1e-4\}$.
- R-Dropout**: We grid search Dropout probability $p \in \{0.1\}$ and $\alpha \in \{0.1, 0.5, 1, 3, 5\}$.
- DPS Dense**: We grid search reserved probability $p \in \{0.1, 0.2, 0.3, 0.4, 0.5\}$ and update ratio $ur \in \{0.05, 0.1, 0.2\}$.
- DPS Mix**: We grid search reserved probability $p \in \{0.1, 0.2, 0.3, 0.4, 0.5\}$, and update ratio $ur \in \{0.05, 0.1, 0.2\}$.

E Appendix E. Mapping Strategy

We train DPS on SNLI and MNLI datasets respectively and evaluate several different target NLI datasets. The SNLI and MNLI datasets contain three labels: entailment, neutral, and contradiction, however, some datasets have only two labels (SciTail, RTE). The SciTail dataset contains two labels: entailment, neutral, and we map the predicted labels neutral and contradiction to neutral, following Mahabadi et al. [2021]. We conduct the same process for RTE.

F Appendix F. Memory Consumption

In addition to time usage, we further analyze memory consumption of various approaches when fine-tuning BERT_{LARGE}. The table below shows the results. DPS Dense requires extra memory because it needs to store Gradient Accumulation Matrix (*GAM*), DPS Mix requires more memory than DPS Dense because it needs to store Frequency Accumulation Matrix (*FAM*) and *GAM*. It is worth noting that since the size of *GAM* and *FAM* is fixed, the additional memory consumption introduced by DPS does not increase as the batch size increases. Therefore, as the batch size increases, the percentage of additional memory consumption decreases for DPS compared to vanilla fine-tuning. Overall, DPS does introduce additional memory overhead, but we believe that the memory consumption for DPS is acceptable compared to other regularization methods.

Batch Size	Vanilla	Mixout	R3F	R-Dropout	CHILD-TUNING _D	DPS Dense	DPS Mix
16	10.6G	12.9G	17.7G	17.7G	10.9G	16.3G	21.1G
32	14.3G	16.3G	28.3G	28.3G	14.7G	20.0G	24.7G

Table 3: Memory consumption for DPS and multiple fine-tuning regularization methods.

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