GEN-LRA: TOWARDS A PRINCIPLED MEMBERSHIP INFERENCE ATTACK FOR GENERATIVE MODELS (SUP PLEMENTAL MATERIALS)

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A APPENDIX

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A.1 ADDITIONAL FIGURES

A.1.1 SAMPLE SIZE AND MIA EFFECTIVENESS

It is known that Membership Inference Attacks benefit from low sample sizes of T, R, and S. We explore the effect of the size of these samples across all models and datasets in figure 1. Here, we see that performance drops off between N=250 and N=1000; however it is relatively the same across all MIAs between N=1000 and N=4000. Across all N-sizes, Gen-LRA has a greater average AUC-ROC then all other MIAs. This further demonstrates that Gen-LRA is an excellent choice for a privacy auditing adversarial attack.

Average AUC-ROC by Sample Size Score Method Gen-LRA 0.56 DCR DCR-Diff 0.55 DOMIAS Average AUC-ROC DPI 0.54 Logan MC 0.53 0.52 0.51 0.50 1000 1500 2000 3000 3500 500 2500 4000 Ν



A.1.2 AVERAGE ACCURACY TABLE

A.1.3 MODEL UTILITY AND GEN-LRA EFFECTIVENESS

We benchmark various statistical metrics used to describe the quality of tabular synthetic data across architectures and datasets. We plot the mean Wasserstein distance and Maximum Mean Discrepancy between the corresponding training and synthetic data against the mean AUC-ROC of Gen-LRA in figure 2. Here, it seems there is some relationship between measures of statistical distance and Gen-LRA's global effectiveness. As these metrics are often used in utility benchmarks for tabular synthetic data, it is important to note that for practitioners, statistical fidelity in synthetic data can

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057	Model	Gen-LRA (Ours)	MC	DCR	DCR-Diff	DPI	DOMIAS	LOGAN 2017
	AdsGAN	0.524 (0.02)	0.513 (0.02)	0.513 (0.02)	0.513 (0.02)	0.515 (0.02)	0.513 (0.02)	0.503 (0.02)
058	ARF	0.539 (0.02)	0.524 (0.02)	0.524 (0.02)	0.529 (0.02)	0.526 (0.02)	0.524 (0.02)	0.503 (0.02)
059	Bayesian Network	0.619 (0.05)	0.629 (0.05)	0.629 (0.05)	0.621 (0.05)	0.538 (0.02)	0.599 (0.05)	0.504 (0.02)
000	CTGAN	0.523 (0.02)	0.509 (0.02)	0.509 (0.02)	0.511 (0.02)	0.513 (0.02)	0.511 (0.02)	0.504 (0.02)
060	Tab-DDPM	0.58 (0.04)	0.564 (0.05)	0.564 (0.05)	0.563 (0.05)	0.537 (0.02)	0.563 (0.04)	0.504 (0.02)
061	Normalizing Flows	0.517 (0.02)	0.504 (0.02)	0.504 (0.02)	0.504 (0.02)	0.505 (0.02)	0.504 (0.02)	0.501 (0.02)
001	PATEGAN	0.514 (0.02)	0.501 (0.02)	0.501 (0.02)	0.499 (0.02)	0.499 (0.02)	0.500 (0.02)	0.501 (0.02)
062	TVAE	0.533 (0.02)	0.520 (0.02)	0.520 (0.02)	0.522 (0.02)	0.517 (0.02)	0.518 (0.02)	0.503 (0.02)
063	Rank	1.3	3.2	3.4	3.6	3.6	3.9	5.5

054 Table 1: Average AUC-ROC for each Membership Inference Attack across model architectures and 055 datasets.

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come at a privacy cost. It also illustrates that measures of utility should include some kind of holdout testing method to consider overfitting.



Figure 2: Average Wasserstein Distance and Average Maximum Mean Discrepancy plotted against Gen-LRA AUC-ROC for benchmarked models. Bayesian Network and Tab-DDPM outperform other models in these performance metrics but have higher privacy risk.

EXPERIMENT DETAILS A.2

A.2.1 SECTION 6.2

We conducted two experiments to evaluate the performance of DCR and Gen-LRA on different types of model failure, with the full results shown in table ??. The experiments were carried out as follows:

Data Copying Simulation In this setup, we let T and R be random samples from a 2-dimensional standard multivariate Gaussian distribution; i.e., $T, R \stackrel{\text{iid}}{\sim} \mathcal{N}_2(\mathbf{0}, \mathbf{I})$. Here, we assume a model \mathcal{M} that exactly reproduces the training examples in its output, meaning S = T. 100

102 **Overfitting Simulation** In this simulation, we again let $R \stackrel{\text{iid}}{\sim} \mathcal{N}_2(\mathbf{0}, \mathbf{I})$, but the sampling distribu-103 tion of T is modified to slightly differ from R, potentially due to sampling variation or bias. In this 104 case, the output S models T well, where $D, S \stackrel{\text{iid}}{\sim} \mathcal{N}_2(\mathbf{0}, \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}).$ 105 106

For both simulations, we set the sample size n = 500 for T, R, and S, and the AUC-ROC of DCR 107 and Gen-LRA was compared over 10,000 iterations.

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108 A.3 ABLATION: DIFFERENT k sizes

Gen-LRA targets local fitting by selecting a subset of S to evaluate likelihoods with. This is im-plemented using the k-nearest neighbors in S to x^* . In practice, this means that k must be selected as a hyperparameter for the attack. In order to understand how k impacts the quality of the attack, we replicate section ?? benchmarking with various k values. We report the average AUC-ROC and standard deviations in table 2. Overall, we find that empirically usually smaller values of k are better although it depends on the model. As stated in section ??, a global attack over all S is unlikely to yield much membership signal. This is confirmed with k = N, where the AUC-ROC is always 0.5 and highlights that overfitting is a local phenomenon and that generative model adversarial attacks should focus on attacking locality to be successful.

Table 2:	Average AUC-ROC	at different k	values for	Gen-LRA.
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Model	k=1	k=3	k=5	k=10	k=15	k=20	k=N
AdsGAN	0.514 (0.02)	0.518 (0.02)	0.519 (0.02)	0.520 (0.02)	0.521 (0.02)	0.521 (0.02)	0.500 (0.00)
ARF	0.532 (0.02)	0.538 (0.02)	0.540 (0.02)	0.540 (0.03)	0.540 (0.03)	0.539 (0.03)	0.500 (0.00)
Bayesian Network	0.650 (0.07)	0.645 (0.07)	0.640 (0.07)	0.634 (0.07)	0.631 (0.07)	0.629 (0.07)	0.500 (0.00)
CTGAN	0.514 (0.02)	0.516 (0.02)	0.517 (0.02)	0.517 (0.02)	0.518 (0.02)	0.518 (0.02)	0.500 (0.00)
Tab-DDPM	0.595 (0.07)	0.595 (0.07)	0.594 (0.07)	0.592 (0.06)	0.591 (0.06)	0.589 (0.06)	0.500 (0.00
Normalizing Flow	0.503 (0.02)	0.503 (0.02)	0.505 (0.02)	0.506 (0.02)	0.506 (0.02)	0.506 (0.02)	0.500 (0.00)
TVAE	0.527 (0.03)	0.531 (0.03)	0.531 (0.03)	0.531 (0.03)	0.530 (0.03)	0.529 (0.03)	0.500 (0.00)

A.4 MIAs FOR GENERATIVE MODELS DESCRIPTIONS

The Membership Inference Attacks referenced in this paper is are described as follows:

- LOGAN Hayes et al. (2017): LOGAN consists of black box and shadow box attack. The black-box version involves training a Generative Adversarial Network (GAN) on the synthetic dataset and using the discriminator to score test data. A calibrated version improves upon this by training a binary classifier to distinguish between the synthetic and reference dataset. In this paper, we only benchmark the calibrated version.
- Distance to Closest Record (DCR) / DCR Difference Chen et al. (2020): DCR is a blackbox attack that scores test data based on a sigmoid score of the distance to the nearest neighbor in the synthetic dataset. DCR Difference enhances this approach by incorporating a reference set, subtracting the distance to the closest record in the reference set from the synthetic set distance.
- MC Hilprecht et al. (2019): MC is based on counting the number of observations in the synthetic dataset that fall into the neighborhood of a test point (Monte Carlo Integration). However, this method does not consider a reference dataset, and the choice of distance metric for defining a neighborhood is a non-trivial hyperparameter to tune.
 - **DOMIAS** van Breugel et al. (2023): DOMIAS is a calibrated attack which scores test data by performing density estimation on both the synthetic and reference datasets. It then calculates the density ratio of the test data between the learned synthetic and reference probability densities.
 - **DPI** Ward et al. (2024): DPI computes the ratio of k-Nearest Neighbors of x^* in the synthetic and reference datasets. It then builds a scoring function by computing the ratio of the sum of data points from each class of neighbors from the respective sets.
- A.5 GENERATIVE MODEL ARCHITECTURE DESCRIPTIONS

In all experiments, we use the implementations of these models from the Python package Synthety
Qian et al. (2023). For benchmarking purposes, we use the default hyperparameters for each model.
A brief description of each model is as follows:

• **CTGAN** Xu et al. (2019): Conditional Tabular Generative Adversarial Network uses a GAN framework with conditional generator and discriminator to capture multi-modal distributions. It employs mode normalization to better learn mixed-type distributions.

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163	• TVAE Xu et al. (2019): Tabular Variational Auto-Encoder is similar to CTGAN in its use of
164	mode normalizing techniques, but instead of a GAN architecture, it employs a Variational
165	Autoencoder.
166	• Normalizing Flows (NFlows) Durkan et al. (2019): Normalizing flows transform a simple
100	base distribution (e.g., Gaussian) into a more complex one matching the data by applying
167	a sequence of invertible, differentiable mappings.
168	• Bayesian Network (BN) Ankan & Panda (2015): Bayesian Networks use a Directed
169	Acyclic Graph to represent the joint probability distribution over variables as a product
170	of marginal and conditional distributions. It then samples the empirical distributions esti-
171	mated from the training dataset.
172	• Adversarial Random Forests (ARF) Watson et al. (2023): ARFs extend the random forest
173	model by adding an adversarial stage. Random forests generate synthetic samples which
174	are scored against the real data by a discriminator network. This score is used to re-train
175	the forests iteratively.
176	• Tab DDPM Kotelnikov et al. (2022): Tabular Denoising Diffusion Probabilistic Model
177	adapts the DDPM framework for image synthesis. It iteratively refines random noise into
178	synthetic data by learning the data distribution through gradients of a classifier on partially
179	corrupted samples with Gaussian noise.
180	• DATECAN Vers et al. (2010). The DATECAN model uses a neural encodente mon die
181	• PAIEGAN 10011 et al. (2019): The PAIEGAN model uses a neural encoder to map dis-
182	generation by the GAN discriminator and generator pair
183	the GANA in the GANA discriminator and generator pair.
184	• Ads-GAN Yoon et al. (2020): Ads-GAN uses a GAN architecture for tabular synthesis but
185	also adds an identifiability metric to increase its ability to not mimic training data.
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187	A.6 BENCHMARKING DATASETS REFERENCES
188	We provide the LIRL for the sources of each dataset considered in the paper. We use datasets com-
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