000 001 002 003 SPECULATE, THEN COLLABORATE: FUSING KNOWL-EDGE OF LANGUAGE MODELS DURING DECODING

Anonymous authors

Paper under double-blind review

ABSTRACT

Large Language Models (LLMs) often excel in specific domains but fall short in others due to the limitations of their training. Thus, enabling LLMs to solve problems collaboratively by integrating their complementary knowledge promises to improve their performance across domains. To realize this potential, we introduce a novel *Collaborative Speculative Decoding (CoSD)* algorithm that enables efficient LLM knowledge fusion at test time without requiring additional model training. CoSD employs a draft model to generate initial sequences and an easy-to-learn rule or decision tree to decide when to invoke an assistant model to improve these drafts. CoSD not only enhances knowledge fusion but also improves inference efficiency, is transferable across domains and models, and offers greater explainability. Experimental results demonstrate that CoSD improves accuracy by up to 10% across benchmarks compared to existing methods, providing a scalable and effective solution for LLM-based applications.

023 024 025

026 027

1 INTRODUCTION

028 029 030 031 032 033 034 035 036 State-of-the-art large language models (LLMs), such as GPT-4 [\(Achiam et al.,](#page-9-0) [2023\)](#page-9-0) and Llama-3 [\(Dubey et al.,](#page-10-0) [2024\)](#page-10-0), have demonstrated impressive capabilities in generating high-quality text across a variety of domains. These models are trained on vast datasets, allowing them to perform well on a wide range of tasks. However, despite their general effectiveness, no single LLM excels uniformly across all domains. Different models tend to have *complementary knowledge*, with each model specializing in certain areas. For example, one model may be more proficient in technical writing, while another may outperform in creative tasks. This heterogeneity has led to an increasing interest in developing methods that can *fuse the knowledge* of multiple LLMs, enabling users to harness their collective strengths for more robust and versatile applications.

037 038 039 040 041 042 043 044 045 To address these challenges, recent research has shifted focus to *test-time* knowledge fusion, which eliminates the need for retraining by combining model outputs during inference. This approach allows users to leverage the complementary knowledge of multiple LLMs without the overhead of additional training. For example, [Wang et al.](#page-11-0) [\(2023\)](#page-11-0) proposed a method that selects expert models dynamically at inference time using supervised learning, while [Ong et al.](#page-11-1) [\(2024\)](#page-11-1) introduced a router model that optimizes the selection of models based on performance and cost. Other approaches focus on integrating outputs through the decoding process, such as token-wise decoding [\(Shen et al.,](#page-11-2) [2024\)](#page-11-2) and character-wise decoding [\(Gu et al.,](#page-10-1) [2024\)](#page-10-1), which combine outputs at a fine-grained level. Although these methods offer potential, they often struggle to balance strong knowledge integration with efficiency, which limits their practicality in real-world applications.

046 047 048 049 050 051 052 053 In response to these limitations, we propose *Collaborative Speculative Decoding* COSD, a novel algorithm designed to efficiently fuse the knowledge of multiple LLMs at inference time. COSD builds upon recent developments in *Speculative Decoding* [\(Leviathan et al.,](#page-11-3) [2023;](#page-11-3) [Xia et al.,](#page-12-0) [2023\)](#page-12-0) to create an efficient system where multiple LLMs collaborate during the inference process. As shown in Figure [1,](#page-2-0) COSD consists of two models: a *draft model* that generates an initial sequence of tokens and an *assistant model* that verifies these tokens in parallel. When the assistant model predicts a token different from that of the draft model, a comparison of their token probabilities is used to determine whether to replace the draft token. This decision-making process can be guided by either a predefined rule set (Rule-Based COSD) or a pre-trained decision tree (Tree-Based COSD). The sequence is **054 055 056** then regenerated and re-verified iteratively until all tokens are accepted, ensuring both accuracy and computational efficiency.

057 058 059 060 061 062 063 064 065 066 COSD presents several notable advantages over existing test-time fusion methods. First, by leveraging speculative decoding, COSD improves inference efficiency, relying on token probabilities rather than more complex and resource-intensive representations like embeddings or hidden states. Second, COSD demonstrates superior knowledge fusion due to the carefully designed decisionmaking process, which can be optimized for specific domains. Third, Rule-Based COSD is highly transferable across different domains and model pairs; once the rules are established with optimal hyperparameters, they can be applied to a broad range of tasks. Similarly, the decision tree-based approach exhibits strong transferability, even when trained on domain-specific data. Finally, COSD offers an interpretable framework, i.e., its use of human-readable rules or decision trees provides transparency, making it easier to evaluate, optimize, and understand compared to less transparent deep learning systems.

067 068 069 070 We validate the effectiveness of COSD through extensive experiments on standard benchmarks and multiple model pairings. Our results show that COSD not only significantly enhances the fusion of LLM knowledge but also improves efficiency and transferability across various domains. The key contributions of this work are as follows:

- We introduce COSD, a novel algorithm that enables efficient fusion of LLM knowledge without requiring retraining.
	- COSD's efficiency and transferability make it practical for a wide range of users, facilitating its implementation through both models and APIs.
	- Our experimental results demonstrate that COSD improves overall accuracy by up to 10% across benchmarks, surpassing the state-of-the-art methods.
- 2 RELATED WORK
- **080 081 082**

083 084 085 086 087 088 089 090 091 092 093 094 095 096 097 098 Language Model Fusion from multiple LMs aims at enhancing the cross-domain performance of the resulting model and reducing bias. The primary efforts for such integration include model merging [\(Goddard et al.,](#page-10-2) [2024\)](#page-10-2), such as model weight averaging [\(Wortsman et al.,](#page-11-4) [2022\)](#page-11-4) and linear mode connectivity [\(Ainsworth et al.,](#page-10-3) [2022;](#page-10-3) [Ito et al.,](#page-10-4) [2024;](#page-10-4) [Wang et al.,](#page-11-5) [2020\)](#page-11-5). Another series of works is called model stacking, which refers to concatenating models along the depth dimension. [Wu](#page-11-6) [et al.](#page-11-6) [\(2024\)](#page-11-6) and [Kim et al.](#page-11-7) [\(2023\)](#page-11-7) stack the decoder blocks to expand the depth of Llama models. For large language models, some other research proposes knowledge fusion [\(Wan et al.,](#page-11-8) [2024\)](#page-11-8). They combine the capabilities of existing LLMs and transfer them into a single LLM. Another important trend of work called Mixture of Expert (MoE) [\(Zhu et al.,](#page-12-1) [2024;](#page-12-1) [Xue et al.,](#page-12-2) [2024\)](#page-12-2) builds sparse neural networks and only activates a subset of parameters (*i.e.,* experts) for each input. However, these methods either require the fused models to have the same structure or require fine-tuning after fusing to achieve the desired model performance. Towards mitigating these flaws, a new wave of works adopt decoding methods to fuse LMs. [Gu et al.](#page-10-1) [\(2024\)](#page-10-1) propose a character-wise ensemble decoding method to fuse two LLMs' outputs. [Shen et al.](#page-11-2) [\(2024\)](#page-11-2) and [Wang et al.](#page-11-0) [\(2023\)](#page-11-0) fuse model knowledge by training to choose between the generation of different LLMs. In our experiments, we consider several baselines from the latter group of works and observe gains in either efficiency or performance when using our method to merge cross-domain knowledge from different LMs when decoding.

099 100 101 102 103 104 105 106 107 Speculative Decoding is an efficient decoding paradigm for LM inference [\(Xia et al.,](#page-12-3) [2024;](#page-12-3) [Stern](#page-11-9) [et al.,](#page-11-9) [2018;](#page-11-9) [Xia et al.,](#page-12-0) [2023\)](#page-12-0). It accelerates the inference process by first generating draft tokens efficiently, and then using an LLM to verify draft tokens in parallel and correct them if needed [\(Leviathan](#page-11-3) [et al.,](#page-11-3) [2023\)](#page-11-3), which avoids the autoregression process. In practice, the draft generator in speculative decoding could be a small LM [\(Chen et al.,](#page-10-5) [2023;](#page-10-5) [Miao et al.,](#page-11-10) [2023;](#page-11-10) [Zhou et al.,](#page-12-4) [2023\)](#page-12-4), a sub-model of an LLM [\(Zhang et al.,](#page-12-5) [2023;](#page-12-5) [Yang et al.,](#page-12-6) [2023;](#page-12-6) [Elhoushi et al.,](#page-10-6) [2024\)](#page-10-6), or a text database retriever [\(He](#page-10-7) [et al.,](#page-10-7) [2023;](#page-10-7) [Li et al.,](#page-11-11) [2024\)](#page-11-11). The final generation of speculative decoding will be similar to the autoregressive generation of the target LLM, which is only acceptable when the target LLM has much better performance but is less efficient than the draft generator. No previous work focuses on using speculative decoding to approach the model fusion problem.

Figure 1: The workflow of collaborative speculative decoding.

3 COLLABORATIVE SPECULATIVE DECODING

124 125 126 127 128 In our Collaborative Speculative Decoding system, our purpose is to fuse the predicted sequences of two LLMs efficiently. We define our problem as follows: given an input sequence x_1, \ldots, x_t , COSD uses a draft model \mathcal{M}_p and an assistant model \mathcal{M}_q to collaboratively generate an output sequence x_{t+1}, \ldots, x_{t+K} that integrates both models' knowledge and expertise.

129 130 131 132 133 134 135 136 137 As Figure [1](#page-2-0) illustrates, the process begins with the draft model \mathcal{M}_p generating a draft sequence $\tilde{x}_{t+1}, \ldots, \tilde{x}_{t+K}$ in an autoregressive manner. Subsequently, the assistant model \mathcal{M}_q verifies the draft tokens and their respective probabilities in parallel, producing an assistant sequence $\hat{x}_{t+1}, \ldots, \hat{x}_{t+K}$. After both sequences are generated, we iterate through the tokens and their corresponding probabilities to verify whether to accept a draft token \tilde{x}_{t+i} or replace it with the corresponding assistant token \hat{x}_{t+i} .
Both rule-based or tree-based verification strategies, use token probabilities to determine whether Both rule-based or tree-based verification strategies, use token probabilities to determine whether a replacement is necessary. When a replacement occurs, all subsequent draft tokens are discarded, and a new draft sequence is generated starting from the replaced token. This process continues until the output reaches the maximum length or an <EOS> token is generated. The full generation and verification process is elaborated in Algorithm [1](#page-3-0) and described in following sections.

139 3.1 GENERATION.

141 142 The generation process follows the principles of Speculative Decoding. First, the draft model \mathcal{M}_p generates a sequence of tokens autoregressively:

$$
\begin{array}{c} 143 \\ 144 \end{array}
$$

145

152 153

138

140

121 122 123

> for $i = 1$ to K do $\widetilde{x}_{t+i} \sim \mathcal{M}_p(x|x_1,\ldots,\widetilde{x}_{t+i-1}),$ (1)

> > (3)

146 147 148 Here, \tilde{x}_{t+i} represents the token predicted by the draft model at position i, selected as the token with the highest probability. The sequence $\tilde{x}_{t+1}, \ldots, \tilde{x}_{t+K}$ is generated autoregressively and produced sequentially.

149 150 151 After the draft sequence is generated, the assistant model \mathcal{M}_q is used to verify these tokens. The assistant model generates tokens in parallel:

$$
i = 1, ..., K \text{ in parallel do}
$$

$$
\hat{x}_{t+i} \sim \mathcal{M}_q(x|x_1, ..., \tilde{x}_{t+i-1}),
$$
 (2)

154 155 156 157 Note that we already have all the draft tokens $\tilde{x}_{t+1}, \ldots, \tilde{x}_{t+K}$ when we generate the assistant tokens. Thus, all the \hat{x}_{t+i} in Eq. (2) can be generated in parallel. The process can also handle cases where the draft and assistant models use different tokenizers. In such cases, the draft sequence is first decoded by the draft model's tokenizer and then encoded by the assistant model's tokenizer:

$$
i = 1, \dots, K \text{ in parallel do}
$$

$$
x_1, \dots, \widetilde{x}_{t+i-1} \xrightarrow[T_p]{decode} \text{Texts} \xrightarrow[T_q]{encode} x_1^*, \dots, x_n^*,
$$

$$
\hat{x}_{t+i} \sim \mathcal{M}_q(x|x_1^*, \dots, x_n^*),
$$

162 163 164 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 Algorithm 1 Workflow of COSD **Input:** Draft model \mathcal{M}_p , assistant model \mathcal{M}_q , input sequence x_1, \ldots, x_t , predefined hyperparameters α , β and trained decision tree \mathcal{T} ; **Output:** Output sequence x_{t+1}, \ldots, x_{t+K} ; Generation 1: for i in $0, 1, \ldots, K$ do 2: $\tilde{x}_{t+i} \sim \mathcal{M}_p(x|x_1,\ldots,\tilde{x}_{t+i-1})$ #Generate draft in an auto-regressive manner. 3: end for 4: Verify the draft in parallel: 5: $i = 1, \ldots, K$ in parallel do 6: $\hat{x}_{t+i} \sim \mathcal{M}_q(x|x_1,\ldots,\tilde{x}_{t+i-1}),$ #Generate the assistant sequence in parallel. 7: Send both $\tilde{x}_1, \ldots, \tilde{x}_K, \hat{x}_1, \ldots, \hat{x}_K$, and all related probabilities $\mathcal{M}_p(\tilde{x}_i), \mathcal{M}_q(\hat{x}_i)$ to verification. **Verification** 8: for i in $0, 1, \ldots, K$ do 9: if $\widetilde{x}_{t+i} \neq \widetilde{x}_{t+i}$ and $\mathcal{M}_n(\widetilde{x}_{t+i}) < \alpha$ and $\mathcal{M}_n(\widetilde{x}_{t+i}) > \beta \cdot \mathcal{M}_n(\widetilde{x}_{t+i})$ then or 10: **if** $\widetilde{x}_{t+i} \neq \hat{x}_{t+i}$ and $\mathcal{T}(\mathcal{M}_p(\widetilde{x}_{t+i}),\mathcal{M}_q(\hat{x}_{t+i})) = 1$ then
11: $x_{t+i} \leftarrow \hat{x}_{t+i}$ $x_{t+i} \leftarrow \hat{x}_{t+i}$ 12: $t \leftarrow t + i$ 13: Exit loop, go to Generation 14: end for

where T_p and T_q are the tokenizers of the draft model and the assistant model respectively. The draft sequence is first decoded into texts by T_p and then encoded by T_q to fit the assistant model.

3.2 VERIFICATION

190 191 192 193 194 195 196 197 After the generation, we have a draft sequence $\tilde{x}_{t+1}, \ldots, \tilde{x}_{t+K}$ and an assistant sequence $\hat{x}_{t+1}, \ldots, \hat{x}_{t+K}$, along with the corresponding probabilities $\mathcal{M}_p(\tilde{x}_{t+i})$ and $\mathcal{M}_q(\hat{x}_{t+i})$. We then use this information to verify whether to keep the draft token \tilde{x}_i or replace it with the assistant token \hat{x}_i and thus ensemble the model knowledge. In order to make COSD suitable for a wider range of tasks, we propose two strategies for verification. The first strategy, called Rule-Based Verification, applies clear rules to decide whether to select the draft token or the assistant token. The second strategy, i.e., Tree-Based Verification, involves training a decision tree to classify and select between the draft and assistant tokens.

198

199 200 201 202 203 Rule-Based Verification. In Rule-Based Verification, the system applies simple yet general rules to determine whether the draft token \tilde{x}_{t+i} should be replaced by the assistant token \hat{x}_{t+i} . The intuition behind these rules is that if the draft model predicts a token with low confidence and the assistant behind these rules is that if the draft model predicts a token with low confidence and the assistant model offers a higher-confidence alternative, the draft token should be replaced. The following rules define the verification process:

$$
\widetilde{x}_{t+i} \neq \hat{x}_{t+i},\tag{4}
$$

$$
\mathcal{M}_n(\widetilde{x}_{t+i}) < \alpha,\tag{5}
$$

$$
\mathcal{M}_p(\widetilde{x}_{t+i}) < \alpha,\tag{5}
$$
\n
$$
\mathcal{M}_q(\hat{x}_{t+i}) > \beta \cdot \mathcal{M}_p(\widetilde{x}_{t+i}),\tag{6}
$$

207 208

204 205 206

209 210 211 212 These conditions check whether (1) the draft and assistant tokens differ, (2) the draft token has a probability below a threshold α , and (3) the assistant token has a probability sufficiently higher than the draft token's probability by a factor of β . If all conditions are met, the draft token is replaced with the assistant token.

213 214 215 Intuitively, the Rule-Based Verification can be explained as follows: if the draft model is uncertain and the assistant model provides a better alternative, the system opts for the assistant's prediction. If a replacement is made, the sequence is updated, and the draft model regenerates from that point onward.

216 217 218 219 220 221 222 223 224 Tree-Based Verification. For domain-specific applications, Rule-Based Verification may not always be optimal. It is necessary to improve performance in specialized domains, such as healthcare [\(Poonia](#page-11-12) [& Al-Alshaikh,](#page-11-12) [2024\)](#page-11-12), smart home [\(Amru et al.,](#page-10-8) [2024\)](#page-10-8), or math [\(Mazraeh et al.,](#page-11-13) [2024\)](#page-11-13). Therefore, we design the Tree-Based Verification method, which involves training a decision tree to decide when to replace a draft token with an assistant token. Training the decision tree on specific domain data allows for a more accurate assessment of knowledge fusion performance within those particular contexts. Specifically, our decision tree T takes two probabilities, $\mathcal{M}_p(\tilde{x}_{t+i})$ and $\mathcal{M}_q(\hat{x}_{t+i})$, as inputs. The decision tree's output $\mathcal{T}(\mathcal{M}_p(\widetilde{x}_{t+i}),\mathcal{M}_q(\hat{x}_{t+i})) \in \{0,1\}$ indicates whether to use the draft token $(y_i = 0)$ or replace it with the assistant token $(y_i = 1)$.

225 226 227 228 229 230 231 232 To train a decision tree suitable for specific domains, we first select a commonly used benchmark dataset D for this domain (e.g., GSM8K [\(Cobbe et al.,](#page-10-9) [2021\)](#page-10-9) in math) with several input and groundtruth output pairs, *i.e.*, x_1, \ldots, x_t and x_{t+1}, \ldots, x_{t+K} . We iterate through all the tokens in the ground-truth output in each pair. For the i -th token, we concatenate the input sequence and the first $i-1$ tokens of output sequences. Then, we feed the concatenated input x_1, \ldots, x_{t+i-1} into the two models separately to obtain the predicted next token $\tilde{x}_{t+i}, \hat{x}_{t+i}$ and their corresponding probabilities $M(\tilde{x}_{t+i})$. This probability pair is one training sample of the decision tree. As for the $\mathcal{M}_p(\tilde{x}_{t+i}), \mathcal{M}_q(\hat{x}_{t+i})$. This probability pair is one training sample of the decision tree. As for the related ground-truth label, we have three rules:

233 • If $\tilde{x}_{t+i} = x_{t+i}$, we assign the label $y_i = 0$ to encourage the decision tree to select the draft token.
• If $\tilde{x}_{t+i} \neq x_{t+i}$ and $\hat{x}_{t+i} = x_{t+i}$, we assign the label $y_i = 1$ to encourage the decision tree to selec

234 235 • If $\tilde{x}_{t+i} \neq x_{t+i}$ and $\hat{x}_{t+i} = x_{t+i}$, we assign the label $y_i = 1$ to encourage the decision tree to select the assistant token the assistant token.

• If neither \tilde{x}_{t+i} nor \hat{x}_{t+i} match the target, we drop the sample and continue the loop with $i \leftarrow i + 1$.

We iterate through all the input-output pairs and finally construct the training data sample in the form of $\{[\mathcal{M}_p(\tilde{x}_i),\mathcal{M}_q(\hat{x}_i)], y_i\}$. In the training process, we aim to train the decision tree classifier $\mathcal{T} : \mathbb{R}^2 \to \{0, 1\}$ to minimize the difference between the predicted label and the ground truth:

$$
239\n240\n241\n242
$$

236 237 238

$$
\min_{\mathcal{T}} \sum_{i=1}^{N} \left[y_i \log(\mathcal{T}(\mathcal{M}_p(\widetilde{x}_i), \mathcal{M}_q(\hat{x}_i))) + (1 - y_i) \log(1 - \mathcal{T}(\mathcal{M}_p(\widetilde{x}_i), \mathcal{M}_q(\hat{x}_i))) \right]. \tag{7}
$$

After training, our decision tree can predict whether to choose the draft token or the assistant token based on the two input probabilities. If the decision tree predicts 1, the same as the rule-based verification, we replace the token, update the accepted token number, and send the new input sequence back to the generation. Since the decision tree is trained on a dataset specific to the corresponding domain, using this decision tree to fuse the model outputs can achieve better results in that domain.

4 EXPERIMENT

4.1 EXPERIMENTAL SETTINGS

254 255 256 257 258 259 260 261 262 263 264 265 266 267 Scenarios, Models, and Benchmarks. We evaluate COSD and compare it against several baselines in scenarios that reflect common use cases where users may seek to fuse the knowledge of multiple LLMs. These scenarios include: (i) **Complementary Knowledge Fusion:** The fused LLMs have complementary knowledge, and users hope that the knowledge fusion system can perform as well as the best model for each task across all tasks; (ii) Catastrophic Forgetting Recovery: The fused models are one base model and a model fine-tuned from the base model. Fine-tuning improves performance in certain domains but reduces the performance in other domains due to catastrophic forgetting. Users expect to heal the catastrophic forgetting by fusing the knowledge of the two LLMs; (iii) Capacity Imbalance: Users use a small draft model and adopt an API of the assistant model with a much larger capacity. The fusion system is expected to perform similarly to the assistant model; (iv) Different Tokenizers: Fuses the LLMs with different tokenizers. To simulate these scenarios, we carefully selected six pairs of LLMs from the HuggingFace repository [\(Jain,](#page-10-10) [2022\)](#page-10-10), representing each of the four use cases outlined above. Table [1](#page-5-0) lists the model pairs and the corresponding simulated scenarios.

268 269 For all the scenarios and model pairs, we use MMLU [\(Hendrycks et al.,](#page-10-11) [2020\)](#page-10-11), GSM8K [\(Cobbe](#page-10-9) [et al.,](#page-10-9) [2021\)](#page-10-9), and HumanEval [\(Chen et al.,](#page-10-12) [2021\)](#page-10-12) as the evaluation benchmark. We use tinyBenchmarks [\(Polo et al.,](#page-11-14) [2024\)](#page-11-14) for MMLU and GSM8K to further increase the efficiency of experiments. **270 271**

Table 1: LLM pairs in the experiments.

Methods	Draft Model	Assist. Model	Simulated Scenario	
Pair 1	Llama 3 Wissenschaft 8B	Llama 3 Bophades 8B	Complementary Knowledge Fusion	
Pair 2	Mistral 7B DARE	Mistral 7B Mixed	Complementary Knowledge Fusion	
Pair 3	Mistral 7B (Jiang et al., 2023)	Mistral Math 7B	Catastrophic Forgetting Recovery	
Pair 4	TinyLlama (Zhang et al., 2024)	Llama 2 Chat	Capacity Imbalance	
Pair 5	Llama 2 Chat (Touvron et al., 2023)	WizardMath (Luo et al., 2023)	Different Tokenizers	
Pair 6	Llama 2 Chat	DeepSeek Coder (Guo et al., 2024)	Different Tokenizers	

These benchmarks test general question-answering, mathematical reasoning, and coding capabilities, providing a comprehensive assessment of the models' abilities across different domains. By using these benchmarks, we can evaluate the effectiveness of COSD and the baselines in fusing complementary knowledge across diverse tasks and model configurations.

284 285 286 287 288 289 290 291 Baselines. We use tree baselines in the experiment: (1) **Speculative Decoding:** It also uses a draft model and an assistant model to generate the output. However, it adopts a different verification algorithm that replaces the draft token when $\frac{\mathcal{M}_p(\widetilde{x}_i)}{\mathcal{M}_q(\hat{x}_i)} < U(0,1)$ (2) **Average Decoding:** It averages the predicted probabilities of the draft model and the assistant model and chooses the final output from the averaged probabilities. (3) Co-LLM [\(Shen et al.,](#page-11-2) [2024\)](#page-11-2): It trains a single layer to classify the hidden state of a base model. The output probability of the layer decides to use the base model generation or evoke an assistant model to help generation.

292 293 294 295 296 297 298 Hyperparameters. We run COSD with the following settings. For Rule-Based COSD, we set $\alpha = 0.5$ and $\beta = 0.5$, which were determined to be the optimal and most transferable parameters based on our analysis in Figure [2.](#page-7-0) For Tree-Based COSD, we randomly select three samples from the AlpacaEval dataset to train the decision tree. It is important to note that we use MMLU, GSM8K, and HumanEval as our benchmarks. Consequently, the training data for the decision tree do not overlap with the test data, creating a more realistic scenario to evaluate the decision tree's transferability across different tasks and domains.

- **300** 4.2 EXPERIMENTAL RESULTS
- **301 302**

303 304 305

299

Fusing LLMs with Complementary Domain Knowledge. We first evaluated the performance of different methods for fusing LLMs with complementary knowledge, with results shown in the pair 1 and pair 2 columns of Table [2.](#page-6-0) Both CoSD-Rule and CoSD-Tree consistently outperformed the baseline methods in terms of overall performance. For instance, in pair 1, CoSD-Rule and CoSD-Tree

306 307 308 309 310 311 312 313 314 315 achieved scores of 56.97 and 58.37 on MMLU, respectively, surpassing all the baselines. Besides, CoSD-Rule also achieves the best performance on GSM8K and HumanEval. Notably, CoSD can match the performance of the better model for each task across all tasks. For example, in pair 1, CoSD achieves a similar MMLU performance to the draft model and a similar performance on GSM8K and HumanEval to the assistant model. A similar conclusion can be drawn from pair 2 as well. Compared with our COSD, Speculative Decoding only performs similarly to the assistant model, thus will be more suitable to the scenario when the assistant model is much stronger than the draft model. Average Decoding can fuse model knowledge. However, it can only achieve an average accuracy across tasks, unlike CoSD, which integrates the strengths of different LLMs. Co-LLM's performance is the closest to COSD, but since it requires training on specific datasets, its transferability across different datasets is inferior to COSD.

316 317 318 319 320 321 322 It is also interesting to see that CoSD-Rule outperforms CoSD-Tree in GSM8K and HumanEval. We attribute this phenomenon to the fact that the rules exhibit greater generalizability compared to the decision tree. Since our decision tree is trained on AlpacaEval, it performs better on some general QA tasks (*e.g.,* MMLU), but does not have an advantage in math (*e.g.,* GSM8K) and coding (*e.g.,* HumanEval). CoSD-Rule is relatively general and performs well across three domains; however, it is not as effective as the decision tree on MMLU (*e.g.,* 56.97 for CoSD-Rule and 58.37 for CoSD-Tree in pair 1).

323 These results highlight the effectiveness of COSD, particularly the superior fusion capabilities across multiple benchmarks and model pairs. The clear improvements in accuracy demonstrate

Models	Benchmarks	Draft	Assist.	Spec. Decoding	Avg. Decoding	$Co-LLM$	CoSD-Rule	CoSD-Tree
Pair 1	MMLU	54.81	52.02	53.20	52.31	55.25	56.97	58.37
	GSM8K	39.79	51.02	43.85	43.89	41.04	45.72	41.89
	HumanEval	21.34	43.90	39.02	38.41	37.25	39.10	36.22
Pair 2	MMLU	65.82	59.26	59.33	62.22	60.40	65.06	63.71
	GSM8K	31.20	42.19	33.36	38.33	38.85	36.81	37.24
	HumanEval	28.66	31.10	14.02	25.60	29.91	31.34	28.29
	MMLU	61.45	46.59	43.39	56.60	58.78	62.41	63.87
Pair 3	GSM8K	25.01	35.43	33.10	36.61	37.15	45.47	33.85
	HumanEval	27.44	9.76	10.97	18.90	21.88	25.61	23.17
Pair 4	MMLU	32.13	47.65	47.30	42.62	47.47	47.84	48.15
	GSM8K	3.36	15.63	14.63	12.12	11.97	12.52	12.29
	HumanEval	8.53	12.20	10.39	12.55	11.73	12.80	10.54

Table 2: The results of fusing LLMs with complementary knowledge and the same tokenizer. Pair 1 and pair 2 are complementary knowledge fusion results. Pair 3 simulates a catastrophic forgetting healing scenario, and pair 4 is a disparate capacity LLM fusion result.

Table 3: Fusing LLMs with different tokenizers.

	Models Benchmarks Draft Assist. Char-ED CoSD-Rule					CoSD-Tree
Pair 5	MMLU GSM8K	47.65 15.63	40.61 51.13	44.29 37.54	50.65 44.88	52.13 37.01
Pair 6	MMLU HumanEval $\begin{array}{ c c c }$ 8.53	47.65	59.63 73.17	52.51 59.04	57.33 59.88	55.20 51.42

that our methods not only efficiently fuse LLMs with complementary knowledge but also enhance performance across a wide range of tasks.

Catastrophic Forgetting Recovery. We select a Mistral base model and a fine-tuned math Mistral model for pair 3 in Table [2](#page-6-0) to simulate the catastrophic forgetting recovery. We found that CoSD-Rule performs particularly well on this type of task. It not only recovers from forgetting across all benchmarks but also outperforms both the draft and assistant models on MMLU and GSM8K. These results suggest that COSD can further enhance the original performance of both models by enabling collaboration between them.

360 361 362 363 364 365 366 367 368 369 Fusing LLMs with disparate capacity. When the assistant model has a much larger capacity than the draft model, the model fusion system is supposed to achieve a similar performance to the draft model. Speculative Decoding is more suited for this task because its verification strategy tends to replace more draft tokens with assistant tokens. However, COSD results in pair 4, Table [2](#page-6-0) are still comparable to Speculative Decoding. For instance, CoSD-Rule has higher MMLU and HumanEval scores than Speculative Decoding and has comparable GSM8K performance to Speculative Decoding. These results on LLMs with disparate capacities indicate that COSD is not only applicable to complementary knowledge LLM fusion but also to efficient inference tasks. When the draft model is smaller and the assistant model is larger, our COSD can achieve performance similar to the assistant model. At the same time, since the assistant model only performs parallel verification, COSD still has more efficient inference compared to using the assistant model alone.

370

371 372 373 374 375 376 377 Fusing LLMs with Different Tokenizers. Although COSD needs to decode and then encode the sequences during the verification when the models have different tokenizers, which sacrifices some efficiency, it can still effectively fuse the model knowledge. In the experiments, we fuse a Llama 2 Chat and a WizardMath to evaluate the COSD performance on MMLU and GSM8K. We fuse a Llama 2 Chat and a Deepseek Coder to evaluate COSD on MMLU and HumanEval. Results are shown in Table [3.](#page-6-1) COSD outperforms the character-wise averaging method CharED [\(Gu et al.,](#page-10-1) [2024\)](#page-10-1) in both model pairs and benchmarks. We do not include other baselines since they are not applicable to the different tokenizer settings.

379 380 381 Table 4: Training the decision tree with different datasets. Each column represents a decision tree trained by the dataset in the column header. Experiments are done by pair 3. We use 10 samples of MMLU, 3 samples of each other datasets to train the decision tree.

Benchmarks MMLU GSM8K			HumanEval	AlpacaEval
MMLU	63.94	60.88	61.23	63.87
GSM8K	35.04	37.17	30.08	33.85
HumanEval	25.62	23.04	23.09	23.17

389 390 391 392 Table 5: Efficiency of LLM Knowledge Fusion. Token latency represents the average time to generate a single token, and acceptance rate refers to the proportion of draft tokens that were not replaced. Typically, the higher the latter, the lower the former, as fewer tokens require replacement and regeneration. Experiments are done by pair 3.

Figure 2: The sum score of MMLU and GSM8K with various α , β settings on pair 1 (left figure) and pair 2 (right figure).

417 418 419 420 421 422 423 Figure [2](#page-7-0) shows the relationship between α , β values in Rule-Based COSD and model performance. The x-axis represents the values of α , and the y-axis represents the values of β . The numbers in the small squares represent the sum score of MMLU and GSM8K, which reflect the overall model performance of COSD. We can see that with $\alpha = 0.5, 0.75$ and $\beta = 0.5, 0.75$, Rule-Based COSD perform consistently well in the two model pairs. We ultimately selected $\alpha = 0.5, \beta = 0.5$ as the general hyperparameters in our experiments. We believe this setting effectively integrates the knowledge of the models.

424 425 426 427 428 429 430 431 Table [4](#page-7-1) displays the impact of the tree training dataset on Tree-Based COSD. The decision tree trained on different datasets performs relatively consistently, even when the training set is not in the same distribution with any benchmark (e.g., AlpacaEval, which achieved good results across all three benchmarks.). When the decision tree's training set shares the same distribution as a particular benchmark, Tree-Based COSD tends to perform slightly better on that benchmark. Therefore, if users are aware of the model's application scenario, they can use the corresponding benchmark from that task to train the decision tree. This would result in a domain-adapted tree that is better suited to the specific task. In addition, as mentioned in the table title, we use very few samples to train the decision tree, thus training decision trees introduces almost no additional computational overhead.

8

Ablation Studies. We have several tunable hy-

In Rule-Based COSD, we have α and β that determine the rules to replace the draft tokens. In Tree-Based COSD, the training data and hyperparameters influence the performance of the decision tree. Thus, we use ablation experiments to identify the impact of these hyperparameters on the

allowing us to determine the optimal and transferable hyperparameter settings.

432 433 434 435 436 437 438 439 Case Studies. We use an example in GSM8K to demonstrate how CoSD effectively combines the knowledge of two models in Table [6.](#page-9-1) CoSD replaces the red tokens generated by the draft model with the green tokens from the assistant model. Neither the draft model nor the assistant generates the correct result when used alone. The main issue with the draft model is its weak mathematical calculation ability (*e.g.,* in the fourth line, it calculates the tax as 20% of 20 to be 10, instead of the correct answer 4). On the other hand, the assistant model performs well in terms of mathematical calculations but lacks the logical rigor of the draft model (it fails to compute the subtotal of \$24 without the tip, leading to the incorrect final calculation of $15+3+2+5$).

440 441 442 443 444 445 COSD effectively integrates the strengths of both models. For instance, in CoSD-Rule, in the fifth line, the assistant model rejects the draft model's incorrect computation of 20% of 20 = 10 and instead uses the correct calculation of $20 * 0.2 = 4$, successfully avoiding the error in the draft model's tax calculation. In the sixth line, the draft model correctly leads to generate the subtotal of \$24, so in the final step, CoSD-Rule computes the simpler $24 + 5$ instead of the more complicated $15 + 3 + 2 + 5$, resulting in the correct answer.

446 447 448 449 450 451 452 Also, there are situations that COSD makes wrong decisions. As shown in Table [9](#page-13-0) in Appendix [A,](#page-12-8) COSD does not always select the correct answer. In the above example, the draft model made the correct choice with high confidence, so the final generation retained the correct answer. However, in the example below, while the draft model also made the correct choice, the assistant model provided an incorrect answer with higher confidence, leading to the final output being changed to the wrong answer. This demonstrates that using confidence as the criterion does not guarantee selecting the correct option but can only aim to choose the correct answer with a higher probability.

453 454 455 456 457 458 459 Efficiency. Since we perform fusion during the inference stage, efficiency is a major advantage of our approach. We compared the time overhead of our method with the baselines. We use token latency and acceptance rate as the metrics for efficiency. As displayed in Table [5,](#page-7-2) Speculative Decoding has the lowest latency among all methods, since it makes the least token replacement. However, although COSD methods replace a few more tokens, the increase in total latency is almost negligible. Considering that COSD has the best knowledge fusion performance, we have achieved a better balance between efficiency and effectiveness.

460 461

462

5 CONCLUSION

463 464 465 466 467 468 469 470 471 472 473 474 In this paper, we fuse the LLMs' knowledge in a simple yet effective way. Our proposed algorithm COSD takes the probabilities of predicted tokens from two LLMs as the feature to verify whether to keep the draft token or adopt the assistant token. The verification strategy can be either a rule-based or a pre-trained decision tree. Our extensive experiments show that COSD performs better than the state-of-the-art methods across 6 LLM pairs and 3 benchmarks. Compared to previous works, COSD has superior knowledge fusion ability, a broader range of application scenarios, and comparable efficiency. It works well in scenarios including complementary knowledge fusion, catastrophic forgetting recovery, knowledge fusion with disparate model capacity, and knowledge fusion with different tokenizers. COSD makes it possible for ordinary users to fuse the LLM knowledge with only the API queries, without any training or fine-tuning of LLMs, or requirements of white-box LLM information such as hidden states. It provides users with better tools to manipulate LLMs in wider application scenarios.

475 476

477

6 LIMITATION

478 479 480 481 While COSD demonstrates strong performance across various scenarios, it is important to acknowledge its limitations. This section highlights cases where COSD may not be applicable and tasks that it fails to address. Identifying these constraints provides clarity on its scope of use and helps guide future improvements. Below, we outline two specific limitations:

482 483 484 485 (1) When the two collaborating models are of similar size and one significantly outperforms the other, COSD offers no advantage over using only the better model. In this case, using the better model only is sufficient. This also requires the user to have prior knowledge of the performance of the two models on different benchmarks and to determine that one model is significantly better than the other. If the user is uncertain, we still recommend using COSD to ensure the best results.

Table 6: An example of how COSD polish the draft generation in GSM8K dataset. The table shows the different outputs for the same question generated by the Draft Model, Assistant Model, and two CoSD algorithms. In the CoSD outputs, tokens that are not highlighted represent accepted draft tokens, while tokens marked in pink are rejected draft tokens, followed by the assistant tokens that replace the rejected ones highlighted in green.

(2) Another limitation of COSD is that it cannot guarantee the replaced assistant token is always better than the discarded draft one. It relies on the confidence scores of the models, which are not always perfectly aligned with token quality. The algorithm selects the output of the more confident model, aiming to maximize the likelihood of choosing a better token, but this approach may occasionally lead to suboptimal results.

533 534 535

REFERENCES

536 537

538 539 Josh Achiam, Steven Adler, Sandhini Agarwal, Lama Ahmad, Ilge Akkaya, Florencia Leoni Aleman, Diogo Almeida, Janko Altenschmidt, Sam Altman, Shyamal Anadkat, et al. Gpt-4 technical report. arXiv preprint arXiv:2303.08774, 2023.

- **540 541 542** Samuel K Ainsworth, Jonathan Hayase, and Siddhartha Srinivasa. Git re-basin: Merging models modulo permutation symmetries. arXiv preprint arXiv:2209.04836, 2022.
- **543 544 545 546** Malothu Amru, Raju Jagadeesh Kannan, Enthrakandi Narasimhan Ganesh, Surulivelu Muthumarilakshmi, Kuppan Padmanaban, Jeyaprakash Jeyapriya, and Subbiah Murugan. Network intrusion detection system by applying ensemble model for smart home. International Journal of Electrical & Computer Engineering (2088-8708), 14(3), 2024.
- **547 548 549** Charlie Chen, Sebastian Borgeaud, Geoffrey Irving, Jean-Baptiste Lespiau, Laurent Sifre, and John Jumper. Accelerating large language model decoding with speculative sampling. arXiv preprint arXiv:2302.01318, 2023.
- **550 551 552 553 554 555 556 557 558 559 560** Mark Chen, Jerry Tworek, Heewoo Jun, Qiming Yuan, Henrique Ponde de Oliveira Pinto, Jared Kaplan, Harri Edwards, Yuri Burda, Nicholas Joseph, Greg Brockman, Alex Ray, Raul Puri, Gretchen Krueger, Michael Petrov, Heidy Khlaaf, Girish Sastry, Pamela Mishkin, Brooke Chan, Scott Gray, Nick Ryder, Mikhail Pavlov, Alethea Power, Lukasz Kaiser, Mohammad Bavarian, Clemens Winter, Philippe Tillet, Felipe Petroski Such, Dave Cummings, Matthias Plappert, Fotios Chantzis, Elizabeth Barnes, Ariel Herbert-Voss, William Hebgen Guss, Alex Nichol, Alex Paino, Nikolas Tezak, Jie Tang, Igor Babuschkin, Suchir Balaji, Shantanu Jain, William Saunders, Christopher Hesse, Andrew N. Carr, Jan Leike, Josh Achiam, Vedant Misra, Evan Morikawa, Alec Radford, Matthew Knight, Miles Brundage, Mira Murati, Katie Mayer, Peter Welinder, Bob McGrew, Dario Amodei, Sam McCandlish, Ilya Sutskever, and Wojciech Zaremba. Evaluating large language models trained on code, 2021.
- **561 562 563** Karl Cobbe, Vineet Kosaraju, Mohammad Bavarian, Mark Chen, Heewoo Jun, Lukasz Kaiser, Matthias Plappert, Jerry Tworek, Jacob Hilton, Reiichiro Nakano, et al. Training verifiers to solve math word problems. arXiv preprint arXiv:2110.14168, 2021.
- **564 565 566 567** Abhimanyu Dubey, Abhinav Jauhri, Abhinav Pandey, Abhishek Kadian, Ahmad Al-Dahle, Aiesha Letman, Akhil Mathur, Alan Schelten, Amy Yang, Angela Fan, et al. The llama 3 herd of models. arXiv preprint arXiv:2407.21783, 2024.
- **568 569 570** Mostafa Elhoushi, Akshat Shrivastava, Diana Liskovich, Basil Hosmer, Bram Wasti, Liangzhen Lai, Anas Mahmoud, Bilge Acun, Saurabh Agarwal, Ahmed Roman, et al. Layer skip: Enabling early exit inference and self-speculative decoding. arXiv preprint arXiv:2404.16710, 2024.
- **571 572 573** Charles Goddard, Shamane Siriwardhana, Malikeh Ehghaghi, Luke Meyers, Vlad Karpukhin, Brian Benedict, Mark McQuade, and Jacob Solawetz. Arcee's mergekit: A toolkit for merging large language models. arXiv preprint arXiv:2403.13257, 2024.
- **574 575 576 577** Kevin Gu, Eva Tuecke, Dmitriy Katz, Raya Horesh, David Alvarez-Melis, and Mikhail Yurochkin. Chared: Character-wise ensemble decoding for large language models. arXiv preprint arXiv:2407.11009, 2024.
- **578 579 580** Daya Guo, Qihao Zhu, Dejian Yang, Zhenda Xie, Kai Dong, Wentao Zhang, Guanting Chen, Xiao Bi, Yu Wu, YK Li, et al. Deepseek-coder: When the large language model meets programming–the rise of code intelligence. arXiv preprint arXiv:2401.14196, 2024.
- **581 582** Zhenyu He, Zexuan Zhong, Tianle Cai, Jason D Lee, and Di He. Rest: Retrieval-based speculative decoding. arXiv preprint arXiv:2311.08252, 2023.
- **583 584 585 586** Dan Hendrycks, Collin Burns, Steven Basart, Andy Zou, Mantas Mazeika, Dawn Song, and Jacob Steinhardt. Measuring massive multitask language understanding. arXiv preprint arXiv:2009.03300, 2020.
	- Akira Ito, Masanori Yamada, and Atsutoshi Kumagai. Analysis of linear mode connectivity via permutation-based weight matching. arXiv preprint arXiv:2402.04051, 2024.

587 588

- **589 590 591** Shashank Mohan Jain. Hugging face. In Introduction to transformers for NLP: With the hugging face library and models to solve problems, pp. 51–67. Springer, 2022.
- **592 593** Albert Q Jiang, Alexandre Sablayrolles, Arthur Mensch, Chris Bamford, Devendra Singh Chaplot, Diego de las Casas, Florian Bressand, Gianna Lengyel, Guillaume Lample, Lucile Saulnier, et al. Mistral 7b. arXiv preprint arXiv:2310.06825, 2023.

Table 7: Average number of iterations for different maximum output lengths.

256 15.29 16.01 14.20 512 21.23 21.95 18.51

689 690 691 692 693 Although the number of iterations scales with the output length, it does not directly imply a proportional increase in generation time. As the number of accepted tokens grows, the number of tokens requiring regeneration decreases significantly. For instance, with a maximum output length of 128, the average number of iterations is 11, but the total generated output length remains around 300 tokens. This highlights the efficiency of our approach in reducing redundant generation.

694 695 696 Collaborate with More LLMs. Our COSD also supports multiple collaborating models. Table [8](#page-12-8) presents the results when three models are used for collaboration:

Table 8: Performance of three collaborator LLMs.

Table 9: Two examples of how COSD modify the generation in MMLU dataset. The example above demonstrates how COSD helps improve generation quality, while the example below shows instances where COSD sometimes selects incorrect answers.

723 724 725 726 727 In this setup, the draft model is TinyLlama, while the assistant models are Llama 2 Chat 7b and Llama-7b. Our findings demonstrate that involving additional models improves prediction accuracy. Table [8](#page-12-8) demonstrates that when three models collaborate if one significantly outperforms the other two, the final system will achieve performance close to that of the best model. This indicates that our algorithm is effective when applied to more than two models. With sufficient LLMs, we can also better utilize training data, even when certain samples are excluded.

728 729 730 731 732 733 734 The Case Study of MMLU. While COSD is effective in many cases, there are instances where it makes incorrect decisions, highlighting its limitations. As shown in Table [9,](#page-13-0) COSD does not always select the correct answer when the draft model and the assistant model disagree. In the first example, the draft model correctly identified the answer with high confidence, which allowed the final output to retain the accurate result. This showcases the potential of COSD to preserve correct answers when confidence aligns with accuracy.

735 736 737 738 739 740 However, in the second example, the draft model once again made the correct prediction, but the assistant model, despite being incorrect, provided an answer with higher confidence. Consequently, the final output was altered to the wrong answer, overriding the draft model's correct prediction. This illustrates a shortcoming of the COSD approach: relying solely on confidence scores as the decision-making criterion does not guarantee correctness. Confidence may reflect certainty but not necessarily accuracy, leading to situations where errors from the assistant model dominate the final outcome.

741 742 743 744 745 746 This limitation suggests that while COSD can improve generation quality by prioritizing higherconfidence predictions, it does so with the assumption that confidence correlates with correctness. In practice, this assumption does not always hold, especially when the assistant model is overconfident in its incorrect predictions. To address this, future improvements could explore additional heuristics or cross-validation mechanisms to better balance confidence with accuracy, ensuring that correct answers are more consistently selected.

747 748

707

711

713 714

- **749**
- **750**
- **751**
- **752**
- **753**
- **754**

755