
Algorithm 1 Training Stage of EEG2Video Framework

Input: (1) training set $\mathcal{D}_{train} = \{x_i, v_i, d_i\}$, where x_i is EEG segments, v_i is video clips, d_i is the fast/slow label (2) stable diffusion model $T2I$, whose VAE encoder is \mathcal{E}_{vae} (3) image caption model B

Output: (1) video diffusion model $T2V$, (2) Seq2Seq model $Seq2Seq$, (3) semantic predictor \mathcal{P}_s , (4) dynamic predictor \mathcal{P}_d

- 1: Initialize text prompts of training dataset $T = \{t_i\}$
 - 2: **for** each $(v_i) \in \mathcal{D}_{train}$ **do**
 - 3: $v_i = \{f_1, f_2, \dots, f_n\}$
 - 4: $t_i \leftarrow B(f_1)$
 - 5: **end for**
 - 6: Initialize latent vectors of all frames $L = \{z_i\}$
 - 7: **for** each $(v_i) \in \mathcal{D}_{train}$ **do**
 - 8: $v_i = \{f_1, f_2, \dots, f_n\}$
 - 9: $z_i = \{l_1, l_2, \dots, l_n\}$
 - 10: **for** each $(f_j) \in v_i$ **do**
 - 11: $l_j \leftarrow VAE(f_j)$
 - 12: **end for**
 - 13: **end for**
 - 14: Fine-tune the $T2I$ with $\{v_i, t_i\}$ to obtain video diffusion model $T2V$
 - 15: Train the Seq2Seq model $Seq2Seq$ with all $\{x_i, z_i\}$ using MSE loss
 - 16: Train the semantic predictor \mathcal{P}_s with all $\{x_i, t_i\}$ using MSE loss
 - 17: Train the dynamic predictor \mathcal{P}_d with all $\{x_i, d_i\}$ using Cross Entropy loss
 - 18: **return** $T2V, Seq2Seq, \mathcal{P}_s, \mathcal{P}_d$
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Algorithm 2 Inference Stage of EEG2Video Framework

Input: (1) EEG segments x_i from test set \mathcal{D}_{test} , (2) video diffusion model $T2V$, (3) Seq2Seq model $Seq2Seq$, (4) semantic predictor \mathcal{P}_s , (5) dynamic predictor \mathcal{P}_d

Output: reconstructed videos \hat{v}_i ,

- 1: $\hat{z}_i \leftarrow Seq2Seq(x_i)$, $t_i \leftarrow \mathcal{P}_s(x_i)$, $d_i \leftarrow \mathcal{P}_d(x_i)$
 - 2: Randomly sample $\epsilon_d = \{\epsilon_d^1, \epsilon_d^2, \dots, \epsilon_d^n\}$, each $\epsilon_d^i \sim \mathcal{N}(0, 1)$
 - 3: Randomly sample $\epsilon_s = \{\epsilon, \epsilon, \dots, \epsilon\}$, where $\epsilon \sim \mathcal{N}(0, 1)$
 - 4: $z_{\mathcal{T}} \leftarrow \sqrt{\alpha_{\mathcal{T}}} \times \hat{z}_i + \sqrt{1 - \alpha_{\mathcal{T}}} \times (\sqrt{\beta} \times \epsilon_s + \sqrt{1 - \beta} \times \epsilon_d)$, where β is determined by d_i
 - 5: Generate videos $\hat{v}_i = T2V(z_{\mathcal{T}}, t_i)$
 - 6: **return** \hat{v}_i
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