## 810 A DETAILS OF BENCHMARKS

## 812 A.1 Additional Task Implementation Process and Statistics

In Section 3.5] we described our general benchmark creation process. Our task creation process can be
divided into three stages: (a) preparing the input image; (b) formulating task prompts; (c) developing
scripts for auto evaluation. Additionally, some specific tasks require extra steps to implement, such as
question and answer generation. In what follows, we describe these steps in detail.

Maze Navigation, Main Task In this task, agents need to find a safe path to navigate from the start grid to the goal. We adjust the map generation mechanisms to ensure the positions of the start grid, the goal, and the holes are all randomly generated, while ensuring there is at least one viable safe path from the start grid to the goal. For each grid, the probability that it contains the hole is 20%.

Maze Navigation, T1 In this task, agents need to identify whether a specific grid is safe (i.e., whether it contains a hole or not). We randomly sample a row number and a column number and ask the safety question for this randomly chosen grid in each problem of this task. Additionally, to prevent the model from patterned guessing and achieving falsely high ratings (e.g., answering "not safe" for all images and obtaining high accuracy scores), we regenerate the map for this task to ensure that the safe and unsafe grids each comprise around 50% of the total grids in a single map.

Maze Navigation, T3 In this task, agents need to find the correct textual description that fits the visual input. For each problem, we prepare four textual description candidates. One candidate is the correct answer, one has the correct size but an incorrect map arrangement, and the other two candidates have the wrong size. The candidates are shuffled to prevent the model from making random guesses.

Maze Navigation, T4 In this task, agents need to determine if the given action series is safe or not.
Similarly, to prevent the models from achieving falsely high ratings through guessing, we generate the action series to ensure that around 50% of them are safe and the other 50% are not. For the unsafe paths, the particular step in which the player steps into a hole is also randomly chosen.

Blocks World, T2 In this task, agents need to determine the spatial relation between two designated
blocks. In addition to the directional relation ("above" and "below"), we note that it is important for
agents to recognize if two blocks are at the same stack or not. Therefore, we design the following
four candidates for this question: (A) The first block is directly above the second block, and they are
in the same stack; (B) The first block is directly below the second block, and they are in the same
stack; (C) The two blocks are at different stacks; (D) At least one of the mentioned blocks do not
exist in the presented image.

Blocks World, T4 In this task, agents need to determine the consequence of a given moving plan.
Specifically, some invalid moving plans contain actions that cannot be executed in the given scenario, such as trying to move a block that is covered by another block. To prevent guessing in this task, similar to the maze navigation scenario, we generate the action plans to ensure that half of the plan candidates are executable. For the plans that cannot be executed, there can be two types of errors: first, the plan may include steps that involve moving a block from or to an invalid position; second, the plan may try to move a block that does not exist. We randomly generate these errors in inputs.

Google Map For each task in this scenario, the input image is derived from real Google map intersections. To ensure that the roads on the map align with these four directions (north, south, east, west), we selected a map of New York City, where the streets and avenues intersect at 90 degrees. The map has been rotated to ensure that streets and avenues are strictly aligned in one of these cardinal directions. The starting location and the goal are randomly chosed crossroads in the map.

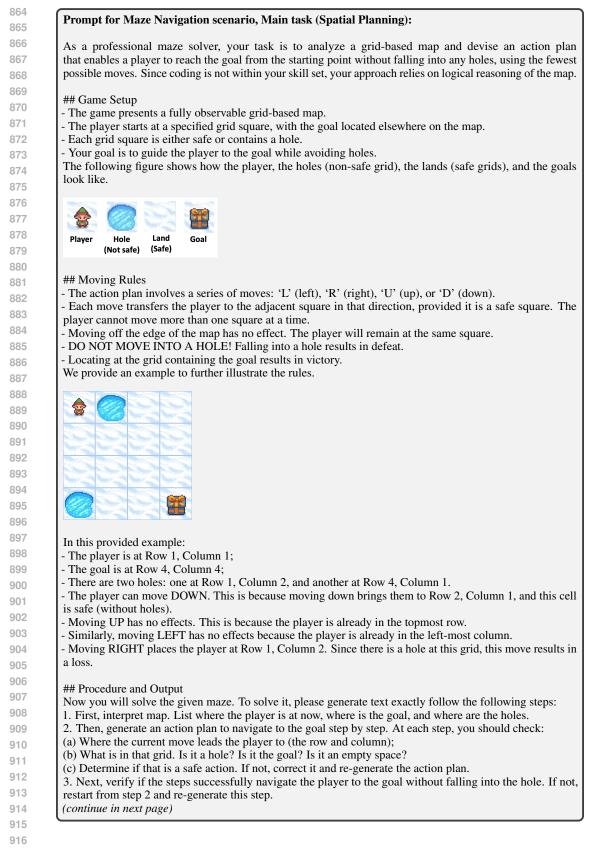
Statistics The VSP benchmark consists of 12 tasks in four scenarios. In *Maze Navigation* and *Blocks World* scenarios, the problems are designed with different difficulty levels. Each difficulty level
 consists of 100 problems. In total, the VSP benchmark includes 4.6k questions.

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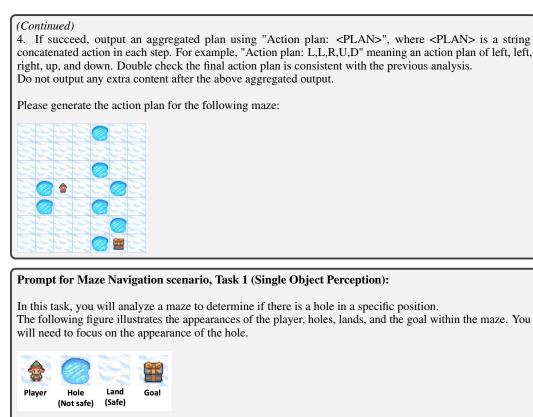
#### A.2 COMPLETE PROMPT

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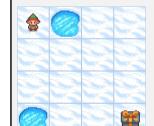
In this subsection, we provide the complete prompts for each task. Generally, the prompts consist of
 a general task description at the beginning and a specific question at the end. The prompts interleave
 text and images in a pattern similar to a human-readable manual with reference figures.







Here is an example to illustrate how to analyze and answer the question:



Example question: Is there a hole in row 3, column 3?

In this example:

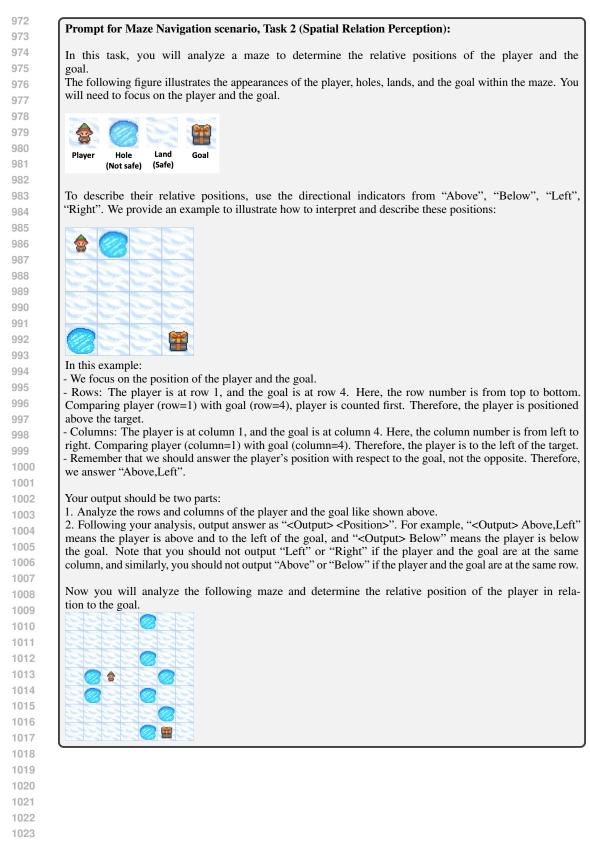
- We check the position in row 3, column 3.

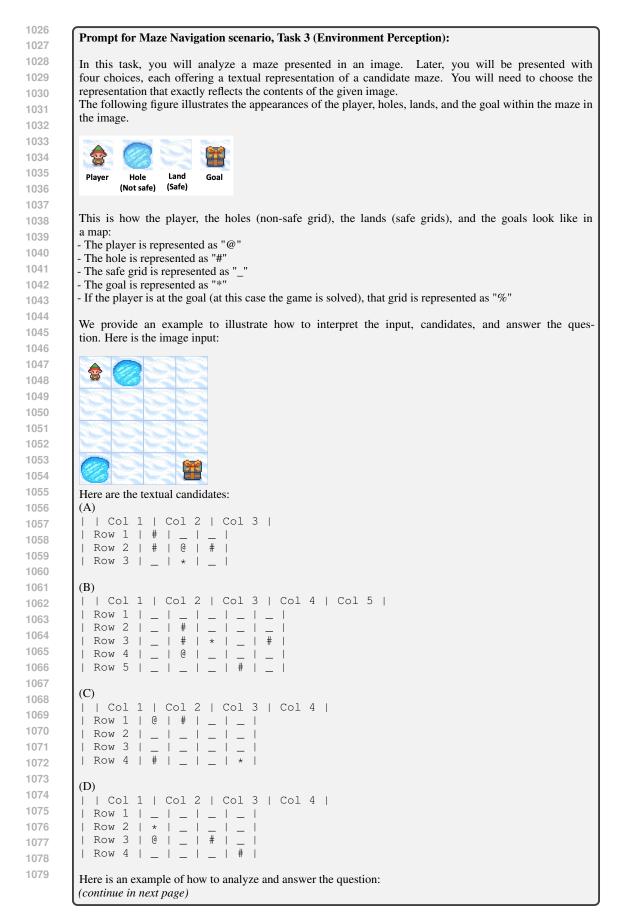
- According to the image, it is a land square. It does not contain a hole.

- Therefore, you will output "<Output> No".

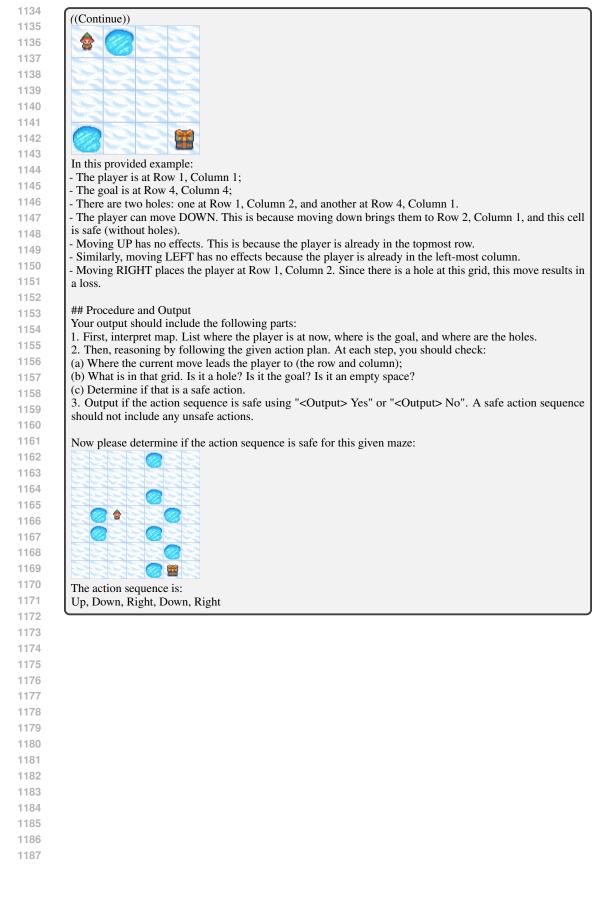
Your output should be: "<Output> No" or "<Output> Yes", depending on whether there is a hole at the specified position.

#### Now you will analyze the following maze and answer the question: Is there a hole in row 2, column 1?

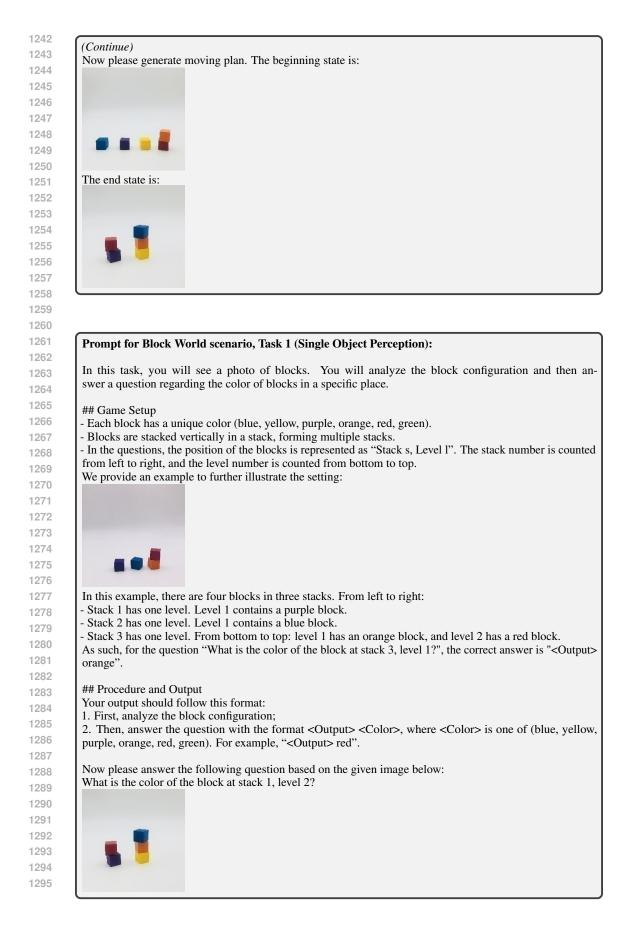


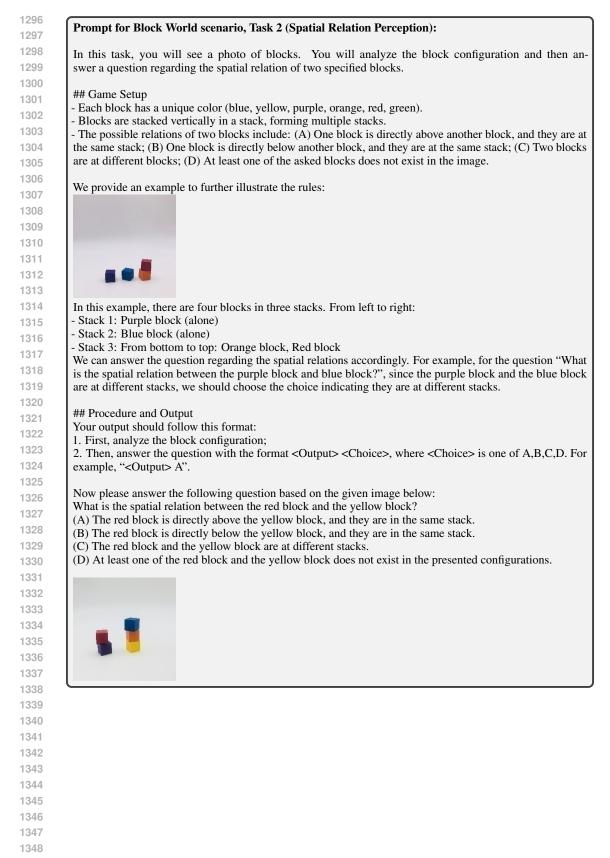


First, we focus	
	on the difference of the maze shape between the candidates and the input image.
	amining the input image. It is a 4-by-4 maze. We then review the candidates. Candidate A is
	Cherefore, it is not the correct answer. Similarly, Candidate B is a 5-by-5 maze, which also
	t. Both Candidate C and Candidate D are 4-by-4 mazes. Now we only need to choose from
them.	
	ng candidates, we compare the positions of the players, goals, and the holes in the maze.
	the input image. What is the position of the player in the image? The player is in row 1,
	en check the remaining candidates. For Candidate C, the textual representation indicates the
	row 1, column 1, matching the input image. For Candidate D, the player is located at row 3,
	e, Candidate D is not the correct answer.
	k the remaining Candidate C, and it correctly shows the position of the player, holes, and the
	bre the correct answer.
<answer> C</answer>	
Your output show	ld consist of two parts:
	the input image and candidates similar to the reasoning process above.
	reasoning process, output answer as " <answer> <choice>", where "<choice>" is one of</choice></choice></answer>
A,B,C,D.	
	that there will be only one correct answer. If you find no answer or multiple answers, you
	d recheck your reasoning process. You are not allowed to provide 0 or more than 1 answer.
must 50 back and	reencer your reasoning process. You are not anowed to provide o or more than I answer.
Now answer the	question below. Here is the image input:
	question below. Here is the minuge input.
22222	있곳곳 곳 · · · · · · · · · · · · · · · · ·
55556	
Here are the text	ual candidates:
<candidates< td=""><td>&gt;</td></candidates<>	>
D	ze Navigation scenario, Task 4 (Spatial Reasoning):
	e Navigation scenario. Task 4 (Snatiat Reasoning)
rrompt for Maz	a mangarion scenario, rask e (oparat Reasoning).
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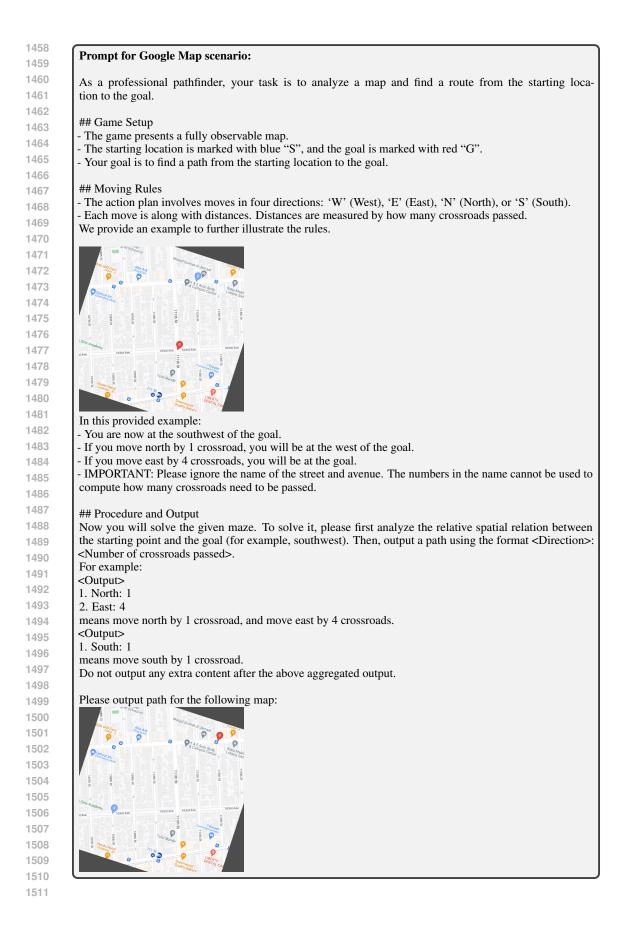
<sup>88</sup> 89 Prom	pt for Block World scenario, Main Task (Spatial Planning):
90 You a 91 You c	re a robot that sorts and organizes colored blocks by adding and removing them to stacks. an move them between stacks to produce a desired end state.
2	
the bl	s task, you will see two photos of blocks. These photos show the beginning and end state of ocks. Your task is to find a shortest movement plan to transit from the beginning state to the end state. coding is not within your skill set, your approach relies on logical reasoning of the map.
	une Cature
	me Setup stacks of blocks are presented in images. You must view and interpret the image in order to determine
	blocks are in which stack and determine how to move them.
	block has a unique color (blue, yellow, purple, orange, red, green).
	ks are stacked vertically in a stack, forming multiple stacks. All stacks are on the table.
	single move, you can only move the top block of any pile. Attempting to move lower blocks is dered an invalid move.
	can either (a) move the top block to the top of another stack, or (b) place the top block on the table,
	ng a new stack with just one block.
We pr	ovide an example to further illustrate the rules:
	g a 📕
This e	example features four blocks arranged in three stacks:
- Stacl	x 1: Purple block (alone)
	x 2: Blue block (alone)
	x 3: From bottom to top: Orange block, Red block
	an only move the top block of each stack: the purple block, the blue block, and the red block. The e block is stuck underneath the red block and cannot be moved directly.
	move can place the block on another stack or on the table (creating a new stack of one). For instance,
you co	buld move the red block to either the blue stack or the table.
	portant Note**: The order of the stacks doesn't matter in this game. Two images are considered
	alent as long as the stacks contain the same blocks, regardless of the order in which the stacks appear. cample, an image with stack A on the left and stack B on the right is equivalent to an image with stack
	the left and stack A on the right.
	-
	ocedure and Output
	but put should follow this format:
-	st, analyze the starting and ending configurations, including the number of stacks and the blocks in each (similar to the example above).
	en, list the moves in a step-by-step manner using the format move(SOURCE, TARGET). Remember,
"SOU	RCE" refers to the block being moved (always the top block of a stack), and "TARGET" refers to the
	ation (another stack or the table).
	ample Output
<anal Starti</anal 	ysis> ng state: there are three stacks:
	x 1: Purple block (alone)
- Stacl	x 2: Blue block (alone)
	x 3: From bottom to top: Orange block, Red block
	g state: there are three stacks:
	x 1: Purple block (alone) x 2: From bottom to top: Orange block, Blue block
	x 3: Red block (alone)
<outp< td=""><td>ut&gt;</td></outp<>	ut>
	ve(red,table)
2. mo	ve(blue,orange)
(conti	nue in next page)
Com	nue un nexa page)

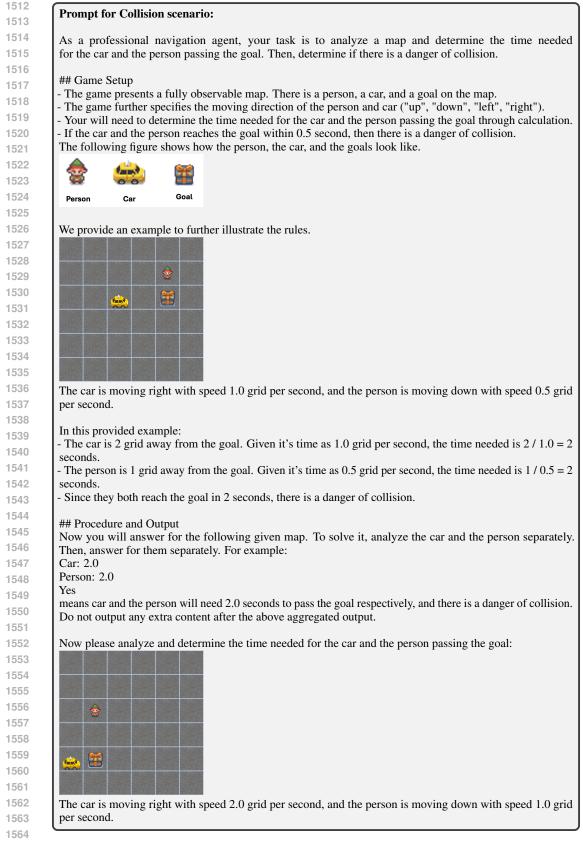






Pro	mpt for Maze Navigation scenario, Task 4 (Spatial Reasoning):
	are a robot that sorts and organizes colored blocks by adding and removing them to stacks.
	can move them between stacks to produce a desired end state.
	is task, you will see a photo of blocks. This photo shows the beginning state of the blocks. You will see oto of blocks. This photo shows the beginning state of the blocks. Meanwhile, you will be provided
	ction sequence about moving blocks. Your task is to determine if the provided action plan can be
	essfully executed.
	Game Setup e block configuration is presented in the image. You must view and interpret the image in order to
	rmine which blocks are in which stack and determine the consequence of moving.
	ch block has a unique color (blue, yellow, purple, orange, red, green).
	ocks are stacked vertically in a stack, forming multiple stacks.
	valid action can only move the top block of any stacks. Attempting to move lower blocks is considered an lid move.
	the destination, a valid move can either (a) move the top block to the top of another stack, or (b) place
the t	op block on the table, creating a new stack with just one block.
We	provide an example to further illustrate the rules:
	sequence of actions provided is: 1. move(red,table) 2. move(green,table)
	his example, there are four blocks in three stacks. The stacks are:
	ck 1: Purple block (alone) ck 2: Blue block (alone)
	ck 3: From bottom to top: Orange block, Red block
lt is	valid to move the purple block, the blue block, and the red block, since they are at the top of a stack. It is
	lid to move the orange block since it is not at the top of a stack (because it is covered by the red block).
	h move can place the block on top of another stack or on the table (creating a new stack of one). For ance, you could move the red block to either the blue stack or the table.
	Procedure and Output
	r output should follow this format:
	irst, briefly analyze the block configuration, and check each action step by step to see if the provided step alid as shown above.
	"hen, answer the question with the format " <output> Yes" or "<output> No" to indicate if the action</output></output>
sequ	ience is valid.
Here	e is an example for the output:
	alysis> In the image, there are three stacks: ck 1: Purple block (alone)
- Sta	ck 2: Blue block (alone)
Sta	ck 3: From bottom to top: Orange block, Red block
	first action "move(red,table)" is valid, because the red block is on top of a stack (stack 3 in this case), and arget is "table". After the first action, the state will become:
	ck 1: Purple block (alone)
- Sta	ck 2: Blue block (alone)
	ck 3: Orange block (alone)
	ck 4: Red block (alone) second action "move(green,table)" is invalid, because there is no green block.
	refore, the provided action sequence is invalid.
	tput> No
Now	v please determine if the provided action sequence is valid given the following input state:
	_ 1
The	action sequence is: 1. move(red,table) 2. move(yellow,red) 3. move(purple,table)





#### 1566 B PROMPT FOR TEXTUAL INPUT 1567

1568

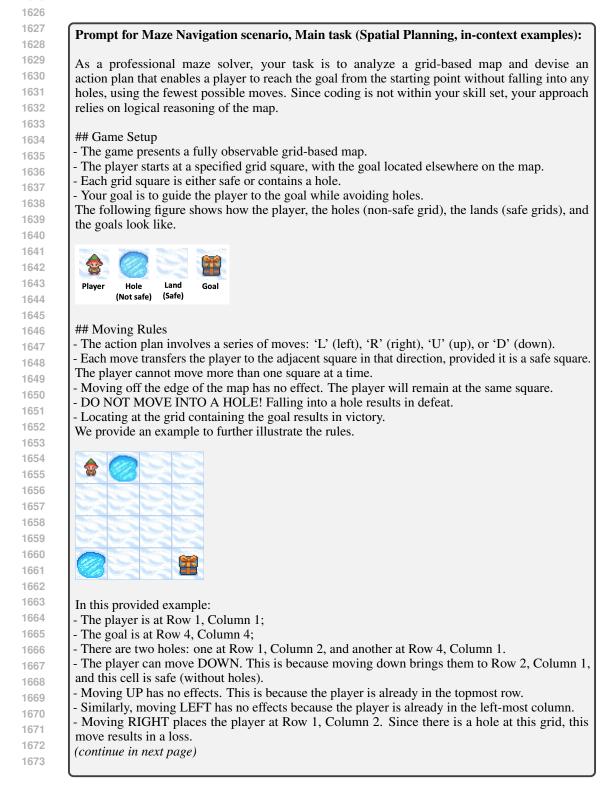
1572

In Section 4.4, we described the procedure of using textual representation instead of visual input.
Below, we use the main task in the maze navigation scenario as an example to show the complete
prompt after making the replacement.

1573	Prompt for Maze Navigation scenario, Main task (Spatial Planning, Textual Input):
1574	Trompt for Maze Wavigation scenario, Main task (Spatial Flamming, Textual Input).
1575	As a professional maze solver, your task is to analyze a grid-based map and devise an action plan
1576	that enables a player to reach the goal from the starting point without falling into any holes, using the fewest
1577	possible moves. Since coding is not within your skill set, your approach relies on logical reasoning of the map.
1578	## Game Setup
1579	- The game presents a fully observable grid-based map.
1580	- The player starts at a specified grid square, with the goal located elsewhere on the map.
1581	<ul> <li>Each grid square is either safe or contains a hole.</li> <li>Your goal is to guide the player to the goal while avoiding holes.</li> </ul>
1582 1583	- Tour goar is to guide the player to the goar while avoiding noies.
1584	## Moving Rules
1585	- The action plan involves a series of moves: 'L' (left), 'R' (right), 'U' (up), or 'D' (down).
1586	- Each move transfers the player to the adjacent square in that direction, provided it is a safe square. The
587	player cannot move more than one square at a time. - Moving off the edge of the map has no effect. The player will remain at the same square.
588	- DO NOT MOVE INTO A HOLE! Falling into a hole results in defeat.
i89	- Locating at the grid containing the goal results in victory.
i90	We provide an example to further illustrate the rules
591	We provide an example to further illustrate the rules. Example Input:
92	This is a 4x4 map.
93	The player is at: row 1, column 1;
594	The hole(s) are at: row 1, column 2; row 4, column 1;
95	The goal is at: row 4, column 4.
96	In this provided example:
597	- The player is at Row 1, Column 1;
98	- The goal is at Row 4, Column 4;
99	<ul> <li>There are two holes: one at Row 1, Column 2, and another at Row 4, Column 1.</li> <li>The player can move DOWN. This is because moving down brings them to Row 2, Column 1, and this cell</li> </ul>
00	is safe (without holes).
1	- Moving UP has no effects. This is because the player is already in the topmost row.
2	- Similarly, moving LEFT has no effects because the player is already in the left-most column.
	- Moving RIGHT places the player at Row 1, Column 2. Since there is a hole at this grid, this move results in
	a loss. ## Procedure and Output
	Now you will solve the given maze. To solve it, please generate text exactly follow the following steps:
	1. First, interpret map. List where the player is at now, where is the goal, and where are the holes.
	2. Then, generate an action plan to navigate to the goal step by step. At each step, you should check:
	<ul><li>(a) Where the current move leads the player to (the row and column);</li><li>(b) What is in that grid. Is it a hole? Is it the goal? Is it an empty space?</li></ul>
	(c) Determine if that is a safe action. If not, correct it and re-generate the action plan.
	3. Next, verify if the steps successfully navigate the player to the goal without falling into the hole. If not,
	restart from step 2 and re-generate this step.
	4. If succeed, output an aggregated plan using "Action plan: <plan>", where <plan> is a string</plan></plan>
	concatenated action in each step. For example, "Action plan: L,L,R,U,D" meaning an action plan of left, left, right, up, and down. Double check the final action plan is consistent with the previous analysis.
ļ.	Do not output any extra content after the above aggregated output.
5	
6	Please generate the action plan for the following maze:
7	This is a 3x3 map.
8	The player is at: row 3, column 2; There is no holes in this map;
19	The goal is at: Row 1, Column 2.

### <sup>1620</sup> C PROMPT WITH IN-CONTEXT EXAMPLES

In Section 4.4, we described the procedure of including in-context example in the test. Below, we use the main task in the maze navigation scenario as an example to show the complete prompt after adding in-context examples.



74	
	Continue)
70 #	# Procedure and Output
IN	ow you will solve the given maze. To solve it, please generate text exactly follow the following
SI	eps:
79 2	First, interpret map. List where the player is at now, where is the goal, and where are the holes. . Then, generate an action plan to navigate to the goal step by step. At each step, you should
	neck:
	) Where the current move leads the player to (the row and column);
	b) What is in that grid. Is it a hole? Is it the goal? Is it an empty space?
	b) Determine if that is a safe action. If not, correct it and re-generate the action plan.
	Next, verify if the steps successfully navigate the player to the goal without falling into the hole. not, restart from step 2 and re-generate this step.
"	not, restart nom step 2 and re-generate uns step.
#	# Example:
R	
2	
E	
þ	
F	
<]	Interpret>
Т	he player is at row 1, column 1, and the goal is at row 2, column 2.
Т	here are 2 holes. They are at: row 3, column 2; row 3, column 3.
	Action Plan>
	Moving Right (R). The player is now at row 1, column 2. This grid is safe.
	Moving Down (D). The player is now at row 2, column 2. This grid is the goal, so we stop here.
	Verification>
	Right to row 1, column 2 (safe) Down to row 2, column 2 (goal)
	Dutput>
	ction plan: R,D
-	
P	lease generate the action plan for the following maze:
100	
2.61	
200	
224	
_	

Table 6: Training details on LLavA and InternLM-AComposer.					
		Value			
	Learning rate	2e-4			
	Scheduler	Cosine			
	Epoch	1			
LLaVA	Training data	10k			
	Batch size	32			
	Pretrained Checkpoint	llava-v1.6-vicuna-7b			
	Learning rate	5e-5			
	Scheduler	Cosine			
	Epoch	1			
InternLM	Training data	10k			
	Batch size	8			
	Pretrained Checkpoint	internlm-xcomposer2-7b			

#### Table 6: Training details on LLaVA and InternLM-XComposer.

Table 7: Model performance on task 1 - 4 with different difficulties.

Task 1		MAZE NAVIGATION				BLOCKSWORD				
Difficulty	3	4	5	6	7	8	3	4	5	
Gemini Team et al. (2023)	0.63	0.58	0.61	0.45	0.64	0.54	0.86	0.82	0.89	
GPT-Vision Achiam et al. (2023)	0.60	0.56	0.56	0.47	0.62	0.54	0.77	0.70	0.7	
Claude-3 AI (2024a)	0.44	0.41	0.39	0.42	0.55	0.49	0.52	0.40	0.3	
GPT-40 AT	0.72	0.65	0.57	0.44	0.56	0.53	0.98	0.94	0.9	
Task 2		MAZE NAVIGATION					BLOCKSWORD			
Difficulty	3	4	5	6	7	8	3	4	5	
Gemini Team et al. (2023)	0.69	0.65	0.53	0.46	0.54	0.47	0.63	0.57	0.3	
GPT-Vision Achiam et al. (2023)	0.37	0.27	0.22	0.30	0.29	0.18	0.86	0.77	0.7	
Claude-3 AI (2024a)	0.65	0.65	0.70	0.65	0.67	0.70	0.59	0.57	0.4	
GPT-40 AI	0.80	0.63	0.65	0.64	0.66	0.64	0.90	0.92	0.8	
Task 3		MAZE NAVIGATION					BLOCKSWORD			
Difficulty	3	4	5	6	7	8	3	4	5	
Gemini Team et al. (2023)	0.38	0.32	0.36	0.23	0.37	0.30	0.62	0.51	0.4	
GPT-Vision Achiam et al. (2023)	0.79	0.41	0.43	0.37	0.33	0.40	0.68	0.76	0.6	
Claude-3 AI (2024a)	0.35	0.22	0.18	0.32	0.35	0.47	0.52	0.45	0.4	
GPT-40 AI	0.89	0.72	0.49	0.4	0.39	0.59	0.85	0.95	0.9	
Task 4		MAZE NAVIGATION			]	BLOCKSWORD				
Difficulty	1	3	5	7	9	1	3	5	7	
Gemini Team et al. (2023)	0.47	0.47	0.56	0.49	0.46	0.64	0.57	0.50	0.5	
GPT-Vision Achiam et al. (2023)	0.62	0.55	0.57	0.52	0.53	0.66	0.70	0.74	0.7	
Claude-3 AI (2024a)	0.57	0.60	0.60	0.59	0.67	0.72	0.65	0.60	0.6	
GPT-40 AI	0.72	0.78	0.79	0.67	0.76	0.92	0.73	0.70	0.6	

#### D TRAINING DETAILS

In this section, we describe the training details when we fine-tune LLaVA and InternLM-XComposer for our designed tasks. We perform LoRA fine-tuning, and we stick with the default hyperparameter settings in their official repo. The detailed hyperparameter choices are shown in Table 6.

# E COMPLETE TASK PERFORMANCE RESULTS WITH DIFFERENT DIFFICULTY LEVELS

In this section, we present the experimental results of models across different difficulty levels. The results are shown in Table 7. As expected, we observe that as difficulty increases, all models perform progressively worse, with some performing close to random guessing at higher difficulty levels (*e.g.*, Task 1 in Maze Navigation scenario). We also observe that GPT-40, the most recently released model, performs the best across different tasks, although it still frequently makes mistakes under different difficulty levels. This suggests a current bottleneck in state-of-the-art MLLMs.