

This appendix is organized as following.

- Section A provides missing proofs of the theoretical results in Section 3.
- Section B provides missing proofs of the theoretical results in Section 4.
- Section C provides more details of experiments.

Appendix A. Missing Proofs of Section 3

A.1. Proof of Lemma 3

Proof Substituting (12a) into (9a), we obtain

$$\left\{ \widehat{f}_\rho(\mathbf{w}_{k+1}) + \frac{1}{2} \|\mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k\|^2 \right\} - \min_{\mathbf{w}} \left\{ \widehat{f}_\rho(\mathbf{w}) + \frac{1}{2} \|\mathbf{w} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k\|^2 \right\} \leq \epsilon_{k+1}/\rho.$$

Applying strong convexity of the objective, the left-hand side can be relaxed as

$$\left\{ \widehat{f}_\rho(\mathbf{w}_{k+1}) + \frac{1}{2} \|\mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k\|^2 \right\} - \min_{\mathbf{w}} \left\{ \widehat{f}_\rho(\mathbf{w}_{k+1}) + \frac{1}{2} \|\mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k\|^2 \right. \\ \left. + \langle \nabla \widehat{f}_\rho(\mathbf{w}_{k+1}) + \mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k, \mathbf{w} - \mathbf{w}_{k+1} \rangle + \frac{\widehat{m} + \rho}{2\rho} \|\mathbf{w} - \mathbf{w}_{k+1}\|^2 \right\} \leq \epsilon_{k+1}/\rho.$$

It is equivalent to

$$-\min_{\mathbf{w}} \left\{ \langle \nabla \widehat{f}_\rho(\mathbf{w}_{k+1}) + \mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k, \mathbf{w} - \mathbf{w}_{k+1} \rangle + \frac{\widehat{m} + \rho}{2\rho} \|\mathbf{w} - \mathbf{w}_{k+1}\|^2 \right\} \leq \epsilon_{k+1}/\rho. \quad (\text{A30})$$

Taking the optimum for \mathbf{w} , we obtain

$$\|\nabla \widehat{f}_\rho(\mathbf{w}_{k+1}) + \mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k\|^2 \leq \frac{2(\rho + \widehat{m})\epsilon_{k+1}}{\rho^2}.$$

This implies that there exists $\boldsymbol{\eta}_{k+1} \in \mathbb{R}^p$ with $\|\boldsymbol{\eta}_{k+1}\|^2 \leq 2(\rho + \widehat{m})\epsilon_{k+1}/\rho^2$ such that

$$\nabla \widehat{f}_\rho(\mathbf{w}_{k+1}) + \mathbf{w}_{k+1} + \mathbf{s}_k - \mathbf{c} - \mathbf{u}_k + \boldsymbol{\eta}_{k+1} = \mathbf{0}.$$

Substituting $\boldsymbol{\beta}_{k+1} = \nabla \widehat{f}_\rho(\mathbf{w}_{k+1})$, it becomes

$$\mathbf{w}_{k+1} = -\mathbf{s}_k + \mathbf{u}_k - (\boldsymbol{\beta}_{k+1} + \boldsymbol{\eta}_{k+1}) + \mathbf{c}. \quad (\text{A31})$$

Substituting (12b) into (9b),

$$\left\{ \widehat{g}_\rho(\mathbf{s}_{k+1}) + \frac{1}{2} \|\alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k\|^2 \right\} \\ - \min_{\mathbf{s}} \left\{ \widehat{g}_\rho(\mathbf{s}) + \frac{1}{2} \|\alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s} - \alpha \mathbf{c} - \mathbf{u}_k\|^2 \right\} \leq \delta_{k+1}/\rho.$$

Applying strong convexity of the objective, the left-hand side can be relaxed as

$$\left\{ \widehat{g}_\rho(\mathbf{s}_{k+1}) + \frac{1}{2} \|\alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k\|^2 \right\}$$

$$\begin{aligned}
 & - \min_{\mathbf{s}} \left\{ \frac{1}{2} \|\alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k\|^2 + \widehat{g}_\rho(\mathbf{s}_{k+1}) \right. \\
 & \quad \left. + \langle \gamma_{k+1} + \alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k, \mathbf{s} - \mathbf{s}_{k+1} \rangle + \frac{1}{2} \|\mathbf{s} - \mathbf{s}_{k+1}\|^2 \right\} \leq \delta_{k+1}/\rho.
 \end{aligned}$$

It is equivalent to

$$- \min_{\mathbf{s}} \left\{ \langle \gamma_{k+1} + \alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k, \mathbf{s} - \mathbf{s}_{k+1} \rangle + \frac{1}{2} \|\mathbf{s} - \mathbf{s}_{k+1}\|^2 \right\} \leq \delta_{k+1}/\rho.$$

Taking the optimum for \mathbf{s} , we obtain

$$\|\gamma_{k+1} + \alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k\|^2 \leq \frac{2\delta_{k+1}}{\rho}.$$

This implies that there exists $\zeta_{k+1} \in \mathbb{R}^p$ with $\|\zeta_{k+1}\|^2 \leq 2\delta_{k+1}/\rho$ such that

$$\gamma_{k+1} + \alpha \mathbf{w}_{k+1} - (1 - \alpha) \mathbf{s}_k + \mathbf{s}_{k+1} - \alpha \mathbf{c} - \mathbf{u}_k + \zeta_{k+1} = \mathbf{0}. \quad (\text{A32})$$

It follows then that

$$\mathbf{s}_{k+1} = -\alpha \mathbf{w}_{k+1} + (1 - \alpha) \mathbf{s}_k + \mathbf{u}_k - (\gamma_{k+1} + \zeta_{k+1}) + \alpha \mathbf{c}.$$

Substituting (A31), we obtain

$$\mathbf{s}_{k+1} = \mathbf{s}_k + (1 - \alpha) \mathbf{u}_k + \alpha (\boldsymbol{\beta}_{k+1} + \boldsymbol{\eta}_{k+1}) - (\gamma_{k+1} + \zeta_{k+1}). \quad (\text{A33})$$

Combining (12c) and (A32), we obtain

$$\mathbf{u}_{k+1} = \gamma_{k+1} + \zeta_{k+1}. \quad (\text{A34})$$

Given (A31), (A33) and (A34), it is straightforward to show

$$\begin{aligned}
 \boldsymbol{\xi}_{k+1} &= (\widehat{\mathbf{A}} \otimes \mathbf{I}_p) \boldsymbol{\xi}_k + (\widehat{\mathbf{B}} \otimes \mathbf{I}_p) \mathbf{v}_k, \\
 \mathbf{y}_k^1 &= (\widehat{\mathbf{C}}^1 \otimes \mathbf{I}_p) \boldsymbol{\xi}_k + (\widehat{\mathbf{D}}^1 \otimes \mathbf{I}_p) \mathbf{v}_k, \\
 \mathbf{y}_k^2 &= (\widehat{\mathbf{C}}^2 \otimes \mathbf{I}_p) \boldsymbol{\xi}_k + (\widehat{\mathbf{D}}^2 \otimes \mathbf{I}_p) \mathbf{v}_k.
 \end{aligned}$$

This completes the proof. ■

A.2. Proof of Lemma 4

Before starting our main proof, we first introduce the following lemma.

Lemma A12 *Under the same setting as Lemma 3, the following inequality holds for $\forall k \geq 0$:*

$$\|a(\mathbf{w}_{k+1} - \mathbf{w}_\star) + b(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_\star)\| \leq \max(|a|, |b|) (\|\boldsymbol{\xi}_k - \boldsymbol{\xi}_\star\| + \|\boldsymbol{\eta}_{k+1}\|). \quad (\text{A35})$$

Proof It can be proved by applying Lemma 1 and the definition of our dynamical system.

$$\begin{aligned}
 & \max(a^2, b^2) \|\mathbf{w}_{k+1} - \mathbf{w}_* + \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*\|^2 - \|a(\mathbf{w}_{k+1} - \mathbf{w}_*) + b(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\|^2 \\
 &= (\max(a^2, b^2) - a^2) \|\mathbf{w}_{k+1} - \mathbf{w}_*\|^2 + 2(\max(a^2, b^2) - ab) \langle \mathbf{w}_{k+1} - \mathbf{w}_*, \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \rangle \\
 & \quad + (\max(a^2, b^2) - b^2) \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*\|^2 \\
 & \geq 2(\max(a^2, b^2) - ab) \langle \mathbf{w}_{k+1} - \mathbf{w}_*, \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \rangle \geq 0,
 \end{aligned}$$

where the last inequality follows from Lemma 1. Thus,

$$\|a(\mathbf{w}_{k+1} - \mathbf{w}_*) + b(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\| \leq \max(|a|, |b|) \|(\mathbf{w}_{k+1} - \mathbf{w}_*) + (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\|. \quad (\text{A36})$$

Applying the definition of our dynamical system,

$$\begin{aligned}
 & (\mathbf{w}_{k+1} - \mathbf{w}_*) + (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \\
 &= -\mathbf{s}_k + \mathbf{u}_k - (\boldsymbol{\beta}_{k+1} + \boldsymbol{\eta}_{k+1}) + \mathbf{c} - (-\mathbf{s}_* + \mathbf{u}_* - \boldsymbol{\beta}_* + \mathbf{c}) + (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \\
 &= -(\mathbf{s}_k - \mathbf{s}_*) + (\mathbf{u}_k - \mathbf{u}_*) - \boldsymbol{\eta}_{k+1}.
 \end{aligned}$$

Thus, $\|(\mathbf{w}_{k+1} - \mathbf{w}_*) + (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\|$ becomes

$$\begin{aligned}
 \|(\mathbf{w}_{k+1} - \mathbf{w}_*) + (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\| &\leq \|(\mathbf{s}_k - \mathbf{s}_*) - (\mathbf{u}_k - \mathbf{u}_*)\| + \|\boldsymbol{\eta}_{k+1}\| \\
 &= \|(\mathbf{s}_k - \mathbf{s}_*) - (\boldsymbol{\gamma}_k - \boldsymbol{\gamma}_*)\| + \|\boldsymbol{\eta}_{k+1}\| \\
 &\leq \sqrt{\|\mathbf{s}_k - \mathbf{s}_*\|^2 + \|\boldsymbol{\gamma}_k - \boldsymbol{\gamma}_*\|^2} + \|\boldsymbol{\eta}_{k+1}\| \\
 &= \left\| \begin{bmatrix} \mathbf{s}_k - \mathbf{s}_* \\ \boldsymbol{\gamma}_k - \boldsymbol{\gamma}_* \end{bmatrix} \right\| + \|\boldsymbol{\eta}_{k+1}\| \\
 &= \left\| \begin{bmatrix} \mathbf{s}_k - \mathbf{s}_* \\ \mathbf{u}_k - \mathbf{u}_* \end{bmatrix} \right\| + \|\boldsymbol{\eta}_{k+1}\| \\
 &= \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| + \|\boldsymbol{\eta}_{k+1}\|,
 \end{aligned}$$

where the second inequality follows from Lemma 1. Substituting it into (A36), we obtain

$$\|a(\mathbf{w}_{k+1} - \mathbf{w}_*) + b(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*)\| \leq \max(|a|, |b|) (\|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| + \|\boldsymbol{\eta}_{k+1}\|).$$

This completes the proof. ■

Next, we start to prove Lemma 4.

A.3. proof of Lemma 4

Proof By the fact that $\boldsymbol{\xi}_*$ is a fixed point of (14), $(\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*)$ can be rewritten as

$$\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_* = ((\widehat{\mathbf{A}} \otimes \mathbf{I}_p) \boldsymbol{\xi}_k + (\widehat{\mathbf{B}} \otimes \mathbf{I}_p) \mathbf{v}_k) - ((\widehat{\mathbf{A}} \otimes \mathbf{I}_p) \boldsymbol{\xi}_* + (\widehat{\mathbf{B}} \otimes \mathbf{I}_p) \mathbf{v}_*) = \begin{bmatrix} \widehat{\mathbf{A}} \otimes \mathbf{I}_p & \widehat{\mathbf{B}} \otimes \mathbf{I}_p \end{bmatrix} \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}.$$

Thus,

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) = \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}^\top \left(\begin{bmatrix} \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} - \tau^2 \widehat{\mathbf{P}} & \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \\ \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} & \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \end{bmatrix} \otimes \mathbf{I}_p \right) \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}.$$

Applying (19), it becomes

$$\begin{aligned}
 V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) &\leq \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}^\top \left(\left(\begin{bmatrix} \widehat{\mathbf{C}}^1 & \widehat{\mathbf{D}}^1 \\ \widehat{\mathbf{C}}^2 & \widehat{\mathbf{D}}^2 \end{bmatrix}^\top \begin{bmatrix} \lambda^1 \widehat{\mathbf{M}}^1 & \mathbf{0} \\ \mathbf{0} & \lambda^2 \widehat{\mathbf{M}}^2 \end{bmatrix} \begin{bmatrix} \widehat{\mathbf{C}}^1 & \widehat{\mathbf{D}}^1 \\ \widehat{\mathbf{C}}^2 & \widehat{\mathbf{D}}^2 \end{bmatrix} \right) \otimes \mathbf{I}_p \right) \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix} \\
 &= \begin{bmatrix} \mathbf{y}_k^1 - \mathbf{y}_*^1 \\ \mathbf{y}_k^2 - \mathbf{y}_*^2 \end{bmatrix}^\top \left(\begin{bmatrix} \lambda^1 \widehat{\mathbf{M}}^1 & \mathbf{0}_2 \\ \mathbf{0}_2 & \lambda^2 \widehat{\mathbf{M}}^2 \end{bmatrix} \otimes \mathbf{I}_p \right) \begin{bmatrix} \mathbf{y}_k^1 - \mathbf{y}_*^1 \\ \mathbf{y}_k^2 - \mathbf{y}_*^2 \end{bmatrix} \\
 &= \lambda^1 (\mathbf{y}_k^1 - \mathbf{y}_*^1)^\top (\widehat{\mathbf{M}}^1 \otimes \mathbf{I}_p) (\mathbf{y}_k^1 - \mathbf{y}_*^1) + \lambda^2 (\mathbf{y}_k^2 - \mathbf{y}_*^2)^\top (\widehat{\mathbf{M}}^2 \otimes \mathbf{I}_p) (\mathbf{y}_k^2 - \mathbf{y}_*^2).
 \end{aligned}$$

Substituting $\widehat{\mathbf{M}}^1$ and $\widehat{\mathbf{M}}^2$, we obtain

$$\begin{aligned}
 V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) &\leq \lambda^1 \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \end{bmatrix}^\top (\widehat{\mathbf{M}}^1 \otimes \mathbf{I}_p) \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \end{bmatrix} - 2\lambda^2 \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\gamma}_{k+1} - \boldsymbol{\gamma}_* \rangle \\
 &\quad + 2\lambda^1 \langle \boldsymbol{\eta}_{k+1}, \widehat{M}_{12}^1 (\mathbf{w}_{k+1} - \mathbf{w}_*) + \widehat{M}_{22}^1 (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \rangle + \lambda^1 \widehat{M}_{22}^1 \|\boldsymbol{\eta}_{k+1}\|^2 - 2\lambda^2 \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle.
 \end{aligned}$$

Applying Lemmas 1 and 2, it becomes

$$\begin{aligned}
 V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) &\leq 2\lambda^1 \langle \boldsymbol{\eta}_{k+1}, \widehat{M}_{12}^1 (\mathbf{w}_{k+1} - \mathbf{w}_*) + \widehat{M}_{22}^1 (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \rangle + \lambda^1 \widehat{M}_{22}^1 \|\boldsymbol{\eta}_{k+1}\|^2 \\
 &\quad - 2\lambda^2 \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle.
 \end{aligned}$$

The right-hand side can be further relaxed as

$$\begin{aligned}
 &V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) \\
 &\leq 2\lambda^1 \langle \boldsymbol{\eta}_{k+1}, \widehat{M}_{12}^1 (\mathbf{w}_{k+1} - \mathbf{w}_*) + \widehat{M}_{22}^1 (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \rangle + \lambda^1 \widehat{M}_{22}^1 \|\boldsymbol{\eta}_{k+1}\|^2 - 2\lambda^2 \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle \\
 &\leq 2\lambda^1 \left\| \widehat{M}_{12}^1 (\mathbf{w}_{k+1} - \mathbf{w}_*) + 2(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) \right\| \|\boldsymbol{\eta}_{k+1}\| + 2\lambda^1 \|\boldsymbol{\eta}_{k+1}\|^2 + 2\lambda^2 \|\mathbf{s}_{k+1} - \mathbf{s}_*\| \|\boldsymbol{\zeta}_{k+1}\|.
 \end{aligned}$$

Applying Lemma A12,

$$\begin{aligned}
 &V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) \\
 &\leq 2\lambda^1 \max(2, |\widehat{M}_{12}^1|) (\|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| + \|\boldsymbol{\eta}_{k+1}\|) \|\boldsymbol{\eta}_{k+1}\| + 2\lambda^1 \|\boldsymbol{\eta}_{k+1}\|^2 + 2\lambda^2 \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \|\boldsymbol{\zeta}_{k+1}\| \\
 &\leq 2\lambda^1 \max(2, |\widehat{M}_{12}^1|) \|\boldsymbol{\eta}_{k+1}\| \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| + 2\lambda^1 (1 + \max(2, |\widehat{M}_{12}^1|)) \|\boldsymbol{\eta}_{k+1}\|^2 + 2\lambda^2 \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \|\boldsymbol{\zeta}_{k+1}\|.
 \end{aligned}$$

It can be rewritten as

$$\begin{aligned}
 V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) &\leq \frac{2\lambda^1 \max(2\rho, \widehat{m} + \widehat{L})}{\rho} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \|\boldsymbol{\eta}_{k+1}\| + \frac{2\lambda^1 \max(3\rho, \rho + \widehat{m} + \widehat{L})}{\rho} \|\boldsymbol{\eta}_{k+1}\|^2 \\
 &\quad + 2\lambda^2 \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \|\boldsymbol{\zeta}_{k+1}\|.
 \end{aligned}$$

Substituting $\|\boldsymbol{\eta}_{k+1}\|^2 \leq 2(\rho + \widehat{m})\epsilon_{k+1}/\rho^2$ and $\|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\|^2 \leq 2\delta_{k+1}/\rho$,

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) \leq \frac{2\sqrt{2}\lambda^1 \sqrt{\rho + \widehat{m}} \max(2\rho, \widehat{m} + \widehat{L})}{\rho^2} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\epsilon_{k+1}} + 2\lambda^2 \sqrt{\frac{2}{\rho}} \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \sqrt{\delta_{k+1}}$$

$$+ \frac{4\lambda^1(\rho + \widehat{m}) \max(3\rho, \rho + \widehat{m} + \widehat{L})}{\rho^3} \epsilon_{k+1}.$$

Substituting $\widehat{\theta}, \widetilde{\theta}$ and $\bar{\theta}$, it becomes

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) \leq \widetilde{\theta} \epsilon_{k+1} + \widehat{\theta} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\epsilon_{k+1}} + \bar{\theta} \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \sqrt{\delta_{k+1}}.$$

This completes the proof. ■

A.4. Proof of Theorem 7

Following is a useful lemma on non-negative sequences that will be used in the analysis of inexact over-relaxed ADMM.

Lemma A13 *Assume that an increasing sequence $\{S_k\}_{k \geq 0}$, three non-negative sequences $\{\widehat{\lambda}_k\}_{k \geq 0}$, $\{\bar{\lambda}_k\}_{k \geq 0}$ and $\{\beta_k\}_{k \geq 0}$ satisfy $S_0 \geq \beta_0^2$ and*

$$\beta_T^2 \leq S_T + \sum_{k=1}^T \widehat{\lambda}_k \beta_{k-1} + \sum_{k=1}^T \bar{\lambda}_k \beta_k, \forall T \geq 1.$$

Then, $\forall T \geq 0$:

$$\beta_T \leq \frac{1}{2} \sum_{k=1}^T (\widehat{\lambda}_k + \bar{\lambda}_k) + \left(S_T + \left(\frac{1}{2} \sum_{k=1}^T (\widehat{\lambda}_k + \bar{\lambda}_k) \right)^2 \right)^{1/2}. \quad (\text{A37})$$

$$\beta_T^2 \leq S_T + \sum_{k=1}^T \widehat{\lambda}_k \beta_{k-1} + \sum_{k=1}^T \bar{\lambda}_k \beta_k \leq \left(\sqrt{S_T} + \sum_{k=1}^T (\widehat{\lambda}_k + \bar{\lambda}_k) \right)^2. \quad (\text{A38})$$

The proof of Lemma A13 is provided in Section A.4.1.

With Lemma A13 at hand, we are ready to prove Theorem 7.

Proof For convenience, we define $E_{k+1} \stackrel{\text{def}}{=} \widetilde{\theta} \epsilon_{k+1} + \widehat{\theta} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\epsilon_{k+1}} + \bar{\theta} \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \sqrt{\delta_{k+1}}, \forall k \geq 0$. Then, the result of Lemma 4 can be rewritten as

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) \leq \tau^2 V_{\mathbf{P}}(\boldsymbol{\xi}_k) + E_{k+1}.$$

Applying the relationship from $k = 0$ to $k = T - 1$ recursively, we obtain

$$V_{\mathbf{P}}(\boldsymbol{\xi}_T) \leq \tau^{2T} V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \sum_{k=1}^T \tau^{2(T-k)} E_k.$$

Substituting E_k , it becomes

$$V_{\mathbf{P}}(\boldsymbol{\xi}_T) \leq \tau^{2T} V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \sum_{k=1}^T \tau^{2(T-k)} \left(\widetilde{\theta} \epsilon_k + \widehat{\theta} \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \bar{\theta} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k} \right).$$

Multiplying both sides with τ^{-2T} ,

$$\tau^{-2T} V_{\mathbf{P}}(\boldsymbol{\xi}_T) \leq V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \tilde{\theta} \sum_{k=1}^T \tau^{-2k} \epsilon_k + \hat{\theta} \sum_{k=1}^T \tau^{-2k} \sqrt{\epsilon_k} \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| + \bar{\theta} \sum_{k=1}^T \tau^{-2k} \sqrt{\delta_k} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\|. \quad (\text{A39})$$

By further relaxing the right-hand side,

$$\tau^{-2T} \sigma_{\mathbf{P}}^{\min} \|\boldsymbol{\xi}_T - \boldsymbol{\xi}_*\| \leq V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \tilde{\theta} \sum_{k=1}^T \tau^{-2k} \epsilon_k + \hat{\theta} \sum_{k=1}^T \tau^{-2k} \sqrt{\epsilon_k} \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| + \bar{\theta} \sum_{k=1}^T \tau^{-2k} \sqrt{\delta_k} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\|.$$

It is equivalent to

$$\tau^{-2T} \|\boldsymbol{\xi}_T - \boldsymbol{\xi}_*\|^2 \leq \frac{1}{\sigma_{\mathbf{P}}^{\min}} \left\{ V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \tilde{\theta} \sum_{k=1}^T \tau^{-2k} \epsilon_k \right\} + \frac{\hat{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-2k} \sqrt{\epsilon_k} \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| + \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-2k} \sqrt{\delta_k} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\|.$$

It can be rewritten as

$$\begin{aligned} (\tau^{-T} \|\boldsymbol{\xi}_T - \boldsymbol{\xi}_*\|)^2 &\leq \frac{1}{\sigma_{\mathbf{P}}^{\min}} \left\{ V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \tilde{\theta} \sum_{k=1}^T \tau^{-2k} \epsilon_k \right\} + \sum_{k=1}^T \left(\tau^{-(k+1)} \frac{\hat{\theta} \sqrt{\epsilon_k}}{\sigma_{\mathbf{P}}^{\min}} \right) \left(\tau^{-(k-1)} \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \right) \\ &\quad + \sum_{k=1}^T \left(\tau^{-k} \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\delta_k} \right) \left(\tau^{-k} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \right). \end{aligned}$$

Applying Lemma A13 with

$$\beta_k \stackrel{\text{def}}{=} \tau^{-k} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\|, \quad S_T \stackrel{\text{def}}{=} \frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-2k} \epsilon_k, \quad \hat{\lambda}_k \stackrel{\text{def}}{=} \tau^{-(k+1)} \frac{\hat{\theta} \sqrt{\epsilon_k}}{\sigma_{\mathbf{P}}^{\min}}, \quad \bar{\lambda}_k \stackrel{\text{def}}{=} \tau^{-k} \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\delta_k},$$

we obtain

$$\begin{aligned} \tau^{-2T} \|\boldsymbol{\xi}_T - \boldsymbol{\xi}_*\|^2 &\leq \left(\sqrt{\frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-2k} \epsilon_k} + \sum_{k=1}^T \left(\tau^{-(k+1)} \frac{\hat{\theta} \sqrt{\epsilon_k}}{\sigma_{\mathbf{P}}^{\min}} + \tau^{-k} \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\delta_k} \right) \right)^2 \\ &\leq \left(\sqrt{\frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}}} + \sqrt{\frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-2k} \epsilon_k} + \frac{\hat{\theta}}{\tau \sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\epsilon_k} + \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\delta_k} \right)^2 \\ &\leq \left(\sqrt{\frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}}} + \sqrt{\frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\epsilon_k}} + \frac{\hat{\theta}}{\tau \sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\epsilon_k} + \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\delta_k} \right)^2. \end{aligned}$$

It can be rewritten as

$$\|\boldsymbol{\xi}_T - \boldsymbol{\xi}_*\|^2 \leq \tau^{2T} \left(\sqrt{\frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}}} + \left(\sqrt{\frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}}} + \frac{\hat{\theta}}{\tau \sigma_{\mathbf{P}}^{\min}} \right) \sum_{k=1}^T \tau^{-k} \sqrt{\epsilon_k} + \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\delta_k} \right)^2.$$

Substituting φ , it becomes

$$\|\varphi_T - \varphi_\star\| \leq \tau^T \left(\sqrt{\kappa_{\mathbf{P}}} \|\varphi_0 - \varphi_\star\| + \left(\sqrt{\frac{\tilde{\theta}}{\sigma_{\mathbf{P}}^{\min}}} + \frac{\hat{\theta}}{\tau \sigma_{\mathbf{P}}^{\min}} \right) \sum_{k=1}^T \tau^{-k} \sqrt{\epsilon_k} + \frac{\bar{\theta}}{\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \tau^{-k} \sqrt{\delta_k} \right).$$

This completes the proof. \blacksquare

A.4.1. PROOF OF LEMMA A13

Proof This lemma is obtained by slightly modifying Lemma 1 presented in (?). We prove it by induction. It is true for $T = 0$ by assumption. Next, we assume it is true for $(T - 1)$, then prove it is also true for T . We denote $\tilde{\beta}_{T-1} \stackrel{\text{def}}{=} \max\{\beta_0, \dots, \beta_{T-1}\}$. It leads to

$$\beta_T^2 \leq S_T + \tilde{\beta}_{T-1} \left(\sum_{k=1}^T \hat{\lambda}_k + \sum_{k=1}^{T-1} \bar{\lambda}_k \right) + \bar{\lambda}_T \beta_T \Rightarrow \left(\beta_T - \frac{\bar{\lambda}_T}{2} \right)^2 \leq S_T + \frac{\bar{\lambda}_T^2}{4} + \tilde{\beta}_{T-1} \left(\sum_{k=1}^T \hat{\lambda}_k + \sum_{k=1}^{T-1} \bar{\lambda}_k \right)$$

The definition of $\tilde{\beta}_T$ implies

$$\tilde{\beta}_T = \max\{\beta_0, \dots, \beta_{T-1}, \beta_T\} \leq \max \left\{ \tilde{\beta}_{T-1}, \frac{\bar{\lambda}_T}{2} + \left(S_T + \frac{\bar{\lambda}_T^2}{4} + \tilde{\beta}_{T-1} \left(\sum_{k=1}^T \hat{\lambda}_k + \sum_{k=1}^{T-1} \bar{\lambda}_k \right) \right)^{1/2} \right\}.$$

The two terms in the maximum are equal if $\left(\tilde{\beta}_{T-1} - \frac{\bar{\lambda}_T}{2} \right)^2 = S_T + \frac{\bar{\lambda}_T^2}{4} + \tilde{\beta}_{T-1} \left(\sum_{k=1}^T \hat{\lambda}_k + \sum_{k=1}^{T-1} \bar{\lambda}_k \right)$, i.e.,

$$\tilde{\beta}_{T-1}^* = \frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) + \left(S_T + \left(\frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) \right)^2 \right)^{1/2}.$$

Then, we can consider two cases.

Case 1: If $\tilde{\beta}_{T-1} \leq \tilde{\beta}_{T-1}^*$, then $\tilde{\beta}_T \leq \tilde{\beta}_{T-1}^*$ since the two terms in the maximum are increasing function of $\tilde{\beta}_{T-1}$.

Case 2: If $\tilde{\beta}_{T-1} > \tilde{\beta}_{T-1}^*$, then

$$\tilde{\beta}_{T-1} > \tilde{\beta}_{T-1}^* = \frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) + \left(S_T + \left(\frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) \right)^2 \right)^{1/2}.$$

This leads to a contradiction as we assume (A37) holds for $(T - 1)$. Combining two cases together, we obtain

$$\beta_T \leq \tilde{\beta}_T \leq \frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) + \left(S_T + \left(\frac{1}{2} \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) \right)^2 \right)^{1/2}.$$

Next, we prove the (A38). It can be proved by applying (A37). Relaxing the right-hand side of (A37), we obtain

$$\beta_k \leq \sqrt{S_k} + \sum_{i=1}^k (\hat{\lambda}_i + \bar{\lambda}_i), \forall k \geq 0.$$

Thus,

$$\begin{aligned} \beta_T^2 &\leq S_T + \sum_{k=1}^T \hat{\lambda}_k \beta_{k-1} + \sum_{k=1}^T \bar{\lambda}_k \beta_k \\ &\leq S_T + \sum_{k=1}^T \hat{\lambda}_k \left(\sqrt{S_{k-1}} + \sum_{i=1}^{k-1} (\hat{\lambda}_i + \bar{\lambda}_i) \right) + \sum_{k=1}^T \bar{\lambda}_k \left(\sqrt{S_k} + \sum_{i=1}^k (\hat{\lambda}_i + \bar{\lambda}_i) \right) \\ &\leq S_T + \left(\sqrt{S_T} + \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) \right) \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k). \end{aligned}$$

It implies

$$\beta_T^2 \leq \left(\sqrt{S_T} + \sum_{k=1}^T (\hat{\lambda}_k + \bar{\lambda}_k) \right)^2.$$

This completes the proof. ■

Appendix B. Missing Proofs of Section 4

B.1. Proof of Lemma 8

Proof Since $\hat{f}_\rho(\mathbf{w})$ is convex and \hat{L}/ρ -smooth, and $\hat{g}_\rho(\mathbf{w})$ is convex,

$$\begin{aligned} \hat{f}_\rho(\mathbf{w}_\star) &\geq \hat{f}_\rho(\mathbf{w}_{k+1}) + \langle \boldsymbol{\beta}_{k+1}, \mathbf{w}_\star - \mathbf{w}_{k+1} \rangle + \frac{\rho}{2\hat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_\star\|^2, \\ \hat{g}_\rho(\mathbf{s}_\star) &\geq \hat{g}_\rho(\mathbf{s}_{k+1}) + \langle \boldsymbol{\gamma}_{k+1}, \mathbf{s}_\star - \mathbf{s}_{k+1} \rangle. \end{aligned}$$

Summing up them together,

$$\hat{f}_\rho(\mathbf{w}_\star) + \hat{g}_\rho(\mathbf{s}_\star) \geq \hat{f}_\rho(\mathbf{w}_{k+1}) + \hat{g}_\rho(\mathbf{s}_{k+1}) + \langle \boldsymbol{\beta}_{k+1}, \mathbf{w}_\star - \mathbf{w}_{k+1} \rangle + \langle \boldsymbol{\gamma}_{k+1}, \mathbf{s}_\star - \mathbf{s}_{k+1} \rangle + \frac{\rho}{2\hat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_\star\|^2.$$

Rearranging both sides,

$$\begin{aligned} &\hat{f}_\rho(\mathbf{w}_\star) - \hat{f}_\rho(\mathbf{w}_{k+1}) + \hat{g}_\rho(\mathbf{s}_\star) - \hat{g}_\rho(\mathbf{s}_{k+1}) - \langle \boldsymbol{\beta}_\star, \mathbf{w}_\star - \mathbf{w}_{k+1} \rangle - \langle \boldsymbol{\gamma}_\star, \mathbf{s}_\star - \mathbf{s}_{k+1} \rangle \\ &\geq -\langle \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_\star, \mathbf{w}_{k+1} - \mathbf{w}_\star \rangle - \langle \boldsymbol{\gamma}_{k+1} - \boldsymbol{\gamma}_\star, \mathbf{s}_{k+1} - \mathbf{s}_\star \rangle + \frac{\rho}{2\hat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_\star\|^2. \end{aligned} \quad (\text{A40})$$

The optimality conditions of $(\mathbf{w}_\star, \mathbf{s}_\star, \mathbf{u}_\star)$ imply

$$\boldsymbol{\beta}_\star - \mathbf{u}_\star = \mathbf{0}, \quad \boldsymbol{\gamma}_\star - \mathbf{u}_\star = \mathbf{0}, \quad \mathbf{w}_\star + \mathbf{s}_\star - \mathbf{c} = \mathbf{0}.$$

Substituting these into (A40), we obtain

$$\hat{f}_\rho(\mathbf{w}_\star) - \hat{f}_\rho(\mathbf{w}_{k+1}) + \hat{g}_\rho(\mathbf{s}_\star) - \hat{g}_\rho(\mathbf{s}_{k+1}) - \langle \mathbf{u}_\star, \mathbf{w}_\star - \mathbf{w}_{k+1} \rangle - \langle \mathbf{u}_\star, \mathbf{s}_\star - \mathbf{s}_{k+1} \rangle + \langle \mathbf{w}_\star + \mathbf{s}_\star - \mathbf{c}, \mathbf{u}_\star - \mathbf{u}_{k+1} \rangle$$

$$\geq -\langle \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*, \mathbf{w}_{k+1} - \mathbf{w}_* \rangle - \langle \boldsymbol{\gamma}_{k+1} - \boldsymbol{\gamma}_*, \mathbf{s}_{k+1} - \mathbf{s}_* \rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*\|^2.$$

It can be rewritten as

$$\begin{aligned} & -\langle \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*, \mathbf{w}_{k+1} - \mathbf{w}_* \rangle - \langle \boldsymbol{\gamma}_{k+1} - \boldsymbol{\gamma}_*, \mathbf{s}_{k+1} - \mathbf{s}_* \rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*\|^2 \\ & \leq \widehat{f}_\rho(\mathbf{w}_*) - \widehat{f}_\rho(\mathbf{w}_{k+1}) + \widehat{g}_\rho(\mathbf{s}_*) - \widehat{g}_\rho(\mathbf{s}_{k+1}) - \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \mathbf{s}_{k+1} - \mathbf{s}_* \\ \mathbf{u}_{k+1} - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix}. \end{aligned}$$

On the other hand, $S(\boldsymbol{\xi}_k, \mathbf{v}_k)$ can be written as

$$\begin{aligned} S(\boldsymbol{\xi}_k, \mathbf{v}_k) &= \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}^\top \left(\left(\begin{bmatrix} \widehat{\mathbf{C}}^1 & \widehat{\mathbf{D}}^1 \\ \widehat{\mathbf{C}}^2 & \widehat{\mathbf{D}}^2 \end{bmatrix}^\top \begin{bmatrix} \widehat{\mathbf{M}}^1 & \mathbf{0} \\ \mathbf{0} & \widehat{\mathbf{M}}^2 \end{bmatrix} \begin{bmatrix} \widehat{\mathbf{C}}^1 & \widehat{\mathbf{D}}^1 \\ \widehat{\mathbf{C}}^2 & \widehat{\mathbf{D}}^2 \end{bmatrix} \right) \otimes \mathbf{I}_p \right) \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{y}_k^1 - \mathbf{y}_*^1 \\ \mathbf{y}_k^2 - \mathbf{y}_*^2 \end{bmatrix}^\top \left(\begin{bmatrix} \widehat{\mathbf{M}}^1 & \mathbf{0} \\ \mathbf{0} & \widehat{\mathbf{M}}^2 \end{bmatrix} \otimes \mathbf{I}_p \right) \begin{bmatrix} \mathbf{y}_k^1 - \mathbf{y}_*^1 \\ \mathbf{y}_k^2 - \mathbf{y}_*^2 \end{bmatrix}. \end{aligned}$$

Substituting $\widehat{\mathbf{M}}^1$ and $\widehat{\mathbf{M}}^2$, it becomes

$$\begin{aligned} S(\boldsymbol{\xi}_k, \mathbf{v}_k) &= -\langle \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*, \mathbf{w}_{k+1} - \mathbf{w}_* \rangle - \langle \boldsymbol{\gamma}_{k+1} - \boldsymbol{\gamma}_*, \mathbf{s}_{k+1} - \mathbf{s}_* \rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*\|^2 \\ & \quad - \langle \boldsymbol{\eta}_{k+1}, \mathbf{w}_{k+1} - \mathbf{w}_* \rangle + \frac{\rho}{\widehat{L}} \langle \boldsymbol{\eta}_{k+1}, \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 - \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle. \end{aligned}$$

Applying (A40), we obtain

$$\begin{aligned} S(\boldsymbol{\xi}_k, \mathbf{v}_k) &\leq \widehat{f}_\rho(\mathbf{w}_*) - \widehat{f}_\rho(\mathbf{w}_{k+1}) + \widehat{g}_\rho(\mathbf{s}_*) - \widehat{g}_\rho(\mathbf{s}_{k+1}) - \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \mathbf{s}_{k+1} - \mathbf{s}_* \\ \mathbf{u}_{k+1} - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix} \\ & \quad - \langle \boldsymbol{\eta}_{k+1}, \mathbf{w}_{k+1} - \mathbf{w}_* \rangle + \frac{\rho}{\widehat{L}} \langle \boldsymbol{\eta}_{k+1}, \boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_* \rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 - \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle. \end{aligned}$$

Rearranging both sides, it becomes

$$\begin{aligned} S(\boldsymbol{\xi}_k, \mathbf{v}_k) &\leq \widehat{f}_\rho(\mathbf{w}_*) - \widehat{f}_\rho(\mathbf{w}_{k+1}) + \widehat{g}_\rho(\mathbf{s}_*) - \widehat{g}_\rho(\mathbf{s}_{k+1}) - \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \mathbf{s}_{k+1} - \mathbf{s}_* \\ \mathbf{u}_{k+1} - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix} \\ & \quad + \left\langle \boldsymbol{\eta}_{k+1}, \frac{\rho}{\widehat{L}} (\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) - (\mathbf{w}_{k+1} - \mathbf{w}_*) \right\rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 - \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle. \end{aligned}$$

This completes the proof. ■

B.2. Proof of Theorem 9

Proof By the fact that $\boldsymbol{\xi}_*$ is a fixed point of (14),

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - V_{\mathbf{P}}(\boldsymbol{\xi}_k) = (\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*)^\top \mathbf{P}(\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*) - (\boldsymbol{\xi}_k - \boldsymbol{\xi}_*)^\top \mathbf{P}(\boldsymbol{\xi}_k - \boldsymbol{\xi}_*)$$

$$= \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}^\top \left(\begin{bmatrix} \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} - \widehat{\mathbf{P}} & \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \\ \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} & \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \end{bmatrix} \otimes \mathbf{I}_p \right) \begin{bmatrix} \boldsymbol{\xi}_k - \boldsymbol{\xi}_* \\ \mathbf{v}_k - \mathbf{v}_* \end{bmatrix}.$$

Applying (27), it becomes

$$V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) - V_{\mathbf{P}}(\boldsymbol{\xi}_k) \leq S(\boldsymbol{\xi}_k, \mathbf{v}_k).$$

Substituting the upper bound of $S(\boldsymbol{\xi}_k, \mathbf{v}_k)$ from Lemma 8, we obtain

$$\begin{aligned} & \widehat{f}_\rho(\mathbf{w}_{k+1}) - \widehat{f}_\rho(\mathbf{w}_*) + \widehat{g}_\rho(\mathbf{s}_{k+1}) - \widehat{g}_\rho(\mathbf{s}_*) + \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \mathbf{s}_{k+1} - \mathbf{s}_* \\ \mathbf{u}_{k+1} - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix} + V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) \\ & \leq V_{\mathbf{P}}(\boldsymbol{\xi}_k) + \left\langle \boldsymbol{\eta}_{k+1}, \frac{\rho}{\widehat{L}}(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) - (\mathbf{w}_{k+1} - \mathbf{w}_*) \right\rangle + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 - \langle \mathbf{s}_{k+1} - \mathbf{s}_*, \boldsymbol{\zeta}_{k+1} \rangle \\ & \leq V_{\mathbf{P}}(\boldsymbol{\xi}_k) + \left\| \frac{\rho}{\widehat{L}}(\boldsymbol{\beta}_{k+1} - \boldsymbol{\beta}_*) - (\mathbf{w}_{k+1} - \mathbf{w}_*) \right\| \|\boldsymbol{\eta}_{k+1}\| + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 + \|\mathbf{s}_{k+1} - \mathbf{s}_*\| \|\boldsymbol{\zeta}_{k+1}\| \\ & \leq V_{\mathbf{P}}(\boldsymbol{\xi}_k) + \frac{\rho + \widehat{L}}{\widehat{L}} (\|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| + \|\boldsymbol{\eta}_{k+1}\|) \|\boldsymbol{\eta}_{k+1}\| + \frac{\rho}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 + \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \|\boldsymbol{\zeta}_{k+1}\| \\ & = V_{\mathbf{P}}(\boldsymbol{\xi}_k) + \frac{\rho + \widehat{L}}{\widehat{L}} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \|\boldsymbol{\eta}_{k+1}\| + \frac{3\rho + 2\widehat{L}}{2\widehat{L}} \|\boldsymbol{\eta}_{k+1}\|^2 + \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \|\boldsymbol{\zeta}_{k+1}\|, \end{aligned}$$

where the last inequality follows from Lemma A12. Substituting $\|\boldsymbol{\eta}_{k+1}\|^2 \leq 2\epsilon_{k+1}/\rho$ and $\|\boldsymbol{\zeta}_{k+1}\|^2 \leq 2\delta_{k+1}/\rho$,

$$\begin{aligned} & \widehat{f}_\rho(\mathbf{w}_{k+1}) - \widehat{f}_\rho(\mathbf{w}_*) + \widehat{g}_\rho(\mathbf{s}_{k+1}) - \widehat{g}_\rho(\mathbf{s}_*) + \begin{bmatrix} \mathbf{w}_{k+1} - \mathbf{w}_* \\ \mathbf{s}_{k+1} - \mathbf{s}_* \\ \mathbf{u}_{k+1} - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix} + V_{\mathbf{P}}(\boldsymbol{\xi}_{k+1}) \\ & \leq V_{\mathbf{P}}(\boldsymbol{\xi}_k) + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\epsilon_{k+1}} + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \epsilon_{k+1} + \sqrt{\frac{2}{\rho}} \|\boldsymbol{\xi}_{k+1} - \boldsymbol{\xi}_*\| \sqrt{\delta_{k+1}}. \end{aligned}$$

Summing up it from $k = 0$ to $k = T - 1$,

$$\begin{aligned} & \sum_{k=1}^T \left\{ \widehat{f}_\rho(\mathbf{w}_k) - \widehat{f}_\rho(\mathbf{w}_*) + \widehat{g}_\rho(\mathbf{s}_k) - \widehat{g}_\rho(\mathbf{s}_*) + \begin{bmatrix} \mathbf{w}_k - \mathbf{w}_* \\ \mathbf{s}_k - \mathbf{s}_* \\ \mathbf{u}_k - \mathbf{u}_* \end{bmatrix}^\top \begin{bmatrix} -\mathbf{u}_* \\ -\mathbf{u}_* \\ \mathbf{w}_* + \mathbf{s}_* - \mathbf{c} \end{bmatrix} \right\} + V_{\mathbf{P}}(\boldsymbol{\xi}_T) \\ & \leq V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k}. \end{aligned}$$

By the definitions of $\mathbf{w}, \mathbf{s}, \widehat{f}_\rho(\mathbf{w})$ and $\widehat{g}_\rho(\mathbf{s})$, it can be rewritten as

$$\frac{1}{\rho} \sum_{k=1}^T \left\{ f(\mathbf{x}_k) - f(\mathbf{x}_*) + g(\mathbf{z}_k) - g(\mathbf{z}_*) + \begin{bmatrix} \mathbf{x}_k - \mathbf{x}_* \\ \mathbf{z}_k - \mathbf{z}_* \\ \rho(\mathbf{u}_k - \mathbf{u}_*) \end{bmatrix}^\top \begin{bmatrix} -\rho\mathbf{A}^\top \mathbf{u}_* \\ -\rho\mathbf{B}^\top \mathbf{u}_* \\ \mathbf{A}\mathbf{x}_* + \mathbf{B}\mathbf{z}_* - \mathbf{c} \end{bmatrix} \right\} + V_{\mathbf{P}}(\boldsymbol{\xi}_T)$$

$$\leq V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k}. \quad (\text{A41})$$

Applying (23) to the right-hand side,

$$V_{\mathbf{P}}(\boldsymbol{\xi}_T) \leq V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k}.$$

By further relaxing the right-hand side,

$$\|\boldsymbol{\xi}_T - \boldsymbol{\xi}_0\|^2 \leq \frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \frac{1}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k}.$$

Applying Lemma A13 with

$$\beta_k \stackrel{\text{def}}{=} \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_0\|, \quad S_T \stackrel{\text{def}}{=} \frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \epsilon_k, \quad \widehat{\lambda}_k \stackrel{\text{def}}{=} \frac{\rho + \widehat{L}}{\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sqrt{\epsilon_k}, \quad \bar{\lambda}_k \stackrel{\text{def}}{=} \frac{1}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sqrt{\delta_k},$$

we obtain

$$\begin{aligned} & \frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \frac{1}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k} \\ & \leq \left(\sqrt{\frac{V_{\mathbf{P}}(\boldsymbol{\xi}_0)}{\sigma_{\mathbf{P}}^{\min}} + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sum_{k=1}^T \epsilon_k} + \frac{\rho + \widehat{L}}{\widehat{L}\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \sqrt{\epsilon_k} + \frac{1}{\sigma_{\mathbf{P}}^{\min}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

It is equivalent to

$$\begin{aligned} & V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k} \\ & \leq \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

By further relaxing right-hand side,

$$\begin{aligned} & V_{\mathbf{P}}(\boldsymbol{\xi}_0) + \frac{3\rho + 2\widehat{L}}{\rho\widehat{L}} \sum_{k=1}^T \epsilon_k + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_{k-1} - \boldsymbol{\xi}_*\| \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho}} \sum_{k=1}^T \|\boldsymbol{\xi}_k - \boldsymbol{\xi}_*\| \sqrt{\delta_k} \\ & \leq \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0)} + \left(\sqrt{\frac{3\rho + 2\widehat{L}}{\rho\widehat{L}}} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \right) \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

Substituting it into (A41), we obtain

$$\begin{aligned} & \frac{1}{\rho} \sum_{k=1}^T \left\{ f(\mathbf{x}_k) - f(\mathbf{x}_\star) + g(\mathbf{z}_k) - g(\mathbf{z}_\star) + \begin{bmatrix} \mathbf{x}_k - \mathbf{x}_\star \\ \mathbf{z}_k - \mathbf{z}_\star \\ \rho(\mathbf{u}_k - \mathbf{u}_\star) \end{bmatrix}^\top \begin{bmatrix} -\rho \mathbf{A}^\top \mathbf{u}_\star \\ -\rho \mathbf{B}^\top \mathbf{u}_\star \\ \mathbf{A}\mathbf{x}_\star + \mathbf{B}\mathbf{z}_\star - \mathbf{c} \end{bmatrix} \right\} + V_{\mathbf{P}}(\boldsymbol{\xi}_k) \\ & \leq \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0)} + \left(\sqrt{\frac{3\rho + 2\widehat{L}}{\rho\widehat{L}}} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \right) \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

Dividing both sides by T ,

$$\begin{aligned} & \frac{1}{T} \sum_{k=1}^T \left\{ f(\mathbf{x}_k) - f(\mathbf{x}_\star) + g(\mathbf{z}_k) - g(\mathbf{z}_\star) + \begin{bmatrix} \mathbf{x}_k - \mathbf{x}_\star \\ \mathbf{z}_k - \mathbf{z}_\star \\ \rho(\mathbf{u}_k - \mathbf{u}_\star) \end{bmatrix}^\top \begin{bmatrix} -\rho \mathbf{A}^\top \mathbf{u}_\star \\ -\rho \mathbf{B}^\top \mathbf{u}_\star \\ \mathbf{A}\mathbf{x}_\star + \mathbf{B}\mathbf{z}_\star - \mathbf{c} \end{bmatrix} \right\} + \frac{\rho}{T} V_{\mathbf{P}}(\boldsymbol{\xi}_k) \\ & \leq \frac{\rho}{T} \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0)} + \left(\sqrt{\frac{3\rho + 2\widehat{L}}{\rho\widehat{L}}} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \right) \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

Applying the convexity of $f(\mathbf{x})$ and $g(\mathbf{z})$,

$$\begin{aligned} & f(\bar{\mathbf{x}}_T) - f(\mathbf{x}_\star) + g(\bar{\mathbf{z}}_T) - g(\mathbf{z}_\star) + \begin{bmatrix} \bar{\mathbf{x}}_T - \mathbf{x}_\star \\ \bar{\mathbf{z}}_T - \mathbf{z}_\star \\ \rho(\bar{\mathbf{u}}_T - \mathbf{u}_\star) \end{bmatrix}^\top \begin{bmatrix} -\rho \mathbf{A}^\top \mathbf{u}_\star \\ -\rho \mathbf{B}^\top \mathbf{u}_\star \\ \mathbf{A}\mathbf{x}_\star + \mathbf{B}\mathbf{z}_\star - \mathbf{c} \end{bmatrix} + \frac{\rho}{T} V_{\mathbf{P}}(\boldsymbol{\xi}_T) \\ & \leq \frac{\rho}{T} \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0)} + \left(\sqrt{\frac{3\rho + 2\widehat{L}}{\rho\widehat{L}}} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \right) \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

Note that $V_{\mathbf{P}}(\boldsymbol{\xi}_T) \geq 0$, thus

$$\begin{aligned} & f(\bar{\mathbf{x}}_T) - f(\mathbf{x}_\star) + g(\bar{\mathbf{z}}_T) - g(\mathbf{z}_\star) + \begin{bmatrix} \bar{\mathbf{x}}_T - \mathbf{x}_\star \\ \bar{\mathbf{z}}_T - \mathbf{z}_\star \\ \rho(\bar{\mathbf{u}}_T - \mathbf{u}_\star) \end{bmatrix}^\top \begin{bmatrix} -\rho \mathbf{A}^\top \mathbf{u}_\star \\ -\rho \mathbf{B}^\top \mathbf{u}_\star \\ \mathbf{A}\mathbf{x}_\star + \mathbf{B}\mathbf{z}_\star - \mathbf{c} \end{bmatrix} \\ & \leq \frac{\rho}{T} \left(\sqrt{V_{\mathbf{P}}(\boldsymbol{\xi}_0)} + \left(\sqrt{\frac{3\rho + 2\widehat{L}}{\rho\widehat{L}}} + \frac{\rho + \widehat{L}}{\widehat{L}} \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \right) \sum_{k=1}^T \sqrt{\epsilon_k} + \sqrt{\frac{2}{\rho\sigma_{\mathbf{P}}^{\min}}} \sum_{k=1}^T \sqrt{\delta_k} \right)^2. \end{aligned}$$

This completes the proof. ■

B.3. Proof of Theorem 11

Proof Without loss of generality, we assume $\rho = 2\rho_0\widehat{L}$ and $\widehat{\mathbf{P}} = x\mathbf{I}_2$ where $\rho_0, x > 0$. Then, $\widehat{\mathbf{M}}^1$ becomes

$$\widehat{\mathbf{M}}^1 = \begin{bmatrix} 0 & -0.5 \\ -0.5 & \rho_0 \end{bmatrix}.$$

We define \mathbf{S} as

$$\mathbf{S} = \begin{bmatrix} \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} - \widehat{\mathbf{P}} & \widehat{\mathbf{A}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \\ \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{A}} & \widehat{\mathbf{B}}^\top \widehat{\mathbf{P}} \widehat{\mathbf{B}} \end{bmatrix} - \begin{bmatrix} \widehat{\mathbf{C}}^1 & \widehat{\mathbf{D}}^1 \\ \widehat{\mathbf{C}}^2 & \widehat{\mathbf{D}}^2 \end{bmatrix}^\top \begin{bmatrix} \widehat{\mathbf{M}}^1 & \mathbf{0} \\ \mathbf{0} & \widehat{\mathbf{M}}^2 \end{bmatrix}.$$

Next, we show that $\det(\mathbf{S}) \leq 0$. Substituting the values of all matrices into \mathbf{S} , we obtain

$$\mathbf{S} \stackrel{\text{def}}{=} \begin{bmatrix} 0 & x(1-\alpha) & x\alpha - 0.5 & x - 0.5 \\ x(1-\alpha) & x\alpha(\alpha - 2) & x\alpha(1-\alpha) + 0.5 & (\alpha - 1)(x - 0.5) \\ x\alpha - 0.5 & x\alpha(1-\alpha) + 0.5 & x\alpha^2 - (\rho_0 + 1) & -\alpha(x - 0.5) \\ x - 0.5 & (\alpha - 1)(x - 0.5) & -\alpha(x - 0.5) & 2x - 1 \end{bmatrix}.$$

Substituting $x = \frac{1}{2}$, \mathbf{S} becomes

$$\mathbf{S} = \begin{bmatrix} 0 & 0.5(1-\alpha) & 0.5(\alpha - 1) & 0 \\ 0.5(1-\alpha) & 0.5\alpha(\alpha - 2) & 0.5\alpha(1-\alpha) + 0.5 & 0 \\ 0.5(\alpha - 1) & 0.5\alpha(1-\alpha) + 0.5 & 0.5\alpha^2 - (\rho_0 + 1) & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

It is easy to see that $\det(\mathbf{S}) = 0$. Thus, $\widehat{\mathbf{P}} = 0.5\mathbf{I}_2$ satisfies the linear matrix inequality (27). This complete the proof. \blacksquare

Appendix C. More Details of Experiments

C.1. Problem Formulation and ADMM Updates

The distributed ℓ_1 -norm regularized logistic regression can be written as

$$\begin{aligned} \min_{\{\mathbf{x}^j, v^j\}_{j=1}^J, \mathbf{z}} \sum_{j=1}^J \sum_{i=1}^{n_j} \log\left(1 + \exp\left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j\right)\right)\right) + \lambda \|\mathbf{z}\|_1 \\ \text{s.t. } \mathbf{x}^j - \mathbf{z} = \mathbf{0}, \quad v^j = \eta, \quad \forall j = 1, \dots, J. \end{aligned} \quad (\text{A42})$$

The augmented Lagrangian of (A42) is formed as

$$\begin{aligned} L_\rho(\{\mathbf{x}^j, v^j\}_{j=1}^J, \mathbf{z}, \{\mathbf{u}^j, s^j\}_{j=1}^J) = \sum_{j=1}^J \sum_{i=1}^{n_j} \log\left(1 + \exp\left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j\right)\right)\right) + \lambda \|\mathbf{z}\|_1 \\ - \rho \sum_{j=1}^J \langle \mathbf{u}^j, \mathbf{x}^j - \mathbf{z} \rangle + \frac{\rho}{2} \sum_{j=1}^J \|\mathbf{x}^j - \mathbf{z}\|^2 - \rho \sum_{j=1}^J s^j (v^j - \eta) + \frac{\rho}{2} \sum_{j=1}^J (v^j - \eta)^2. \end{aligned}$$

Updates for (\mathbf{x}^j, v^j)

For $\forall j = 1, \dots, J$, \mathbf{x}_{k+1}^j and v_{k+1}^j can be obtained by solving

$$\min_{\mathbf{x}^j, v^j} \left\{ \sum_{i=1}^{n_j} \log\left(1 + \exp\left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j\right)\right)\right) + \frac{\rho}{2} \|\mathbf{x}^j - \mathbf{u}_k^j - \mathbf{z}_k\|^2 + \frac{\rho}{2} (v^j - s_k^j - \eta_k)^2 \right\}. \quad (\text{A43})$$

It does not have an analytical solution, thus we apply L-BFGS to solve it. We need to compute the duality gap when it be used as the criteria to terminate L-BFGS solver. Thus, we derive the dual problem. For convenience, define $\bar{\mathbf{x}}_k^j$ and \bar{v}_k^j as $\bar{\mathbf{x}}_k^j = \mathbf{u}_k^j + \mathbf{z}_k^j$ and $\bar{v}_k^j = s_k^j + \eta_k^j$. Then, (A43) can be written as

$$\min_{\mathbf{x}^j, v^j} \left\{ \sum_{i=1}^{n_j} \log \left(1 + \exp \left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j \right) \right) \right) + \frac{\rho}{2} \|\mathbf{x}^j - \bar{\mathbf{x}}_k^j\|^2 + \frac{\rho}{2} (v^j - \bar{v}_k^j)^2 \right\}. \quad (\text{A44})$$

The dual problem of (A44) is

$$\begin{aligned} \max_{\boldsymbol{\theta}^j} \left\{ - \sum_{i=1}^{n_j} \left\{ \theta_i^j \log \theta_i^j + (1 - \theta_i^j) \log(1 - \theta_i^j) \right\} - \frac{1}{2\rho} \|\bar{\mathbf{A}}^j \boldsymbol{\theta}^j\|^2 - \langle \bar{\mathbf{x}}_k^j, \bar{\mathbf{A}}^j \boldsymbol{\theta}^j \rangle - \frac{1}{2\rho} \langle \mathbf{b}^j, \boldsymbol{\theta}^j \rangle^2 \right. \\ \left. - \bar{v}_k^j \langle \mathbf{b}^j, \boldsymbol{\theta}^j \rangle \right\} \\ \text{s.t. } \theta_i^j \in (0, 1), \end{aligned} \quad (\text{A45})$$

where $\bar{\mathbf{A}}^j = [b_1^j \mathbf{a}_1^j, \dots, b_{n_j}^j \mathbf{a}_{n_j}^j]$ and $\mathbf{b}^j = [b_1^j, \dots, b_{n_j}^j]$. In addition, the KKT condition of (A44) establishes

$$(\theta_i^j)^* = \frac{\exp \left(-b_i^j \left(\langle \mathbf{a}_i^j, (\mathbf{x}^j)^* \rangle + (v^j)^* \right) \right)}{1 + \exp \left(-b_i^j \left(\langle \mathbf{a}_i^j, (\mathbf{x}^j)^* \rangle + (v^j)^* \right) \right)}. \quad (\text{A46})$$

Thus, given a primal solution \mathbf{x}^j, v^j , we can get a dual solution θ^j as

$$\theta_i^j = \frac{\exp \left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j \right) \right)}{1 + \exp \left(-b_i^j \left(\langle \mathbf{a}_i^j, \mathbf{x}^j \rangle + v^j \right) \right)}, \forall i = 1, \dots, n_j. \quad (\text{A47})$$

It is straightforward to show $\boldsymbol{\theta}^j$ is a feasible solution. Then, the dual gap $G(\mathbf{x}^j, \boldsymbol{\theta}^j)$ can be computed by applying (A43) and (A45).

Updates for (\mathbf{Z}, η)

Specifically, \mathbf{z} and η can be obtained by solving

$$\min_{\mathbf{z}, \eta} \left\{ \lambda \|\mathbf{z}\|_1 + \sum_{j=1}^J \frac{\rho}{2} \left\| \alpha \mathbf{x}_{k+1}^j + (1 - \alpha) \mathbf{z}_k - \mathbf{u}_k^j - \mathbf{z} \right\|^2 + \sum_{j=1}^J \frac{\rho}{2} \left(\alpha v_{k+1}^j + (1 - \alpha) \eta_k - s_k^j - \eta \right)^2 \right\}.$$

Thus, we obtain

$$\mathbf{z}_{k+1} = \mathcal{S}_{\frac{\lambda}{\rho J}} \left(\frac{1}{J} \sum_{j=1}^J \left(\alpha \mathbf{x}_{k+1}^j + (1 - \alpha) \mathbf{z}_k - \mathbf{u}_k^j \right) \right) \text{ and } \eta_{k+1} = \frac{1}{J} \sum_{j=1}^J \left(\alpha v_{k+1}^j + (1 - \alpha) \eta_k - s_k^j \right),$$

where $\mathcal{S}_{\frac{\lambda}{\rho J}}(\cdot)$ denotes the Soft Thresholding operator for ℓ_1 -norm.

Updates for (\mathbf{u}^j, s^j)

For $\forall j = 1, \dots, J$, \mathbf{u}^j and s^j can be updated as following

$$\mathbf{u}_{k+1}^j = \mathbf{u}_k^j - \left(\alpha \mathbf{x}_{k+1}^j + (1 - \alpha) \mathbf{z}_k - \mathbf{z}_{k+1} \right) \text{ and } s_{k+1}^j = s_k^j - \left(\alpha v_{k+1}^j + (1 - \alpha) \eta_k - \eta_{k+1} \right).$$

C.2. Experiment Setting

We define $n = \sum_{j=1}^J n_j$ as the total number of samples over all workers. We use n^+ and n^- to denote the total number of positive and negative samples, respectively, overall all workers. By collecting the data over all workers, (A42) is equivalent to

$$\min_{\mathbf{x}, v, \mathbf{z}} \sum_{i=1}^n \log(1 + \exp(-b_i(\langle \mathbf{a}_i, \mathbf{x} \rangle + v))) + \lambda \|\mathbf{z}\|_1 \quad \text{s.t.} \quad \mathbf{x} - \mathbf{z} = \mathbf{0}. \quad (\text{A48})$$

Koh et al. (2007) show that the dual problem of (A48) is

$$\max_{\boldsymbol{\beta}} - \sum_{i=1}^n \left\{ \beta_i \log \beta_i + (1 - \beta_i) \log(1 - \beta_i) \right\} \quad \text{s.t.} \quad \|\tilde{\mathbf{A}}\boldsymbol{\beta}\|_{\infty} \leq \lambda, \quad \langle \mathbf{b}, \boldsymbol{\beta} \rangle = 0, \quad (\text{A49})$$

where $\tilde{\mathbf{A}} = [b_1 \mathbf{a}_1, \dots, b_n \mathbf{a}_n]$. It is easy to see there exists a λ_{\max} such that (A48) and (A49) have an analytical solution for any $\lambda \geq \lambda_{\max}$. Specifically, for any $\lambda \geq \lambda_{\max}$, we have

$$\mathbf{w}_{\lambda}^* = \mathbf{0}, \quad c_{\lambda}^* = 0, \quad (\beta_{\lambda})_i^* = \begin{cases} \frac{n^-}{n} & \text{if } b_i = 1, \\ \frac{n^+}{n} & \text{if } b_i = -1 \end{cases} \quad \forall i = 1, \dots, n.$$

The value of λ_{\max} can be computed by $\lambda_{\max} = \|\tilde{\mathbf{A}}\boldsymbol{\beta}_{\lambda_{\max}}^*\|_{\infty}$. In our experiments, we set the value of λ as $\lambda = 0.05\lambda_{\max}$ for both datasets. Consequently, we obtain $\lambda = 5.751$ and $\lambda = 6.892$ for *MDS* and *RCV1*, respectively. For initialization, we set $\mathbf{w}_0^j = \mathbf{0}, v_0^j = 0, \mathbf{u}_0^j = \mathbf{0}, \forall j = 1, \dots, J$ and $\mathbf{z}_0 = \mathbf{0}$.