Probabilistic Residual User Clustering

Anonymous authors
Paper under double-blind review

Abstract

Modern recommender systems are typically based on deep learning (DL) models, where a dense encoder learns representations of users and items. As a result, these systems often suffer from the black-box nature and computational complexity of the underlying models, making it difficult to systematically interpret their outputs and enhance their recommendation capabilities. To address this problem, we propose Probabilistic Residual User Clustering (PRUC), a causal Bayesian recommendation model based on user clustering. Specifically, we address this problem by (1) dividing users into clusters in an unsupervised manner and identifying causal confounders that influence latent variables, (2) developing sub-models for each confounder given the observable variables, and (3) generating recommendations by aggregating the rating residuals under each confounder using do-calculus. Experiments demonstrate that our plug-and-play PRUC is compatible with various base DL recommender systems, significantly improving their performance while automatically discovering meaningful user clusters.

1 Introduction

Over the past decade, personalized recommendations have significantly improved user experiences in domains such as e-commerce and social media. The recommender systems driving these advancements often rely on sophisticated deep learning (DL) models (Chung et al., 2014; Vaswani et al., 2017; Wu et al., 2019) capable of handling vast amounts of data, enabling highly accurate predictions and personalized interactions. Despite their effectiveness, these models often function as black boxes, lacking transparency and interpretability. This limitation poses significant challenges, particularly when diagnosing and enhancing the performance of recommender systems in scenarios involving domain shifts, such as changes in users' countries. Cold-start scenarios, a critical problem in recommendation systems, exacerbate these issues due to the presence of heterogeneous features and the influence of diverse and spurious patterns. As a result, existing models exhibit notably low performance in such settings.

Existing work (Yuan et al., 2020; Wu et al., 2020; Bi et al., 2020; Li et al., 2019; Hansen et al., 2020; Liang et al., 2020; Zhu et al., 2020; Liu et al., 2020; Kweon et al., 2024) often addresses domain shift by establishing connections across different domains through shared users or items. However, in real-world applications, such overlap is often unavailable. For instance, when recommending distinct items to users from different countries, there is typically no overlap in either users or items. This scenario demands more sophisticated modeling to account for shared confounders. For example, consider position/exposure bias in recommender systems: if the system ranks the item (e.g., an ad) higher, users are biased to rate it higher or have a higher probability to click it. Another example is popularity bias; users have a higher probability to click popular or trending items. A system must correct for such biases; otherwise, its accuracy will decline significantly when previously popular items lose their popularity. Additionally, existing methods often fail to consider latent user clusters when cluster IDs are not available in the datasets, therefore failing to model (dis)similarities among users.

To address these problems, we propose a novel causal hierarchical Bayesian deep learning model, dubbed *Probabilistic Residual User Clustering (PRUC)*, as a *plug-and-play* framework to improve and potentially interpret any base recommender systems. Fig. 1 shows the simplified overview of our framework. **During the training stage**, given any base recommender (e.g., DLRM (Naumov et al., 2019), CDL (Wang et al.,

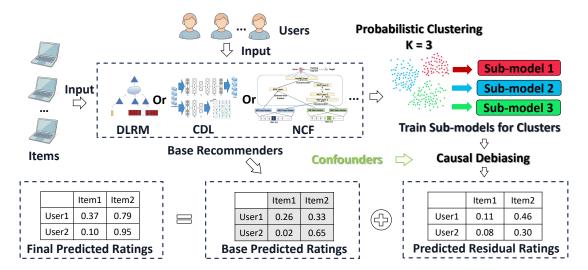


Figure 1: A detailed illustration of our proposed PRUC framework, highlighting the sequential stages and key components involved in its processing workflow. **Training:** Given any base recommender (e.g., DLRM (Naumov et al., 2019), CDL (Wang et al., 2015), or NCF (He et al., 2017)), PRUC is learned by jointly (1) computing its predicted ratings and the residual ratings (i.e., the difference between the ground-truth ratings and the base model's predicted ratings), (2) dividing users into latent clusters based on the residual ratings using our probabilistic clustering method, (3) training a sub-model for each latent user cluster. **Inference:** Once PRUC is learned, given a new user-item pair, PRUC can then (1) estimate the user's cluster ID to select the proper sub-model, (2) use this sub-model to perform causal inference to debias potential confounders and predict the residual rating, and (3) add this predicted residual rating to the base predicted rating to obtain the final predicted rating, thereby producing the final recommendation.

2015), or NCF (He et al., 2017)), PRUC is learned by jointly (1) computing its predicted ratings and the residual ratings (i.e., the difference between the ground-truth ratings and the base model's predicted ratings), (2) dividing users into latent clusters based on the residual ratings using our probabilistic clustering method, (3) training a sub-model for each latent user cluster. **During the inference stage**, once PRUC is learned, given a new user-item pair, PRUC can then (1) estimate the user's cluster ID to select the proper sub-model, (2) use this sub-model to perform causal inference to debias potential confounders and predict the residual rating, and (3) add this predicted residual rating to the base predicted rating to obtain the final predicted rating, thereby producing the final recommendation. Notably, PRUC is *plug-and-play*, i.e., it is compatible with any base DL recommendation model and can enhance the original model's performance.

Our contributions are as follows:

- We identify the existence of user clusters in various datasets, as well as latent confounders that have a causal effect on user and item hidden representations in DL models.
- We propose a causal Bayesian framework to discover the latent structures of users, items, and ratings. We incorporate user clusters and causal confounders as latent variables in the causal structural model (SCM) and perform inference via do-calculus over the confounders.
- We formulate the rating prediction problem as residual prediction, i.e., predicting the difference between the ground-truth user ratings and the base DL model's predicted ratings, to enhance the performance of base DL recommenders.
- Experiments verify that our *plug-and-play* PRUC is compatible with various base DL recommender systems, significantly improving their performance while automatically discovering meaningful user clusters.

2 Probabilistic Residual User Clustering

In this section, we describe our proposed PRUC framework.

2.1 Problem Setting and Notations

Consider a recommendation dataset containing I users and J items. A DL encoder $f_v(\cdot): \mathbb{R}^d \to \mathbb{R}^h$ encodes each item j's raw features $\mathbf{x}_j^v \in \mathbb{R}^d$ into $f_v(\mathbf{x}_j^v)$; assume there exists another decoder deep learning model $f_x(\cdot): \mathbb{R}^h \to \mathbb{R}^d$, which decodes latent representation \mathbf{v}_j back to the raw item features \mathbf{x}_j^v . For a given user i and an item j, there is a ground-truth rating $R_{ij} \in \mathbb{R}$, a base predicted rating $\widehat{R}_{ij} \in \mathbb{R}$ provided by a base recommender, and a residual rating $\widehat{R}_{ij} = R_{ij} - \widehat{R}_{ij}$. There is a latent cluster ID k ($k \in \{1, ..., K\}$) that indicates which user group user i belongs to. We assume that there exists a user latent vector $\mathbf{u}_i \in \mathbb{R}^h$ for each user i and an item latent vector $\mathbf{v}_j \in \mathbb{R}^h$ for each item j; they are both impacted by a causal confounder $\mathbf{s} \in \mathbb{R}^g$, where $g \ll h$.

Our goal is to predict the final rating R using the residual R, i.e., $R = \hat{R} + \tilde{R}$, where \hat{R} represents the rating from the original (base) DL recommender. When the original recommender is provided, \hat{R} is fixed; therefore we only need to learn \hat{R} in order to predict the final rating R. For generality, we assume M domains, where m_i and m_j denote the domain ID of user i and item j, respectively.

2.2 Method Overview

We use a variational Bayesian framework to learn the latent parameters. Fig. 2 illustrates the corresponding probabilistic graphical model (PGM).

Generative Process. Below we describe the generative process of PRUC shown in Fig. 2.

For each domain $m \in \{1, 2, ..., M\}$:

• Draw the confounder \mathbf{s}_m from a prior distribution, for example, $p(\mathbf{s}) \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$:

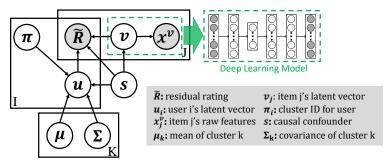


Figure 2: Probabilistic graphical model of our PRUC framework.

- For each user i:
 - Draw the user cluster ID π_i from categorical distribution π .
 - Draw user latent variable \mathbf{u}_i from the π_i 'th Gaussian distribution, i.e., $p(\mathbf{u}_i | \{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K, \mathbf{s}, \pi) \sim \mathcal{N}(\boldsymbol{\mu}_{\pi_i} + \mathbf{W}_u \mathbf{s}_m, \boldsymbol{\Sigma}_{\pi_i})$. Notice that \mathbf{W}_u is the learnable global parameter shared by all users.
 - For each item j:
 - * Draw item latent variable v_j from distribution $p(\mathbf{v}_j|\mathbf{s}) \sim \mathcal{N}(\mathbf{W}_v\mathbf{s}_m, \lambda_v^{-1}\mathbf{I})$, where \mathbf{W}_v is the learnable global parameter shared by all items, \mathbf{I} is the identity matrix, and $\lambda_v \in \mathbb{R}$ is the precision.
 - * Draw the residual rating \widetilde{R}_{ij} from distribution $p(\widetilde{R}_{ij}|\mathbf{u}_i,\mathbf{v}_j,\mathbf{s}) \sim \mathcal{N}(\mathbf{u}_i^{\top}\mathbf{v}_j + \mathbf{w}_R^{\top}\mathbf{s}_m, \lambda_{\widetilde{R}_{ij}}^{-1})$, where \mathbf{w}_R is the learnable vector shared by all ratings and $\lambda_{\widetilde{R}_{ij}}$ is the precision.
 - * Draw raw item features \mathbf{x}_j^v from distribution $p(\mathbf{x}_j^v|\mathbf{v}_j) \sim \mathcal{N}(f_x(\mathbf{v}_j), \lambda_x^{-1}\mathbf{I})$, where \mathbf{I} is the identity matrix and $\lambda_x \in \mathbb{R}$ is the precision. f_x is a parameterized function that could be learned.

Model Factorization. As shown in Fig. 2, we factorize the generative model into four conditional distributions:

$$p(\mathbf{u}_{i}, \mathbf{v}_{j}, \mathbf{x}_{j}^{v}, \widetilde{R}_{ij} | \{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\}_{k=1}^{K}, \mathbf{s}_{m}, \boldsymbol{\pi})$$

$$= p(\widetilde{R}_{ij} | \mathbf{u}_{i}, \mathbf{v}_{j}, \mathbf{s}_{m}) p(\mathbf{u}_{i} | \{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\}_{k=1}^{K}, \mathbf{s}_{m}, \boldsymbol{\pi}) p(\mathbf{x}_{i}^{v} | \mathbf{v}_{j}) p(\mathbf{v}_{j} | \mathbf{s}_{m}). \tag{1}$$

Each distribution is assumed as a Gaussian distribution and is shown as follows:

$$p(\widetilde{R}_{ij}|\mathbf{u}_i, \mathbf{v}_j, \mathbf{s}_m) = \mathcal{N}(\mathbf{u}_i^{\top} \mathbf{v}_j + \mathbf{w}_R^{\top} \mathbf{s}_m, \lambda_{\widetilde{R}_{ij}}^{-1}),$$
(2)

$$p(\mathbf{u}_i|\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K, \mathbf{s}_m, \boldsymbol{\pi}) = \mathcal{N}(\boldsymbol{\mu}_{\pi_i} + \mathbf{W}_u \mathbf{s}_m, \boldsymbol{\Sigma}_{\pi_i}),$$
(3)

$$p(\mathbf{x}_{j}^{v}|\mathbf{v}_{j}) = \mathcal{N}(f_{x}(\mathbf{v}_{j}), \lambda_{x}^{-1}\mathbf{I}), \tag{4}$$

$$p(\mathbf{v}_{i}|\mathbf{s}_{m}) = \mathcal{N}(\mathbf{W}_{v}\mathbf{s}_{m}, \lambda_{v}^{-1}\mathbf{I}), \tag{5}$$

where i and j refers to the user index and the item index, respectively. We employ an inference distribution $q(\mathbf{u}_i, \mathbf{v}_j | \mathbf{x}_j^v)$ to approximate the distribution $p(\mathbf{u}_i, \mathbf{v}_j | \mathbf{x}_j^v)$ for the inference model.

$$q(\mathbf{u}_i, \mathbf{v}_j | \mathbf{x}_i^v) = q(\mathbf{u}_i)q(\mathbf{v}_j | \mathbf{x}_i^v). \tag{6}$$

More specifically, we assumes $q(\mathbf{v}_j|\mathbf{x}_i^v)$ follows a gaussian distribution:

$$q(\mathbf{v}_j|\mathbf{x}_j^v) = \mathcal{N}(f_v(\mathbf{x}_j^v), \Lambda_v^{-1}\mathbf{I}). \tag{7}$$

Here, j is the item index, $\Lambda_v \in \mathbb{R}$ refers to the precision, and f_v is a learnable mapping function.

Learning Objective. We maximize an evidence lower bound (ELBO) as our learning objective for both generative and inference model.

$$\mathcal{L}_{ELBO}(\mathbf{x}_{j}^{v}, \widetilde{R}_{ij})$$

$$= \mathbb{E}_{q(\mathbf{u}_{i}, \mathbf{v}_{j} | \mathbf{x}_{j}^{v})} \left[\log p(\mathbf{u}_{i}, \mathbf{v}_{j}, \mathbf{x}_{j}^{v}, \widetilde{R}_{ij} | \{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\}_{k=1}^{K}, \mathbf{s}_{m}, \boldsymbol{\pi}) \right]$$

$$- \mathbb{E}_{q(\mathbf{u}_{i}, \mathbf{v}_{j} | \mathbf{x}_{j}^{v})} \left[\log q(\mathbf{v}_{j} | \mathbf{x}_{j}^{v}) \right]. \tag{8}$$

Combining Eqn. 1 and Eqn. 6, we obtain the following decomposition:

$$\mathcal{L}_{ELBO}(\mathbf{x}_{j}^{v}, \widetilde{R}_{ij})$$

$$= \mathbb{E}_{q(\mathbf{u}_{i})} \left[\log p(\mathbf{u}_{i} | \{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\}_{k=1}^{K}, \mathbf{s}_{m}, \pi) \right]$$
(9)

$$+ \mathbb{E}_{q(\mathbf{v}_j|\mathbf{x}_j^v)} \left[\log p(\mathbf{x}_j^v|\mathbf{v}_j) \right]$$
 (10)

$$+ \mathbb{E}_{q(\mathbf{u}_{i}, \mathbf{v}_{j} | \mathbf{x}_{j}^{v})} \left[\log p(\widetilde{R}_{ij} | \mathbf{u}_{i}, \mathbf{v}_{j}, \mathbf{s}_{m}) \right]$$

$$(11)$$

$$-D_{KL}(q(\mathbf{v}_j|\mathbf{x}_j^v)||p(\mathbf{v}_j|\mathbf{s}_m)), \tag{12}$$

where $D_{KL}(\cdot||\cdot)$ is the Kullback-Leibler (KL) divergence. For Eqn. 9, we compute the log likelihood for each cluster k as

$$\log p(\mathbf{u}_i|\{\boldsymbol{\mu}_k,\boldsymbol{\Sigma}_k\},\mathbf{s}_m,\pi) = -\frac{1}{2}\sum_{i\in L}[\log |\boldsymbol{\Sigma}_k| + (\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u\mathbf{s}_m)^{\top}\boldsymbol{\Sigma}_k^{-1}(\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u\mathbf{s}_m)] + C,$$

where i is the user index, I_k is the set of user index that belongs to cluster k, and C is a constant.

Similarly, all the other terms can be expanded as:

$$\log p(\mathbf{x}_j^v|\mathbf{v}_j) = -\frac{\lambda_x}{2} \|\mathbf{x}_j^v - f_x(\mathbf{v}_j)\|^2 + C,$$
(13)

$$\log p(\widetilde{R}_{ij}|\mathbf{u}_i, \mathbf{v}_j, \mathbf{s}) = -\frac{\lambda_{\widetilde{R}_{ij}}}{2} \left(\widetilde{R}_{ij} - \mathbf{u}_i^{\top} \mathbf{v}_j - \mathbf{w}_R^{\top} \mathbf{s}_m \right)^2 + C, \tag{14}$$

$$D_{KL}(q(\mathbf{v}_j|\mathbf{x}_j^v)||p(\mathbf{v}_j|\mathbf{s}_m)) = \frac{\lambda_v}{2}||\mathbf{v}_j - \mathbf{W}_v\mathbf{s}_m||^2$$

$$-\frac{\Lambda_v}{2} \|\mathbf{v}_j - f_v(\mathbf{x}_j^v)\|^2 + C. \tag{15}$$

Intuition for Each Term in Eqn. 8. Below, we describe the intuition of each term in Eqn. 8:

- 1. Regularize Latent Variable \mathbf{u}_i (Eqn. 9). $\mathbb{E}_{q(\mathbf{u}_i)}[p(\mathbf{u}_i|\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K, \mathbf{s}_m, \pi)]$ aims to regularize user i's latent variable \mathbf{u}_i , ensuring \mathbf{u}_i is close to the center of its corresponding user cluster π_i , and therefore close to other users' latent embeddings in the same cluster.
- 2. Reconstruct Data \mathbf{x}_j^v from \mathbf{v}_j (Eqn. 10). $q(\mathbf{v}_j|\mathbf{x}_j^v)$ and $p(\mathbf{x}_j^v|\mathbf{v}_j)$ are to reconstruct data \mathbf{x}_j^v from the inferred \mathbf{v}_j , which encourage the latent variable \mathbf{v}_j to maintain as much relevant information as possible from the raw features \mathbf{x}_j^v .
- 3. Predict Residual Rating \widetilde{R}_{ij} from \mathbf{u}_i and \mathbf{v}_j (Eqn. 11). $p(\widetilde{R}_{ij}|\mathbf{u}_i,\mathbf{v}_j,\mathbf{s}_m)$ use the inferred \mathbf{u}_i , \mathbf{v}_j , and the causal confounder \mathbf{s}_m to predict the residual rating, thereby encouraging \mathbf{u}_i and \mathbf{v}_j to retain more information to maximize prediction performance.
- 4. Regularize Latent Variable \mathbf{v}_j (Eqn. 12). $D_{KL}(q(\mathbf{v}_j|\mathbf{x}_j^v)||p(\mathbf{v}_j|\mathbf{s}_m))$ is the KL divergence term between the inference model $q(\cdot|\mathbf{x}_j^v)$ and the generative model $p(\cdot|\mathbf{s}_m)$; this encourages the inferred posterior $q(\mathbf{v}_j|\mathbf{x}_j^v)$ to be close to the prior distribution $p(\mathbf{v}_j|\mathbf{s}_m)$.

2.3 Inference and Learning

In our framework, we need to learn several parameters, including the Gaussian parameters $\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$, user latent \mathbf{u} , item latent \mathbf{v} , and the parameters of the functions $f_x(\cdot)$ and $f_v(\cdot)$, as well as \mathbf{W}_u , \mathbf{W}_v , and \mathbf{w}_R . The following sections detail the learning process for all these parameters. The complete algorithm is outlined in Algorithm 1.

1) $\{\mu_k, \Sigma_k\}_{k=1}^K$. To optimize $\{\mu_k, \Sigma_k\}_{k=1}^K$, we take derivative of Eqn. 13 w.r.t. μ_k and Σ_k as follows:

$$\frac{\partial \mathcal{L}}{\partial \boldsymbol{\mu}_k} = \boldsymbol{\Sigma}_k^{-1} \left(\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u \mathbf{s}_m \right), \tag{16}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{\Sigma}_k} = \frac{1}{2} \mathbf{\Sigma}_k^{-1} \left[\left(\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u \mathbf{s}_m \right) \left(\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u \mathbf{s}_m \right)^\top - \mathbf{\Sigma}_k \right] \mathbf{\Sigma}_k^{-1}. \tag{17}$$

Setting Eqn. 16 and Eqn. 17 to zero leads to the following update rules, respectively:

$$\mu_k = \frac{1}{|I_k|} \sum_{i \in I_k} \left(\mathbf{u}_i - \mathbf{W}_u \mathbf{s}_m \right), \tag{18}$$

$$\Sigma_k = \frac{1}{|I_k|} \sum_{i \in I_k} (\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u \mathbf{s}_m) (\mathbf{u}_i - \boldsymbol{\mu}_k - \mathbf{W}_u \mathbf{s}_m)^{\mathsf{T}},$$
(19)

where I_k is the set of user index i that belongs to cluster k.

2) $\mathbf{u}_i, \mathbf{v}_j$. After computing the gradients of Eqn. 8 w.r.t. to \mathbf{u}_i and \mathbf{v}_j , we obtain the following update rules:

$$\mathbf{u}_{i} = (\mathbf{\Sigma}_{\pi_{i}} \mathbf{V} \lambda_{\widetilde{R}_{(i,:)}} \mathbf{V}^{\top} + \mathbf{I})^{-1} \left[\boldsymbol{\mu}_{\pi_{i}} + \mathbf{W}_{u} \mathbf{s}_{m} + \mathbf{\Sigma}_{\pi_{i}} \mathbf{V} \lambda_{\widetilde{R}_{(i,:)}} (\widetilde{\mathbf{R}}_{(i,:)} - \mathbf{w}_{R}^{\top} \mathbf{s}_{m} \mathbf{I}) \right], \tag{20}$$

$$\mathbf{v}_{j} = \left[\mathbf{U} \lambda_{\widetilde{R}_{(:,j)}} \mathbf{U}^{\top} + (\lambda_{v} - \Lambda_{v}) \mathbf{I} \right]^{-1} \left[\lambda_{v} \mathbf{W}_{v} \mathbf{s}_{m} - \Lambda_{v} f_{v}(\mathbf{x}_{j}^{v}) + \mathbf{U} \lambda_{\widetilde{R}_{(:,j)}} (\widetilde{\mathbf{R}}_{(:,j)} - \mathbf{w}_{R}^{\top} \mathbf{s}_{m} \mathbf{I}) \right].$$
(21)

Note that here \mathbf{U} and \mathbf{V} refer to user latent matrix $(\mathbf{u}_i)_{i=1}^I$ and item latent matrix $(\mathbf{v}_j)_{j=1}^J$. $\widetilde{\mathbf{R}}_{(i,:)} := (\widetilde{R}_{1j}, \cdots, \widetilde{R}_{Ij})^{\top}$. $\lambda_{\widetilde{R}_{(i,:)}} := \operatorname{diag}(\lambda_{\widetilde{R}_{i1}}, \cdots, \lambda_{\widetilde{R}_{iJ}})$, $\lambda_{\widetilde{R}_{(:,j)}} := \operatorname{diag}(\lambda_{\widetilde{R}_{1j}}, \cdots, \lambda_{\widetilde{R}_{Ij}})$.

Algorithm 1 Learning Algorithm of PRUC

Input: Raw item features \mathbf{x}^v , initialized $f_x(\cdot)$ and $f_v(\cdot)$ parameters, $\mathbf{W}_u, \mathbf{W}_v, \mathbf{w}_R$, initialized Gaussian parameters $\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$, and the number of epochs T.

for t = 1 : T do

for $m = 1 : M \operatorname{do}$

Update \mathbf{u}_i and \mathbf{v}_i using Eqn. 20 and Eqn. 21.

Update $\mathbf{W}_u, \mathbf{W}_v, \mathbf{w}_R$ using Eqn. 22, Eqn. 23 and Eqn. 24.

Update the parameters of $f_v(\cdot)$ using gradient ascent of \mathcal{L} in Eqn. 8.

Update $\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$ using Eqn. 18 and Eqn. 19, respectively; update parameters of $f_x(\cdot)$ using gradient ascent of \mathcal{L} in Eqn. 8.

Output: $f_x(\cdot)$ and $f_v(\cdot)$ parameters, $\mathbf{W}_u, \mathbf{W}_v, \mathbf{w}_R$, and Gaussian parameters $\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$.

3) \mathbf{W}_u , \mathbf{W}_v , \mathbf{w}_R . The update rules for \mathbf{W}_u , \mathbf{W}_v , and \mathbf{w}_R are as follows:

$$\mathbf{W}_{u} = \frac{1}{I} \left(\sum_{i=1}^{I} \mathbf{u}_{i} - \sum_{k=1}^{K} |I_{k}| \boldsymbol{\mu}_{k} \right) \mathbf{s}_{m}^{\mathsf{T}} (\mathbf{s}_{m} \mathbf{s}_{m}^{\mathsf{T}})^{-1},$$
(22)

$$\mathbf{W}_v = \frac{1}{J} \sum_{j=1}^{J} \mathbf{v}_j \mathbf{s}_m^{\mathsf{T}} (\mathbf{s}_m \mathbf{s}_m^{\mathsf{T}})^{-1}, \tag{23}$$

$$\mathbf{w}_{R} = \frac{\sum_{i,j} \lambda_{\widetilde{R}_{ij}} (\widetilde{R}_{ij} - \mathbf{u}_{i}^{\top} \mathbf{v}_{j})}{\sum_{i,j} \lambda_{\widetilde{R}_{ij}}} (\mathbf{s}_{m} \mathbf{s}_{m}^{\top})^{-1} \mathbf{s}_{m}.$$
(24)

4) Parameters of $f_x(\cdot)$ and $f_v(\cdot)$. We use gradient ascent of \mathcal{L} in Eqn. 8 to update these parameters.

Inference. Inference includes the *E-Step* in Algorithm 1, where PRUC updates learnable parameters $\mathbf{W}_u, \mathbf{W}_v, \mathbf{w}_R$, and the parameters of encoder model $f_v(\cdot)$ using gradient ascent of \mathcal{L} in Eqn. 8.

Learning. Learning includes the iteration between the *E-Step* and *M-Step* in Algorithm 1 until convergence. In each *M-Step*, we update the Gaussian parameters $\{\mu_k, \Sigma_k\}_{k=1}^K$ following the update rule from Eqn. 18 and Eqn. 19, respectively; we also update parameters of decoder model $f_x(\cdot)$ using gradient ascent of \mathcal{L} in Eqn. 8.

2.4 Plug-and-Play PRUC

Below we discuss key components of our plug-and-play PRUC after learning all parameters with Algorithm 1.

Inferring User Cluster π_i . With the learned Gaussian mixture's parameters, i.e., the mean and covariance μ_k and Σ_k for each Gaussian component k (each Gaussian component represents one user cluster) from Algorithm 1, PRUC infers the cluster for each user i, i.e., $p(\pi_i | \tilde{R}_{ij}, \{\mathbf{u}_i\}, \{\mathbf{v}_j\}, \{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K)$, determining which cluster π_i user i belongs to.

Isolating Causal Confounders \mathbf{s}_m . With the structured causal model (SCM), we isolate the *causal* confounders \mathbf{s}_m for each domain m by approximating its posterior distribution $p(\mathbf{s}_m | \widetilde{R}, \mathbf{x}_j^v, \{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K)$ via variational domain indexing (VDI) (Xu et al., 2023). In this way, we can minimize the bias introduced by the causal confounder \mathbf{s}_m when inferring \mathbf{u}_i and \mathbf{v}_j using Eqn. 20 and Eqn. 21, respectively.

Debiasing the Causal Confounders. Under our PRUC framework, for each inferred user cluster k, we perform causal inference for each user i in this cluster to predict the residual \widetilde{R}_{ij} (for each item j) while debiasing the causal confounders \mathbf{s} . Specifically, with the inferred \mathbf{u}_i and \mathbf{v}_j (using Eqn. 20 and Eqn. 21) and \mathbf{s}_m , we can predict \widetilde{R}_{ij} by do-calculus as

$$p^{(k)}(\widetilde{R}_{ij}|do(\mathbf{u}_i), do(\mathbf{v}_j)) = \sum_{m=1}^{M} p^{(k)}(\widetilde{R}_{ij}|\mathbf{u}_i, \mathbf{v}_j, \mathbf{s}_m) p(\mathbf{s}_m),$$
(25)

where $p^{(k)}(\widetilde{R}_{ij}|\mathbf{u}_i,\mathbf{v}_j,\mathbf{s})$ represents the k'th sub-model trained from the k'th cluster's user data. In practice, we use $k = \pi_i$ (π_i is user i's cluster) when predicting user i's rating \widetilde{R}_{ij} .

Note that performing causal inference by intervening $(\mathbf{u}_i, \mathbf{v}_j)$ effectively cuts the relations between the causal confounders \mathbf{s} and $(\mathbf{u}_i, \mathbf{v}_j)$. Fig. 3 demonstrate the do-calculus that PRUC performs for debiasing the causal confounder \mathbf{s} .

Intuition behind Do-Calculus. The rationale of performing do-calculus in PRUC is that getting interventional distributions often requires intervening the recommender system to collect training data, which is expensive in practice. In contrast, do-calculus works by leveraging existing data to estimate the conditional distribution $p^{(k)}(\hat{R}_{ij}|\mathbf{u}_i,\mathbf{v}_j,\mathbf{s})$, and therefore prevent the potential cost (and risk) of actually intervening the system.

Summary. To summarize, for each user i, PRUC causally infer the residual rating \widetilde{R}_i as follows:

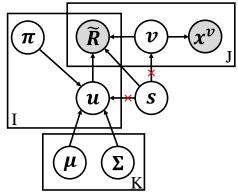


Figure 3: Causal inference in PRUC is equivalent to cutting the the confounder \mathbf{s} 's influence on \mathbf{u}_i and \mathbf{v} .

- 1. Infer the user cluster π_i by approximating its posterior $p(\pi_i|\mathbf{u}_i,\mathbf{v}_j,\mathbf{x}_i^v,\{\boldsymbol{\mu}_k,\boldsymbol{\Sigma}_k\}_{k=1}^K)$.
- 2. Infer the residual rating \widetilde{R}_{ij} by causal Bayesian model averaging defined in Eqn. 25.
- 3. Predict the final rating as $R = \tilde{R} + \hat{R}$, where \hat{R} is the base recommender's prediction.

3 Experiments

In this section, we evaluate our PRUC as a plug-and-play framework to enhance arbitrary base recommenders on XMRec and MovieLens.

3.1 Datasets

XMRec. XMRec (Bonab et al., 2021) is a dataset encompassing 18 local markets (i.e., countries), 16 distinct product categories, and 52.5 million user-item interactions. For each item j, we use its item descriptions from the dataset as the item features \mathbf{x}_j^v . Users with fewer than three purchases are excluded from experiments. We use three training-testing domain splits: France, Italy, India \rightarrow Japan, Mexico; Mexico, Spain, India \rightarrow Japan, Germany; and Germany, Italy, Japan \rightarrow United States, India. We use the production country of the products as the casual confounders \mathbf{s}_m .

MovieLens. MovieLens (Harper & Konstan, 2015) features movie ratings from users of varying ages. We use movie titles and movie plots as the item features \mathbf{x}_j^v . User features are derived from the first three films each user rated. Users who rated fewer than five movies or whose ratings do not exceed 3 are omitted. Post-filtering, our experiments involve 6,034 users and 3,705 items. We use two training-testing domain splits based on user ages: 1-18, 18-25, 35-45, 45-50, 50-56, $56^+ \rightarrow 25$ -35; and 25-35 \rightarrow all the previous mentioned age groups. For brevity, we refer to each age group by the starting age, e.g., "1" for "1-18". We use the normalized movie released years as causal confounders \mathbf{s}_m .

In all experiments, we use a cold-start setting where each testing domain user has only one rating in the training set, making the recommendations extremely challenging.

3.2 Base Recommenders and Baselines

Note that our PRUC method is a *plug-and-play* solution, compatible with *any* base recommenders. In this paper, we select the following five base recommenders to demonstrate PRUC's enhancement of state-of-the-art recommendation models.

Data	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	CDL (Base Model)	0.0143	0.0016	0.0028	0.0009	0.0009
	PRUC (Full)	0.1091	0.0128	0.0463	0.0108	0.0068
	DLRM (Base Model)	0.0044	0.0004	0.0004	0.0002	0.0002
	PRUC (Full)	0.0295	0.0035	0.0048	0.0018	0.0018
France, Italy, India \rightarrow Japan, Mexico	PerK (Base Model)	0.1098	0.0128	0.0512	0.0112	0.0068
	PRUC (Full)	0.1635	0.0192	0.0637	0.0151	0.0102
	NCF (Base Model)	0.0131	0.0148	0.0026	0.0008	0.0008
	PRUC (Full)	0.1137	0.0137	0.0309	0.0090	0.0073
	LightGCN (Base Model)	0.0182	0.0021	0.0050	0.0014	0.0011
	PRUC (Full)	0.1003	0.0121	0.0316	0.0084	0.0064
	CDL (Base Model)	0.1127	0.0135	0.0301	0.0086	0.0072
	PRUC (Full)	0.1761	0.0230	0.0593	0.0163	0.0123
	DLRM (Base Model)	0.0756	0.0093	0.0085	0.0041	0.0049
	PRUC (Full)	0.2017	0.0246	0.0545	0.0156	0.0131
Mexico, Spain, India \rightarrow Japan, Germany	PerK (Base Model)	0.1443	0.0177	0.0601	0.0143	0.0094
	PRUC (Full)	0.2750	0.0335	0.1086	0.0263	0.0179
	NCF (Base Model)	0.0096	0.0012	0.0022	0.0007	0.0007
	PRUC (Full)	0.1558	0.0202	0.0280	0.0107	0.0108
	LightGCN (Base Model) PRUC (Full)	0.0165 0.1064	0.0022 0.0138	0.0061 0.0278	0.0016 0.0087	0.0012 0.0077
	CDL (Base Model)	0.0252	0.0055	0.0084	0.0040	0.0031
	PRUC (Full)	0.0257	0.0058	0.0078	0.0041	0.0033
	DLRM (Base Model)	0.0024	0.0006	0.0003	0.0003	0.0003
	PRUC (Full)	0.0066	0.0016	0.0024	0.0012	0.0009
Germany, Italy, Japan \rightarrow United States, India	PerK (Base Model)	0.0148	0.0033	0.0041	0.0022	0.0018
	PRUC (Full)	0.0207	0.0046	0.0060	0.0031	0.0026
	NCF (Base Model)	0.0018	0.0005	0.0004	0.0003	0.0003
	PRUC (Full)	0.0126	0.0033	0.0021	0.0018	0.0019
	LightGCN (Base Model) PRUC (Full)	0.0016 0.0052	0.0004 0.0013	0.0002 0.0013	0.0002 0.0008	0.0003 0.0007

Table 1: Performance of PRUC with different base models on XMRec. The best results are marked with **bold face**.

- CDL (Wang et al., 2015) is a Bayesian deep framework that jointly integrates deep representation learning of content information with collaborative filtering on the ratings (feedback) matrix within a unified model.
- **DLRM** (Naumov et al., 2019) learns embeddings to represent both sparse and dense features by a neural network and predicts event probability.
- **PerK** (Kweon et al., 2024) uses calibrated interaction probabilities to determine the expected user utility and selects the optimal recommendation size K to maximize it.
- NCF (He et al., 2017) proposes a generalized matrix factorization framework by replacing the inner product with a trainable neural network.
- **LightGCN** (He et al., 2020) simplifies the design of Graph Convolutional Networks (GCNs) for recommendation tasks, making it easier to train and enhancing overall performance compared with traditional GCNs.

Here CDL, DLRM, PerK, NCF and LightGCN serve as both (1) our **baselines** to compare against and (2) our **base recommenders** to enhance (see Fig. 2). For more details on training configurations, see Appendex B.2.

3.3 Metrics

We use five metrics for evaluation: Recall, Precision, mAP, F1, and NDCG.

Recall. Recall@N measures the proportion of relevant items retrieved among the top N recommended items for user i:

$$\operatorname{Recall}_{i}@N = \sum_{n=1}^{N} \operatorname{rel}_{i,n}/|J_{i}|, \tag{26}$$

Table 2: Performance of PRUC with	h different base models on MovieLens	The best results are marked with bold
face.		

Data	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	CDL (Base Model)	0.0179	0.0274	0.0045	0.0581	0.0587
	PRUC (Full)	0.0252	0.0409	0.0072	0.1071	0.1076
	DLRM (Base Model)	0.0714	0.1096	0.0285	0.2433	0.2366
	PRUC (Full)	0.0716	0.1101	0.0284	0.2431	0.2372
$1, 18, 35, 45, 50, 56 \rightarrow 25$	PerK (Base Model)	0.0682	0.1029	0.0290	0.2224	0.2107
	PRUC (Full)	0.0690	0.1037	0.0287	0.2190	0.2110
	NCF (Base Model)	0.0050	0.0250	0.0011	0.0251	0.0251
	PRUC (Full)	0.0240	0.0387	0.0057	0.0947	0.1005
	LightGCN (Base Model) PRUC (Full)	0.0081 0.0249	0.0132 0.0402	0.0019 0.0069	0.0381 0.1076	0.0358 0.1055
	CDL (Base Model)	0.0576	0.0848	0.0174	0.1602	0.1716
	PRUC (Full)	0.0645	0.0952	0.0202	0.1772	0.1897
	DLRM (Base Model)	0.0848	0.1342	0.0382	0.3347	0.3225
	PRUC (Full)	0.0903	0.1405	0.0414	0.3455	0.3319
$25 \rightarrow 1, 18, 35, 45, 50, 56$	PerK (Base Model)	0.0746	0.1164	0.0324	0.2701	0.2661
	PRUC (Full)	0.0792	0.1225	0.0355	0.2821	0.2757
	NCF (Base Model)	0.0140	0.0229	0.0030	0.0633	0.0652
	PRUC (Full)	0.0450	0.0694	0.0144	0.1639	0.1711
	LightGCN (Base Model) PRUC (Full)	0.0093 0.0290	0.0157 0.0480	0.0022 0.0097	0.0497 0.1493	0.0482 0.1395

where $rel_{i,n}$ is an indicator that equals 1 if the item at rank n is relevant to user i, and 0 otherwise. $|J_i|$ denotes the total number of relevant items for user i.

Precision. Precision@N measures the proportion of the top N recommended items that are relevant to user i:

$$Precision_i@N = \sum_{n=1}^{N} {}^{rel_{i,n}}/N,$$
(27)

where $rel_{i,n}$ is 1 if the item at rank n is relevant to user i, and 0 otherwise.

 \mathbf{mAP} . Mean Average Precision (mAP) computes the average precision over all relevant items for user i. See Appendix B.1 for more details.

F1-score. The F1 Score@N for user i is the harmonic mean of Precision@N and Recall@N, providing a balance between the two metrics:

$$F1_i@N = 2 \times Precision_i@N \times Recall_i@N/Precision_i@N + Recall_i@N,$$
(28)

where $\operatorname{Recall}_i@N$ and $\operatorname{Precision}_i@N$ are defined in Eqn. 26 and Eqn. 27, respectively.

NDCG. Normalized Discounted Cumulative Gain (NDCG@N) evaluates the quality of the ranked list by considering the positions of the relevant items, giving higher scores to items appearing earlier in the list. See Appendix B.1 for more details.

All metrics are computed by averaging over all users i.

3.4 Results

Results for Different Base Models. Table 1 and Table 2 show the performance of PRUC with various base models across different metrics on both datasets. Results show that our full model ("PRUC (Full)") can generally boosts the base models' performance.

Recall@N with Larger N. Fig. 4 shows Recall@N for N = 50, 100, 150, 200, 250, 300 across three base models (CDL, DLRM, and PerK) and three training-testing domain splits. These figures indicate that PRUC

Table 3: Comparison between PRUC w/o Causality and PRUC (Full) on a specific domain with different base models on XMRec. The best results are marked with **bold face**.

Data	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	CDL (Base Model) CDL PRUC w/o Causality PRUC (Full)	0.0143 0.1058 0.1091	0.0016 0.0126 0.0128	0.0028 0.0333 0.0463	0.0009 0.0088 0.0108	0.0009 0.0067 0.0068
	DLRM (Base Model) DLRM PRUC w/o Causality PRUC (Full)	0.0044 0.0232 0.0295	0.0004 0.0026 0.0035	0.0004 0.0039 0.0048	0.0002 0.0014 0.0018	0.0002 0.0014 0.0018
France, Italy, India $\rightarrow \! \! \mathrm{Japan},$ Mexico	PerK (Base Model) PerK PRUC w/o Causality PRUC (Full)	0.1098 0.1376 0.1635	0.0128 0.0160 0.0192	0.0512 0.0558 0.0637	0.0112 0.0129 0.0151	0.0068 0.0085 0.0102
	NCF (Base Model) NCF PRUC w/o Causality PRUC (Full)	0.0131 0.1056 0.1137	0.0148 0.0126 0.0137	0.0026 0.0235 0.0309	0.0008 0.0074 0.0090	0.0008 0.0067 0.0073
	LightGCN (Base Model) LightGCN PRUC w/o Causality PRUC (Full)	0.0182 0.0940 0.1003	0.0021 0.0112 0.0121	0.0050 0.0289 0.0316	0.0014 0.0076 0.0084	0.0011 0.0059 0.0064

Table 4: Performance of PRUC with different base models on MovieLens. The best results are marked with **bold** face.

Data	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0179 0.0186 0.0252	0.0274 0.0302 0.0409	0.0045 0.0057 0.0072	0.0581 0.0863 0.1071	0.0587 0.0801 0.1076
	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0714 0.0232 0.0716	0.1096 0.0026 0.1101	0.0285 0.0039 0.0284	0.2433 0.0014 0.2431	0.2366 0.0014 0.2372
$1,\ 18,\ 35,\ 45,\ 50,\ 56\ {\rightarrow} 25$	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.0682 0.0582 0.0690	0.1029 0.0877 0.1037	0.0290 0.0212 0.0287	0.2224 0.1755 0.2190	0.2107 0.1787 0.2110
	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0050 0.0231 0.0240	0.0250 0.0374 0.0387	0.0011 0.0055 0.0057	0.0251 0.0927 0.0947	0.0251 0.0989 0.1005
	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0081 0.0248 0.0249	0.0132 0.0402 0.0402	0.0019 0.0070 0.0069	0.0381 0.1077 0.1076	0.0358 0.1053 0.1055

surpasses the base models even without the causality component ("PRUC w/o Causality"), while full PRUC consistently outperforms its non-causal counterpart in all settings. We observe similar results for other base models.

Visualizations of the Clusters. Fig. 5 visualizes the user latent **u** for all five base models on the XMRec dataset. Each visualization shows a distinct separation into 3 clusters, indicating successful user grouping of our model. Furthermore, Figure 6 illustrates the relationship between user clusters and items using the CDL-based PRUC model on the same dataset. For each user, we selected the item with the highest rating they have given, recorded the item ID and its rating, and visualized the results. Different clusters are represented using distinct colors, effectively showcasing the distribution and preferences of users within each cluster. For instance, Cluster 1 (Red) shows pronounced preferences for 4-5 specific items, underscoring the impact of user clustering on improving PRUC's performance.

Performance of Each Clusters Discovered by PRUC. For a deeper understanding of the model performance, we include more fine-grained results for different clusters discovered by PRUC in Appendix B.3. Results show that our PRUC can usually improve performance in most clusters.

Ablation Study. The comparison in Table 3, Table 4, and Fig. 4 highlights the performance difference between 'PRUC w/o Causality' and 'PRUC (Full)'. The results consistently show that 'PRUC (Full)' outperforms its counterpart, 'PRUC w/o Causality', emphasizing the crucial role of causal inference in enhancing

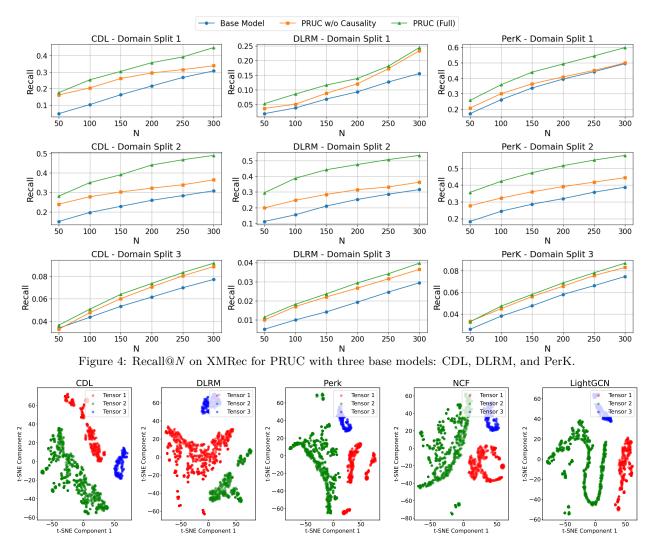


Figure 5: Clusters of users based on the user latent \mathbf{u} from PRUC with base models CDL (left), DLRM (left center), PerK (center), NCF (right center) and LightGCN (right) for the split "France, Italy, India \rightarrow Japan, Mexico". All user latents are reduced to 2D by t-SNE.

the effectiveness of the PRUC model. Furthermore, a comparison between the base model and 'PRUC w/o Causality' also reveals notable performance improvements, validating the efficacy of PRUC's user cluster discovery. Additional details on the ablation study for other domains can be found in Appendix B.4.

4 Related Work

Domain-Dependent Recommendation. Previous work has explored various in-domain recommendation scenarios. Early methods, such as PMF (Mnih & Salakhutdinov, 2007) and BPR (Rendle et al., 2012), applied collaborative filtering techniques to address challenges in recommendation. Later, methods such as GRU4Rec (Hidasi et al., 2016), SAS4Rec (Kang & McAuley, 2018), KGAT (Wang et al., 2019), and PerK (Kweon et al., 2024) leveraged advanced deep learning models to enhance the performance of recommender systems. These approaches focus on rating data between items and users but do not incorporate item features. Collaborative deep learning (CDL) models (Wang et al., 2015; 2016; Zhang et al., 2016; Li & She, 2017) incorporate content to enable pretrained recommenders, making them more versatile in different contexts, e.g., cold start scenarios.

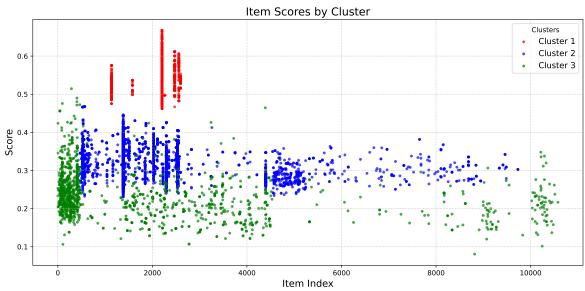


Figure 6: Clusters of users based on their highest rated items, using the CDL-based PRUC model applied to the XMRec dataset. X-axis indicates the item ID, while Y-axis indicates the score of the item. Clusters are distinguished by different colors.

Despite significant advances in in-domain recommendations, cross-domain recommendation remains relatively understudied. Existing work has utilized domain adaptation techniques (Xu et al., 2023; Liu et al., 2023; Shi & Wang, 2023; Xu et al., 2022; Wang et al., 2020a; Ganin et al., 2016) to tackle this challenge, often relying on common users or items across source (training) and target (testing) domains (Yuan et al., 2020; Wu et al., 2020; Bi et al., 2020; Li et al., 2019; Hansen et al., 2020; Liang et al., 2020; Zhu et al., 2020; Liu et al., 2020). On the other hand, some methods enhance recommendation performance in both source and target domains simultaneously (Li & Tuzhilin, 2020; Hu et al., 2018; Zhao et al., 2019). In contrast to existing approaches, our PRUC first infers user clusters and confounders before making recommendations based on the identified user clusters, leading to improved generalization and robustness against domain shifts.

Causal Inference for Recommendation. Causal inference (Pearl, 2009) has been widely applied to model cause-and-effect relationships between variables in the machine learning community. Recently, it has been employed to improve the performance of recommender systems (Wang et al., 2020b). PDA (Zhang et al., 2021) uses causal intervention to address popularity bias in recommendations, while DICE (Zheng et al., 2021) learns representations from user interactions based on the structured causal model (SCM). Additionally, some research focuses on debiasing recommendations without adopting a causal inference perspective (Li et al., 2021; Wang et al., 2022; Chen et al., 2023). However, these approaches do not consider user groups within the SCM framework. In contrast, our method divides users into clusters based on a confounder variable and generates recommendations by aggregating user ratings through do-calculus, providing a more interpretable and sophisticated approach.

5 Conclusion

In this paper, we address the problem of cross-domain recommendation by introducing a novel causal Bayesian framework, named Probabilistic Residual User Clustering (PRUC). PRUC generates recommendations by: (1) inferring the user cluster ID, (2) inferring the residual rating based on our causal debiasing framework, and (3) predicting the final rating as a correction to the base model's prediction. PRUC can enhance the performance of any base recommenders in a plug-and-play manner, and automatically discover meaningful user clusters. As a general probabilistic framework compatible with various recommendation systems, PRUC can be extended to additional modalities beyond textual data in future research. Furthermore, PRUC provides interpretability by uncovering latent user preferences and biases that influence rating predictions. Its modular design also allows seamless integration with deep learning-based recommenders, making it a scalable and adaptable solution for diverse recommendation scenarios.

References

- Ye Bi, Liqiang Song, Mengqiu Yao, Zhenyu Wu, Jianming Wang, and Jing Xiao. A heterogeneous information network based cross domain insurance recommendation system for cold start users. In *SIGIR*, pp. 2211–2220, 2020.
- Hamed Bonab, Mohammad Aliannejadi, Ali Vardasbi, Evangelos Kanoulas, and James Allan. Cross-market product recommendation. In *Proceedings of the 30th ACM International Conference on Information & Knowledge Management*, pp. 110–119, 2021.
- Jiawei Chen, Hande Dong, Xiang Wang, Fuli Feng, Meng Wang, and Xiangnan He. Bias and debias in recommender system: A survey and future directions. *ACM Transactions on Information Systems*, 41(3): 1–39, 2023.
- Junyoung Chung, cCaglar Gülccehre, KyungHyun Cho, and Yoshua Bengio. Empirical evaluation of gated recurrent neural networks on sequence modeling. CoRR, abs/1412.3555, 2014. URL http://arxiv.org/abs/1412.3555.
- Yaroslav Ganin, Evgeniya Ustinova, Hana Ajakan, Pascal Germain, Hugo Larochelle, Fran**c**cois Laviolette, Mario Marchand, and Victor Lempitsky. Domain-adversarial training of neural networks. *JMLR*, 17(1): 2096–2030, 2016.
- Casper Hansen, Christian Hansen, Jakob Grue Simonsen, Stephen Alstrup, and Christina Lioma. Content-aware neural hashing for cold-start recommendation. In *SIGIR*, pp. 971–980, 2020.
- F Maxwell Harper and Joseph A Konstan. The movielens datasets: History and context. Acm transactions on interactive intelligent systems (tiis), 5(4):1–19, 2015.
- Xiangnan He, Lizi Liao, Hanwang Zhang, Liqiang Nie, Xia Hu, and Tat-Seng Chua. Neural collaborative filtering. In *Proceedings of the 26th international conference on world wide web*, pp. 173–182, 2017.
- Xiangnan He, Kuan Deng, Xiang Wang, Yan Li, Yongdong Zhang, and Meng Wang. Lightgen: Simplifying and powering graph convolution network for recommendation. In *Proceedings of the 43rd International ACM SIGIR conference on research and development in Information Retrieval*, pp. 639–648, 2020.
- Balázs Hidasi, Alexandros Karatzoglou, Linas Baltrunas, and Domonkos Tikk. Session-based recommendations with recurrent neural networks. In Yoshua Bengio and Yann LeCun (eds.), ICLR, 2016.
- Guangneng Hu, Yu Zhang, and Qiang Yang. CoNet: Collaborative cross networks for cross-domain recommendation. In *Proceedings of the 27th ACM International Conference on Information and Knowledge Management*, CIKM, pp. 667–676, 2018.
- Wang-Cheng Kang and Julian McAuley. Self-attentive sequential recommendation. In 2018 IEEE international conference on data mining (ICDM), pp. 197–206. IEEE, 2018.
- Diederik P. Kingma and Jimmy Ba. Adam: A method for stochastic optimization. In ICLR, 2015.
- Wonbin Kweon, SeongKu Kang, Sanghwan Jang, and Hwanjo Yu. Top-personalized-k recommendation. In *Proceedings of the ACM on Web Conference 2024*, pp. 3388–3399, 2024.
- Jingjing Li, Mengmeng Jing, Ke Lu, Lei Zhu, Yang Yang, and Zi Huang. From zero-shot learning to cold-start recommendation. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 33, pp. 4189–4196, 2019.
- Pan Li and Alexander Tuzhilin. DDTCDR: deep dual transfer cross domain recommendation. In James Caverlee, Xia (Ben) Hu, Mounia Lalmas, and Wei Wang (eds.), WSDM '20: The Thirteenth ACM International Conference on Web Search and Data Mining, Houston, TX, USA, February 3-7, 2020, pp. 331–339. ACM, 2020. doi: 10.1145/3336191.3371793. URL https://doi.org/10.1145/3336191.3371793.

- Siqing Li, Liuyi Yao, Shanlei Mu, Wayne Xin Zhao, Yaliang Li, Tonglei Guo, Bolin Ding, and Ji-Rong Wen. Debiasing learning based cross-domain recommendation. In *Proceedings of the 27th ACM SIGKDD Conference on Knowledge Discovery & Data Mining*, pp. 3190–3199, 2021.
- Xiaopeng Li and James She. Collaborative variational autoencoder for recommender systems. In *KDD*, pp. 305–314, 2017.
- Tingting Liang, Congying Xia, Yuyu Yin, and Philip S. Yu. Joint training capsule network for cold start recommendation. In *SIGIR*, pp. 1769–1772, 2020.
- Siwei Liu, Iadh Ounis, Craig Macdonald, and Zaiqiao Meng. A heterogeneous graph neural model for cold-start recommendation. In *Proceedings of the 43rd International ACM SIGIR Conference on Research and Development in Information Retrieval*, pp. 2029–2032, 2020.
- Tianyi Liu, Zihao Xu, Hao He, Guangyuan Hao, Guang-He Lee, and Hao Wang. Taxonomy-structured domain adaptation. In *ICML*, 2023.
- Andriy Mnih and Russ R Salakhutdinov. Probabilistic matrix factorization. Advances in neural information processing systems, 20, 2007.
- Maxim Naumov, Dheevatsa Mudigere, Hao-Jun Michael Shi, Jianyu Huang, Narayanan Sundaraman, Jongsoo Park, Xiaodong Wang, Udit Gupta, Carole-Jean Wu, Alisson G Azzolini, et al. Deep learning recommendation model for personalization and recommendation systems. arXiv preprint arXiv:1906.00091, 2019.
- Judea Pearl. Causality. Cambridge university press, 2009.
- Steffen Rendle, Christoph Freudenthaler, Zeno Gantner, and Lars Schmidt-Thieme. Bpr: Bayesian personalized ranking from implicit feedback. arXiv preprint arXiv:1205.2618, 2012.
- Haizhou Shi and Hao Wang. A unified approach to domain incremental learning with memory: Theory and algorithm. In *NeurIPS*, 2023.
- Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N Gomez, Lukasz Kaiser, and Illia Polosukhin. Attention is all you need. *Advances in neural information processing systems*, 30, 2017.
- Hao Wang, Naiyan Wang, and Dit-Yan Yeung. Collaborative deep learning for recommender systems. In *Proceedings of the 21th ACM SIGKDD international conference on knowledge discovery and data mining*, pp. 1235–1244, 2015.
- Hao Wang, SHI Xingjian, and Dit-Yan Yeung. Collaborative recurrent autoencoder: Recommend while learning to fill in the blanks. In NIPS, pp. 415–423, 2016.
- Hao Wang, Hao He, and Dina Katabi. Continuously indexed domain adaptation. In ICML, 2020a.
- Xiang Wang, Xiangnan He, Yixin Cao, Meng Liu, and Tat-Seng Chua. Kgat: Knowledge graph attention network for recommendation. In *Proceedings of the 25th ACM SIGKDD international conference on knowledge discovery & data mining*, pp. 950–958, 2019.
- Yixin Wang, Dawen Liang, Laurent Charlin, and David M Blei. Causal inference for recommender systems. In *Proceedings of the 14th ACM Conference on Recommender Systems*, pp. 426–431, 2020b.
- Zimu Wang, Yue He, Jiashuo Liu, Wenchao Zou, Philip S. Yu, and Peng Cui. Invariant preference learning for general debiasing in recommendation. In *KDD '22: The 28th ACM SIGKDD Conference on Knowledge Discovery and Data Mining*, pp. 1969–1978, 2022.
- Le Wu, Yonghui Yang, Lei Chen, Defu Lian, Richang Hong, and Meng Wang. Learning to transfer graph embeddings for inductive graph based recommendation. In *SIGIR*, pp. 1211–1220, 2020.

Shu Wu, Yuyuan Tang, Yanqiao Zhu, Liang Wang, Xing Xie, and Tieniu Tan. Session-based recommendation with graph neural networks. In *Proceedings of the AAAI conference on artificial intelligence*, volume 33, pp. 346–353, 2019.

Zihao Xu, Guang-He Lee, Yuyang Wang, Hao Wang, et al. Graph-relational domain adaptation. In *ICLR*, 2022.

Zihao Xu, Guangyuan Hao, Hao He, and Hao Wang. Domain indexing variational bayes: Interpretable domain index for domain adaptation. In *ICLR*, 2023.

Fajie Yuan, Xiangnan He, Alexandros Karatzoglou, and Liguang Zhang. Parameter-efficient transfer from sequential behaviors for user modeling and recommendation. In SIGIR, pp. 1469–1478, 2020.

Fuzheng Zhang, Nicholas Jing Yuan, Defu Lian, Xing Xie, and Wei-Ying Ma. Collaborative knowledge base embedding for recommender systems. In *KDD*, pp. 353–362. ACM, 2016.

Yang Zhang, Fuli Feng, Xiangnan He, Tianxin Wei, Chonggang Song, Guohui Ling, and Yongdong Zhang. Causal intervention for leveraging popularity bias in recommendation. In *Proceedings of the 44th International ACM SIGIR Conference on Research and Development in Information Retrieval*, pp. 11–20, 2021.

Cheng Zhao, Chenliang Li, and Cong Fu. Cross-domain recommendation via preference propagation graphnet. In *Proceedings of the 28th ACM International Conference on Information and Knowledge Management, CIKM*, pp. 2165–2168, 2019.

Yu Zheng, Chen Gao, Xiang Li, Xiangnan He, Yong Li, and Depeng Jin. Disentangling user interest and conformity for recommendation with causal embedding. In *Proceedings of the Web Conference 2021*, pp. 2980–2991, 2021.

Ziwei Zhu, Shahin Sefati, Parsa Saadatpanah, and James Caverlee. Recommendation for new users and new items via randomized training and mixture-of-experts transformation. In SIGIR, pp. 1121–1130, 2020.

A Appendix

B More Details on Experiments and Implementation

B.1 Metrics

mAP. mAP is defined as:

$$AP_{i} = \frac{1}{|J_{i}|} \sum_{n=1}^{N} rel_{i,n} \times Precision_{i}@n,$$
(29)

where N is the total number of recommended items, $Precision_i@n$ is the precision at rank n, and $|J_i|$ is the total number of relevant items for user i. The mean Average Precision (mAP) is then calculated by averaging AP_i over all users:

$$mAP = \frac{1}{|I|} \sum_{i=1}^{|I|} AP_i, \tag{30}$$

where |I| is the total number of users.

NDCG. NDCG@N is computed as follows.

First, the Discounted Cumulative Gain (DCG@N) is calculated:

$$DCG_i@N = \sum_{n=1}^{N} \frac{2^{rel_{i,n}} - 1}{\log_2(n+1)},$$
(31)

where $\operatorname{rel}_{i,n}$ denotes the relevance of the item at position n for user i. Next, the Ideal Discounted Cumulative Gain (IDCG@N), representing the maximum possible DCG (i.e., all relevant items ranked at the top), is calculated as:

$$IDCG_i@N = \sum_{n=1}^{\min(N,|J_i|)} \frac{2^1 - 1}{\log_2(n+1)} = \sum_{n=1}^{\min(N,|J_i|)} \frac{1}{\log_2(n+1)},$$
(32)

where $|J_i|$ denotes the total number of relevant items for user i.

Finally, the Normalized Discounted Cumulative Gain is obtained by normalizing DCG@N by IDCG@N:

$$NDCG_i@N = \frac{DCG_i@N}{IDCG_i@N}.$$
(33)

Here the logarithmic term $\log_2(n+1)$ discounts the relevance based on the item's position in the ranked list, serving as the normalization factor.

B.2 Training Configurations

Following CDL (Wang et al., 2015), we set the hidden dimension h = 50 for all latent vectors, as well as for the encoder and decoder networks. During training, we use AdamW (Kingma & Ba, 2015) as our optimizer, with a learning rate of 10^{-3} and a batch size of 256. The base models were trained for 100 epochs, while PRUC was trained for 150 epochs. All experiments were conducted on an NVIDIA RTX A5000 GPU.

B.3 Performance of Each Clusters Discovered by PRUC

Table 10, 11, 12, 13, 14 show PRUC's performance across different clusters on XMRec using CDL, DLRM, PerK, NCF, and LightGCN as base models. These results support the conclusion that PRUC improves upon the base models even without incorporating the causality component. Furthermore, the full PRUC consistently outperforms its non-causal counterpart across all configurations. For example, CDL, as the base model, achieves a recall@20 of 0.0241 for User Cluster 1 in the split of "France, Italy, India \rightarrow Japan, Mexico". When PRUC without the causal inference component is applied, recall improves to 0.0278. The full PRUC further enhances performance for this metric, achieving a recall@20 of 0.0708.

Table 5, 6, 7, 8, 9 show PRUC's performance across different clusters on MovieLens with the same five base models. Even with some fluctuations, the similar improvements are consistent with the results for XMRec.

B.4 Ablation Study

The performance comparison across Table 5-14 shows that "PRUC (Full)" generally outperforms "PRUC w/o Causality", highlighting the effectiveness of causal inference in PRUC. Additionally, comparing the base model with "PRUC w/o Causality" reveals performance enhancements, suggesting that PRUC's user cluster discovery significantly boosts performance.

Table 5: Performance of PRUC on different user clusters with CDL as the base model on MovieLens. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0
$1,18,35,45,50,56\to\!25$	2	CDL (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
	3	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0179 0.0186 0.0252	0.0274 0.0302 0.0409	0.0045 0.0056 0.0072	0.0581 0.0864 0.1071	0.0587 0.0802 0.1077
$25 \rightarrow 1, 18, 35, 45, 50, 56$	1	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0558 0.0317 0.0558	0.0861 0.0528 0.0861	0.0174 0.0095 0.0174	0.1758 0.1511 0.1759	0.1879 0.1572 0.1879
	2	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0651 0.0676 0.1016	0.0795 0.0880 0.1341	0.0173 0.0183 0.0319	0.0938 0.1159 0.1832	0.1020 0.1259 0.1972
	3	CDL (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -

Table 6: Performance of PRUC on different user clusters with DLRM as the base model on MovieLens. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	DLRM (Base Model) - PRUC w/o Causality - PRUC (Full) -	- - -	- - -	- - -	- - -	
$1,18,35,45,50,56\to\!25$	2	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0714 0.0269 0.0716	0.1097 0.0434 0.1101	0.0285 0.0073 0.0284	0.2433 0.1078 0.2431	0.2367 0.1112 0.2372
	3	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0
$25 \rightarrow 1, 18, 35, 45, 50, 56$	1	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0790 0.0328 0.0848	0.1264 0.0548 0.1366	0.0343 0.0116 0.0396	0.3266 0.1716 0.3634	0.3146 0.1656 0.3505
	2	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0882 0.0975 0.1119	0.1390 0.1382 0.1561	0.0405 0.0426 0.0486	0.3396 0.2572 0.2745	0.3271 0.2374 0.2583
	3	DLRM (Base Model) PRUC w/o Causality PRUC (Full)			- - -	- - -	

Table 7: Performance of PRUC on different user clusters with Perk as the base model on MovieLens. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	Perk (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
$1,18,35,45,50,56\to 25$	2	Perk (Base Model) PRUC w/o Causality PRUC (Full)	0.0686 0.0583 0.0683	0.1040 0.0884 0.1036	0.0295 0.0215 0.0288	0.2271 0.1788 0.2215	0.2150 0.1820 0.2136
	3	Perk (Base Model) PRUC w/o Causality PRUC (Full)	0.0585 0.0550 0.0847	0.0745 0.0701 0.1074	0.0173 0.0139 0.0277	0.1053 0.0942 0.1559	0.1023 0.0967 0.1467
	1	Perk (Base Model) PRUC w/o Causality PRUC (Full)	0.0745 0.0319 0.0745	0.1179 0.0530 0.1179	0.0332 0.0140 0.0332	0.2868 0.1811 0.2870	0.2826 0.1563 0.2828
$25 \rightarrow 1, 18, 35, 45, 50, 56$	2	Perk (Base Model) PRUC w/o Causality PRUC (Full)	0.0750 0.0939 0.0984	0.1090 0.1338 0.1407	0.0292 0.0367 0.0446	0.2033 0.2399 0.2628	0.1995 0.2323 0.2469
	3	Perk (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -		- - -	- - -

Table 8: Performance of PRUC on different user clusters with NCF as the base model on MovieLens. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.1964	0.0 0.0 0.1325	0.0 0.0 0.0230	0.0 0.0 0.0754	0.0 0.0 0.1000
$1,18,35,45,50,56\to 25$	2	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0051 0.0271 0.0285	0.0087 0.0443 0.0463	0.0011 0.0067 0.0070	0.0282 0.1134 0.1159	0.0279 0.1210 0.1231
	3	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0047 0.0125 0.0120	0.0074 0.0192 0.0185	0.0009 0.0023 0.0022	0.0172 0.0386 0.0389	0.0177 0.0409 0.0410
	1	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0149 0.0309 0.0306	0.0248 0.0515 0.0512	0.0032 0.0088 0.0087	0.0710 0.1494 0.1484	0.0729 0.1555 0.1551
$25 \to 1, 18, 35, 45, 50, 56$	2	NCF (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
	3	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0098 0.0941 0.1071	0.0150 0.1316 0.1481	0.0021 0.0312 0.0392	0.0302 0.2094 0.2309	0.0319 0.2185 0.2402

Table 9: Performance of PRUC on different user clusters with LightGCN as the base model on MovieLens. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
$1,18,35,45,50,56\to 25$	2	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0081 0.0248 0.0248	0.0132 0.0402 0.0401	0.0019 0.0070 0.0069	0.0381 0.1075 0.1073	0.0358 0.1052 0.1053
	3	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0226 0.0214 0.0563	0.0224 0.0378 0.0884	0.0075 0.0115 0.0226	0.0227 0.1911 0.2219	0.0222 0.1611 0.2056
$25 \rightarrow 1, 18, 35, 45, 50, 56$	1	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0094 0.0300 0.0288	0.0157 0.0495 0.0477	0.0022 0.0101 0.0097	0.0498 0.1515 0.1492	0.0484 0.1416 0.1394
	2	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0068 0.0297 0.0531	0.0110 0.0428 0.0793	0.0011 0.0130 0.0204	0.0277 0.0953 0.1597	0.0294 0.0765 0.1559
	3	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -

Table 10: Performance of PRUC on different user clusters with CDL as the base model on XMRec. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0241 0.1972 0.0708	0.0028 0.0238 0.0074	0.0062 0.0905 0.0652	0.0018 0.0197 0.0105	0.0015 0.0127 0.0039
France, Italy, India \rightarrow Japan, Mexico	2	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0126 0.0902 0.1156	0.0014 0.0107 0.0138	0.0022 0.0236 0.0431	0.0007 0.0069 0.0109	0.0008 0.0057 0.0073
	3	CDL (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
	1	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.1742 0.2114 0.1665	0.0225 0.0267 0.0222	0.0333 0.0707 0.0634	0.0123 0.0194 0.0170	0.0120 0.0142 0.0119
Mexico, Spain, India $\to \! \mathrm{Japan},$ Germany	2	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0903 0.1532 0.1796	0.0102 0.0187 0.0233	0.0289 0.0524 0.0579	0.0072 0.0136 0.0160	0.0054 0.0100 0.0124
	3	CDL (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
	1	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0262 0.0261 0.0266	0.0059 0.0063 0.0064	0.0079 0.0072 0.0062	0.0041 0.0044 0.0042	0.0033 0.0036 0.0037
Germany, Italy, Japan \rightarrow United States, India	2	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0244 0.0166 0.0250	0.0054 0.0037 0.0055	0.0088 0.0041 0.0088	0.0042 0.00234 0.0042	0.0031 0.0021 0.0031
	3	CDL (Base Model) PRUC w/o Causality PRUC (Full)	0.0277 0.0194 0.0278	0.0049 0.0045 0.0049	0.0066 0.0049 0.0067	0.0028 0.0030 0.0028	0.0027 0.0026 0.0027

Table 11: Performance of PRUC on different user clusters with DLRM as the base model on XMRec. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
	1	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0051 0.0246 0.0345	0.0005 0.0027 0.004	0.0004 0.0039 0.0056	0.0002 0.0014 0.0021	0.0003 0.0014 0.0021
France, Italy, India \rightarrow Japan, Mexico	2	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0000 0.0150 0.0000	0.0000 0.0017 0.0000	0.0000 0.0040 0.0000	0.0000 0.0010 0.0000	0.0000 0.0009 0.0000
	3	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
	1	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0000 0.3296 0.3074	0.0000 0.0416 0.0395	0.0000 0.0203 0.0213	0.0000 0.0153 0.0152	0.0000 0.0222 0.0211
Mexico, Spain, India $\to\!\!\operatorname{Japan},$ Germany	2	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0780 0.1398 0.1984	0.0096 0.0174 0.0241	0.0087 0.0277 0.0555	0.0042 0.0096 0.0157	0.0051 0.0093 0.0128
	3	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -		- - -	- - -
	1	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0023 0.0042 0.0046	0.0006 0.0011 0.0011	0.0003 0.0010 0.0009	0.0003 0.0007 0.0007	0.0003 0.0007 0.0006
Germany, Italy, Japan \rightarrow United States, India	2	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0018 0.0045 0.0045	0.0005 0.0012 0.0011	0.0003 0.0010 0.0012	0.0003 0.0007 0.0007	0.0003 0.0007 0.0007
	3	DLRM (Base Model) PRUC w/o Causality PRUC (Full)	0.0036 0.0052 0.0141	0.0008 0.0015 0.0034	0.0005 0.0009 0.0075	0.0004 0.0009 0.0032	0.0004 0.0009 0.0019

Table 12: Performance of PRUC on different user clusters with PerK as the base model on XMRec. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
France, Italy, India \rightarrow Japan, Mexico	1	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.1752 0.2153 0.1782	0.0204 0.0260 0.0210	0.1152 0.1255 0.1162	0.022 0.0252 0.0226	0.0108 0.0139 0.0114
	2	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.0986 0.1243 0.1629	0.0115 0.0143 0.0189	0.0403 0.0440 0.0548	0.0094 0.0108 0.0138	0.0061 0.0076 0.0100
	3	PerK (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
Mexico, Spain, India →Japan, Germany	1	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.1434 0.2175 0.2905	0.0176 0.0262 0.0353	0.0582 0.0913 0.1157	0.014 0.0217 0.0278	0.0094 0.0140 0.0188
	2	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.1495 0.2783 0.1790	0.0184 0.0307 0.0224	0.0723 0.0964 0.0646	0.0166 0.0232 0.0167	0.0098 0.0163 0.0120
	3	PerK (Base Model) PRUC w/o Causality PRUC (Full)		- - -	- - -	- - -	- - -
Germany, Italy, Japan \rightarrow United States, India	1	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.0194 0.0295 0.0308	0.0043 0.0066 0.0068	0.0057 0.0087 0.0086	0.003 0.0046 0.0046	0.0024 0.0037 0.0038
	2	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.0126 0.0155 0.0162	0.0028 0.0035 0.0037	0.0032 0.0040 0.0048	0.0018 0.0022 0.0025	0.0016 0.0020 0.0021
	3	PerK (Base Model) PRUC w/o Causality PRUC (Full)	0.0261 0.0174 0.0266	0.0035 0.0027 0.0041	0.0091 0.0013 0.0102	0.0025 0.0012 0.0033	0.0019 0.0014 0.0022

Table 13: Performance of PRUC on different user clusters with NCF as the base model on XMRec. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
France, Italy, India \rightarrow Japan, Mexico	1	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0090 0.2013 0.1581	0.0010 0.0238 0.0176	0.0019 0.0537 0.0476	0.0005 0.0151 0.0122	0.0005 0.0127 0.0093
	2	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0165 0.0893 0.1062	0.0019 0.0107 0.0130	0.0032 0.0184 0.0280	0.0010 0.0061 0.0084	0.0010 0.0057 0.0069
	3	NCF (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
Mexico, Spain, India →Japan, Germany	1	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0097 0.1081 0.1560	0.0013 0.0142 0.0202	0.0022 0.0181 0.0280	0.0007 0.0073 0.0107	0.0007 0.0076 0.0108
	2	NCF (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -		
	3	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0
Germany, Italy, Japan \rightarrow United States, India	1	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0020 0.0204 0.0214	0.0005 0.0051 0.0055	0.0006 0.0041 0.0039	0.0004 0.0030 0.0032	0.0003 0.0029 0.0031
	2	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0018 0.0064 0.0079	0.0005 0.0015 0.0021	0.0003 0.0008 0.0011	0.0003 0.0008 0.0011	0.0003 0.0009 0.0012
	3	NCF (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0

Table 14: Performance of PRUC on different user clusters with LightGCN as the base model on XMRec. "-" means a cluster contains only training-set users, i.e., no test-set users to evaluate. The best results are marked with **bold** face.

Data	Cluster	Method	Recall@20	F1@20	MAP@20	NDCG@20	Precision@20
France, Italy, India \rightarrow Japan, Mexico	1	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0261 0.1742 0.1400	0.0034 0.0209 0.0154	0.0028 0.0749 0.0482	0.0015 0.0167 0.0115	0.0018 0.0111 0.0081
	2	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0168 0.0804 0.0936	0.0019 0.0095 0.0115	0.0054 0.0211 0.0288	0.0013 0.0060 0.0079	0.0010 0.0051 0.0061
	3	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	- - -
Mexico, Spain, India →Japan, Germany	1	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0093 0.0972 0.0	0.0009 0.0097 0.0	0.0046 0.0129 0.0	0.0008 0.0045 0.0	0.0005 0.0051 0.0
	2	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0170 0.1040 0.1790	0.0023 0.0135 0.0224	0.0062 0.0215 0.0646	0.0017 0.0077 0.0167	0.0012 0.0072 0.0120
	3	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	- - -	- - -	- - -	- - -	
Germany, Italy, Japan \rightarrow United States, India	1	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0016 0.0062 0.0066	0.0005 0.0017 0.0017	0.0002 0.0012 0.0014	0.0002 0.0010 0.0011	0.0003 0.0010 0.0010
	2	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0	0.0 0.0 0.0
	3	LightGCN (Base Model) PRUC w/o Causality PRUC (Full)	0.0016 0.0037 0.0039	0.0004 0.0009 0.0008	.0002 0.0010 0.0012	0.0002 0.0006 0.0006	0.0002 0.0005 0.0005