Supplementary Material for "RangePerception: Taming LiDAR Range View for Efficient and Accurate 3D Object Detection"

Yeqi Bai¹ Ben Fei^{1,2} Youquan Liu¹ Tao Ma^{1,3}
Yuenan Hou¹ Botian Shi^{1,*} Yikang Li¹

¹ Shanghai AI Laboratory ² Fudan University

³ Multimedia Laboratory, The Chinese University of Hong Kong {baiyeqi,feiben,liuyouquan,matao}@pjlab.org.cn {houyuenan,shibotian,liyikang}@pjlab.org.cn

Supplementary material is available at https://rangeperception.github.io, to enhance the accessibility and comprehension of this study.

^{*}Corresponding author