

Table 1: Discounted return of different choices of α , averaged over 3 random seeds. The best results have been boldened, and $\alpha = 1$ corresponds to original GoFAR algorithm

$\alpha \setminus$ Env	FetchReach	FetchPick	FetchPush	FetchSlide	HandReach
0.01	27.4 ± 0.29	18.5 ± 0.1	18.0 ± 1.8	2.36 ± 1.13	8.72 ± 1.69
0.02	27.4 ± 0.32	18.7 ± 1.8	18.6 ± 2.6	2.40 ± 0.47	7.96 ± 1.27
0.05	27.4 ± 0.32	17.3 ± 1.1	19.3 ± 2.0	3.18 ± 0.90	8.98 ± 3.11
0.1	27.4 ± 0.33	20.3 ± 1.3	20.3 ± 2.5	3.22 ± 0.38	5.28 ± 1.25
0.2	27.4 ± 0.32	20.7 ± 0.9	17.7 ± 2.9	2.25 ± 0.23	2.92 ± 0.98
0.5	27.5 ± 0.29	18.5 ± 0.4	20.1 ± 2.2	3.47 ± 1.08	5.74 ± 2.72
1	27.3 ± 0.34	18.2 ± 1.2	19.6 ± 1.6	2.75 ± 1.84	7.13 ± 3.60
2	27.4 ± 0.29	18.3 ± 0.7	19.6 ± 1.4	1.80 ± 0.66	3.99 ± 1.88

Table 2: Final distance of different choices of α , averaged over 3 random seeds. The best results have been boldened, and $\alpha = 1$ corresponds to original GoFAR algorithm

$\alpha \setminus$ Env	FetchReach	FetchPick	FetchPush	FetchSlide	HandReach
0.01	0.0171 ± 0.0017	0.042 ± 0.004	0.033 ± 0.001	0.1177 ± 0.012	0.0269 ± 0.0049
0.02	0.0168 ± 0.0016	0.045 ± 0.012	0.031 ± 0.002	0.1085 ± 0.010	0.0274 ± 0.0049
0.05	0.0181 ± 0.0011	0.052 ± 0.013	0.032 ± 0.002	0.1061 ± 0.009	0.0270 ± 0.0049
0.1	0.0173 ± 0.0014	0.032 ± 0.010	0.027 ± 0.002	0.1018 ± 0.002	0.0275 ± 0.0043
0.2	0.0172 ± 0.0019	0.031 ± 0.004	0.031 ± 0.003	0.1029 ± 0.010	0.0275 ± 0.0046
0.5	0.0166 ± 0.0011	0.044 ± 0.009	0.031 ± 0.005	0.1017 ± 0.017	0.026826 ± 0.0049
1	0.0175 ± 0.0013	0.043 ± 0.011	0.043 ± 0.012	0.1202 ± 0.019	0.026828 ± 0.0044
2	0.0171 ± 0.0011	0.034 ± 0.005	0.032 ± 0.001	0.1044 ± 0.011	0.0275 ± 0.0045