# **RMM: Reinforced Memory Management** for Class-Incremental Learning *Supplementary Materials*

Yaoyao Liu<sup>1</sup> Bernt Schiele<sup>1</sup> Qianru Sun<sup>2</sup>

<sup>1</sup>Max Planck Institute for Informatics, Saarland Informatics Campus <sup>2</sup>School of Computing and Information Systems, Singapore Management University {yaoyao.liu, schiele}@mpi-inf.mpg.de qianrusun@smu.edu.sg

These supplementary materials include the additional results for comparing to the state-of-the-art ( A), the experiments with a growing memory budget ( B), more details about memory budgets ( C), more ablation results ( D), additional information ( E), the instruction for the PyTorch code ( F) and the checklist ( G).

# A Additional Results for Comparing to the State-of-the-Art.

This is supplementary to Section 5.2 "Comparing to the State-of-the-Art." In Table S1, we supplement the last-phase accuracies (%) of RMM and some recent CIL methods [3, 5, 8, 10–12]. In Table S2, we supplement the 95% confidence intervals of POD-AANets *w*/ RMM.

For Table S1, we can observe: 1) our RMM consistently improves the two top baselines LU-CIR+AANets and POD+AANets [10] in all settings; 2) our POD-AANets *w*/ RMM achieves the best performances.

Matha d	CIFAR-100		Imag	ImageNet-Subset			ImageNet-Full		
Method	N=5	10	25	5	10	25	5	10	25
LwF [8]	45.34	41.86	41.07	44.74	39.22	37.40	39.63	38.31	39.84
iCaRL [12]	39.01	46.16	43.04	55.76	50.32	45.72	50.57	40.44	40.52
LUCIR [5]	54.47	52.98	49.37	60.88	56.66	50.10	58.34	51.70	46.83
Mnemonics [11]	55.49	53.08	49.71	64.06	62.36	60.02	58.23	56.28	52.80
PODNet [3]	54.95	53.29	52.17	68.08	65.57	58.50	60.28	58.61	50.63
LUCIR-AANets [10]	58.75	56.88	53.89	64.52	58.90	56.73	58.32	55.69	52.78
w/ RMM (ours)	60.48	58.96	54.51	67.42	66.60	63.12	58.86	55.97	53.41
POD-AANets [10]	57.81	55.70	52.53	70.02	68.97	63.89	61.10	57.70	53.41
w/ RMM (ours)	59.00	59.03	56.50	73.80	71.40	68.84	62.50	60.10	55.50

Table S1: Supplementary to Table 1. Last-phase accuracies (%) using two state-of-the-art methods (LUCIR+AANets and POD+AANets [10]) w/ and w/o our RMM plugged in. The upper block is for recent CIL methods. For fair comparison, we re-implement these methods using our strict memory budget (see "**Memory Budget**" in Section 5.1) based on the public code.

35th Conference on Neural Information Processing Systems (NeurIPS 2021).

		CIFAR-100		ImageNet-Subset			
Method	N=5	10	25	5	10	25	
BiC [15]	54.90±0.38	51.82±0.47	49.72±0.52	_	_	_	
LUCIR [5]	$63.34{\scriptstyle\pm0.30}$	$62.47{\scriptstyle\pm0.29}$	$59.69{\scriptstyle \pm 0.28}$	$71.21{\scriptstyle\pm0.45}$	$68.21{\scriptstyle \pm 0.41}$	$64.15{\scriptstyle\pm 0.32}$	
PODNet [3]	$64.60{\scriptstyle \pm 0.15}$	$63.13{\scriptstyle \pm 0.42}$	$61.96{\scriptstyle \pm 0.25}$	$76.45{\scriptstyle \pm 0.40}$	$74.66{\scriptstyle \pm 0.32}$	$70.15{\scriptstyle \pm 0.41}$	
POD-AANets [10]	66.61±0.91	64.61±1.13	62.63±0.98	77.36±0.06	$75.83 \pm 0.05$	72.18±0.07	
POD-AANets [10] w/ RMM (ours)	$\textbf{68.86}{\scriptstyle \pm 1.02}$	$67.61{\scriptstyle \pm 0.69}$	$66.21{\scriptstyle \pm 0.62}$	$79.52{\scriptstyle \pm 0.05}$	$\textbf{78.47}{\scriptstyle \pm 0.04}$	$76.54{\scriptstyle \pm 0.06}$	

Table S2: Supplementary to Table 1. Average accuracies (%) with 95% confidence intervals.

## **B** Experiments with a Growing Memory Budget

This is supplementary to Section 5.2 "Comparing to the State-of-the-Art." In Table S3, we supplement the average accuracies (%) of RMM and some recent CIL methods [3, 5, 6, 8, 10–12, 14, 15] using the setting that allows the memory budget to grow along with phases (i.e., the second setting in Section 5.1 "Memory Budget"). In this setting, for saving exemplars, we allocate a memory budget of 1,000 samples since the 0-th phase, and we allocate an additional memory budget of 20 samples for each new class in each phase. For example, on CIFAR-100 (N=5), the total memory budget of the 1-st phase is set as 6,000 samples (6,000 samples = 10 classes/phase × 500 samples/class + 1,000 samples), and the total memory budget of the 2-nd phase is set as 6,200 samples (6,200 samples = 10 classes/phase × 500 samples/class + 1,000 samples = 20 samples/class + 10 classes).

Matha J		CIFAR-100	)	ImageNet-Subset		
Method	N=5	10	25	5	10	25
LwF [8]	49.59	46.98	45.51	53.62	47.64	44.32
iCaRL [12]	57.12	52.66	48.22	65.44	59.88	52.97
BiC [15]	59.36	54.20	50.00	70.07	64.96	57.73
LUCIR [5]	63.17	60.14	57.54	70.84	68.32	61.44
TPCIL [14]	65.34	63.58	-	76.27	74.81	_
DDE [6]	65.42	64.12	-	76.71	75.41	_
Mnemonics [11]	63.34	62.28	60.96	72.58	71.37	69.74
PODNet [3]	64.83	63.19	60.72	75.54	74.33	68.31
LUCIR-AANets [10]	66.74	65.29	63.50	72.55	69.22	67.60
POD-AANets [10]	66.31	64.31	62.31	76.96	75.58	71.78
w/ RMM (ours)	68.36	66.67	64.12	79.50	78.11	75.01

From Table S3, we can observe: our POD-AANets *w*/ RMM achieves the best performances using the setting that allows the memory budget to grow along with phases.

Table S3: Supplementary to Table 1. Average accuracies (%) across all phases using the growing memory budget. For the related methods [3, 5, 6, 8, 10–12, 14, 15], we directly use the results reported in their original papers.

## C More Details about Memory Budgets

This is supplementary to to Section 5.1 "Memory Budget." In Table S4, we supplement the total memory budgets and the memory budgets when we use cross-validation (i.e., all past, future, and validation data are accessible) to find the best fixed memory split between old and new class data. In every benchmark, the total budget of memory depends on the phase number N. For example, on CIFAR-100, the total memory budget is set as 7,000 samples when N=5 (7,000 samples = 10

classes/phase  $\times$  500 samples/class + 2,000 samples). Please note that 2,000 is a bounded memory budget allocated since the 0-th phase for saving exemplars.

Detect	CIFAR-100		ImageNet-Subset			ImageNet-Full			
Dataset	N=5	10	25	5	10	25	5	10	25
Total Memory Budget	7,000	4,500	3,000	15,000	8,500	4,600	 150,000	85,000	46,000
CrossVal Fixed - New CrossVal Fixed - Old	1,000 6,000	500 4,000	200 2,800	3,900 11,100	1,950 6,550	780 3,820	52,000 98,000	26,000 59,000	7,800 38,200

Table S4: Supplementary to Section 5.1 "Memory Budget." The memory budgets (i.e., the numbers of samples) for different settings. The first block shows the total memory budget, and the second block shows the memory budgets when we use cross-validation (i.e., all past, future, and validation data are accessible) to find the best fixed memory split between old and new class data.

# **D** More Ablation Results

Ablation Results in Unknown Scenarios. This is supplementary to Section 5.2 "Ablation Results." We may not know the number of incremental phases or the classes in future phases in real-world application scenarios. To evaluate the performance of our RMM in unknown scenarios, we supplemented the experiments of using the policy functions trained "in distinct numbers of phases" and "on different datasets" and show the testing results of CIFAR-100 in Table S5. It is clear in the table that even if the policy is learned in a different setting, it does not hurt much compared to the best performance achieved in the same setting (**bold**). For example, when tested on the target CIL task of "CIFAR-100, N=25", using the policy learned on "ImageNet-Subset, N=5" (66.21%, optimal), and it is 2.8 percentage points higher than the baseline (62.63%). The reason is that our RMM policy is learned on the pseudo CIL tasks synthesized in different settings, i.e., trained in a setting-agnostic manner.

No.	Method	Policy learned on	Tested on "CIFAR-100 N=5"	Tested on "CIFAR-100" N=10"	Tested on "CIFAR-100 <i>N</i> =25"
1	Baseline	-	66.61	64.61	62.63
2		"CIFAR-100, N=5"	68.86	67.53	65.70
3	w/ RMM	"CIFAR-100, N=10"	68.47	67.61	65.98
4		"CIFAR-100, N=25"	68.28	67.06	66.21
5		"ImageNet-Subset, N=5"	68.62	67.45	65.40
6	w/ RMM	"ImageNet-Subset, N=10"	68.84	67.22	65.77
7		"ImageNet-Subset, $N=25$ "	67.96	67.04	65.82

Table S5: Supplementary to Table 2. Average recognition accuracy across all phases (%). Row 1 (baseline) is from the sota method POD-AANets [25]. In Rows 2-7, we show the results for training the RMM policy on pseudo CIL tasks synthesized in one setting and evaluating the policy on the target CIL task in another setting. For example, Row 5 is for training the policy on "ImageNet-Subset, N=5" and testing it on "CIFAR-100, N=5/10/25".

Ablation Results for Transferability Properties. This is supplementary to Section 5.2 "Ablation Results." Our learning and application of RMM policy functions do not require datasets to have good transferability properties. To verify this, we supplement the experiments using a new dataset — Non-Overlapping ImageNet (NO-ImageNet) by removing any overlapping classes between ImageNet and CIFAR-100 (if several classes in ImageNet are semantically close to a class on CIFAR-100, all

of them will be removed). We learn the RMM policy on NO-ImageNet and then apply it in the CIL tasks of CIFAR-100. In Table S6, we can see the clear improvements, e.g., 2.97 percentage points on N=10 comparing "policy learned on NO-ImageNet" (67.58%) to the baseline (64.61%). The reason is that the memory allocation in RMM is realized through the meta-learned hyperparameters (using pseudo CIL tasks), and hyperparameters have been shown easier to be transferred among different tasks or datasets (than network parameters that encode detailed image patterns). We can find some similar conclusions in few-shot learning that meta-learned hyperparameters can be transferred among different few-shot tasks [9]. The experiment results on the out-of-domain datasets (e.g., stylized ImageNet-Subset [4]) are available in Table S7.

No.	Method	Policy learned on	Tested on "CIFAR-100 N=5"	Tested on "CIFAR-100" N=10"	Tested on "CIFAR-100 <i>N</i> =25"
1	Baseline	_	66.61	64.61	62.63
2	w/ RMM	CIFAR-100	68.86	67.61	66.21
3	W/ KIVIIVI	NO-ImageNet	68.59	67.58	65.23

Table S6: Average recognition accuracy across all phases (%). Row 1 (baseline) is from the sota method POD-AANets [10]. In Rows 2 and 3, we show the results for training the RMM policy on pseudo CIL tasks synthesized in one setting and evaluating the policy on the target CIL task in another setting. For example, Row 3 is for training the RMM policy on the Non-Overlapping ImageNet (NO-ImageNet) and testing it on CIFAR-100 with N=5, 10, 25 (the number of phases in training is the same as each test case).

No.	Method	Policy learned on	N=5	N = 10	N=25
1	Baseline	–	49.02	44.59	38.23
2	w/ RMM	ImageNet-Subset	53.15	50.05	42.89

Table S7: Average recognition accuracy across all phases (%) on stylized ImageNet-Subset [4]. In this dataset, the class order and data splits are the same as ImageNet-Subset [12], and the images are from stylized ImageNet [4]. Row 1 (baseline) is from the sota method POD-AANets [10]. In Row 2, we show the results for training the RMM policy on pseudo CIL tasks synthesized using ImageNet-Subset and evaluating the policy on the target CIL tasks from stylized ImageNet-Subset.

Ablation Results for Memory Budgets. This is supplementary to Section 5.2 "Ablation Results." We conduct the experiments by increasing the total memory budget from 1,000 to 4,000 and report the results in Table S8. We observe that (1) the improvement by RMM is more significant for a smaller memory budget, and (2) our RMM improves the performance by a clear margin when the memory budget is increased a lot, e.g., to 4,000. Our explanation is that the effectiveness of RMM is because it relieves the problem of data imbalance between old and new classes. If the memory budget is limited (e.g., 1,000), RMM is clearly helpful. If the memory budget increases to certain levels (e.g., 2,000 and 4,000) that the imbalance between old and new classes is still significant, RMM is also helpful. If the memory budget is unlimited, which means it can be used to store all old-class data, there is no imbalance problem anymore and thus no need to adjust the memory allocation.

**Using the Entropy for Splitting the Data in Groups.** This is supplementary to Section 5.2 "Ablation Results." The entropy is often used to measure the uncertainty of the data, e.g., for curriculum learning [1] and open set recognition [2]. We used it to split classes into two groups: (1) high-entropy classes that are more uncertain and need more exemplars; and (2) low-entropy classes that are less uncertain and need fewer exemplars. As suggested in the review, we also try prediction scores in Level-2 (Table S9), and see slightly lower performance (than using entropy), while still achieving satisfactory performance.

# **E** Additional Information

Hardware Information. We run our experiments using GPU workstations as follows,

No.	Method	Memory budget of exemplars	N=5	N=10	N=25
1	Baseline	1000	64.31	60.97	58.77
2	w/ RMM (ours)	1000	68.20	65.57	63.08
	margin		+3.9	+4.6	+4.3
3	Baseline	2000	66.61	64.61	62.63
4	w/ RMM (ours)	2000	68.86	67.61	66.21
	margin		+2.3	+3	+3.6
5	Baseline	4000	67.86	66.87	65.74
6	w/ RMM (ours)	4000	70.12	69.05	67.72
	margin		+2.3	+2.2	+2

Table S8: Supplementary to Table 2. Average recognition accuracy across all phases (%) on CIFAR-100, N=5/10/25. Row 1 (baseline) is from the sota method POD-AANets [10].

No.	Method	Tested on " $N=5$ "	Tested on "N=10"	Tested on "N=25"
1	Baseline	66.61	64.61	62.63
2	Using entropy for grouping (ours)	68.86	67.61	66.21
3	Using prediction scores for grouping	67.96	67.02	66.02

Table S9: Supplementary to Table 2. Average recognition accuracy across all phases (%) on CIFAR-100. Row 1 (baseline) is from the sota method POD-AANets [10]. In Rows 2 and 3, we show the results for using different metrics to group classes for Level-2 policy. For example, Row 3 shows the results of using prediction score for grouping classes on "CIFAR-100, N=5/10/25".

- CPU: AMD EPYC 7502P 32-Core Processor
- GPU: NVIDIA Quadro RTX 8000, 48 GB GDDR6
- Memory: 1024 GiB = 8x 128GiB, DDR4, 3200 MHz, ECC

Licenses. The code for the following papers using the MIT License: AANets [10], iCaRL [12], Mnemonics [11], and PODNet [3].

**About the Datasets.** We use two datasets in our paper: CIFAR-100 [7] and ImageNet [13]. The data for both datasets are downloaded from their official websites and allowed to use for non-commercial research and educational purposes.

# F PyTorch Code

The code is available at https://class-il.mpi-inf.mpg.de/rmm/.

**Getting Started.** To run this repository, we kindly advise you to install python 3.6 and PyTorch 1.2.0 with Anaconda. You may download Anaconda and read the installation instruction on the official website (https://www.anaconda.com/download/).

Create a new environment and install PyTorch and torchvision on it:

```
conda create --name rmm-pytorch python=3.6
conda activate rmm-pytorch
conda install pytorch=1.2.0
conda install torchvision -c pytorch
```

Install other requirements:

```
pip install PyYaml scikit-learn matplotlib pandas requests psutil tqdm
    Pillow==6.2.0
```

#### **Running experiments on CIFAR-100.**

Run the PyTorch code (data will be downloaded automatically):

python run\_exp\_cifar100.py

#### **Running experiments on ImageNet-Subset.**

Put the training data for ImageNet in:

./data/imagenet/train

Put the validation data for ImageNet in:

./data/imagenet/val

Run the PyTorch code:

python run\_exp\_imgnet.py

# **G** Checklist

- 1. For all authors...
  - (a) Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope? [Yes]
  - (b) Did you describe the limitations of your work? [Yes]
  - (c) Did you discuss any potential negative societal impacts of your work? [Yes]
  - (d) Have you read the ethics review guidelines and ensured that your paper conforms to them? [Yes]
- 2. If you are including theoretical results...
  - (a) Did you state the full set of assumptions of all theoretical results? [N/A]
  - (b) Did you include complete proofs of all theoretical results? [N/A]
- 3. If you ran experiments...
  - (a) Did you include the code, data, and instructions needed to reproduce the main experimental results (either in the supplemental material or as a URL)? [Yes] The code is available at https://class-il.mpi-inf.mpg.de/rmm/
  - (b) Did you specify all the training details (e.g., data splits, hyperparameters, how they were chosen)? [Yes] See Section 5.1 and the supplementary materials.
  - (c) Did you report error bars (e.g., with respect to the random seed after running experiments multiple times)? [Yes] See Table S2.
  - (d) Did you include the total amount of compute and the type of resources used (e.g., type of GPUs, internal cluster, or cloud provider)? [Yes] See Section E.
- 4. If you are using existing assets (e.g., code, data, models) or curating/releasing new assets...
  - (a) If your work uses existing assets, did you cite the creators? [Yes] See Section 5.1.
  - (b) Did you mention the license of the assets? [Yes] See Section E.
  - (c) Did you include any new assets either in the supplemental material or as a URL? [Yes] See Section E.
  - (d) Did you discuss whether and how consent was obtained from people whose data you're using/curating? [Yes] See Section E.

- (e) Did you discuss whether the data you are using/curating contains personally identifiable information or offensive content? [Yes] See Section E.
- 5. If you used crowdsourcing or conducted research with human subjects...
  - (a) Did you include the full text of instructions given to participants and screenshots, if applicable? [N/A]
  - (b) Did you describe any potential participant risks, with links to Institutional Review Board (IRB) approvals, if applicable? [N/A]
  - (c) Did you include the estimated hourly wage paid to participants and the total amount spent on participant compensation? [N/A]

## References

- Yoshua Bengio, Jérôme Louradour, Ronan Collobert, and Jason Weston. Curriculum learning. In *ICML*, pages 41–48, 2009.
- [2] Akshay Raj Dhamija, Manuel Günther, and Terrance E Boult. Reducing network agnostophobia. In *NeurIPS*, 2018.
- [3] Arthur Douillard, Matthieu Cord, Charles Ollion, Thomas Robert, and Eduardo Valle. Podnet: Pooled outputs distillation for small-tasks incremental learning. In *ECCV*, 2020.
- [4] Robert Geirhos, Patricia Rubisch, Claudio Michaelis, Matthias Bethge, Felix A. Wichmann, and Wieland Brendel. Imagenet-trained cnns are biased towards texture; increasing shape bias improves accuracy and robustness. In *ICLR*, 2019.
- [5] Saihui Hou, Xinyu Pan, Chen Change Loy, Zilei Wang, and Dahua Lin. Learning a unified classifier incrementally via rebalancing. In CVPR, pages 831–839, 2019.
- [6] Xinting Hu, Kaihua Tang, Chunyan Miao, Xian-Sheng Hua, and Hanwang Zhang. Distilling causal effect of data in class-incremental learning. In *CVPR*, 2021.
- [7] Alex Krizhevsky, Geoffrey Hinton, et al. Learning multiple layers of features from tiny images. Technical report, Citeseer, 2009.
- [8] Zhizhong Li and Derek Hoiem. Learning without forgetting. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 40(12):2935–2947, 2018.
- [9] Yaoyao Liu, Bernt Schiele, and Qianru Sun. An ensemble of epoch-wise empirical bayes for few-shot learning. In *ECCV*, pages 404–421. Springer, 2020.
- [10] Yaoyao Liu, Bernt Schiele, and Qianru Sun. Adaptive aggregation networks for classincremental learning. In CVPR, 2021.
- [11] Yaoyao Liu, Yuting Su, An-An Liu, Bernt Schiele, and Qianru Sun. Mnemonics training: Multi-class incremental learning without forgetting. In CVPR, pages 12245–12254, 2020.
- [12] Sylvestre-Alvise Rebuffi, Alexander Kolesnikov, Georg Sperl, and Christoph H Lampert. iCaRL: Incremental classifier and representation learning. In *CVPR*, pages 5533–5542, 2017.
- [13] Olga Russakovsky, Jia Deng, Hao Su, Jonathan Krause, Sanjeev Satheesh, Sean Ma, Zhiheng Huang, Andrej Karpathy, Aditya Khosla, Michael Bernstein, et al. Imagenet large scale visual recognition challenge. *International Journal of Computer Vision*, 115(3):211–252, 2015.
- [14] Xiaoyu Tao, Xinyuan Chang, Xiaopeng Hong, Xing Wei, and Yihong Gong. Topologypreserving class-incremental learning. In ECCV, 2020.
- [15] Yue Wu, Yinpeng Chen, Lijuan Wang, Yuancheng Ye, Zicheng Liu, Yandong Guo, and Yun Fu. Large scale incremental learning. In *CVPR*, pages 374–382, 2019.