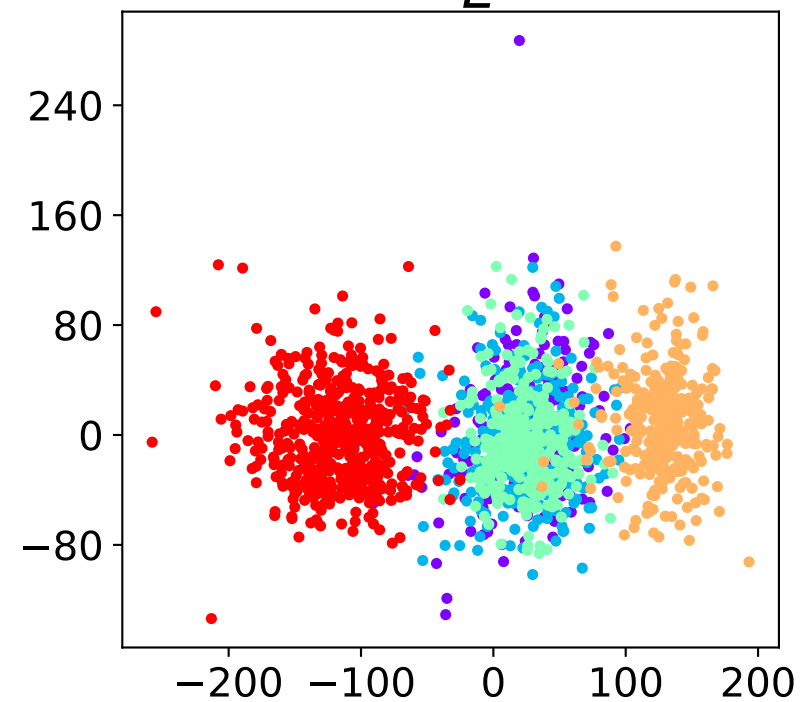
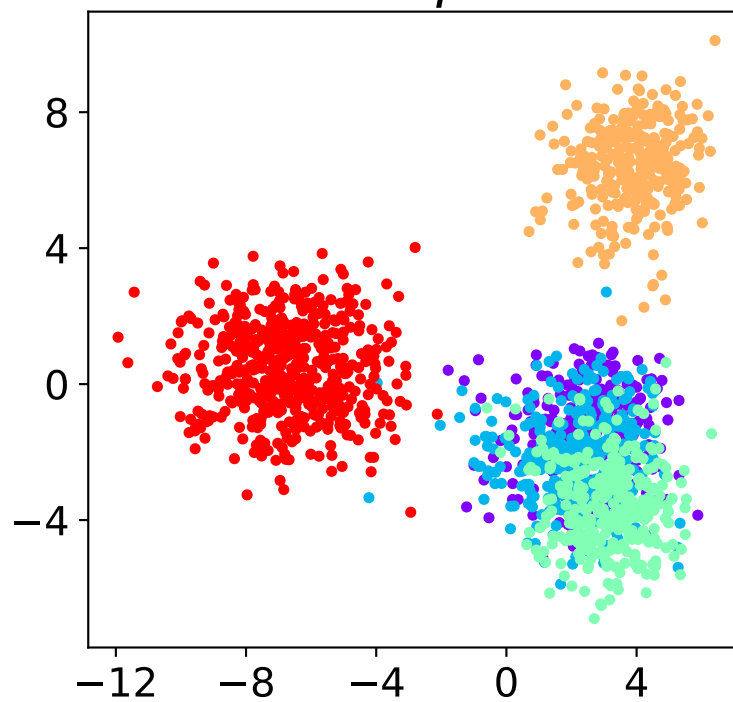
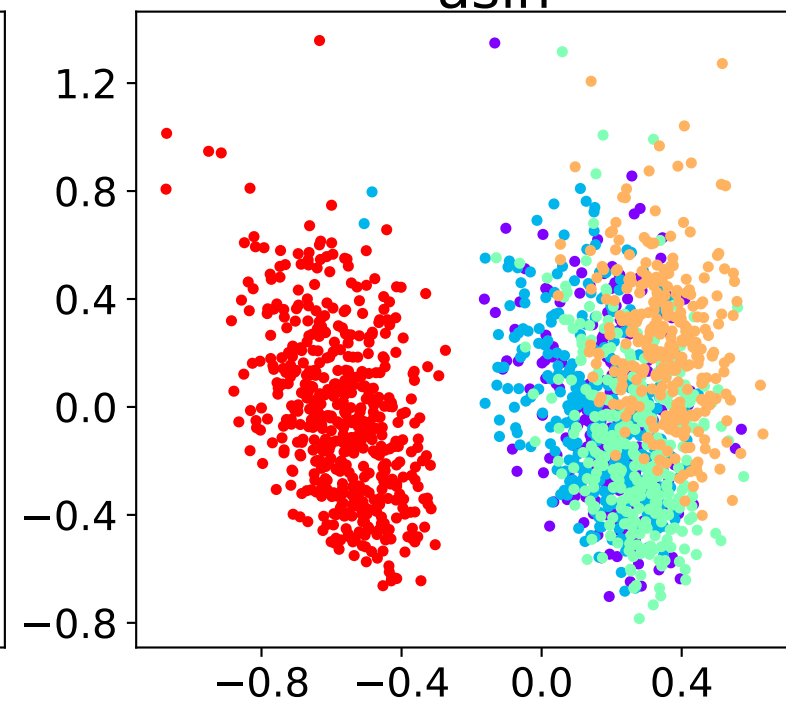
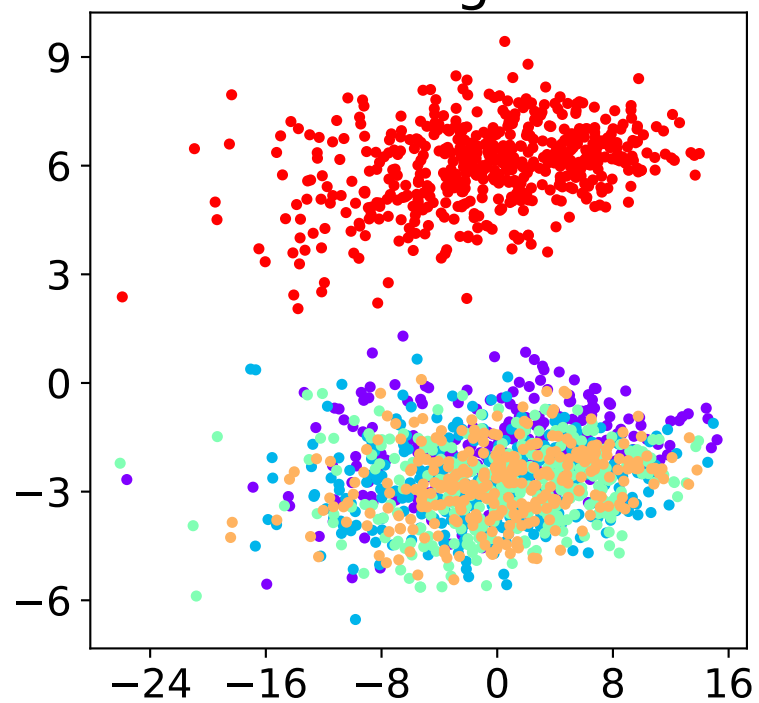
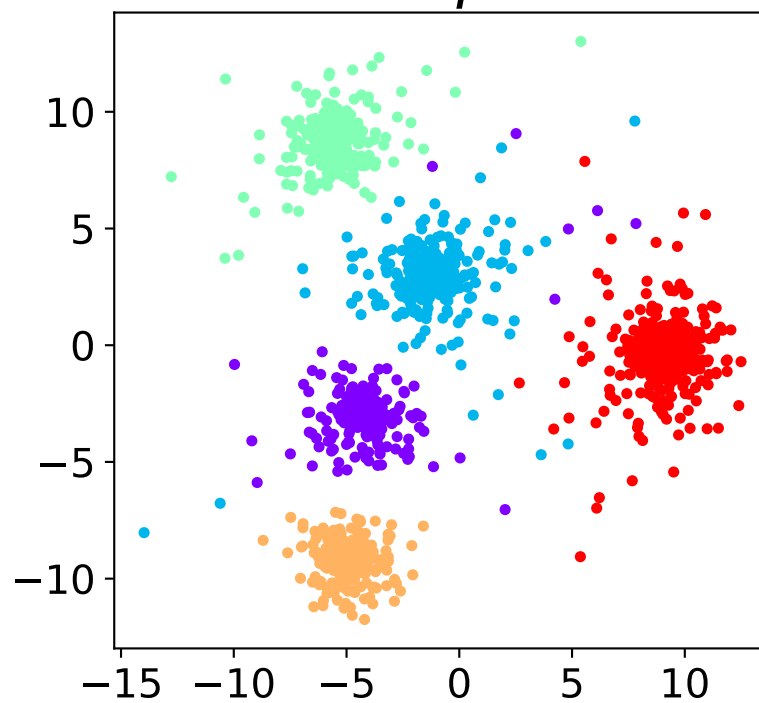


$D_E$  $D_r$  $D_{\text{asin}}$  $D_{\log}$  $D_P$  $D_{NB}$ 