



- Joint Max-margin Direction
- Joint Training trajectory
- Continual Learning trajectory
- Task 0 Data ($y = +1$)
- × Task 0 Data ($y = -1$)
- Task 1 Data ($y = +1$)
- × Task 1 Data ($y = -1$)
- Task 2 Data ($y = +1$)
- × Task 2 Data ($y = -1$)