A Proofs

Lemma 1. Assume that Assumptions $\boxed{1}$ and $\boxed{2}$ hold, the iterations satisfy the following inequality for all $k \in \mathbb{N}$:

$$\mathbb{E}_{\xi_{k}}[F(W_{k+1}, H_{k+1})] - F(W_{k}, H_{k}) \leq -(\mu - \frac{1}{2}\alpha_{k}LM_{G})\alpha_{k}[\|\nabla F_{W}(W_{k}, H_{k})\|_{2}^{2} + \|\nabla F_{H}(W_{k}, H_{k})\|_{2}^{2}] + \alpha_{k}^{2}LM.$$
(A.1)

$$\begin{split} &Proof. \ \ \text{Under Assumption} \ \overline{\mathbb{I}}, \text{ for any } \{W, \widetilde{W}\} \in \mathbb{R}^d_1 \text{ and } \{H, \widetilde{H}\} \in \mathbb{R}^d_2, \text{ one obtains} \\ &F(W, H) - F(\widetilde{W}, \widetilde{H}) = \left(F(W, H) - F(\widetilde{W}, H)\right) + \left(F(\widetilde{W}, H) - F(\widetilde{W}, \widetilde{H})\right) \\ &= \int_0^1 \frac{\partial F\left(\widetilde{W} + t(W - \widetilde{W}), H\right)}{\partial t} dt + \int_0^1 \frac{\partial F\left(\widetilde{W}, \widetilde{H} + t(H - \widetilde{H})\right)}{\partial t} dt \\ &= \int_0^1 \nabla F_W\left(\widetilde{W} + t(W - \widetilde{W}), H\right)^T(W - \widetilde{W}) dt + \int_0^1 \nabla F_H\left(\widetilde{W}, \widetilde{H} + t(H - \widetilde{H})\right)^T(H - \widetilde{H}) dt \\ &= \nabla F_W(\widetilde{W}, H)^T(W - \widetilde{W}) + \int_0^1 \left[\nabla F_W(\widetilde{W} + t(W - \widetilde{W}), H) - \nabla F_W(\widetilde{W}, H)\right]^T(W - \widetilde{W}) dt \\ &+ \nabla F_H(\widetilde{W}, \widetilde{H})^T(H - \widetilde{H}) + \int_0^1 \left[\nabla F_H(\widetilde{W}, \widetilde{H} + t(H - \widetilde{H})) - \nabla F_H(\widetilde{W}, \widetilde{H})\right]^T(H - \widetilde{H}) dt \\ &\leq \nabla F_W(\widetilde{W}, H)^T(W - \widetilde{W}) + \int_0^1 L \|t(W - \widetilde{W})\|_2 \|W - \widetilde{W}\|_2 dt \\ &+ \nabla F_H(\widetilde{W}, \widetilde{H})^T(H - \widetilde{H}) + \int_0^1 L \|t(H - \widetilde{H})\|_2 \|H - \widetilde{H}\|_2 dt \\ &\leq \nabla F_W(\widetilde{W}, H)^T(W - \widetilde{W}) + \nabla F_H(\widetilde{W}, \widetilde{H})^T(H - \widetilde{H}) + \frac{1}{2} L (\|W - \widetilde{W})\|_2^2 + \|H - \widetilde{H}\|_2^2). \end{split}$$

Therefore, the iterations generated by stochastic gradient algorithm satisfy

$$F(W_{k+1}, H_{k+1}) - F(W_k, H_k) \leq \nabla F_W(W_k, H_{k+1})^T (W_{k+1} - W_k) + \frac{1}{2} L \|W_{k+1} - W_k\|_2^2$$

$$+ \nabla F_H(W_k, H_k)^T (H_{k+1} - H_k) + \frac{1}{2} L \|H_{k+1} - H_k\|_2^2$$

$$\leq -\alpha_k \nabla F_W(W_k, H_{k+1})^T g(W_k, H_k; \xi_k) + \frac{1}{2} \alpha_k^2 L \|g(W_k, H_k; \xi_k)\|_2^2$$

$$- \alpha_k \nabla F_H(W_k, H_k)^T q(W_k, H_k; \xi_k) + \frac{1}{2} \alpha_k^2 L \|g(W_k, H_k; \xi_k)\|_2^2.$$

Taking expectations in these inequalities with respect to the distribution of ξ_k , and noting that (W_{k+1}, H_{k+1}) —but not (W_k, H_k) —depends on ξ_k , we obtain

$$\begin{split} \mathbb{E}_{\xi_{k}}[F(W_{k+1}, H_{k+1})] - F(W_{k}, H_{k}) &\leq -\alpha_{k} \nabla F_{W}(W_{k}, H_{k+1})^{T} \mathbb{E}_{\xi_{k}}[g(W_{k}, H_{k}; \xi_{k})] \\ &- \alpha_{k} \nabla F_{H}(W_{k}, H_{k})^{T} \mathbb{E}_{\xi_{k}}[q(W_{k}, H_{k}; \xi_{k})] \\ &+ \frac{1}{2} \alpha_{k}^{2} L \mathbb{E}_{\xi_{k}} \left[\|g(W_{k}, H_{k}; \xi_{k})\|_{2}^{2} \right] + \frac{1}{2} \alpha_{k}^{2} L \mathbb{E}_{\xi_{k}} \left[\|q(W_{k}, H_{k}; \xi_{k})\|_{2}^{2} \right] \end{split}$$

Combine Assumption 2 with Definition 4.6 we have the second moment of $g(W_k, H_k; \xi_k)$ and $g(W_k, H_k; \xi_k)$ satisfy

$$\mathbb{E}_{\xi_k} [\|g(W_k, H_k; \xi_k)\|_2^2] \le M + M_G \|\nabla F_W(W_k, H_k)\|_2^2,$$

$$\mathbb{E}_{\xi_k} [\|g(W_k, H_k; \xi_k)\|_2^2] \le M + M_G \|\nabla F_H(W_k, H_k)\|_2^2, \quad with \ M_G := M_V + \mu_G^2 \ge \mu^2 > 0.$$

Therefore we have

$$\begin{split} \mathbb{E}_{\xi_{k}} \left[F(W_{k+1}, H_{k+1}) \right] - F(W_{k}, H_{k}) &\leq -\mu \alpha_{k} \left[\| \nabla F_{W}(W_{k}, H_{k}) \|_{2}^{2} + \| \nabla F_{H}(W_{k}, H_{k}) \|_{2}^{2} \right] \\ &+ \frac{1}{2} \alpha_{k}^{2} L \left[M + M_{G} \left(\| \nabla F_{W}(W_{k}, H_{k}) \|_{2}^{2} + \| \nabla F_{H}(W_{k}, H_{k}) \|_{2}^{2} \right) \right] \\ &\leq - \left(\mu - \frac{1}{2} \alpha_{k} L M_{G} \right) \alpha_{k} \left[\| \nabla F_{W}(W_{k}, H_{k}) \|_{2}^{2} + \| \nabla F_{H}(W_{k}, H_{k}) \|_{2}^{2} \right] \\ &+ \alpha_{k}^{2} L M. \end{split}$$

Proof of Theorem 1

Proof. Taking the total expectation of Eq. A.1 and from the condition of $0 < \bar{\alpha} \le \frac{\mu}{LM_G}$,

$$\mathbb{E}[F(W_{k+1}, H_{k+1})] - \mathbb{E}[F(W_k, H_k)] \le -(\mu - \frac{1}{2}\bar{\alpha}LM_G)\bar{\alpha}\mathbb{E}[\|\nabla F(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] + \bar{\alpha}^2LM$$

$$\le -\frac{1}{2}\mu\bar{\alpha}\mathbb{E}[\|\nabla F_W(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] + \bar{\alpha}^2LM.$$

Summing both sides of this inequality for $k \in \{1, ..., K\}$ and recalling Assumption 2 (a) gives

$$F_{inf} - F(W_1, H_1) \le \mathbb{E}[F(W_{K+1}, H_{K+1})] - F(W_1)$$

$$\le -\frac{1}{2}\mu\bar{\alpha} \sum_{k=1}^{K} \mathbb{E}[\|\nabla F_W(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] + K\bar{\alpha}^2 LM.$$

Rearranging above inequality and dividing further by K yields the result.

Proof of Theorem 2

Proof. The second condition in Eq. 4.10 ensures that $\lim_{k\to\infty}\alpha_k=0$, meaning that without loss of generality, we may assume that $\alpha_k LM_G\leq \mu$ for all $k\in\mathbb{N}$. Taking the total expectation of Eq. A.1, we obtain

$$\mathbb{E}[F(W_{k+1}, H_{k+1})] - \mathbb{E}[F(W_k, H_k)] \le -(\mu - \frac{1}{2}\bar{\alpha}LM_G)\bar{\alpha}\mathbb{E}[\|\nabla F(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2]$$

$$\le -\frac{1}{2}\mu\alpha_k\mathbb{E}[\|\nabla F_W(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] + \alpha_k^2LM.$$

Summing both sides of this inequality for $k \in \{1, ..., K\}$ and recalling Assumption 2(a) gives

$$F_{inf} - F(W_1, H_1) \leq \mathbb{E}[F(W_{K+1}, H_{K+1})] - F(W_1, H_1)$$

$$\leq -\frac{1}{2}\mu \sum_{k=1}^{K} \alpha_k \mathbb{E}[\|\nabla F_W(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] + LM \sum_{k=1}^{K} \alpha_k^2.$$

Rearranging the above inequality and dividing further by $\mu/2$, we obtain

$$\sum_{k=1}^{K} \alpha_k \mathbb{E}[\|\nabla F(W_k, H_k)\|_2^2 + \|\nabla F_H(W_k, H_k)\|_2^2] \le \frac{2(F(W_1, H_1) - F_{inf})}{\mu} + \frac{2LM}{\mu} \sum_{k=1}^{K} \alpha_k^2.$$

Then, we get the desired result by dividing A_k on the both sides.

B Sufficient Direction Constant

Assumption 2(b) states that, in expectation, the vectors $g(W_k, H_k; \xi_k)$ and $q(W_k, H_k; \xi_k)$ are sufficient descent directions for F from W_k and H_k with norms comparable to the norms of the gradients. It guarantees that the model moves towards the descending direction of the loss function. Following the experimental setup in Section 5.1 we demonstrate that the proposed method empirically satisfies Assumption 2(b), and visualize in Figure 7 the sufficient direction constant μ for the (partial) convolutional layers of the four models during the end-to-end training using TREC. For SqueezeNet and ResNet-34, we show one block as the representative, since the other blocks have similar performance.

Several insights can be drawn from Figure 7 (i) The value of μ of each convolutional layer is consistently greater than zero, indicating that Assumption 2(b) is satisfied, further ensuring the convergence of the TREC-equipped CNNs. (ii) The lower convolutional layers have smaller μ compared to the upper ones. (iii) The value of μ gradually increases through iterations. In fact, the

closer μ is to 1, the more the model moves toward the sufficient direction. Thus the gap between μ and 1 reflects the difference between the current descent direction of the model and the steepest descent direction [14]. The smaller values of μ in the lower convolutional layers in the early epochs indicate a larger difference in the descent direction. It is because the guidance obtained from the loss in the lower convolutinoal layers comes from back-propagation, which accumulates the disparities. Small μ values in the early epochs help the model avoid being trapped in local minimums, while large μ values in the later epochs help the model converge.

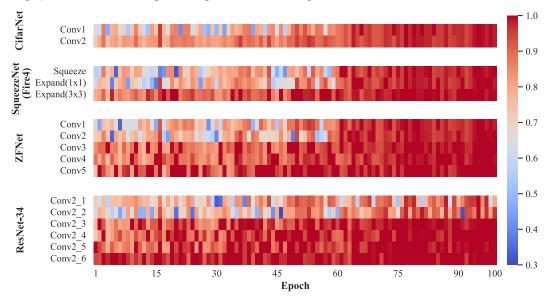


Figure 7: Sufficient direction constant μ .

C Single-Layer Performance

C.1 Single-Layer Performance Benefits

Table 3: Single-layer performance benefits. Conf. means configuration, L is the width of submatrices, H is the number of hash functions, r_t represents the redundancy ratio, and Δ Acc is the accuracy difference.

Network	Layer	Coı	nf. H	r_t	Speedup	$\Delta Acc.$ (vs. Conventional)	ΔAcc. (vs. Deep Reuse)
CifarNet	Conv1	5	15	0.9429	1.81×	-0.0132	0.0428
	Conv2	10	10	0.7947	$1.52 \times$	-0.0077	0.0316
Average				0.8688	1.66×	-0.0105	0.0372
ZfNet	Conv1	147	5	0.9997	1.22×	-0.0011	0.0457
	Conv2	300	5	0.9967	$4.69 \times$	-0.0037	0.0319
	Conv3	432	5	0.9884	$4.72 \times$	-0.0076	0.0389
	Conv4	432	5	0.9982	$6.23 \times$	-0.0105	0.0228
	Conv5	288	5	0.9842	$5.58 \times$	-0.0068	0.0311
Average				0.9934	4.49×	-0.0059	0.0341
Vanilla SqueezeNet	Conv1	9	5	0.9969	1.27×	-0.0066	0.0311
	Fire2 - squeeze	96	4	0.9922	$1.02 \times$	-0.0179	0.0310
	Fire2 - 1×1 expand	8	5	0.9934	$4.61 \times$	0.0006	0.0233
	Fire2 - 3×3 expand	48	5	0.9875	$6.04 \times$	0.0040	0.0182
	Fire3 - squeeze	64	4	0.9877	$1.30 \times$	0.0029	0.0138
	Fire3 - 1×1 expand	8	5	0.9932	$4.51 \times$	0.0055	0.0132
	Fire3 - 3×3 expand	72	5	0.9876	$6.43 \times$	0.0029	0.0138
	Fire4 - squeeze	64	4	0.9980	$1.07 \times$	-0.0062	0.0337
	Fire4 - 1×1 expand	16	5	0.9879	$3.61 \times$	0.0037	0.0240

Network	Layer	Cor	nf. H	r_t	Speedup	$\Delta Acc.$ (vs. Conventional)	ΔAcc. (vs. Deep Reuse)
	Fire4 - 3×3 expand	144	5	0.9877	5.86×	0.0035	0.0289
	Fire5 - squeeze	128	4	0.9844	$1.05 \times$	0.0001	0.0139
Vanilla SqueezeNet	Fire5 - 1×1 expand	4	5	0.9906	$4.96 \times$	-0.0009	0.0151
	Fire5 - 3×3 expand	144	5	0.9500	$3.25 \times$	-0.0064	0.0162
	Fire6 - squeeze	32	5	0.9598	$1.78 \times$	-0.0008	0.1935
	Fire6 - 1×1 expand	6	5	0.9736	$2.84 \times$	0.0064	0.0213
	Fire6 - 3×3 expand	54	5	0.9504	$16.06 \times$	-0.0078	0.0159
	Fire7 - squeeze	48	5	0.9600	$1.39 \times$	-0.0023	0.0146
	Fire7 - 1×1 expand	6	5	0.9754	$2.67 \times$	0.0049	0.0224
	Fire7 - 3×3 expand	216	5	0.9523	$16.95 \times$	-0.0052	0.0105
	Fire8 - squeeze	8	5	0.9784	$1.39 \times$	-0.0063	0.0805
	Fire8 - 1×1 expand	4	5	0.9710	$4.31 \times$	0.0065	0.0224
	Fire8 - 3×3 expand	288	5	0.9500	$18.66 \times$	-0.0042	0.0127
	Fire9 - squeeze	256	5	0.9250	$1.07 \times$	0.0062	0.2365
	Fire9 - 1×1 expand	8	5	0.8563	$1.10 \times$	0.0037	0.0201
	Fire9 - 3×3 expand	288	5	0.8156	$12.63 \times$	0.0058	0.0148
	Conv10	4	5	0.9235	$1.32 \times$	-0.0084	0.1901
Average				0.9626	4.89×	-0.0006	0.0435
	Conv1	9	5	0.9969	1.27×	0.0122	0.0783
	Fire2 - squeeze	96	4	0.9926	$1.07 \times$	0.0144	0.0559
	Fire2 - 1×1 expand	8	5	0.9914	$1.41 \times$	0.0023	0.0149
	Fire2 - 3×3 expand	48	5	0.9897	$5.90 \times$	0.0002	0.0156
	Bypass1 - 1×1	32	5	0.9940	2.45×	0.0071	0.0232
	Fire3 - squeeze	64	4	0.9877	1.07×	-0.0051	0.0145
	Fire3 - 1×1 expand	8	5	0.9918	2.30×	-0.0033	0.0167
	Fire3 - 3×3 expand	24	5	0.9876	5.85×	-0.0013	0.0222
	Fire4 - squeeze	64	5	0.9895	1.00×	-0.0040	0.0162
	Fire4 - 1×1 expand	16	5	0.9881	1.45×	-0.0037	0.0102
	Fire4 - 3×3 expand	48	5	0.9876	6.36×	0.0012	0.0254
	Bypass2 - 1×1	4	8	0.9933	$2.53\times$	-0.0012	0.0277
	Fire5 - squeeze	64	4	0.9824	1.84×	-0.0012	0.0188
	Fire5 - squeeze Fire5 - 1×1 expand	16	5	0.9524	4.51×	0.0016	0.0163
SqueezeNet +	Fire5 - 1×1 expand Fire5 - 3×3 expand	48	5	0.9531	11.83×	0.0010	0.0103
		128	5	0.9342	1.01×	-0.001	0.0213
Complex Bypass	Fire6 - squeeze		5	0.9719			
	Fire6 - 1×1 expand	32			4.40×	-0.0071	0.0189
	Fire6 - 3×3 expand	72	5	0.9534	12.50×	0.0002	0.0242
	Bypass3 - 1×1	32	5	0.9768	5.29×	0.0021	0.0192
	Fire7 - squeeze	48	5	0.9648	1.71×	0.0003	0.0257
	Fire 7 - 1×1 expand	24	5	0.9570	4.00×	-0.0046	0.0265
	Fire 7 - 3×3 expand	48	5	0.9531	9.36×	-0.0025	0.0357
	Fire8 - squeeze	64	4	0.9685	1.03×	-0.0003	0.0299
	Fire8 - 1×1 expand	16	5	0.9645	$2.15\times$	0.0012	0.0164
	Fire8 - 3×3 expand	64	5	0.9550	7.57×	-0.0022	0.0188
	Bypass4 - 1×1	128	5	0.9609	1.12×	-0.0045	0.0385
	Fire9 - squeeze	128	4	0.8938	1.01×	-0.0078	0.0138
	Fire $9 - 1 \times 1$ expand	16	5	0.8391	1.53×	-0.0019	0.0188
	Fire9 - 3×3 expand	96	5	0.8406	11.64×	-0.0022	0.0235
	Conv10	4	5	0.9438	1.29×	0.0057	0.0326
Average				0.9629	3.88×	-0.0003	0.0249
ResNet	Conv1	25	5	0.8396	7.64×	-0.00063	0.0236
	Conv2-1	144	5	0.9942	$7.69 \times$	-0.0010	0.0353
	Conv2-2	144	5	0.9876	$7.99 \times$	-0.0002	0.0255
			5	0.9919	$7.80 \times$	-0.0027	0.0455
	Conv2-3	144					
$(ImageNet-64\times64)$	Conv2-3 Conv2-4	144	5	0.9880	$7.98 \times$	0.0008	0.0301
	Conv2-3						

Network	Layer	Cor	nf. H	$-r_t$	Speedup	Δ Acc. (vs. Conventional)	ΔAcc. (vs. Deep Reuse)
ResNet	Conv3-1	144	5	0.9510	6.75×	-0.0030	0.0250
	Conv3-2	144	5	0.9579	$7.18 \times$	-0.0044	0.0169
	Conv3-3	144	5	0.9500	$6.87 \times$	-0.0007	0.0302
	Conv3-4	144	5	0.9537	$7.02 \times$	-0.0045	0.0190
	Conv3-5	144	5	0.9528	$6.98 \times$	-0.0008	0.0398
	Conv3-6	144	5	0.9554	$7.09 \times$	-0.0023	0.0229
	Conv3-7	144	5	0.9557	$7.10 \times$	0.0028	0.0262
	Conv3-8	144	5	0.995	$7.49 \times$	-0.0011	0.0195
	Conv4-1	288	5	0.9815	$1.88 \times$	-0.0003	0.0386
	Conv4-2	72	5	0.9802	$2.99 \times$	-0.0036	0.0330
	Conv4-3	72	5	0.9804	$3.00 \times$	-0.0022	0.0168
	Conv4-4	72	5	0.9802	$2.99 \times$	-0.0002	0.0515
	Conv4-5	72	5	0.9800	$2.99 \times$	-0.0015	0.0275
$(ImageNet-64\times64)$	Conv4-6	72	5	0.9802	$2.99 \times$	-0.0009	0.0607
	Conv4-7	72	5	0.9812	$3.01 \times$	-0.0002	0.0311
	Conv4-8	72	5	0.9800	$2.99 \times$	0.0001	0.0376
	Conv4-9	72	5	0.9803	$3.00 \times$	0.0001	0.0196
	Conv4-10	72	5	0.9804	$3.00 \times$	-0.0010	0.0427
	Conv4-11	72	5	0.9838	$3.06 \times$	-0.0009	0.0500
	Conv4-12	72	5	0.9800	$2.99 \times$	-0.0013	0.0271
	Conv5-1	36	5	0.9279	$1.54 \times$	-0.0023	0.0506
	Conv5-2	114	5	0.9239	$1.20 \times$	0.0005	0.0327
	Conv5-3	96	5	0.973	$1.01 \times$	-0.0011	0.0242
	Conv5-4	96	5	0.925	$1.01 \times$	-0.0023	0.0441
	Conv5-5	96	5	0.93	$1.04 \times$	-0.0007	0.0180
	Conv5-6	96	5	0.9268	$1.01 \times$	-0.0011	0.0420
Average				0.9630	4.64×	-0.0013	0.0326

C.2 Sensitivity Study: Performance on Varying Batch Sizes

In this section, we perform an analysis of the impact of batch size on TREC inference performance. Due to the stringent memory limit of MCU, it is infeasible to run the inferences on larger batch sizes. We hence use servers for this experiment and focus on the amount of avoided redundancy. We visualize in Figure 8 the impact of batch size on the average redundancy ratio (r_t) , the larger the more redundancy is avoided. It can be seen that as batch sizes increase, the redundancy ratios also increase. It is intuitive: A larger batch increases the number of neuron vectors in the input matrix, and hence increases the possibility for reusing the results. This suggests that TREC can bring in more computational savings at larger batch sizes.

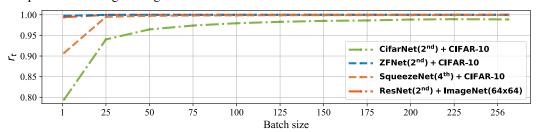


Figure 8: The impact of batch size on remaining ratio(r_t).