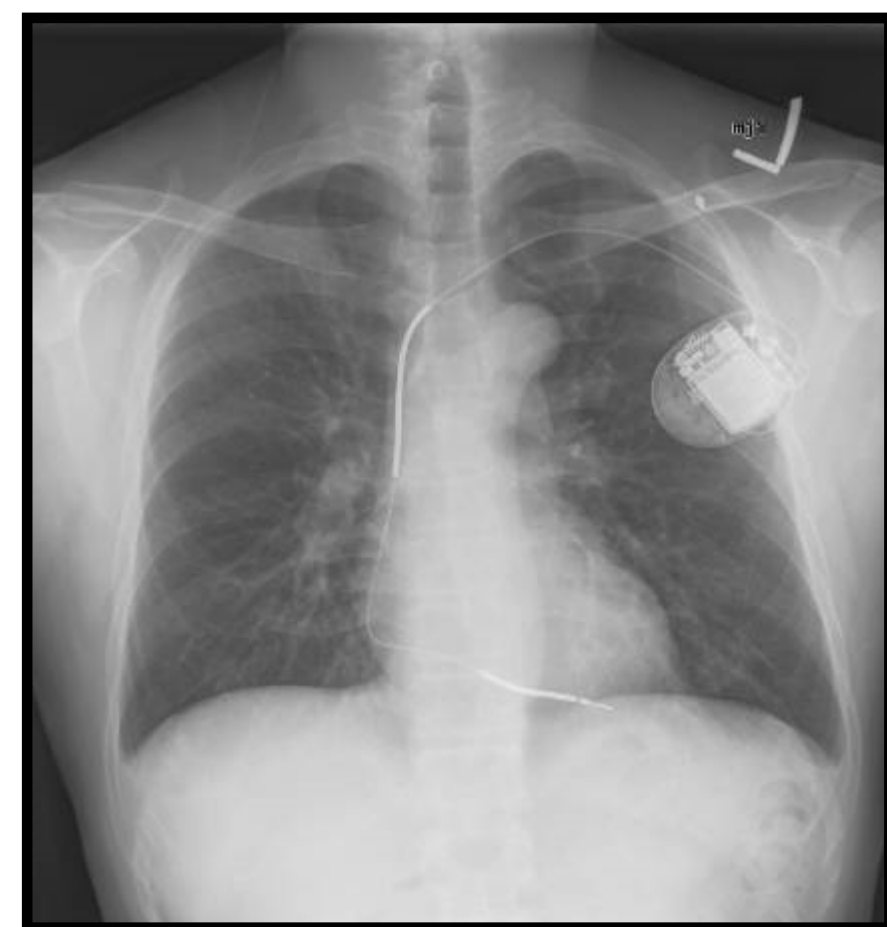
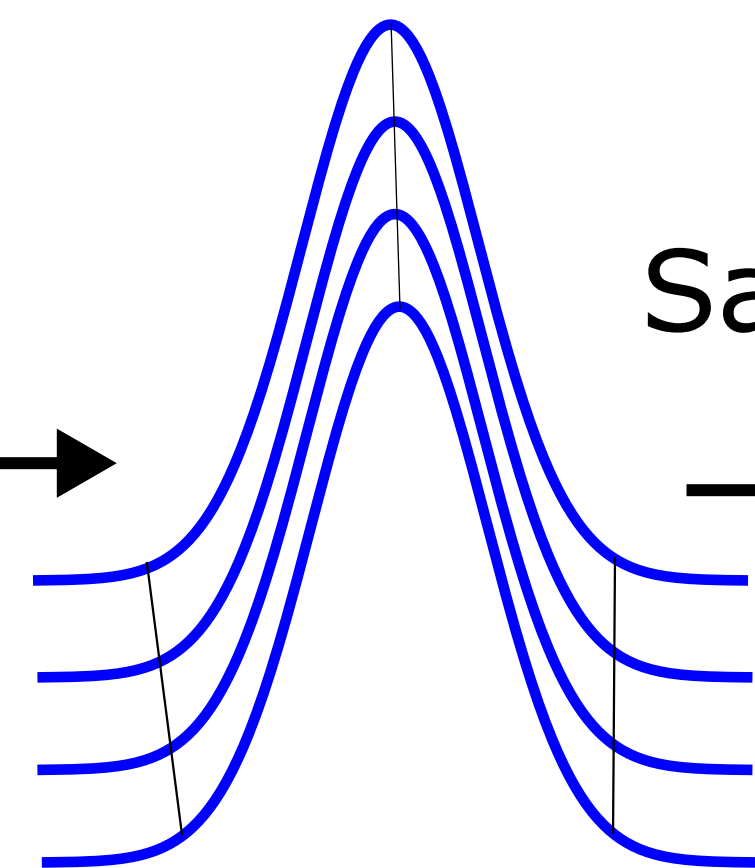
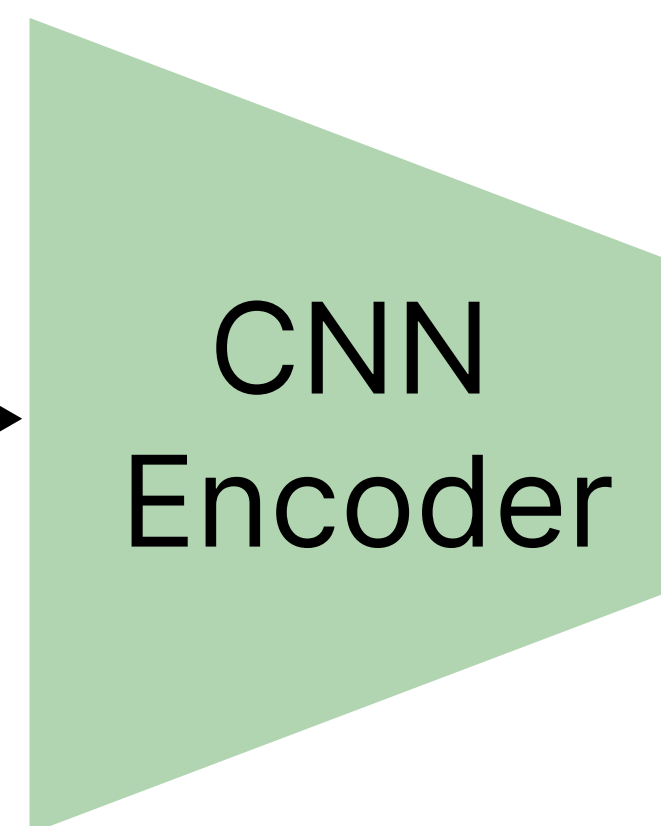


## Input Image



## Latent Uncertainty

$$\mathbf{z} \sim \mathcal{N}(\mu, \sigma^2)$$

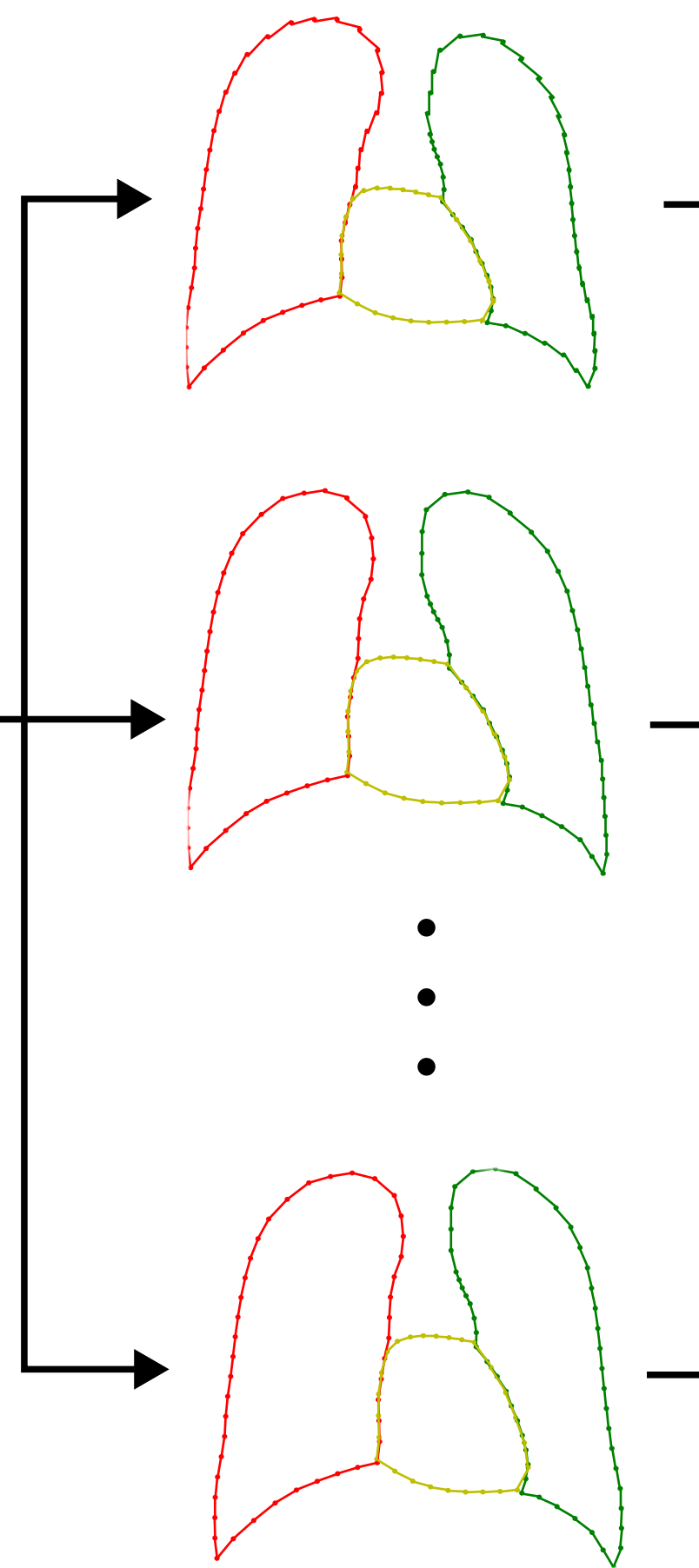


Latent space

Sampling



## Landmark-based Segmentations



## Node-wise Predictive Uncertainty

