(a) Ref1: PET   (b) Ref2: T1   (c) Ref3: Flair   (d) Ref4: CT

(e) Flo1: T1   (f) Flo2: Flair   (g) Flo3: CT   (h) Flo4: PET

(i) GT1: T1   (j) GT2: Flair   (k) GT3: CT   (l) GT4: PET

Fig. 4: Sample slices of 3D image pairs from the evaluation dataset generated from the CERMEP-IDB-MRXFDG dataset [9]. (a-d) the reference (transformed) images and (e-h) the floating images. Image (e) is to be registered to (a); (f) to (b), (g) to (c) and (h) to (d). The bottom row shows the ground-truth (GT) of each floating (Flo) image aligned to the corresponding reference (Ref) image.