

Table 1: We evaluate reconstruction accuracy for "challenge" tasks that come from concepts / categories not present in the target training set. For both layout and 3D CSG, we observe that our joint paradigm that integrates an edit network with *one-shot* models outperforms the alternative of using only *one-shot* models.

	Layout <i>cIoU</i> \uparrow	3D CSG <i>IoU</i> \uparrow
<i>OS Only</i>	75.8	60.8
<i>OS + Edit (Ours)</i>	87.6	70.9

Method	Chamfer Distance \downarrow
<i>Ours (default)</i>	0.111
<i>No FT</i>	0.321
<i>No one-shot FT</i>	0.230
<i>No edit FT</i>	0.123
<i>No edit PT</i>	0.145

Figure 1: We extend the ablation study from our main submission and evaluate how a subset of these conditions performs on the 2D CSG domain.

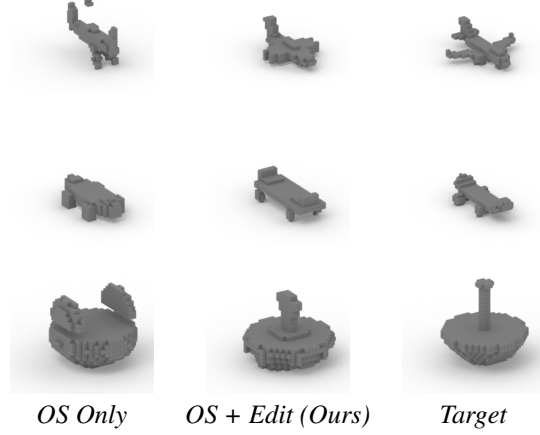


Figure 2: Qualitative reconstructions of "challenge" tasks for the 3D CSG domain.

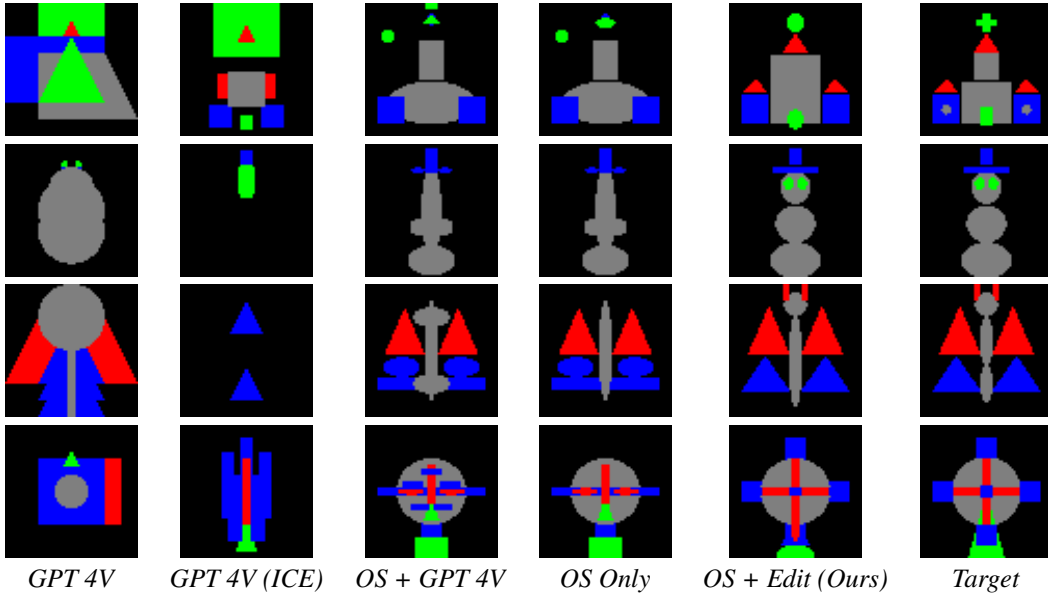


Figure 3: Qualitative reconstructions of "challenge" tasks for the layout domain. We compare against GPT-4V in a zero-shot setting (column 1), when an in-content example (ICE) is provided in the prompt (column 2), and when the one-shot model's predicted program is provided as input (column 3). Our approach (column 5) finds more accurate reconstructions of these out-of-distribution targets (column 6) compared with using only the one-shot network (column 4).