THE ASYMPTOTIC SPECTRUM OF THE HESSIAN OF DNN THROUGHOUT TRAINING

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Abstract

The dynamics of DNNs during gradient descent is described by the so-called Neural Tangent Kernel (NTK). In this article, we show that the NTK allows one to gain precise insight into the Hessian of the cost of DNNs: we obtain a full characterization of the asymptotics of the spectrum of the Hessian, at initialization and during training.

1. Introduction

The advent of deep learning has sparked a lot of interest in the loss surface of deep neural networks (DNN), and in particular its Hessian. However to our knowledge, there is still no theoretical description of the spectrum of the Hessian. Nevertheless a number of phenomena have been observed numerically.

The loss surface of neural networks has been compared to the energy landscape of different physical models Choromanska et al. (2015); Geiger et al. (2018); Mei et al. (2018). It appears that the loss surface of DNNs may change significantly depending on the width of the network (the number of neurons in the hidden layer), motivating the distinction between the underand over-parametrized regimes Baity-Jesi et al. (2018); Geiger et al. (2018; 2019).

The non-convexity of the loss function implies the existence of a very large number of saddle points, which could slow down training. In particular, in Pascanu et al. (2014); Dauphin et al. (2014), a relation between the rank of saddle points (the number of negative eigenvalues of the Hessian) and their loss has been observed.

For overparametrized DNNs, a possibly more important phenomenon is the large number of flat directions Baity-Jesi et al. (2018). The existence of these flat minima is conjectured to be related to the generalization of DNNs and may depend on the training procedure Hochreiter & Schmidhuber (1997); Chaudhari et al. (2016); Wu et al. (2017).

Recent results have obtained strong convergence guarantees for shallow networks Rotskoff & Vanden-Eijnden (2018); Chizat & Bach (2018a); Mei et al. (2018) and also for deep networks in the over-parametrized regime Jacot et al. (2018); Du et al. (2019); Allen-Zhu et al. (2018).

In Jacot et al. (2018) it has been shown, using a functional approach, that in the infinite width-limit, DNNs behave like kernel methods with respect to the so-called Neural Tangent Kernel, which is determined by the architecture of the network. This strengthens the connections between neural networks and kernel methods Neal (1996); Cho & Saul (2009); Lee et al. (2018).

This raises the question: can we use these new results to gain insight into the behavior of the Hessian of the loss of DNNs, at least in the small region explored by the parameters during training?

1.1. Contributions

Following ideas introduced in Jacot et al. (2018), we consider the training of L+1-layered DNNs in a functional setting. For a functional cost C, the Hessian of the loss $\mathbb{R}^P \ni \theta \mapsto C\left(F^{(L)}\left(\theta\right)\right)$ is the sum of two $P \times P$ matrices I and S. We show the following results for large P and for a fixed number of datapoints N:

- The first matrix I is positive semi-definite and its eigenvalues are given by the (weighted) kernel PCA of the dataset with respect to the NTK. The dominating eigenvalues are the principal components of the data followed by a high number of small eigenvalues. The "flat directions" are spanned by the small eigenvalues and the null-space (of dimension at least P-N when there is a single output). Because the NTK is asymptotically constant Jacot et al. (2018), these results apply at initialization, during training and at convergence.
- The second matrix S can be viewed as residual contribution to H, since it vanishes as the network converges to a global minimum. We compute the limit of the first moment Tr(S) and characterize its evolution during training, of the second moment $\text{Tr}(S^2)$ which stays constant during training, and show that the higher moments vanish.
- Regarding the sum H = I + S, we show that the matrices I and S are asymptotically orthogonal to each other at initialization and during training. In particular, the moments of the matrices I and S add up: $tr(H^k) \approx tr(I^k) + tr(S^k)$.

These results give, for any depth and a fairly general non-linearity, a complete description of the spectrum of the Hessian in terms of the NTK at initialization and throughout training. This gives theoretical confirmation of a number of observations about the Hessian Hochreiter & Schmidhuber (1997); Pascanu et al. (2014); Dauphin et al. (2014); Chaudhari et al. (2016); Wu et al. (2017); Pennington & Bahri (2017); Geiger et al. (2018), and sheds a new light on them.

1.2. Related works

The Hessian of the loss has been studied through the decomposition I + S in a number of previous works Sagun et al. (2017); Pennington & Bahri (2017); Geiger et al. (2018).

For least-squares and cross-entropy costs, the first matrix I is equal to the Fisher matrix Wagenaar (1998); Pascanu & Bengio (2013), whose moments have been described for shallow networks in Pennington & Worah (2018). For deep networks, the first two moments and the operator norm of the Fisher matrix for a least squares loss were computed at initialization in Karakida et al. (2018) conditionally on a certain independence assumption; our method does not require such assumptions. Note that their approach implicitly uses the NTK.

The second matrix S has been studied in Pennington & Bahri (2017); Geiger et al. (2018) for shallow networks, conditionally on a number of assumptions. Note that in the setting of Pennington & Bahri (2017), the matrices I and S are assumed to be freely independent, which allows them to study the spectrum of the Hessian; in our setting, we show that the two matrices I and S are asymptotically orthogonal to each other.

2. Setup

We consider deep fully connected artificial neural networks (DNNs) using the setup and NTK parametrization of Jacot et al. (2018), taking an arbitrary nonlinearity $\sigma \in C_b^4(\mathbb{R})$ (i.e. $\sigma: \mathbb{R} \to \mathbb{R}$ that is 4 times continuously differentiable function with all four derivatives bounded). The layers are numbered from 0 (input) to L (output), each containing n_ℓ neurons for $\ell=0,\ldots,L$. The $P=\sum_{\ell=0}^{L-1} (n_\ell+1)\,n_{\ell+1}$ parameters consist of the weight matrices $W^{(\ell)}\in\mathbb{R}^{n_{\ell+1}\times n_\ell}$ and bias vectors $b^{(\ell)}\in\mathbb{R}^{n_{\ell+1}}$ for $\ell=0,\ldots,L-1$. We aggregate the parameters into the vector $\theta\in\mathbb{R}^P$.

The activations and pre-activations of the layers are defined recursively for an input $x \in \mathbb{R}^{n_0}$, setting $\alpha^{(0)}(x;\theta) = x$:

$$\begin{split} \tilde{\alpha}^{(\ell+1)}(x;\theta) &= \frac{1}{\sqrt{n_{\ell}}} W^{(\ell)} \alpha^{(\ell)}(x;\theta) + \beta b^{(\ell)}, \\ \alpha^{(\ell+1)}(x;\theta) &= \sigma \big(\tilde{\alpha}^{(\ell+1)}(x;\theta) \big). \end{split}$$

The parameter β is added to tune the influence of the bias on training¹. All parameters are initialized as iid $\mathcal{N}(0,1)$ Gaussians.

We will in particular study the network function, which maps inputs x to the activation of the output layer (before the last non-linearity):

$$f_{\theta}(x) = \tilde{\alpha}^{(L)}(x;\theta).$$

In this paper, we will study the limit of various objects as $n_1, \ldots, n_L \to \infty$ sequentially, i.e. we first take $n_1 \to \infty$, then $n_2 \to \infty$, etc. This greatly simplifies the proofs, but they could in principle be extended to the simultaneous limit, i.e. when $n_1 = \ldots = n_{L-1} \to \infty$. All our numerical experiments are done with 'rectangular' networks (with $n_1 = \ldots = n_{L-1}$) and match closely the predictions for the sequential limit.

In the limit we study in this paper, the NTK is asymptotically fixed, as in Jacot et al. (2018); Allen-Zhu et al. (2018); Du et al. (2019); Arora et al. (2019). By rescaling the outputs of DNNs as the width increases, one can reach another limit where the NTK is not fixed Chizat & Bach (2018a;b); Rotskoff & Vanden-Eijnden (2018); Mei et al. (2019). The behavior of the Hessian in this other limit may be significantly different.

2.1. Functional viewpoint

The network function lives in a function space $f_{\theta} \in \mathcal{F} := [\mathbb{R}^{n_0} \to \mathbb{R}^{n_L}]$ and we call the function $F^{(L)} : \mathbb{R}^P \to \mathcal{F}$ that maps the parameters θ to the network function f_{θ} the realization function. We study the differential behavior of $F^{(L)}$:

- The derivative $\mathcal{D}F^{(L)} \in \mathbb{R}^P \otimes \mathcal{F}$ is a function-valued vector of dimension P. The p-th entry $\mathcal{D}_p F^{(L)} = \partial_{\theta_p} f_{\theta} \in \mathcal{F}$ represents how modifying the parameter θ_p modifies the function f_{θ} in the space \mathcal{F} .
- The Hessian $\mathcal{H}F^{(L)} \in \mathbb{R}^P \otimes \mathbb{R}^P \otimes \mathcal{F}$ is a function-valued $P \times P$ matrix.

The network is trained with respect to the cost functional:

$$C(f) = \frac{1}{N} \sum_{i=1}^{N} c_i (f(x_i)),$$

for strictly convex c_i , summing over a finite dataset $x_1, \ldots, x_N \in \mathbb{R}^{n_0}$ of size N. The parameters are then trained with gradient descent on the composition $\mathcal{C} \circ F^{(L)}$, which defines the usual loss surface of neural networks.

In this setting, we define the finite realization function $Y^{(L)}: \mathbb{R}^P \to \mathbb{R}^{Nn_L}$ mapping parameters θ to be the restriction of the network function f_{θ} to the training set $y_{ik} = f_{\theta,k}(x_i)$. The Jacobian $\mathcal{D}Y^{(L)}$ is hence an $Nn_L \times P$ matrix and its Hessian $\mathcal{H}Y^{(L)}$ is a $P \times P \times Nn_L$ tensor. Defining the restricted cost $C(y) = \frac{1}{N} \sum_i c_i(y_i)$, we have $C \circ F^{(L)} = C \circ Y^{(L)}$.

For our analysis, we require that the gradient norm $\|\mathcal{D}C\|$ does not explode during training. The following condition is sufficient:

Definition 1. A loss $C : \mathbb{R}^{Nn_L} \to \mathbb{R}$ has bounded gradients over sublevel sets (BGOSS) if the norm of the gradient is bounded over all sets $U_a = \{Y \in \mathbb{R}^{Nn_L} : C(Y) \leq a\}$.

For example, the Mean Square Error (MSE) $C(Y) = \frac{1}{2N} \|Y^* - Y\|^2$ for the labels $Y^* \in \mathbb{R}^{Nn_L}$ has BGOSS because $\|\nabla C(Y)\|^2 = \frac{1}{N} \|Y^* - Y\|^2 = 2C(Y)$. For the binary and softmax cross-entropy the gradient is uniformly bounded, see Proposition 2 in Appendix A.

¹In our experiments, we take $\beta = 0.1$.

2.2. Neural Tangent Kernel

The behavior during training of the network function f_{θ} in the function space \mathcal{F} is described by a (multi-dimensional) kernel, the Neural Tangent Kernel (NTK)

$$\Theta_{k,k'}^{(L)}(x,x') = \sum_{p=1}^{P} \partial_{\theta_p} f_{\theta,k}(x) \partial_{\theta_p} f_{\theta,k'}(x').$$

During training, the function f_{θ} follows the so-called kernel gradient descent with respect to the NTK, which is defined as

$$\partial_t f_{\theta(t)}(x) = -\nabla_{\Theta^{(L)}} C_{|f_{\theta(t)}}(x) := -\frac{1}{N} \sum_{i=1}^N \Theta^{(L)}(x, x_i) \nabla c_i (f_{\theta(t)}(x_i)).$$

In the infinite-width limit (letting $n_1 \to \infty, \dots, n_{L-1} \to \infty$ sequentially) and for losses with BGOSS, the NTK converges to a deterministic limit $\Theta^{(L)} \to \Theta^{(L)}_{\infty} \otimes Id_{n_L}$, which is constant during training, uniformly on finite time intervals [0, T] Jacot et al. (2018). In the case of the MSE loss, the uniform convergence of the NTK was proven for $T = \infty$ in Arora et al. (2019).

The limiting NTK $\Theta_{\infty}^{(L)}: \mathbb{R}^{n_0} \times \mathbb{R}^{n_0} \to \mathbb{R}$ is constructed as follows:

(1) For $f,g:\mathbb{R}\to\mathbb{R}$ and a kernel $K:\mathbb{R}^{n_0}\times\mathbb{R}^{n_0}\to\mathbb{R}$, define the kernel $\mathbb{L}_K^{f,g}:\mathbb{R}^{n_0}\times\mathbb{R}^{n_0}\to\mathbb{R}$ by

$$\mathbb{L}_{K}^{f,g}(x_0,x_1) = \mathbb{E}_{(a_0,a_1)} \left[f(a_0)g(a_1) \right],$$

for (a_0, a_1) a centered Gaussian vector with covariance matrix $(K(x_i, x_j))_{i,j=0,1}$. For f = g, we denote by \mathbb{L}_K^f the kernel $\mathbb{L}_K^{f,f}$.

- (2) We define the kernels $\Sigma_{\infty}^{(\ell)}$ for each layer of the network, starting with $\Sigma_{\infty}^{(1)}(x_0, x_1) = \frac{1}{n_0}(x_0^T x_1) + \beta^2$ and then recursively by $\Sigma_{\infty}^{(\ell+1)} = \mathbb{L}_{\Sigma_{\infty}^{(\ell)}}^{\sigma} + \beta^2$, for $\ell = 1, \ldots, L-1$, where σ is the network non-linearity.
- (3) The limiting NTK $\Theta_{\infty}^{(L)}$ is defined in terms of the kernels $\Sigma_{\infty}^{(\ell)}$ and the kernels $\dot{\Sigma}_{\infty}^{(\ell)} = \mathbb{L}_{\Sigma_{\infty}^{(\ell-1)}}^{\dot{\sigma}}$:

$$\Theta_{\infty}^{(L)} = \sum_{\ell=1}^{L} \Sigma_{\infty}^{(\ell)} \dot{\Sigma}_{\infty}^{(\ell+1)} \dots \dot{\Sigma}_{\infty}^{(L)}.$$

The NTK leads to convergence guarantees for DNNs in the infinite-width limit, and connect their generalization properties to those of kernel methods Jacot et al. (2018); Arora et al. (2019).

2.3. Gram Matrices

For a finite dataset $x_1, \ldots, x_N \in \mathbb{R}^{n_0}$ and a fixed depth $L \geq 1$, we denote by $\tilde{\Theta} \in \mathbb{R}^{Nn_L \times Nn_L}$ the Gram matrix of x_1, \ldots, x_N with respect to the limiting NTK, defined by

$$\tilde{\Theta}_{ik,jm} = \Theta_{\infty}^{(L)} \left(x_i, x_{i'} \right) \delta_{km}.$$

It is block diagonal because different outputs $k \neq m$ are asymptotically uncorrelated.

Similarly, for any (scalar) kernel $\mathcal{K}^{(L)}$ (such as the limiting kernels $\Sigma_{\infty}^{(L)}$, $\Lambda_{\infty}^{(L)}$, $\Upsilon_{\infty}^{(L)}$, $\Phi_{\infty}^{(L)}$, $\Xi_{\infty}^{(L)}$ introduced later), we will use the same notation, denoting the Gram matrix of the datapoints by $\tilde{\mathcal{K}}$.

3. Main Theorems

3.1. Hessian as I + S

Using the above setup, the Hessian H of the loss $C \circ F^{(L)}$ is the sum of two terms, with the entry $H_{p,p'}$ given by

$$H_{p,p'} = \mathcal{HC}_{|f_{\theta}}(\partial_{\theta_{p}}F, \partial_{\theta_{p'}}F) + \mathcal{DC}_{|f_{\theta}}(\partial_{\theta_{p},\theta_{p'}}F).$$

For a finite dataset, the Hessian matrix $\mathcal{H}(C \circ Y^{(L)})$ is equal to the sum of two matrices

$$I = \left(\mathcal{D}Y^{(L)}\right)^T \mathcal{H}C\mathcal{D}Y^{(L)} \quad \text{and} \quad S = \nabla C \cdot \mathcal{H}Y^{(L)}$$

where $\mathcal{D}Y^{(L)}$ is a $Nn_L \times P$ matrix, $\mathcal{H}C$ is a $Nn_L \times Nn_L$ matrix and $\mathcal{H}Y^{(L)}$ is a $P \times P \times Nn_L$ tensor to which we apply a scalar product (denoted by ·) in its last dimension with the Nn_L vector ∇C to obtain a $P \times P$ matrix.

Our main contribution is the following theorem, which describes the limiting moments $\text{Tr}(H^k)$ in terms of the moments of I and S:

Theorem 1. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, in the sequential limit $n_1 \to \infty, \ldots, n_{L-1} \to \infty$, we have for all $k \geq 1$

$$\operatorname{Tr}\left(H\left(t\right)^{k}\right) \approx \operatorname{Tr}\left(I\left(t\right)^{k}\right) + \operatorname{Tr}\left(S\left(t\right)^{k}\right).$$

The limits of $\operatorname{Tr}\left(I\left(t\right)^{k}\right)$ and $\operatorname{Tr}\left(S\left(t\right)^{k}\right)$ can be expressed in terms of the NTK $\Theta_{\infty}^{(L)}$, the kernel $\Upsilon_{\infty}^{(L)}$ and the non-symmetric kernels $\Phi_{\infty}^{(L)}$, $\Lambda_{\infty}^{(L)}$ defined in Appendix C:

• The moments $\operatorname{Tr}\left(I\left(t\right)^{k}\right)$ converge to the following limits (with the convention that $i_{k+1}=i_{1}$):

$$\operatorname{Tr}\left(I\left(t\right)^{k}\right) \to \operatorname{Tr}\left(\left(\mathcal{H}C(Y\left(t\right))\tilde{\Theta}\right)^{k}\right) = \frac{1}{N^{k}} \sum_{i_{1},...,i_{k}=1}^{N} \prod_{m=1}^{k} c_{i_{m}}''(f_{\theta(t)}(x_{i_{m}}))\Theta_{\infty}^{(L)}(x_{i_{m}},x_{i_{m+1}}).$$

• The first moment $\operatorname{Tr}(S(t))$ converges to the limit:

$$\operatorname{Tr}\left(S\left(t\right)\right) = \left(G(t)\right)^{T} \nabla C(Y(t)).$$

At initialization (G(0), Y(0)) form a Gaussian pair of Nn_L -vectors, independent for differing output indices $k = 1, ..., n_L$ and with covariance $\mathbb{E}\left[G_{ik}(0)Y_{i'k'}(0)\right] = \delta_{kk'}\Phi_{\infty}^{(L)}(x_i, x_{i'})$ for a (non-symmetric) $N \times N$ limiting kernel $\Phi_{\infty}^{(L)}(x_i, x_{i'})$. During training, both vectors follow the differential equations

$$\partial_t G(t) = -\tilde{\Lambda} \nabla C(Y(t))$$
$$\partial_t Y(t) = -\tilde{\Theta} \nabla C(Y(t)).$$

• The second moment $\operatorname{Tr}\left(S\left(t\right)^{2}\right)$ converges to the following limit defined in terms of the Gram matrix $\tilde{\Upsilon}$:

$$\operatorname{Tr}\left(S^{2}\right) \to \left(\nabla C(Y(t))\right)^{T} \tilde{\Upsilon} \nabla C(Y(t))$$

• The higher moments $\operatorname{Tr}\left(S\left(t\right)^{k}\right)$ for $k\geq 3$ vanish.

Proof. The moments of I and S can be studied separately because the moments of their sum is asymptotically equal to the sum of their moments by Proposition 5 below. The limiting moments of I and S are respectively described by Propositions 1 and 4 below.

In the case of a MSE loss $C(Y) = \frac{1}{2N} \|Y - Y^*\|^2$, the first and second derivatives take simple forms $\nabla C(Y) = \frac{1}{N} (Y - Y^*)$ and $\mathcal{H}C(Y) = \frac{1}{N} Id_{Nn_L}$ and the differential equations can be solved to obtain more explicit formulae:

Corollary 1. For the MSE loss C and $\sigma \in C_b^4(\mathbb{R})$, in the limit $n_1, ..., n_{L-1} \to \infty$, we have uniformly over [0,T]

$$\operatorname{Tr}\left(H(t)^{k}\right) \to \frac{1}{N^{k}}\operatorname{Tr}\left(\tilde{\Theta}^{k}\right) + \operatorname{Tr}\left(S(t)^{k}\right)$$

where

$$\begin{split} \operatorname{Tr}\left(S(t)\right) &\to -\frac{1}{N}(Y^* - Y(0))^T \left(Id_{Nn_L} + e^{-t\tilde{\Theta}}\right) \tilde{\Theta}^{-1} \tilde{\Lambda}^T e^{-t\tilde{\Theta}} (Y^* - Y(0)) \\ &\quad + \frac{1}{N} G(0)^T e^{-t\tilde{\Theta}} (Y^* - Y(0)) \\ \operatorname{Tr}\left(S(t)^2\right) &\to \frac{1}{N^2} (Y^* - Y(0))^T e^{-t\tilde{\Theta}} \tilde{\Upsilon} e^{-t\tilde{\Theta}} (Y^* - Y(0)) \\ \operatorname{Tr}\left(S(t)^k\right) &\to 0 \quad when \ k > 2. \end{split}$$

In expectation we have:

$$\mathbb{E}\left[\operatorname{Tr}\left(S(t)\right)\right] \to -\frac{1}{N}Tr\left(\left(Id_{Nn_L} + e^{-t\tilde{\Theta}}\right)\tilde{\Theta}^{-1}\tilde{\Lambda}^T e^{-t\tilde{\Theta}}\left(\tilde{\Sigma} + Y^*Y^{*T}\right)\right) + \frac{1}{N}Tr\left(e^{-t\tilde{\Theta}}\tilde{\Phi}^T\right)$$

$$\mathbb{E}\left[\operatorname{Tr}\left(S(t)^2\right)\right] \to \frac{1}{N^2}Tr\left(e^{-t\tilde{\Theta}}\tilde{\Upsilon}e^{-t\tilde{\Theta}}\left(\tilde{\Sigma} + Y^*Y^{*T}\right)\right).$$

Proof. The moments of I are constant because $\mathcal{H}C = \frac{1}{N}Id_{Nn_L}$ is constant. For the moments of S, we first solve the differential equation for Y(t):

$$Y(t) = Y^* - e^{-t\tilde{\Theta}}(Y^* - Y(0)).$$

Noting $Y(t) - Y(0) = -\tilde{\Theta} \int_0^t \nabla C(s) ds$, we have

$$G(t) = G(0) - \tilde{\Lambda} \int_0^t \nabla C(s) ds$$

$$= G(0) + \tilde{\Lambda} \tilde{\Theta}^{-1} (Y(t) - Y(0))$$

$$= G(0) + \tilde{\Lambda} \tilde{\Theta}^{-1} \left(Id_{Nn_L} + e^{-t\tilde{\Theta}} \right) (Y^* - Y(0))$$

The expectation of the first moment of S then follows.

3.2. Mutual Orthogonality of I and S

A first key ingredient to prove Theorem 1 is the asymptotic mutual orthogonality of the matrices I and S

Proposition (Proposition 5 in Appendix D). For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, we have uniformly over [0,T]

$$\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}||IS||_F=0.$$

As a consequence
$$\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}\operatorname{Tr}\left(\left[I+S\right]^k\right)-\left[\operatorname{Tr}\left(I^k\right)+\operatorname{Tr}\left(S^k\right)\right]=0.$$

Remark 1. If two matrices A and B are mutually orthogonal (i.e. AB=0) the range of A is contained in the nullspace of B and vice versa. The non-zero eigenvalues of the sum A+B are therefore given by the union of the non-zero eigenvalues of A and B. Furthermore the moments of A and B add up: $\mathrm{Tr}\left(\left[A+B\right]^k\right)=\mathrm{Tr}\left(A^k\right)+\mathrm{Tr}\left(B^k\right)$. Proposition 5 shows that this is what happens asymptotically for I and S.

Note that both matrices I and S have large nullspaces: indeed assuming a constant width $w = n_1 = ... = n_{L-1}$, we have $Rank(I) \leq Nn_L$ and $Rank(S) \leq 2(L-1)wNn_L$ (see Appendix C), while the number of parameters P scales as w^2 (when L > 2).

Figure 2 illustrates the mutual orthogonality of I and S.

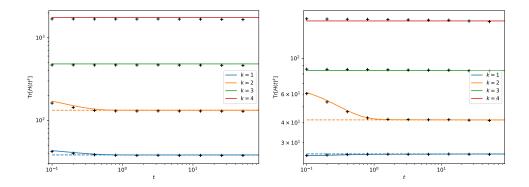


FIGURE 1. Comparison of the theoretical prediction of Corollary 1 for the expectation of the first 4 moments (colored lines) to the empirical average over 250 trials (black crosses) for a rectangular network with two hidden layers of finite widths $n_1 = n_2 = 5000 \ (L=3)$ with the smooth ReLU (left) and the normalized smooth ReLU (right), for the MSE loss on scaled down 14x14 MNIST with N=256. Only the first two moments are affected by S at the beginning of training.

3.3. The matrix S

The matrix $S = \nabla C \cdot \mathcal{H}Y^{(L)}$ is best understood as a perturbation to I, which vanishes as the network converges because $\nabla C \to 0$. To calculate its moments, we note that

$$\operatorname{Tr}\left(\nabla C \cdot \mathcal{H}Y^{(L)}\right) = \left(\sum_{p=1}^{P} \partial_{\theta_{p}^{2}}^{2} Y\right)^{T} \nabla C = G^{T} \nabla C,$$

where the vector $G = \sum_{k=1}^{P} \partial_{\theta_p^2}^2 Y \in \mathbb{R}^{Nn_L}$ is the evaluation of the function $g_{\theta}(x) = \sum_{k=1}^{P} \partial_{\theta_x^2}^2 f_{\theta}(x)$ on the training set.

For the second moment we have

$$\operatorname{Tr}\left(\left(\nabla C \cdot \mathcal{H}Y^{(L)}\right)^{2}\right) = \nabla C^{T}\left(\sum_{p,p'=1}^{P} \partial_{\theta_{p}\theta_{p'}}^{2} Y\left(\partial_{\theta_{p}\theta_{p'}}^{2} Y\right)^{T}\right) \nabla C = \nabla C^{T} \tilde{\Upsilon} \nabla C$$

for $\tilde{\Upsilon}$ the Gram matrix of the kernel $\Upsilon^{(L)}(x,y) = \sum_{p,p'=1}^{P} \partial_{\theta_p\theta_{p'}}^2 f_{\theta}(x) \left(\partial_{\theta_p\theta_{p'}}^2 f_{\theta}(y)\right)^T$.

The following proposition desribes the limit of the function g_{θ} and the kernel $\Upsilon^{(L)}$ and the vanishing of the higher moments:

Proposition (Proposition 4 in Appendix C). For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, the first two moments of S take the form

$$\operatorname{Tr}(S(t)) = G(t)^{T} \nabla C(t)$$
$$\operatorname{Tr}(S(t)^{2}) = \nabla C(t)^{T} \tilde{\Upsilon}(t) \nabla C(t)$$

- At initialization, g_{θ} and f_{θ} converge to a (centered) Gaussian pair with covariances

$$\mathbb{E}[g_{\theta,k}(x)g_{\theta,k'}(x')] = \delta_{kk'}\Xi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[g_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Phi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[f_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Sigma_{\infty}^{(L)}(x,x')$$

and during training g_{θ} evolves according to

$$\partial_t g_{\theta,k}(x) = \sum_{i=1}^N \Lambda_{\infty}^{(L)}(x,x_i) \partial_{ik} C(Y(t)).$$

- Uniformly over any interval [0,T], the kernel $\Upsilon^{(L)}$ has a deterministic and fixed limit $\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}\Upsilon^{(L)}_{kk'}(x,x')=\delta_{kk'}\Upsilon^{(L)}_{\infty}(x,x')$ with limiting kernel:

$$\Upsilon_{\infty}^{(L)}(x,x') = \sum_{\ell=1}^{L-1} \left(\Theta_{\infty}^{(\ell)}(x,x')^2 \ddot{\Sigma}_{\infty}^{(\ell)}(x,x') + 2\Theta_{\infty}^{(\ell)}(x,x') \dot{\Sigma}_{\infty}^{(\ell)}(x,x') \right) \dot{\Sigma}_{\infty}^{(\ell+1)}(x,x') \cdots \dot{\Sigma}_{\infty}^{(L-1)}(x,x').$$

- The higher moment k > 2 vanish: $\lim_{n_{L-1} \to \infty} \cdots \lim_{n_1 \to \infty} \operatorname{Tr}(S^k) = 0$.

This result has a number of consequences for infinitely wide networks:

- (1) At initialization, the matrix S has a finite Frobenius norm $||S||_F^2 = \text{Tr}(S^2) = \nabla C^T \tilde{\Upsilon} \nabla C$, because Υ converges to a fixed limit. As the network converges, the derivative of the cost goes to zero $\nabla C(t) \to 0$ and so does the Frobenius norm of S.
- (2) In contrast the operator norm of S vanishes already at initialization (because for all even k, we have $||S||_{op} \leq \sqrt[k]{\operatorname{Tr}(S^k)} \to 0$). At initialization, the vanishing of S in operator norm but not in Frobenius norm can be explained by the matrix S having a growing number of eigenvalues of shrinking intensity as the width grows.
- (3) When it comes to the first moment of S, Proposition 4 shows that the spectrum of S is in general not symmetric. For the MSE loss the expectation of the first moment at initialization is

$$\mathbb{E}\left[\operatorname{Tr}(S)\right] = \mathbb{E}\left[\left(Y - Y^*\right)^T G\right] = \mathbb{E}\left[Y^T G\right] - \left(Y^*\right)^T \mathbb{E}\left[G\right] = \operatorname{Tr}\left(\tilde{\Phi}\right) - 0$$

which may be positive or negative depending on the choice of nonlinearity: with a smooth ReLU, it is positive, while for the arc-tangent or the normalized smooth ReLU, it can be negative (see Figure 1).

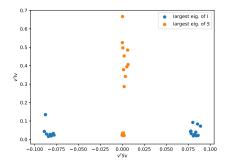
This is in contrast to the result obtained in Pennington & Bahri (2017); Geiger et al. (2018) for the shallow ReLU networks, taking the second derivative of the ReLU to be zero. Under this assumption the spectrum of S is symmetric: if the eigenvalues are ordered from lowest to highest, $\lambda_i = -\lambda_{P-i}$ and Tr(S) = 0.

These observations suggest that S has little influence on the shape of the surface, especially towards the end of training, the matrix I however has an interesting structure.

3.4. The matrix I

At a global minimizer θ^* , the spectrum of I describes how the loss behaves around θ^* . Along the eigenvectors of the biggest eigenvalues of I, the loss increases rapidely, while small eigenvalues correspond to flat directions. Numerically, it has been observed that the matrix I features a few dominating eigenvalues and a bulk of small eigenvalues Sagun et al. (2016; 2017); Gur-Ari et al. (2018); Papyan (2019). This leads to a narrow valley structure of the loss around a minimum: the biggest eigenvalues are the 'cliffs' of the valley, i.e. the directions along which the loss grows fastest, while the small eigenvalues form the 'flat directions' or the bottom of the valley.

Note that the rank of I is bounded by Nn_L and in the overparametrized regime, when $Nn_L < P$, the matrix I will have a large nullspace, these are directions along which the value of the function on the training set does not change. Note that in the overparametrized regime, global minima are not isolated: they lie in a manifold of dimension at least $P - Nn_L$ and the nullspace of I is tangent to this solution manifold.



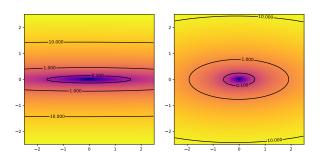


FIGURE 2. Illustration of the mutual orthogonality of I and S. For the 20 first eigenvectors of I (blue) and S (orange), we plot the Rayleigh quotients $v^T I v$ and $v^T S v$ (with L=3, $n_1=n_2=1000$ and the normalized ReLU on 14x14 MNIST with N=256). We see that the directions where I is large are directions where S is small and vice versa.

FIGURE 3. Plot of the loss surface around a global minimum along the first (along the y coordinate) and fourth (x coordinate) eigenvectors of I. The network has L=4, width $n_1=n_2=n_3=1000$ for the smooth ReLU (left) and the normalized smooth ReLU (right). The data is uniform on the unit disk. Normalizing the non-linearity greatly reduces the narrow valley structure of the loss thus speeding up training.

The matrix I is closely related to the NTK Gram matrix:

$$\tilde{\Theta} = \mathcal{D}Y^{(L)} \left(\mathcal{D}Y^{(L)}\right)^T \text{ and } I = \left(\mathcal{D}Y^{(L)}\right)^T \mathcal{H}C\mathcal{D}Y^{(L)}.$$

As a result, the limiting spectrum of the matrix I can be directly obtained from the NTK²

Proposition 1. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, uniformly over any interval [0,T], the moments $\mathrm{Tr}(I^k)$ converge to the following limit (with the convention that $i_{k+1} = i_1$):

$$\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}\operatorname{Tr}\left(I^k\right)=\operatorname{Tr}\left(\left(\mathcal{H}C(Y_t)\tilde{\Theta}\right)^k\right)=\frac{1}{N^k}\sum_{i_1,\ldots,i_k=1}^N\prod_{m=1}^kc_{i_m}''(f_{\theta(t)}(x_{i_m}))\Theta_{\infty}^{(L)}(x_{i_m},x_{i_{m+1}})$$

Proof. It follows from
$$\operatorname{Tr}\left(I^{k}\right) = \operatorname{Tr}\left(\left(\left(\mathcal{D}Y^{(L)}\right)^{T}\mathcal{H}C\mathcal{D}Y^{(L)}\right)^{k}\right) = \operatorname{Tr}\left(\left(\mathcal{H}C\tilde{\Theta}\right)^{k}\right)$$
 and the asymptotic of the NTK Jacot et al. (2018).

3.4.1. Mean-Square Error

When the loss is the MSE, $\mathcal{H}C$ is equal to $\frac{1}{N}Id_{Nn_L}$. As a result, $\tilde{\Theta}$ and I have the same non-zero eigenvalues up to a scaling of 1/N. Because the NTK is assymptotically fixed, the spectrum of I is also fixed in the limit.

The eigenvectors of the NTK Gram matrix are the kernel principal components of the data. The biggest principal components are the directions in function space which are most favorised by the NTK. This gives a functional interpretation of the narrow valley structure in DNNs: the cliffs of the valley are the biggest principal components, while the flat directions are the smallest components.

Remark 2. As the depth L of the network increases, one can observe two regimes Poole et al. (2016); Jacot et al. (2019): Order/Freeze where the NTK converges to a constant and Chaos where the NTK converges to a Kronecker delta. In the Order/Freeze the $Nn_L \times Nn_L$

 $^{^2}$ This result was already obtained in Karakida et al. (2018), but without identifying the NTK explicitely and only at initialization.

Gram matrix approaches a block diagonal matrix with n_L constant blocks, and as a result n_L eigenvalues of I dominate the other ones, corresponding to constant directions along each outputs (this is line with the observations of Papyan (2019)). This leads to a narrow valley for the loss and slows down training. In contrast, in the Chaos regime, the NTK Gram matrix approaches a scaled identity matrix, and the spectrum of I should hence concentrate around a positive value, hence speeding up training. Figure 3 illustrates this phenomenon: with the smooth ReLU we observe a narrow valley, while with the normalized smooth ReLU (which lies in the Chaos according to Jacot et al. (2019)) the narrowness of the loss is reduced. A similar phenomenon may explain why normalization helps smoothing the loss surface and speed up training Santurkar et al. (2018); Ghorbani et al. (2019).

3.4.2. Cross-Entropy Loss

For a binary cross-entropy loss with labels $Y^* \in \{-1, +1\}^N$

$$C(Y) = \frac{1}{N} \sum_{i=1}^{N} log \left(1 + e^{-Y_i^* Y_i} \right),$$

 $\mathcal{H}C$ is a diagonal matrix whose entries depend on Y (but not on Y^*):

$$\mathcal{H}_{ii}C(Y) = \frac{1}{N} \frac{1}{1 + e^{-Y_i} + e^{Y_i}}.$$

The eigenvectors of I then correspond to the weighted kernel principal component of the data. The positive weights $\frac{1}{1+e^{-Y_i}+e^{Y_i}}$ approach 1/3 as Y_i goes to 0, i.e. when it is close to the decision boundary from one class to the other, and as $Y_i \to \pm \infty$ the weight go to zero. The weights evolve in time through Y_i , the spectrum of I is therefore not asymptotically fixed as in the MSE case, but the functional interpretation of the spectrum in terms of the kernel principal components remains.

4. Conclusion

We have given an explicit formula for the limiting moments of the Hessian of DNNs throughout training. We have used the common decomposition of the Hessian in two terms I and S and have shown that the two terms are asymptotically mutually orthogonal, such that they can be studied separately.

The matrix S vanishes in Frobenius norm as the network converges and has vanishing operator norm throughout training. The matrix I is arguably the most important as it describes the narrow valley structure of the loss around a global minimum. The eigendecomposition of I is related to the (weighted) kernel principal components of the data w.r.t. the NTK.

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APPENDIX A. PROOFS

For the proofs of the theorems and propositions presented in the main text, we reformulate the setup of Jacot et al. (2018). For a fixed training set $x_1, ..., x_N$, we consider a (possibly random) time-varying training direction $D(t) \in \mathbb{R}^{Nn_L}$ which describes how each of the outputs must be modified. In the case of gradient descent on a cost C(Y), the training direction is $D(t) = \nabla C(Y(t))$. The parameters are updated according to the differential equation

$$\partial_t \theta(t) = (\partial_\theta Y(t))^T D(t).$$

Under the condition that $\int_0^T \|D(t)\|_2 dt$ is stochastically bounded as the width of the network goes to infinity, the NTK $\Theta^{(L)}$ converges to its fixed limit uniformly over [0,T].

The reason we consider a general training direction (and not only a gradient of a loss) is that we can split a network in two at a layer ℓ and the training of the smaller network will

be according to the training direction $D_i^{(\ell)}(t)$ given by

$$D_i^{(\ell)}(t) = diag\left(\dot{\sigma}\left(\alpha^{(\ell)}(x_i)\right)\right) \left(\frac{1}{\sqrt{n_\ell}} W^{(\ell)}\right)^T \dots diag\left(\dot{\sigma}\left(\alpha^{(L-1)}(x_i)\right)\right) \left(\frac{1}{\sqrt{n_{L-1}}} W^{(L-1)}\right)^T D_i(t)$$

because the derivatives $\dot{\sigma}$ are bounded and by Lemma 1 of the Appendix of Jacot et al. (2018), this training direction satisfies the constraints even though it is not the gradient of a loss. As a consequence, as $n_1 \to \infty, ..., n_{\ell-1} \to \infty$ the NTK of the smaller network $\Theta^{(\ell)}$ also converges to its limit uniformly over [0,T]. As we let $n_\ell \to \infty$ the pre-activations $\tilde{\alpha}_i^{(\ell)}$ and weights $W_{ij}^{(\ell)}$ move at a rate of $1/\sqrt{n_\ell}$. We will use this rate of change to prove that other types of kernels are constant during training.

When a network is trained with gradient descent on a loss C with BGOSS, the integral $\int_0^T \|D(t)\|_2 dt$ is stochastically bounded. Because the loss is decreasing during training, the outputs Y(t) lie in the sublevel set $U_{C(Y(0))}$ for all times t. The norm of the gradient is hence bounded for all times t. Because the distribution of Y(0) converges to a multivariate Gaussian, b(C(Y(0))) is stochastically bounded as the width grows, where b(a) is a bound on the norm of the gradient on U_a . We then have the bound $\int_0^T \|D(t)\|_2 dt \leq Tb(C(Y(0)))$ which is itself stochastically bounded.

For the binary and softmax cross-entropy losses the gradient is uniformly bounded:

Proposition 2. For the binary cross-entropy loss C and any $Y \in \mathbb{R}^N$, $\|\nabla C(Y)\|_2 \leq \frac{1}{\sqrt{N}}$.

For the softmax cross-entropy loss C on $c \in \mathbb{N}$ classes and any $Y \in \mathbb{R}^{Nc}$, $\|\nabla C(Y)\|_2 \leq \frac{\sqrt{2c}}{\sqrt{N}}$.

Proof. The binary cross-entropy loss with labels $Y^* \in \{0,1\}^N$ is

$$C(Y) = -\frac{1}{N} \sum_{i=1}^{N} \log \frac{e^{Y_i Y_i^*}}{1 + e^{Y_i}} = \frac{1}{N} \sum_{i=1}^{N} \log (1 + e^{Y_i}) - Y_i Y_i^*$$

and the gradient at an input i is

$$\partial_i C(Y) = \frac{1}{N} \frac{e^{Y_i} - Y_i^* (1 + e^{Y_i})}{1 + e^{Y_i}}$$

which is bounded in absolute value by $\frac{1}{N}$ for both $Y_i^* = 0, 1$ such that $\|\nabla C(Y)\|_2 \leq \frac{1}{\sqrt{N}}$.

The softmax cross-entropy loss over c classes with labels $Y^* \in \{1, \dots, c\}^N$ is defined by

$$C(Y) = -\frac{1}{N} \sum_{i=1}^{N} \log \frac{e^{Y_{iY_{i}^{*}}}}{\sum_{k=1}^{c} e^{Y_{ik}}} = \frac{1}{N} \sum_{i=1}^{N} \log \left(\sum_{k=1}^{c} e^{Y_{ik}} \right) - Y_{iY_{i}^{*}}.$$

The gradient is at an input i and output class m is

$$\partial_{im}C(Y) = \frac{1}{N} \left(\frac{e^{Y_{im}}}{\sum_{k=1}^{c} e^{Y_{ik}}} - \delta_{Y_i^*m} \right)$$

which is bounded in absolute value by $\frac{2}{N}$ such that $\|\nabla C(Y)\|_2 \leq \frac{\sqrt{2c}}{\sqrt{N}}$.

Appendix B. Preliminaries

To study the moments of the matrix S, we first have to show that two tensors vanish as $n_1, ..., n_{L-1} \to \infty$:

$$\Omega_{k_0,k_1,k_2}^{(L)}(x_0,x_1,x_2) = (\nabla f_{\theta,k_0}(x_0))^T \mathcal{H} f_{\theta,k_1}(x_1) \nabla f_{\theta,k_2}(x_2)$$

$$\Gamma_{k_0,k_1,k_2,k_3}^{(L)}(x_0,x_1,x_2,x_4) = (\nabla f_{\theta,k_0}(x_0))^T \mathcal{H} f_{\theta,k_1}(x_1) \mathcal{H} f_{\theta,k_2}(x_2) \nabla f_{\theta,k_3}(x_3).$$

We study these tensors recursively, for this, we need a recursive definition for the first derivatives $\partial_{\theta_p} f_{\theta,k}(x)$ and second derivatives $\partial^2_{\theta_p\theta_{p'}} f_{\theta,k}(x)$. The value of these derivatives depend on the layer ℓ the parameters θ_p and $\theta_{p'}$ belong to, and on whether they are connection weights $W_{mk}^{(\ell)}$ or biases $b_k^{(\ell)}$. The derivatives with respect to the parameters of the last layer are

$$\partial_{W_{mk}^{(L-1)}} f_{\theta,k'}(x) = \frac{1}{\sqrt{n_{L-1}}} \alpha_m^{(L-1)}(x) \delta_{kk'}$$
$$\partial_{b_{+}^{(L-1)}} f_{\theta,k'}(x) = \beta^2 \delta_{kk'}$$

for parameters θ_p which belong to the lower layers the derivatives can be defined recursively by

$$\partial_{\theta_p} f_{\theta,k}(x) = \frac{1}{\sqrt{n_{L-1}}} \sum_{m=1}^{n_{L-1}} \partial_{\theta_p} \tilde{\alpha}_m^{(L-1)}(x) \dot{\sigma} \left(\tilde{\alpha}_m^{(L-1)}(x) \right) W_{mk}^{(L-1)}.$$

For the second derivatives, we first note that if either of the parameters θ_p or $\theta_{p'}$ are bias of the last layer, or if they are both connection weights of the last layer, then $\partial^2_{\theta_p\theta_{p'}}f_{\theta,k}(x)=0$. Two cases are left: when one parameter is a connection weight of the last layer and the others belong to the lower layers, and when both belong to the lower layers. Both cases can be defined recursively in terms of the first and second derivatives of $\tilde{\alpha}_m^{(L-1)}$:

$$\begin{split} \partial^2_{\theta_p W^{(L)}_{mk}} f_{\theta,k'}(x) &= \frac{1}{\sqrt{n_{L-1}}} \partial_{\theta_p} \tilde{\alpha}^{(L-1)}_m(x) \dot{\sigma} \left(\tilde{\alpha}^{(L-1)}_m(x) \right) \delta_{kk'} \\ \partial^2_{\theta_p \theta_{p'}} f_{\theta,k'}(x) &= \frac{1}{\sqrt{n_{L-1}}} \sum_{m=1}^{n_{L-1}} \partial^2_{\theta_p \theta_{p'}} \tilde{\alpha}^{(L-1)}_m(x) \dot{\sigma} \left(\tilde{\alpha}^{(L-1)}_m(x) \right) W^{(L-1)}_{mk} \\ &+ \frac{1}{\sqrt{n_{L-1}}} \sum_{m=1}^{n_{L-1}} \partial_{\theta_p} \tilde{\alpha}^{(L-1)}_m(x) \partial_{\theta_{p'}} \tilde{\alpha}^{(L-1)}_m(x) \dot{\sigma} \left(\tilde{\alpha}^{(L-1)}_m(x) \right) W^{(L-1)}_{mk}. \end{split}$$

Using these recursive definitions, the tensors $\Omega^{(L+1)}$ and $\Gamma^{(L+1)}$ are given in terms of $\Theta^{(L)}, \Omega^{(L)}$ and $\Gamma^{(L)}$, in the same manner that the NTK $\Theta^{(L+1)}$ is defined recursively in terms of $\Theta^{(L)}$ in Jacot et al. (2018).

Lemma 1. For any loss C with BGOSS and $\sigma \in C_h^4(\mathbb{R})$, we have uniformly over [0,T]

$$\lim_{n_{L-1} \to \infty} \cdots \lim_{n_1 \to \infty} \Omega_{k_0, k_1, k_2}^{(L)}(x_0, x_1, x_2) = 0$$

Proof. The proof is done by induction. When L=1 the second derivatives $\partial^2_{\theta_p\theta_{p'}}f_{\theta,k}(x)=0$ and $\Omega^{(L)}_{k_0,k_1,k_2}(x_0,x_1,x_2)=0$.

For the induction step, we write $\Omega^{(\ell+1)}_{k_0,k_1,k_2}(x_0,x_1,x_2)$ recursively as

$$\begin{split} & n_{\ell}^{-3/2} \sum_{m_0, m_1, m_2} \Theta_{m_0, m_1}^{(\ell)}(x_0, x_1) \Theta_{m_1, m_2}^{(\ell)}(x_1, x_2) \dot{\sigma}(\tilde{\alpha}_{m_0}^{(\ell)}(x_0)) \ddot{\sigma}(\tilde{\alpha}_{m_1}^{(\ell)}(x_1)) \dot{\sigma}(\tilde{\alpha}_{m_2}^{(\ell)}(x_2)) W_{m_0 k_0}^{(\ell)} W_{m_1 k_1}^{(\ell)} W_{m_2 k_2}^{(\ell)} \\ & + n_{\ell}^{-3/2} \sum_{m_0, m_1, m_2} \Omega_{m_0, m_1, m_2}^{(\ell)}(x_0, x_1, x_2) \dot{\sigma}(\tilde{\alpha}_{m_0}^{(\ell)}(x_0)) \dot{\sigma}(\tilde{\alpha}_{m_1}^{(\ell)}(x_1)) \dot{\sigma}(\tilde{\alpha}_{m_2}^{(\ell)}(x_2)) W_{m_0 k_0}^{(\ell)} W_{m_1 k_1}^{(\ell)} W_{m_2 k_2}^{(\ell)} \\ & + n_{\ell}^{-3/2} \sum_{m_0, m_1} \Theta_{m_0, m_1}^{(\ell)}(x_0, x_1) \dot{\sigma}(\tilde{\alpha}_{m_0}^{(\ell)}(x_0)) \dot{\sigma}(\tilde{\alpha}_{m_1}^{(\ell)}(x_1)) \sigma(\tilde{\alpha}_{m_1}^{(\ell)}(x_2)) W_{m_0 k_0}^{(\ell)} \delta_{k_1 k_2} \\ & + n_{\ell}^{-3/2} \sum_{m_1, m_2} \Theta_{m_1, m_2}^{(\ell)}(x_1, x_2) \sigma(\tilde{\alpha}_{m_1}^{(\ell)}(x_0)) \dot{\sigma}(\tilde{\alpha}_{m_1}^{(\ell)}(x_1)) \dot{\sigma}(\tilde{\alpha}_{m_2}^{(\ell)}(x_2)) \delta_{k_0 k_1} W_{m_2 k_2}^{(\ell)}. \end{split}$$

As $n_1, ..., n_{\ell-1} \to \infty$ and for any times t < T, the NTK $\Theta^{(\ell)}$ converges to its limit while $\Omega^{(\ell)}$ vanishes. The second summand hence vanishes and the others converge to

$$n_{\ell}^{-3/2} \sum_{m} \Theta_{\infty}^{(\ell)}(x_{0},x_{1}) \Theta_{\infty}^{(\ell)}(x_{1},x_{2}) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{0})) \ddot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{1})) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{2})) W_{mk_{0}}^{(\ell)} W_{mk_{1}}^{(\ell)} W_{mk_{2}}^{(\ell)}$$

$$+ n_{\ell}^{-3/2} \sum_{m} \Theta_{\infty}^{(\ell)}(x_{0}, x_{1}) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{0})) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{1})) \sigma(\tilde{\alpha}_{m}^{(\ell)}(x_{2})) W_{mk_{0}}^{(\ell)} \delta_{k_{1}k_{2}}$$

$$+ n_{\ell}^{-3/2} \sum_{m} \Theta_{\infty}^{(\ell)}(x_{1}, x_{2}) \sigma(\tilde{\alpha}_{m}^{(\ell)}(x_{0})) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{1})) \dot{\sigma}(\tilde{\alpha}_{m}^{(\ell)}(x_{2})) \delta_{k_{0}k_{1}} W_{mk_{2}}^{(\ell)}.$$

At initialization, all terms vanish as $n_\ell \to \infty$ because all summands are independent with zero mean and finite variance: in the $n_1 \to \infty, \dots, n_{\ell-1} \to \infty$ limit, the $\tilde{\alpha}_m^{(\ell)}(x)$ are independent for different m, see Jacot et al. (2018). During training, the weights $W^{(\ell)}$ and preactivations $\tilde{\alpha}^{(\ell)}$ move at a rate of $1/\sqrt{n_\ell}$ (see the proof of convergence of the NTK in Jacot et al. (2018)). Since $\dot{\sigma}$ is Lipschitz, we obtain that the motion during training of each of the sums is of order $n_\ell^{-3/2+1/2} = n_\ell^{-1}$. As a result, uniformly over times $t \in [0,T]$, all the sums vanish. \square

Similarily, we have

Lemma 2. For any loss C with BGOSS and $\sigma \in C_h^4(\mathbb{R})$, we have uniformly over [0,T]

$$\lim_{n_{L-1} \to \infty} \cdots \lim_{n_1 \to \infty} \Gamma_{k_0, k_1, k_2, k_3}^{(L)}(x_0, x_1, x_2, x_3) = 0$$

Proof. The proof is done by induction. When L=1 the hessian $\mathcal{H}F^{(1)}=0$, such that $\Gamma_{k_0,k_1,k_2,k_3}^{(L)}(x_0,x_1,x_2,x_3)=0$.

For the induction step, $\Gamma^{(\ell+1)}$ can be defined recursively:

$$\begin{split} &+n_{L}^{-2}\sum_{m_{1},m_{2}}\Theta_{m_{1},m_{2}}^{(L)}(x_{1},x_{2})\sigma(\alpha_{m_{1}}^{(L)}(x_{0}))\dot{\sigma}(\alpha_{m_{1}}^{(L)}(x_{1}))\dot{\sigma}(\alpha_{m_{2}}^{(L)}(x_{2}))\sigma(\alpha_{m_{2}}^{(L)}(x_{3}))\delta_{k_{0}k_{1}}\delta_{k_{2}k_{3}}\\ &+n_{L}^{-2}\sum_{m_{0},m_{1},m_{3}}\Theta_{m_{0},m_{1}}^{(L)}(x_{0},x_{1})\Theta_{m_{1},m_{3}}^{(L)}(x_{2},x_{3})\dot{\sigma}(\alpha_{m_{0}}^{(L)}(x_{0}))\dot{\sigma}(\alpha_{m_{1}}^{(L)}(x_{1}))\dot{\sigma}(\alpha_{m_{1}}^{(L)}(x_{2}))\dot{\sigma}(\alpha_{m_{3}}^{(L)}(x_{3}))\\ &&W_{m_{0}k_{0}}^{(L)}\delta_{k_{1}k_{2}}W_{m_{3}k_{3}}^{(L)}\end{split}$$

As $n_1, ..., n_{\ell-1} \to \infty$ and for any times t < T, the NTK $\Theta^{(\ell)}$ converges to its limit while $\Omega^{(\ell)}$ and $\Gamma^{(\ell)}$ vanishes. $\Gamma^{(L+1)}_{k_0, k_1, k_2, k_3}(x_0, x_1, x_2, x_3)$ therefore converges to:

$$+n_{L}^{-2}\sum_{m}\Theta_{\infty}^{(L)}(x_{0},x_{1})\Theta_{\infty}^{(L)}(x_{1},x_{2})\Theta_{\infty}^{(L)}(x_{2},x_{3})\dot{\sigma}(\alpha_{m}^{(L)}(x_{0}))\ddot{\sigma}(\alpha_{m}^{(L)}(x_{1}))\ddot{\sigma}(\alpha_{m}^{(L)}(x_{2}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{3}))$$

$$-W_{mk_{0}}^{(L)}W_{mk_{1}}^{(L)}W_{mk_{2}}^{(L)}W_{mk_{3}}^{(L)}$$

$$+n_{L}^{-2}\sum_{m}\Theta_{\infty}^{(L)}(x_{1},x_{2})\Theta_{\infty}^{(L)}(x_{2},x_{3})\sigma(\alpha_{m}^{(L)}(x_{0}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{1}))\ddot{\sigma}(\alpha_{m}^{(L)}(x_{2}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{3}))$$

$$-\delta_{k_{0}k_{1}}W_{mk_{2}}^{(L)}W_{mk_{3}}^{(L)}$$

$$+n_{L}^{-2}\sum_{m}\Theta_{\infty}^{(L)}(x_{0},x_{1})\Theta_{\infty}^{(L)}(x_{1},x_{2})\dot{\sigma}(\alpha_{m}^{(L)}(x_{0}))\ddot{\sigma}(\alpha_{m}^{(L)}(x_{1}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{2}))\sigma(\alpha_{m}^{(L)}(x_{3}))$$

$$-W_{mk_{0}}^{(L)}W_{mk_{1}}^{(L)}\delta_{k_{2}k_{3}}$$

$$+n_{L}^{-2}\sum_{m}\Theta_{\infty}^{(L)}(x_{1},x_{2})\sigma(\alpha_{m}^{(L)}(x_{0}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{1}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{2}))\sigma(\alpha_{m}^{(L)}(x_{3}))\delta_{k_{0}k_{1}}\delta_{k_{2}k_{3}}$$

$$+n_{L}^{-2}\sum_{m}\Theta_{\infty}^{(L)}(x_{0},x_{1})\Theta_{\infty}^{(L)}(x_{2},x_{3})\dot{\sigma}(\alpha_{m}^{(L)}(x_{0}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{1}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{2}))\dot{\sigma}(\alpha_{m}^{(L)}(x_{3}))$$

$$-W_{mk_{0}}^{(L)}\delta_{k_{1}k_{2}}W_{mk_{2}}^{(L)}$$

$$-W_{mk_{0}}^{(L)}\delta_{k_{1}k_{2}}W_{mk_{2}}^{(L)}$$

For the convergence during training, we proceed similarly to the proof of Lemma 1. At initialization, all terms vanish as $n_{\ell} \to \infty$ because all summands are independent (after taking the $n_1, \ldots, n_{L-1} \to \infty$ limit) with zero mean and finite variance. During training, the weights $W^{(\ell)}$ and preactivations $\tilde{\alpha}^{(\ell)}$ move at a rate of $1/\sqrt{n_{\ell}}$ which leads to a change of order $n_{\ell}^{-2+1/2} = n_{\ell}^{-1.5}$, which vanishes for all times t too.

Appendix C. The Matrix S

We now have the theoretical tools to describe the moments of the matrix S. We first give a bound for the rank of S:

Proposition 3.
$$Rank(S) \le 2(n_1 + ... + n_{L-1})Nn_L$$

Proof. We first observe that S is given by a sum of Nn_L matrices:

$$S_{pp'} = \sum_{i=1}^{N} \sum_{k=1}^{n_L} \partial_{ik} C \partial_{\theta_p \theta_p}^2 f_{\theta,k}(x_i).$$

It is therefore sufficient to show that the rank of each matrices $\mathcal{H}f_{\theta,k}(x) = \left(\partial^2_{\theta_p\theta_{p'}}f_{\theta,k}(x_i)\right)_{p,p'}$ is bounded by $2(n_1 + ... + n_L)$.

The derivatives $\partial_{\theta_p} f_{\theta,k}(x)$ have different definition depending on whether the parameter θ_p is a connection weight $W_{ij}^{(\ell)}$ or a bias $b_i^{(\ell)}$:

$$\begin{split} \partial_{W_{ij}^{(\ell)}} f_{\theta,k}(x) &= \frac{1}{\sqrt{n_\ell}} \alpha_i^{(\ell)}(x;\theta) \partial_{\tilde{\alpha}_j^{(\ell+1)}(x;\theta)} f_{\theta,k}(x) \\ \partial_{b_i^{(\ell)}} f_{\theta,k}(x) &= \beta \partial_{\tilde{\alpha}_j^{(\ell+1)}(x;\theta)} f_{\theta,k}(x) \end{split}$$

These formulas only depend on θ through the values $\left(\alpha_i^{(\ell)}(x;\theta)\right)_{\ell,i}$ and $\left(\partial_{\tilde{\alpha}_i^{(\ell)}(x;\theta)}f_{\theta,k}(x)\right)_{\ell,i}$ for $\ell=1,...,L-1$ (note that both $\alpha_i^{(0)}(x)=x_i$ and $\partial_{\tilde{\alpha}_i^{(L)}(x;\theta)}f_{\theta,k}(x)=\delta_{ik}$ do not depend on θ). Together there are $2(n_1+...+n_{L-1})$ of them. As a consequence, the map $\theta\mapsto \left(\partial_{\theta_p}f_{\theta,k}(x_i)\right)_p$ can be written as a composition

$$\theta \in \mathbb{R}^P \mapsto \left(\alpha_i^{(\ell)}(x;\theta), \partial_{\tilde{\alpha}_i^{(\ell)}(x;\theta)} f_{\theta,k}(x)\right)_{\ell,i} \in \mathbb{R}^{2(n_1 + \dots + n_{L-1})} \mapsto \left(\partial_{\theta_p} f_{\theta,k}(x_i)\right)_p \in \mathbb{R}^P$$

and the matrix $\mathcal{H}f_{\theta,k}(x)$ is equal to the Jacobian of this map. By the chain rule, $\mathcal{H}f_{\theta,k}(x)$ is the matrix multiplication of the Jacobians of the two submaps, whose rank are bounded by $2(n_1 + ... + n_{L-1})$, hence bounding the rank of $\mathcal{H}f_{\theta,k}(x)$. And because S is a sum of Nn_L matrices of rank smaller than $2(n_1 + ... + n_{L-1})$, the rank of S is bounded by $2(n_1 + ... + n_{L-1})Nn_L$.

C.1. Moments

Let us now prove Proposition 4:

Proposition 4. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, the first two moments of S take the form

$$\operatorname{Tr}(S(t)) = G(t)^{T} \nabla C(t)$$
$$\operatorname{Tr}(S(t)^{2}) = \nabla C(t)^{T} \tilde{\Upsilon}(t) \nabla C(t)$$

- At initialization, g_{θ} and f_{θ} converge to a (centered) Gaussian pair with covariances

$$\mathbb{E}[g_{\theta,k}(x)g_{\theta,k'}(x')] = \delta_{kk'}\Xi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[g_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Phi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[f_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Sigma_{\infty}^{(L)}(x,x')$$

and during training g_{θ} evolves according to

$$\partial_t g_{\theta,k}(x) = \sum_{i=1}^N \Lambda_{\infty}^{(L)}(x,x_i) \partial_{ik} C(Y(t)).$$

- Uniformly over any interval [0,T] where $\int_0^T \|\nabla C(t)\|_2 dt$ is stochastically bounded, the kernel $\Upsilon^{(L)}$ has a deterministic and fixed limit $\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}\Upsilon^{(L)}_{kk'}(x,x')=\delta_{kk'}\Upsilon^{(L)}_{\infty}(x,x')$ with limiting kernel:

$$\Upsilon_{\infty}^{(L)}(x,x') = \sum_{\ell=1}^{L-1} \left(\Theta_{\infty}^{(\ell)}(x,x')^2 \ddot{\Sigma}^{(\ell)}(x,x') + 2\Theta_{\infty}^{(\ell)}(x,x') \dot{\Sigma}^{(\ell)}(x,x') \right) \dot{\Sigma}^{(\ell+1)}(x,x') \cdots \dot{\Sigma}^{(L-1)}(x,x').$$

- The higher moment k > 2 vanish: $\lim_{n_{L-1} \to \infty} \cdots \lim_{n_1 \to \infty} \operatorname{Tr}(S^k) = 0$.

Proof. The first moment of S takes the form

$$\operatorname{Tr}(S) = \sum_{p} (\nabla C)^{T} \mathcal{H}_{p,p} Y = (\nabla C)^{T} G$$

where G is the restriction to the training set of the function $g_{\theta}(x) = \sum_{p} \partial_{\theta_{p}\theta_{p}}^{2} f_{\theta}(x)$. This process is random at initialization and varies during training. Lemma 3 below shows that, in the infinite width limit, it is a Gaussian process at initialization which then evolves according to a simple differential equation, hence describing the evolution of the first moment during training.

The second moment of S takes the form:

$$\operatorname{Tr}(S^{2}) = \sum_{p_{1}, p_{2}=1}^{P} \sum_{i_{1}, i_{2}=1}^{N} \partial_{\theta_{p_{1}}, \theta_{p_{2}}}^{2} f_{\theta, k_{1}}(x_{1}) \partial_{\theta_{p_{2}}, \theta_{p_{1}}}^{2} f_{\theta, k_{2}}(x_{2}) c'_{i_{1}}(x_{i_{1}}) c'_{i_{2}}(x_{i_{2}})$$
$$= (\nabla C)^{T} \tilde{\Upsilon} \nabla C$$

where $\Upsilon_{k_1,k_2}^{(L)}(x_1,x_2) = \sum_{p_1,p_2=1}^P \partial_{\theta_{p_1},\theta_{p_2}}^2 f_{\theta,k_1}(x_1) \partial_{\theta_{p_2},\theta_{p_1}}^2 f_{\theta,k_2}(x_2)$ is a multidimensional kernel and $\tilde{\Upsilon}$ is its Gram matrix. Lemma 4 below shows that in the infinite-width limit, $\Upsilon_{k_1,k_2}^{(L)}(x_1,x_2)$ converges to a deterministic and time-independent limit $\Upsilon_{\infty}^{(L)}(x_1,x_2)\delta_{k_1k_2}$.

To show that $\operatorname{Tr}(S^k) \to 0$ for all k > 2, it suffices to show that $\|S^2\|_F \to 0$ as $|\operatorname{Tr}(S^k)| < \|S^2\|_F \|S\|_F^{k-2}$ and we know that $\|S\|_F \to (\partial_Y C)^T \, \tilde{\Upsilon} \partial_Y C$ is finite. We have that

$$||S^{2}||_{F} = \sum_{i_{0}, i_{1}, i_{2}, i_{3}=1}^{N} \sum_{k_{0}, k_{1}, k_{2}, k_{3}=1}^{n_{L}} \Psi_{k_{0}, k_{1}, k_{2}, k_{3}}^{(L)}(x_{i_{0}}, x_{i_{1}}, x_{i_{2}}, x_{i_{3}}) \partial_{f_{\theta, k_{0}}(x_{i_{0}})} C \partial_{f_{\theta, k_{1}}(x_{i_{1}})} C \partial_{f_{\theta, k_{2}}(x_{i_{2}})} C \partial_{f_{\theta, k_{3}}(x_{i_{3}})} C \partial_{f_{\theta,$$

for $\tilde{\Psi}$ the $Nn_L \times Nn_L \times Nn_L \times Nn_L$ finite version of

$$\begin{split} \Psi_{k_0,k_1,k_2,k_3}^{(L)}(x_{i_0},x_{i_1},x_{i_2},x_{i_3}) &= \sum_{p_0,p_1,p_2,p_3=1}^P \partial_{\theta_{p_0},\theta_{p_1}}^2 f_{\theta,k_0}(x_0) \partial_{\theta_{p_1},\theta_{p_2}}^2 f_{\theta,k_1}(x_1) \\ &\qquad \qquad \partial_{\theta_{p_2},\theta_{p_3}}^2 f_{\theta,k_2}(x_2) \partial_{\theta_{p_3},\theta_{p_0}}^2 f_{\theta,k_3}(x_3) \end{split}$$

which vanishes in the infinite width limit by Lemma 5 below.

Lemma 3. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, at initialization g_θ and f_θ converge to a (centered) Gaussian pair with covariances

$$\mathbb{E}[g_{\theta,k}(x)g_{\theta,k'}(x')] = \delta_{kk'}\Xi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[g_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Phi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}[f_{\theta,k}(x)f_{\theta,k'}(x')] = \delta_{kk'}\Sigma_{\infty}^{(L)}(x,x')$$

and during training g_{θ} evolves according to

$$\partial_t g_{\theta}(x) = \sum_{i=1}^N \Lambda_{\infty}^{(L)}(x, x_i) D_i(t)$$

Proof. When L = 1, $g_{\theta}(x)$ is 0 for any x and θ .

For the inductive step, the trace $g_{\theta,k}^{(L+1)}(x)$ is defined recursively as

$$\frac{1}{\sqrt{n_L}} \sum_{m=1}^{n_L} g_{\theta,m}^{(L)}(x) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) W_{mk}^{(L)} + \operatorname{Tr} \left(\nabla f_{\theta,m}(x) \left(\nabla f_{\theta,m}(x) \right)^T \right) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) W_{mk}^{(L)}$$

First note that $\operatorname{Tr}\left(\nabla f_{\theta,m}(x) \left(\nabla f_{\theta,m}(x)\right)^T\right) = \Theta_{mm}^{(L)}(x,x)$. Now let $n_1, ... n_{L-1} \to \infty$, by the induction hypothesis, the pairs $(g_{\theta,m}^{(L)}, \tilde{\alpha}_m^{(L)})$ converge to iid Gaussian pairs of processes with covariance $\Phi_{\infty}^{(L)}$ at initialization.

At initialization, conditioned on the values of $g_m^{(L)}$, $\tilde{\alpha}_m^{(L)}$ the pairs $(g_k^{(L+1)}, f_\theta)$ follow a centered Gaussian distribution with (conditioned) covariance

$$\mathbb{E}[g_{\theta,k}^{(L+1)}(x)g_{\theta,k'}^{(L+1)}(x')|g_{\theta,m}^{(L)},\tilde{\alpha}_{m}^{(L)}] = \frac{\delta_{kk'}}{n_L} \sum_{m=1}^{n_L} \left(g_{\theta,m}^{(L)}(x)\dot{\sigma}\left(\tilde{\alpha}_{m}^{(L)}(x)\right) + \Theta_{\infty}^{(L)}(x,x)\ddot{\sigma}\left(\tilde{\alpha}_{m}^{(L)}(x)\right)\right)$$

$$\left(g_{\theta,m}^{(L)}(x')\dot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x')\right) + \Theta_{\infty}^{(L)}(x',x')\ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x')\right)\right)$$

$$\mathbb{E}[g_{\theta,k}^{(L+1)}(x)f_{\theta,k'}(x')|g_{\theta,m}^{(L)},\tilde{\alpha}_m^{(L)}] = \frac{\delta_{kk'}}{n_L}\sum_{m=1}^{n_L} \left(g_{\theta,m}^{(L)}(x)\dot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x)\right) + \Theta_{\infty}^{(L)}(x,x)\ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x)\right)\right)$$

$$\sigma\left(\tilde{\alpha}_m^{(L)}(x')\right)$$

$$\mathbb{E}[f_{\theta,k}(x)f_{\theta,k'}(x')|g_{\theta,m}^{(L)},\tilde{\alpha}_m^{(L)}] = \frac{\delta_{kk'}}{n_L}\sum_{m=1}^{n_L} \sigma\left(\tilde{\alpha}_m^{(L)}(x)\right)\sigma\left(\tilde{\alpha}_m^{(L)}(x')\right) + \beta^2.$$

As $n_L \to \infty$, by the law of large number, these (random) covariances converge to their expectations which are deterministic, hence the pairs $(g_k^{(L+1)}, f_{\theta k})$ have asymptotically the same Gaussian distribution independent of $g_m^{(L)}, \tilde{\alpha}_m^{(L)}$:

$$\mathbb{E}\left[g_{\theta,k}^{(L)}(x)g_{\theta,k'}^{(L)}(x')\right] \to \delta_{kk'}\Xi_{\infty}^{(L)}(x,x')$$

$$\mathbb{E}\left[g_{\theta,k}^{(L)}(x)f_{\theta,k'}^{(L)}(x')\right] \to \delta_{kk'}\Phi_{\infty}^{(L)}(x,x)$$

$$\mathbb{E}\left[f_{\theta,k}^{(L)}(x)f_{\theta,k'}^{(L)}(x')\right] \to \delta_{kk'}\Sigma_{\infty}^{(L)}(x,x)$$

with
$$\Xi_{\infty}^{(1)}(x,x') = \Phi_{\infty}^{(1)}(x,x') = 0$$
 and
$$\Xi_{\infty}^{(L+1)}(x,x') = \mathbb{E}\left[gg'\dot{\sigma}(\alpha)\dot{\sigma}(\alpha')\right] + \Theta_{\infty}^{(L)}(x',x')\mathbb{E}\left[g\dot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right] + \Theta_{\infty}^{(L)}(x,x)\mathbb{E}\left[g'\dot{\sigma}(\alpha')\ddot{\sigma}(\alpha)\right] + \Theta_{\infty}^{(L)}(x,x)\Theta_{\infty}^{(L)}(x',x')\mathbb{E}\left[\ddot{\sigma}(\alpha')\ddot{\sigma}(\alpha)\right] = \Xi_{\infty}^{(L)}(x,x')\dot{\Sigma}_{\infty}^{(L)}(x,x') + \left(\Phi_{\infty}^{(L)}(x,x')\Phi_{\infty}^{(L)}(x',x) + \Phi_{\infty}^{(L)}(x,x)\Phi_{\infty}^{(L)}(x',x')\right)\ddot{\Sigma}_{\infty}^{(L)}(x,x') + \Phi_{\infty}^{(L)}(x,x')\Phi_{\infty}^{(L)}(x',x')\mathbb{E}\left[\ddot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right] + \Phi_{\infty}^{(L)}(x,x')\Phi_{\infty}^{(L)}(x',x')\mathbb{E}\left[\ddot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right] + \Theta_{\infty}^{(L)}(x,x')\left(\Phi_{\infty}^{(L)}(x,x)\ddot{\Sigma}_{\infty}^{(L)}(x,x') + \Phi_{\infty}^{(L)}(x,x')\mathbb{E}\left[\ddot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right]\right) + \Theta_{\infty}^{(L)}(x,x)\Theta_{\infty}^{(L)}(x',x')\ddot{\Sigma}_{\infty}^{(L)}(x,x') + \Phi_{\infty}^{(L)}(x',x)\mathbb{E}\left[\ddot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right]\right) + \Theta_{\infty}^{(L)}(x,x)\Theta_{\infty}^{(L)}(x',x')\ddot{\Sigma}_{\infty}^{(L)}(x,x') + \Phi_{\infty}^{(L)}(x',x)\mathbb{E}\left[\ddot{\sigma}(\alpha)\ddot{\sigma}(\alpha')\right]\right) + \Theta_{\infty}^{(L)}(x,x)\Theta_{\infty}^{(L)}(x',x')\ddot{\Sigma}_{\infty}^{(L)}(x,x')$$

and

$$\begin{split} \Phi_{\infty}^{(L+1)}(x,x') &= \mathbb{E}\left[g\dot{\sigma}(\alpha)\sigma(\alpha')\right] + \Theta_{\infty}^{(L)}(x,x)\mathbb{E}\left[\ddot{\sigma}(\alpha)\sigma(\alpha')\right] \\ &= \Phi_{\infty}^{(L)}(x,x')\dot{\Sigma}^{(L+1)}(x,x') + \left(\Phi_{\infty}^{(L)}(x,x) + \Theta_{\infty}^{(L)}(x,x)\right)\mathbb{E}\left[\ddot{\sigma}(\alpha)\sigma(\alpha')\right] \end{split}$$

where (g, g', α, α') is a Gaussian quadruple of covariance

$$\begin{pmatrix} \Xi_{\infty}^{(L)}(x,x) & \Xi_{\infty}^{(L)}(x,x') & \Phi_{\infty}^{(L)}(x,x) & \Phi_{\infty}^{(L)}(x,x') \\ \Xi_{\infty}^{(L)}(x,x') & \Xi_{\infty}^{(L)}(x',x') & \Phi_{\infty}^{(L)}(x',x) & \Phi_{\infty}^{(L)}(x',x') \\ \Phi_{\infty}^{(L)}(x,x) & \Phi_{\infty}^{(L)}(x',x) & \Sigma_{\infty}^{(L)}(x,x) & \Sigma_{\infty}^{(L)}(x,x') \\ \Phi_{\infty}^{(L)}(x,x') & \Phi_{\infty}^{(L)}(x',x') & \Sigma_{\infty}^{(L)}(x,x') & \Sigma_{\infty}^{(L)}(x',x') \end{pmatrix}.$$

During training, the parameters follow the gradient $\partial_t \theta(t) = (\partial_\theta Y(t))^T D(t)$. By the induction hypothesis, the traces $g_{\theta,m}^{(L)}$ then evolve according to the differential equation

$$\partial_t g_{\theta,m}^{(L)}(x) = \frac{1}{\sqrt{n_L}} \sum_{i=1}^N \sum_{m=1}^{n_L} \Lambda_{mm'}^{(L)}(x, x_i) \dot{\sigma}(\tilde{\alpha}_{m'}^{(L)}(x)) \left(W_{m'}^{(L)}\right)^T D_i(t)$$

and in the limit as $n_1, ..., n_{L-1} \to \infty$, the kernel $\Lambda_{mm'}^{(L)}(x, x_i)$ converges to a deterministic and fixed limit $\delta_{mm'}\Lambda_{\infty}^{(L)}(x, x_i)$. Note that as n_L grows, the $g_{\theta,m}^{(L)}(x)$ move at a rate of $1/\sqrt{n_L}$

just like the pre-activations $\tilde{\alpha}_m^{(L)}$. Even though they move less and less, together they affect the trace $g_{\theta,k}^{(L+1)}$ which follows the differential equation

$$\partial_t g_{\theta,k}^{(L+1)}(x) = \sum_{i=1}^N \sum_{k'=1}^{n_L} \Lambda_{kk'}^{(L+1)}(x, x_i) D_{ik'}(t)$$

where

$$\begin{split} \Lambda_{kk'}^{(L+1)}(x,x') &= \frac{1}{n_L} \sum_{m,m'} \Lambda_{mm'}^{(L)}(x,x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m,m'} g_{\theta,m}^{(L)}(x) \Theta_{mm'}^{(L)}(x,x') \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m} g_{\theta,m}^{(L)}(x) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \sigma \left(\tilde{\alpha}_m^{(L)}(x') \right) \delta_{kk'} \\ &+ \frac{2}{n_L} \sum_{m,m'} \Omega_{m'mm}^{(L)}(x',x,x) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m,m'} \Theta_{mm}^{(L)}(x,x) \Theta_{mm'}^{(L)}(x,x') \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m} \Theta_{mm}^{(L)}(x,x) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \sigma \left(\tilde{\alpha}_m^{(L)}(x') \right) \delta_{kk'}. \end{split}$$

As $n_1, ..., n_{L-1} \to \infty$, the kernels $\Theta_{mm'}^{(L)}(x, x')$ and $\Lambda_{mm'}^{(L)}(x, x')$ converge to their limit and $\Omega_{m'mm}^{(L)}(x', x, x)$ vanishes:

$$\begin{split} \Lambda_{kk'}^{(L)}(x,x') &\to \frac{1}{n_L} \sum_m \Lambda_{\infty}^{(L)}(x,x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) W_{mk}^{(L)} W_{mk'}^{(L)} \\ &+ \frac{1}{n_L} \sum_m g_{\theta,m}^{(L)}(x) \Theta_{\infty}^{(L)}(x,x') \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) W_{mk}^{(L)} W_{mk'}^{(L)} \\ &+ \frac{1}{n_L} \sum_m g_{\theta,m}^{(L)}(x) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \sigma \left(\tilde{\alpha}_m^{(L)}(x') \right) \delta_{kk'} \\ &+ \frac{1}{n_L} \sum_m \Theta_{\infty}^{(L)}(x,x) \Theta_{\infty}^{(L)}(x,x') \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) W_{mk}^{(L)} W_{mk'}^{(L)} \\ &+ \frac{1}{n_L} \sum_m \Theta_{\infty}^{(L)}(x,x) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \sigma \left(\tilde{\alpha}_m^{(L)}(x') \right) \delta_{kk'} \end{split}$$

By the law of large numbers, as $n_L \to \infty$, at initialization $\Lambda_{kk'}^{(L+1)}(x,x') \to \delta_{kk'}\Lambda_{\infty}^{(L+1)}(x,x')$ where

$$\begin{split} \Lambda_{\infty}^{(L+1)}(x,x') &= \Lambda_{\infty}^{(L)}(x,x') \dot{\Sigma}_{\infty}^{(L+1)}(x,x') \\ &+ \Theta_{\infty}^{(L)}(x,x') \mathbb{E} \left[g \ddot{\sigma} \left(\alpha \right) \dot{\sigma} \left(\alpha' \right) \right] \\ &+ \mathbb{E} \left[g \dot{\sigma} \left(\alpha \right) \sigma \left(\alpha' \right) \right] \\ &+ \Theta_{\infty}^{(L)}(x,x) \Theta_{\infty}^{(L)}(x,x') \mathbb{E} \left[\ddot{\sigma} \left(\alpha \right) \dot{\sigma} \left(\alpha' \right) \right] \\ &+ \Theta_{\infty}^{(L)}(x,x) \mathbb{E} \left[\ddot{\sigma} \left(\alpha \right) \sigma \left(\alpha' \right) \right] \\ &= \Lambda_{\infty}^{(L)}(x,x') \dot{\Sigma}_{\infty}^{(L+1)}(x,x') \\ &+ \Theta_{\infty}^{(L)}(x,x') \left(\Phi_{\infty}^{(L)}(x,x') \ddot{\Sigma}_{\infty}^{(L+1)}(x,x') + \Phi_{\infty}^{(L)}(x,x) \mathbb{E} \left[\ddot{\sigma} \left(\alpha \right) \dot{\sigma} \left(\alpha' \right) \right] \right) \\ &+ \Phi_{\infty}^{(L)}(x,x') \dot{\Sigma}_{\infty}^{(L+1)}(x,x') + \Phi_{\infty}^{(L)}(x,x) \mathbb{E} \left[\ddot{\sigma} \left(\alpha \right) \sigma \left(\alpha' \right) \right] \\ &+ \Theta_{\infty}^{(L)}(x,x) \Theta_{\infty}^{(L)}(x,x') \mathbb{E} \left[\ddot{\sigma} \left(\alpha \right) \dot{\sigma} \left(\alpha' \right) \right] \end{split}$$

$$+\Theta_{\infty}^{(L)}(x,x)\mathbb{E}\left[\ddot{\sigma}\left(\alpha\right)\dot{\sigma}\left(\alpha'\right)\right]$$

During training $\Theta_{\infty}^{(L)}$ and $\Lambda_{\infty}^{(L)}$ are fixed in the limit $n_1, ..., n_{L-1} \to \infty$, and the values $g_{\theta,m}^{(L)}(x)$, $\tilde{\alpha}_m^{(L)}(x)$ and $W_{mk}^{(L)}$ vary at a rate of $1/\sqrt{n_L}$ which induce a change of the same rate to $\Lambda_{kk'}^{(L)}(x,x')$, which is therefore asymptotically fixed during training as $n_L \to \infty$.

The next lemma describes the asymptotic limit of the kernel $\Upsilon^{(L)}$:

Lemma 4. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, the second moment of the Hessian of the realization function $\mathcal{H}F^{(L)}$ converges uniformly over [0,T] to a fixed limit as $n_1,...n_{L-1} \to \infty$

$$\Upsilon_{kk'}^{(L)}(x,x') \to \delta_{kk'} \sum_{\ell=1}^{L-1} \left(\Theta_{\infty}^{(\ell)}(x,x')^2 \ddot{\Sigma}_{\infty}^{(\ell)}(x,x') + 2\Theta_{\infty}^{(\ell)}(x,x') \dot{\Sigma}_{\infty}^{(\ell)}(x,x') \right) \dot{\Sigma}_{\infty}^{(\ell+1)}(x,x') \cdots \dot{\Sigma}_{\infty}^{(L-1)}(x,x').$$

Proof. The proof is by induction on the depth L. The case L=1 is trivially true because $\partial^2_{\theta_n\theta_{n'}}f_{\theta,k}(x)=0$ for all p,p',k,x. For the induction step we observe that

$$\begin{split} &\Upsilon_{k,k'}^{(L)}(x,x') \\ &= \sum_{p_1,p_2=1}^{P} \partial_{\theta_{p_1},\theta_{p_2}}^2 f_{\theta,k}(x) \partial_{\theta_{p_2},\theta_{p_1}}^2 f_{\theta,k'}(x') \\ &= \frac{1}{n_L} \sum_{m,m'=1}^{n_L} \Upsilon_{m,m'}^{(L)}(x,x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m,m'=1}^{n_L} \Omega_{m',m,m'}^{(L)}(x',x,x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \ddot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m,m'=1}^{n_L} \Omega_{m,m',m}^{(L)}(x,x',x) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{1}{n_L} \sum_{m,m'=1}^{n_L} \Theta_{m,m'}^{(L)}(x,x') \Theta_{m',m}^{(L)}(x',x) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \ddot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) W_{mk}^{(L)} W_{m'k'}^{(L)} \\ &+ \frac{2}{n_L} \sum_{m=1}^{n_L} \Theta_{m,m'}^{(L)}(x,x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_{m'}^{(L)}(x') \right) \delta_{kk'} \end{split}$$

if we now let the width of the lower layers grow to infinity $n_1, ... n_{L-1} \to \infty$, the tensor $\Omega^{(L)}$ vanishes and $\Upsilon_{m,m'}^{(L)}$ and the NTK $\Theta_{m,m'}^{(L)}$ converge to limits which are non-zero only when m=m'. As a result, the term above converges to

$$\frac{1}{n_L} \sum_{m=1}^{n_L} \Upsilon_{\infty}^{(L)}(x, x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) W_{mk}^{(L)} W_{mk'}^{(L)} \\
+ \frac{1}{n_L} \sum_{m=1}^{n_L} \Theta_{\infty}^{(L)}(x, x')^2 \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \ddot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) W_{mk}^{(L)} W_{mk'}^{(L)} \\
+ \frac{2}{n_L} \sum_{m=1}^{n_L} \Theta_{\infty}^{(L)}(x, x') \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x) \right) \dot{\sigma} \left(\tilde{\alpha}_m^{(L)}(x') \right) \delta_{kk'}$$

At initialization, we can apply the law of large numbers as $n_L \to \infty$ such that it converges to $\Upsilon^{(L+1)}_{\infty}(x,x')\delta_{kk'}$, for the kernel $\Upsilon^{(L+1)}_{\infty}(x,x')$ defined recursively by

$$\Upsilon_{\infty}^{(L+1)}(x,x') = \Upsilon_{\infty}^{(L)}(x,x')\dot{\Sigma}_{\infty}^{(L)}(x,x') + \Theta_{\infty}^{(L)}(x,x')^2 \ddot{\Sigma}_{\infty}^{(L)}(x,x') + 2\Theta_{\infty}^{(L)}(x,x')\dot{\Sigma}_{\infty}^{(L)}(x,x')$$

and
$$\Upsilon_{\infty}^{(1)}(x, x') = 0$$
.

For the convergence during training, we proceed similarly to the proof of Lemma 1: the activations $\tilde{\alpha}_m^{(L)}(x)$ and weights $W_{mk}^{(L)}$ move at a rate of $1/\sqrt{n_L}$ and the change to $\Upsilon_{kk'}^{(L+1)}$ is therefore of order $1/\sqrt{n_L}$ and vanishes as $n_L \to 0$.

Finally, the next lemma shows the vanishing of the tensor $\Psi_{k_0,k_1,k_2,k_3}^{(L)}$ to prove that the higher moments of S vanish.

Lemma 5. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, uniformly over [0,T]

$$\lim_{n_{L-1}\to\infty}\cdots\lim_{n_{1}\to\infty}\Psi_{k_{0},k_{1},k_{2},k_{3}}^{(L)}(x_{i_{0}},x_{i_{1}},x_{i_{2}},x_{i_{3}})=0$$

Proof. When L = 1 the Hessian is zero and $\Psi_{k_0, k_1, k_2, k_3}^{(1)}(x_{i_0}, x_{i_1}, x_{i_2}, x_{i_3}) = 0$.

For the induction step, we write $\Psi_{k_0,k_1,k_2,k_3}^{(L+1)}(x_{i_0},x_{i_1},x_{i_2},x_{i_3})$ recursively, because it contains many terms, we change the notation, writing $\begin{bmatrix} x_0 & x_1 \\ m_0 & m_1 \end{bmatrix}$ for $\Theta_{m_0,m_1}^{(L)}(x_0,x_1)$, $\begin{bmatrix} x_0 & x_1 & x_2 \\ m_0 & m_1 & m_2 \end{bmatrix}$ for $\Omega_{m_0,m_1,m_2}^{(L)}(x_0,x_1,x_2)$ and $\begin{bmatrix} x_0 & x_1 & x_2 & x_3 \\ m_0 & m_1 & m_2 & m_3 \end{bmatrix}$ for $\Gamma_{m_0,m_1,m_2,m_3}^{(L)}(x_0,x_1,x_2,x_3)$. The value $\Psi_{k_0,k_1,k_2,k_3}^{(L+1)}(x_{i_0},x_{i_1},x_{i_2},x_{i_3})$ is then equal to

$$\begin{split} n_L^{-2} & \sum_{m_0,m_1,m_2,m_3} \Psi_{m_0,m_1,m_2,m_3}^{(L)}(x_0,x_1,x_2,x_3) \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k_1}^{(L)} W_{m_2k_2}^{(L)} W_{m_3k_3}^{(L)} \\ & + n_L^{-2} \sum_{m_0,m_1,m_2,m_3} \left[\begin{array}{c} x_0 & x_1 \\ m_0 & m_1 \end{array} \right] \left[\begin{array}{c} x_1 & x_2 \\ m_1 & m_2 \end{array} \right] \left[\begin{array}{c} x_2 & x_3 \\ m_2 & m_3 \end{array} \right] \left[\begin{array}{c} x_3 & x_0 \\ m_3 & m_0 \end{array} \right] \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k_1}^{(L)} W_{m_2k_2}^{(L)} W_{m_3k_3}^{(L)} \\ & + n_L^{-2} \sum_{m_0,m_1,m_2,m_3} \left[\begin{array}{c} x_0 & x_1 & x_2 \\ m_0 & m_1 & m_2 \end{array} \right] \left[\begin{array}{c} x_2 & x_3 \\ m_2 & m_3 \end{array} \right] \left[\begin{array}{c} x_3 & x_0 \\ m_3 & m_0 \end{array} \right] \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k_1}^{(L)} W_{m_2k_2}^{(L)} W_{m_3k_3}^{(L)} \\ & + n_L^{-2} \sum_{m_0,m_1,m_2,m_3} \left[\begin{array}{c} x_0 & x_1 \\ m_0 & m_1 \end{array} \right] \left[\begin{array}{c} x_1 & x_2 & x_3 \\ m_1 & m_2 \end{array} \right] \left[\begin{array}{c} x_3 & x_0 \\ m_3 & m_0 \end{array} \right] \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k_1}^{(L)} W_{m_2k_2}^{(L)} W_{m_3k_3}^{(L)} \\ & + n_L^{-2} \sum_{m_0,m_1,m_2,m_3} \left[\begin{array}{c} x_0 & x_1 \\ m_0 & m_1 \end{array} \right] \left[\begin{array}{c} x_1 & x_2 \\ m_1 & m_2 \end{array} \right] \left[\begin{array}{c} x_2 & x_3 \\ m_2 & m_3 \end{array} \right] \left[\begin{array}{c} x_3 & x_0 \\ m_3 & x_0 \end{array} \right] \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k_1}^{(L)} W_{m_2k_2}^{(L)} W_{m_3k_3}^{(L)} \\ & + n_L^{-2} \sum_{m_0,m_1,m_2,m_3} \left[\begin{array}{c} x_1 & x_2 \\ m_1 & m_2 \end{array} \right] \left[\begin{array}{c} x_2 & x_3 \\ m_2 & m_3 \end{array} \right] \left[\begin{array}{c} x_3 & x_0 \\ m_3 & x_0 \end{array} \right] \dot{\sigma} \left(\check{\alpha}_{m_0}^{(L)}(x_0) \right) \dot{\sigma} \left(\check{\alpha}_{m_1}^{(L)}(x_1) \right) \\ & \dot{\sigma} \left(\check{\alpha}_{m_2}^{(L)}(x_2) \right) \dot{\sigma} \left(\check{\alpha}_{m_3}^{(L)}(x_3) \right) W_{m_0k_0}^{(L)} W_{m_1k$$

Even though this is a very large formula one can notice that most terms are "rotation of each other". Moreover, as $n_1, ..., n_{L-1} \to \infty$, all terms containing either an $\Psi^{(L)}$, an $\Omega^{(L)}$ or a $\Gamma^{(L)}$ vanish. For the remaining terms, we may replace the NTKs $\Theta^{(L)}$ by their limit and

as a result
$$\Psi_{k_0,k_1,k_2,k_3}^{(L+1)}(x_0,x_1)\Theta_{\infty}^{(L)}(x_1,x_2)\Theta_{\infty}^{(L)}(x_2,x_3)\Theta_{\infty}^{(L)}(x_3,x_0)\ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x_0)\right)\ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x_1)\right)$$

$$\qquad \qquad \ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x_2)\right)\ddot{\sigma}\left(\tilde{\alpha}_m^{(L)}(x_3)\right)W_{mk_0}^{(L)}W_{mk_1}^{(L)}W_{mk_2}^{(L)}W_{mk_3}^$$

And all these sums vanish as $n_L \to \infty$ thanks to the prefactor n_L^{-2} , proving the vanishing of $\Psi_{k_0,k_1,k_2,k_3}^{(L+1)}(x_{i_0},x_{i_1},x_{i_2},x_{i_3})$ in the infinite width limit.

During training, the activations $\tilde{\alpha}_m^{(L)}(x)$ and weights $W_{mk}^{(L)}$ move at a rate of $1/\sqrt{n_L}$ which induces a change to $\Psi^{(L+1)}$ of order $n_L^{-3/2}$ which vanishes in the infinite width limit.

Appendix D. Orthogonality of I and S

From Lemma 2 and the vanishing of the tensor $\Gamma^{(L)}$ as proven in Lemma 2, we can easily prove the orthogonality of I and S of Proposition 5:

Proposition 5. For any loss C with BGOSS and $\sigma \in C_b^4(\mathbb{R})$, we have uniformly over [0,T]

$$\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}||IS||_F=0.$$

As a consequence $\lim_{n_{L-1}\to\infty}\cdots\lim_{n_1\to\infty}\operatorname{Tr}\left(\left[I+S\right]^k\right)-\left[\operatorname{Tr}\left(I^k\right)+\operatorname{Tr}\left(S^k\right)\right]=0.$

Proof. The Frobenius norm of IS is equal to

$$||IS||_F^2 = ||DYHC(DY)^T(\nabla C \cdot HY)||_F^2$$

$$= \sum_{p_1, p_2 = 1}^P \left(\sum_{p=1}^P \sum_{i_1, i_2 = 1}^N \sum_{k_1, k_2 = 1}^{n_L} \partial_{\theta_{p_1}} f_{\theta, k_1}(x_{i_1}) c_{k_1}''(x_{i_1}) \partial_{\theta_p} f_{\theta, k_1}(x_{i_1}) \partial_{\theta_p, \theta_{p_3}}^2 f_{\theta, k_2}(x_2)(x_{i_2}) c_{k_2}'(x_{i_2})\right)^2$$

$$=\sum_{i_1,i_2,i_1',i_2'=1}^{N}\sum_{k_1,k_2,k_1',k_2'=1}^{n_L}c_{k_1}''(x_{i_1})c_{k_1'}''(x_{i_1'})c_{k_2}'(x_{i_2})c_{k_2'}'(x_{i_2'})\Theta_{k_1,k_1'}(x_{i_1},x_{i_1'})\Gamma_{k_1,k_2,k_2',k_1'}(x_{i_1},x_{i_2},x_{i_2'},x_{i_1'})$$

and Γ vanishes as $n_1, ..., n_{L-1} \to \infty$ by Lemma 2.

The k-th moment of the sum $\operatorname{Tr}(I+S)^k$ is equal to the sum over all $\operatorname{Tr}(A_1\cdots A_k)$ for any word $A_1\ldots A_k$ of $A_i\in\{I,S\}$. The difference $\operatorname{Tr}\left([I+S]^k\right)-\left[\operatorname{Tr}\left(I^k\right)+\operatorname{Tr}\left(S^k\right)\right]$ is hence equal to the sum over all mixed words, i.e. words $A_1\ldots A_k$ which contain at least one I and one S. Such words must contain two consecutive terms A_mA_{m+1} one equal to I and the other equal to I. We can then bound the trace by

$$|\operatorname{Tr}(A_1 \cdots A_k)| \le ||A_1||_F \cdots ||A_{m-1}||_F ||A_m A_{m+1}||_F ||A_{m+2}||_F \cdots ||A_k||_F$$

which vanishes in the infinite width limit because $||I||_F$ and $||S||_F$ are bounded and $||A_mA_{m+1}||_F = ||IS||_F$ vanishes.