
Supplementary Materials: Understanding the Failure of Batch Normalization for Transformers in NLP

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A Experimental Details

In the main paper, we sketch the experimental settings. Here, we report the details. Our WMT16 experiments require two NVIDIA 3090 GPUs with 24GB memory each, and other experiments are implemented with one NVIDIA 3090 GPU.

Neural Machine Translation

Datasets We use two widely used datasets: IWSLT14 German-to-English (De-En) dataset and WMT16 English-to-German (En-De) dataset. IWSLT14/WMT16 contains 0.15M/4.5M sentence pairs.

Configurations Our code is based on *fairseq* [1]¹. We use six encoder layers and six decoder layers for both datasets. We keep the Transformer decoder unchanged and only modify normalization layers in Transformer encoder throughout NMT experiments. We follow the model settings in [2] for IWSLT14 and apply Transformer_{base} model [3] for WMT16. At test phase, we averaged the last six checkpoints and measure case sensitive tokenized BLEU [4] with beam size 4/5 and length penalty 0.6/1.0 for IWSLT14/WMT16. We use Adam with $(\beta_1, \beta_2) = (0.9, 0.98)$, an inverse square root learning rate scheduler, and a warmup stage with 8000 steps. We apply labeling smoothing $\epsilon_{ls} = 0.1$. For IWSLT14, we set num-tokens=4096, max-epochs=60, dropout=0.3, attention dropout=0.1, activation dropout=0.1 and lr= $5e^{-4}/1.5e^{-3}$ for Post-Norm/Pre-Norm Transformer. For WMT16, we set num-tokens=8192, update-freq=4, max-epochs=20, dropout=0.1, attention dropout=0.1, activation dropout=0.1 and lr= $7e^{-4}/2e^{-3}$ for Post-Norm/Pre-Norm Transformer.

Language Modeling

Datasets We conduct experiments on PTB (0.93M tokens) [5] and WikiText-103 (WT103)(100M tokens) [6]. We follow the evaluation scheme in [7] and use perplexity (PPL) of test set to compare the model performance.

Configurations Following the experimental settings in [2][8], we use three and six layers tensorized transformer core-1 for PTB and Wikitext-103 separately. We use the same hyperparameters for Post-Norm and Pre-Norm Transformer. We use Adam optimizer and set lr= $2.5e^{-4}$ with linear decay. For PTB, we use dropout=0.3, batch size=120, max-steps=20000. For PTB, we use dropout=0.1, batch size=60, max-steps=200000.

¹<https://github.com/pytorch/fairseq>. MIT license.

Named Entity Recognition

Datasets We choose two widely used NER datasets: CoNLL2003 (English) [9] and Resume (Chinese) [10]. CoNLL2003/Resume contains four/eight kinds of named entities. CoNLL2003 contains 14.0k/3.2k/3.5k sentences for train/dev/test split while Resume includes 3.8k/0.5k/0.5k sentences for train/dev/test set. We use F1 score to measure the model performance.

Configurations We mainly follow the experimental settings in [11]. We use two and four layers transformer encoder for CoNLL2003 and Resume, respectively. An additional CRF layer [12] is added to model the transition probability. We use SGD optimizer with 0.9 momentum and 1% total steps as warmup steps. We set the learning rate to be $9e^{-4}$ and $7e^{-4}$ for CoNLL2003 and Resume.

Text Classification

Datasets For text classification, we use the code² and most configurations in [13]. We select one small scale dataset (IMDB [14]) and three large scale datasets (Yelp, DBPedia, Sogou News), including two sentiment classification tasks (IMDB, Yelp) and two topic classification tasks (DBPedia, Sogou News).

Configurations We use six Transformer encoder layers with a CLS token at the beginning of each sentence for classification. We extract 30% of training data as validation set for all datasets. The best checkpoint for the validation is applied in the test phase. We run three times with different random seeds for each setting and report the mean accuracy.

B Optimal Hyperparameters

For RBN, we choose λ, ν both from $\{0, 0.01, 0.1, 1\}$ by validation loss. We empirically find that increasing the mean penalty on NMT for Post-Norm Transformer can further improve the BLEU scores. Thus, we apply $(\lambda, \nu) = (10, 0) / (100, 0)$ on ISWLT14/WMT16 for Post-Norm Transformer exceptionally.

Table 1: Optimal hyperparameters (λ, ν) for each experimental setting. (λ, ν) are mean and variance penalty coefficients separately.

Task	NMT		LM		NER			TextCls		
Datasets	IWSLT14	WMT16	PTB	WT103	Resume	CoNLL	IMDB	Sogou	DBPedia	Yelp
Post-Norm	(10,0)	(100,0)	(0.1,0.01)	(0.1,0.01)	(0.01,0)	(0.01,0)	(0.1,0)	(0.1,0.01)	(0.1,0.01)	(0,0.1)
Pre-Norm	(0.1,0.01)	(0.1,0)	(0.01,0)	(0.1,0)	(0.01,0)	(0.01,0)	(0,0.01)	(0.1,0.01)	(0.1,0.01)	(0.1,0.01)

C Average TID of BN and RBN

In the main paper, we have shown the TID of the last BN (RBN) layer on various NLP datasets with Post-Norm or Pre-Norm Transformer. Here, we report the average TID of all BN (RBN) layers (Table 2). RBN decreases the average TID of BN.

D Figures of TID Through Training

We have shown the average mean and variance TID on WMT16/CoNLL/IMDB/WT103 for Pre-Norm Transformer with BN and RBN in the main paper. Here, we plot the average mean and variance TID on other datasets with Pre-Norm and Post-Norm Transformers in Figures 1 to 4. RBN reduces the TID of BN effectively.

²<https://github.com/declare-lab/identifiable-transformers>. Apache-2.0 license.

Table 2: Average TID of all BN/RBN layer in Post-Norm and Pre-Norm Transformers on various natural language tasks at the end of training. RBN reduces the TID of BN effectively.

Task	NMT		LM		NER			TextCls		
Datasets	IWSLT14	WMT16	PTB	WT103	Resume	CoNLL	IMDB	Sogou	DBPedia	Yelp
Post-Norm Transformer										
Mean TID of BN_avg	2.8%	3.0%	1.0%	0.9%	5.0%	9.9%	1.5%	1.9%	1.3%	2.7%
Mean TID of RBN_avg	0.8%	1.5%	1.0%	1.0%	4.4%	5.6%	0.4%	0.4%	0.4%	0.4%
Var TID of BN_avg	7.1%	4.9%	1.1%	2.2%	4.2%	9.8%	3.1%	2.1%	1.4%	3.9%
Var TID of RBN_avg	2.6%	2.8%	1.0%	1.0%	4.0%	6.5%	1.7%	0.3%	0.3%	0.2%
Pre-Norm Transformer										
Mean TID of BN_avg	3.2%	7.6%	1.6%	2.1%	10.3%	10.8%	2.1%	4.2%	2.5%	4.2%
Mean TID of RBN_avg	3.0%	1.6%	1.6%	2.0%	6.7%	5.9%	0.8%	1.2%	1.2%	1.1%
Var TID of BN_avg	5.5%	12.8%	1.6%	1.9%	8.1%	7.4%	3.6%	3.7%	2.1%	5.1%
Var TID of RBN_avg	1.6%	5.6%	1.6%	1.8%	7.5%	6.1%	1.9%	0.5%	0.5%	0.5%

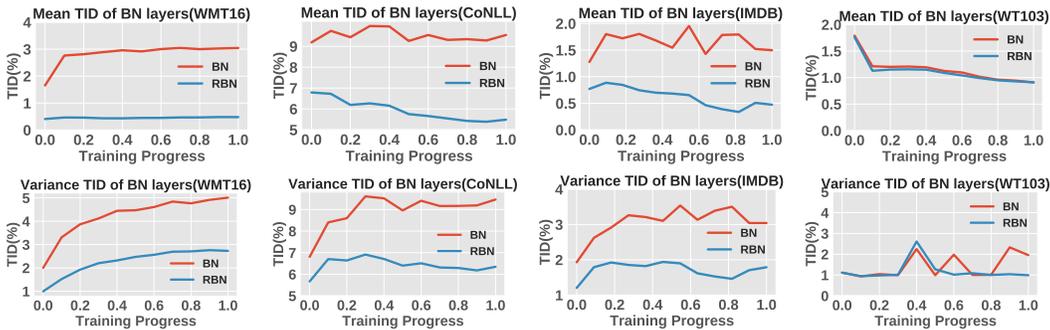


Figure 1: Averaged Mean and Variance TID on WMT16/CoNLL/IMDB/WT103 for Post-Norm Transformer with BN and RBN.

E Other settings of BN in Test Stage

In the main paper, we test BN (RBN) with population statistics estimated by Exponential Moving Average (EMA). Here, we test two other settings of BN on IWSLT14 dataset. In the first setting (Table 3), we reestimate the population statistics of BN by running two more epochs with zero learning rate. In the second setting (Table 4), we test BN with batch statistics of different effective batch size (max-tokens).

From Table 3, we can see that reestimating the population statistics leads to similar results as EMA. However, using batch statistics instead of population statistics boosts the performance of Post-Norm Transformer_{BN}, but hurts the performance of Pre-Norm Transformer_{BN} and Post-Norm Transformer_{RBN} (Table 4). Pre-Norm Transformer_{RBN} is robust to different max-tokens. Note that Transformer_{LN} achieves 35.5 BLEU in both Pre-Norm and Post-Norm settings. BN can not match the performance of LN by changing the test settings.

Table 3: EMA: Use population statistics estimated by EMA. Reestimation: Run two more epochs with zero learning rate to update population statistics. The performance metric is BLEU.

	Post-BN	Post-RBN	Pre-BN	Pre-RBN
EMA	34.0	35.5	34.8	35.6
Reestimation	33.8	35.6	34.9	35.4

F Configurations of BN’s Variants

We compare the performance of RBN with Power Normalization (PN) [2], Batch Renormalization (BRN) [15] and Moving Averaging Batch Normalization (MABN) [16] in the main paper. We mainly

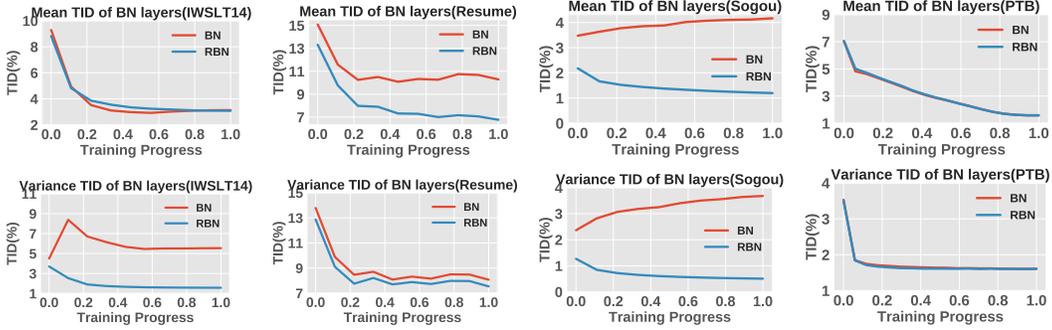


Figure 2: Averaged Mean and Variance TID on IWSLT14/Resume/Sogou/PTB for Pre-Norm Transformer with BN and RBN.

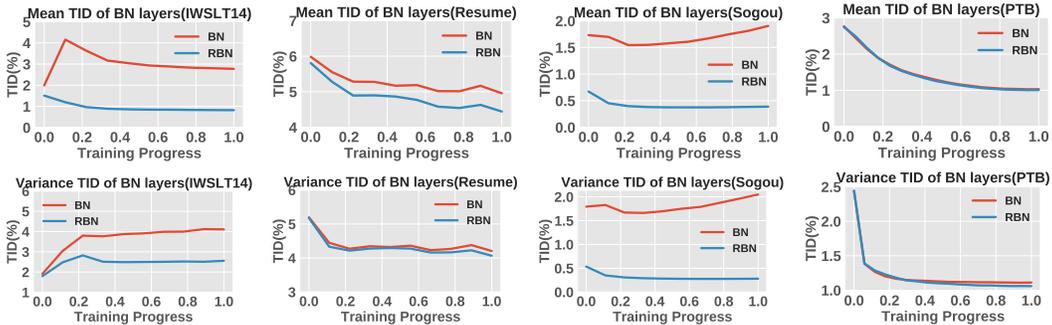


Figure 3: Averaged Mean and Variance TID on IWSLT14/Resume/Sogou/PTB for Post-Norm Transformer with BN and RBN.

follow the hyperparameters in their papers. For PN, we use 4000 warmups, and set forward and backward momentum as 0.9. For BRN, we use one epoch BN as warmup and linearly increase r to 3 and d to 5. r and d are renormalizing factors. For MABN, we use 16 mini-batches to compute simple moving average statistics and momentum $\alpha = 0.98$ to compute exponential moving average statistics.

G Potential Negative Societal Impact

We spend many GPU hours on running experiments which may negatively impact the environment.

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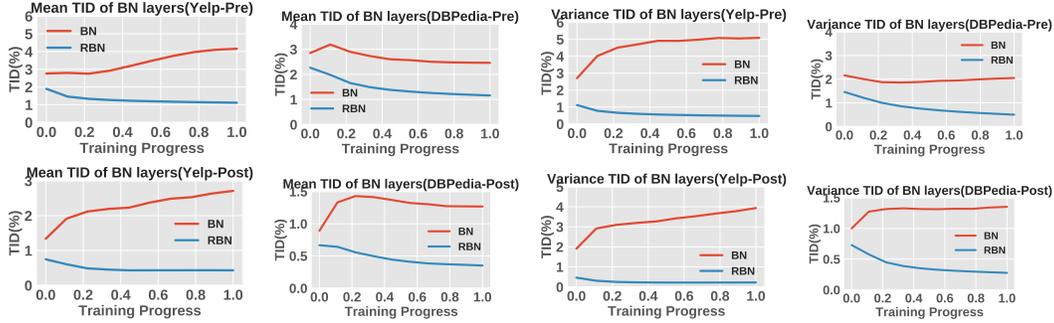


Figure 4: Averaged Mean and Variance TID on Yelp/DBPedia for Pre-Norm Transformer (upper) and Post-Norm Transformer (bottom) with BN and RBN.

Table 4: Testing BN (RBN) with batch statistics of different max-tokens.

Max-tokens	Post-BN	Post-RBN	Pre-BN	Pre-RBN
EMA	34.0	35.5	34.8	35.6
512	34.8	34.9	27.2	35.6
1024	35.1	34.9	30.9	35.6
2048	35.2	34.9	32.3	35.6
4096	35.2	34.9	32.7	35.6
8192	35.2	34.9	32.8	35.6
16384	35.2	34.8	32.9	35.6

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