

Input Space

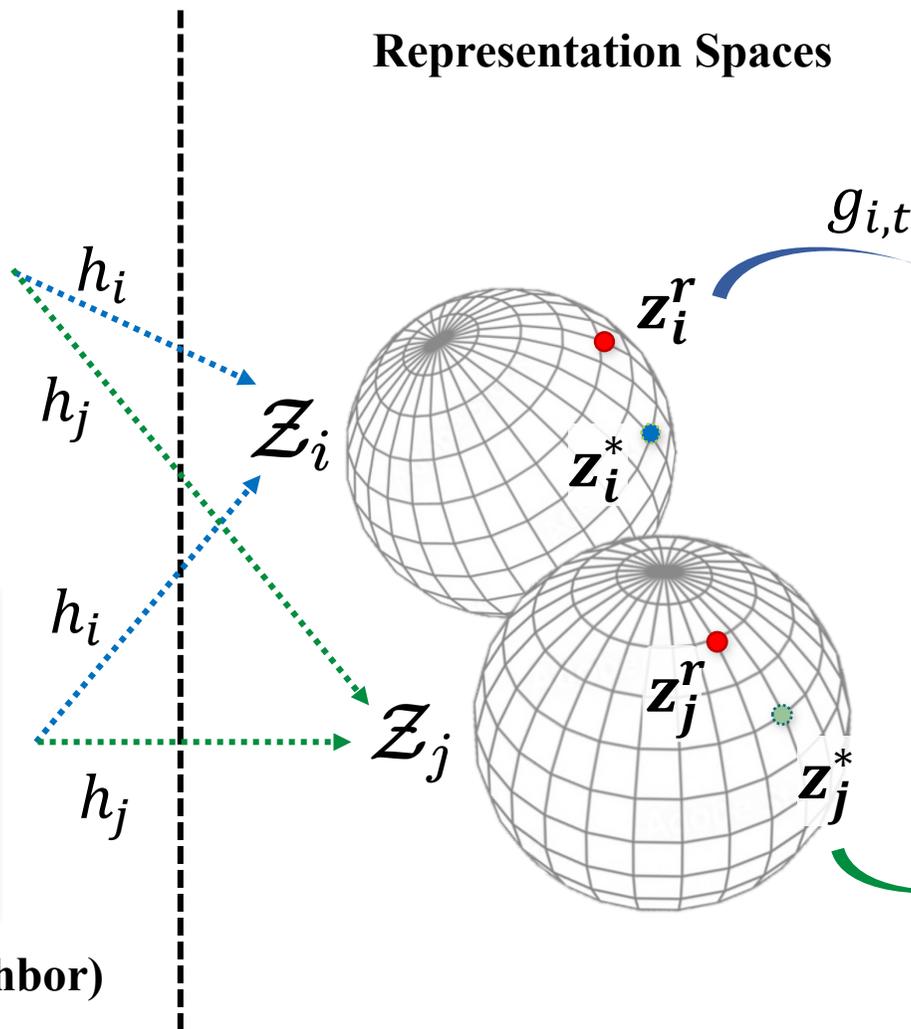


\mathbf{x}^* (Test Point)



\mathbf{x}^r (Reliable Neighbor)

Representation Spaces



Downstream Output Space

