

396 A Appendix

397 A.1 Training Details

398 **Pseudo mask preparation details.** Empirically, in the divide stage, we set the confidence threshold
399 $\tau = 0.3$; in the conquer stage, we choose threshold $\theta_{merge} = [0.6, 0.5, 0.4, 0.3, 0.2, 0.1]$. For each
400 image, the divide-and-conquer pipeline generates on average 334 pseudo masks. In the self-training
401 phase, the $\tau_{self-train} = 0.7$, and each image has 448 pseudo masks per image after merging high-
402 confidence mask predictions generated by UnSAM. When merging the pseudo masks with the ground
403 truths for training UnSAM+, we select $\tau_{UnSAM+} = 0.02$.

404 **Whole-image segmentation.** UnSAM picks DINO [8] pre-trained ResNet-50 [18] as the backbone
405 and Mask2former [9] as the mask decoder. Given the abundant number of pseudo masks generated,
406 UnSAM augments data only by cropping a 1024×1024 region from the original image. To cope
407 with a large amount of ‘ground-truth’ masks per image, we find that having 2000 learnable queries
408 produces the best result. We randomly select at most 200 ‘ground-truth’ masks per image to speed
409 up the training process. The default learning rate is 5×10^{-5} with batch size equals 16 and weight
410 decay 5×10^{-2} . We train the model for 8 epochs. All model training in this paper was conducted
411 using either 4 A100 GPUs or 8 RTX 3090 GPUs.

412 **Promptable segmentation.** UnSAM uses the self-supervised pretrained Swin-Transformer [25],
413 specifically the Swin-Tiny model, as the backbone and leverages Semantic-SAM [23] as the base
414 model. Given at most 6 levels of masks corresponding to one input point in SA-1B [21], we set the
415 number of hierarchy levels to 6, which is also the number of predicted masks UnSAM generates per
416 prompt during inference. However, one can easily train with a different number of granularity levels
417 as needed. The default learning rate is 1×10^{-4} with a batch size of 8. The learning rate decreases
418 by a factor of 10 at 90% and 95% of the training iterations. We train the model for 4 epochs.

419 A.2 Preliminary: Cut and Learn (CutLER) and MaskCut

420 CutLER [39] introduces a cut-and-learn pipeline to precisely segment instances without supervision.
421 The initial phase, known as the cut stage, uses a normalized cut-based method, MaskCut [39], to
422 generate high-quality instance masks that serve as pseudo-labels for subsequent learning phases.
423 MaskCut begins by harnessing semantic information extracted from ‘key’ features K_i of patch
424 i in the last attention layer of unsupervised vision transformers. It then calculates a patch-wise
425 cosine similarity matrix $W_{ij} = \frac{K_i K_j}{|K_i|_2 |K_j|_2}$. To extract multiple instance masks from a single image,
426 MaskCut initially applies Normalized Cuts [31], which identify the eigenvector x corresponding
427 to the second smallest eigenvalue. The vector x is then bi-partitioned to extract the foreground
428 instance mask M^s . Subsequent iterations repeat this operation but adjust by masking out patches
429 from previously segmented instances in the affinity matrix: $W_{ij}^t = \frac{(K_i \sum_{s=1}^t M_{ij}^s)(K_j \sum_{s=1}^t M_{ij}^s)}{\|K_i\|_2 \|K_j\|_2}$
430 Subsequently, CutLER’s learning stage trains a segmentation/detection model with drop-loss, which
431 encourages the model to explore areas not previously identified by MaskCut. An iterative self-training
432 phase is employed for continuously refining the model’s performance.

433 A.3 Preliminary: Segment Anything Model (SAM) and SA-1B

434 Inspired by achievement in the NLP field, the Segment Anything project [21] introduces the novel
435 *promptable segmentation task*. At its core lies the Segment Anything Model (SAM) [21], which
436 is capable of producing segmentation masks given user-provided text, points, boxes, and masks
437 in a zero-shot manner. SAM comprises three key components: an MAE [17] pre-trained Vision
438 Transformer [14] that extracts image embeddings, the prompt encoders that embed various types of
439 prompts, and a lightweight Transformer [36] decoder that predicts segmentation masks by integrating
440 image and prompt embeddings.

441 One significant contribution of SAM [21] is the release of the SA-1B dataset, which comprises 11
442 million high-resolution images and 1.1 billion segmentation masks, providing a substantial resource
443 for training and evaluating segmentation models. In particular, annotators interactively used SAM to
444 annotate images, and this newly annotated data was then utilized to iteratively update SAM. This
445 cycle was repeated multiple times to progressively enhance both the model and the dataset.

446 While SAM [21] significantly accelerates the labeling of segmentation masks, annotating an image
447 still requires approximately 14 seconds per mask. Given that each image contains over 100 masks,
448 this equates to more than 30 minutes per image, posing a substantial cost and making it challenging
449 to scale up the training data effectively.

450 **A.4 Evaluation Datasets**

451 **COCO** (Common Objects in Context) [24] is a widely utilized object detection and segmentation
452 dataset. It consists of 115,000 labeled training images, 5,000 labeled validation images, and more
453 than 200,000 unlabeled images. Its object segmentation covers 80 categories and is mainly on the
454 instance-level. We evaluate our model on COCO *Val2017* with 5000 validation images without
455 training or fine-tuning on any images from the COCO training set. The metrics we choose are
456 class-agnostic COCO style averaged precision and averaged recall for the whole-image inference
457 task, and MaxIoU and OracleIoU for the promptable segmentation task.

458 **SA-1B** [21] consists of 11 million high-resolution (1500 on average) images and 1.1 billion segmen-
459 tation masks, approximately 100 masks per image. All masks are collected in a class-agnostic manner
460 with various subject themes including locations, objects, and scenes. Masks cover a wide range of
461 granularity levels, from large scale objects to fine-grained details. In the whole-image inference
462 task, we randomly selected 1000 SA-1B images that are not used to generate pseudo labels as the
463 validation set.

464 **LVIS** (Large Vocabulary Instance Segmentation) [15] has 164,000 images with more than 1,200
465 categories and more than 2 million high-quality instance-level segmentation masks. It has a long tail
466 distribution that naturally reveals a large number of rare categories. In the whole-image inference
467 task, we evaluate our model using its 5000 validation images in a zero-shot manner.

468 **EntitySeg** [29] is an open-world, class-agnostic dataset that consists of 33277 images in total. There
469 are on average 18.1 entities per image. More than 80% of its images are of high resolution with
470 at least 1000 pixels for the width. EntitySeg also has more accurate boundary annotations. In
471 the whole-image inference task, we evaluate our model with 1314 low resolution version images
472 (800×1300 on average) in a zero-shot manner.

473 **PACO** (Parts and Attributes of Common Objects) [30] is a detection dataset that provides 641,000
474 masks for part-level entities not included in traditional datasets. It covers 75 object categories and
475 456 object-part categories. In the whole-image inference task, we evaluate our model with 2410
476 validation images in a zero-shot manner.

477 **PartImageNet** [16] is a large-scale, high quality dataset with rich part segmentation annotations on a
478 general set of classes with non-rigid, articulated objects. It includes 158 classes and 24,000 images
479 from ImageNet [13]. In the whole-image inference task, we evaluate our model with 2956 validation
480 images in a zero-shot manner.

481 **ADE20K** [48] is composed of 25,574 training and 2,000 testing images spanning 365 different scenes.
482 It mainly covers semantic-level segmentation with 150 semantic categories and 707,868 objects from
483 3,688 categories. In the whole-image inference task, we evaluate our model with 2000 testing images
484 in a zero-shot manner.

485 **A.5 More Visualizations**

486 We provide more qualitative results of UnSAM and UnSAM+ in a zero-shot manner in Figure A1,
487 Figure A2, and Figure A3.



Figure A1: More visualizations on SA-1B [21]. From top to bottom are raw images, segmentation by SAM, segmentation by UnSAM, and segmentation by UnSAM+.

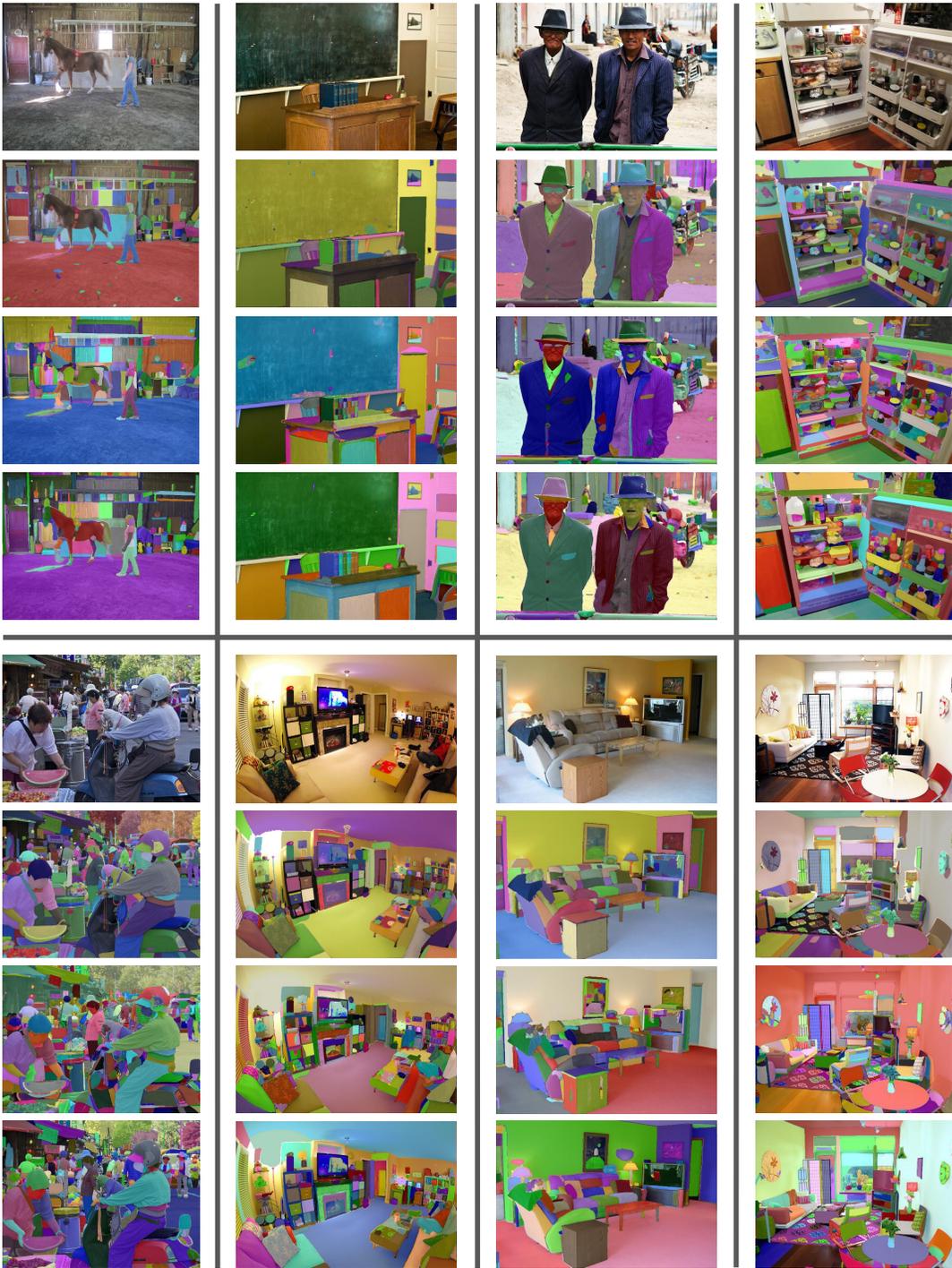


Figure A2: More visualizations on COCO [24]. From top to bottom are raw images, segmentation by SAM, segmentation by UnSAM, and segmentation by UnSAM+.

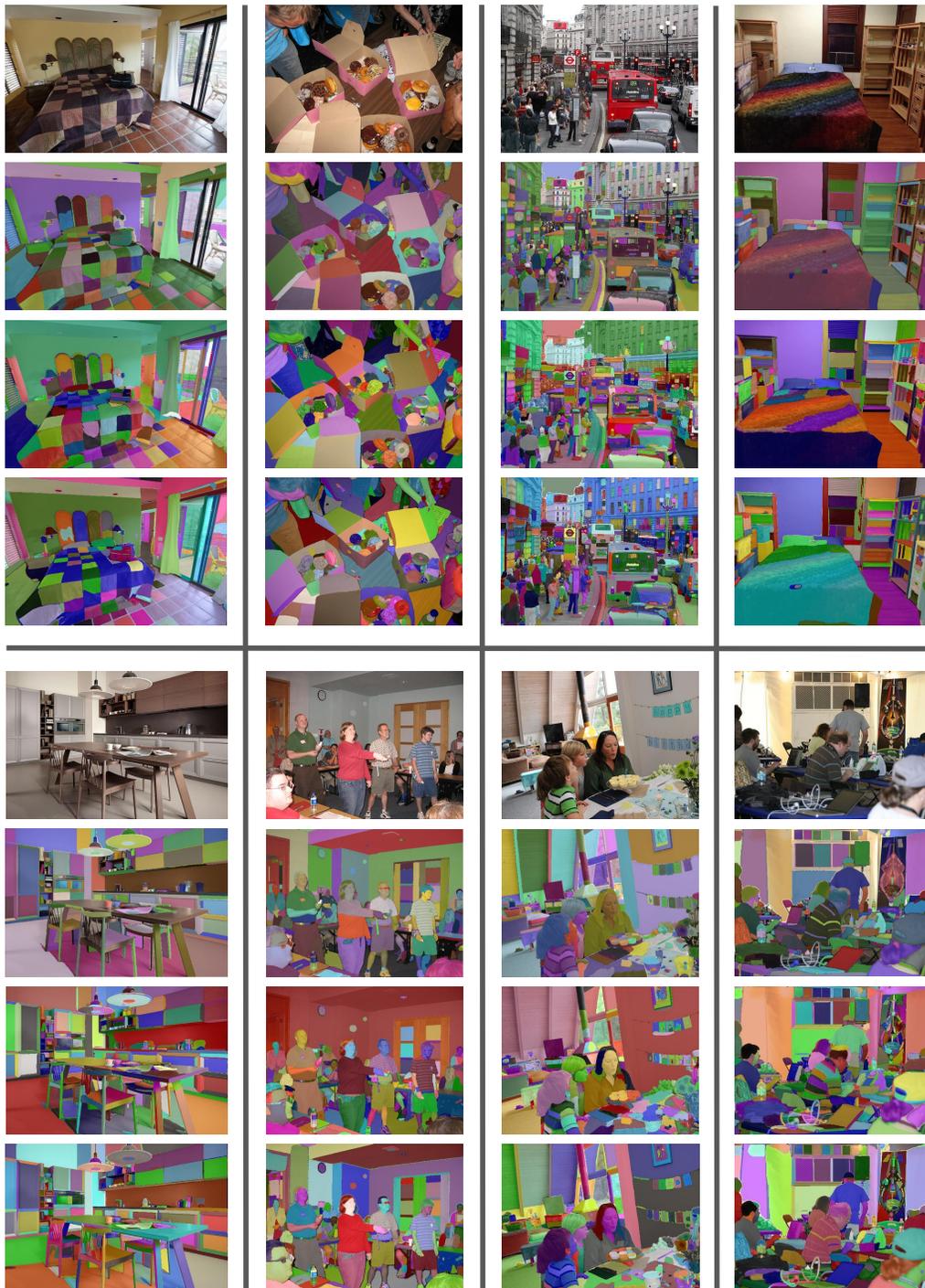


Figure A3: More visualizations on PACO [30]. From top to bottom are raw images, segmentation by SAM, segmentation by UnSAM, and segmentation by UnSAM+.



Figure A4: Failure cases of UnSAM. From left to right are raw images, segmentation by SAM, and segmentation by UnSAM.

488 **A.6 Limitations**

489 In images with very dense fine-grained details, UnSAM tends to miss repetitive instances with similar
 490 texture. As showed in Figure A4, in the first row, although UnSAM accurately segments the leaves
 491 in the center of the picture, it misses some leaves located at the top of the image. Additionally,
 492 UnSAM occasionally over-segment images. In the second row, the right sleeve cuff of the dancer
 493 has meaningless segmentation masks. This issue mainly arises because the unsupervised clustering
 494 method mistakenly considers some information, such as folds and shadows on clothing, as criteria for
 495 distinguishing different entities. In contrast, human annotators can use prior knowledge to inform the
 496 model that such information should not be valid criteria. In this regard, unsupervised methods still
 497 need to close the gap with supervised methods.

498 **A.7 Ethical Considerations**

499 We train UnSAM and UnSAM+ on ground truths of and pseudo masks generated on SA-1B [21].
 500 SA-1B contains licensed images that are filtered for objectionable content. It is geographically
 501 diverse, but some regions and economic groups are underrepresented. Downstream use of UnSAM
 502 and UnSAM+ may create their own potential biases concerns for specific use cases.

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