487 A **Proofs of Lemmas and Theorems**

488 A.1 Proof of Proposition 1

Proposition 1. If the learning target is non-identifiable (i.e., every edge in the target is non-identifiable) a priori,
 then SCL is not better than random guessing.

Re-statement: We take learning target as the orientation of an edge as an example, so we are analyzing the performance of a binary classifier against random guessing. The conclusion can be easily extended to general case.

Denote random guessing as a degenerated estimator $r(X) \equiv 0.5$, which indicates the probability of label = 1 is always 0.5, regardless of any input.

Denote the joint probability distribution of X and Y as \mathbb{P} and the space of all joint probability distribution is \mathcal{P} , then we aim to prove the following statement which is in an adversarial setting:

$$r = \underset{f \in \mathcal{C}}{\operatorname{arg min}} \sup_{\mathbb{P} \in \mathcal{P}} E_{(X,Y) \sim \mathbb{P}} \left[-Y \log f \left(X \right) - (1 - Y) \log \left(1 - f \left(X \right) \right) \right]$$

⁴⁹⁶ The expectation is the standard binary cross entropy loss; we are allowed to enumerate every possible joint

⁴⁹⁷ probability distribution in \mathcal{P} because the learning target is non-identifiable. C is the space of all possible binary ⁴⁹⁸ classifiers.

Proof. Given any binary classifier f, we partition the space of X by A, B and C where $A = \{x | f(x) > 0.5\}$, $B = \{x | f(x) < 0.5\}$, $C = \{x | f(x) = 0.5\}$. Then we construct the following joint probability distribution P^* :

$$P^{*}(X,Y) = \begin{cases} P^{*}(Y=0|X=x) = 1 \text{ if } x \in A \\ P^{*}(Y=1|X=x) = 1 \text{ if } x \in B \\ arbitrary \text{ if } x \in C \end{cases}$$

Then it is easy to see that $E_{(X,Y)\sim P^*}[-Y\log f(X) - (1-Y)\log(1-f(X))] \ge 1$. Note that 500 $E[-Y\log r(X) - (1-Y)\log(1-r(X))] \equiv 1$, thus r achieves minimum worse-case loss. \Box

501 A.2 Proof of Proposition 2

502 **Proposition 2.** If ML4C-Learner is a perfect classifier, then ML4C outputs correct CPDAG of a canonical 503 dataset (i.e., ML4C is perfect).

Proof. Classical constraint-based methods consist of three steps: skeleton identification, v-structure identification, and further edge orientation by applying Meek rules [37]. It has been proved in PC [34] that when learning from a canonical dataset, if both the identified skeleton and v-structures are correct, then the learned CPDAG is correct. ML4C follows the three steps, with the correct skeleton is given as input, and ML4C-Learner is responsible for v-structure identification. Thus, assuming ML4C-Learner is a perfect classifier (i.e., correctly identifies all v-structures) implies that ML4C outputs correct CPDAG.

510 A.3 Proof of Lemma 1

Lemma 1. Sepsets S of any UT of a canonical dataset is non-empty.

Proof. According to Lemma 3.3.9 of [35], in a directed acyclic graph G, if X is not a descendant of Y, and X and Y are not adjacent, then X and Y are d-separated by **Parents**(Y). Given an UT $\langle X, T, Y \rangle$, X and Y are not adjacent. Either X is not a descendant of Y, or Y is not a descendant of X, otherwise a loop will be introduced. Thus there either exists **Parents** $(X) \equiv PC_X \cup T$, or **Parents** $(Y) \equiv PC_Y \cup T$, which belongs to S. Thus S is non-empty.

517 A.4 Proof of Lemma 2

Lemma 2 (Existence of weak discriminative predicate). For a canonical dataset with infinite samples, the following are three weak discriminative predicates: i) $\{X \sim Y | T\} > 0$, ii) $\{X \sim Y | \mathcal{PC}_T\} = 0$, iii) $\{PC_X \sim PC_Y | S \cup T\} > 0$.

521 *Proof.* For a canonical dataset with infinite samples,

5221. $\{X \sim Y | T\} > 0$: 1) $\langle X, T, Y \rangle$ is a v-structure $\Rightarrow T$ is a collider $\Rightarrow T$ unblocks X and Y through523path $X - T - Y \Rightarrow \{X \sim Y | T\} > 0$ holds TRUE.2) if $\langle X, T, Y \rangle$ is not a v-structure, then524 $\{X \sim Y | T\} > 0$ can be TRUE or FALSE. e.g., it is FALSE for $X \to T \to Y$ (no more paths connect525X and Y), but if there exists another node $X \to T' \to Y$, it is evaluated TRUE. Therefore, it satisfies526criterion ii) of definition [12] but not i) hence it is a weak discriminative predicate.

527	2. $\{X \sim Y \mathcal{PC}_T\} = 0: 1$ $\langle X, T, Y \rangle$ is not a v-structure $\Rightarrow T$ is a non-collider $\Rightarrow \forall pc_t \in \mathcal{PC}_T$, there
528	exists a path $X - T - Y$ from X to Y, where T is the only node on path, T is a non-collider,
529	and $T \notin \{pc_t\} \Rightarrow pc_t$ does not block the path $\Rightarrow \{X \sim Y \mathcal{PC}_T\} = 0$ always holds FALSE. 2) if
530	$\langle X, T, Y \rangle$ is a v-structure, then $\{X \sim Y \mathcal{PC}_T\} = 0$ can be TRUE or FALSE. Therefore, it satisfies
531	criterion i) but not ii) hence it's a weak discriminative predicate.
599	3 $\{PC_{X} \in PC_{Y} S \mid T\} > 0; 1\} / X T V$ is a v-structure $\rightarrow T$ is a collider $\rightarrow \forall nc \in C$

532 3. $\{PC_X \sim PC_Y | S \cup T\} > 0$: 1) $\langle X, T, Y \rangle$ is a v-structure $\Rightarrow T$ is a collider $\Rightarrow \forall pc_x \in PC_X, pc_y \in PC_Y, S \in S, S \cup T$ unblock pc_x and pc_y through path $pc_x - X - T - Y - pc_y \Rightarrow \{pc_x \sim pc_y | S \cup T\} > 0$ always hold TRUE. 2) if $\langle X, T, Y \rangle$ is not a v-structure then it can be TRUE 535 or FALSE. Therefore, it satisfies criterion ii) but not i) hence it's a weak discriminative predicate.

536

537 A.5 Proof of Lemma 3

Lemma 3 (Existence of strong discriminative predicate). For a canonical dataset with infinite samples, the following are three strong discriminative predicates: i) OLP(T, S) = 0, ii) OLP(T, S) < 0.5, iii) OLP(T, S) < 540 $1 \land \min \{X \sim Y | T \cup S\} > 0$.

Proof. First, it is known that the following three algorithms are sound and complete for a canonical dataset with infinite samples: CPC [28], MPC [8] and GLL-MB [3]. Below we translate each predicate and then show that these predicates are equivalent to the criterion to identify v-structures in CPC [28], MPC [8] and GLL-MB [3] respectively.

545	1.	Predicate $OLP(T, S) = 0 \iff \forall S \in S, T \notin S$, which states that predicate is TRUE if and only if
546		T is not in any d-separation set of X and Y . This is exactly the criterion of CPC for identifying
547		v-structures [28].

- 548 2. Predicate OLP(T, S) < 0.5 indicates that only if more than half of the d-separation sets do not contain 549 T, then the UT is oriented as a v-structure. This is called majority-rule PC algorithm MPC 8 for 550 v-structure identification.
- 551 3. Predicate $OLP(T, S) < 1 \land \min\{X \sim Y | T \cup S\} > 0 \Rightarrow \exists S \in S, T \notin S \text{ and } X \text{ and } Y \text{ are dependent}$ 552 when conditioning on $T \cup S$, which is the criterion used for GLL-MB \exists to identify v-structures.

553

554 A.6 Proof of Theorem 1

Theorem 1. *ML4C-Learner tends to a perfect classifier on classifying a canonical dataset with sufficient samples.*

⁵⁵⁷ *Proof.* According to Lemma 3 there exists strong discriminative predicate P which achieves zero loss given a canonical dataset and sufficient samples. Thus, when adequate ML model is chosen, ML4C-Learner can achieve no worse performance than P (e.g., we can set the parameters of ML4C-Learner so that it approximates predicate P initially, and then apply standard gradient descent procedure). By considering proposition 2 we complete the proof.

562 **B** Implementation Details

563 B.1 Calculating conditional dependencies

There are several ways to measure the conditional dependence, such as p-value by testing of conditional independence, or conditional mutual information [9]. For categorical variables, a good choice is G^2 test [1]. In

our implementation, we adopt an approximate version of G^2 statistic, and use p-value to measure the conditional dependence.

Moreover, considering p-value can easily vanish due to numerical precision in 64-bit computers. Therefore, we use a transformation of p-value to avoid the issue, as additional quantity to measure conditional dependency. We first define complementary error function as

$$g(z) = 1 - \frac{2}{\sqrt{\pi}} \int_0^z e^{-t^2} dt,$$

and we use quantity z by inverse of g:

$$z = g^{-1}(x).$$

Given a p-value x, we use g^{-1} as a non-linear transformation to obtain a better re-scaled quantity to measure conditional dependency. Intuitively, z can be viewed as z-sigma for a standard normal distribution, e.g., if p-value is 0.05, then z = 2, since 2-sigma indicates probability of values that lie within 2-sigma interval in a

571 normal distribution is 0.95.

572 B.2 ML4C Training and inference details

573 B.2.1 Data synthesis details

Graph structure: We adopt the Erdős-Rényi (ER) model [13] and the Scale-Free (SF) model [2], which are 574 two commonly used model for graph synthesis. We categorize the scale of the graph (number of nodes d) into 575 four classes: small, medium, large, and very large, corresponding to d being uniformly sampled from intervals 576 [10, 20], [21, 50], [51, 100], and [101, 1000], respectively. Given the number of nodes d, the sparsity of the 577 graph (defined as the ratio of the average number of edges to the number of nodes, i.e., the average in-degree 578 of all nodes) is randomly sampled from a uniform distribution [1.2, 1.7]. Given the number of nodes and the 579 expected number of edges, the graph skeleton is generated accordingly by the two random graph models. Then 580 the skeleton is randomly oriented to a DAG by upper triangular permutation. 581

Conditional probability table: Now we illustrate how we come up with Conditional Probability Table (CPT) 582 for each node. In accordance with the topological ordering of the graph, each node is first assigned its cardinality, 583 which is randomly sampled from a truncated normal distribution $\mathcal{N}(\mu = 2, \sigma = \frac{1.5}{m}, \min = 2)$, where m 584 denotes the maximum number of peers of the node (i.e. $\max\{in-degree of the effect nodes of this node\}$). This 585 regularization is designed to make the forward sampling process faster and prevent some certain nodes with 586 many cause nodes from getting stuck. Since the number of different conditions to be enumerated is exponential 587 $(\prod_{c \in \text{ causes cardinality}_{c})$, node with a larger maximum peers number tends to have smaller cardinality. Next, we 588 enumerate each of its unique conditions (given by combinations of its cause nodes' cardinalities) and randomly 589 generate its probability distribution at each condition. The probability distribution is sampled from a Dirichlet 590 distribution with parameter $\alpha \sim U[0.1, 1.0]$ and grid number as this code's cardinality. 591

Training data: Having CPT specification of each node, a sample of 10k rows of observations is obtained for each graph according to the standard Bayesian network forward sampling. This generates a total dataset of 4 scales × 2 graph models × 50 graphs for each class = 400 unique graphs and the corresponding sampled data. Different SCL algorithms are then further used to extract the required features corresponding to the respective learning targets, e.g., all edges of all graphs for pairwise SCL algorithms. For our ML4C learning targets, all UTs are extracted from graphs, consisting of a total of 97,010 V-structures (label=1) and 195,691 non-V-structures (label=0).

599 **B.2.2 XGBoost hyper-parameter settings**

We use xgb.XGBClassifier(), the Python API provided by XGBoost [6], to implement the binary classifier ML4C-Learner. All hyper-parameters are set as default. We set the threshold value T = 0.1.

602 **B.3 Post processing**

Although ML4C-Learner achieves high accuracy on classifying UTs into v-structures or non-v-structures (UT-F1 = 0.9, as shown in Table]), it is still possible to have conflicts among the detected v-structures. We adopt a straightforward heuristic to resolve conflicts: suppose we have two conflict v-structures $A \rightarrow B \leftarrow C$ and $B \rightarrow C \leftarrow D$, we discard the one with lower probability score (by ML4C-Learner). We continue such pairwise conflict resolving until no more conflicts exist. We use the left v-structures to construct the partial DAG (bottom-right of Figure 1(b)). Pseudo-code is shown in Algorithm [1]

609 C Details of Evaluation

610 C.1 Evaluation metrics

611 We calculate SHD at CPDAG level. Specifically, SHD is computed between the learned CPDAG(\hat{G}) and ground

truth CPDAG(G), i.e., the smallest number of edge additions, deletions, direction reversals and type changes

613 (directed vs. undirected) to convert the output CPDAG to ground truth CPDAG. As is shown in Table 5, SHD is

equal to the sum of the number of Xs in the table.

F1-score is then calculated based on the identifiable edges of $CPDAG(\hat{G})$ and CPDAG(G), where the accuracy (precision) is equal to True Positive Rate (TPR) and the recall (recall) is equal to 1 - False Discovery Rate (FDR).

Algorithm 1: Conflict resolving

in result CPDAG \rightarrow	iden (d	lirected)	uniden	missing in
in truth CPDAG \downarrow	right	wrong	(undirected)	skeleton
iden	✓1	X (2)	X (3)	X (4)
uniden	X (5	✓ (6)	X (7)
nonexist	X (8	X (9)	✓ 10

Table 5: SHD calculation details.

Details about the specific calculation can also refer to Table 5

precision=TPR =
$$\frac{1}{(1+2)+(3)+(4)}$$
,
recall=1-FDR = $\frac{1}{(1+2)+(5)+(8)}$,

615 C.2 Full result of Table 1: End-to-end comparison

Here we report full results including other 5 smallest and trivial datasets. Note that 1) All F1-score degrade into 0. on sachs dataset, because that sachs has no identifiable edges. 2) The rank(SHD) row is also re-calculated

618 over full datasets.

619 C.3 Predicates in Table 2: Reliability

Table 2 shows the performance of 4 weak discriminative predicates and 4 strong discriminative predicates. Specifically, the four strong predicates are respectively 1) $t \sim U[0, 1]$, $OLP(T, S) \ge t$; 2) OLP(T, S) == 0; 3) OLP(T, S) == 0 and $\{X \sim Y | S \cup T\} > 0$; 4) $\{X \sim Y | S \vee T\} > 0$. The four weak predicates are respectively 1) $\{PC_X \sim PC_Y | T\} > 0$; 2) $\{PC_X \sim PC_Y | S \vee T\} > 0$; 3) $\{X \sim Y | PC_T\} == 0$; 4) $\{X \sim Y | S \lor \mathcal{PC}_T\} > 0$.

625 C.4 Details of Table 4: Transferability

To evaluate ML4C's transferability across different domains, we train on dataset generated using one configuration, and test on another. By default the configuration is that: #nodes=50, sparsity=#edges/#nodes=1.5, generating model=ER, and sample size=10000. We conduct controlled trials on the four configuration domains listed above (shown as the four big bars of Table 4).

When we test transferability over one domain (e.g., the first bar, #nodes), then #nodes is set from 4 options (10, 50, 100, 1k), and $4 \times 4 = 16$ pairs of train-test experiments are conducted. For each experiment, 50 graphs are synthesized for training and another 5 graphs for test. Except for the target domain (#nodes), all the other

Table 6: Full result of Table 1.

Datasets			suj	pervise	d			unsupervised							no skeleton input		
#nodes/#e	edges	ML4C	Jarfo	D2C	RCC	NCC	PC	CPC	MPC	GMB	GES	GS	HC	CDS	DGNN	BLIP	GNIP
cancer 5/4	SHD F1	0 1.0	.00	.25	.00	0 1.0	.50	0 1.0	0 1.0	0 1.0	.25	0 1.0	0 1.0	.50	.00	.00	0 1.0
earthquake 5/4	SHD F1	0 1.0	4 .00	2 .50	4 .00	0 1.0	2 .50	0 1.0	0 1.0	0 1.0	0 1.0	0 1.0	4 .00	0 1.0	4 .00	5 .00	0 1.0
survey 6/6	SHD F1	1 .83	4 .50	5 .25	4 .33	0 1.0	0 1.0	1 .83	1 .83	0 1.0	4 .44	0 1.0	6 .00	5 .25	6 .00	6 .00	6 .00
asia 8/8	SHD F1	0 1.0	5 .33	.15	$^{1}_{.80}$	0 1.0	.80	.67	0 1.0	0 1.0	0 1.0	0 1.0	0 1.0	.67	16 .20	6 .57	.91
sachs 11/17	SHD F1	0 .00	9 .00	11 .00	.8 .00	12 .00	13 .00	0 .00	0 .00	13 .00	14 .00	11 .00	0 .00	. 8 . 00	16 .00	. 00	0 .00
child 20/25	SHD F1	0 1.0	18 .24	16 .43	18 .33	20 .12	22 .12	13 .00	9 .74	20 .12	15 .47	13 .59	13 .57	18 .34	23 .25	0 1.0	0 1.0
insurance 27/52	SHD F1	.89	41 .26	30 .44	34 .42	28 .44	36 .39	34 .00	21 .66	29 .55	34 .46	28 .56	19 .76	36 .36	53 .05	35 .51	14 .82
water 32/66	SHD F1	.94	33 .52	43 .34	31 .56	0 1.0	4 .97	60 .00	7 .91	.87 .87	38 .49	27 .62	38 .46	18 .76	61 .00	65 .20	52 .50
mildew 35/46	SHD F1	6 .87	-	17 .68	25 .50	34 .33	21 .56	-	-	7 .85	3 .93	9 .80	23 .64	18 .65	52 .19	36 .41	-
alarm 37/46	SHD F1	1 .98	21 .57	26 .44	18 .64	20 .57	20 .57	20 .57	6 .92	17 .64	.86	3 .94	21 .66	18 .62	46 .12	17 .82	.98
barley 48/84	SHD F1	5 .95	48 .46	55 .38	50 .44	0 1.0	3 .96	-	-	8 .91	42 .59	-	34 .72	50 .43	87 .00	60 .48	42 .67
hailfinder 56/66	SHD F1	11 .80	47 .37	41 .45	43 .42	0 1.0	17 .85	2	-	26 .70	60 .21	-	59 .23	44 .42	76 .00	111 .18	118 .12
hepar2 70/123	SHD F1	0 1.0	54 .59	81 .34	59 .54	0 1.0	35 .72	27 .81	37 .70	14 .89	46 .75	40 .70	35 .81	75 .39	123 .00	79 .54	61 .68
win95pts 76/112	SHD F1	1 .99	65 .43	51 .54	33 .73	0 1.0	.95	42 .64	7 .95	5 .97	32 .77	21 .85	16 .91	50 .57	112 .00	103 .47	-
pathfinder 109/195	SHD F1	25 .77	157 .21	145 .29	151 .21	0 1.0	150 .29	-	-	147 .30	158 .29	-	168 .28	148 .31	196 .00	241 .07	-
munin1 186/273	SHD F1	10 .97	169 .42	154 .47	153 .46	72 .77	86 .71	117 .58	-	84 .72	109 .67	-	233 .26	151 .50	-	257 .42	-
andes 223/338	SHD F1	0 1.0	226 .35	209 .41	246 .29	0 1.0	.4 .99	83 .75	.4 .99	.98	47 .92	15 .96	38 .92	149 .60	-	175 .76	-
diabetes 413/602	SHD F1	25 .96	220 .62	395 .38	237 .62	48 .96	0 1.0	2	-	204 .68	146 .77	-	592 .03	368 .43	-	534 .43	-
pigs 441/592	SHD F1	0 1.0	350 .44	332 .46	263 .59	400 .35	400 .35	-	-	268 .56	0 1.0	-	532 .18	316 .50	-	6 1.0	-
link 724/1125	SHD F1	0 1.0	731 .38	630 .45	638 .45	749 .39	737 .40	-	-	204 .81	324 .80	-	1047 .14	400 .64	-	947 .49	-
munin 1041/1397	SHD F1	72 .95	967 .36	790 .48	816 .44	0 1.0	156 .89	-	-	458 .69	661 .62	-	1397 .00	795 .51	-	1599 .29	-
munin2 1003/1244	SHD F1	118 .92	554 .60	611 .56	646 .55	1052 .19	898 .30	-	-	536 .57	632 .58	-	1240 .01	753 .49	-	1321 .46	-
munin3 1041/1306	SHD F1	113 .92	616 .58	629 .57	688 .54	1048 .25	860 .37	-	-	544 .60	566 .65	-	1306 .00	819 .46	-	1539 .26	-
munin4 1038/1388	SHD F1	126 .93	696 .54	658 .56	776 .50	1058 .29	876 .39	2	-	649 .55	618 .64	-	1388 .00	812 .49	-	1627 .28	-
rank(SHD)	$_{\pm stdd}^{mean}$	1.6 1.0	9.5 3.1	8.9 3.6	8.3 2.3	4.7 4.3	6.7 3.8	9.4 4.3	7.9 4.9	4.2 3.1	6.1 3.7	8.2 4.6	8.0 3.7	7.9 2.7	13.5 1.8	10.9 3.6	9.5 5.0
UT-F1	mean ±stdd	.90 .13	.22 .17	.19 .13	.27 .18	.66 .40	.50 .34	.53 .33	.87 .16	.59 .32	.54 .28	.77 .24	.47 .35	.30 .22	.09 .07	.36 .29	.70 .33

domains use the default configuration. The result SHD and F1-score are reported as mean value and standard deviation over the five test graphs.

635 D Code and Data

636 D.1 URLs of all competitors

637 We use open-source codes of other algorithms for evaluation.

- For Jarfo, RCC, NCC, GES, GS(Grow-Shrink), and CDS, we use the API provided by Causal Discovery Toolbox [18]: https://github.com/FenTechSolutions/CausalDiscoveryToolbox
- 640 For HC(Hill-Climbing) we use pgmpy https://github.com/pgmpy/pgmpy with BDeu score.
- For PC we use the official R package pcalg https://cran.r-project.org/web/packages/pcalg

For Conservative-PC and Majority-rule PC, we slightly modify the source code of pcalg to enable a faster run

on large scale datasets. GLL-MB is also implemented based on pcalg. Reviewers can download our modified

644 implementation of these 3 algorithms from http://ml4c.xyz

645 D.2 Algorithms starting from data: DAG-GNN/BLIP/GOBNILP

646 **D.2.1 Code URL**

- 647 1. GOBNILP: https://bitbucket.org/jamescussens/pygobnilp/
- 648 2. BLIP: https://cran.r-project.org/web/packages/r.blip/
- 5. DAG-GNN: We use a repository with a standard and clean version of the DAG-GNN algorithm, which
 is well maintained and can be found at https://github.com/ronikobrosly/DAG_from_GNN/.

651 D.2.2 Hyper-parameter settings

- 1. Time limit: The running time of all programs is limited to 24 hours.
- 453 2. Max-in-degree: The max-in-degree threshold for BILP is set to 6. The max-in-degree threshold for
 GOBNILP is set to 3.
- Configurations of DAG-GNN are as follows. Epochs=300, batch size=100, learning rate=3e-3, graph
 threshold=0.3. Graph threshold is a threshold for weighted adjacency matrix (i.e., any weights > -0.3
 and < 0.3 means the two variables are not adjacent).

658 D.2.3 Verifying the results of DAG-GNN

- To make sure DAG-GNN is correctly executed, we have carefully experiment DAG-GNN from the following two aspects:
- 661 **Reproducing the results of paper [38]** We take the child dataset as an example to test the reproducibility, because the data set has been reported by [38]. As can be seen from Table [7] the BIC scores are similar to

Table 7	F	Reprodu	cing	results	for	child
ruore /		copro au	wing.	rebuild	101	CIIIG

	groundtruth	child
BIC	-1.23e+4	-1.36e+4

662

the results reported in the original paper (child: -1.38e+4). That is to say, the results in Yu et al.'s paper are

664 reproduced by us.

Different graph thresholds The following are the BIC scores on the data sets of alarm and water with different graph thresholds. The graph threshold recommended by [38] is 0.3. It can be seen that the performance

	Groundtruth	0.1	0.2	0.3	0.4	0.5
alarm	-1.08e+5	-1.90e+5	-1.44e+5	-1.59e+5	-1.77e+5	-1.91e+5
water	-1.35e+5	-1.32e+5	-1.37e+5	-1.44e+5	-1.53e+5	-1.62e+5

Table 8: Results with different graph thresholds

666

is stable when the threshold is around 0.3. We have verified that there are similar conclusions on other data sets.

668 Therefore 0.3 should be a reasonable threshold.

669 D.3 ML4C: Code and data

For reviewers to check reproducibility of our results reported in 5 we put our code and data on an anonymous site http://ml4c.xyz