Appendices

A MORE TECHNOLOGY DETAILS

A.1 POS WEIGHT AND NEG WEIGHT

In the "Pos Weight" method, we impose a large weight w_p to the positives. We set w_p as the times of positive targets to unlabeled targets in each training batch. Previous study (Li et al., 2020) had stated that negative sampling can be considered as a type of negative weighting method. And this work experimentally find that negative sampling even work better. In our experiments, we undersampling the unlabeled targets as the "Neg Weight" method. Unlabeled targets 10 times the number of positive targets are retained in each training batch.

A.2 EVALUATION METRICS

We compute the F1 scores based on TP (True Positive), FP (False Positive), and FN (False Negative).

$$Recall = TP/(TP + FN),$$

$$Precision = TP/(TP + FP),$$

$$F1 = 2 * Recall * Precision/(Recall + Precision).$$
(7)

We choose the widely used evaluation metric mAP on multi-label image classification. N_c is the number of images containing class c, Precision(k, c) is the precision for class c when retrieving k best predictions and rel(k, c) is the relevance indicator function that is 1 if the class c is in the ground-truth of the image at rank k. We also compute the performance across all classes using mean average precision (mAP), where C is the number of classes.

$$AP_{c} = \frac{1}{N_{c}} \sum_{k=1}^{N} Precision(k, c) * rel(k, c),$$

$$mAP = \frac{1}{C} \sum_{c} AP_{c}$$
(8)

B MORE EXPERIMENTS

B.1 DOCUMENT-LEVEL RELATION EXTRACTION

Training curve. In Figure 4, we display the reward and loss curves of our model in three annotation rations, 10%, 50%, and 100%. Our experimental settings were conducted under partially annotated multi-label tasks, but we also compute metrics on ground Truth during the experiment. As shown in Figure 5, we take annotations ratio=50% as an example, although the F1 scores were low on the partially annotated dataset, the F1 scores are about 20 percentage points higher on the ground truth.

All experiments on different ratios of annotated labels To fully verify the effectiveness and robustness of our model, we randomly constructed three versions of data sets and tested the DREEAM model, Pos Weight, Neg Weight, and our PAPG model on all data sets respectively. The results are shown in Table 6.

Experiments on selecting action sampling ratios (Take annotations ratio=50% as an example) In order to select the action sampling ratio hyperparameter, we conducted comparative experiments from 0.1 to 0.9, and finally found that the model performed best when the hyperparameter was 0.4. The results are shown in Table 7.

Value Network Performance of Our PAPG We iteratively train our value network and policy network. After multiple rounds of iterations, the performance of value network has been greatly improved. The performance of value network of our PAPG are shown in Table 8.

Case study. In Table 13, we show an example on the prediction of each method. Our PAPG predicts more true positives.

B.2 MULTI-LABEL IMAGE CLASSIFICATION

The experimental results on extra evaluation metrics and annotation ratios. In Table 9 and Table 10, we show Precision and Recall of CIFAR10 and the results of other annotation ratios on Ms-COCO. Table 11 shows the stability of our method PAPG. The standard deviation was computed from three different runs on the MS-COCO dataset.



Figure 4: Train Curve.



Annotations Ratio = 50%

Figure 5: Metric Comparison under Ground Truth and Partially Annotations. Left: Ground Truth, Right: Partially Annotations

		v	ersion	0	v	version1			ersion	2	average		
Method	Data Ratio	Р	R	F1	Р	R	F1	Р	R	F1	Р	R	F1
	10%	91.23	4.53	8.64	90.88	3.54	6.82	87.39	3.38	6.5	89.83	3.82	7.32
	20%	90.74	10.0	18.02	92.37	9.65	17.47	90.86	9.8	17.69	91.32	9.82	17.73
	30%	92.45	19.94	32.8	92.48	19.95	32.82	91.19	22.35	35.9	92.04	20.75	33.84
	40%	93.12	28.08	43.15	91.92	34.82	50.51	92.25	36.34	52.14	92.43	33.08	48.6
DREEAM	50%	92.69	43.63	59.33	91.25	43.28	58.71	91.44	39.29	54.96	91.79	42.07	57.67
	60%	92.16	48.56	63.6	90.49	56.52	69.58	89.52	55.68	68.66	90.72	53.59	67.28
	70%	88.56	60.15	71.64	91.28	55.69	69.17	88.92	60.51	71.01	89.59	58.78	70.61
	80%	87.91	65.18	74.86	89.83	62.75	73.89	86.95	66.49	75.36	88.23	64.81	74.7
	90%	87.49	66.86	75.79	87.61	67.66	76.35	86.4	68.75	76.57	87.17	67.76	76.24
	10%	84.43	34.1	48.57	84.61	43.22	57.21	85.8	42.21	56.58	84.95	39.84	54.12
	20%	87.72	47.36	61.51	82.51	57.19	67.56	86.61	51.3	64.44	85.61	51.95	64.5
	30%	83.57	61.65	70.95	87.05	57.04	68.92	85.75	59.23	70.07	85.46	59.31	69.98
	40%	87.51	59.26	70.67	84.29	65.91	73.97	85.65	64.14	73.35	85.82	63.1	72.66
Pos Weight	50%	83.66	68.09	75.08	85.78	66.33	74.81	85.66	65.92	74.5	85.03	66.78	74.8
	60%	84.85	68.57	75.85	85.55	68.09	75.83	84.51	68.87	75.89	84.97	68.51	75.86
	70%	82.77	73.07	77.62	83.0	73.13	77.76	84.37	71.4	77.34	83.38	72.53	77.57
	80%	83.57	73.82	78.39	82.46	75.68	78.93	83.64	73.61	78.31	83.22	74.37	78.54
	90%	83.9	74.54	78.94	82.48	76.44	79.35	82.87	75.8	79.18	83.08	75.59	79.16
	10%	88.1	29.67	44.39	86.06	30.1	44.6	86.06	32.37	47.05	86.74	30.71	45.35
	20%	82.94	55.7	66.64	83.72	55.24	66.56	85.49	51.25	64.08	84.05	54.06	65.76
	30%	85.9	58.87	69.86	86.47	55.99	67.97	82.7	63.04	71.55	85.02	59.3	69.79
	40%	86.1	62.08	72.14	85.55	62.72	72.37	85.19	64.47	73.39	85.61	63.09	72.63
Neg Weight	50%	84.25	67.83	75.15	84.27	68.5	75.57	83.64	68.37	75.24	84.05	68.23	75.32
	60%	84.25	69.76	76.32	84.39	69.17	76.02	82.92	71.29	76.67	83.85	70.07	76.34
	70%	81.89	73.52	77.48	82.88	73.03	77.64	83.74	71.72	77.27	82.84	72.76	77.46
	80%	80.99	76.24	78.54	82.51	74.83	78.48	81.58	74.93	78.11	81.69	75.33	78.38
	90%	80.85	77.08	78.92	80.7	76.93	78.77	80.92	77.22	79.03	80.82	77.08	78.91
	10%	64.47	72.78	68.37	62.39	74.98	68.11	48.65	83.15	61.39	58.5	76.97	65.96
	20%	82.25	66.75	73.69	86.2	58.91	69.99	81.94	67.33	73.92	83.46	64.33	72.53
	30%	83.71	67.98	75.03	86.03	63.58	73.12	80.87	71.56	75.93	83.54	67.71	74.69
Our PAPG	40%	84.56	68.92	75.94	83.21	70.08	76.08	83.78	69.2	75.8	83.85	69.4	75.94
	50%	81.4	72.86	76.89	80.32	74.34	77.21	82.55	73.62	77.83	81.42	73.61	77.31
	60%	82.3	73.97	77.92	80.4	75.35	77.79	80.61	74.7	77.54	81.1	74.67	77.75
	70%	83.34	13.57	/8.15	83.27	13.87	18.29	83.25	/4.36	/8.55	83.29	/3.93	18.33
	80%	81.92	/3.63	/8.00	81.68	78.01	18.15	02.77	80.57	/0.56	15.46	//.41	15.99
	90%	80.83	//.58	/9.18	80.41	/8.01	/9.19	80.97	//.48	/9.19	80.74	//.69	19.2

Table 6: Results of DREEAM, Pos Weight, Neg Weight, PAPG on different ratios of annotated labels

	version0			v	version1			version2			average		
Sampling Ratio	Р	R	F1	Р	R	F1	P	R	F1	Р	R	F1	
0.1	71.21	82.27	76.34	77.19	77.3	77.25	81.53	71.14	75.98	76.64	76.9	76.52	
0.2	75.22	79.23	77.17	79.72	74.82	77.19	83.26	68.4	75.14	79.4	74.15	76.5	
0.3	76.79	77.88	77.33	80.57	73.6	76.93	84.88	66.84	74.79	80.75	72.77	76.35	
0.4	78.26	77.18	77.72	81.1	73.58	77.16	83.94	67.4	74.77	81.1	72.72	76.55	
0.5	78.35	77.1	77.72	83.26	72.1	77.28	85.23	65.7	74.2	82.28	71.63	76.4	
0.6	79.54	76.04	77.75	83.22	71.41	76.86	85.41	65.74	74.29	82.72	71.06	76.3	
0.7	80.74	75.35	77.95	83.03	71.12	76.61	86.41	64.4	73.8	83.39	70.29	76.12	
0.8	80.43	75.12	77.68	83.92	70.6	76.69	84.65	65.7	73.98	83.0	70.47	76.12	
0.9	81.04	74.62	77.7	84.45	69.83	76.45	84.44	65.74	73.92	83.31	70.06	76.02	

Table 7: Action Sampling Ratio

	version0			version1			v	ersion	2	average			
Data Ratio	Р	R	F1	Р	R	F1	P	R	F1	P	R	F1	
10%	60.69	74.91	67.06	57.47	77.17	65.88	45.89	84.41	59.46	54.68	78.83	64.13	
20%	81.16	67.2	73.52	86.34	58.12	69.47	83.3	63.88	72.3	83.6	63.07	71.76	
30%	83.1	66.99	74.18	83.65	64.82	73.04	80.95	69.74	74.93	82.57	67.18	74.05	
40%	85.19	66.35	74.6	83.25	69.41	75.7	83.12	69.13	75.48	83.85	68.3	75.26	
50%	80.44	72.78	76.42	78.51	75.1	76.76	83.24	72.89	77.28	80.73	73.59	76.82	
60%	83.53	71.8	77.22	79.9	74.35	77.02	80.59	73.6	76.93	81.34	73.25	77.06	
70%	86.14	69.18	76.74	87.65	66.63	75.71	85.57	69.9	76.94	86.45	68.57	76.46	
80%	85.77	70.19	77.2	83.64	72.85	77.87	79.93	71.16	75.29	83.11	71.4	76.79	
90%	83.86	74.78	79.06	82.85	74.42	78.41	83.77	74.42	78.82	83.49	74.54	78.76	

Table 8: Value Network Performance of Our PAPG. We construct the training set three times with different random seeds, corresponding to the three versions.

	nnPU			ImbnnPU			Negative Mode			Our PAPG		
Data Ratio	Р	R	F1	Р	R	F1	Р	R	F1	Р	R	F1
10%	52.0	39.3	44.8	41.3	59.2	48.6	40.4	3.8	7.0	47.7	53.0	50.2
20%	54.6	42.6	47.9	43.9	66.8	53.0	76.8	9.6	17.1	61.4	68.1	64.6
30%	58.4	42.3	49.1	43.9	66.8	53.0	71.1	18.0	28.7	59.6	75.6	66.6
40%	57.1	45.1	50.4	54.8	73.7	62.8	76.9	24.9	37.6	62.1	74.6	67.8
50%	56.9	49.2	52.8	61.5	69.4	65.2	75.0	45.8	56.9	63.8	76.9	69.8
60%	59.4	49.7	54.1	61.5	68.1	64.6	69.1	46.5	55.6	65.0	77.7	70.8
70%	61.7	51.5	56.1	62.6	67.4	64.9	82.2	52.7	64.2	72.6	77.7	75.1
80%	63.0	52.7	57.4	63.2	72.8	67.7	79.5	64.4	71.2	78.9	73.0	75.8
90%	70.4	47.5	56.7	62.7	77.2	69.2	82.5	69.1	75.2	75.2	78.7	76.9

Table 9: The results of CIFAR10 dataset. We consider the original class 'airplane' as the positive targets.

	Pos Weight			Neg Weight			Negative Mode			Our PAPG		
Data Ratio	Р	R	F1	Р	R	F1	P	R	F1	Р	R	F1
20%	72.8	69.5	71.1	89.7	39.5	54.9	87.9	9.9	17.9	79.4	67.2	72.8
40%	74.3	75.0	74.7	82.5	65.6	73.1	90.3	28.0	42.8	83.0	74.4	78.5
60%	74.6	79.0	76.7	80.1	74.0	76.9	96.0	47.0	63.1	79.4	76.5	77.9
80%	72.5	83.1	77.4	83.1	75.7	79.2	92.8	65.3	76.6	82.4	77.5	79.9

Table 10: The results of other annotation ratios on MS-COCO dataset.

Standard Deviation										
10	%	30%		50	%	70	%	90%		
F1	mAP	F1	mAP	F1	mAP	F1	mAP	F1	mAP	
68.3(0.12)	66.6(0.33)	77.0(0.30)	77.5(0.25)	79.1(0.15)	80.4(0.13)	79.0(0.10)	81.4(0.15)	80.5(0.05)	83.4(0.05)	

Table 11: The standard deviations (\cdot) of F1 and mAP were computed from three different runs on the MS-COCO dataset.

Table 12: Experimental Results on COCO datasets with varying ratios of positive classes annotations.

	10%		30	30%		50%		%	90%	
Method	F1	mAP								
ERP	-	63.8	-	71.0	-	73.5	-	73.8	-	74.4
ROLE	-	58.2	-	72.4	-	76.6	-	79.5	-	81.1
P-ASL+Negative	45.2	66.9	52.1	74.6	54.0	76.9	71.9	81.0	80.3	83.3
P-ASL+Counting	5.1	46.4	26.4	63.4	53.7	76.1	71.6	80.1	60.4	80.4
Pos Weight	66.7	64.3	73.0	72.7	75.7	76.7	76.0	79.9	77.5	82.6
Neg Weight	24.0	56.9	68.7	74.8	75.9	78.0	77.9	79.7	80.5	82.8
Negative Mode	6.4	50.6	33.7	64.3	52.9	73.8	72.3	81.2	80.1	83.5
PAPG (Ours)	68.3	66.6	77.0	77.5	79.1	80.4	79.0	81.4	80.5	83.4

Item	Content or Triples
Title	Guido Bonatti
Document	Guido Bonatti (died between 1296 and 1300) was an Italian mathematician, astronomer and astrologer, who was the most celebrated astrologer of the 13th century. Bonatti was advisor of Frederick II, Holy Roman Emperor, Ezzelino da Romano III, Guido Novello da Polenta and Guido I da Montefeltro. He also served the communal governments of Florence, Siena and Forlì. His employers were all Ghibellines (supporters of the Holy Roman Emperor), who were in conflict with the Guelphs (supporters of the Pope), and all were excommunicated at some time or another. Bonatti 's astrological reputation was also criticised in Dante's Divine Comedy, where he is depicted as residing in hell as punishment for his astrology. His most famous work was his Liber Astronomiae or 'Book of Astronomy', written around 1277. This remained a classic astrology textbook for two centuries.
DREEAM	$\langle Dante, notable work, Divine Comedy \rangle$
Pos Weight	<pre></pre>
Neg Weight	 (Guido Bonatti, notable work, Liber Astronomiae) (Guido Bonatti, notable work, Book of Astronomy) (Dante, notable work, Divine Comedy) (Divine Comedy, author, Dante)
Our PAPG	 \langle Guido Bonatti, notable work, Liber Astronomiae \langle Guido Bonatti, notable work, Book of Astronomy \langle Dante, notable work, Divine Comedy \langle Divine Comedy, creator, Dante \langle Divine Comedy, author, Dante \langle Liber Astronomiae, author, Guido Bonatti \langle
Ground Truth	\(Guido Bonatti, date of death, 1296\) \(Guido Bonatti, date of death, 1300\) \(Divine Comedy, characters, Guido Bonatti\) \(Divine Comedy, creator, Dante\) \(Divine Comedy, author, Dante\) \(Divine Comedy, author, Dante\) \(Book of Astronomy, author, Guido Bonatti\) \(Cuido Bonatti, country of citizenship, Italian\) \(Guido Bonatti, notable work, Liber Astronomiae\) \(Quido Bonatti, present in work, Divine Comedy\) \(Guido Bonatti, notable work, Book of Astronomy\)

Table 13: An Example from Re-DocRED