

Table 1: Effect of different information exchange modes and no explicit exchange mode on the RelMSE. Reported errors are multiplied by 10^2 .

| mode | CF (u) | CF (v) | CF (p) | MP (u) | MP (v) | MP (α) | Avg |
|-------------|-------------|-------------|-------------|--------------|--------------|-----------------|--------------|
| No exchange | 11.12 | 13.70 | 14.21 | 75.52 | 54.96 | 121.63 | 48.52 |
| Mixture | 7.33 | 7.54 | 5.91 | 20.88 | 25.12 | 71.3 | 23.01 |
| Addition | 6.11 | 6.28 | 4.87 | 16.89 | 22.93 | 22.79 | 13.31 |
| SEA | 1.64 | 1.49 | 1.14 | 17.18 | 23.45 | 22.45 | 11.22 |

Table 2: Effect of time invariant parameter injection to the SEA implemented temporal transformer.

| mode | Cylinder flow | Multiphase flow |
|-------------------|---------------|-----------------|
| Without injection | 0.015 | 0.4381 |
| With injection | 0.014 | 0.2157 |

Table 3: Effect of batch size on autoregressive generation RelMSE for a SEA implemented model.

| batch size | Cylinder flow | Multiphase flow |
|------------|---------------|-----------------|
| 1 | 0.107 | 0.4063 |
| 2 | 0.1076 | 0.5562 |
| 4 | 0.1101 | 1.1877 |

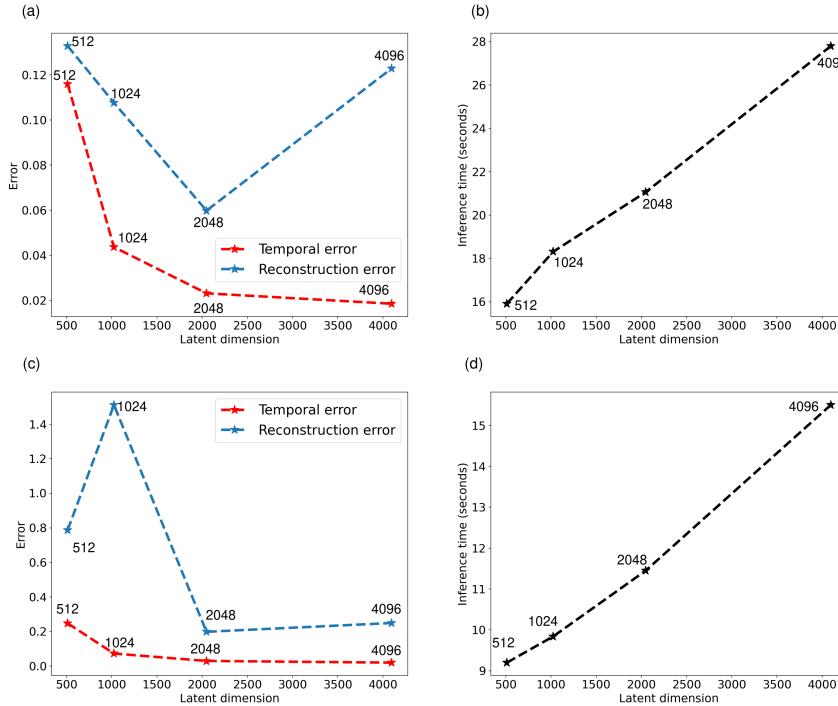


Figure 1: Detailed evaluation of error components and inference times (Reported in seconds) with respect to model dimensions for (a) error in cylinder flow, (b) inference time for cylinder flow, (c) error in multiphase flow, and (d) inference time for multiphase flow.