Table 1: Ablation on the choice of constructive model as the conquering policy in KP. ICAM and POMO are two available constructive solvers for KP. The datasets are the same as Table 11 in the original paper. The value shown in the table is the gap to optimal.

| Method | KP500 | KP1,000 | KP2,000 | KP5,000 |
|-----------------------|---------|---------|---------|---------|
| UDC- x_{50} (ICAM) | 0.0247% | 0.0260% | 0.0237% | 0.0249% |
| UDC- x_{250} (ICAM) | 0.0083% | 0.0106% | 0.0105% | 0.0100% |
| UDC- x_{50} (POMO) | 0.0255% | 0.0252% | 0.0253% | 0.0242% |
| UDC- x_{250} (POMO) | 0.0098% | 0.0107% | 0.0119% | 0.0113% |

Table 2: Ablation on whether to enable the DCR in training UDC for KP. The version with disabling DCR (i.e., Disable DCR) is the same as Table 11 in the original paper and the datasets are also the same. The value shown in the table is the gap to optimal.

| Method | KP500 | KP1,000 | KP2,000 | KP5,000 |
|------------------------------|---------|---------|---------|---------|
| UDC- x_{50} (Disable DCR) | 0.0247% | 0.0260% | 0.0237% | 0.0249% |
| UDC- x_{250} (Disable DCR) | 0.0083% | 0.0106% | 0.0105% | 0.0100% |
| UDC- x_{50} (Enable DCR) | 0.0105% | 0.0258% | 0.0254% | 0.0273% |
| UDC- x_{250} (Enable DCR) | 0.0080% | 0.0117% | 0.0128% | 0.0095% |

Table 3: The revised version of Table 12 in the original paper. The time (i.e., Time in the table) of LKH3 on three datasets is now accurately listed.

| | OVRP500 | | | OVRP1,000 | | | OVRP2,000 | | |
|-----------------------------|---------|--------|-------|-----------|---------|-------|-----------|---------|------|
| Method | Obj. | Gap | Time | Obj. | Gap | Time | Obj. | Gap | Time |
| LKH3 | 23.51 | - | 16m | 28.96 | - | 32m | 39.88 | - | 27m |
| POMO | 28.73 | 22.21% | 1.5m | 59.26 | 104.61% | 16m | 108.82 | 172.90% | 16m |
| UDC- $x_2(\alpha = 50)$ | 25.82 | 9.86% | 1.4m | 33.01 | 13.97% | 3m | 51.11 | 28.17% | 42s |
| UDC- $x_{50}(\alpha = 50)$ | 24.39 | 3.77% | 7.9m | 29.95 | 3.41% | 15.5m | 44.19 | 10.82% | 4.5m |
| UDC- $x_{250}(\alpha = 50)$ | 24.18 | 2.85% | 34.5m | 29.66 | 2.39% | 1.1h | 43.35 | 8.71% | 20m |

Table 4: Ablation on different algorithms as initial solutions x_0 . The conquering stages of all the variants are the constructive of UDC. Random-UDC represents directly a random solution as the initial solution. Nearest Greedy-UDC uses the nearest greedy algorithm (starting from the first node) and Random Insertion-UDC employs the random insertion heuristic as the initial solution. $\alpha = 1$ in all UDC variants. UDC- x_2 and UDC- x_{50} is the original version. Obj. is the objective value and Gap represents the gap to the best method.

| Method | TSP500 | | TSP1,000 | | TSP2,000 | |
|---------------------------------|--------|---------|----------|---------|----------|---------|
| Method | Obj. | Gap | Obj. | Gap | Obj. | Gap |
| Concorde | 16.52 | - | 23.12 | - | 32.45 | - |
| Random-UDC- x_2 | 33.98 | 105.68% | 67.82 | 193.34% | 134.98 | 315.98% |
| Random-UDC- x_{50} | 26.11 | 58.01% | 52.48 | 126.98% | 104.48 | 221.96% |
| Nearest Greedy-UDC- x_2 | 18.48 | 11.87% | 26.42 | 14.27% | 37.48 | 15.50% |
| Nearest Greedy-UDC- $m{x}_{50}$ | 17.88 | 8.23% | 25.75 | 11.38% | 36.80 | 13.40% |
| Random Insertion-UDC- x_2 | 17.09 | 3.45% | 24.08 | 4.17% | 34.00 | 4.78% |
| Random Insertion-UDC- x_{50} | 16.84 | 1.93% | 23.75 | 2.73% | 33.55 | 3.38% |
| UDC- x_2 | 17.12 | 3.62% | 24.06 | 4.05% | 34.44 | 6.13% |
| UDC- x_{50} | 16.92 | 2.41% | 23.68 | 2.42% | 33.60 | 3.54% |