

Figure 1: The visualization of Cross-Domain Prototype Conversion in the UEM framework, which involves the following steps: 1) As an example, for prototype conversion of domain A, we first translate all prototypes of domain B along the vector connecting the centers of the two domains to domain A. 2) Next, all prototypes in domain A use the Hungarian algorithm to find the nearest translated domain B prototypes. 3) For each prototype pair determined by the Hungarian algorithm, we check if they satisfy the merging condition (Eq.9 in the paper). If they do, the prototypes are merged by averaging; if not, they remain unchanged. 4) Finally, the prototype set for domain A is composed of the merged prototypes, the unmerged original domain A prototypes, and the unmerged translated domain B prototypes.

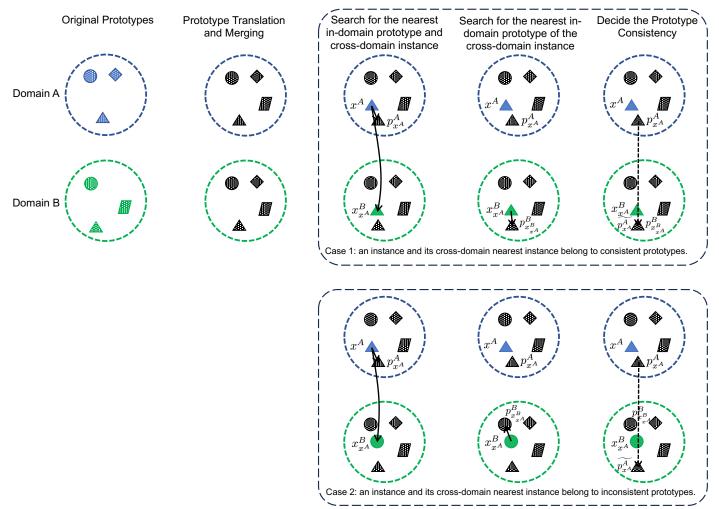


Figure 2: The visualization of Switchable Nearest Neighboring Match in the UEM framework, which involves the following steps: 1) The prototypes of domains A and B are transformed according to the previously described prototype conversion strategy. 2) For an instance  $x^A$  in domain A, we first find its nearest domain A prototype  $p_{xA}^A$  based on the product of cosine similarity and Euclidean distance. We also find  $x^A$ 's nearest domain B instance  $x_{xA}^B$  using the same criteria (refer to Eq.15 and Eq.16 in the paper). 3) For the nearest domain B instance  $x_{xA}^B$ , we then find its nearest domain B prototype  $p_{xA}^B$ . 4) If  $p_{xA}^B$  matches  $p_{xA}^A$  across domains (i.e., if we translate  $p_{xA}^A$  from domain A to B, the translated  $\widetilde{p_{xA}^A}$  is the same as  $p_{xA}^B$ ), we consider  $x^A$  and  $x_{xA}^B$  as a positive pair in contrastive learning (Eq.17). Otherwise, we only consider  $x^A$  and  $\widetilde{p_{xA}^A}$  as a positive pair in contrastive learning.