

1 Checklist

- 2 1. For all authors...
 - 3 (a) Do the main claims made in the abstract and introduction accurately reflect the paper's
4 contributions and scope? [Yes] See Section 4.
 - 5 (b) Did you describe the limitations of your work? [Yes] See Appendix F.
 - 6 (c) Did you discuss any potential negative societal impacts of your work? [Yes] See
7 Appendix G.
 - 8 (d) Have you read the ethics review guidelines and ensured that your paper conforms to
9 them? [Yes]
- 10 2. If you are including theoretical results...
 - 11 (a) Did you state the full set of assumptions of all theoretical results? [N/A]
 - 12 (b) Did you include complete proofs of all theoretical results? [N/A]
- 13 3. If you ran experiments...
 - 14 (a) Did you include the code, data, and instructions needed to reproduce the main experi-
15 mental results (either in the supplemental material or as a URL)? [Yes] We open the
16 source code publicly after the acceptance (<https://github.com/ahyungshin/AnoFormer>).
 - 17 (b) Did you specify all the training details (e.g., data splits, hyperparameters, how they
18 were chosen)? [Yes] See Section 4, Appendix A, and Appendix B.
 - 19 (c) Did you report error bars (e.g., with respect to the random seed after running experi-
20 ments multiple times)? [Yes] See Figure 3.
 - 21 (d) Did you include the total amount of compute and the type of resources used (e.g., type
22 of GPUs, internal cluster, or cloud provider)? [Yes] See Appendix D.
- 23 4. If you are using existing assets (e.g., code, data, models) or curating/releasing new assets...
 - 24 (a) If your work uses existing assets, did you cite the creators? [Yes] See Section 4 and
25 Reference.
 - 26 (b) Did you mention the license of the assets? [Yes]
 - 27 (c) Did you include any new assets either in the supplemental material or as a URL? [Yes]
28 See Appendix A
 - 29 (d) Did you discuss whether and how consent was obtained from people whose data you're
30 using/curating? [Yes]
 - 31 (e) Did you discuss whether the data you are using/curating contains personally identifiable
32 information or offensive content? [Yes]
- 33 5. If you used crowdsourcing or conducted research with human subjects...
 - 34 (a) Did you include the full text of instructions given to participants and screenshots, if
35 applicable? [N/A]
 - 36 (b) Did you describe any potential participant risks, with links to Institutional Review
37 Board (IRB) approvals, if applicable? [N/A]
 - 38 (c) Did you include the estimated hourly wage paid to participants and the total amount
39 spent on participant compensation? [N/A]

Supplementary:

AnoFormer: Time Series Anomaly Detection using Transformer-based GAN with Two-Step Masking

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40 Here we provide a brief outline of the appendices. In Appendix A, we provide details of datasets. In
41 Appendix B, we provide additional experiments about hyperparameter sensitivity. In Appendix C, we
42 discuss how to select the layer for entropy-based re-masking strategy. In Appendix D, we study the
43 effectiveness of our embedding method. In Appendix E and F, we discuss the limitations and broader
44 impacts of our methods.

45 A Dataset

46 We used a total of four time series anomaly detection datasets. In the training set, all datasets contain
47 normal data only. Table 1 shows details of each dataset.

- 48 1. NeurIPS-TS¹: This is the dataset which introduces a new taxonomy for time series outliers.
49 It includes total of five different time series anomaly scenarios that cover point-global,
50 point-contextual, pattern-shapelet, pattern-seasonal, and pattern-trend. We created our own
51 dataset using the open source code. Datasets will be made public after the review.
- 52 2. MIT-BIH Arrhythmia Database²: This database contains 48 ECG records of test subjects
53 from Beth Israel Hospital. As recommended by the Association for the Advancement of
54 Medical Instrumentation (AAMI) [1], there are five classes that are Normal (N), Supraventricular
55 Ectopic Beat (S), Ventricular Ectopic Beat (V), Fusion (F), and Unknown Beat
56 (Q).
- 57 3. 2D-gesture³: This dataset contains time series of X and Y coordinates of an actor’s right
58 hand. The actor grabs a gun from his hip-mounted holster, and then shoots at the target.
59 Finally, the actor returns it to the holster. The anomalous region is that the actor misses the
60 holster when returning the gun.
- 61 4. Power-demand⁴: This is the dataset measuring the power consumption for the Dutch
62 research facility for the entire year of 1997.

63 B Hyperparameter Sensitivity

64 For the proposed AnoFormer, we set the quantization resolution K as 400 in the main paper. Moreover,
65 for the proposed two-step masking, we set the mask ratio r_m as 50%, the mask length l_m as 10% of
66 the sequence length, the stride of sliding window as a half of l_m , and the re-masking ratio as 50% of
67 the parts masked in Step 1. We further analyzed the sensitivity of hyperparameters in AnoFormer.

¹<https://github.com/datamllab/tods/tree/benchmark>

²<https://physionet.org/content/mitdb/1.0.0/>,

³<https://www.cs.ucr.edu/~eamonn/discords/>.

⁴<https://www.cs.ucr.edu/~eamonn/discords/>.

Table 1: Statistical details of four datasets.

Datasets		Dimension	Length	# Training	# Validation	# Test
NeurIPS-TS	(A) Point-Global	1	100	18,000	8,954	11,927
	(B) Point-Contextual	1	100	18,000	8,954	11,927
	(C) Pattern-Shapelet	1	100	18,000	8,954	11,927
	(D) Pattern-Seasonal	1	100	18,000	8,954	11,927
	(E) Pattern-Trend	1	100	18,000	8,954	11,927
MIT-BIH		1	320	62,436	8,025	27,107
2D-gesture		2	64	1,093	469	46
Power-demand		1	512	1,088	467	224

68 First, we provide the performances and the visualization results for the different number of K in
69 Table 2. We found that our model is not sensitive to the different values of K , and we set $K = 400$
70 consistently for all experiments because this is visually similar to the original signal.

Table 2: Sensitivity for the quantization resolution.

# of tokens	100	200	300	400	500
AUROC	0.9791	0.9806	0.9793	0.9758	0.9719
AUPRC	0.9880	0.9883	0.9874	0.9854	0.9826
F1 score	0.9453	0.9435	0.9388	0.9400	0.9289

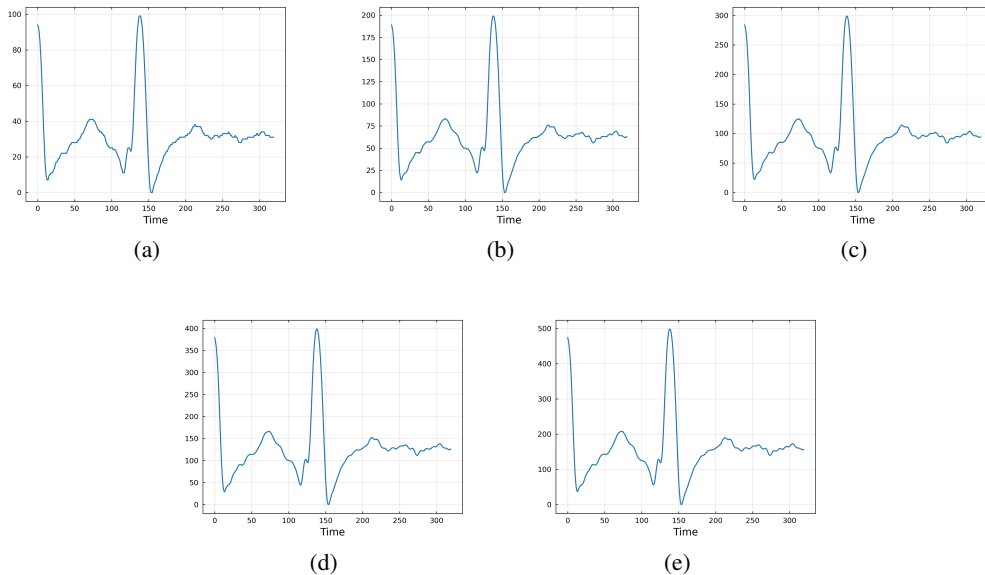


Figure 1: Visualization for each K in MIT-BIH dataset: (a) $K = 100$, (b) $K = 200$, (c) $K=300$, (d) $K = 400$, and (e) $K = 500$. When K is 100 or 200, those signals look discrete ones.

71 Table 3 shows the performances for the different strides of sliding window s_m while fixing the length
72 of the mask section l_m as 10% of T . As already explained, the number of masks n_m in the mask
73 pool was automatically determined by in Equation 1 by using the values of s_m and l_m . Our model

Table 3: Sensitivity for the stride of the sliding window.

Stride	3	5	10
# of pool	8	4	2
AUROC	0.9714	0.9758	0.9721
AUPRC	0.9828	0.9854	0.9834
F1 score	0.9344	0.9400	0.9315

74 performed better when the stride was 5, which is a half of l_m .

$$n_m = 2 \times \left\lceil \frac{l_m}{s_m} \right\rceil. \quad (1)$$

75 We also present the compared results depending on the different re-masking ratios in Table 4. When
 76 we re-masked a half of the masked parts in Step 1 for the proposed entropy-based re-masking, the
 77 performance was the highest among them. To sum up, AnoFormer shows the robust performances to
 the changes of the hyperparameters.

Table 4: Sensitivity for the entropy-based re-masking ratio.

entropy-based re-masking ratio	+10%	+20%	+25%	+30%	+40%
AUROC	0.9682	0.9726	0.9758	0.9615	0.9285
AUPRC	0.9797	0.9841	0.9854	0.9747	0.9538
F1 score	0.9291	0.9363	0.9400	0.9115	0.8823

78

79 C How to Select the Layers for Entropy-based Re-masking?

80 For entropy-based re-masking, we average the entropies from all layers. Attentions are often uniformly
 81 distributed in the first block of Transformer [2]. We further analyzed the performance of the last-layer
 82 usage. This is because the last layer reflects the characteristics of the data the best. As shown in Table
 83 5, using all layers for re-masking achieved the best performance. This results show that each layer of
 transformer contains meaningful information to reconstruct the signal.

Table 5: Experiment to select layers to calculate entropy.

Layer Selection	AUROC	AUPRC	F1 score
Last layer	0.9735	0.9846	0.9371
All layers	0.9758	0.9854	0.9400

84

85 D Effectiveness of the Proposed Embedding Method

86 The existing transformer-based time series processing methods utilize linear layers for token embed-
 87 ding and use the mean squared error to reconstruct time series data. Different from these studies, we
 88 apply the embedding matrix to process time series data. To this end, we replace the reconstruction loss
 89 to the cross-entropy. In other words, we change the regression problem to the simple classification
 90 one. We further examine the effects of the proposed embedding method. As shown in Figure 2,
 91 using embedding matrix achieved better performance with a large margin and converged quickly. We
 92 empirically demonstrated that the proposed embedding strategy is effective to process time series
 93 data and is superior to the reconstruction-based anomaly detection problem.

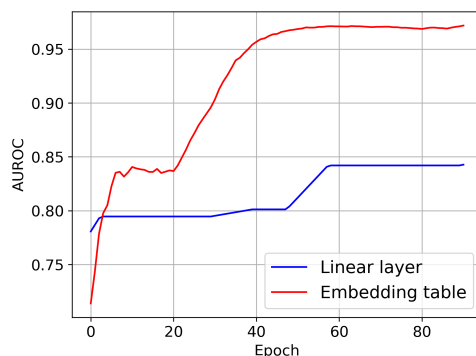


Figure 2: Performance comparison of different embedding methods.

94 **E Limitation**

95 Since we combine the signals generated through Step 1 and Step 2 for the final output, there is a
 96 problem of noisiness at the mask boundary. In addition, in Step 2 of the proposed masking method,
 97 we provide entropy-based feedback to the masked part in Step 1, but we do not provide feedback
 98 on the exclusive part of Step 2. Moreover, there is a problem that the inference time is long because
 99 we perform the forwarding operation twice for one signal. However, this is not a big deal because
 100 accuracy is more important than detecting in real time. In the future, we plan to solve those problems.

101 **F Broader Impact**

102 Recently, many researches actively conduct anomaly detection using deep learning. Accordingly,
 103 not only does the performance improve, but many industrial areas apply anomaly detection model
 104 effectively in the real world. Anomaly detection is generally used positively. It improves safety and
 105 prevents potential risks and financial losses by detecting anomalies in healthcare, manufacturing, and
 106 autonomous driving, etc. However, the system can be stuck into confirmation bias, *i.e.*, the model can
 107 ignore new forms of anomalies. We can cope with this situation by updating the model periodically
 108 for new knowledge.

109 **References**

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 114 transformer. In *Proceedings of the AAAI conference on artificial intelligence*, volume 34, pages
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