

Sparse view 3D Scene Completion

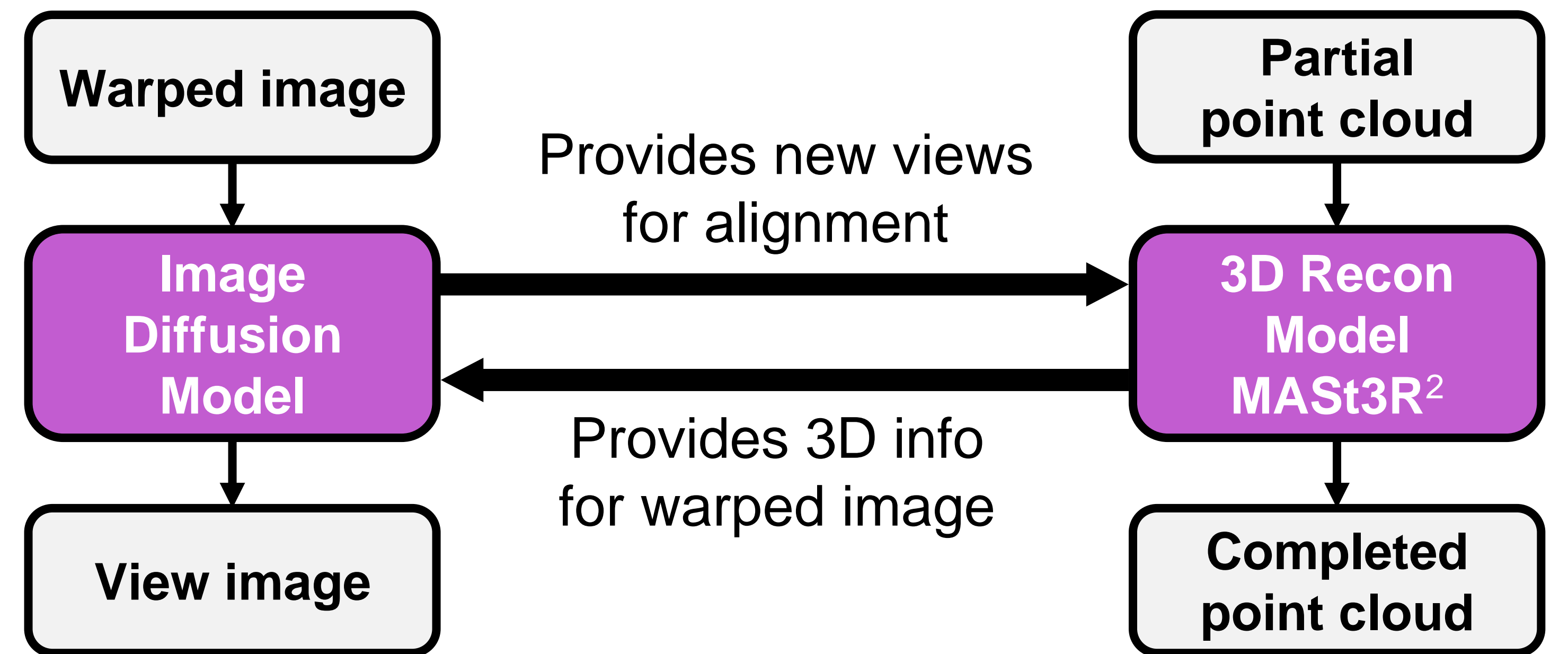
Optimization + Generation Problem



Existing 3DGS¹-based methods:

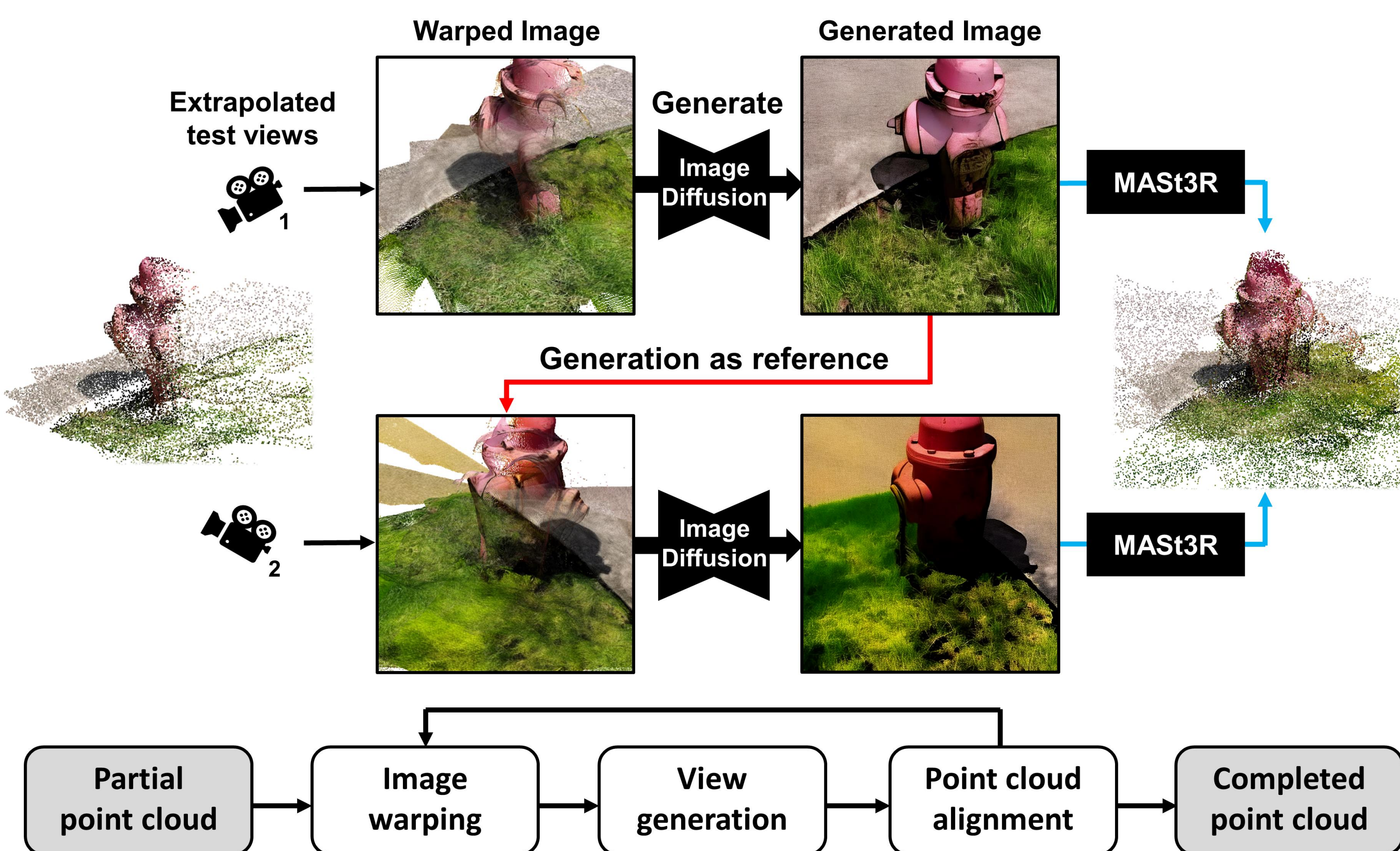
- Easily **overfit** to input views
- Difficult to produce **extrapolated** views
- Refining can't fully leverage the **diffusion prior**

Iterative Generation & Alignment



Ensure 3D Consistency & Realistic Extrapolation

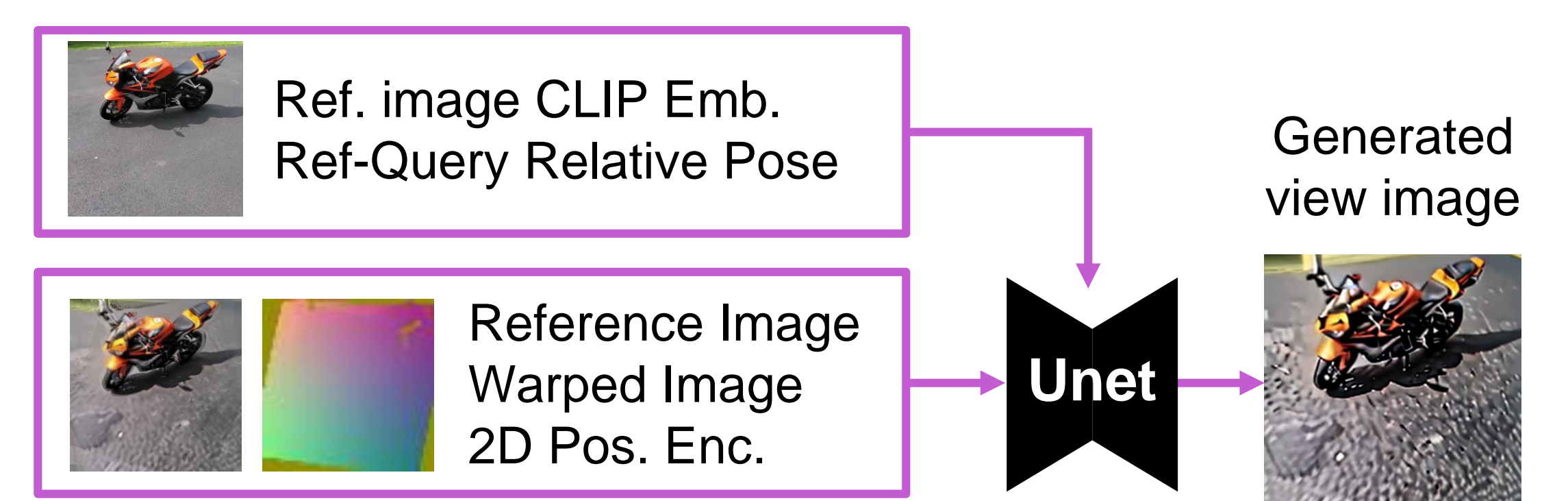
Proposed Method



1. Depth-aware Warped Image Generation

$$I_{warp} = H_{warp} I_{ref} = K P_{query} P_{ref}^{-1} D_{ref} K^{-1} I_{ref}$$

2. Warped Image-conditioned Diffusion



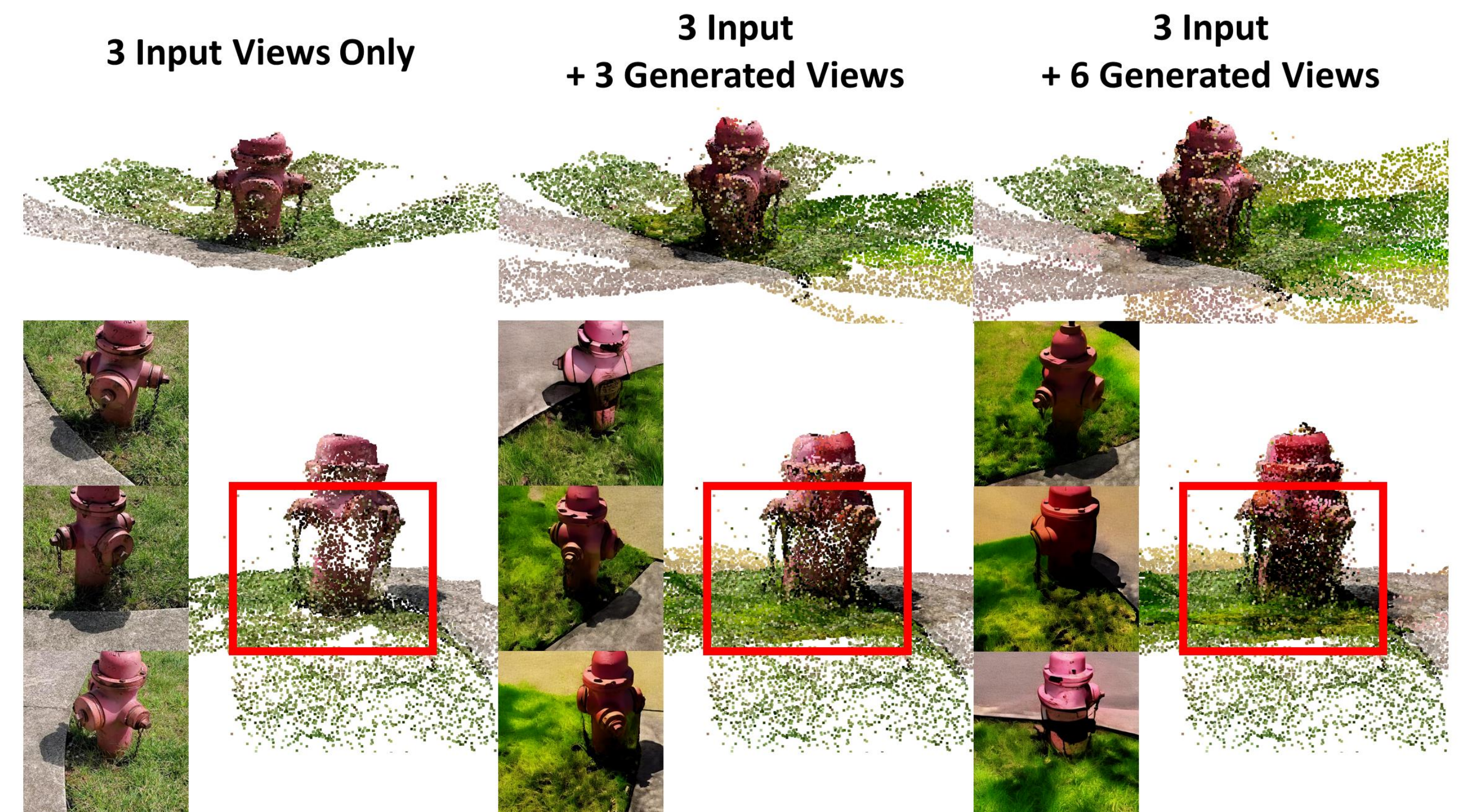
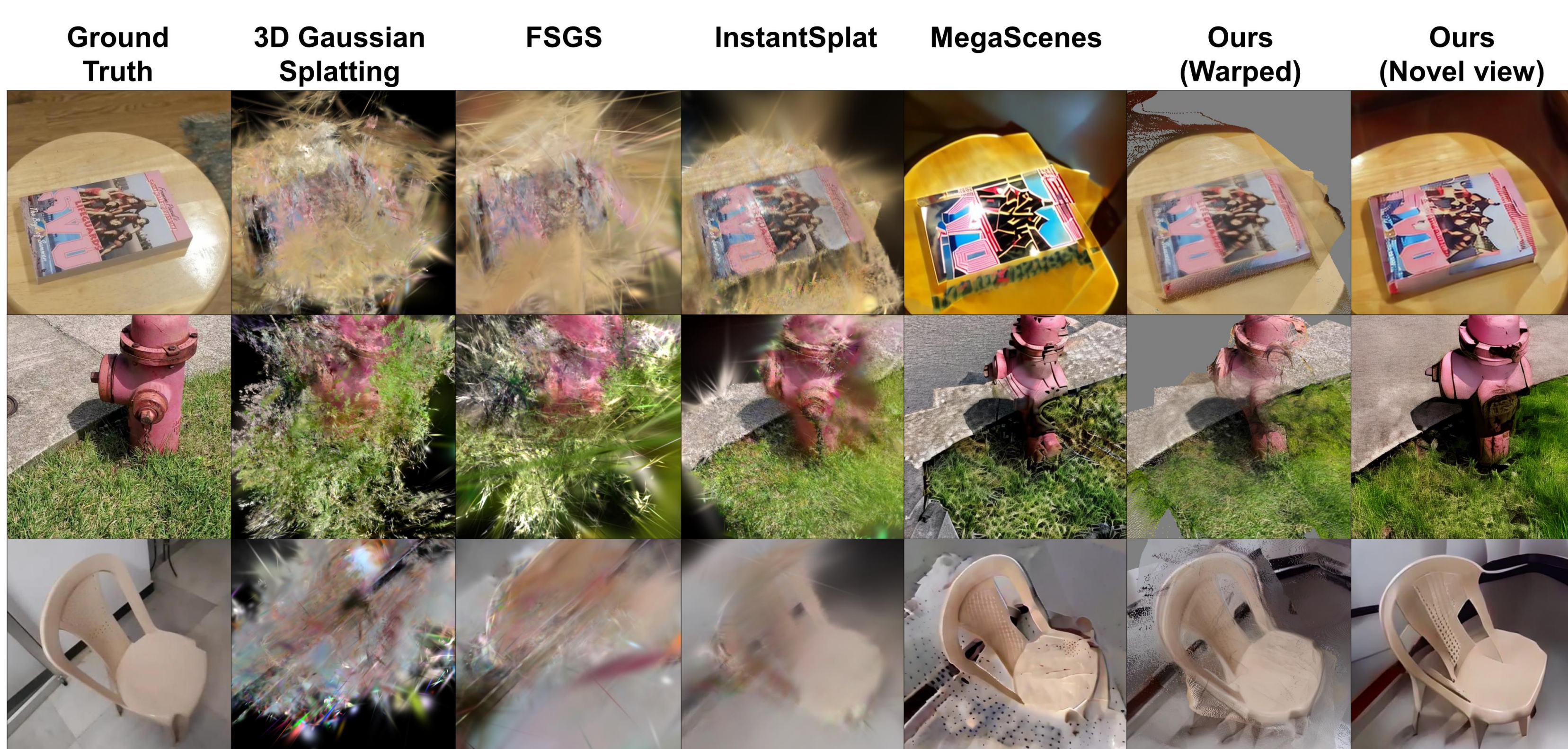
- Fine-tune **ZeroNVS³** model to generate views
- Add warped Image / Positional Encoding inputs
- **Per-scene LoRA** via cross-input view generation

3. Incremental 3D Reconstruction

- Optimize only the new images' **depth maps**

Results

		LPIPS ↓		DISTS ↓		Masked PSNR ↑		Masked SSIM ↑		Perfrom Time ↓	
		3-view	6-view	3-view	6-view	3-view	6-view	3-view	6-view	3-view	6-view
3DGS based	3DGS	0.707	0.640	0.385	0.351	12.759	14.342	0.583	0.621	291.7	335.7
	FSGS	0.666	0.596	0.384	0.338	14.784	15.218	0.684	0.673	108.8	118.8
	InstantSplat	0.588	0.481	0.327	0.276	16.792	18.149	0.750	0.753	71.1	103.6
Diffusion based	DN Gaussian	0.723	0.644	0.417	0.354	13.759	14.463	0.683	0.677	159.5	141.4
	ZeroNVS	0.694	0.652	0.339	0.311	12.641	12.812	0.606	0.569	22.6	37.0
	MegaScenes	0.603	0.526	0.279	0.245	14.352	14.783	0.646	0.631	38.0	59.3
	Ours	0.577	0.525	0.266	0.246	14.397	14.694	0.645	0.616	38.5	59.4



- Proposed method achieves strong results on **LPIPS (realism)** and **DISTS (geometric consistency)**.
- Proposed model can **generate extrapolated views** that 3D reconstruction model can **confidently rely on**.
- Previously **unseen parts** of the scene **are gradually filled in** by the generated views.

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Reference

¹ Kerbl, Bernhard, et al. "3d gaussian splatting for real-time radiance field rendering." *ACM Trans. Graph.* 42.4 (2023): 139-1.

² Leroy, Vincent, Yohann Cabon, and Jérôme Revaud. "Grounding image matching in 3d with mast3r." *European Conference on Computer Vision*. Cham: Springer Nature Switzerland, 2024.

³ Sargent, Kyle, et al. "Zeronvs: Zero-shot 360-degree view synthesis from a single image." *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*. 2024.