

Supplementary Materials — SPA: A Graph Spectral Alignment Perspective for Domain Adaptation

In the appendix, we firstly provide more details of experiment setup in Section A, including experimental environment and implementation details. In the Section B, we offer more details of experiments to unsupervised domain adaptation in Section B.1, and then show the extension on semi-supervised domain adaptation in Section B.2. Finally, we further give a detailed model analysis of our SPA model in Section B.3, including robust analysis, parameter sensitivity, the analysis of transferability and discriminability, and finally more feature visualization.

A More Setup

Hardware and Software Configurations. All experiments are conducted on a server with the following configurations:

- Operating System: Ubuntu 20.04.4 LTS
- CPU: Intel(R) Xeon(R) Platinum 8358P CPU @ 2.60GHz, 32 cores, 128 processors
- GPU: NVIDIA GeForce RTX 3090

More Implementation Details. We use PyTorch and tllib toolbox [12] to implement our method and fine-tune ResNet pre-trained on ImageNet [10, 11]. Following the standard protocols for unsupervised domain adaptation in previous methods [20, 22], we use the same backbone networks for fair comparisons. For Office31 and OfficeHome dataset, we use ResNet-50 as the backbone network. For VisDA2017 and DomainNet dataset, we use ResNet-101 as the backbone network. Following previous work [20], we adopt mini-batch stochastic gradient descent (SGD) to learn the feature encoder by fine-tuning from the ImageNet pre-trained model with the learning rate 0.001, and new layers, as bottleneck layer and classification layer. The learning rates of the layers trained from scratch are set to be 0.01. We use the the same learning rate schedule in [20, 21], including a learning rate scheduler with a momentum of 0.9, a weight decay of 0.005, the bottleneck size of 256, and batch size of 32.

We report main experimental results with the average accuracy over 5 random trials with the initial seed 0. For transductive unsupervised domain adaptation, the reported accuracy is computed on the complete unlabeled target data, following established protocol for UDA [7, 21, 14, 3, 20]. For inductive unsupervised domain adaptation on DomainNet, the reported accuracy is computed on the provided test dataset.. We use a standard batch size of 32 for both source and target in all experiments and for all variants of our method. The reverse validation [19, 30] is conducted to select hyper-parameters. For both unsupervised domain adaptation (UDA) and semi-supervised domain adaptation (SSDA) scenarios, we fix the coefficient of \mathcal{L}_{nas} as 0.2 and the coefficient of \mathcal{L}_{gsa} as 1.0, while we will offer a sensitivity analysis for this two coefficients in the following section. More details refer to our code in the supplemental materials.

B More Experiments

B.1 Unsupervised Domain Adaptation

In the main paper, we present the classification accuracy results on VisDA2017 dataset for unsupervised domain adaptation and leave out per-category accuracy details. In the appendix, Table 1, we give the full table on VisDA2017, using ResNet101 as backbone. Looking into this table, we can find that our SPA model consistently outperforms most of domain adaptation methods. For classic baselines, we improve DANN [7] by 30.3%, and CDAN [21] by 14 %. For recent and state-of-the-art baselines, our results is 4% higher than NWD [2] and 0.5 % better than FixBi [22]. Our SPA model ranks top in 6 out of 12 categories, ranks top 2 in 9 out of 12 categories, and SPA also achieves the best classification accuracy in total.

47 Furthermore, in the main paper, we present the classification accuracy results on original DomainNet
48 with 365 categories. While the original DomainNet dataset has noisy labels, the previous work [25]
49 use a subset of it that contains 126 categories from C, P, R and S, 4 domains in total, which we refer
50 to as DomainNet126. In the appendix, Table 2, we show the results on DomainNet126. Our SPA
51 model consistently ranks top among 12 tasks across 4 domains and achieves the best accuracy of 77.1
52 %, which is 12.3 % better than the second one. For classic baselines, we improve DANN [7] by 20.2
53 %, and CDAN [21] by 16 %.

Table 1: Per-category Accuracy (%) on VisDA2017 for unsupervised domain adaptation, using ResNet101 as backbone. All the results are based on ResNet101 except those with mark †, which are based on ResNet50. The best accuracy is indicated in **bold** and the second best one is underlined.

Method	aero	bike	bus	car	horse	knife	motor	person	plant	skate	train	truck	Avg.
<i>Source Only</i> [10]	55.1	53.3	61.9	59.1	80.6	17.9	79.7	31.2	81.0	26.5	73.5	8.5	52.4
DANN [7]	81.9	77.7	82.8	44.3	81.2	29.5	65.1	28.6	51.9	54.6	82.8	7.8	57.4
CDAN [21]	85.2	66.9	83.0	50.8	84.2	74.9	88.1	74.5	83.4	76.0	81.9	38.0	73.7
MixMatch [1]	93.9	71.8	93.5	82.1	95.3	0.7	90.8	38.1	94.5	96.0	86.3	2.2	70.4
BSP [3]	92.4	61.0	81.0	57.5	89.0	80.6	90.1	77.0	84.2	77.9	82.1	38.4	75.9
NPL [17]	90.9	74.6	73.2	55.8	89.6	64.6	86.8	68.7	90.7	64.8	89.5	47.7	74.7
GVB [5]	-	-	-	-	-	-	-	-	-	-	-	-	75.3 [†]
MCC [14]	92.2	82.9	76.8	66.6	90.9	78.5	87.9	73.8	90.1	76.1	87.1	41.0	78.8
BNM [4]	93.6	68.3	78.9	70.3	91.1	82.8	<u>93.0</u>	78.7	90.9	76.5	89.1	40.9	79.5
ATDOC [20]	95.3	84.7	82.4	<u>75.6</u>	95.8	97.7	88.7	76.6	<u>94.0</u>	91.7	91.5	61.9	86.3
FixBi [22]	<u>96.1</u>	<u>87.8</u>	90.5	90.3	<u>96.8</u>	95.3	92.8	88.7	97.2	<u>94.2</u>	90.9	25.7	<u>87.2</u>
SDAT [24]	<u>94.8</u>	<u>77.1</u>	82.8	60.9	<u>92.3</u>	95.2	91.7	79.9	89.9	91.2	88.5	41.2	82.1
NWD [2]	<u>96.1</u>	82.7	76.8	71.4	92.5	<u>96.8</u>	88.2	<u>81.3</u>	92.2	88.7	84.1	53.7	83.7
SPA (Ours)	98.5	92.2	<u>86.3</u>	63.0	97.5	95.4	93.5	80.7	97.2	95.2	<u>91.1</u>	<u>61.4</u>	87.7

Table 2: Classification Accuracy (%) on DomainNet126 for unsupervised domain adaptation, using ResNet101 as backbone. The best accuracy is indicated in **bold** and the second best one is underlined.

Method	C→P	C→R	C→S	P→C	P→R	P→S	R→C	R→P	R→S	S→C	S→P	S→R	Avg.
<i>Source Only</i> [10]	38.4	50.9	43.9	50.3	66.7	39.9	54.6	57.9	43.7	52.5	43.5	48.3	49.2
DANN [7]	46.5	58.2	51.6	52.7	64.2	52.9	61.7	60.3	53.9	62.7	56.7	61.6	56.9
MCD [26]	43.7	55.7	47.6	51.9	67.8	45.0	52.9	57.3	40.4	56.3	50.8	56.8	52.3
BSP [3]	45.7	58.7	55.5	48.6	65.2	48.6	55.2	60.8	48.6	56.8	55.8	61.4	55.1
CDAN [21]	50.9	61.6	54.8	59.4	68.5	55.5	70.4	66.9	57.7	64.2	59.1	64.3	61.1
SAFN [29]	50.0	58.7	52.4	56.3	<u>73.7</u>	53.5	55.8	64.8	48.5	60.7	59.5	64.3	58.2
RSDA [9]	45.5	56.6	46.6	45.7	60.4	48.6	54.6	61.5	50.9	56.1	54.0	58.6	53.4
PAN [28]	<u>58.8</u>	65.2	54.6	57.5	70.5	53.1	67.6	66.7	55.9	64.4	60.2	66.6	61.8
MemSAC [15]	53.6	<u>66.5</u>	<u>58.8</u>	<u>63.2</u>	71.2	<u>58.1</u>	<u>73.2</u>	<u>70.5</u>	<u>61.5</u>	<u>68.8</u>	<u>64.1</u>	<u>67.6</u>	<u>64.8</u>
SPA (Ours)	73.5	84.0	70.6	76.5	85.9	71.9	76.6	77.0	69.8	78.3	76.8	83.9	77.1

Table 3: Classification Accuracy (%) on DomainNet126 for 1-shot and 3-shot semi-supervised domain adaptation, using ResNet34 as backbone. The best accuracy is indicated in **bold** and the second best one is underlined.

Method	C→S		P→C		P→R		R→C		R→P		R→S		S→P		Avg.	
	1-	3-	1-	3-	1-	3-	1-	3-	1-	3-	1-	3-	1-	3-	1-	3-
<i>S + T</i> [10]	54.8	57.9	59.2	63.0	73.7	75.6	61.2	63.9	64.5	66.3	52.0	56.0	60.4	62.2	60.8	63.6
DANN [7]	52.8	55.4	70.3	72.2	56.3	59.6	58.2	59.8	61.4	62.8	52.2	54.9	57.4	59.9	58.4	60.7
ENT [8]	54.6	60.0	65.4	71.1	75.0	78.6	65.2	71.0	65.9	69.2	52.1	61.1	59.7	62.1	62.6	67.6
MME [25]	56.3	61.8	69.0	71.7	76.1	78.5	70.0	72.2	67.7	69.7	61.0	61.9	64.8	66.8	66.4	68.9
APE [16]	56.7	63.1	72.9	76.7	76.6	79.4	70.4	76.6	70.8	72.1	63.0	<u>67.8</u>	64.5	66.1	67.6	71.7
BiAT [13]	57.9	61.5	71.6	74.6	77.0	78.6	73.0	74.9	68.0	68.8	58.5	62.1	63.9	67.5	67.1	69.7
MixMatch [11]	59.3	62.7	66.7	68.7	74.8	78.8	69.4	72.6	67.8	68.8	62.5	65.6	66.3	67.1	66.7	69.2
NPL [17]	62.5	64.5	67.6	70.7	78.3	79.3	70.9	72.9	69.2	70.7	62.0	64.8	67.0	68.6	68.2	70.2
BNM [4]	58.4	62.6	69.4	72.7	77.0	79.5	69.8	73.7	69.8	71.2	61.4	65.1	64.1	67.6	67.1	70.3
MCC [14]	56.8	60.5	62.8	66.5	75.3	76.5	65.5	67.2	66.9	68.1	57.6	59.8	63.4	65.0	64.0	66.2
ATDOC [20]	<u>65.6</u>	<u>66.7</u>	72.8	74.2	81.2	<u>81.2</u>	<u>74.9</u>	<u>76.9</u>	71.3	<u>72.5</u>	65.2	64.6	<u>68.7</u>	<u>70.8</u>	<u>71.4</u>	<u>72.4</u>
AESL [23]	59.5	65.2	<u>74.6</u>	76.2	72.4	74.1	74.8	77.3	79.4	80.5	66.2	69.5	66.6	69.6	70.5	73.2
SPA (Ours)	65.9	67.0	74.8	<u>76.5</u>	<u>81.1</u>	82.3	75.3	76.0	<u>71.8</u>	72.2	<u>65.8</u>	67.2	69.8	71.1	72.1	73.2

Table 4: Classification Accuracy (%) on OfficeHome for 1-shot and 3-shot semi-supervised domain adaptation, using ResNet34 as backbone. The best accuracy is indicated in **bold** and the second best one is underlined.

Method (1-shot)	A→C	A→P	A→R	C→A	C→P	C→R	P→A	P→C	P→R	R→A	R→C	R→P	Avg.
<i>S + T</i> [10]	52.1	78.6	66.2	74.4	48.3	57.2	69.8	50.9	73.8	70.0	56.3	68.1	63.8
DANN [7]	53.1	74.8	64.5	68.4	51.9	55.7	67.9	52.3	73.9	69.2	54.1	66.8	62.7
ENT [8]	53.6	81.9	70.4	79.9	51.9	63.0	75.0	52.9	76.7	73.2	63.2	73.6	67.9
MME [25]	<u>61.9</u>	<u>82.8</u>	71.2	79.2	57.4	<u>64.7</u>	75.5	<u>59.6</u>	77.8	<u>74.8</u>	65.7	74.5	70.4
APE [16]	60.7	81.6	<u>72.5</u>	<u>78.6</u>	58.3	63.6	76.1	53.9	75.2	<u>72.3</u>	63.6	69.8	68.9
CDAC [18]	<u>61.9</u>	83.1	<u>72.7</u>	80.0	<u>59.3</u>	64.6	<u>75.9</u>	61.2	<u>78.5</u>	75.3	64.5	<u>75.1</u>	<u>71.0</u>
SPA (Ours)	62.3	76.7	79.0	66.6	77.3	76.4	65.7	59.1	80.7	71.4	<u>65.2</u>	84.1	72.0
Method (3-shot)	A→C	A→P	A→R	C→A	C→P	C→R	P→A	P→C	P→R	R→A	R→C	R→P	Avg.
<i>S + T</i> [10]	55.7	80.8	67.8	73.1	53.8	63.5	73.1	54.0	74.2	68.3	57.6	72.3	66.2
DANN [7]	57.3	75.5	65.2	69.2	51.8	56.6	68.3	54.7	73.8	67.1	55.1	67.5	63.5
ENT [8]	62.6	<u>85.7</u>	70.2	79.9	60.5	63.9	79.5	61.3	79.1	76.4	64.7	79.1	71.9
MME [25]	64.6	85.5	71.3	80.1	64.6	65.5	79.0	63.6	79.7	<u>76.6</u>	<u>67.2</u>	79.3	73.1
APE [16]	<u>66.4</u>	86.2	<u>73.4</u>	82.0	65.2	66.1	81.1	63.9	80.2	76.8	66.6	79.9	74.0
CDAC [18]	67.8	85.6	<u>72.2</u>	<u>81.9</u>	<u>67.0</u>	<u>67.5</u>	<u>80.3</u>	65.9	<u>80.6</u>	80.2	67.4	<u>81.4</u>	<u>74.2</u>
SPA (Ours)	63.1	81.0	80.2	68.5	81.7	77.5	69.5	<u>65.2</u>	82.0	73.9	<u>67.2</u>	87.0	74.7

54 B.2 Semi-supervised Domain Adaptation

55 We also extend our SPA model to semi-supervised domain adaptation (SSDA) scenario and conduct
 56 experiments on 1-shot and 3-shot setting, and *S + T* in SSDA task means the model trained only by
 57 the labeled source and target data.

58 We present the classification accuracy results on DomainNet126 and OfficeHome datasets for SSDA
 59 scenario in the Table 3 and Table 4 respectively. Looking at the details, Table 3 shows the classification
 60 results for 1-shot and 3-shot SSDA setting on DomainNet126 dataset. For the 1-shot setting, our SPA
 61 model can improve DANN [7] by 13.7 % and ENT [8] by 9.5 %. our SPA consistently ranks top
 62 among 4 out of 7 tasks and ranks top 2 among all tasks, achieving the best accuracy of 72.1 %, which
 63 is better 1.6 % than the second one. For the 3-shot setting, our SPA model can improve DANN [7] by
 64 12.5 % and ENT [8] by 5.6 %. SPA achieves the best accuracy of 73.2 %, comparable with recent
 65 work AESL [23].

66 Furthermore, Table 4 shows the classification results for 1-shot and 3-shot SSDA setting on Office-
 67 Home dataset. To verify that our SPA model can also generalize to SSDA scenario, we compare SPA
 68 with several classic and recent baselines. The first section of the table shows our SPA model can
 69 improve DANN [7] by 9.3 % and ENT [8] by 4.1 % in the 1-shot setting. The second section shows
 70 our SPA model can improve DANN [7] by 11.2 % and ENT [8] by 2.8 % in the 3-shot setting. This
 71 shows that our SPA model can greatly improve the classic baselines and achieve comparable results
 72 with CDAC [18].

73 B.3 Model Analysis

74 **Robustness Analysis.** In the main paper, we have already verified the robustness of SPA to different
 75 graph structures on OfficeHome dataset. In the appendix, we further show the experimental results
 76 on Office31 dataset in Table 5. Similarly, we conduct experiments on different types of Laplacian
 77 matrix, similarity metric of graph relations, and k number of nearest neighbors of KNN classification
 78 methods. The Laplacian matrices are chosen from the random walk laplacian matrix $\mathbf{L}_{rwk} = \mathbf{D}^{-1}\mathbf{A}$,
 79 and the symmetrically normalized Laplacian matrix $\mathbf{L}_{sym} = \mathbf{I} - \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$, where \mathbf{D} denotes
 80 the degree matrix based on the adjacency matrix \mathbf{A} . In addition, the similarity metrics are chosen from
 81 cosine similarity and Gaussian similarity, and different $k = 3, 5$ when applying KNN classification
 82 algorithm. From Table 5, We can find that different types of Laplacian matrix still lead to comparable
 83 results. As for the similarity metric, the Gaussian similarity brings better performance than cosine
 84 similarity. On Office31 dataset, 5-NN graphs is superior than 3-NN graphs when combining with
 85 \mathbf{L}_{rwk} , and comparable when combining with \mathbf{L}_{sym} . For all these aforementioned experiments results,
 86 the differences between them are within 1% around, confirming the robustness of SPA.

Table 5: Classification Accuracy (%) on OfficeHome for unsupervised domain adaptation. The table is divided into three sections corresponding to robustness analysis, and parameter sensitivity, each separated by a double horizontal line.

Method	A→D	A→W	D→A	D→W	W→A	W→D	Avg.
$\beta = 0.1$	94.2	95.1	76.6	98.9	78.6	99.6	90.5
$\beta = 0.3$	94.0	96.2	76.9	98.9	79.3	99.8	90.8
$\beta = 0.5$	94.0	96.4	77.9	99.0	78.0	99.8	90.8
$\beta = 0.7$	94.4	96.0	79.0	98.6	80.3	100.	91.4
$\beta = 0.8$	94.2	95.7	76.1	98.6	78.3	99.8	90.5
<hr/>							
L_{rwk} w/ <i>cos</i>	93.8	95.0	76.3	98.6	79.7	100.	90.6
L_{rwk} w/ <i>gauss</i>	95.0	95.6	78.2	98.6	80.0	99.8	91.2
L_{sym} w/ <i>cos</i>	93.8	93.8	78.5	98.6	79.9	100.	90.8
L_{sym} w/ <i>gauss</i>	93.8	95.6	79.4	98.6	78.8	99.8	91.0
<hr/>							
L_{rwk} w/ $k = 3$	93.8	95.2	78.3	98.9	80.4	99.8	91.1
L_{rwk} w/ $k = 5$	93.8	95.0	76.3	98.6	79.7	100.	90.6
L_{sym} w/ $k = 3$	94.0	95.8	75.2	99.0	80.5	100.	90.7
L_{sym} w/ $k = 5$	93.8	93.8	78.5	98.6	79.9	100.	90.8

87 **Parameter Sensitivity.** In the main paper, we have already analyzed the experiments on the
88 hyperparameter β of exponential moving averaging strategy for memory updates and verify that SPA
89 is insensitive to this hyperparameter. Here, we show the experimental results on Office31 dataset in
90 Table 5. Similarly, we design experiments on the hyperparameter β of exponential moving averaging
91 strategy for memory updates, choosing $\beta = 0.1, 0.3, 0.5, 0.7, 0.9$ respectively. These results are based
92 on DANN [7]. From the series of results, we can find that in Office31 dataset, the choice of $\beta = 0.7$
93 outperforms than others. In addition, the differences between these results are within 1.0%, which
94 means that SPA is relatively stable to this hyperparameter.

95 Furthermore, we design experiments for the coefficient of \mathcal{L}_{nas} and the coefficient of \mathcal{L}_{gsa} to analyze
96 the stability of SPA. The experimental results are shown in the Figure 2. These results are based
97 on DANN [7]. Fixing the coefficient of $\mathcal{L}_{nas} = 0.2$, the coefficient of \mathcal{L}_{gsa} changes from 0.1 to 0.9.
98 Fixing the coefficient of $\mathcal{L}_{gsa} = 1.0$, the coefficient of \mathcal{L}_{nas} changes from 0.1 to 0.9. From the series
99 of results, we can find that in OfficeHome dataset, the choice of different coefficients result in similar
100 results, which means that SPA is insensitive to these coefficients.

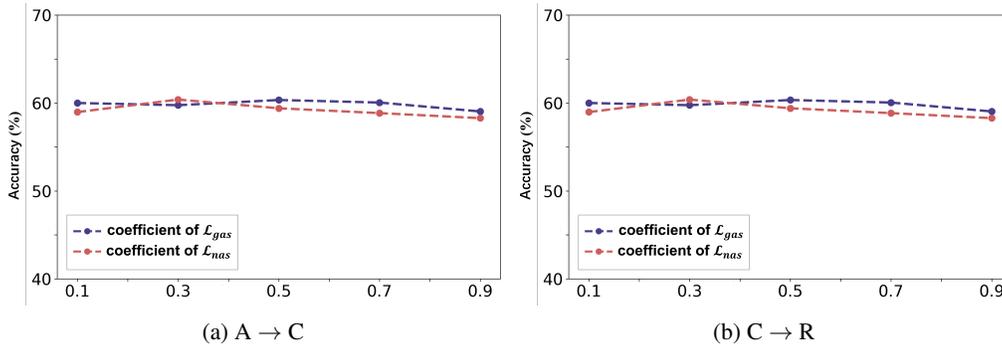


Figure 1: Parameter Sensitivity. The line plot of the coefficient of \mathcal{L}_{nas} and the coefficient of \mathcal{L}_{gsa} change from 0.1 to 0.9, leading to different accuracy results. The experiments are conducted on OfficeHome dataset, where (a) is A → C setting and (b) is C → R setting.

101 **Transferability and Discriminability.** The \mathcal{A} -distance [27] measures the distribution discrepancy
102 that is defined as $d_{\mathcal{A}} = 2(1 - 2\epsilon)$, where ϵ is the classifier loss to discriminate the source and target
103 domains. Smaller \mathcal{A} -distance indicates better domain-invariant features. Figure 2a shows that SPA
104 can achieve a lower $d_{\mathcal{A}}$, implying a lower generalization error. Furthermore, following previous work
105 [3], we further offer the source accuracy and target accuracy specifically, in Figure 2b and Figure 2c.
106 We can find that various methods achieve similar results of source accuracy, and SPA can always
107 achieve higher target accuracy. Combined with the experimental results in Figure 2a, this reveals that
108 SPA enhances transferability while still keep a strong discriminability. Back to our Introduction, this

109 means that SPA can find a more suitable utilization of intra-domain information and inter-domain
 110 information to properly align target samples.

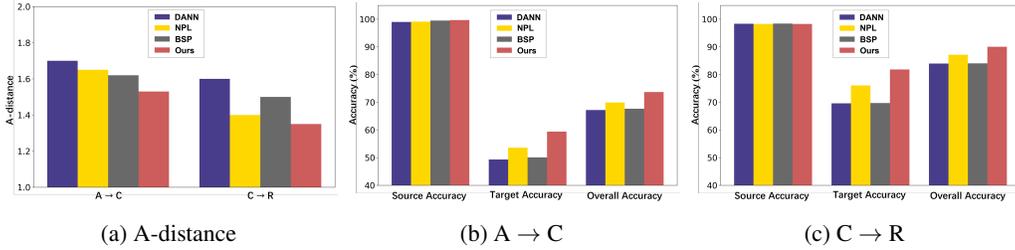


Figure 2: Transferability and Discriminability. We compare SPA with DANN [7], BSP [3] and NPL [17] on OfficeHome dataset, where (a) is \mathcal{A} -distance in $A \rightarrow C$ and $C \rightarrow R$ setting, (b) is accuracy results in $A \rightarrow C$ setting and (c) is accuracy results in $C \rightarrow R$ setting.

111 **Feature Visualization.** To demonstrate the learning ability of SPA, we visualize the features of
 112 DANN [7], BSP [4], NPL [17] and SPA with the t-SNE embedding [6] under the $C \rightarrow R$ setting
 113 of OfficeHome Dataset in the main paper, referred as Figure 6. In the appendix, we offer more
 114 visualization figures, including Figure 3 in $A \rightarrow D$ setting and Figure 4 in $A \rightarrow W$ setting on
 115 Office31 dataset, Figure 5 in $A \rightarrow C$ setting on OfficeHome dataset. According to all the figures, the
 116 observations are consistent that the source features and target features learned by SPA are transferred
 117 better. These observations imply the superiority of SPA over discriminability and transferability in
 118 unsupervised domain adaptation scenario.

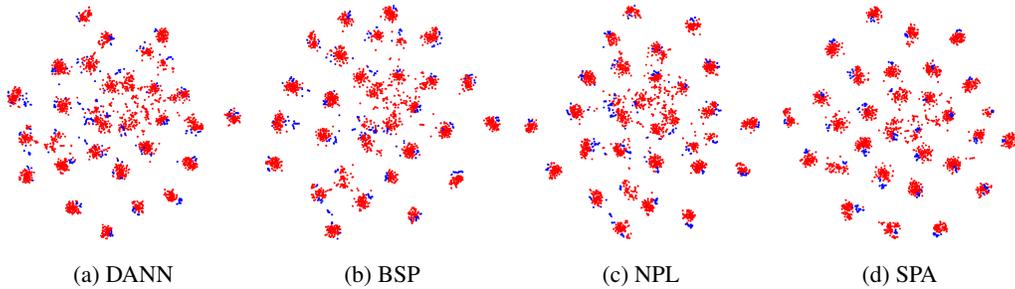


Figure 3: Feature Visualization. the t-SNE plot of DANN [7], BSP [4], NPL [17], and SPA features on office31 dataset in the $A \rightarrow D$ setting. We use red markers for source domain features and blue markers for target domain features.

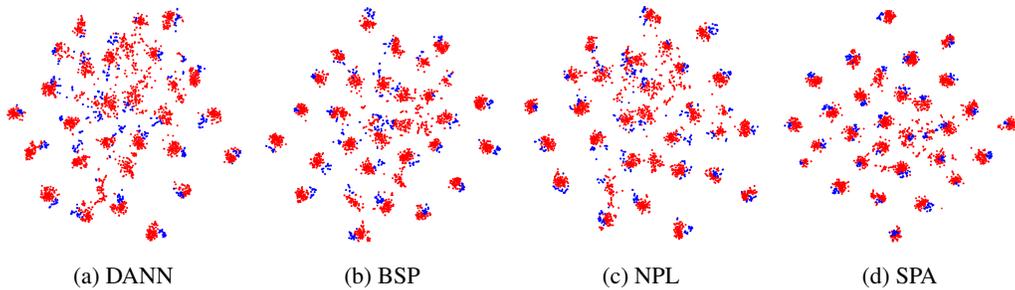


Figure 4: Feature Visualization. the t-SNE plot of DANN [7], BSP [4], NPL [17], and SPA features on Office31 dataset in the $A \rightarrow W$ setting. We use red markers for source domain features and blue markers for target domain features.

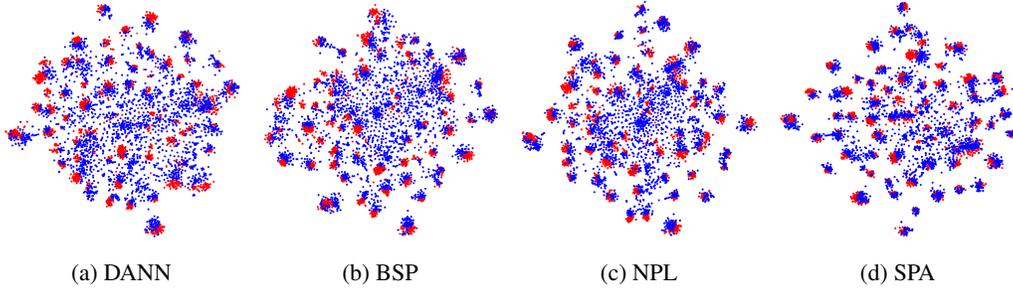


Figure 5: Feature Visualization. the t-SNE plot of DANN [7], BSP [4], NPL [17], and SPA features on OfficeHome dataset in the $A \rightarrow C$ setting. We use red markers for source domain features and blue markers for target domain features.

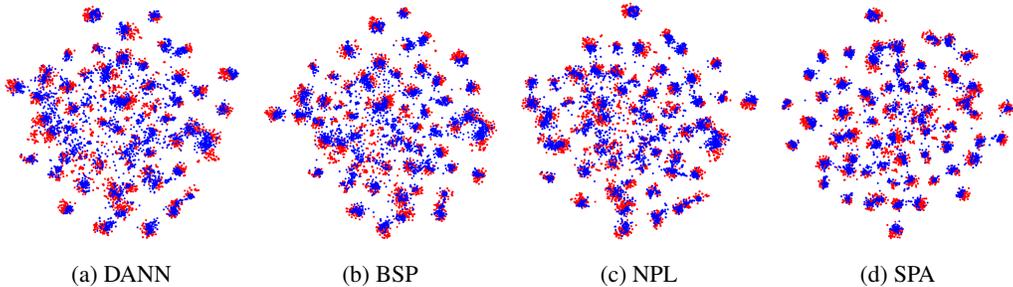


Figure 6: Feature Visualization. the t-SNE plot of DANN [7], BSP [4], NPL [17], and SPA features on OfficeHome dataset in the $C \rightarrow R$ setting. We use red markers for source domain features and blue markers for target domain features.

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