Figure 1: Model performance across different return ranges for the Walker2D-medium-replay task.
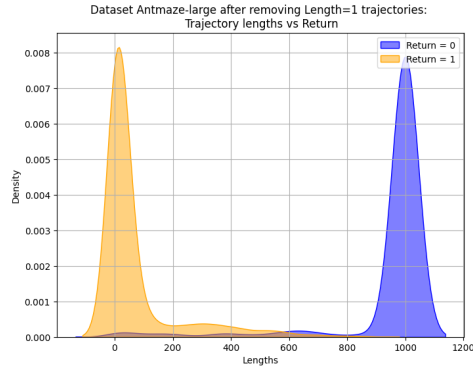

Figure 2: Trajectory length and return distribution in dataset Antmaze-large-diverse after removing length=1 trajectories
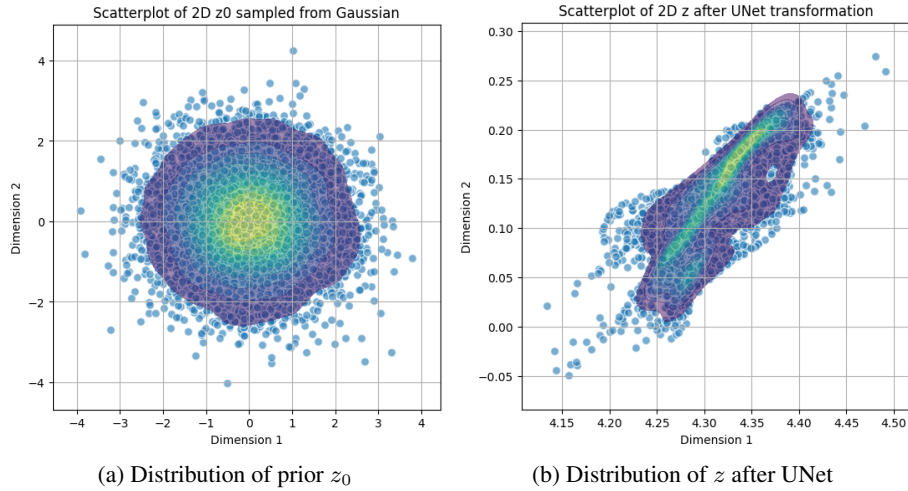

(a) Distribution of prior z_0

(b) Distribution of z after UNet

Figure 3: Distribution of the prior z_0 and the distribution of $z =$UNet(z_0) in a toy 2D example