

Figure 1: Visualization of Skill Retriever on the LIBERO-goal Scenario. Left: T-SNE visualization of the state space of the existing dataset for each stage. Middle: Visualization of the stages where skills retrieved by the Skill Retriever, after all CiL stages of learning. Right: Map showing the stages of each dataset and the retrieved skills. This demonstrates that the Skill Retriever can find skills capable of handling the given state, even in the LIBERO scenario. Additionally, in task-specific parts (a), it accurately retrieves the skills, and in parts showing similar behaviors (b), it shares skills.



Figure 2: Revised Figure 1. We have improved the illustration to make it more intuitive.



Figure 3: Evolving Kitchen-*complete* and Evolving Kitchen-*incomplete* training curves represent the cumulative task success rate up to a given stage. The success rate is scaled such that achieving success in all tasks by the final stage is represented as 100. This result corresponds to the data presented in Table 1 of our paper.