

Supplementary Material for ‘A Bilingual, Open World Video Text Dataset and End-to-end Video Text Spotter with Transformer’

A Appendix

A.1 Data Distribution for BOVText

The data distribution for 32 open scenarios. We present the 31 open scenarios and an "Unknown" scenarios distribution on BOVText in three levels, *i.e.*, video, video frames, and text instances, as shown in Figure. 1 and Table 1. BOVText spans various video domains with these scenarios in the existing datasets (*e.g.*, Driving for RoadText-1k [20], Vlog(supermarket, shopping street, indoor), Travel(hotel, railway station) for LSVTD [3]) and more open domains that are not yet supported (*e.g.*, Game(PUBG mobile, Honor of Kings...), Sport(NBA, world cup...), News). We expect that the open-world scenarios can provide a comprehensive effectiveness evaluation for advanced video text models in different scenarios.

Scenarios	Video	Video Frames	Text Instances	Scenarios	Video	Video Frames	Text Instances
Cartoon	67(3.2%)	64,359(3.6%)	123,191(2.1%)	Sport	71(4.8%)	54,643(3.1%)	266,996(4.6%)
Vlog	90(4.2%)	83,891(4.7%)	214,910(3.7%)	News Report	100(4.1%)	66,207(3.7%)	178,000(3.1%)
Driving	71(3.8%)	61,626(3.5%)	151,994(2.6%)	Celebrity	50(2.4%)	39,958(2.3%)	121,235(2.1%)
Advertising	32(1.7%)	28,645(1.6%)	91,090(1.0%)	Technology	68(3.1%)	53,305(3.1%)	140,172(2.4%)
Activity	35(1.6%)	26,837(1.4%)	67,879(1.2%)	Program	42(2.3%)	38,108(2.2%)	214,561(3.7%)
Comedy	88(4.5%)	79,206(4.5%)	317,865(5.5%)	Game	21(1.0%)	33,925(1.9%)	84,106(1.5%)
Interview	37(1.3%)	31,440(1.8%)	63,616(1.1%)	Livestreaming	64(3.1%)	62,130(3.6%)	211,569(3.6%)
Government	66(2.5%)	45,457(2.6%)	93,874(1.6%)	Speech	69(3.2%)	56,646(3.1%)	175,119(3.0%)
Travel	74(4.3%)	71,291(4.1%)	280,446(4.8%)	Movie	106(5.6%)	108,110(6.3%)	299,760(5.2%)
Campus	52(2.3%)	43,469(2.5%)	139,760(2.4%)	Photograph	70(2.8%)	64,025(3.6%)	173,832(3.0%)
International	55(3.1%)	52,774(3.6%)	132,117(2.3%)	Education	74(3.4%)	59,824(3.6%)	360,774(6.2%)
Short Video	70(4.4%)	59,756(3.4%)	326,930(5.6%)	Dance	43(1.9%)	27,941(1.6%)	71,740(1.2%)
Makeup	63(3.1%)	54,643(3.1%)	111,814(1.9%)	Fishery	81(4.5%)	75,018(4.3%)	230,085(4.0%)
Talent	86(4.1%)	71,024(4.1%)	339,382(5.9%)	Fashion	63(3.0%)	46,337(2.6%)	98,942(1.7%)
Beauty Industry	40(1.9%)	41,350(2.4%)	132,025(2.3%)	Introduction	64(3.8%)	59,048(3.4%)	236,721(4.1%)
Eating	56(2.7%)	62,893(3.6%)	191,035(3.3%)	Unknown	53(2.5%)	33,712(1.9%)	150,721(2.6%)

Table 1: **The Data Distribution for 32 Open Scenarios.** In green refers to these scenarios only supported by BOVText. "%" denotes the percentage of each scenario data for whole data.

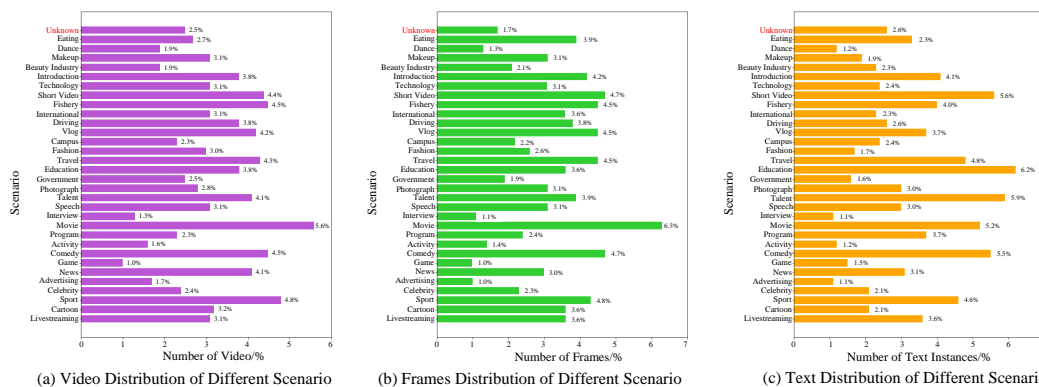


Figure 1: **The Data Distribution for 32 Open Scenarios.** (a) Video distribution for different scenarios. (b) Video frames distribution for different scenarios. (c) Text instance distribution for different scenarios.

	Languages			Text Category			
	English	Chinese	Alphanumeric	Caption Text	Scene Text	Title	Others
Video	842(45%)	1521(82%)	1023(55%)	1523(82%)	1336(72%)	222(12%)	148(8%)
Video Frames	671,462(40%)	1,449,824(86%)	775,021(46%)	1,327,382(79%)	930,359(55%)	167,011(10%)	116,914(7%)
Text Instances	2,785,643(38%)	5,308,766(72%)	3,150,256(43%)	3,296,101(39%)	3,981,574(52%)	291,690(4%)	364,613(5%)

Table 2: **Statistics of text language and category in BOVText.** In green refers to these text category only supported by BOVText. "%" denotes the percentage of each scenario data for whole data.

The data distribution for multilingual text and text categories. As shown in Figure. 2, BOVText provides two language text annotation and for text categories annotation (*i.e.*, caption, title, scene text, or others). BOVText, as the first benchmark for support various text categories annotation, can provide a novel perspective and in favor of other video-and-language tasks, more details in A.6 Link to Other Video-and-Language tasks and video understanding demo video in the supplementary material. Besides, BOVText, as the first large-scale, multilingual video text benchmark dataset, can promote video text multilingual spotting in the community.

A.2 BOVText Metrics

The proposed BOVText includes four tasks: (1) Video Text Detection; (2) Video Text Recognition; (3) Video Text Tracking. (4) End to End Text Spotting in Videos. *MOTP* (Multiple Object Tracking Precision) [1], *MOTA* (Multiple Object Tracking Accuracy) and *IDF₁* [5, 21] as the three important metrics are used to evaluate task3 (text tracking) and task4 (text spotting) for BOVText. Following the previous works [9, 20], BOVText evaluates text tracking methods in video and compare their performance with the MOTA and MOTP, which are given by:

$$MOTP = \frac{\sum_{i,t}(1 - d_t^i)}{\sum_t c_t}, \quad (1)$$

where c_t denotes the number of matches found for time t . For each of these matches, calculate the iou d_t^i between the object o^i and its corresponding hypothesis. It shows the ability of the tracker to estimate precise object positions. MOTA is calculated as follows:

$$MOTA = 1 - \frac{\sum_t(m_t + fp_t + mme_t)}{\sum_t g_t}, \quad (2)$$

where m_t , fp_t and mme_t are the number of misses, false positives, and mismatches, respectively. g_t is the number of objects present at time t . It shows the tracker’s performance at detecting objects and keeping their trajectories, independent of the precision of the location. *ID_{F1}* is the ratio of correctly identified detections over the average number of ground-truth and computed detections. And the metric is more reasonable to evaluate ID switches in some cases. We evaluate the metrics in BOVText by:

$$ID_{tp} = \sum_h \sum_t m(h, o, \Delta_t, \Delta_s), \quad (3)$$

$$ID_{F1} = \frac{2ID_{tp}}{2ID_{tp} + ID_{fp} + ID_{fn}}, \quad (4)$$

where ID_{tp} , ID_{fp} and ID_{fn} refer to true positive, false positive and false negative of matching ID. Besides, the ID metric [5] also includes *MT* (Mostly Tracked) Number of objects tracked for at least 80 percent of lifespan, *ML* (Mostly Lost) Number of objects tracked less than 20 percent of lifespan. Δ_t and Δ_s refer to time matching and space location matching, respectively.

For Task4 (End to End Text Spotting in Videos), the objective of this task is to recognize words in the video as well as localize them in terms of time and space. We use *ID_{F1}* to evaluate our BOVText, which focuses on text instance ID tracking and recognition results that be required by many downstream tasks. More specifically,

$$ID_{tp} = \sum_h \sum_t m(h, o, \Delta_t, \Delta_s, \Delta_r), \quad (5)$$

$$ID_{F1} = \frac{2TID_{tp}}{2TID_{tp} + TID_{fp} + TID_{fn}}, \quad (6)$$

where Δ_t , Δ_s and Δ_r refer to ID matching, space location matching and recognition result matching. h and o denote hypothesis set (*e.g.*, predicted ID I_p , box locations L_p , recognition results R_p) and

Method	Text Detection on ICDAR2015/%			Text Tracking on ICDAR2015(video)/%		
	Precision	Recall	F-score	ID _{F1} /%	MOTA	MOTP
Ours,w/o angle prediction	73.5	65.1	68.5	36.1	16.4	68.7
Ours,w/ angle prediction(L1 loss)	84.2	82.3	83.2	54.7	43.2	74.5
Ours,w/ angle prediction(cosine loss)	86.8	81.7	84.2(+15.7)	57.3(+21.2)	44.1(+27.7)	75.8(+7.1)

Table 3: **Ablation study for angle prediction.** The gaps of at least (+7.1%) improvement after using angle prediction are shown in green.

Query	Text Tracking on ICDAR2015(video)/%			ShortSide	Text Tracking on ICDAR2015(video)/%			
	ID _{F1} /%	MOTA	MOTP		ID _{F1} /%	MOTA	MOTP	FPS
Obejct query	54.2	40.5	76.6	480	52.6	41.5	74.5	16
Obejct + tracking query	57.3	44.1	75.8	640	56.7	43.8	74.5	13
-	-	-	-	800	57.3	44.1	75.8	9

Table 4: **Ablation study for input query and input image size.** Tracking query bring huge improvement with 3.1% ID_{F1}.

ground truth set with (ID I_g , box locations L_g , recognition ground true R_g). And the three matching can be obtained by:

$$\Delta_t : I_p = I_g, \quad \Delta_s : IoU(L_p, L_g) > 0, \quad \Delta_r : R_p = R_g. \quad (7)$$

The match of h and o is a true positives of text ID (i.e., ID_{tp}) when these conditions (i.e., Δ_t , Δ_s and Δ_r are met. Similarly, false positive (i.e., ID_{fp}) and false negative (i.e., ID_{fn}) of text ID can be obtained for ID_{F1} calculation.

A.3 More details for experiments

TransVTSpotter. All experiments are conducted on Tesla V100 GPU. We train the model for 150 epochs and the learning rate drops by a factor of 10 at the 100th epoch.

Baselines concerning the existing methods. Video-based text spotting methods are rare and lack open-source algorithms. Therefore, we adopt various mature image-based techniques to compare and evaluate the efficiency of BOVText. **Detection.** EAST [32] as one of the popular regression-based methods is used to test our BOVText. The method adopts FCNs to predict shrinkable text score maps, rotation angles. For segmentation based methods, we adopt PSENet [27] and DB [13] to evaluate our BOVText. PSENet [27] generates various scales of shrunked text segmentation maps, then gradually expands kernels to generate the final text instance. **Recognition.** Recent methods mainly include two techniques, Connectionist Temporal Classification (CTC) and attention mechanism. In CTC-based methods, CRNN [22] as the representation, which introduced CTC decoder into scene text recognition with BiLSTM to model the feature sequence. In Attention-based methods, RARE [23] normalizes the input text image using the Spatial Transformer Network (STN [7]). Then, it estimates the output character sequence from the identified features with the attention module. **Text Tracking Trajectory Generation.** With text detection and recognition in a static image, we only obtain text localization and recognition information without temporal information, which are insufficient for video spotting evaluation (e.g., ID_{F1} , $MOTA$ and $MOTP$). Following the work [28], we link and match text objects in the current frame and several frames by IOU and edit the distance of text. All of the experiments use the same strategy: (1) Training detector and recognizer with BOVText. (2) Matching text objects with corresponding text tracking trajectory id.

A.4 Ablation study for TransVTSpotter

Angle Prediction. The angle prediction and corresponding loss are the main contributions for TransVTSpotter. As shown in Table 3, we conduct three experiments to test the effectiveness of the angle prediction and corresponding cosine loss. Without using angle prediction, model with upright-bounding box(two points) results show a dissatisfactory performance(i.e., 68.5% f-score for detection and 36.1% ID_{F1} for tracking). Compared with using angle prediction, there is around 20% performance gap. Besides, using cosine loss present a better performance than the counterpart of L1 loss(84.2% v.s 83.2% for text detection F-score)

Tracking Query Tracking query is important for our framework, which uses the knowledge of previously detected objects to obtain a set of tracking boxes. As shown in Table 4, for only object

Method	ICDAR2015(video,T)/%			ICDAR2015(video,S)/%			Minetto [17](video,T)/%			YVT [19](video,T)/%		
	MOTA	MOTP	ID _{F1}	MOTA	MOTP	ID _{F1}	MOTA	MOTP	ID _{F1}	MOTA	MOTP	ID _{F1}
USTB_TexVideo [8]	7.4	70.7	25.9	15.6	68.5	28.2	-	-	-	-	-	-
StradVision-1 [8]	7.9	70.2	25.8	8.9	70.2	31.9	-	-	-	-	-	-
USTB_TexVideo II-2 [8]	12.3	71.8	21.9	13.2	66.6	21.3	-	-	-	-	-	-
AJOU [8, 10]	16.4	72.7	36.1	-	-	-	-	-	-	-	-	-
AGD with AGD [31]	-	-	-	-	-	-	75.6	74.7	-	-	-	-
AGD with EAGD [31]	-	-	-	-	-	-	81.3	75.7	-	-	-	-
Wei <i>et al.</i> [6]	-	-	-	-	-	-	83.5	76.8	-	-	-	-
Free [4]	43.2	76.8	57.9	52.9	74.8	61.8	-	-	-	54.0	78.0	-
TransVTSpotter(ours)	44.1	75.8	57.3	53.2	74.9	61.5	84.1	77.6	74.7	53.9	75.9	64.5

Table 5: **Experiments for TransVTSpotter on ICDAR2015(video), Minetto and YVT.** ‘D’, ‘R’, ‘T’ and ‘S’ denotes the Detection, Recognition, Tracking, Spotting, respectively. ‘video’ or ‘image’ denote the image or video level dataset.

query, with only learned object query is input as decoder query, and associating the generated detection to track. This solution achieves a not bad performance by 54.2 ID_{F1}. But, with tracking query, the performance present further improvement(3.1% ID_{F1})

Accuracy vs. Speed We analyze the inference speed of TransVTSpotter. The time cost is measured using a single Tesla V100 GPU. Table 4 shows the effect of input image size. With input image size increasing, the model present a better ID_{F1} performance from 52.6 to 67.3. When the short-side of the input image is by 800 pixels, the speech and performance all present relatively satisfactory results, so we set it as the default setting in the experiment.

A.5 Comparison with State-of-The-Arts for TransVTSpotter

As shown in Table 5, we evaluate TransSpotter on ICDAR2015(video) [33], Minetto(video) [17] and YVT(video) [19] for tracking and video text spotting task. Minetto consists of 5 videos in outdoor scenes. The frame size is 640 x 480 and all videos are used for test when the model training on ICDAR2015(video). Our TransVTSpotter obtains 44.1% and 84.1% for tracking task(MOTA) on ICDAR2015(video) and Minetto, at least 0.6% improvement than the previous models.

A.6 Link to Other Video-and-Language Applications

In this section, we show that the practicability of the proposed BOVText, not a toy benchmark, which can promote other video-and-text application research.

Text spotting in static images has numerous application scenarios: (1) Automatic data entry. SF-Express¹ utilizes OCR techniques to accelerate the data entry process. NEBO² performs instant transcription as the user writes down notes. (2) Autonomous vehicle [16, 15]. Text-embedded panels carry important information, *e.g.*, geo-location, current traffic condition, navigation, and etc. (3) Text-based reading comprehension. TextCaps [24] and text-based VQA [25, 2] show the new vision-and-language tasks, which need to recognize text, relate it to its visual context, semantic, and visual reasoning between multiple text tokens and visual entities, such as objects. Similarly, there are many application demands for video text understanding across various industries and in our daily lives. We list the most outstanding ones that significantly impact, improving our productivity and life quality. **Firstly**, automatically describing video with natural language [30, 29] can bridge video and language. **Secondly**, video text automatic translation³ can be extremely helpful as people travel, and help video-sharing websites⁴ to cut down language barriers. **Finally**, text-based video retrieval [11, 14] is an irreplaceable business for many companies, such as Google and YouTube. More details and analyses for application scenarios concerning BOVText in the supplementary material.

Video Understanding. As shown in Figure. 2 (a), the example concerning the task of describing video with natural language is from MSR-VTT [30], and there has been increasing interest in video understanding [29, 12]. However, video description with only visual information is difficult and limited, even for a human. For the annotation of the sample video, *i.e.*, "A man in a blue suit

¹<https://www.sf-express.com/cn/sc/>

²<https://www.myscript.com/nebo/>

³<https://translate.google.com/intl/en/about/>

⁴<https://www.youtube.com/>



Figure 2: **The Real Application Tasks Link to BOVText.** (a) Video Understanding, automatically describing visual content with natural language. (b) Video Caption Translation, extremely helpful for people who travel abroad and video-sharing websites such as YouTube. (c) Video Retrieval, accurate semantic information for text in videos can promote video retrieval.

and purple tie discusses millennial investing fear", we can not learn the information of "millennial investing fear" from the visual information in the video. By comparison, caption and scene texts in the video contain accurate information of "millennial investing fear", which can help the model to describe the video better. We argue that the same as general human understanding, videos without captions and audio, is difficult to be properly understood by the model. We hope the release of BOVText can promote efficient video text reading, further enhancing automatic video description.

Video Text Automatic Translation. Another practical application is video text automatic translation, as shown in Figure. 2 (b). The application may be unnecessary for several professional teams or classic movies due to the professional translator or huge cost investment. But for international video-sharing websites^{5 6} with millions of users, it isn't easy to apply multilingual caption and scene text in billions of videos. Therefore, efficient translation concerning caption text (e.g., overlap, song title, logos) and scene text (e.g., street signs, business signs, words on shirt) still need further exploration and research. The large-scale and multilingual BOVText contributes various real scenarios for the development of video text automatic translation.

Video Retrieval. Video retrieval with textual cues [18, 26] is also a very important application direction for video-and-text research, as shown in Figure. 2 (c). To the best of my knowledge, video retrieval with text information in the video is still almost a blank field of study and immature application in the industry. The most existing video retrieval methods are stiff combinations of text detection and recognition, invalid for the example with a sentence query. Besides, similar to video understanding, for the query of the sample video, i.e., "The lakers play host to Golden State", we

⁵<https://www.youtube.com/>

⁶<https://www.kuaishou.com/en>

can not obtain the correct related video without scene text or caption information. The missing information needs to recover by understanding the video with key video text information such as "GOLDEN STATE WARRIORS, LOS ANGELES LAKERS". The proposed BOVText with various text types (e.g., caption, song title, logos, street signs, business signs) and annotation can promote the research concerning efficient video retrieval.

A.6.1 Limitations

Although the proposed BOVText supports all video text spotting tasks, *i.e.*, *text detection, recognition, tracking end to end video text spotting*, the potential contributions for other tasks still need mining. For example, as shown in Figure. 2 (c), we do not provide the corresponding annotation (*i.e.*, the query for each video) and metrics concerning video retrieval, but the annotation and metric are easy to obtain due to text spotting annotation already existed. Therefore, there are still many potential contributions for other tasks on BOVText, we want to take these as the future research directions and provide a complete solution method.

A.7 Potential Negative Societal Impacts and Solution

We argue that there mainly exists slight potential negative societal impacts for personal privacy. Although much personal information, *e.g.*, *names, identifying information, human faces*, have been blurred to protect privacy, there still might exist a little risk.

How to blur human faces. We blur the human faces in BOVText with four steps. Firstly, human faces in each frame would be detected by *face recognition*⁷ - a powerful, simple, and easy-to-use face recognition open source project with complete development documents and application cases. Secondly, with the location box from the previous step, we extract face ROI from the original image. Thirdly, we blur the face ROI with Gaussian Blur operation in OpenCV⁸. Finally, we store the blurred face in the original image and recover to video.

A.8 License and Copyright

The released video dataset includes two parts: 1,494 videos from *KuaiShou*⁹ and 356 videos from *YouTube*¹⁰. For those videos from *KuaiShou*, we mask the private information such as the human face, which has passed the examination of the legal department and copyright department of KuaiShou corporation. Thus, we own the copyright for these videos. For those videos from *YouTube*, to the best of our knowledge at the time of download, we have exercised caution to download only those videos that were available on YouTube with a Creative Commons CC-BY (v3.0) License. We don't own the copyright of those videos and provide them for non-commercial research purposes only. All data in our project is open source under CC-by 4.0 license and only be used for research purposes.

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⁷https://github.com/ageitgey/face_recognition

⁸https://www.tutorialspoint.com/opencv/opencv_gaussian_blur.htm

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