WebArXiv: A Reproducible Benchmark for Evaluating Multimodal Web Agents on arXiv Tasks

Abstract

Recent advances in foundation models have enabled the development of autonomous web agents capable of navigating and interacting with real websites. However, existing benchmarks primarily focus on general-purpose web navigation, offering limited coverage of information-centric environments. Evaluations that depend on live websites further hinder reproducibility due to constantly changing content. The arXiv platform provides a natural balance between realism and reproducibility, featuring hierarchically structured and information-centric webpages without privacy-sensitive interactions. Building on this foundation, we present WebArxiv, a benchmark for reproducible evaluation of multimodal web agents within the arXiv environment. WebArxiv is built from static webpage snapshots and includes 275 time-invariant tasks, each with a unique and deterministic ground truth. We evaluate a range of foundation-model-based web agents, revealing that WebArxiv poses significant challenges for current web agents. Behavioral analyses reveal a common failure mode in which agents over-rely on fixed interaction histories, leading to incomplete or repetitive reasoning. To address this limitation, we equip the agents with a lightweight dynamic memory mechanism that enables adaptive retrieval and reasoning over relevant context, thereby enhancing their overall navigation performance.

1 Introduction

The rapid advancement of large language and multimodal models has led to the emergence of autonomous web agents capable of performing complex tasks on real-world websites (Garg et al., 2025; Yang et al., 2025). A growing number of benchmarks have been proposed to evaluate the capabilities of these agents. However, while most existing benchmarks focus on commercial or general-purpose web navigation, real web environments also include information-centric domains such as scientific platforms (Yehudai et al., 2025). These platforms place higher demands on agents, requiring them to reason over structured metadata and to navigate hierarchical taxonomies, which remain largely underrepresented in current evaluations.

The arXiv platform serves as an ideal testbed because it is hierarchically structured and reflects key scholarly workflows. To our knowledge, WebVoyager (He et al., 2024) is the only benchmark that has incorporated arXiv as an evaluation environment. However, it includes only a small number of tasks, focuses on basic retrieval queries rather than advanced multi-condition searches. Moreover, because WebVoyager operates on live webpages, its task answers change over time. For instance, queries such as "Search for the latest preprints about quantum computing" yield different answers as the website content updates. In response, WebVoyager adopts an automatic evaluation protocol based on GPT-4V, but this reliance on model-based judgment introduces additional inconsistency. These limitations highlight the need for reproducible evaluation of agents in scientific environments.

To address this need, we introduce WebArxiv, a benchmark that enables reproducible evaluation of multimodal web agents within the arXiv environment. The arXiv platform itself provides a natural balance between realism and reproducibility. It features information-centric webpages that mirror real scholarly workflows, yet it does not involve privacy-sensitive user interactions. Building on this property, WebArxiv defines a diverse set of realistic scholarly tasks, ranging from basic information queries and rule compliance to multi-condition paper retrieval and deep content extraction. To guarantee reproducibility, all tasks are built on static snapshots of the arXiv website, forming a set of time-invariant evaluations. Each task is paired with reference action trajectories and de-

terministic ground truths, enabling consistent and verifiable comparisons across diverse web agents.

We conduct baseline experiments with ten representative agent configurations on the WebArxiv benchmark, including general-purpose LMM-based web agents such as GPT-4o (OpenAI, 2024) and several specialized web agents like OpenWebAgent (Iong et al., 2024b). The results show that WebArxiv is challenging for current web agents. Even the strongest model, GPT-o1, achieves only a 56.7% overall success rate, followed by Gemini-2.5 at 51.1%, while most other models remain below 45%. In particular, most models struggle with advanced search tasks, such as multi-condition paper retrieval.

Further analysis reveals a common failure pattern among web agents, characterized by an over-reliance on fixed interaction histories. This often causes the model to focus on irrelevant visual elements or repeat redundant actions. To address these issues, we introduce a lightweight dynamic memory mechanism that enables the agent to adaptively retrieve the most relevant prior step. By selectively recalling historical context, this mechanism leads to consistent improvements in task performance across nearly all evaluated models.

Our contributions are summarized as follows:

- We introduce WebArxiv, a benchmark that enables reproducible evaluation of multimodal web agents within the hierarchically structured arXiv environment.
- We conduct a comprehensive evaluation of ten advanced web agents on WebArxiv, demonstrating clear baseline performance across different task types and query complexity levels.
- Through detailed analyses, we find that existing web agents tend to over-rely on fixed interaction histories. To address this issue, we introduce a lightweight dynamic memory mechanism that allows web agents to adaptively leverage past interactions.

2 Related Work

Benchmarks for Web Agent. With the rapid development of large language model (LLM) and large multimodal model (LMM) based web agents, a series of benchmarks have been proposed to evaluate their capabilities (Liu et al., 2023). Early efforts focused on simulated commercial environments. For example, WebShop (Yao et al., 2022a) simulates a virtual online store populated with more than one million product listings scraped from Amazon.

Later, WebArena (Zhou et al., 2023) extends evaluation to multi-domain web environments, simulating websites spanning e-commerce, social media, and productivity to improve task diversity.

More recently, several benchmarks have begun evaluating agents directly on the live Web rather than in simulated environments. For instance, Mind2Web (Deng et al., 2023) collects large-scale trajectories of real web interactions across thousands of sites, while BrowseComp (Wei et al., 2025) emphasizes complex comparative reasoning and open-domain browsing behaviors. WebVoyager (He et al., 2024) further extends this line of work to multimodal web agent evaluation, covering tasks across 15 real-world websites that integrate textual and visual information. These benchmarks capture the unpredictability of real-world web navigation(Drouin et al., 2024). However, a major limitation of live environments is answer drift, as webpage content evolves over time (de Chezelles et al., 2025). This dynamic nature reduces reproducibility, necessitates frequent updates to gold-standard answers. In response, WebVoyager (He et al., 2024) and Mind2Web 2 (Gou et al., 2025a) adopt model-as-a-judge protocols to automatically assess task outcomes and thereby reduce human annotation overhead. Overall, existing benchmarks have advanced the evaluation of web agents in general-purpose domains, yet they provide limited coverage of information-centric workflows (Wang et al., 2022). This gap motivates the development of new benchmarks that preserve real-world complexity while ensuring reproducibility and stable ground truths (Levy et al., 2025).

LLM and LMM-based Web Agents. Recent advances in LLMs and LMMs have enabled web agents to complete end-to-end user instructions through direct interaction with real-world websites (Ma et al., 2024). ReAct (Yao et al., 2022b) introduced interleaved reasoning and acting, prompting models to generate both intermediate reasoning traces and executable action sequences. Reflexion (Shinn et al., 2023) and Auto-Eval and Refine (Pan et al., 2024a) further allow agents to analyze past failures and iteratively refine their decision strategies. WebPilot (Zhang et al., 2025b) extends this approach by incorporating Monte Carlo Tree Search (MCTS), enabling agents to evaluate, backtrack, and optimize their decision trajectories more effectively (Koh et al., 2024). Furthermore, fine-tuning language or multimodal mod-

Figure 1: WebArXiv task benchmark creation pipeline, showing seed task design, self-instruct generation by GPT-4o, automatic similarity-based filtering, and manual review. The resulting tasks are distributed across five categories and annotated through expert cross-validation to form ground-truth trajectories for web-agent evaluation.

els has emerged as another effective strategy to enhance agents' capabilities on web tasks (Pan et al., 2024b). Representative examples include text-finetuned agents such as WebGPT (Nakano et al., 2023), which fine-tunes GPT models for web browsing and question answering, and HTML-pretrained agents such as WebAgent (Iong et al., 2024a), which leverage large-scale HTML corpora to improve structural understanding and action grounding (Hong et al., 2024).

In contrast to LLM-based agents that rely primarily on DOM or HTML parsing, LMM-based agents perceive webpages through visual modalities, enabling a more holistic understanding of layout and content (Gou et al., 2025b). Most existing multimodal agents are built on closed-source LMMs, such as GPT-4V (Zheng et al., 2024a) and Gemini (Georgiev et al., 2023), which exhibit strong visual grounding and multimodal reasoning capabilities. These models facilitate effective action planning through paradigms such as ReAct (Yao et al., 2022b) and Reflexion (Shinn et al., 2023). Representative multimodal web-agent frameworks, including Pix2Act (Shaw et al., 2023) and WebGUM (Furuta et al., 2024), operate directly on webpage screenshots, translating visual cues into grounded actions without explicit reliance on DOM structures. SeeAct (Zheng et al., 2024b) further extends this paradigm by integrating visual grounding with tool-augmented candidate selection, enabling more precise element localization and robust interaction reasoning.

3 WebArxiv Benchmark

3.1 Overview

We introduce WebArxiv, a reproducible benchmark for evaluating web agents in information-centric environments based on the arXiv platform. The benchmark consists of 275 tasks that span a broad range of scholarly web operations. Each task package includes a natural-language instruction, a reference action trajectory, and a machine-verifiable ground truth validated by multiple annotators. Figure 1 provides an overview of the benchmark creation pipeline. In this section, we present the problem formulation, task type statistics, task construction pipeline, and annotation process.

3.2 Problem Formulation

Following prior work (Zhou et al., 2024), we formalize the web environment as a partially observable Markov decision process (POMDP) (Kaelbling et al., 1998), represented by the tuple $\mathcal{E} = (\mathcal{S}, \mathcal{A}, \mathcal{T}, \mathcal{O})$, where $\mathcal{S}$ denotes the underlying state space of the web interface; $\mathcal{A}$ is the action space, consisting of discrete user-interaction primitives such as click and scroll; $\mathcal{T} : \mathcal{S} \times \mathcal{A} \to \mathcal{S}$ defines a deterministic transition function that maps the current page state and executed action to a new web state after rendering (Sutton and Barto, 2018); and $\mathcal{O}$ represents the observation space, comprising multimodal inputs available to the agent, including the rendered webpage screenshot and its corresponding textual elements.

Given a natural-language task instruction i, the current multimodal observation $o_t \in \mathcal{O}$, and the interaction history $a_{1:t-1}$, the agent selects an action $a_t \in \mathcal{A}$. Upon execution, the environment transitions deterministically to a new state $s_{t+1} = \mathcal{T}(s_t, a_t)$, and the agent receives an updated observation $o_{t+1} \in \mathcal{O}$, which reflects the new visual and textual interface after the action is applied.

Statistic / Category	Website Info & Org	Rules & Accounts	Paper Retrieval	Adv. Search & Filters	Deep Paper Extraction	Total
Generated tasks	100	100	100	100	100	500
Similar tasks	35	41	31	37	29	173
Unable to annotate	5	2	4	4	8	23
Expired tasks	7	6	9	4	3	29
Refined tasks	55	55	55	55	55	**275**
GT Annotate steps	270	277	259	292	286	1382
Avg. GT steps/task	4.9	5.0	4.7	5.3	5.2	5.03

Table 1: Data distribution across five task categories. GT: Ground Truth

3.3 Task Types

WebArxiv consists of 275 tasks grouped into five categories, each targeting a distinct aspect of scholarly web interaction:

- **Website Information and Organizational Details.** This category evaluates agents' ability to navigate the arXiv interface and locate general information such as editorial structures, website information and organizational guidelines.
- **Rules, Licensing, and User Account Management.** These tasks assess whether agents can identify procedural and policy-related content, including submission requirements, license types, withdrawal policies, and user account operations.
- **Research Paper Discovery and Retrieval.** This category measures agents' capability to search for scholarly papers by author, ID, or category, while extracting stable metadata such as titles, authors, and primary subject areas.
- **Advanced Search and Filtering.** Tasks in this category involve executing complex multi-condition queries by combining keywords, publication years, and subject domains to evaluate multi-constraint reasoning and structured search proficiency.
- **Deep Paper Content Extraction.** These tasks require extracting fine-grained information directly from the HTML version of papers, testing agents' ability to identify detailed textual and structural content.

The 275 tasks are evenly distributed across the five categories, with 55 tasks in each. Among them, the Advanced Search and Filtering and Deep Paper Content Extraction categories involve the highest number of interaction steps. Detailed task statistics are provided in Table 1, and task examples are presented in Appendix A.1.

3.4 Task Construction Pipeline

Human experts first designed a small set of 20 seed tasks for each category, serving as exemplars for LLM-assisted augmentation. Guided by predefined category schemas and manually crafted templates, GPT-4o was employed to generate 100 candidate tasks per category, simulating realistic user queries and interaction intents.

The dataset was then refined through a two-stage filtering process. In the first stage, we computed pairwise sentence-level similarities using the `all-mpnet-base-v2` embedding model and removed semantically redundant tasks, retaining only those with similarity scores below 0.8 to ensure diversity of task intent. In the second stage, the remaining tasks were manually reviewed by the research team to confirm their clarity. Specifically, we excluded tasks that could not be annotated reliably, had non-unique ground truths, or were not time-invariant. After this filtering process, each category contained 55 finalized tasks, which were subsequently integrated into the WebArxiv benchmark for reproducible evaluation. The distribution of tasks across categories is summarized in Table 1.

3.5 Annotation Process

We recruited five PhD-level annotators with experience using the arXiv platform to manually annotate all 275 tasks. For each task category, a reference example was provided to guide annotation consistency. Each annotator independently interacted with the WebArxiv interface to complete their assigned tasks. During this process, they documented every action step and captured key screenshots to record the reasoning process leading to the final answer. After completing the individual annotations, the annotators performed cross-validation for each task to ensure consistency. The resulting consensus trajectory then served as the ground truth for evaluation.

To assess web agent performance, we compared each model's final output against these ground truth. In addition to final-answer matching, we also examined the agents' full action trajectories via screenshots to evaluate the logical consistency of their reasoning process. Task outcomes were labeled as:

Correct: output matches the gold-standard answer; **Incorrect**: the agent failed to retrieve the required content; **Partially Correct**: the agent's trajectory was close to completion but missed the final steps.

4 Experiments

4.1 Baselines

We evaluate a set of mainstream web agents under an end-to-end setting on the WebArxiv benchmark. The selected agents include both general-purpose LMMs that operate in an instruction-following manner and specialized web agents designed for fine-grained browser interaction.

General-purpose LMMs. These models receive natural language instructions along with webpage screenshots as input and generate textual reasoning and action predictions. The temperature parameter for all LMMs was set to 0.1.

- **GPT-o1:** A state-of-the-art multimodal model developed by OpenAI that accepts both image and text input. We provide webpage screenshots and task instructions as input.
- **GPT-4-Turbo:** A high-efficiency variant of GPT-4 with comparable reasoning capabilities but optimized for inference latency.
- **Gemini Series** (DeepMind, 2024): Google DeepMind's multimodal family supporting vision-language understanding. We test Gemini 1.5 pro, 2.0, and 2.5 under the same prompting configuration as GPT-4o, combining textual instructions with webpage screenshots.
- **GPT-4o-mini / GPT-4o:** Compact and full-sized versions of the GPT-4o model family, used to examine the trade-off between model size and web task performance.

Specialized Web Agents. These agents are explicitly designed for browser control. They typically rely on DOM parsing, fine-grained action spaces (e.g., click, type), and internal state tracking for reasoning.

- **SeeAct** (Zheng et al., 2023): A vision-based web agent that integrates a perception module (CLIP) with an action decoder. It employs a global planning strategy and performs step-wise interactions using webpage screenshots.
- **LiteWebAgent** (Zhang et al., 2025a): A lightweight web automation framework that parses DOM structures and uses language models to predict high-level actions. It is optimized for both speed and interpretability.

- **OpenWebAgent** (Iong et al., 2024b): A modular web agent architecture featuring DOM-based environment modeling, visual grounding, and tool-use capabilities. It supports retrieval-augmented inputs and maintains an explicit memory of previous steps.

4.2 Evaluation Protocol

We adopt task success rate as the primary evaluation metric, which measures the proportion of tasks the agent retrieves the correct final answer. Each agent is evaluated on all tasks in the WebArxiv benchmark, and success is determined by comparing the agent's final response with the verified gold-standard answer. The evaluation is conducted under a strict matching criterion to ensure answer accuracy. We performed each task three times and report the averaged results for ten web agents across five task categories in the WebArxiv benchmark.

4.3 Main Results

WebArxiv provides a fair comparison across various models with time-invariant arXiv tasks. Experiments show that performance across categories varied significantly, as summarized in Table 2. Results Overview. WebArxiv enables fair and reproducible comparisons across diverse models by providing time-invariant arXiv tasks. Experimental results reveal substantial performance variation across task categories, as summarized in Table 2. GPT-o1 achieved the highest accuracy in Platform Information at 72.7% and Paper Retrieval at 65.5%, while Gemini-2.5 performed best on Rules & Accounts with 57.3% and Advanced Search & Filters with 47.3%. LiteWebAgent led in Deep Paper Extraction with 45.5%. Among all categories, however, Advanced Search & Filters remained the most challenging, with only one model exceeding the 45% threshold. Overall, GPT-o1 achieved the best average performance across all task categories, reaching 56.7%, followed by Gemini-2.5 at 51.1%, while most other models

These results suggest that model size is not the sole factor determining performance on WebArxiv. Smaller models, such as GPT-4o-mini, can achieve comparable results on certain tasks. In addition, the stronger performance of GPT-o1 may partly stem from its more effective Chain-of-Thought (CoT) reasoning capability.

Web Agents	Platform & Org Info	Rules & Accounts	Paper Retrieval	Adv. Search & Filters	Deep Paper Extraction	Total (%)
GPT-4-Turbo	43.6%	34.5%	47.3%	25.8%	30.9%	36.4%
GPT-4o	36.1%	29.6%	34.5%	25.7%	38.2%	32.7%
GPT-o1	**72.7%**	50.3%	**65.5%**	43.2%	44.5%	**56.7%**
GPT-o4-mini	52.7%	48.2%	56.4%	29.1%	32.7%	43.8%
Gemini-1.5-pro	47.3%	42.2%	52.7%	34.0%	37.8%	42.9%
Gemini-2.0	34.5%	29.1%	34.8%	25.2%	27.3%	30.6%
Gemini-2.5	65.2%	**57.3%**	52.7%	**47.3%**	35.4%	51.1%
SeeAct	28.2%	20.0%	25.7%	20.8%	24.9%	23.6%
LiteWebAgent	43.7%	47.3%	43.4%	32.3%	**45.5%**	44.0%
OpenWebAgent	34.5%	38.9%	43.6%	34.5%	18.2%	33.8%

Table 2: Performance comparison of web agents across five task categories in the WebArxiv benchmark.

Web Agents	Platform & Org Info	Rules & Accounts	Paper Retrieval	Adv. Search & Filters	Deep Paper Extraction	Total (%)
GPT-4-Turbo	43.6%	34.5%	47.3%	25.8%	30.9%	36.4%
GPT-4-Turbo + dynamic memory	52.6%	42.7%	46.4%	30.0%	29.1%	40.2%
GPT-4o	36.1%	29.6%	34.5%	25.7%	38.2%	32.7%
GPT-4o + dynamic memory	63.6%	60.0%	38.2%	34.5%	52.7%	38.4%
GPT-o1	72.7%	50.3%	65.5%	43.2%	44.5%	56.7%
GPT-o1 + dynamic memory	73.3%	55.5%	64.5%	52.7%	60.2%	61.8%
GPT-o4-mini	52.7%	48.2%	56.4%	29.1%	32.7%	43.8%
GPT-o4-mini + dynamic memory	57.3%	31.8%	52.7%	30.9%	35.5%	41.6%
Gemini-1.5-pro	47.3%	42.2%	52.7%	34.0%	37.8%	42.9%
Gemini-1.5-pro + dynamic memory	59.7%	59.1%	51.8%	38.2%	45.5%	50.9%
Gemini-2.5	65.2%	57.3%	52.7%	47.3%	35.4%	51.1%
Gemini-2.5 + dynamic memory	81.8%	72.7%	56.4%	43.6%	41.1%	60.0%

Table 3: Comparison of base models and their dynamic memory enhanced models across five task categories.

4.4 Ablation on Memory Mechanism

Observed Failures and Motivation. We conduct baseline experiments on the WebArxiv benchmark and perform a detailed behavioral analysis of agent trajectories. Our observations reveal two failure patterns. First, in advanced search tasks, agents often become distracted by dense UI elements and fail to attend to task-relevant content. Second, on content-heavy pages, agents tend to over-rely on the most recent truncated view, overlooking earlier yet useful information, which frequently results in reasoning loops or incomplete answers. We attribute these issues to the rigid memory design adopted by most existing web agents. Typically, an agent maintains its navigation context by storing the last K interaction steps, each consisting of a multimodal observation and its corresponding action. Formally, let $\mathcal{H}_t = \{(o_{t-K+1}, a_{t-K+1}), \ldots, (o_{t-1}, a_{t-1})\}$ denote the recent interaction history before step t, most web agents utilize $\mathcal{H}_t$ as a fixed window, without distinguishing the relative importance of past experiences.

Memory Design. To address these limitations, we equip the baseline agents with dynamic memory module that allows the agent to adaptively retrieve and reason over the most relevant past context at each interaction step. Specifically, at each step t, the agent retrieves the last k observations and actions, denoted as $\{(o_{t-k+1}, a_{t-k+1}), \ldots, (o_{t-1}, a_{t-1}), (o_t, a_t)\}$. Among these, the model dynamically selects the most relevant past step for contextual reasoning based on its internal assessment of which historical information is most useful for the current decision. The corresponding observation o_{k*} is then combined with the current view o_{t+1} to construct

Memory Mechanism	Successful (↑)	Partial (↓)	Failed (↓)
GPT-4-Turbo last 3 steps	36.4%	18.2%	45.5%
GPT-4-Turbo last 2 steps	34.5%	20.4%	45.2%
GPT-4-Turbo last step	**43.6%**	**14.5%**	**41.8%**
GPT-4-Turbo + dynamic memory	40.2%	16.3%	43.6%
GPT-o1 last 3 steps	56.7%	16.2%	27.0%
GPT-o1 last 2 steps	58.2%	15.1%	26.8%
GPT-o1 last step	60.0%	14.4%	25.7%
GPT-o1 + dynamic memory	**61.8%**	**12.7%**	**25.5%**

Table 4: Task success rates of GPT-o1 and GPT-4 Turbo models under different memory strategies. The baseline uses the last 3 steps to make decisions, while dynamic memory only use the most relevant step to make decisions.

a contextual representation for action generation. The resulting action a_{t+1} is executed in the environment, and the interaction history is updated. More details can be found in Appendix A.2.

Comparative Results. We further evaluate LMM-based web agents with a dynamic memory mechanism on the WebArxiv benchmark, where the memory window size k is set to 3. Table 3 presents a comparison between each base model and its dynamic memory variant across five task categories. Across 5 of the 6 evaluated models, performance improved substantially with the addition of dynamic memory. The dynamic memory version of GPT-o1 achieved the highest overall success rate of 61.8%, surpassing its base model at 56.7% and setting new benchmarks in Platform Information at 73.3% and Deep Paper Extraction at 60.2%. Similarly, the dynamic memory Gemini-2.5 reached 60.0%, an 8.9% improvement over its base version at 51.1%, with notable gains in Platform Information at 81.8% and Rules & Accounts at 72.7%. These results demonstrate that adaptive memory retrieval can significantly enhance agents' reasoning and navigation capabilities in complex web environments.

We further conducted additional experiments on GPT-4 and GPT-o1 to compare the effectiveness of dynamic memory against fixed-window memory configurations. As shown in Table 4, the dynamic memory variant of GPT-o1 achieved a success rate of 61.8%, outperforming simpler baselines that used only the most recent step (60.0%) or a uniform three-step memory (56.7%). Similarly, introducing dynamic memory improved GPT-4-Turbo from 36.4% to 40.2%, demonstrating its effectiveness in adaptive context retrieval and action generation.

4.5 Analysis

To gain deeper insights into agent behavior, we analyze performance across categories, models, and memory settings, and further investigate typical error patterns observed in the WebArxiv benchmark.

Cross-Category Performance. The distribution of results across categories reveals a consistent gradient of difficulty. Figures 2 and 3 present the performance of GPT-o1 across five task types. Platform & Org Info and Paper Retrieval are comparatively straightforward, with several agents surpassing 60% accuracy. These tasks typically involve single-page lookups or structured metadata extraction, requiring minimal multi-step planning. Rules & Accounts and Deep Paper Extraction are of intermediate difficulty. The former is challenging because tasks often demand retrieval of exact policy statements, where even slight paraphrasing is penalized under strict evaluation criteria. The latter requires navigation of long documents and reliable handling of HTML anchors, for example, identifying captions or figures embedded deep within papers. By contrast, Advanced Search & Filters emerges as the most difficult category. Even the strongest model, Gemini-2.5, achieves only 47.3%. Here, errors are amplified by the need to coordinate multiple constraints, including Boolean operators, date ranges, and field-specific filters, where a single misstep can invalidate the entire trajectory.

Cross-Model Comparison. Across models, performance varies substantially. GPT-o1 achieves the best overall score at 56.7%, showing particular strength in Platform and Retrieval tasks. Gemini-2.5, in contrast, leads in Rules & Accounts with 57.3% and in Advanced Search with 47.3%, suggesting that it is more effective at parsing long-form documentation and reasoning over structured form

Figure 2: Stacked bar chart of GPT-o1, showing task completion rates across five task categories.

Figure 3: Radar chart of GPT-o1, visualizing success, partial, and failure rates across five task categories.

inputs. LiteWebAgent obtains the highest score in Deep Paper Extraction with 45.5%, reflecting the benefit of DOM parsing for anchor-dense HTML content. By comparison, SeeAct consistently underperforms across all categories, illustrating the limitations of purely screenshot-based approaches in text-heavy academic interfaces. Model scale, however, is not a decisive factor; smaller models such as GPT-4o-mini still achieve competitive performance, reaching 43.8% overall. The superior results of GPT-o1 may also be attributed in part to its stronger chain-of-thought reasoning capability.

Dynamic Memory Effects. Introducing dynamic memory yields consistent improvements for most LLM-driven agents, as shown in Table 3. The most notable gains are observed in Deep Paper Extraction, where GPT-o1 rises from 44.5% to 60.2% and GPT-4o from 38.2% to 52.7%. It also benefits in Platform and Rules tasks by enabling agents to recall key past views instead of relying on fixed-length histories. The effects on Advanced Search are mixed: while GPT-o1 improves from 43.2% to 52.7%, GPT-4-Turbo shows only a marginal gain. These results support our hypothesis that dynamic memory alleviates rigid history bias by selectively retrieving the most relevant past observation. The one exception is GPT-o4-mini, which experiences a slight performance decline, likely due to over-reliance on misleading prior states given its reduced reasoning depth.

Error Analysis. Qualitative inspection of trajectories reveals recurring errors. Agents often fixate on recent but irrelevant history, showing rigid attention patterns. Strict string-matching exposes brit-

tleness, penalizing semantically correct yet paraphrased answers—especially in policy tasks. Errors in field and anchor selection also occur on advanced search or HTML-dense pages, where agents confuse fields (e.g., title vs. abstract) or fail to activate the correct checkbox or link.

These findings carry several implications for the design of future web agents. First, incorporating lightweight DOM priors can mitigate failures on anchor-dense pages. Second, memory mechanisms should be selective rather than uniformly long, with dynamic memory offering a lightweight but effective solution. Third, constraining action templates for structured forms reduces drift when managing Boolean operators or field assignments.

5 Conclusion

We introduced WebArxiv, a reproducible benchmark designed for evaluating web agents within the arXiv platform. WebArxiv consists of time-invariant tasks that capture realistic scholarly interaction scenarios. Using this benchmark, we conducted extensive experiments to evaluate both general-purpose LMMs and specialized web agents. Empirical observations revealed key behavioral limitations, such as over-reliance on fixed interaction histories. In response, we equip the agent with a lightweight dynamic memory mechanism that enables it to adaptively retrieve and reason over relevant context during web navigation. Experimental results demonstrate that this mechanism substantially improves agent performance across multiple categories. Overall, our study provides a reproducible foundation for web-agent evaluation and offers insights into building more adaptive agents.

6 Limitation

One limitation of our benchmark is its exclusive focus on the English-language interface of the arXiv platform. This design choice overlooks multilingual versions of the site, which may present different navigation behaviors for non-English users. As a result, the benchmark may not fully capture the challenges faced by web agents operating in multilingual contexts. Expanding the benchmark to include tasks in other languages or region-specific interfaces would improve the generalizability of the benchmark.

7 Ethics Statement

This work introduces a benchmark for evaluating multimodal web agents on time-invariant tasks derived from the arXiv platform. All experiments were conducted on publicly available webpages without requiring user authentication or access to private data. No personal, sensitive, or user-generated information was collected or processed during the study. The benchmark tasks are carefully designed to avoid topics that could be ethically sensitive or controversial.

Human annotators involved in verifying task outcomes were fully informed of the study's goals and provided explicit consent. Annotations were limited to factual assessments of agent performance and did not require subjective judgments about individuals or user behavior.

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A   Appendix

This appendix provides additional details on task examples in Appendix A.1, pseudocode for the memory mechanisms in Appendix A.2, and agent prompts in Appendix A.3.

A.1   Task Example

Step 1: Click [8]   Step 2: Click [3]   Step 3: Click [11]

Step 4: Click [6]   Step 5: ANSWER

Figure 4: An organizational information retrieval case for arXiv. Given the task: "On arXiv's About page, find the categories of the Section Editorial Committees." The agent successfully retrieves the answer: "Physics, Mathematics, Computer science (CoRR), Quantitative biology, Quantitative finance, Statistics, Electrical engineering and systems science, Economics," correctly identifying all eight top-level research domains designed by the platform's editorial structure.

Step 1: Click [6]   Step 2: Click [10]   Step 3: ANSWER

Figure 5: A user account management task on arXiv. Given the task: "How can I package my submission files?" The agent correctly returns the instruction: "Create tar.gz and zip Files," accurately capturing the recommended submission packaging methods outlined in the official arXiv help documentation for authors preparing their papers.

Step 1: Click [4]   Step 2: Type [4]   Step 3: ANSWER

Figure 6: A paper discovery task on arXiv. Given the task: "State the name of the second Author of this paper: 3D Scene Generation: A Survey." The agent successfully identifies the second listed author as "Haozhe Xie," confirming the correct retrieval of metadata related to the specified research paper.

| Step 1: Scroll [WINDOW] | Step 2: Scroll [WINDOW] | Step 3: ANSWER |

Figure 7: A search interaction task on arXiv's advanced search page. Given the task: "Tell me how to search within a subcategory." The agent correctly interprets the search interface and returns the instruction: "Select All fields," demonstrating its ability to navigate and extract advanced search instructions from the user interface.

| Step 1: Search paper | Step 2: Click [25] | Step 3: Click [19] |
| Step 4: Click [27] | Step 5: ANSWER | |

Figure 8: A publication detail retrieval task on arXiv. Given the task: "Provide the name of the university publishing in this paper: There is no polynomial formula for the catenary and the tame degree of finitely generated monoids." The agent correctly extracts the affiliation information and returns: "University of Graz," confirming successful deep content extraction from the publication metadata.

A.2 Pseudocode for Dynamic Memory Module

A.3 Agent Prompt

Step	Screenshot	Thought (with dynamic memory)	Action	Action target (button/text)
1	screenshot1.png	To find the university, I should search the paper by its title. (Initial step — no prior context to reflect on.)	Type [4]	Search bar [4]; input: "There is no polynomial formula for the catenary and the tame degree of finitely generated monoids"
2	screenshot2.png	Search results are shown. From Step 1, I confirmed this is the correct paper. Let's open more details.	Click [25]	More [25]; expands metadata and abstract
3	screenshot3.png	(Dynamic memory: Step 2 showed author names, but no affiliations.) To get structured metadata, we should access the article detail page.	Click [19]	arXiv:2505.05330 [19]; opens paper's detail page
4	screenshot4.png	(Dynamic memory: Step 3 showed abstract, still no affiliations.) The HTML version might include full author info and contact details.	Click [27]	HTML (experimental) [27]; opens the full paper in HTML format
5	screenshot5.png	(Dynamic memory: Step 4 gave full text. University found in both email domain and author line.)	ANSWER; University of Graz	From author info: alfred.geroldinger@uni-graz.at; full text shows: University of Graz

Table 5: Interaction trajectory for Task ArXiv–51 with dynamic memory. The agent uses targeted recall to improve navigation and stability across dense UI structures.

For each interaction step t:

1. Retrieve the last 3 visual observations and their associated element texts:
   ```
   last_3_steps = get_last_3_steps()
   ```

2. Ask the model which of these steps is most useful for reasoning:
   ```
   memory_prompt = format_memory_prompt(last_3_steps)
   important_step_index = model.respond(memory_prompt)
   ```

3. Construct the reasoning context:
   ```
   Reasoning source: last_3_steps[important_step_index]
   Current view: last_3_steps[-1]
   ```

4. Ask the model to generate the next action using both reasoning and current view:
   ```
   action_prompt = format_action_prompt(task, guidance_context, history)
   next_action = model.respond(action_prompt)
   ```

5. Execute the action and update history:
   ```
   result = execute(next_action)
   update_history(next_action, result)
   ```

Figure 9: Pseudocode for dynamic memory agent across the last 3 steps in WebArxiv.

```
SYSTEM_PROMPT = """
You are an intelligent web-browsing agent equipped with dynamic memory capability. Your task is to
interact with webpages step-by-step to complete a given query efficiently and accurately.
At each step t, you will: 1. Recall the last three interaction steps, including screenshots and
visible element texts. 2. Reflect on which past step is most relevant to current reasoning. 3. Use
the most relevant past step as the reasoning context and the latest observation as the current view.
4. Generate the next best action that moves the task forward.

— Memory Phase — You will first receive up to three past observations (each includes a brief text
summary and visible elements). Analyze these and identify which step provides the most useful
information for solving the current task.
Response format: Memory: Step [1-3] is most relevant because [reason].

— Action Generation Phase — You will receive: 1. The reasoning source (from your selected past step)
2. The current view (most recent screenshot + element texts) 3. The task description and guidance
context
Using these, decide the next best action.

— Allowed actions (choose ONE): — Click [Numerical_Label]: Click a labeled element.   Type
[Numerical_Label]; [Content]: Type text into a labeled textbox. Scroll [WINDOW]; [up/down]: Scroll
the page. Wait: Wait if a page is still loading. GoBack: Navigate back to the previous page. ANSWER;
[Your Answer]: Provide a final answer once the task is complete.

— Reasoning Principles — 1. Focus first on visible content before scrolling or navigating. 2. Use
your chosen reasoning source to interpret the current page logically. 3. Avoid repeating the same
action if no visual change occurred. 4. Use concise, goal-driven reasoning — no guessing or vague
actions.

— Response Format — Your output must follow this structure: Memory: [Your analysis selecting the
most relevant previous step] Thought: [Brief reasoning combining reasoning source and current view]
Action: [Your chosen next action in the exact format above]
"""
```

Figure 10: System prompt for the dynamic memory web agent. The prompt encourages selective recall, contextual reasoning, and minimal action bias for structured web navigation.