IvoryOS: An Interoperable Platform and Community for Self-Driving Labs

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1. Introduction

Self-driving laboratories (SDLs) promise to accelerate scientific discovery by tightly coupling automation, data acquisition, and AI–driven decision making. Despite significant advances in optimization algorithms and robotic platforms, the practical development and adoption of SDLs remain challenging. A major barrier is the lack of hardware–software interoperability, which forces most SDL projects to rely on bespoke engineering solutions that tightly couple hardware control, experimental logic, and optimization workflows. This fragmentation introduces repetitive works, limits reuse and reduces reproducibility [1, 2]. Furthermore, SDL development requires close collaboration between domain scientists and engineers; however, such "bilingual" expertise is rare, as current educational and training pipelines remain largely siloed by discipline. As a result, experimentalists are constrained by limited programming fluency, while engineers lack context when building SDL infrastructures. Together, these challenges hinder platform reproducibility, scalability, and the broader adoption of SDL technologies.

2. Interoperable SDL Interface

Interoperability and visual interfaces are critical to lowering the barrier to building and operating SDLs. Interoperable software decouples hardware control, experimental logic, and optimization strategies, enabling reuse across instruments, workflows, and laboratories while improving reproducibility and long-term maintainability. At the same time, visual interfaces provide an accessible layer that allows domain scientists to design, inspect, and modify experimental workflows without requiring deep programming expertise.

2.1 IvoryOS architecture

IvoryOS introduces an interoperable orchestrator that enables closed-loop experimentation on existing automated protocols without imposing a new abstraction layer [3]. Rather than requiring protocols to be rewritten in a domain-specific language, IvoryOS programmatically introspects executable Python code to extract protocol metadata, which is then used to dynamically generate operation menus for the controller and workflow builder (Figure 1). Scientists can directly use the protocols or low-code design a sequential experiment workflows that supports dynamic parameters. With the workflow engine, the experiment can be executed in closed-loop with options

of several open-source optimizer libraries. Simultaneously, the workflow engine supports granular process control, and systematic logging and error handling across iterations.

Fig. 1: IvoryOS Architecture Overview

2.2 Optimization Standardization Schema

The optimization layer employs a structured schema to interface with different Bayesian optimization (BO) engines, including Ax [4], BayBE [5], and NIMO [6]. By standardizing experimental data input and output, this layer enables users to interchange optimization providers and strategies without modifying the underlying experimental code.

2.3 Natural Language Layer

To further reduce the on-boarding time, this orchestrator is also extensible with a Model Context Protocol (MCP) server. The server uses Application Programming Interface (API) request to communicate to the main orchestration layer, enabling AI-native decision-making that can plan, adapt, and optimize experiments in real time [7]. Because all metadata is derived directly from executable code, it remains synchronized with the underlying experiment and requires no manual specification or schema maintenance.

2.4 Demonstration in SDLs

This approach is validated through several automation scenarios, including high-throughput parameter sweep, closed-loop optimization and multi-instrument workflows. In these demonstrations, the same experimental interface is successfully deployed on more than 20 robotic platforms in different institutions without modification of the underlying control code. This highlights how introspection-based metadata decouples experimental design from algorithmic choice. Additionally, we show that experimental workflows expressed through IvoryOS interfaces can be shared and re-executed across deployments with minimal configuration effort. Such reproducibility within the domain is critical for knowledge transfer and for accelerating the development of scientific automation.

2.5 Ecosystem and Community Effects

Beyond individual laboratories, IvoryOS supports a community-driven ecosystem for scientific automation. Developers can share metadata for instrument drivers, reusable data analysis modules, and experiment templates without requiring standardization. The platform automatically generates an installation package that launches IvoryOS, reducing the complexity of setting up Python environments and dependencies. This ecosystem provides a curated catalog of automation-ready instruments and software, enabling anyone to construct a customized platform and execute SDL workflows with minimal coding effort. While accelerating and democratizing the research and development of SDLs, this also accelerates the training of programming along with the susses of platform development.

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