The Learning Trajectories of Individual Tokens in Language Model Training

Abstract

This study investigates token learning in language models by analyzing the token-level training trajectories of three English-trained models of the OLMo architecture (40M, 150M, and 1B parameters). Building on initial observations of training trajectories, we proceed to quantifying the relative contributions of frequency, token length, and token nature to the learning process. We find that frequency is the primary factor in determining the learning time of a token, although the nature of the token also has a non-negligible effect. Conversely, surprisal at learning time is driven predominantly by token nature, with frequency playing a secondary but significant role, particularly in smaller architectures. Our findings suggest that we might be able to reduce the time a model needs to learn a token. But they also suggest that there is a limit to the learning of a token, that might be fundamentally constrained by the token's nature.

1 Introduction

Tokenization is deterministic, occurs before training, and is not necessarily optimal. However, it plays a fundamental role, both in the architecture of the model, by imposing the dimension of the embedding matrix, and in the shaping of the data, by influencing its granularity and distribution. Language models are learners of tokens in context. However, what "learning a token" might mean for a language model is not well defined. In this study, we aim to clarify this notion by introducing a methodology to study token trajectories.

The form and number of tokens impact model learning. Studies show that tokenization might benefit from pruning infrequent tokens (Chizhov et al., 2024) and that identifying underperforming tokens (Land and Bartolo, 2024) or token training dynamics (Lin et al., 2025) might improve training. While these studies are interested in tokens primarily as

means of optimizing training, they do not offer a comprehensive perspective on the variety of tokens that compose a language model's vocabulary, their characteristics, and their training dynamics.

We are used to look at loss curves that average over tokens in a text sample. However, we are less used to look at the loss for each individual token, that is, the average surprisal of a token over multiple contexts. While the loss over a dataset shows us if the text becomes less surprising to the model during training, the token loss shows us if the token becomes less surprising in appropriate contexts, or more simply, it shows us whether the token is "learned". To compute learning curves for individual tokens, we evaluate each target token across a set of contexts at different training checkpoints. For each checkpoint, we extract the next-token surprisal (negative log-likelihood) for the target token. By averaging these values across the context set, we derive a mean token-level surprisal (effectively the cross-entropy) for each checkpoint, allowing us to track the model's learning progress over time.

We make the following hypothesis: the characteristics of a token, including both intrinsic properties, such as its length, and distributional, such as its frequency, play a part in how a token is learned by a language model (LM). In an ideal scenario, given a token and an evaluation dataset composed of a set of contexts of that token, we would be able to determine when the learning trajectory has converged and training on additional instances is redundant.

We introduce our methodology in Section 3. Following an examination of training dynamics across a diverse set of tokens, we formally define our research questions in Section 4. After establishing a method to detect token convergence (Section 5), we measure the impact of frequency, token length, and token nature in Section 6. [1]

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[1] Code and data can be found at https://anonymous.4open.science/r/lm-memgen-24DC/.

2 Related Work

Training trajectories. Interest in studying training trajectories is not restricted to LMs. Toneva et al. (2019) investigate the learning dynamics of neural network image classifiers, in order to identify which examples are forgotten over the course of learning. They draw inspiration from studies on catastrophic forgetting (Hu et al., 2019), and find that some examples seen during training are unforgettable, while others, especially those with noisy labels, are easily forgotten.

Memorization. While studies on memorization in LMs have different objectives than ours, their object of study is similar to ours and their insights and methodology serve us as starting points. Whereas these studies focus on contexts seen during training, we evaluate contexts that, to the best of our knowledge, remain unseen during training. Interest in memorization comes from two main areas: security and factual knowledge. Loosely, a token is memorized if the model generates it exactly as it appeared in the training data when given the same context. Carlini et al. (2023) find that larger models memorize more, and that repeated examples and longer sequences facilitate extraction of memorized data. Tirumala et al. (2022) show that larger models memorize faster and forget less. Biderman et al. (2023a) show that memorization in language models cannot be predicted from smaller or partial models. Finally, (Biderman et al., 2023b) show that training order has little impact on memorization.

Language acquisition. Training trajectories can also shed light on word acquisition in language models. More similar to us, Chang and Bergen (2022) establish ages of acquisition for 600 tokens, based on learning curves. They find that frequency plays a greater role in language models than in children, and that language models seem to learn unigram and then bigram probabilities in a systematic way during training. They are also sensitive to features such as sentence length and lexical class. Motivated by the language acquisition comparison, and in contrast with the present study, they restrict selection to tokens that are English words and define token learning by drawing inspiration from theories of word learning in children.

Trajectories of examples. Related studies look at token-context pairs in order to determine their trajectories during training. Xia et al. (2023) find that, early in training, the same pairs have similar trends independently of model scale, while larger models unlock new phenomena later. Chang et al. (2024) extend their study and find that more frequent token-context pairs reach lower surprisals and are less likely to be forgotten. While our work is technically similar in some aspects, the main difference is that we look at tokens trajectories by abstracting over their contexts, while in the studies mentioned here, the focus is on token-context pairs.

3 Methodology

We analyzed the training trajectories of three models of the OLMo family: the OLMo-1B model trained and provided by Groeneveld et al. (2024), and two models that we trained ourselves using the same framework, of size 150M and 40M parameters, respectively. The OLMo-1B model was trained on a subsample of 2T tokens of the English corpus Dolma (Soldaini et al., 2024), in one pass over the (shuffled) training data. The two smaller models were trained on a prefix of the same data, scaled by their size. We have followed the *Chinchilla* scaling laws (Hoffmann et al., 2022) and scaled the size of the training data using OLMo-1B as a reference. The 150M model, approximately $8\times$ smaller than OLMo-1B, was therefore trained on $8\times$ less data. Similarly, the OLMo-40M model was trained on $12\times$ less data (details in Appendix A). All models were trained beyond the $\sim$20 token per parameter scaling law recommendation.

In order to compute training trajectories, we need to 1) select a subset of tokens, 2) construct evaluation datasets with contexts for each token and 3) identify the checkpoints at which the models will be evaluated.

Tokens. The three models share a common vocabulary of 50,280 tokens. Given the significant computational cost required to evaluate the full vocabulary (1,000 contexts $\times$ 50,000 tokens $\times$ 70 checkpoints $\times$ 3 models $\approx$ 10.5T inferences), we perform our analysis on a subset of $N = 510$ tokens. This subset was constructed using a hybrid sampling strategy: a uniform random sample of $n = 255$ tokens to ensure broad coverage, supplemented by two targeted samples: one based on frequency ($n = 88$) and another based on token nature ($n = 167$). To sample by frequency, we first needed to estimate the frequency of each token in a training batch. We performed this estimation by averaging over token counts in 500 randomly sampled batches and validated the estimate using pivotal bootstrap (Appendix B). We were then able to

assign the tokens to 10 balanced frequency ranges, between 0 and 1,000,000 and sample 10 tokens from each of the 10 frequency ranges, if possible, amounting to a total of 88 tokens. To sample by token nature, we defined 12 "token nature" categories and sampled from the vocabulary accordingly. These 12 categories are: *Delimiter*, *Digit*, *Letter*, *Subword*, *Punctuation*, *Punctuation prefix*, *Punctuation suffix*, *Number prefix*, *Number suffix*, *Word*, *Prefix* and *Suffix*. A description of the categories and examples are given in Appendix C. We sample up to 14 tokens for each category, amounting to 167 additional tokens. This approach aims to capture the linguistic and distributional diversity of the vocabulary while maintaining a manageable evaluation scale. Frequency, token nature and token length distributions of the token population and the sample are provided in Appendix D.

Evaluation contexts. To obtain evaluation contexts, we use a held-out portion of the training data, consisting of 38,020 batches of 2,048 contexts of size 2,048 tokens, unseen by the selected checkpoints. From this data, we extract the prefix of the first sequence in each batch that contains the target token, up to a total of 1,000 contexts per target token. Following previous studies (Chang and Bergen, 2022; Carlini et al., 2023) we impose a minimum context length of 20 tokens, resulting in context lengths ranging from 20 to 2047. This choice is also motivated by preliminary experiments in which we observed a high variability in surprisal for contexts shorter than 20 tokens. As contexts are cut and shuffled before training, no position bias is expected (analysis in Appendix E).

Checkpoints. To create training trajectories we measure token surprisal at different checkpoints in model training. For OLMo-1B, 351 checkpoints are available, between step 1,000 and step 700,000. A checkpoint is numbered according to the number of processed batches: checkpoint N is a snapshot of the model after it has seen N batches of 4M tokens. We select a subset of 49 checkpoints, uniformly spaced (every 10,000) between checkpoint 10,000 and checkpoint 700,000, except between checkpoints 117,850 and 330,000, where no checkpoints are available. The final OLMo-1B model corresponds to checkpoint 738,020, but we limit our study to checkpoint 700,000, as the training data seen after this point is used for evaluation. For the 150M model we select the $8\times$ smaller equivalents, that is, the checkpoints between 1,200 and 84,000, every 1200 steps (70 checkpoints in to-

tal). Similarly, for the 40M model, we select the $12\times$ smaller equivalents, that is, 70 checkpoints between 300 and 21,000, every 300 steps.

4 Token Trajectory Experiments

Examples of the learning curves obtained using the procedure described in the previous section are presented in Figure 1. We present the trajectories for 2 randomly-selected tokens in each of 5 frequency ranges (0-10 to 50,000-100,000). To compare models of different capacities, we map training checkpoints for each model onto a scale of 1 to 70, which we term *learning timepoints*. This alignment ensures that models are compared at stages of data exposure that were adjusted by capacity (number of parameters). Under this mapping, the x-axis represents the i-th timepoint rather than checkpoints. Furthermore, we reduce the visual scale of the training curves to highlight trajectory dynamics, resulting in comparable y-axis lengths and scales but differing lower and upper y-axis bounds.

Surprisal at convergence time seems to depend on model size and the type of token. Smaller models seem to start, evolve and converge at higher levels of surprisal. More generally, the value of the surprisal seems to be correlated to the size of the model, imposing a consistent gap between models. The size of the gap also seems correlated to token frequency: infrequent tokens impose larger gaps in surprisal while for frequent ones the gaps are less distinguishable. However, surprisal at convergence time is only partially explained by frequency and model size. An infrequent token such as .",", has a surprisal value similar to the token Ġmore, which is 1000 times more frequent. When looking at a larger range of tokens (Appendix F) we find that infrequent tokens exhibit significantly higher surprisal variance, which progressively compresses as frequency increases. The trajectories in Appendix F also show that while the lower bound of surprisal appears independent of frequency, with low-surprisal tokens present in different frequency ranges, the upper bound decreases as frequency increases. This suggests that while high frequency is not a requirement for low surprisal, it acts as a constraint that limits the average surprisal a token can elicit.

Model scale does not seem to dictate token convergence time. While several curves seem to converge toward the end of training, others appear to continue to decrease, suggesting that fur-

Figure 1: Training trajectories for OLMo-1B, OLMo-150M and OLMo-40M models, for two tokens (in red) per frequency range (in green).

ther learning remains possible. Interestingly, the point of convergence does not appear to follow a uniform pattern dictated by model scale. For infrequent tokens, we observe significant idiosyncratic behavior: for the token Ġ298[2], the two smaller models converge more rapidly than the OLMo-1B model, although at higher surprisals. However, this trend reverses for the token .",", from the same frequency range, where the larger models (150M and 1B) reach an early plateau, while the 40M model continues to improve. In contrast, high-frequency tokens such as Ġclear, Ġmore, and Ġand seem to exhibit much higher consistency across models, with all of them appearing to reach convergence early in the training process. A possible interpretation would be that these discrepancies suggest a potential change in learning priority based on model scale: constrained by their limited parameter budget, smaller models may deprioritize infrequent tokens to focus on the high-frequency vocabulary.

Smaller models seem to transition to a moderate slope slower. The trajectories generally follow power-law dynamics, characterized by a sharp initial descent followed by a transition to a more gradual slope. This change in regime, from rapid initial learning to a moderate slope, seems to occur consistently before the 20th timepoint. This transition appears to be dependent on the size of the model: larger models reach the moderate-slope regime more rapidly, whereas the smallest model (40M) exhibits a more prolonged initial descent before the slope stabilizes. One interpretation of

this regime change might be that models undergo an initial phase of feature acquisition, followed by a phase of refinement. If this holds, our results suggest that smaller models require a longer period of data exposure relative to scale, before progressing to the refinement stage. Conversely, larger models might be more efficient and transition regimes faster.

Building upon these preliminary observations, we address the following research questions:

- How can the time of acquisition (or convergence) of a specific token be formally defined and localized ?

- To what extent does a token's frequency and nature influence its timepoint of convergence?

- To what extent does a token's frequency and nature influence its surprisal at convergence?

- Does model scale influence token convergence time and surprisal value?

5 Empirical Convergence

To formalize the notion of token convergence, we define empirical convergence as follows:

The training curve of a token converges if a sequence of checkpoints can be identified such that it includes the last checkpoint and that there are no significant differences between the mean surprisal values at these checkpoints. We define the **convergence checkpoint** *as the first checkpoint in the sequence and the* **convergence surprisal** *as the mean surprisal at the convergence checkpoint.*

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[2]The "Ġ" character denotes a leading space in BPE tokenization. We keep Unicode placeholder characters such as "Ġ" to match OLMo's vocabulary file and avoid ambiguity.

Methodology. To identify the longest stable sequence, a backwards pairwise comparison is conducted starting from the final checkpoint. The algorithm allows for minor fluctuations as long as they are preceded by a stable plateau. To ensure that these small fluctuations do not add up to a significant gradual shift, we perform a final verification comparing the beginning to the end of the sequence to confirm they remain equivalent. A description of the algorithm is provided in Appendix G.

To establish the equivalence of the mean surprisals of two checkpoints we used a two one-sided t-test (Lakens, 2017). Contrary to a classic t-test that cannot assert equivalence, this procedure permits to establish it (within specified confidence intervals) by showing that the difference between two means is inferior to a provided threshold. This brings about the question of determining the value of the threshold that would best define practical equivalence.

We find that for all models, increasing this equivalence threshold (hereafter named SESOI for smallest effect size of interest) from 0.01 to 0.4 results in a shift from none to all tokens converging. This indicates that during late training, mean surprisal fluctuations are confined to a narrow band, which interestingly, is of the same size across the three models. In the absence of a standardized criterion for selecting a surprisal threshold, the choice of a specific value, such as 0.1 rather than 0.2, depends on the resources available and the purpose of the model. To account for this, we adopt the notation model-x to denote token convergence for a given model under a SESOI threshold of x.

The proposed algorithm is largely robust to variations in hyperparameters, specifically sequence length (L_{seq}), ending sequence (L_{end}), and granularity (Appendix H). Consequently, we set L_{end} and L_{seq} at 3 and 5, respectively, while adopting the finest available granularity corresponding to the selected checkpoints.

Results. The number of converged tokens remains notably consistent across the three models when the hyperparameters of the algorithm are fixed: between 340 and 385 converged tokens for a SESOI of 0.1 and between 500 and 505 for a SESOI of 0.2. This consistency suggests that convergence follows a similar pattern across models, independently of their capacity. While similar numbers of tokens seem to converge in all models, tokens in the smaller 40M model seem to converge later than in the larger models: the histogram of

Figure 2: Histograms of convergence checkpoints, for a SESOI of 0.1 and 0.2, respectively.

Figure 3: Histograms of convergence surprisals, for a SESOI of 0.1 and 0.2, respectively.

convergence checkpoints in Figure 2 shows that the 40M architecture has a peak in the distribution of convergence checkpoints located towards later stages of training compared to its counterparts. We also observe that the stricter threshold value of 0.1 exerts a flattening effect on the distribution. This is expected, as a narrower surprisal band increases sensitivity to noise, thus dispersing the checkpoints at which individual tokens converge.

Convergence surprisal distributions are more uniform than convergence checkpoints (Figure 3). Furthermore, the form of the distributions seems robust to change in the convergence threshold. However, convergence surprisal ranges seem sensitive to model scale, with larger models attaining lower convergence surprisals than their counterparts.

6 Explaining Convergence

Having identified the tokens that converge under our definition and their time of convergence, we proceed to explain convergence based on three independent variables: token estimated frequency, token length, and token nature. We perform two linear regressions, where we explain convergence

Model	40M		150M		1B	
SESOI	0.1	0.2	0.1	0.2	0.1	0.2
λ^*	1.7	1.4	0.6	0.7	1.5	1.3

Table 1: Optimal transformations of the response variable **convergence checkpoint**.

	Partial R^2 (Predictors)			
Model	f	n	l	**Total R^2**
40M-0.1	0.3032	0.1136	0.0275	0.380
40M-0.2	0.3730	0.1685	0.0312	0.468
150M-0.1	0.3233	0.1172	0.0315	0.385
150M-0.2	0.3796	0.1499	0.0529	0.445
1B-0.1	0.2592	0.1473	0.0296	0.353
1B-0.2	0.3438	0.1339	0.0251	0.446

Table 2: Feature importance in explaining convergence checkpoint. Partial R^2 for a feature x represents the proportion of the variation in the convergence checkpoint that is explained by x, which was not already explained by the other variables in the model.

checkpoint and convergence surprisal separately, as two distinct response variables. The independent variables frequency and length are treated as numerical features. The categorical feature, token nature, is modeled using dummy variables, with the category *Word* designated as the reference.

6.1 Convergence Checkpoint

Methodology. Initial data inspection reveals that the relation between frequency and convergence checkpoint seems to follow a power-law, while that between token length and convergence checkpoint seems more noisy and difficult to assess visually. Given these observations, the data does not fulfill the assumptions of linear regression without transformation. To determine the transformations that would best linearize the data, we perform a grid search of transformations on the independent variables and use the Box-Cox method (Montgomery et al., 2012) to find the best transformation of the dependent variable (Appendix I).

Across all model scales and parameters, the optimal transformation for frequency is found to be the logarithm. This suggests that the relationship between frequency and the convergence checkpoint is power-law-driven and invariant to model scale, which aligns with the broader implications of Zipf's Law (Zipf, 1949) regarding the logarithmic nature of word frequency distribution.

Unlike frequency, the optimal transformation for token length is sensitive to model scale and convergence threshold. At a 0.1 threshold, the optimal transformation is consistently logarithmic. At a more permissive 0.2, the influence of length weakens as scale increases. However, since using non-logarithmic transformations amounted to marginal gains for the 40M and 1B models, and to ensure a consistent cross-model comparison, we adopt a unified model with log transformations for both frequency and length.

The optimal transformations for convergence checkpoint vary with model scale (Table 1). While the 40M and 1B models exhibit diminishing returns in convergence checkpoint with an increase in features ($\lambda > 1$), the 150M model shows accelerating returns ($\lambda \approx 0.5$). This suggests that convergence behavior does not follow a linear path as models grow larger, but rather oscillates with model capacity. However, the 1B model results may be less stable due to missing checkpoints.

We model the relation between convergence checkpoint and the independent variables with the linear regression model defined in the equation below.

$$y_i^\lambda = \beta_0 + \beta_1 \ln(f_i) + \beta_2 \ln(l_i) + \sum_{k=1}^{11} \gamma_k N_{ik} + \varepsilon_i$$

The term y_i represents the convergence checkpoint of token i. The power, λ, represents the model-specific optimal power transformation of the checkpoint determined via the Box-Cox method. The f_i and l_i terms denote the frequency and length of the token i. The term N_{ik} represents indicator variables corresponding to the token nature categorical feature. The coefficients γ_k capture category-specific changes in the convergence checkpoint relative to the reference category "Word", and ε_i denotes the error term.

Results. The resulting coefficients of determination (Total R^2) are presented in Table 2. The R^2 values are very similar across models when fixing the convergence threshold to 0.1 (SESOI), suggesting that the features consistently explain between 35% and 38% of the variability in convergence checkpoints, regardless of model size.

When increasing the SESOI threshold, and thus the number of converged tokens, R^2 increases across models. The increase may reflect that, as more converging tokens are observed, the models

Model	y	f		l	
		$\%y$	Δ_y	$\%y$	Δ_y
40M	12.3k	-6.05	-744	-7.68	-944
	14.1k	-4.80	-677	-6.09	-859
	19.8k	-2.69	-534	-3.42	-677
150M	31.2k	-11.63	-3,630	-14.90	-4,650
	39.6k	-10.08	-3,993	-12.92	-5,115
	79.2k	-6.65	-5,268	-8.52	-6,750
1B	340k	-9.01	-30,619	-14.08	-47,884
	420k	-6.56	-27,549	-10.26	-43,083
	660k	-3.33	-21,977	-5.21	-34,368

Table 3: Percentage change in convergence checkpoint ($\%y$) for 100% feature (frequency f and length l) increase. Step deltas (Δ_y) represent the absolute reduction in checkpoints at convergence, when doubling frequency or length. The SESOI threshold is of 0.1.

Model	Stage (Checkpoints)	$\Delta\%$	Steps Δ
40M	Early (12.3k)	-11.58	-1424
	Mid (14.1k)	-9.10	-1282
	Late (19.8k)	-5.03	-996
150M	Early (31.2k)	-27.57	-8602
	Mid (39.6k)	-24.10	-9545
	Late (79.2k)	-16.20	-12,831
1B	Early (110k)	-33.13	-112,651
	Mid (330k)	-23.44	-98,444
	Late (550k)	-11.51	-75,961

Table 4: Relative impact of token nature *Suffix* with respect to reference category *Word* on convergence checkpoints across models. The SESOI threshold is of 0.1.

gain additional information about token behavior, leading to reduced noise and more stable estimates.

Frequency has the highest explanatory power across models (Table 2). For the 40M-0.1 model, frequency uniquely accounts for 80% of the total R^2, while for the 150M model it accounts for 83%. For the 1B model, it accounts for 71% of the total R^2 when the threshold is 0.1, and for slightly less when using the more permissive threshold of 0.2. The second most important feature is token nature, which has a consistent impact across models and thresholds, independently explaining between 28% and 39% of the total R^2 variability in the convergence checkpoint. Token length exhibits limited explanatory power across all models.

Given the non-linear relationship between the features and the target variable, specifically the power-law transformation y^λ, the regression coefficients cannot be interpreted directly. Therefore, to quantify the precise impact of frequency and length on the convergence checkpoint, we calculate the percentage change in the convergence checkpoint relative to a 100% change in the independent variables (details in Appendix J). We evaluate their impact on three types of tokens: early-converging (25th percentile), median-converging, and late-converging (maximum checkpoint). We note that the results are robust to the SESOI threshold, therefore we report only the 0.1 threshold results in Table 3 (complete results in Appendix K).

Discussion The percentage gain in checkpoint convergence ($\%y$) from doubling token frequency is between 3% and 12% across model scales. In terms of percentages, it is the early-convergent tokens that seem to have the highest reduction in number of checkpoints. However, in absolute numbers, the values are comparable among tokens converging at different stages. In other words, having a $2\times$ higher frequency leads to approximately a 10% reduction in the number of checkpoints needed for convergence. This effect is more powerful for early-converging tokens in models 40M and 1B, while for model 150M it is so for late-converging tokens. Perhaps counterintuitively, the effect is more powerful in larger models than in the smaller model, suggesting a higher inertia in smaller models.

While a higher token length yields a comparable gain in convergence checkpoints, this appears to contradict its relatively small explanatory power in our regression models. This discrepancy might stem from the differing scales of the predictors: a 100% increase represents a far more substantial change in the narrow range of token lengths than a twofold increase does within the large range of frequencies.

Token nature also has a definitive impact on convergence checkpoint. To illustrate this aspect, we choose the category *Suffix*, for which we present the results in Table 4 (the complete results are provided in Appendix C). *Suffix* tokens converge sooner than *Word* tokens of mean frequency and length. While this effect is present across all stages, it is most pronounced for early-converging tokens and appears to scale with model capacity, with larger models exhibiting a greater sensitivity to token nature than the 40M variant. As shown in Appendix C, the coefficients are negative for all categories that are significant, indicating that they converge earlier than *Word* tokens, when all else is at the mean. This would suggest that *Word* tokens represent the most difficult category to learn. Other high-impact categories include single-character classes such as *Digit*, *Letter*, and *Subword*. Additionally,

Model	40M		150M		1B	
SESOI	0.1	0.2	0.1	0.2	0.1	0.2
λ^*	0.9	0.9	0.8	0.8	0.6	0.7

Table 5: Optimal transformations of the response variable **convergence surprisal**.

	Partial R^2 (Predictors)			
Model	f	n	l	**Total R^2**
40M-0.1	0.4529	0.4270	0.0229	0.658
40M-0.2	0.4173	0.4209	0.0189	0.603
150M-0.1	0.3427	0.4488	0.0088	0.599
150M-0.2	0.3287	0.4302	0.0065	0.576
1B-0.1	0.3270	0.4500	0.0181	0.573
1B-0.2	0.2785	0.4141	0.0032	0.542

Table 6: Feature importance in explaining **convergence surprisal**. Partial R^2 for a feature x represents the proportion of the variation in the convergence checkpoint that is explained by x, which was not already explained by the other variables in the model.

we observe distinct scaling trends: *Punctuation* only becomes a significant predictor in larger models, while *Numbers* lose significance as model size increases. Finally, the lexical role appears to supersede morphological roles, as the distinction between prefixes and suffixes does not yield a consistent cross-category effect.

6.2 Convergence Surprisal

The optimal feature transformations when explaining convergence surprisal are logarithm for frequency and inverse for token length. While model selection criteria narrowly favored an inverse transformation for token length, we ultimately utilized a logarithmic transformation for both frequency and length to be consistent with the previous analysis.

The optimal lambda values indicate a quasilinear relation between the log-transformed features and convergence surprisal, consistent across LMs (Table 5). Furthermore, lambda seems to decrease by 0.05 every time the model doubles in size, indicating that the optimal lambda parameter might decrease log-linearly with size. In other words, in the larger model of size 1B, the gap in surprisal values between frequent and infrequent tokens is less pronounced than in smaller models. These findings confirm our observations of a consistent gap between models of different sizes.

The features explain a high proportion of variance in convergence surprisal, with R^2 values ranging from 54% to 65% (Table 6). Frequency is a consistent predictor, but its relative contribution decreases as the model grows in size. Token nature, on the other hand, gains in importance, becoming the primary predictor of convergence surprisal in larger models, suggesting that larger architectures are less dependent on raw frequency and more reliant on the intrinsic nature of the token. Interestingly, a consistent set of categories, namely *Digit*, *Letter*, *Suffix*, *Number suffix*, *Delimiter* and *Subword*, are significant and show similar standardized coefficients across model scales and convergence thresholds (Appendix L). This might suggest that convergence surprisal is to an extent token-inherent, independently of the effect of model size.

While the convergence checkpoint can naturally be associated to the moment in training when the token was sufficiently learned, convergence surprisal is difficult to interpret. We might be tempted to interpret it as a measure of performance, of how "well" the token was learned by the model, and the effect of model size supports this interpretation. However, next-word prediction is not deterministic: in many cases multiple tokens are equally valid at a specific position, and it is expected that an appropriate model would reflect this behavior. In other words, even supposing the model was perfect, a context might have two equally valid continuations. At the beginning of training, we cannot know if surprisal is high due to insufficient data or due to some intrinsic characteristics of the token. At convergence, we can suppose that what was to be learned by the model was learned, and that token surprisal rather reflects a token-inherent property, namely the extent to which the token is substitutable for another.

7 Conclusions

In this study we have shown that token-level training trajectories are useful tools for understanding how models learn. We showed that these trajectories follow structured patterns, partly governed by frequency and token nature. Although scaling the model improves both convergence speed and surprisal value, the two behave differently: convergence checkpoint seems to follow a frequency-based 'recipe', while the surprisal reached at convergence seems more inherent to the token's nature. In future work we aim to leverage these findings to develop an efficient learning method that modifies training data to reach token convergence faster.

Limitations

Our analysis focuses on English-trained models to establish token convergence patterns. While the 510 tokens were selected via a stratified sampling method to ensure representation across frequencies and categories, the extent to which these patterns generalize to other languages remains an open question. Future work is required to determine if the conclusions identified here are universal or need to be adapted to specific languages.

We restricted our scope to the OLMo model family to maintain a consistent tokenization strategy. Since token boundaries and therefore their characteristics vary significantly across segmentations, holding the tokenizer constant was a methodological choice meant to ensure that our observations of convergence timepoint and surprisal were functions of model scale rather than confounding segmentation strategies. While this ensures high internal validity, the absolute values of convergence time and surprisal may shift under different tokenization strategies.

The selection of a specific convergence threshold (SESOI) could hinder the generality of our claims. However, the consistency of results across the two thresholds we have investigated (Section 6) shows that our qualitative findings are not dependent on a single arbitrary value.

Ethical considerations

B2. The OLMo-1B model is released under the Apache license 2.0, which permits use of the models. The license for the code and data that we release are present in the repository url we provide in Section 1.

C1. The approximate number of GPU hours was of 20,000 hours on a V100 80GB GPU.

C4. We used spacy version 3.7.2 to determine if a token belongs to the English vocabulary.

E1. Copilot was used as a coding assistant and ChatGPT and Gemini for brainstorming and rephrasing.

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A   Training details of OLMo models

The complete configurations are provided in the Github repository.

Model	# param.	Train (# tokens)	Train (# steps)	Batch size	Context size	Layers	Attn. Heads
OLMo-40M	38M	0.10×10^{12}	24,000	2048	2048	16	16
OLMo-150M	151M	0.35×10^{12}	84,000	2048	2048	12	12
OLMo-1B	1.12B	2.93×10^{12}	700,000	2048	2048	8	8

Table 7: Details on the training of new OLMo models (and existing model OLMo-1B).

B   Frequency estimation

We estimated the frequency of a token in the training data as the average frequency of the token over 500 batches sampled randomly from the first 700,000 batches in the training data of the OLMo-1B model.

To validate these estimates, a pivotal intervals bootstrap (Wasserman, 2004) ($n = 1000$ resamplings, size 250) was performed. Across the 49,955 tokens with non-null frequency, the median 95% confidence interval (CI) width was 1.70 (IQR: 1.05–2.89), with 90% of tokens maintaining CI width inferior to 5. In other words, for a median token, its true frequency falls within a window of size 1.70 centered around the estimate in 95% of cases. We report CI widths statistics in Figure 4 and Table 8. Given that high-frequency tokens skew absolute CI distributions (higher frequencies have higher CI intervals), we also report CI widths relative to the mean in Figure 5 and Table 8. This relative measure shows that for the median token, the true value of the frequency is within $\pm$ 6.5% of the estimate in 95% of cases.

Statistic	95% CI Width	Relative Width
Mean (Std. Dev)	2.78 (6.54)	0.20 (0.29)
Median	1.70	0.13
25th Percentile	1.05	0.08
75th Percentile	2.89	0.22
90th Percentile	5.06	0.37
Maximum	468.23	5.00

Table 8: Descriptive statistics for absolute and relative 95% confidence interval widths across 49,955 tokens.

Figure 4: Histogram of CI widths.

Figure 5: Histogram of CI widths relative to mean frequency.

C Description of token categories.

We define the following 12 token categories. To identify to which category a token belongs, the conditions are verified in the order given below until one is satisfied. For example, a token of nature *suffix* is an alphabetic string that did not validate any previous category. The tokens in the last category, *subword*, are tokens that did not validate any of the previous 11 categories. The examples are given in the format used in the vocabulary file and might contain placeholders, such as $\dot{G}$, the placeholder for the space character " ". We chose this format so that strings can be searched in the vocabulary file of the model.

We considered that a token belongs to the category *Word* if it can be assigned a POS tag. We used the POS tagger provided by spacy version 3.7.2. This approach had better coverage than the list of headwords in nltk version 3.9.1 which we used as comparison. Numerical tokens or punctuations being tagged as words was unlikely to be an issue, given that these categories were checked before. We present the heuristics we used for extraction and examples of tokens from each category in Table 9. To simplify, we indicate whether or not a token is a word as belonging or not to **V**.

Token nature	Conditions	Examples from sample
digit	isdigit, len 1	*0, 1, 2*
number suffix	isdigit	*04, 181, 1981, 830, 76*
number prefix	starts with space, isdigit	*Ġ2002, Ġ122,Ġ349*
delimiter	isspace or contains tab or newline	(23 consecutive spaces), *Ċĉ* (\n and \t)
punctuation	∈ string.punctuation, len 1	*\ or) or / or Ġ,*
punctuation suffix	∈ string.punctuation	*+\ or .\",\" or #{$ or —* (3 dashes)
punctuation prefix	starts with space, ∈ string.punctuation	*Ġ{\ or Ġ= or Ġ- or Ġ[],*
letter	isalpha, len 1	*æīĠ or åĪ¶* (Chinese characters)
prefix	starts with space, isalpha, ∉ V	*ĠFe, Ġvitro, ĠRS, ĠÃ§, Ġfacto, ĠR*
word	starts with space, isalpha, ∈ V	*ĠHar, Ġsolved, ĠCycle, ĠVideo*
suffix	isalpha	*correct, amic, rangian, inject, aving*
subword	OTHER	*à®* (sequence of bytes)

Table 9: Description and examples of **token nature** categories.

D Additional information on tokens distribution.

Comparative histograms of the 50,280 tokens in the OLMo vocabulary and the 510 token sample on frequency range, token nature and token length are given in Figures 6, 7 and 8.

Figure 6: **Left:** Histogram of token counts by frequency range for all tokens in the vocabulary. **Right:** for the 510 token sample.

Figure 7: **Left:** Histogram of token counts by token nature for all tokens in the vocabulary. **Right:** for the 510 token sample.

Figure 8: **Left:** Histogram of token counts by token length for all tokens in the vocabulary. **Right:** for the 510 token sample.

E Average token position in context

The contexts are sampled from held-out training data, that has already been arranged into batches of random contexts of length 2048 tokens. The position of the target token in context ranges therefore between 20 (the minimum context size we imposed) and 2047, the context window minus the target token. If the documents composing the training data were split according to sentence or paragraph boundaries, we might expect a position bias to emerge, that is, some tokens to appear primarily in a specific absolute position. For example, a pronoun would appear primarily in the first position in a sentence, leading to a smaller average than less syntactically-constrained tokens. However, as the data comes from training batches, it is not split according to sentence boundaries, but it is split in contiguous chunks of 2048 tokens and shuffled randomly, making contexts extend beyond sentence, paragraph and document boundaries. We thus expect the position bias to be mitigated.

We analyze the mean position per token by computing the mean length of the 1000 contexts for each token. As shown in Figure 9, the average positions of tokens form a tight cluster around the mean cross-token position of 1034.4, closely aligning with the theoretical midpoint of 1033.5 = (20 + 2047)/2, suggesting that tokens are uniformly distributed throughout the context window. While individual token occurrences are broadly distributed ($\sigma = 594$), the mean positions across the sample are highly consistent, varying by only 1.8% ($SD_{\bar{x}} = 18.55$).

Figure 9: Scatter plot of the average position vs. standard deviation of the position for the 510 tokens.

F Trajectories for a larger range of tokens

In Figures 10, 11 and 12, we plot 8 tokens per frequency range for each of the 3 models (in order OLMo-40M, OLMo-150M and OLMo-1B), as well as the average surprisal and standard deviation among the total 510 tokens.

Figure 10: Training trajectories of different tokens and the per-frequency average curve and standard deviation for model **OLMo-40M**.

Figure 11: Training trajectories of different tokens and the per-frequency average curve and standard deviation for model **OLMo-150M**.

Figure 12: Training trajectories of different tokens and the per-frequency average curve and standard deviation for model **OLMo-1B**.

G   Convergence Algorithm

Algorithm 1: Token-wise Convergence Detection

Input   : tokens $\mathcal{T} = \{t_1, \ldots, t_n\}$, checkpoints $\mathcal{C} = \{c_1, \ldots, c_m\}$, surprisals
              $\mathcal{S} = \{s_1, \ldots, s_m\}$

Output   : convergence status, convergence checkpoint c^*, convergence surprisal s^*

Parameters : L_{end} (Min. ending plateau length), L_{seq} (Min. total sequence length)

Constants : L_{min} (Min. plateau length) = 2

---

1 foreach *token $t \in \mathcal{T}$* **do**

2      $\mathcal{P}_t \leftarrow \emptyset$;   // List of plateaus for token t

3      $S_{curr} \leftarrow [c_1]$;   // Current sequence

      // Identify plateaus

4   **for** $i \leftarrow 2$ **to** m **do**

5   **if** is_equivalent*(c_{i-1}, c_i)* **then**

6   Append c_i to S_{curr};

7   **else**

8   **if** $|S_{curr}| \geq L_{min}$ **then**

9   Add S_{curr} to $\mathcal{P}_t$;

10            $S_{curr} \leftarrow [c_i]$;   // Reset sequence to current checkpoint

      // Check the final sequence

11   **if** $|S_{curr}| \geq L_{min}$ **then**

12   Add S_{curr} to $\mathcal{P}_t$;

      // Evaluate Convergence

13      $\mathcal{P}_{end} \leftarrow$ last plateau of $\mathcal{P}_t$;

14      $\mathcal{S}_{res} \leftarrow$ concatenate all $c \in \mathcal{P}_t$;

15   **if** $|\mathcal{P}_{end}| \geq L_{end}$ ***and*** $|\mathcal{S}_{res}| \geq L_{seq}$ ***and*** $c_m \in \mathcal{S}_{res}$ **then**

16         $c^* \leftarrow$ first element of $\mathcal{S}_{res}$;

17         $s^* \leftarrow \frac{1}{|\mathcal{S}_{res}|} \sum s \in \mathcal{S}_{res}$;   // Mean surprisal of resulting sequence

18   **return true**, c^*, s^*;

19 return false, none, none;

Algorithm 2: Checkpoint Equivalence with TOST for Paired Samples

Used as is_equivalent(c_i, c_j)

Input : paired surprisals $\mathcal{X}_i = \{x_1, \ldots, x_n\}$, $\mathcal{Y}_j = \{y_1, \ldots, y_n\}$ (the surprisal values of checkpoints c_i and c_j on n evaluation items), smallest effect size of interest (SESOI) δ, significance level α

Output : p-values (p_1, p_2)

// Compute paired differences
1 **for** $i \leftarrow 1$ **to** n **do**
2     $d_i \leftarrow y_i - x_i$;
3 $n \leftarrow |\{d_i\}|$;

// Compute summary statistics
4 $\bar{d} \leftarrow \frac{1}{n}\sum_{i=1}^{n} d_i$;   // Mean difference
5 $s_d \leftarrow \sqrt{\frac{1}{n-1}\sum_{i=1}^{n}(d_i - \bar{d})^2}$;   // Sample std. dev.
6 $\text{SE} \leftarrow s_d/\sqrt{n}$;   // Standard error
7 $\text{df} \leftarrow n - 1$;
  ;   // Degrees of freedom

// Compute TOST statistics
8 $t_1 \leftarrow (\bar{d} + \delta)/\text{SE}$;   // Test $\mu_d > -\delta$
9 $p_1 \leftarrow 1 - \text{CDF}(t_1, \text{df})$
10 $t_2 \leftarrow (\bar{d} - \delta)/\text{SE}$;   // Test $\mu_d < \delta$
11 $p_2 \leftarrow \text{CDF}(t_2, \text{df})$

// Decide equivalence
12 **if** $p_1 < \alpha$ **and** $p_2 < \alpha$ **then**
13   **return** *true*
14 **return** *false*

H   Convergence parameters

We study how the parameters of the convergence algorithm, ending plateau length L_{end}, sequence length L_{seq}, effect size SESOI and α, as well as the input checkpoints granularity affect the outcome number of converged tokens.

H.1   SESOI, L_{min}, L_{seq}

To identify the impact of these parameters on the number of convergent tokens, we conducted a sensitivity analysis using the OLMo-1B model at the 700,000-step checkpoint. While holding the model architecture and final checkpoint constant, we varied the following variables:

- checkpoint granularity: 1) every 10,000 checkpoints (49 checkpoints), 2) every 20,000 checkpoints (24) and 3) every 50,000 checkpoints (10)

- $L_{end} \in \{2, 3, 4\}$

- $L_{seq} \in \{3, 4, 5\}$

- SESOI $\in \{0.01, 0.05, 0.1, 0.15, 0.2, 0.3, 0.4\}$

We plot the resulting number of converged tokens for each configuration in Figure 13. As expected, the effect size (SESOI) parameter is the primary determinant of the output. Increasing the parameter from 0.01 to 0.4 results in a shift from none to all tokens converging in all configurations. Additionally, the results seem robust with respect to the checkpoints granularity. Halving the number of checkpoints, by

Figure 13: Number of converged tokens depending on convergence parameters SESOI, L_{end} and L_{seq} and input checkpoints granularity (step) for the OLMo-1B model.

increasing the granularity from 10,000 (49 checkpoints) to 20,000 (24 checkpoints), results in overlapping curves. At 50,000, the number of converging tokens is consistently lower, but the small number of resulting checkpoints (10) may affect the results. Finally, the parameters L_{end} and L_{seq} seem to have little influence on the curves. As a result, we fix henceforth L_{end} and L_{seq} to 3 and 5, and the granularity to 10,000, for more precision. There is no absolute way to decide on the SESOI value. Whether the threshold for convergence should be a mean surprisal value of 0.1 instead of 0.2, for example, depends on the resources available and the purpose of the model.

H.2 Final checkpoint

Figure 14: Number of converged tokens at different checkpoints, depending on effect size SESOI for OLMo-40M, 150M and 1B, respectively.

The convergence detection algorithm operates by evaluating each intermediate checkpoint against a 'final' checkpoint of the model. Because this approach defines convergence relative to the last provided

checkpoint, the selection of the final training step may affect the output. Following the parameters established in Subsection H.1, we utilized a sequence length (L_{seq}) of 5 and a threshold (L_{end}) of 3 and a granularity of 10,000 for OLMo-1B. To account for varying training scales, we set the corresponding granularity to 1,200 for OLMo-150M, and 300 for OLMo-40M.

To determine how the choice of the final checkpoint affects convergence detection, we varied the final checkpoint for each model. The checkpoints were sampled at seven equal intervals based on model-specific granularity: $300i$ for OLMo-40M, $1,200i$ for OLMo-150M, and $10,000i$ for OLMo-1B, where $i \in \{1, 2, \ldots, 7\}$. We also varied the SESOI value across the following values $\{0.01, 0.05, 0.1, 0.15, 0.2, 0.3, 0.4\}$.

The results are reported in Figure 14. Convergent tokens counts generally exhibit an upward trajectory, following the intuition that more and more tokens converge as training progresses. One exception is the model OLMo-150M, for which we observe that the final number of converged tokens seems to be attained early, around checkpoint 40,000-50,000. Across all three models, the lower boundary (SESOI = 0.01) consistently yields zero converged tokens, confirming that this threshold is too restrictive for practical convergence detection. In contrast, the higher boundary changes during training and across models, suggesting a refinement process is taking place. For model OLMo-1B, a permissive 0.4 threshold leads to 96% token convergence at checkpoint 100,000, however, by checkpoint 700,000, a significantly stricter 0.2 threshold leads to a similar proportion of 98% of tokens converging.

I Transformations for predicting checkpoint

In this section we detail the methodology used to find the optimal transformations that linearize the data in order to apply linear regression. We perform a grid-search of transformations on the independent variables and use the Box-Cox method (Montgomery et al., 2012) to find the best transformation of the dependent variable. We test several candidate transformations t of the independent variables: square root, logarithmic, multiplicative inverse and identity. For the dependent variable, we cannot directly apply transformations, as the error metrics, which are computed on the dependent variable, will no longer be comparable due to the resulting changes in scale. To counter this issue, the Box-Cox method first normalizes the transformed dependent variable by the geometric mean and then computes the error metrics (Eq. 1 and 2). This procedure ensures that the residual sum of squares error metric (RSS) values are scale-invariant and allows for a valid comparison of model fit across the range of transformations. We tested 41 power values for the dependent variable (λ) between -2 and 2, corresponding to multiplicative inverse ($\lambda = -1, \frac{1}{y}$), log ($\lambda = 0$), linear ($\lambda = 1, y^1$), square root ($\lambda = 0.5, \sqrt{y}$), quadratic ($\lambda = 2, y^2$) and other transformations corresponding to power values in between.

$$y^{(\lambda)} = \begin{cases} \frac{y^{\lambda} - 1}{\lambda \cdot \dot{y}^{\lambda-1}} & \text{if } \lambda \neq 0 \\ \dot{y} \ln(y_i) & \text{if } \lambda = 0 \end{cases} \qquad (1)$$

where $\dot{y}$ represents the geometric mean of the dependent variable y, defined as:

$$\dot{y} = \exp\left(\frac{1}{n}\sum_{i=1}^{n}\ln(y_i)\right) \qquad (2)$$

For each model scale and SESOI parameter, we apply each of the four transformations t to frequency and length and each of the 41 Box-Cox transformations (given by λ values $\in \{-2, 2\}$) to the checkpoint variable while normalizing by the geometric mean. We compute the standardized RSS values for each of the 656 transformations and select the frequency and length transformations as well as the λ value for the convergence checkpoint that minimizes the RSS.

J Interpreting results as elasticity

Given the non-linear relationship between the features and the target variable, specifically the power-law transformation y^{λ}, the regression coefficients cannot be interpreted directly. To provide a more intuitive

measure of feature importance, we calculate the point elasticity ($\epsilon = \frac{\%\Delta y}{\%\Delta x}$). This represents the predicted percentage change in the convergence checkpoint y resulting from a 1% change in a given feature x. By applying the partial derivative with respect to either one of the features (denoted as x) to both sides of the equation in (6.1), we obtain the equation in (3). We replace (3) in the elasticity equation and obtain (4). Given a $\%\Delta x$ change in x, the resulting $\%\Delta y$ is the elasticity ϵ multiplied by the change in x. The elasticity for the numeric features does not depend on the value of x, but does depend on the value of y, that is, tokens that converge early have a different behavior than tokens that converge late.

$$\frac{\partial y}{\partial x} = \frac{\beta}{x\lambda y^{\lambda-1}} \tag{3}$$

$$\epsilon_x = \frac{\%\Delta y}{\%\Delta x} = \frac{\partial y}{\partial x}\frac{x}{y} = \frac{\beta}{x\lambda y^{\lambda-1}}\frac{x}{y} = \frac{\beta}{\lambda y^\lambda} \tag{4}$$

Given that token nature is not a numeric variable, we cannot compute elasticity. We will compute instead the percentage change in convergence checkpoint when switching from the reference category (the category 'Word') to one of the other token natures (such as 'Suffix', 'Digit' etc.). We define relative change of the category k w.r.t the reference category as shown in (5). We replace y_k using the regression formula (6.1) and obtain (6), where we note the other features with their coefficients and the intercept as Base, to simplify. We replace back Base as y_{ref}^λ (the reference category has a γ of 0) and obtain (7).

$$\Delta y_{\text{rel}} = \frac{y_k - y_{\text{ref}}}{y_{\text{ref}}} \tag{5}$$

$$\Delta y_{\text{rel}} = \frac{y_k}{y_{\text{ref}}} - 1 = \frac{(\text{Base} + \gamma_k)^{1/\lambda}}{(\text{Base})^{1/\lambda}} - 1 = \left(1 + \frac{\gamma_k}{\text{Base}}\right)^{1/\lambda} - 1 \tag{6}$$

$$\Delta y_{\text{rel}} = \left(1 + \frac{\gamma_k}{y_{\text{ref}}^\lambda}\right)^{1/\lambda} - 1 \tag{7}$$

K   Checkpoint further details

We report the complete results on the impact of frequency and token length in Table 3. Additionally, we report the results of the impact of different token natures (*Digit*, *Letter*) in Tables 11-15.

Model	Token	Ckpt (y)	$\%\Delta y_f$	Steps Δ_f	$\%\Delta y_l$	Steps Δ_l
40M-0.1	9	12,300	-6.05	-744	-7.68	-944
40M-0.1	IST	14,100	-4.80	-677	-6.09	-859
40M-0.1	isle	19,800	-2.69	-534	-3.42	-677
40M-0.2	OME	9,300	-7.50	-697	-7.86	-731
40M-0.2	Template	10,800	-6.08	-657	-6.37	-688
40M-0.2	Ġ$("#	17,700	-3.04	-539	-3.19	-565
150M-0.1	*[9spaces]*	31,200	-11.63	-3,630	-14.90	-4,650
150M-0.1	1	39,600	-10.08	-3,993	-12.92	-5,115
150M-0.1	Ġlibr	79,200	-6.65	-5,268	-8.52	-6,750
150M-0.2	4	20,400	-12.24	-2,497	-17.30	-3,529
150M-0.2	Bal	26,400	-10.22	-2,698	-14.44	-3,813
150M-0.2	Ġ}\	72,000	-5.06	-3,645	-7.16	-5,152
1B-0.1	1	340,000	-9.01	-30,619	-14.08	-47,884
1B-0.1	Ñİ	420,000	-6.56	-27,549	-10.26	-43,083
1B-0.1	åıÍ	660,000	-3.33	-21,977	-5.21	-34,368
1B-0.2[3]	Ġgrow	330,000	-9.15%	-30,199	-8.85%	-29,217
1B-0.2	Ġgenotypes	550,000	-4.71%	-25,909	-4.56%	-25,065

Table 10: Shift in checkpoint (y) for 100% feature increase. Step deltas represent the absolute reduction in training steps at convergence, when doubling frequency ($\%\Delta y_f$) or length ($\%\Delta y_l$).

Model	Stage (Steps)	Δ%	Steps Δ
40M-0.1	Early (12.3k)	-35.77	-4400
	Mid (14.1k)	-27.36	-3858
	Late (19.8k)	-14.61	-2892
150M-0.1	Early (31.2k)	-37.77	-11783
	Mid (39.6k)	-33.15	-13127
	Late (79.2k)	-22.47	-17796

Table 11: Impact of **Letter** token nature on convergence checkpoints relative to Word tokens across model scales.

Model	Stage (Steps)	Δ%	Steps Δ
40M-0.1	Early (12.3k)	-21.96	-2701
	Mid (14.1k)	-17.08	-2408
	Late (19.8k)	-9.31	-1844
150M-0.1	Early (31.2k)	-30.52	-9522
	Mid (39.6k)	-26.71	-10578
	Late (79.2k)	-18.00	-14253

Table 12: Impact of **Digit** token nature on convergence checkpoints relative to Word tokens different model scales.

Model	Stage (Steps)	Δ%	Steps Δ
40M-0.1	Early (12.3k)	-11.57	-1423
	Mid (14.1k)	-9.09	-1281
	Late (19.8k)	-5.03	-995
150M-0.1	Early (31.2k)	-21.51	-6711
	Mid (39.6k)	-18.76	-7430
	Late (79.2k)	-12.55	-9943

Table 13: Impact of **Number Prefix** token nature on convergence checkpoints across models and thresholds.

Model	Stage (Steps)	Δ%	Steps Δ
40M-0.1	Early (12.3k)	-15.75	-1937
	Mid (14.1k)	-12.32	-1738
	Late (19.8k)	-6.78	-1342
150M-0.1	Early (31.2k)	-37.91	-11827
	Mid (39.6k)	-33.27	-13177
	Late (79.2k)	-22.56	-17866
1B-0.1	Early (110k)	-27.66	-94033
	Mid (330k)	-19.68	-82664
	Late (550k)	-9.72	-64170

Table 14: Impact of **Number Suffix** token nature on convergence checkpoints across models and thresholds.

Model	Stage (Steps)	Δ%	Steps Δ
40M-0.1	Early (12.3k)	-15.21	-1871
	Mid (14.1k)	-11.91	-1680
	Late (19.8k)	-6.56	-1298
150M-0.1	Early (31.2k)	-20.50	-6397
	Mid (39.6k)	-17.88	-7080
	Late (79.2k)	-11.95	-9467

Table 15: Impact of **Delimiter** token nature on convergence checkpoints across models.

L   Surprisal further details

We report the standardized coefficients for the features involved in predicting convergence surprisal in Table 16.

Predictor	40M-0.1	40M-0.2	150M-0.1	150M-0.2	1B-0.1	1B-0.2
Obs.	385	505	379	500	340	500
R^2	0.641	0.603	0.599	0.576	0.573	0.542
Adjusted R^2	0.629	0.593	0.585	0.565	0.556	0.529
Numeric Features						
Frequency	-0.682	-0.643	-0.566	-0.557	-0.581	-0.507
Token Length	-0.166	-0.150	—	—	-0.164	—
Character Types						
Digit	-0.186	-0.169	-0.151	-0.148	-0.163	-0.126
Letter	-0.261	-0.318	-0.303	-0.285	-0.339	-0.273
Punctuation	—	—	—	—	—	—
Affixes						
Prefix	—	-0.061	—	—	—	—
Suffix	-0.532	-0.561	-0.561	-0.583	-0.616	-0.584
Num. Pref.	—	—	—	—	—	—
Num. Suff.	-0.152	-0.144	-0.114	-0.106	-0.085	—
Punct. Pref.	—	—	—	—	—	—
Punct. Suff.	—	—	—	—	—	—
Other						
Delimiter	-0.214	-0.233	-0.268	-0.249	-0.241	-0.201
Subword	-0.353	-0.316	-0.279	-0.275	-0.308	-0.247

Table 16: Standardized regression coefficients (β^*) across model scales and thresholds. Negative values indicate lower convergence surprisal.