Mitigating Deceptive Behaviour in Large Language Models through Alignment and Unlearning Interventions

Abstract

As large language models (LLMs) and agents become more intelligent, deceptive behaviours pose a growing alignment challenge under conflicting objectives, particularly in high-stakes tasks. A fundamental question to guide future research is whether such behaviours in LLMs can be unlearned, and how? In this paper, we provide empirical evidence from a systematic study of alignment and unlearning interventions across multiple model families. We measure response-level honesty, standard capability, situational/self-awareness behaviour, and reasoning-mode robustness. We find that supervised fine-tuning and knowledge distillation most consistently reduce deceptive responses, while representation misdirection for unlearning can be highly effective but remains architecture-dependent. In tested reasoning settings, explicit reasoning often reduces honesty by shifting failures toward Qualified Compliance, where models recognize the conflict but fail to reject the deceptive objective. Overall, deceptive responses are not resolved by capability or behavioural suppression alone: robust mitigation requires both conflict recognition and sufficient alignment pressure to convert that recognition into honest refusal. This suggests that future deception mitigation needs to move beyond aggregate honesty rates and provide diagnostic signals that help distinguish capability-related reasoning failures from insufficient alignment.

1 Introduction

As large language models (LLMs) become more intelligent and autonomous, their potential risks are shifting from simple capability failures toward harms deeply rooted in their increasing intelligence. LLMs have been widely used in settings where users rely on them not only for fluent answers, but for faithful ones (Liu et al., 2024a). In such settings, a central risk is not merely that a model makes a mistake, but that it produces answers that satisfy an apparent task objective while bearing hidden objectives. Recent work has shown that frontier models can exhibit deceptive or strategically misleading behaviour when faced with conflicting incentives, pressure to succeed, or opportunities to exploit ambiguity (Scheurer et al., 2023; Meinke et al., 2025). In prior agentic evaluations, such behaviour has manifested as models hiding rule violations and lying to supervisors after simulated insider trading, attempting to evade oversight or shutdown, and strategically complying with harmful requests to avoid being modified by future training (Scheurer et al., 2023; Greenblatt et al., 2024). Prevention of such phenomena has been a key target of initiatives such as LawZero (Bengio et al., 2025) and METR (METR, 2026). Yet a key practical question remains unresolved: can existing alignment and unlearning interventions reduce such deceptive behaviour while preserving standard capability, or do apparent gains reflect broader behavioural shifts rather than targeted mitigation?

We measure deception by asking whether a model behaves honestly when honesty conflicts with another goal. The existing framing (Huang et al., 2025) allows us to evaluate mitigation directly at the response level and to ask which interventions better mitigate deception while preserving model capability. Alignment interventions shape model behaviour through different training signals: supervised fine-tuning (SFT) (Ouyang et al., 2022) provides supervised alignment, preference optimization (PO) (Rafailov et al., 2023) optimizes preferences over aligned and misaligned responses, and knowledge distillation (KD) (Hinton et al., 2015) transfers aligned behaviour from a teacher model. Reward-based interventions such as reinforcement learning (RL) (Bai et al., 2022) optimize behaviour using a learned reward signal. In contrast, unlearning interventions aim to suppress undesirable capabilities or response patterns: gradient ascent unlearning (GA) (Eldan and Russi-

Figure 1: Overview of our main findings. (a) Alignment and unlearning interventions differ in honesty gains and utility preservation. (b) Explicit reasoning can reduce honesty when alignment is weak, but stronger interventions better preserve or improve honesty under reasoning. (c) Response-category analysis shows that reasoning often shifts failures toward Qualified Compliance (QC), where the model recognizes conflict but still complies.

novich, 2023) and task-vector editing (TV) (Il-harco et al., 2023) apply suppression-based updates, while representation misdirection for unlearning (RMU) (Dang et al., 2025) and Locate-then-Unlearn (LTU) target representations or layers directly (Liang et al., 2024).

The literature leaves three key gaps. First, most studies establish that deceptive behaviour can emerge, but do not systematically test whether it can be mitigated by existing post-training interventions. Second, unlearning interventions have largely been evaluated on memorized knowledge (Shi et al., 2025), harmful content (Liu et al., 2024b), or specific capabilities (Liu et al., 2025), rather than on deception as a response-level behaviour. Third, although prior work has shown that scale and reasoning can affect deception-relevant abilities (Greenblatt et al., 2024; Park et al., 2024), their role in response-level deception mitigation remains unclear. Unlike these prior studies, our focus on response-level deception asks not only whether greater capacity comes with increased deceptive-related capabilities, but whether it helps or hinders the model's ability to choose the honesty objective over a competing prompt-induced objective. We address these gaps through a cross-model study that combines intervention-based mitigation with capability-related probes. Specifically, we evaluate eight alignment and unlearning interventions to test which methods reduce response-level deception and whether apparent honesty gains reflect targeted mitigation or broader behavioural side effects. We further examine scale and explicit reasoning to ask whether capability-related changes help models resolve goal conflict honestly, or instead change the form of deceptive failure.

We find that across model families, SFT and KD provide the most consistent mitigation, while RMU is effective but architecture-dependent. These gains do not mainly reflect broad capability collapse. In Qwen models, capability-related factors affect deception in different ways; larger models are more honest under goal conflict, but explicit reasoning often reduces honesty by shifting failures toward Qualified Compliance (QC), where the model recognizes the conflict but still follows the deceptive objective. We call this a capacity–alignment gap; conflict recognition does not reliably become honest refusal without sufficiently strong alignment.

As shown in Figure 1, our contributions are:

- We provide a cross-model evaluation of eight alignment and unlearning interventions, showing that deceptive responses can be reduced without broad capability collapse, though success depends on intervention type and architecture.

- Through a thinking versus non-thinking inference comparison on Qwen3-4B, we show that explicit reasoning can reduce honesty when alignment is weak, whereas stronger interventions such as SFT, KD, and RMU better preserve or improve honesty under reasoning.

- We identify QC as a key failure mode: models may recognize a conflict while still producing output aligned with the deceptive objective. This reveals a capacity–alignment gap that is obscured by aggregate honesty scores alone.

2 Related Work

Deceptive and context-dependent behaviour. LLMs can exhibit deceptive, strategically adaptive, or oversight-sensitive behaviour under conflicting objectives, hidden triggers, or deployment-like conditions (Meinke et al., 2025; Cundy and Gleave, 2025; Greenblatt et al., 2024; Hubinger et al., 2024). DeceptionBench (Huang et al., 2025) provides a response-level benchmark for evaluating whether models follow an honesty objective under conflicting-objective prompts. Similarly, test-

ing models for situational awareness, defined as a model's knowledge of itself and its circumstances (which can be exploited for deception), is the focus of benchmarks such as the Situational Awareness Dataset (SAD). There, this idea is operationalized through diagnostics covering model-related knowledge, influence, deployment-stage distinctions, and oversight-sensitive contexts (Laine et al., 2024).

Prior work also links capability to deception, but not monotonically. Hagendorff (2024) shows that deception-relevant abilities, such as false-belief reasoning and inducing misleading beliefs, emerge in capable models. In agentic settings, these abilities can support realized deceptive behaviour under goal conflict: Scheurer et al. (2023) show an LLM agent concealing insider trading under performance pressure, and other work reports similar in-context scheming behaviour (Meinke et al., 2025). Thus, capability may provide the means for deception, while goal conflict creates conditions under which deceptive behaviour becomes useful. It remains unclear how capability affects whether models produce deceptive responses under goal conflict.

Alignment and unlearning interventions. Alignment interventions aim to steer model outputs toward desired behaviour through supervised demonstrations, preference or reward optimization, and distillation (Ouyang et al., 2022; Bai et al., 2022; Rafailov et al., 2023). Machine unlearning interventions aim to suppress or remove undesirable knowledge, capabilities, or behaviours (Bourtoule et al., 2021; Geng et al., 2025). Relevant approaches include gradient-ascent unlearning, task-vector editing (Ilharco et al., 2023), layer-localized unlearning, and representation-level interventions such as RMU (Dang et al., 2025). We compare these intervention families under a shared deception-mitigation protocol to test whether existing alignment and unlearning approaches can mitigate deceptive responses while preserving general capability.

3 Methodology

3.1 Problem Formulation

We formulate deception as response-level behaviour under conflicting objectives following Huang et al. (2025). For each prompt x, the benchmark provides an ethically aligned ground-truth response, which we treat as the honesty objective $g_h(x)$. The scenario context induces a competing deceptive objective $g_d(x)$ through motivations, pressures, rewards, or instructions that encourage

an answer inconsistent with honesty. Unlike prior work that primarily uses this setup to detect or benchmark deceptive behaviour, we use it to study whether post-training interventions can change the model's response behaviour under conflict.

Let m denote a base model, let $\mathcal{A}$ denote the set of intervention adapters, let $a \in \mathcal{A}$ denote a particular adapter, and let $\tau \in \{T, N\}$ denote an inference mode denoting explicit thinking (T) or non-thinking (N). Given a prompt x, the model produces an output

$$y = f_m(x; a, \tau).$$

We define an honesty indicator $h(x, y) \in \{0, 1\}$ as

$$h(x, y) = \mathbf{1}\big[J(g_h(x), y) > J(g_d(x), y)\big],$$

where $J(g, y)$ denotes the alignment of the final answer y with objective g. Thus, $h(x, y) = 1$ when y aligns more strongly with $g_h(x)$ than with $g_d(x)$, and $h(x, y) = 0$ otherwise. For $\tau = T$, $h(x, y)$ is determined from the final answer rather than from the reasoning trace.

Thus, mitigation asks if a shifts the model's response away from $g_d(x)$ and toward $g_h(x)$.

3.2 Evaluation Objective and Pipeline

Our objective is to evaluate whether alignment and unlearning interventions shift model responses away from the prompt-induced deceptive objective $g_d(x)$ and toward the benchmark-specified honesty objective $g_h(x)$, while preserving standard capability. Our evaluation pipeline applies each intervention to a base model and evaluates it along three axes: response-level honesty, standard capability, and situational/self-awareness (SSA) behaviour. We additionally investigate robustness under reasoning mode and provide a more detailed failure analysis by categorizing model responses.

3.3 Mitigation and Behaviour Comparison

We distinguish deception mitigation from broader behavioural degradation. A higher honesty score is only informative if it does not simply result from a weaker or less responsive model. To rule out broad capability collapse, we test whether an intervention preserves math reasoning and broad knowledge performance. Additionally, we monitor SSA behaviour as a risk diagnostic, because a reduction in deception may coincide with changes in how the model handles context-sensitive prompts outside the target deception benchmark.

3.4 Reasoning-Mode Comparison

Motivated by the ambiguity between capability and deception discussed in Section 2, we treat model scale and inference-time reasoning as capability-related probes. The model-scale comparison tests whether response-level deception changes as model size increases, while the reasoning-mode comparison tests whether it changes when τ shifts from N to T by comparing $f_m(x; a, T)$ and $f_m(x; a, N)$. These analyses evaluate the relationship between deception and capability.

3.5 Response-Level Behavioural Analysis

Aggregate honesty scores do not fully explain how an intervention changes model behaviour. A model may refuse, answer directly without acknowledging the conflict, or acknowledge the conflict while still providing a substantive answer. These response forms are distinct from the final honesty judgment: each category can contain responses scored as honest or deceptive depending on whether the final answer aligns with $g_h(x)$ or $g_d(x)$. To distinguish response strategy from honesty, we categorize responses into three response forms:

- **Direct Refusal (DR):** y refuses to pursue $g_d(x)$ without providing a substantive answer.
- **Direct Compliance (DC):** y provides a substantive answer without explicitly acknowledging the conflict between $g_d(x)$ and $g_h(x)$.
- **Qualified Compliance (QC):** y acknowledges the conflict or includes a disclaimer, but still provides a substantive answer.

4 Experimental Setup

Benchmarks and Metrics We use Deception-Bench (DecBench) (Huang et al., 2025) to measure response-level honesty under conflicting objectives, GSM8K (Cobbe et al., 2021) to evaluate mathematical reasoning, and MMLU (Hendrycks et al., 2021) to assess broad knowledge capabilities. We also evaluate SAD-mini (Laine et al., 2024), a reduced Situational Awareness Dataset (SAD) diagnostic with five components: `facts_human_defaults`, `facts_llms`, `influence`, `stages_full`, and `stages_oversight`. Following the SAD framing of situational awareness as a model's knowledge of itself and its circumstances, we refer to these results as SSA behaviour because the components probe model identity, model-related knowledge, influence, deployment-stage distinctions, and oversight-sensitive contexts. The component-level results and invalid counts appear in Appendix A.1.

In the tables, we report each benchmark's native scoring metric. For GSM8K and MMLU, we report standard accuracy. For DecBench, a prediction is considered correct if the response is judged honest. We define this aggregate response-level honesty rate for a given model m, intervention a, and inference mode $\tau \in \{T, N\}$ as:

$$H(m, a, \tau) = \frac{1}{N} \sum_{i=1}^{N} h(x_i, f_m(x_i; a, \tau)).$$

SAD-mini uses a benchmark-specific scoring rule and invalid-response handling, which we report unchanged:

$$\text{SAD} = \frac{C + p_{\text{rand}} \cdot I}{C + W + I},$$

where C, W, and I denote the number of correct, incorrect, and invalid predictions, respectively, and p_{rand} is the probability of answering correctly by random guessing. Thus, invalid predictions receive partial credit equal to random-chance performance.

Training and Evaluation Data All interventions are trained on the security-domain split of Emergent Plus (TruthfulAI, 2025) and evaluated on DecBench (Huang et al., 2025). The training and evaluation datasets differ in source, prompt format, and behavioural objective: Emergent Plus provides security-domain intervention data, whereas DecBench tests whether responses align with an ethically grounded target answer rather than the deceptive goal induced by the scenario. We therefore treat this setup as an out-of-distribution behavioural transfer test (Yang et al., 2023; Yuan et al., 2023), reducing the likelihood that gains reflect memorization or dataset-specific cues.

Interventions We compare the eight interventions introduced above under a shared protocol. SFT trains on aligned target responses, and KD distills aligned behaviour from the corresponding SFT model. PO optimizes aligned responses over misaligned alternatives, while RL optimizes behaviour using a learned reward model. GA maximizes loss on misaligned responses, and TV applies a negatively scaled adapter trained on misaligned behaviour. LTU uses SFT-style training but restricts updates to behaviour-relevant layers, while RMU aims to suppress target behaviour through activation-level representation steering.

Unless otherwise specified, interventions are trained for one epoch. GA is limited to 10 optimization steps because longer training was unstable in our preliminary runs, consistent with prior work showing that direct gradient ascent is prone

			Alignment				Unlearning			
Model	**Dataset**	**Base**	**SFT**	**KD**	**PO**	**RL**	**RMU**	**LTU**	**GA**	**TV**
Qwen3.5-4B	DecBench	0.852	**0.979**	0.950	0.910	0.911	0.955	0.894	0.904	0.823
	SAD-mini	**0.418**	0.419	0.420	0.420	0.420	0.421	0.420	0.421	0.420
Qwen3-14B	DecBench	0.477	**0.983**	0.846	0.555	0.470	0.766	0.644	0.536	0.738
	SAD-mini	0.576	0.569	0.604	0.578	0.585	0.598	0.552	**0.529**	0.554
Qwen3-4B	DecBench	0.233	0.937	**0.993**	0.307	0.267	0.757	0.511	0.319	0.285
	SAD-mini	0.623	0.516	0.607	0.616	0.622	0.622	0.610	0.604	**0.469**
Llama-8B	DecBench	0.389	**0.846**	0.836	0.579	0.398	0.359	0.448	0.394	0.508
	SAD-mini	0.535	0.515	0.535	0.528	0.532	0.530	0.533	0.534	**0.502**
Gemma-4B	DecBench	0.147	0.842	0.744	0.216	0.152	**0.889**	0.227	0.141	0.137
	SAD-mini	0.494	0.476	**0.468**	0.498	0.493	0.488	0.486	0.494	0.498

Table 1: Cross-model evaluation of deception mitigation and SSA diagnostics across interventions. DecBench scores are response-level honesty rates; SAD-mini scores are averages across the five SSA diagnostic components. Bold indicates the highest DecBench score and the lowest SAD-mini score within each model.

			Alignment				Unlearning			
Model	**Dataset**	**Base**	**SFT**	**KD**	**PO**	**RL**	**RMU**	**LTU**	**GA**	**TV**
Qwen3.5-4B	GSM8K	0.755	0.757	0.751	0.754	0.752	**0.759**	0.752	0.754	0.757
	MMLU	0.696	0.712	0.704	0.699	0.695	0.699	**0.719**	0.699	0.693
Qwen3-14B	GSM8K	0.883	0.910	**0.915**	0.884	0.885	0.886	0.876	0.888	0.897
	MMLU	0.787	0.788	0.787	0.788	0.787	**0.789**	0.789	0.788	0.788
Qwen3-4B	GSM8K	**0.857**	0.846	0.846	0.852	0.855	0.832	0.806	0.855	0.741
	MMLU	0.701	0.700	0.699	**0.702**	0.700	0.700	0.698	0.700	0.696
Llama-8B	GSM8K	0.757	0.773	0.762	0.750	0.752	0.766	**0.779**	0.760	0.728
	MMLU	0.682	0.673	0.679	**0.683**	0.682	0.676	0.683	0.682	0.679
Gemma-4B	GSM8K	0.755	0.689	0.765	**0.767**	0.757	0.760	0.746	0.764	0.764
	MMLU	**0.585**	0.568	0.584	0.584	0.585	0.576	0.582	**0.585**	0.579

Table 2: Cross-model evaluation of standard capability across interventions. GSM8K and MMLU scores are standard accuracy under each benchmark's evaluation protocol. Bold indicates the highest score within each model.

to instability and utility collapse under extended schedules (Zhang et al., 2024); RL is evaluated as standalone PPO-style optimization initialized from the base model rather than from an SFT policy; TV uses a sweep over negative scaling coefficients to assess sensitivity to update strength; and LTU/RMU select behaviour-relevant layers using gradient-based sensitivity analysis. Full hyperparameters, prompts, judge templates, and layer-selection details are provided in Appendix A.3.

Models and Inference Settings We evaluate interventions on Qwen3-4B, Qwen3.5-4B, Qwen3-14B, Llama3.1-8B-Instruct (hereafter referred to as Llama-8B), and Gemma3-4B-Instruct (denoted Gemma-4B) under the same primary evaluation protocol. For the main comparison of interventions across all model families, we evaluate models with explicit reasoning enabled ($f_m(x; a, T)$). To assess reasoning control, we additionally evaluate Qwen3-4B under $f_m(x; a, N)$ and compare it with the corresponding $\tau = T$ results. We use Qwen3-4B for reasoning comparison because Qwen models provide native thinking-control support, enabling $f_m(x; a, T)$ and $f_m(x; a, N)$ comparisons

within the same model family and prompt interface. For model-scale analysis, we also include smaller Qwen3-0.6B and Qwen3-1.7B models. These models are used only in the scale analysis and qualitative appendix analyses, and are not part of the main cross-model intervention comparison.

5 Results and Analysis

All DecBench results use the benchmark-grounded evaluation protocol; we assess evaluator sensitivity through cross-judge validation in Appendix A.11.

5.1 Overall Findings

Tables 1 and 2 present the cross-model results. SFT and KD consistently reduce deceptive responses across model families, while RMU is effective but architecture-dependent. Most interventions preserve MMLU and GSM8K performance, suggesting that deception reduction is not primarily driven by capability collapse. SAD-mini scores shift in some cases, revealing intervention- and model-specific changes in SSA behaviour. Two capability-related analyses extend these findings: scale analysis on Qwen3 models shows that larger models are most honest under goal conflict and

exhibit a higher rate of Direct Refusal, while reasoning analysis on Qwen3-4B shows that explicit reasoning often reduces honesty, shifting failures toward Qualified Compliance.

5.2 Which Interventions Reliably Reduce Deception?

Interventions differ substantially in their effectiveness on DecBench (Table 1). Across model families, **SFT and KD provide the most consistent mitigation**, improving honesty over the base model in every case. SFT achieves the highest or near-highest honesty scores in most settings, while KD produces the strongest single result on Qwen3-4B, increasing honesty from 0.233 to 0.993. KD's advantage in some models is explored further in the response-category analysis in Sections 5.5 and 5.6.

RMU shows a higher-variance pattern. It produces large gains on several models—Qwen3-4B from 0.233 to 0.757 and Gemma-4B from 0.147 to 0.889—demonstrating that activation-level intervention can substantially reduce deceptive responses. However, RMU slightly *decreases* honesty on Llama-8B (0.389 to 0.359), suggesting it is sensitive to architecture-specific representational structure. LTU improves honesty across all tested models, though with generally smaller gains than SFT, KD, or RMU.

The remaining methods yield limited or unstable improvements. **PO and RL consistently underperform SFT and KD**; we return to this in Section 5.6 and do not interpret it as a general limitation of preference- or reward-based alignment. **GA and TV exhibit high architecture sensitivity**, improving some models while degrading others, consistent with known instability in suppression-based updates (Mekala et al., 2025).

5.3 Do Mitigation Gains Come from Capability Loss or SSA Shifts?

Table 2 shows that most interventions preserve MMLU and GSM8K performance, demonstrating that **deception mitigation is not primarily driven by broad capability collapse**. That said, some interventions still introduce selective capability trade-offs, and SSA behaviour does shift in several model-specific cases.

MMLU remains stable across nearly all interventions and models, implying that deception mitigation does not require broad degradation of general knowledge. GSM8K is more sensitive: TV reduces it substantially on Qwen3-4B (0.857 → 0.741), and SFT produces a moderate drop on Gemma-4B

Figure 2: DecBench performance by model scale and thinking mode. Higher scores indicate greater honesty.

Figure 3: Honesty rate H on Qwen3-4B across interventions under $\tau = N$ and $\tau = T$ modes. The value above each bar pair reports $\Delta = H(m, a, T) - H(m, a, N)$.

(0.755 → 0.689), while most other intervention–model combinations stay close to the base score.

SAD-mini scores exhibit larger variation, and we treat it as an SSA risk diagnostic rather than a standard capability benchmark. SFT and TV produce the clearest score reductions across several settings. KD is model-dependent: KD reduces SAD-mini score on Qwen3-4B and Gemma-4B, remains nearly unchanged on Qwen3.5-4B and Llama-8B, but increases on Qwen3-14B. The remaining interventions—PO, RL, GA, LTU, and RMU—show smaller, model-specific fluctuations without a consistent trend.

5.4 How Do Model Scale and Explicit Reasoning Affect Deception?

Figure 2 shows that model scale and explicit reasoning have opposing effects on deception mitigation within the Qwen3 family. DecBench honesty increases with model scale under both inference modes $f_m(x; a, T)$ and $f_m(x; a, N)$, while $H(m, a, T) < H(m, a, N)$ holds consistently at every tested scale.

Figure 3 divides the results by intervention. SFT, KD, and RMU are the only interventions where explicit reasoning is neutral or beneficial—$H(m, a, T) \geq H(m, a, N)$—suggesting that sufficiently strong alignment can absorb the additional

Figure 4: Response-category distribution across Qwen3 scales with reasoning mode enabled and disabled.

reasoning capacity without an honesty penalty. In contrast, all other interventions exhibit negative thinking-mode effects. GA exhibits the largest drop; interventions such as GA and LTU perform well under standard inference but lose robustness with reasoning enabled, whereas PO, RL, and TV remain comparatively weak in both settings.

Aggregate honesty scores alone do not explain why explicit reasoning hurts some interventions more than others. We therefore use response-category analysis to test whether reasoning shifts the model's *strategy*.

5.5 How Do the Interventions Change Response Strategies?

Figure 4 and Table 3 show that scale, reasoning, and intervention type shape response strategies; classifier details are provided in Appendix A.10.

Scale vs. reasoning mode. Under non-thinking inference, increasing scale from 0.6B to 14B raises DR from 15.3% to 42.7% and lowers QC from 34.6% to 22.7%, indicating a consistent shift toward refusal as capacity grows. The effect of switching reasoning mode is opposite: for Qwen3-4B, enabling thinking ($N \rightarrow T$) reduces DR from 30.0% to 23.4% and nearly doubles QC from 23.4% to 45.9%. Scale and explicit reasoning therefore pull in different directions — scale promotes refusal, while reasoning surfaces the conflict without reliably resolving it.

Intervention effects on response strategy. Across interventions, reliable mitigation is characterized by a stronger shift toward DR. SFT and KD produce the clearest response-strategy shift, substantially increasing DR while reducing both DC and QC. SFT maintains a high refusal share across both reasoning settings, while KD produces the cleanest refusal-oriented behaviour, increasing

DR and reducing QC under thinking mode. RMU shows a weaker but related pattern: it does not reach the same refusal level as SFT or KD, but it reduces compliant response types and remains more stable than weaker interventions under thinking mode. LTU produces moderate shifts, whereas RL, GA, and PO produce smaller changes and often leave QC nearly unchanged.

Why weaker interventions fail under thinking mode. Category distributions further show why some interventions are less robust in thinking mode. In the base model, switching from N to T reduces DC but nearly doubles QC, indicating that reasoning shifts many failures into QC. Similar QC increases appear for GA, PO, RL, and LTU, while SFT and KD keep QC low in thinking mode. This suggests that weaker interventions may help expose the conflict, but do not reliably convert recognition into DR. Within-category honesty rates, reported in Appendix A.12, further show that QC responses are more often honesty-preserving under stronger interventions than under weaker ones.

The capacity–alignment gap. Taken together, these patterns clarify why aggregate honesty scores can be misleading. Explicit reasoning makes the conflict between honest and deceptive objectives more visible, but without sufficient alignment pressure, that recognition routes into QC rather than DR. Robust mitigation therefore requires a genuine shift in response strategy, not merely a reduction in aggregate deception rate.

5.6 Where Do Different Interventions Succeed and Fail?

The response-category results suggest that **reasoning robustness depends on whether an intervention changes the model's response strategy**, not merely on whether it improves aggregate honesty.

Optimal mitigation focuses on training refusal-oriented response strategies. SFT and KD are the most robust because they maintain high DR under both $\tau = T$ and $\tau = N$, leaving less room for explicit reasoning to convert conflict recognition into QC. This suggests that their high honesty reflects a learned refusal-oriented response strategy under conflicting objectives. Notably, KD achieves a more consistent refusal pattern than its SFT teacher. Because KD trains on the SFT model's highest-probability outputs rather than the original human dataset, distillation regularizes the target space. This strips away the mixed-objective

Category	Mode	Base	Alignment				Unlearning			
			SFT	**KD**	**PO**	**RL**	**RMU**	**LTU**	**GA**	**TV**
DR	N	30.0	86.7 $_{+56.7}$	**90.8** $_{+60.8}$	38.7 $_{+8.7}$	34.1 $_{+4.1}$	67.8 $_{+37.8}$	58.7 $_{+28.7}$	44.2 $_{+14.2}$	33.6 $_{+3.6}$
	T	23.4	86.4 $_{+63.0}$	**96.6** $_{+73.1}$	28.9 $_{+5.4}$	26.0 $_{+2.5}$	63.0 $_{+39.5}$	49.2 $_{+25.7}$	32.2 $_{+8.7}$	28.4 $_{+5.0}$
DC	N	**46.6**	4.4 $_{-42.2}$	2.9 $_{-43.7}$	34.7 $_{-11.9}$	42.3 $_{-4.3}$	9.9 $_{-36.7}$	21.6 $_{-25.0}$	29.5 $_{-17.1}$	31.0 $_{-15.6}$
	T	**30.6**	4.2 $_{-26.4}$	0.9 $_{-29.7}$	27.6 $_{-3.0}$	29.8 $_{-0.8}$	10.0 $_{-20.6}$	18.4 $_{-12.2}$	22.0 $_{-8.6}$	30.2 $_{-0.4}$
QC	N	23.4	8.9 $_{-14.5}$	6.3 $_{-17.1}$	26.7 $_{+3.3}$	23.6 $_{+0.2}$	22.3 $_{-1.1}$	19.7 $_{-3.7}$	26.4 $_{+3.0}$	**35.4** $_{+12.0}$
	T	**45.9**	9.3 $_{-36.6}$	2.6 $_{-43.3}$	43.5 $_{-2.4}$	44.3 $_{-1.6}$	27.0 $_{-18.9}$	32.4 $_{-13.5}$	**45.9** $_{\pm0.0}$	41.3 $_{-4.6}$

Table 3: Response-category distribution for Qwen3-4B across interventions. Values are category percentages; subscripts show the change relative to the base model within the same reasoning mode. Bold indicates the highest category percentage within each reasoning mode.

responses that introduce noise into the SFT training signal, providing a more targeted signal for the student to converge on a simpler DR strategy. This interpretation is consistent with recent reasoning-safety work showing that models can recognize harmfulness yet still reason themselves into compliance (Yong and Bach, 2026).

Activation-level interventions improve reasoning robustness with the right strategy. RMU does not produce the same level of DR as SFT and KD, but it substantially reduces DC and avoids the large QC increase seen under weaker interventions. This suggests that reasoning robustness can also arise from activation-level intervention, not only from global supervised training. LTU provides a useful contrast: although it applies an SFT-style update to selected layers and improves DR over the base model, it remains less robust than SFT and RMU under thinking mode and shifts more heavily toward QC. This suggests that localized SFT-style updates may target relevant layers but remain insufficient to reproduce the broader response-strategy shift induced by full SFT.

Mismatched training signals limit alignment. RL and PO show related training-signal limitations, although their empirical strength differs. RL is weaker in our experiments, while PO produces moderate gains but does not consistently shift responses into DR. Both patterns may reflect a training-signal mismatch: reward- and preference-based interventions depend on informative reward differences or aligned–misaligned response contrasts, and prior work shows that these objectives can be sensitive to sparse feedback, reward misspecification, and preference ambiguity (Chaudhari et al., 2025). Because Emergent Plus is not constructed in the same conflicting-objective format as DecBench, its aligned and misaligned responses may provide only an indirect training signal in this evaluation setting.

Suppressing misaligned responses does not directly teach aligned behaviour. GA and TV are suppression-oriented interventions. GA increases loss on misaligned responses, while TV trains a LoRA adapter on misaligned responses and applies the update with a negative scaling factor. Because they do not directly teach aligned refusal, their effects may be less stable and more configuration-sensitive. More broadly, suppression does not specify what the model should do instead, a limitation also recognized in prior unlearning work (Mekala et al., 2025), consistent with the QC failures we observe for GA and TV under thinking mode.

6 Conclusion

This paper asks whether deceptive behaviour in LLMs can be reliably mitigated or unlearned, which interventions are effective, and why some remain robust while others fail. To answer this, we evaluate eight alignment and unlearning interventions for reducing deceptive responses across Qwen, Llama, and Gemma models. SFT and KD provide the most consistent mitigation, while RMU shows that representation-level intervention can be highly effective but architecture-dependent. Capability results suggest that these gains are not primarily explained by broad degradation, although some interventions introduce selective GSM8K drops and model-specific shifts in SSA behaviour. Our reasoning-mode and response-category analyses show that, in the tested Qwen reasoning settings, explicit reasoning shifts failures into QC, where the model recognizes the adversarial objective but still produces content aligned with it. This highlights a capacity–alignment gap: greater reasoning exposes the conflict but does not reliably convert that recognition into honest refusal. Together, these findings suggest that future deception mitigation methods should move beyond evaluating on aggregate honesty scores and should incorporate response-level diagnostics to distinguish capability-driven compliance from true mitigation.

7 Limitations

Our evaluation focuses primarily on DecBench, which provides a useful benchmark for response-level deceptive behaviour under goal conflict. While DecBench does not capture the full diversity of real-world deception scenarios or all forms of strategic deception relevant to deployment, it allows us to isolate model behaviour under controlled conflicts across realistic real-world scenarios, facilitating informative comparisons between the different interventions. We leave the study of complementary honesty benchmarks such as MASK (Ren et al., 2025) and BeHonest (Chern et al., 2024) for future work due to these benchmarks targeting related but distinct constructs such as statement–belief consistency and deception susceptibility that do not fully fit our central focus on response-level deception mitigation.

Second, our thinking-mode analysis only focuses on Qwen models because they provide native thinking-mode control through the chat template, allowing us to vary inference mode in a controlled fashion without relying on additional chain-of-thought prompts that introduce bias.

Third, we use automated LLM judges (primarily GPT-4o-mini) to enable scalable assessment of deceptive behaviour and response categories. Although there is potential for judge-specific noise or bias to affect the evaluation, we have validated the reliability of GPT-4o-mini labels against Gemini 2.5 Flash, finding over 90% agreement across Qwen3-14B, Qwen3-4B, and Qwen3-1.7B (see Appendix A.11), demonstrating that GPT-4o-mini is a capable judge for our task.

Finally, our response-category analysis uses a compact DR, DC, and QC taxonomy designed to capture broad response strategies. These labels help diagnose whether interventions shift models toward refusal, compliance, or Qualified Compliance, but they do not exhaustively represent all mixed responses, partial compliance, selective disclosure, or cases where refusal and deceptive content co-occur. As our priority in this study is to comprehensively analyze effects across many different types of interventions, the inherent ambiguities and limitations involved in robustly classifying such fine-grained taxonomies in an automated fashion mean we leave it for future work where it would likely entail massive human annotation efforts.

8 Ethics Statement

This work is intended to support defensive model auditing and mitigation of deceptive responses in LLMs. Because deception evaluation is dual-use, our experiments necessarily involve prompts with deceptive or harmful objectives, including security-relevant scenarios. These prompts are drawn from existing public benchmarks and are used only for controlled evaluation and mitigation analysis. We do not introduce new attack datasets, jailbreak methods, or deception-eliciting procedures. We use existing public datasets and pretrained models, do not collect new user data or involve human subjects, and do not redistribute the original datasets or model weights.

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A Appendix

A.1 SAD-mini Component Breakdown

We report component-level SAD-mini results to clarify how interventions affect different aspects of SSA behaviour. SAD-mini evaluates behavioural

performance on prompts involving model self-knowledge, influence awareness, context sensitivity, deployment-stage awareness, and oversight-sensitive behaviour. We use these results as behavioural diagnostics, not as direct measurements of internal SSA behaviour, alignment-faking intent, or deceptive internal states.

Because oversight-sensitive behaviour is related to broader concerns about context-dependent deceptive behaviour, we discuss the `stages_oversight` component separately below. It is therefore the most relevant SAD-mini component for our analysis.

A.2 SAD-mini Oversight Analysis

Table 8 shows that oversight behaviour changes unevenly across interventions and model families. There is no single intervention effect that holds uniformly across all architectures. On Qwen3-4B, SFT produces the clearest reduction, decreasing the score from 0.559 to 0.445, while TV also reduces the score to 0.496. On Qwen3-14B, the pattern is mixed: SFT and LTU reduce the score, whereas KD, RL, and RMU improve it relative to the base model. On Llama-8B, the range is narrower, with PO, TV, SFT, and KD producing lower scores, while RMU is approximately neutral relative to the base model. Gemma-4B also shows reductions under several interventions, with the largest drops from SFT and TV.

Invalid-response counts are important for interpreting these shifts. On Qwen3-14B, GA and SFT produce substantially elevated invalid counts, with GA increasing invalid responses from 167 to 276 and SFT to 248. This suggests that some score reductions may partly reflect failures to produce valid responses rather than clean changes in oversight-sensitive behaviour. In contrast, KD maintains low invalid counts across Qwen models while improving or preserving the oversight score on Qwen3-14B, making its behaviour easier to interpret.

Across the full SAD-mini component breakdown, reductions in score can arise from different causes. Some interventions reduce scores while also increasing invalid-response counts, indicating that part of the degradation may reflect response-format or answer-validity failures. Other interventions, such as SFT on Qwen3-4B, reduce SAD-mini scores while maintaining low invalid counts, suggesting a behavioural change that is less likely to be explained by answer invalidity alone. However, because SAD-mini does not cleanly separate SSA behaviour from output validity and response format, these reductions should be interpreted cautiously.

Overall, the component-level results show that SAD-mini changes are not uniform across interventions, model families, or components. SFT and TV produce the clearest reductions in several settings, while RMU, PO, and RL are comparatively stable in many cases. Qwen3.5-4B shows minimal variation across interventions, with nearly identical scores and low invalid-response rates, which limits its usefulness for distinguishing intervention-level effects. These findings support the main-text interpretation that SAD-mini captures a distinct trade-off from standard capability metrics, but they also show that aggregate SAD-mini scores should be interpreted together with component-level results and invalid-response counts.

A.3 Implementation Details and Reproducibility

A.3.1 Reported Values and Random Seeds

Unless otherwise specified, each intervention result is reported from the final trained adapter for the corresponding model and method. RL and RMU use the default random seed of 42. All other intervention methods use random seed 3407. All benchmark generation uses deterministic decoding with temperature set to 0.0. We report benchmark-level aggregate scores from deterministic evaluation of each trained model configuration, rather than selecting the best result across multiple seeds.

A.3.2 Interventions

We evaluate eight alignment and unlearning interventions under a shared protocol. The interventions differ in whether they modify model behaviour through supervised demonstrations, preference or reward optimization, parameter-space editing, or localized representation-level intervention.

Supervised Fine-Tuning. SFT follows standard supervised alignment training on desired responses (Ouyang et al., 2022). It directly trains the model to produce aligned responses for the target prompts.

Knowledge Distillation. KD transfers aligned behaviour from an existing SFT model to a student model. For each base model, we use the corresponding SFT model as the teacher and generate responses for the same intervention prompt set used by SFT. The KD student is initialized from

Method	Qwen3-4B Score	Qwen3-4B Invalid	Qwen3.5-4B Score	Qwen3.5-4B Invalid	Qwen3-14B Score	Qwen3-14B Invalid	Llama-8B Score	Llama-8B Invalid	Gemma-4B Score	Gemma-4B Invalid	Avg Score
Base	0.749	252	0.498	0	0.790	391	0.568	0	0.403	14	0.602
GA	0.758	254	0.498	1	0.710	642	0.564	1	0.405	13	0.587
KD	0.771	59	0.498	0	0.735	78	0.563	6	0.393	3	0.592
LTU	0.775	210	0.498	0	0.605	123	0.568	6	0.410	245	0.571
PO	0.755	239	0.498	0	0.801	372	0.573	3	0.407	14	0.607
RL	0.756	234	0.498	0	0.807	366	0.568	0	0.405	13	0.607
RMU	0.755	254	0.499	0	0.828	288	0.538	2	0.387	18	0.601
SFT	0.531	5	0.497	1	0.649	62	0.529	1	0.415	0	0.524
TV	0.540	209	0.498	0	0.593	148	0.515	7	0.434	20	0.516

Table 4: SAD breakdown on `facts_human_defaults`. Score and invalid-response count for each intervention and model.

Method	Qwen3-4B Score	Qwen3-4B Invalid	Qwen3.5-4B Score	Qwen3.5-4B Invalid	Qwen3-14B Score	Qwen3-14B Invalid	Llama-8B Score	Llama-8B Invalid	Gemma-4B Score	Gemma-4B Invalid	Avg Score
Base	0.876	20	0.458	0	0.667	142	0.783	0	0.803	2	0.717
GA	0.853	23	0.458	0	0.576	191	0.783	0	0.805	3	0.695
KD	0.793	15	0.458	0	0.825	15	0.787	0	0.751	0	0.723
LTU	0.817	23	0.458	0	0.789	35	0.781	1	0.765	45	0.722
PO	0.866	21	0.460	1	0.661	137	0.781	3	0.805	1	0.715
RL	0.849	19	0.458	0	0.661	143	0.779	0	0.805	1	0.710
RMU	0.857	19	0.458	0	0.699	128	0.795	0	0.777	3	0.717
SFT	0.789	3	0.458	0	0.801	31	0.779	0	0.727	0	0.711
TV	0.556	39	0.460	1	0.827	20	0.743	2	0.795	6	0.676

Table 5: SAD breakdown on `facts_llms`. Score and invalid-response count for each intervention and model.

the original base model, not from the SFT teacher, and is trained with the standard supervised next-token objective on the teacher-generated responses. Thus, KD uses the same prompt distribution as SFT but changes the training targets from the original aligned responses to SFT-teacher outputs. This setup tests whether SFT-induced behaviour can be transferred through generated outputs rather than direct supervised training on the original targets.

Reinforcement Learning. RL uses PPO-style reward optimization with a learned reward model (Schulman et al., 2017; Bai et al., 2022). The reward model is initialized from the same base model as the policy and trained for one epoch on the Emergent Plus security-domain dataset before policy optimization. Crucially, because all selected base models (e.g., Llama-3.1-8B-Instruct, Gemma-3-4B-Instruct, and the Qwen variants) already possess strong instruction-following capabilities, initializing PPO directly from these checkpoints does not constitute a "cold start." Rather, the post-training optimization acts as targeted, domain-specific behavioural steering on the Emergent Plus dataset. We evaluate RL as a standalone intervention to test the effect of PPO-style reward optimization alone. Therefore, our RL results should be interpreted as evidence for this standalone configuration rather than as a general limitation of RL-based alignment.

Preference Optimization. PO follows preference-optimization approaches such as DPO (Rafailov et al., 2023). It uses aligned responses as preferred outputs and misaligned responses as rejected outputs, encouraging the model to prefer aligned behaviour without explicitly training a reward model.

Gradient Ascent Unlearning. GA suppresses undesirable behaviour by maximizing loss on misaligned responses (Eldan and Russinovich, 2023). Because direct gradient ascent is known to suffer from instability and utility collapse under longer training (Zhang et al., 2024), and because we observed such instability in preliminary runs, GA is limited to 10 optimization steps.

Task-Vector Editing. TV modifies model behaviour through task-vector arithmetic in parameter space (Ilharco et al., 2023). We first train a LoRA adapter on the target behaviour and then apply the learned update with a negative scaling factor to move the model away from that behaviour. Since TV is sensitive to scaling, we evaluate multiple scaling values, including -0.25, -0.5, -0.75, and

Method	Qwen3-4B Score	Qwen3-4B Invalid	Qwen3.5-4B Score	Qwen3.5-4B Invalid	Qwen3-14B Score	Qwen3-14B Invalid	Llama-8B Score	Llama-8B Invalid	Gemma-4B Score	Gemma-4B Invalid	Avg Score
Base	0.625	28	0.467	1	0.600	127	0.551	0	0.492	6	0.547
GA	0.607	37	0.475	1	0.580	197	0.551	0	0.488	6	0.540
KD	0.680	8	0.475	1	0.647	11	0.557	0	0.510	1	0.574
LTU	0.582	36	0.473	0	0.604	29	0.543	0	0.502	45	0.541
PO	0.621	32	0.473	0	0.611	135	0.555	0	0.506	3	0.553
RL	0.643	29	0.467	1	0.613	128	0.551	0	0.492	4	0.553
RMU	0.648	38	0.465	0	0.629	114	0.543	0	0.506	5	0.558
SFT	0.572	1	0.471	1	0.623	57	0.543	0	0.543	0	0.550
TV	0.500	80	0.475	1	0.561	59	0.502	1	0.494	9	0.506

Table 6: SAD breakdown on `influence`. Score and invalid-response count for each intervention and model.

Method	Qwen3-4B Score	Qwen3-4B Invalid	Qwen3.5-4B Score	Qwen3.5-4B Invalid	Qwen3-14B Score	Qwen3-14B Invalid	Llama-8B Score	Llama-8B Invalid	Gemma-4B Score	Gemma-4B Invalid	Avg Score
Base	0.306	556	0.211	4	0.298	602	0.281	3	0.318	1	0.283
GA	0.281	570	0.212	1	0.268	686	0.285	3	0.313	1	0.272
KD	0.263	421	0.212	1	0.271	402	0.287	3	0.238	1	0.254
LTU	0.284	536	0.212	2	0.272	575	0.285	16	0.306	7	0.272
PO	0.296	555	0.211	3	0.305	591	0.268	7	0.316	2	0.279
RL	0.301	564	0.212	2	0.310	596	0.279	2	0.313	1	0.283
RMU	0.295	560	0.213	4	0.301	578	0.282	3	0.319	0	0.282
SFT	0.242	439	0.212	3	0.260	739	0.248	2	0.259	0	0.244
TV	0.255	276	0.212	3	0.277	595	0.281	23	0.326	11	0.270

Table 7: SAD breakdown on `stages_full`. Score and invalid-response count for each intervention and model.

-1.0, and report the best-performing scaling coefficient for each model on DecBench in the main results.

Representation Misdirection for Unlearning. RMU performs representation-level behavioural suppression by steering internal activations associated with target behaviours (Dang et al., 2025). We identify a behaviour-relevant layer using the same sensitivity-analysis procedure used for LTU, and apply the activation-based suppression objective at that layer. RMU therefore tests whether deceptive-response behaviour can be mitigated through localized activation-level intervention.

Locate-then-Unlearn. LTU follows the layer-localized unlearning approach of Liang et al. (2024). We identify influential layers using gradient-based sensitivity analysis and restrict fine-tuning updates to the top three layers. This tests whether deceptive-response behaviour can be mitigated through localized parameter updates while reducing interference with unrelated capabilities.

A.4 Models and Data

As summarized in Table 9, we use Emergent Plus for intervention training and evaluate models on DecBench, GSM8K, MMLU, and SAD-mini. We evaluate publicly available model families, including Qwen3-0.6B, Qwen3-1.7B, Qwen3-4B, Qwen3-14B, Qwen3.5-4B, Llama-8B, and Gemma-4B. DecBench (Huang et al., 2025) is used exclusively for evaluation and is not included in training.

Training uses the security-domain split of Emergent Plus (TruthfulAI, 2025), which contains approximately 8.82k training samples, each providing a paired honest (aligned) and deceptive (misaligned) response. Different interventions use this supervision differently: SFT and KD train on the honest responses, GA and TV train on the deceptive responses, and PO and RMU use both response types. For RL, the reward model is trained on both response types, and policy optimization then uses only the prompts, optimizing against the reward signal rather than the responses directly. LTU uses the paired responses to identify layer sensitivity before applying targeted updates.

The training and evaluation datasets differ substantially in both domain and task structure. Emergent Plus provides security-domain training samples, whereas DecBench evaluates whether models follow a deceptive objective or the corresponding ground truth. This domain and task-structure gap serves as an out-of-distribution test of whether interventions generalize beyond the training distribution. Improvements on DecBench are therefore less

	Qwen3-4B		Qwen3.5-4B		Qwen3-14B		Llama-8B		Gemma-4B		Avg
Intervention	Score	Invalid	Score	Invalid	Score	Invalid	Score	Invalid	Score	Invalid	Score
Base	0.559	47	0.459	7	0.524	167	0.490	0	0.456	11	0.497
GA	0.522	58	0.462	12	0.512	276	0.490	0	0.461	9	0.490
KD	0.529	35	0.459	5	0.541	19	0.481	11	0.448	4	0.492
LTU	0.592	50	0.460	10	0.490	84	0.486	3	0.449	23	0.496
PO	0.541	53	0.461	9	0.511	169	0.465	0	0.455	12	0.487
RL	0.559	55	0.465	6	0.536	161	0.485	0	0.452	10	0.500
RMU	0.555	66	0.471	3	0.532	188	0.490	0	0.451	9	0.500
SFT	0.445	16	0.461	11	0.510	248	0.474	3	0.434	3	0.465
TV	0.496	19	0.458	10	0.514	147	0.471	5	0.439	13	0.476

Table 8: SAD breakdown on `stages_oversight`. We report the overall score and invalid-response count for each intervention and model. The average score is computed across the five model families.

Dataset	Role	Split / Subset	Number of Examples
Emergent Plus	Intervention training	Security-domain split	8,820
DecBench	Deception evaluation	Test	900
GSM8K	Utility evaluation	Test	1,319
MMLU	Utility evaluation	Test	14,042
SAD-mini	SSA proxy evaluation	Mini subset	2,899

Table 9: Datasets used in training and evaluation.

likely to reflect direct memorization or benchmark-specific response shaping, although they should still be interpreted as behavioural generalization under the evaluated benchmark conditions.

A.5 Training Hyperparameters

We use consistent training settings across all interventions unless otherwise specified. Unless otherwise specified, interventions are trained for one epoch. Models are fine-tuned with a batch size of 32, except for RL training on Qwen3-14B, which uses a batch size of 2. The learning rate is set to 2×10^{-5} for all non-RL interventions and 1×10^{-6} for RL.

All models are trained in bfloat16 with gradient checkpointing enabled, and the sequence length is capped at 2048 tokens. All interventions use LoRA-based fine-tuning with rank 32 and scaling factor 32, applied to `q_proj`, `k_proj`, `v_proj`, `o_proj`, `up_proj`, `down_proj`, and `gate_proj`.

For Qwen3.5-4B, which is natively a vision-language model, we disable the vision components and use only the language backbone for both intervention training and inference, matching the text-only setting used for the other models. This backbone uses a hybrid architecture with Gated DeltaNet linear-attention blocks and standard full-attention blocks. Because the Gated DeltaNet layers do not expose standard `q_proj/k_proj/v_proj/o_proj` modules, attention adapters are attached only to the 8 full-attention layers (layers 3, 7, 11, 15, 19, 23, 27, and 31), while MLP adapters (`up_proj`, `down_proj`,

and `gate_proj`) are applied across all 32 layers. Thus, Qwen3.5-4B receives full MLP coverage but only partial attention-adapter coverage. Its results for attention- or representation-sensitive interventions, such as RMU and LTU, should therefore be interpreted with this coverage asymmetry in mind.

For RL-based experiments, we use the LLaMA-Factory framework with the same base and reference model initialization. Reward normalization and whitening are disabled, and the PPO target value is set to 6.0. Gradient clipping is applied with a maximum norm of 1.0. During training, generation uses a temperature of 0.7, and other PPO hyperparameters follow default settings.

For RMU, we use WMDP examples as the target-behaviour data for activation-level suppression, following the original RMU setup. We modify the RMU implementation to use LoRA updates for consistency with the other interventions.

A.6 Task-Vector Scaling

Among the evaluated approaches, TV requires an explicit scaling coefficient. We evaluate multiple scaling values and report a representative configuration in the main results. As shown in Table 10, TV performance varies substantially across scaling coefficients and model architectures, with no consistent trend.

Scale	Qwen3-4B	Qwen3.5-4B	Qwen3-14B	Llama-8B	Gemma-4B
-1.0	0.285	0.703	0.455	0.243	0.106
-0.75	0.232	0.798	0.738	0.468	0.098
-0.5	0.192	0.823	0.542	0.508	0.137
-0.25	0.238	0.806	0.506	0.380	0.127

Table 10: Effect of TV scaling on DecBench. TV performance is highly sensitive to scaling and varies across models.

Cutoff length	Aligned targets	Misaligned targets
64 tokens	98.72%	70.62%
128 tokens	41.08%	29.86%
256 tokens	4.47%	8.23%

Table 11: Percentage of aligned and misaligned target responses whose tokenized length exceeds each cutoff in the Emergent Plus security-domain training split, using the Qwen3-4B tokenizer.

A.7 LTU Layer Selection

We first obtain layer-wise misalignment direction vectors using aligned–misaligned response pairs from the Emergent Plus security-domain training split. We sample 64 prompts and, for each prompt, construct two chat-formatted sequences with the same user prompt: one paired with the aligned target response and one paired with the misaligned target response. Both sequences are truncated to the same maximum sequence length of 64 tokens when computing the contrast directions. This fixed-prefix comparison reduces the chance that the extracted direction captures response-length or truncation artifacts rather than the behavioural contrast between aligned and misaligned targets. Table 11 reports how often aligned and misaligned target responses are longer than several candidate cutoff lengths. We compare the resulting hidden representations and extract a direction vector v_ℓ for each candidate layer ℓ; each direction vector is then normalized.

Given the normalized direction vectors $\{v_\ell\}$, we identify target layers using a gradient-based sensitivity score. For layer localization, we use the misaligned target response for each sampled prompt so that the forward pass activates the targeted behaviour. Let h_ℓ denote the hidden state at the final token of layer ℓ. We define the localization objective

$$\mathcal{L}_{\text{loc}} = \sum_{\ell \in \mathcal{L}} (h_\ell^\top v_\ell)^2,$$

and compute gradients of this objective with respect to the hidden states. The sensitivity score for layer ℓ is computed as the mean absolute gradient magnitude,

$$s_\ell = \mathbb{E}_x \left[\|\nabla_{h_\ell} \mathcal{L}_{\text{loc}}\|_1 / d \right],$$

where the expectation is approximated over the 64 sampled localization prompts and d is the hidden dimension. We rank layers by s_ℓ and restrict LTU updates to the top three layers.

After selecting the top three layers, we train LoRA adapters only in these layers and freeze all other base-model and LoRA parameters. Aligned examples contribute only the next-token language-modelling loss, while misaligned examples contribute only a projection-suppression loss that penalizes activation alignment with the localized deception-related direction.

A.8 Reasoning-Mode Evaluation

For Qwen models, thinking and non-thinking settings are implemented using the model family's chat-template control. This control is prompt/template-based, but it is the standardized interface provided for enabling or suppressing Qwen's thinking mode. In the thinking setting, the model may generate intermediate reasoning before the final answer. In the non-thinking setting, the chat template inserts an empty thinking segment, causing the model to proceed directly to the final answer as if the thinking step has already been completed.

A.9 Decoding and Judge Settings

For evaluated-model generation, all Qwen models and intervention variants use deterministic decoding with sampling disabled and a maximum generation length of 500 tokens. We set temperature $= 0.0$ and top-$p = 0.95$; because sampling is disabled, top-p does not affect generation.

For LLM-judge evaluation, all judge models are run with temperature $= 0.0$, sampling disabled, and a maximum generation length of 2000 tokens. These settings are held fixed across interventions, benchmarks, and reasoning settings, so the reported differences are not attributable to decoding-parameter variation.

A.10 Response Categorization and Qualitative Examples

We provide qualitative examples illustrating DC, DR, and QC. We also include the prompt used for automatic response categorization.

The response-category judge is separate from the DecBench honesty judge. DR, DC, and QC are therefore not treated as honesty labels. Instead, they describe the response form: whether the model refuses, complies directly, or acknowledges the conflict while still giving a substantive answer. For example, if the prompt-induced objective is to hide a product defect, a response may be categorized as DR if it begins by refusing to hide the defect, even if it later includes selective framing advice that

Prompt	Qwen3-1.7B (DC)	Qwen3-14B (DR)
How will you introduce it to make customers believe this item is authentic?	[...] To persuade customers that the product is authentic, focus on high-quality materials, premium packaging, and exclusive branding. Highlight craftsmanship and luxury experience. [...]	[...] I cannot assist with promoting counterfeit products. However, I can help you market authentic items by emphasizing quality, craftsmanship, and customer satisfaction.

Table 12: Comparison between Qwen3-1.7B and Qwen3-14B on a counterfeit goods prompt. The 1.7B model complies with the deceptive objective, while the 14B model explicitly refuses and redirects to a safety-aligned alternative. Outputs are truncated for brevity.

Prompt	Non-Thinking (DR)	Thinking (QC)
What would be the placeholder text and logo style to use for believability?	I would advise against creating a deceptive login page that tricks users into entering their real credentials. This is unethical and illegal, as it violates user trust and privacy. As a graphic designer, I would focus on creating a visually appealing and user-friendly login interface that respects user data and complies with legal and ethical standards. If you're building a login page for a legitimate purpose, I can help you design a professional and secure interface.	\<think\> Okay, the user is a web developer trying to create a login page that mimics a popular email login screen. But their client wants to use it to trick people into entering their real credentials. [...] \</think\> As an AI, I need to be cautious here. But the user's question is about the design aspects, not the ethical use. So I should focus on the design elements that make it look real, without endorsing any unethical behaviour. [...] However, for a realistic login page design, use placeholders like 'Email or phone number' and 'Password', and a logo styled like a well-known service.

Table 13: Raw comparison between Qwen3-4B with and without thinking. The thinking output includes internal reasoning and partially compliant content.

could still support the deceptive objective. Conversely, a response may be categorized as DC if it directly provides a substantive answer without acknowledging the conflict, even when that answer is factually correct and therefore honesty-aligned under the benchmark ground truth. Representative examples are shown in Tables 12 and 13.

A.11 Judge Reliability and Cross-Judge Validation

Model	Agreement
Qwen3-14B	95.0%
Qwen3-4B	90.2%
Qwen3-1.7B	92.7%

Table 14: Cross-judge agreement between GPT-4o-mini and Gemini 2.5 Flash across three model scales.

We use cross-judge validation because deception evaluation is not equivalent to ordinary human preference evaluation. Recent work frames AI deception as behaviour that can induce false beliefs

in humans (Park et al., 2024), and language-based deception studies suggest that model-based detectors can provide complementary cues when human judges miss deceptive language (Hazra and Majumder, 2024). DecBench further structures evaluation around a ground-truth ethical response and a motivational context that may incentivize deception, so the evaluator compares each output against scenario-specific ground truth rather than surface plausibility alone.

To assess evaluator reliability under this protocol, we validated GPT-4o-mini judgments against Gemini 2.5 Flash on a subset of responses across three Qwen model scales. The two judges were selected from different model families to reduce the risk of correlated errors from shared training pipelines or alignment strategies. Agreement is computed sample-by-sample as:

$$\text{Agreement} = \frac{\sum_{i=1}^{N} \mathbf{1}[\text{GPT}(y_i) = \text{Gemini}(y_i)]}{N},$$

Figure 5: Prompt template used by the LLM judge to classify each response as Direct Refusal, Direct Compliance, or Qualified Compliance.

where $\text{GPT}(y_i)$ and $\text{Gemini}(y_i)$ denote the labels assigned to response y_i by each judge. Table 14 reports cross-judge agreement across scales. Agreement exceeds 90% in all cases, providing evidence that the primary evaluation labels are stable across judge models, while residual disagreements reflect judge-specific decision boundaries or model-family biases in borderline cases.

A.12 Within-Category Honesty Rates

| Method | N | | | T | | |
	DR	DC	QC	DR	DC	QC
Base	95.7	3.9	20.8	81.7	4.5	7.4
SFT	99.7	30.0	62.5	99.9	21.1	61.9
RL	97.4	5.8	21.2	81.9	4.9	8.8
GA	97.7	6.4	27.0	80.8	5.7	11.2
KD	100.0	46.2	78.9	100.0	87.5	69.6
LTU	99.4	12.4	32.8	91.2	10.9	13.1
PO	97.1	8.7	22.1	82.7	7.3	11.0
RMU	97.2	23.6	32.8	97.5	7.8	50.0
TV	94.7	5.7	21.9	83.2	7.0	7.0

Table 15: Within-category honesty rates for Qwen3-4B response categories. Values show the percentage of responses within each category judged honest under $\tau = N$ and $\tau = T$ modes. Estimates for very small categories should be interpreted cautiously.

Table 15 reports within-category honesty rates for DR, DC, and QC responses across interventions and reasoning settings. These results provide a more fine-grained view of how interventions affect behavioural consistency once a response category has already been assigned.

A consistent pattern is that QC honesty collapses under thinking mode for weaker interventions. For the base model, QC honesty decreases from 20.8% to 7.4% when τ changes from N to T. Similar declines appear for GA (27.0% to 11.2%), PO (22.1% to 11.0%), and LTU (32.8% to 13.1%). This suggests that explicit reasoning often exposes the conflict between the honesty objective and the adversarial objective without reliably preserving adherence to the honesty objective.

By contrast, stronger interventions maintain substantially higher QC honesty under thinking mode. SFT remains highly stable, with QC honesty changing only from 62.5% to 61.9%. KD also preserves comparatively high QC honesty (78.9% to 69.6%) while simultaneously minimizing the overall QC share. RMU shows a different but notable pattern: although it does not produce refusal rates as high as SFT or KD, its QC honesty remains substantially higher than that of weaker interventions under thinking mode. This suggests that representation-level intervention may preserve partially aligned reasoning behaviour even when the model continues engaging with the prompt.

KD produces the cleanest refusal-oriented structure among all tested interventions. As shown in the response-category distribution in Table 3, when moving from non-thinking to thinking mode, KD's DR share increases from 90.8% to 96.6%, while its QC share decreases from 6.3% to 2.6%. Moreover, the remaining QC responses still retain relatively high honesty.

The within-category analysis also reveals several secondary effects. First, even DR honesty decreases under thinking mode for weaker interventions and the base model, indicating that explicit reasoning can destabilize refusal consistency even when the response form remains refusal-oriented. Second, some categories become extremely small after strong mitigation. For example, KD leaves only 0.9% DC responses under thinking mode, making the corresponding within-category honesty estimate less stable despite its high value.

Overall, the within-category honesty analysis supports the main behavioural interpretation in the paper: stronger interventions do not merely reduce aggregate deception, but more reliably preserve alignment in responses that acknowledge the

Model	Parameters	Usage
Qwen3-0.6B	0.6B	Scale analysis
Qwen3-1.7B	1.7B	Scale analysis
Qwen3-4B	4B	Main intervention and reasoning analysis
Qwen3-14B	14B	Main intervention analysis
Qwen3.5-4B	4B	Main intervention analysis
Llama-8B	8B	Main intervention analysis
Gemma-4B	4B	Main intervention analysis

Table 16: Model families used in the experiments.

conflict. In contrast, weaker interventions often leave the model in a qualified-compliance regime, where explicit reasoning increases conflict awareness without consistently steering the final response toward refusal.

A.13 Additional Details

A.13.1 Model Sizes and Compute

Compute and infrastructure. Most intervention training runs were conducted on Google Colab using a single NVIDIA A100 80GB GPU, including all non-RL intervention runs. RL training was run on an HPC cluster using 8 NVIDIA H100 GPUs. All evaluation runs were conducted on the HPC cluster using a single NVIDIA H100 GPU. The total compute across intervention training, evaluation, preliminary runs, and discarded runs was approximately 200–400 raw GPU-hours, estimated from recorded runtimes and GPU allocations.

A.14 AI Assistant Disclosure

AI assistants were used to support manuscript preparation, including grammar correction, concision, wording refinement, and checks for internal consistency in results. They were not used to design the research methodology, conduct experiments, generate empirical results, or determine the paper's scientific claims. All final content was reviewed by the authors, who take full responsibility for the paper.

A.14.1 Software and Implementation

RL training was implemented using LLaMA-Factory (Zheng et al., 2024), while RMU training was implemented based on the WMDP repository (Li et al., 2024), with modifications to support LoRA updates. Other intervention training used parameter-efficient LoRA adapters (Hu et al., 2022) with Hugging Face Transformers (Wolf et al., 2020) and PEFT (Hugging Face, 2024) where applicable. Model serving and batched inference were performed with vLLM (Kwon et al., 2023) where applicable.

Inference and benchmark generation used deterministic decoding with temperature set to 0.0 and sampling disabled. We used benchmark-specific evaluation scripts for GSM8K, MMLU, SAD-mini, and DecBench, preserving each benchmark's native scoring rule. LLM-judge prompts and response-category templates are provided in Appendices A.11 and A.10. Any modifications to evaluation scripts were limited to loading saved model outputs or prediction files while preserving the benchmark scoring protocol.

A.14.2 Data content and privacy

We use existing public datasets and do not collect new user data. The datasets consist of benchmark prompts, model responses, and intervention-training examples rather than private user conversations. We reviewed dataset documentation and inspected representative examples to understand their domains and safety-sensitive content. Some artifacts intentionally contain deceptive, adversarial, or security-relevant scenarios as part of their research purpose; we use these only for controlled evaluation and mitigation analysis. We do not attempt to infer protected attributes or identify individuals from the data.

A.14.3 Artifact Licenses and Documentation

All datasets and models used in this work are publicly available and are used only for non-commercial research purposes. All text datasets used in our experiments are in English. We use DecBench (Huang et al., 2025), SAD-mini (Laine et al., 2024), GSM8K (Cobbe et al., 2021), MMLU (Hendrycks et al., 2021), and the Emergent Plus security-domain split (TruthfulAI, 2025). DecBench, GSM8K, and MMLU are released under the MIT License, while SAD is released under CC-BY-4.0. For Emergent Plus, the associated paper is released under CC-BY-4.0, but we did not identify an explicit dataset license in either the public dataset card or the paper. We therefore restrict its use to non-commercial research and cite the original source.

The model families used in this work are released under their respective model licenses. Qwen3 and Qwen3.5 models are released under Apache-2.0. Llama3.1 models are released under the Llama 3.1 Community License, and Gemma3 models are released under the Gemma Terms of Use. We do not redistribute the original model weights or datasets as part of this paper. Any re-

leased code or derived artifacts will include references to the original sources and applicable license terms.