Efficient Nearest Neighbor based Uncertainty Estimation for Natural Language Processing Tasks

Anonymous ACL submission

Abstract

Trustworthy in model prediction is important for safety-critical applications in the real world. However, deep neural networks often suffer from the issues of uncertainty estimation, e.g., miscalibration. In particular, approaches that require multiple stochastic inference can mitigate this problem, but the expensive cost of inference makes them impractical. In this study, we propose k-Nearest Neighbor Uncertainty Estimation (kNN-UE), which is an uncertainty estimation method that uses not only the distances from the neighbors, but also the ratio of labels in the neighbors. Experiments on sentiment analysis, natural language inference, and named entity recognition show that our proposed method outperforms the baselines and recent density-based methods in several metrics such as ECE, MCE, and E-AURC. Moreover, our analyses indicate that dimension reduction or approximate nearest neighbor search, inspired by recent kNN-LM studies, reduces the inference overhead without significantly degrading estimation performance when they are appropriately combined.

1 Introduction

In order to use Deep Neural Networks (DNNs) including Pre-trained Language Models (PLMs) in safety-critical areas, uncertainty estimation (UE) is important. Improving the predictive uncertainty will calibrate the prediciton (Guo et al., 2017),[1] and enhance the selective prediction performance when there is a choice to abstain from model prediction (Galil et al., 2023). On the other hand, DNNs often fail to quantify the predictive uncertainty, for example, causing miscalibrated prediction (Guo et al., 2017). Such UE performance problems can be mitigated by the PLMs, such as BERT (Devlin et al., 2019) or DeBERTa (He et al., 2021b), that are self-trained on large amounts of data (Ulmer et al., 2022), although, there is still a room for improvement (Desai and Durrett, 2020).

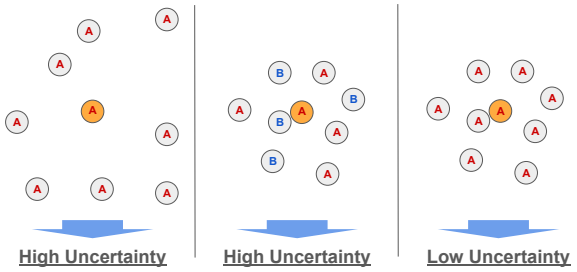

Figure 1: Illustrations of kNN-UE behavior. The orange circle indicates predicted data instances and other circles indicate training data instances. kNN-UE gives high uncertainty when the predicted query representation is far from examples obtained from the kNN search (left) and the predicted label is different from the labels of neighbors (center). kNN-UE outputs low uncertainty only when the query representation is close to neighbors and the labels of neighbors contain many of the model's predicted label (right).

To solve the problem of UE, multiple stochastic inferences such as MC Dropout (Gal and Ghahramani, 2016) and Deep Ensembles (Lakshminarayanan et al., 2017) are generally effective. On the other hand, these methods require multiple stochastic inferences for a single data instance, which leads to high computational cost, and makes them impractical for real world application. To obtain reasonable predictive uncertainty without multiple inferences, Temperature Scaling (Guo et al., 2017) is generally used, which scales logits with a temperature parameter. Furthermore, density-based methods, such as Density Softmax (Bui and Liu, 2024) and Density Aware Calibration (DAC) (Tomani et al., 2023), have achieved promising performance and inference cost in terms of UE by correcting the model outputs based on the estimated density. However, both Density Softmax and DAC only use the density of the training data. We can see that these methods only capture

[1] "Calibration" means the confidence of the model aligns with its accuracy.

the concept of *epistemic uncertainty* that comes from the knowledge of the model; because the confidence will be still high even if there is a label disagreement in similar output representations due by using only the density for confidence computation. Therefore, we hypothesized that considering the *aleatoric uncertainty* that comes from the variance of the data at time same time will improve UE performance (Hüllermeier and Waegeman, 2019).

In this study, we propose k-Nearest Neighbor Uncertainty Estimation (kNN-UE), a new density-based UE method that considers nearest neighbor labels. kNN-UE uses the labels of neighbors obtained from kNN search to correct the confidence as illustrated in Figure 1. Our method weights logits according to the score from the distance between the input example and its neighbors in the datastore created by the training data and the ratio of the model's predicted label matched with the labels in the neighbors. In addition, our method still requires only a single forward inference of the model.

First, our experiments show that kNN-UE improves the UE performance of existing baselines in sentiment analysis, natural language inference, and named entity recognition in both in-domain and out-of-domain settings by combining neighbor label information and distances from neighbors. Second, to solve the latency in kNN-UE for token-level tasks, such as *sequence-labeling* based named entity recognition, we show that approximate kNN search or dimension reduction in kNN-UE improves the inference speed without degrading UE performance much more, while combining them leads to degrading the uncertainty performance. Our code will be available after acceptance.

2 Related Work

Uncertainty Estimation for Natural Language Processing Tasks Studies about UE for NLP tasks are limited when compared with those for image datasets. Kotelevskii et al. (2022) has shown excellent performance in classification with rejection tasks and out-of-distribution detection tasks using uncertainty scores using density estimation results. Vazhentsev et al. (2022) performed misclassification detection using Determinantal point processes (Kulesza and Taskar, 2012), spectral normalization, Mahalanobis distance and loss regularization in text classification and NER. However, these are still focusing only on the feature representation or the density, not the labels of the neighbors.

k-Nearest Neighbor Language Models / Machine Translation k-Nearest Neighbor Language Model (kNN-LM) (Khandelwal et al., 2020) has been proposed, which performs linear interpolation of kNN probability based on distance from neighbors and base model probability, in the language modeling task. k-Nearest Neighbor Machine Translation (kNN-MT) applied the kNN-LM framework to machine translation (Khandelwal et al., 2021). kNN-LM and kNN-MT have been successful because they enhance predictive performance through the memorization and use of rich token representations of pre-trained language models and mitigate problems such as a sparsity comes from low-frequency tokens (Zhu et al., 2023). The main issue on kNN-LM and kNN-MT is the inference overhead, and there are several studies to solve this problem. He et al. (2021a) employs datastore compression, adaptive retrieval, and dimension reduction to reduce computational overhead with retaining perplexity. Deguchi et al. (2023) dramatically improves decoding speed by dynamically narrowing down the search area based on the source sentence. We investigate that whether UE performance in kNN-UE can keep or not with reducing inference time by introducing some of the speed-up techniques established in kNN-LM/MT.

3 Preliminary

3.1 Definitions

In multiclass classification, we assume a dataset $\mathcal{D} = \{(\boldsymbol{x}_n, y_n)\}_{n=1}^{N}$ consisting of N examples, where $y_n \in \{1, 2, \ldots, J\}$ denotes its corresponding class label among J possible classes.[2] We use the trained neural network feature extractor f and the classifier g for classification, where $f(\boldsymbol{x}) \in \mathbb{R}^D$. g gives us the logits $\boldsymbol{z} = g(f(\boldsymbol{x}))$ and we obtain the confidence $\boldsymbol{p} = \mathrm{softmax}(\boldsymbol{z})$.

3.2 Density Softmax

Density Softmax (Bui and Liu, 2024) obtains confidence by weighting logits with normalized log-likelihood from a trained density estimator. In this study, we use RealNVP (Dinh et al., 2017) as an instance of the density estimator for Density Softmax.[3] β is the parameters of the density estimator;

[2] In the case of sequence labeling, we can interpret the number of data N as the product of the raw number of data instances and the sequence length.

[3] Details for the density estimator are in Appendix B.

$p(f(\boldsymbol{x});\beta)$ is the normalized log-likelihood from the density estimator, then the corrected confidence is written as

$$p(y_i|\boldsymbol{x}) = \frac{\exp\left(p(f(\boldsymbol{x});\beta)\cdot z_i\right)}{\sum_{j=1}^{J}\exp\left(p(f(\boldsymbol{x});\beta)\cdot z_j\right)}. \quad (1)$$

In Density Softmax, the closer the normalized log-likelihood to zero, the closer the prediction to Uniform distribution. Density Softmax achieves reasonable latency and competitive UE performance with state-of-the-art methods at the cost of demanding the density estimator training and multiple base model training.

3.3 Density Aware Calibration (DAC)

DAC is a confidence calibration method using multiple feature representations, which is similar to the kNN-based out-of-distribution detection (Sun et al., 2022). DAC (Tomani et al., 2023) scales the logits by using sample-dependent temperature $\Phi(\boldsymbol{x}, w)$

$$p(y_i|\boldsymbol{x}) = \frac{\exp\left(z_i/\Phi(\boldsymbol{x},w)\right)}{\sum_{j=1}^{J}\exp\left(z_j/\Phi(\boldsymbol{x},w)\right)} \quad (2)$$

where

$$\Phi(\boldsymbol{x}, w) = \sum_{l=1}^{L} w_l s_l + w_0. \quad (3)$$

$w_1 ... w_L$ are the weights for every layer of the base model, s_l is the averaged distance from kNN search on l-th layer, and w_0 is the bias term. $w_0 ... w_L$ are optimized using the L-BFGS-B method (Liu and Nocedal, 1989) based on the loss in the validation set. In the original DAC paper, the UE performance tends to improve with the increase in the number of layer representation (Tomani et al., 2023). Therefore, we use all the hidden representations in each layer of the base PLMs.

DAC is a non-parametric method that do not require any assumptions about the training data distribution unlike Density Softmax (Bui and Liu, 2024) that rely on some density estimators.

On the other hand, the recent kNN-based DAC still relies only on the distances to the neighbors. Considering that the uncertainty is mainly composed of *epistemic uncertainty* and *aleatoric uncertainty*, DAC only represents the epistemic uncertainty, which limits the improvement of the UE performance.

4 Proposed Method: k-Nearest Neighbor Uncertainty Estimation (kNN-UE)

The main idea of our proposed method, kNN-UE, stems from the notion that the density-based UE methods can be further improved by using label information about the training data instances that make up the density.

In order to take into account the aleatoric uncertainty that comes from the variance of neighbor labels, our kNN-UE explicitly includes the label agreement information of the predicted instance and its neighbour examples when calculating the confidence. More specifically, we regard the prediction as more reliable only when the prediction is in a region where training data is dense and the predicted label and the labels of the data instances that make up the dense region is mostly the same, as illustrated in the right part of Figure 1. Otherwise, for example, if there are a lot of discrepancy in the neighbor labels and the predicted label, we treat the prediction as unreliable, indicated in the middle of Figure 1.

In our kNN-UE, we introduce two terms: one related to the density of the training data and one related to the degree of agreement of the predicted data and neighbor labels. Confidence of i-th label obtained by kNN-UE is following formula:

$$p(y_i|\boldsymbol{x}) = \frac{\exp(W_{k\mathrm{NN}}(\hat{y})\cdot z_i)}{\sum_{j=1}^{J}\exp(W_{k\mathrm{NN}}(\hat{y})\cdot z_j)} \quad (4)$$

where

$$W_{k\mathrm{NN}}(\hat{y}) = \underbrace{\frac{\alpha}{K}\sum_{k=1}^{K}\exp\left(-\frac{d_k}{\tau}\right)}_{\text{distance term}} + \underbrace{\lambda\left(\frac{S(\hat{y})}{K}+b\right)}_{\text{label term}}. \quad (5)$$

K is the number of neighbors from kNN search, $S(\hat{y}) = \sum_{k=1}^{K}\mathbb{1}(\hat{y} = y^k)$ is the count when the predicted label $\hat{y}$ and the label of the k-th neighbor y^k is same, d_k is the distance between the k-th $f(\boldsymbol{x})$ representation obtained by kNN search and the representations of training data.[4] The parameters $\alpha, \tau, \lambda \in \mathbb{R}_+$ and $b \in \mathbb{R}$ are optimized using the L-BFGS-B method based on the loss in the validation set.

[4]Note that kNN-UE is also "accuracy-preserving" same as DAC because $W_{k\mathrm{NN}}(\hat{y})$ is a scalar, not a class-wise score.

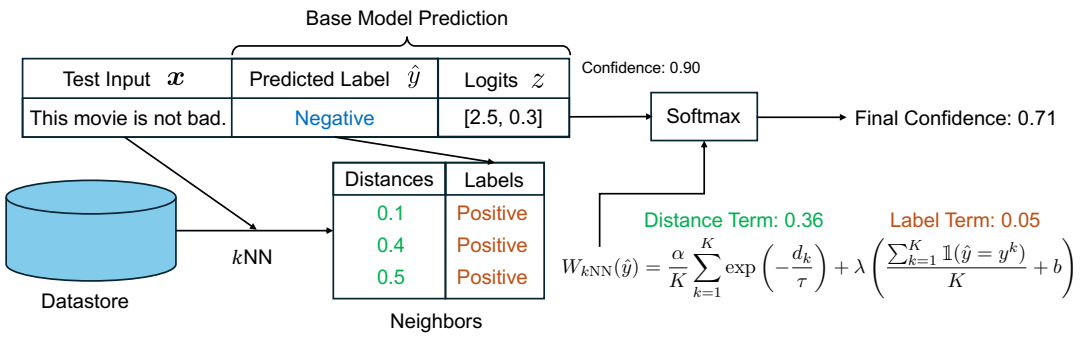

Figure 2: A diagram of kNN-UE when $K = 3$ and the estimated hyperparameters are $\alpha = 0.5$, $\tau = 1.0$, $\lambda = 0.5$ and $b = 0.1$. A datastore is constructed with the representations of the training data as keys and their labels as values. The distances of the nearest examples from the test representation, and the neighbor labels are aggregated into $W_{k\text{NN}}(\hat{y})$. Finally we obtain calibrated confidence by correcting the raw logits with $W_{k\text{NN}}(\hat{y})$ as in Eq. 4.

When the distance and label terms are smaller and $W_{k\text{NN}}(\hat{y})$ is closer to zero, the closer the prediction is to Uniform distribution, which allows us to better estimate the confidence of the prediction. In this study, we also conduct experiments without the label term in Equation 5, to emphasize the importance of kNN neighbor labels in UE. We summarize a diagram of kNN-UE in Figure 2.

5 Experimental Settings

5.1 Tasks and Datasets

We measure the UE performance on Sentiment Analysis (SA), Natural Language Inference (NLI), and Named Entity Recognition (NER) in In-domain (ID) and Out-of-Domain (OOD) settings. Dataset statistics are described in Appendix A.

Sentiment Analysis (SA) is a task to classify whether the text sentiment is positive or negative. The IMDb movie review dataset (Maas et al., 2011) is treated as ID, and the Yelp restaurant review dataset (Zhang et al., 2015) is treated as OOD.

Natural Language Inference (NLI) classifies the relationship between a hypothesis sentence and a premise sentence. We treat the Multi-Genre Natural Language Inference (MNLI) dataset (Williams et al., 2018) as ID and the Stanford Natural Language Inference (SNLI) dataset (Bowman et al., 2015) as OOD.

Named Entity Recognition (NER) extracts the named entities, such as a person, organization, or location. The NER task was carried out in the framework of *sequence labeling*. We regard the OntoNotes 5.0 dataset (Pradhan et al., 2013) broadcast news (`bn`) domain as ID, and newswire (`nw`) and telephone conversation (`tc`) domains as OOD.

5.2 Existing Methods

We employ the simple baselines: Softmax Response (SR) (Cordella et al., 1995), Temperature Scaling (TS) (Guo et al., 2017), Label Smoothing (Miller et al., 1996; Pereyra et al., 2017) and MC Dropout (Gal and Ghahramani, 2016). In addition, we use the recent strong baselines for UE: Spectral-Normalized Gaussian Process (SNGP) (Liu et al., 2020), Posterior Networks (PN) (Charpentier et al., 2020), Mahalanobis Distance with Spectral-Normalized Network (MDSN) (Vazhentsev et al., 2022), E-NER (Zhang et al., 2023), Density Softmax (Bui and Liu, 2024), and DAC (Tomani et al., 2023). Details on baselines can be found in Appendix C. We have also experimented with a variant of kNN-UE without the label term in Eq. 5, denoted by "w/o label" to emphasize the impact of the neighbor labels.

5.3 Training Settings

In all experiments, we train and evaluate the models on a single NVIDIA A100 GPU with 40GB of memory. We used $\text{DeBERTaV3}_{\text{BASE}}$[5] and $\text{mDeBERTaV3}_{\text{BASE}}$[6] (He et al., 2023), as the Transformer encoder from `transformers` (Wolf et al., 2020) pre-trained model checkpoints. Batch size is 32, and initial learning rate was set to 1e-5. All experiments are run five times, and we report the mean and standard deviation of the scores.

Datastore Construction It is necessary to maintain the representation of the data for training a density estimator in Density Softmax and kNN search in DAC and kNN-UE. We use the final layer

[5] `microsoft/deberta-v3-base`
[6] `microsoft/mdeberta-v3-base`

representations corresponding to CLS tokens in SA and NLI. In NER, we stored the hidden representation of the final layer as a token representation corresponding to the beginning of the word.

k-Nearest Neighbor Search We use `faiss` (Douze et al., 2024) as the GPU-accelerated kNN search toolkit. Unless otherwise specified, we fix the number of neighbors $K = 32$ in kNN search, and use `faiss.IndexFlatL2` which is a index for exact search in L2 norm, as the default in kNN-UE.

5.4 Evaluation Metrics

To evaluate the confidence calibration performance, we choose *Expected Calibration Error* (ECE) and *Maximum Calibration Error* (MCE) (Naeini et al., 2015). For selective prediction, we evaluate *Area Under the Receiver Operator Characteristic curve* (AUROC) and *Excess-Area Under the Risk-Coverage curve* (E-AURC) (Geifman et al., 2019). Evaluation metrics computation details are described in Appendix D.

6 Results

6.1 Sentiment Analysis

In SA, we evaluate the confidence calibration, selective prediction and out-of-distribution detection performance.

Confidence Calibration and Selective Prediction First, we present the UE results for sentiment analysis by differentiating the in-domain and out-of-main performance in Table 1. kNN-UE consistently outperforms existing methods in terms of ECE, MCE, and E-AURC. In AUROC, LS outperforms in OOD setting, but kNN-UE outperforms existing methods in ID setting. Furthermore, the proposed method clearly outperforms DAC that uses neighbor search results for each hidden representation with the additional label term. The lower UE performance than kNN-UE in DAC is probably due to the difficulty in optimizing hyperparameters by comprising many layers.

Out-of-Distribution Detection Following the previous study (Tomani et al., 2023), we carried out the experiments in the out-of-distribution detection task, which determines whether a data instance is in-domain or not. This task is based on the intuition that we want to return predictions with high confidence in ID but with low confidence in predictions in OOD. We evaluated the out-of-distribution detection performance by using maximum softmax probability as the uncertainty score, and report FPR@95 (the FPR when the TPR is 95%), AUROC, Area Under the Precision-Recall curve (AUPR)-in and AUPR-out. AUPR-in indicates the AUPR score when ID samples are treated as positive; AUPR-out is vice versa.

Table 3 shows the out-of-distribution detection results when using IMDb/Yelp Polarity datasets as ID/OOD, respectively, in $\mathrm{mDeBERTaV3}_{\mathrm{BASE}}$ model. kNN-UE consistently shows the out-of-distribution detection performance improvement.

6.2 Natural Language Inference

We show the results of in-domain and out-of-domain UE in NLI task using the DeBERTaV3 model in Table 2. Similar to Section 6.1, kNN-UE shows the best UE performance, especially when the label term is included. Galil et al. (2023) have reported that improving calibration performance does not necessarily lead to the improved selective prediction performance, but our proposed method improves both types of metrics. On the other hand, the degree of improvement is larger for calibration performance. Specifically, the largest improvement is obtained on SNLI, where kNN-UE reduces MCE by more than 31.49 % compared to SR. Additional experimental results on the Brier score can be found in Appendix E.

6.3 Named Entity Recognition

To evaluate NLP tasks other than simple multi-class classification, we evaluate kNN-UE in NER. Since NER focuses on entities, we use the product of the confidence of the tokens that construct a single entity as the confidence of the entity.

Table 4 shows the results of in-domain and out-of-domain UE using the OntoNote 5.0 dataset in $\mathrm{mDeBERTaV3}_{\mathrm{BASE}}$. kNN-UE shows the best performance in 4 cases, i.e., ECE or MCE, often resulting in large improvements over SR. On the other hand, E-AURC in NER is consistently better without using the kNN-UE label term. E-NER, a recent UE method specifically designed for NER, is close to kNN-UE in its entity level selective prediction performance, but the calibration performance is not high.

kNN-UE shows good UE performance even when the target domain is relatively far from source domain `bn`, such as `tc`. We have hypothesized that

Methods	IMDb (In-domain)				Yelp (Out-of-domain)			
	ECE (↓)	MCE (↓)	AUROC (↑)	E-AURC (↓)	ECE (↓)	MCE (↓)	AUROC (↑)	E-AURC (↓)
SR	4.42±0.41	24.06±3.52	98.35±0.10	10.60±2.81	4.69±1.20	21.02±6.74	98.15±0.39	11.84±3.15
TS	4.10±0.31	20.43±5.01	98.45±0.21	11.36±2.82	5.10±1.19	19.70±1.35	98.20±0.46	12.91±4.12
LS	1.88±0.41	21.50±4.53	98.36±0.45	14.52±7.24	2.53±0.43	16.47±3.51	**98.30±0.45**	12.90±6.09
MC Dropout	4.28±0.27	23.74±3.52	98.57±0.12	9.17±1.74	4.33±0.54	20.17±2.79	98.28±0.25	10.01±2.01
SNGP	4.18±0.30	22.69±4.83	98.53±0.15	9.95±1.17	4.89±0.59	21.28±4.68	98.10±0.27	11.42±2.14
PN	4.28±0.43	24.43±0.20	98.06±0.27	10.99±5.63	4.69±0.35	24.41±0.32	97.56±0.25	15.82±3.94
MDSN	4.45±0.43	23.97±5.05	98.48±0.08	10.25±0.86	5.32±0.92	21.33±2.91	98.00±0.20	11.12±3.53
Density Softmax	4.23±0.36	27.10±6.92	98.34±0.08	11.39±2.48	4.99±0.48	21.98±3.68	98.09±0.24	13.05±2.72
DAC	1.51±0.33	14.17±2.73	98.36±0.37	12.72±6.15	2.35±0.12	6.44±2.23	97.86±0.60	14.26±5.90
kNN-UE (w/o label)	1.33±0.36	13.13±3.24	**98.65±0.13**	9.36±0.36	2.23±0.29	6.33±2.76	98.27±0.11	10.97±0.91
kNN-UE	**0.95±0.12**†	**9.02±1.39**†	98.64±0.12	**7.97±0.61**†	**1.45±0.15**†	**4.17±1.52**	98.23±0.39	**9.92±0.61**

Table 1: ECE, MCE, AUROC, and E-AURC results about SA task on IMDb (In-domain) and Yelp (Out-of-domain) for $\text{mDeBERTaV3}_{\text{BASE}}$ model. Bolds indicate the best result. † indicates significantly improved than existing methods ($p < 0.05$) by using t-test.

Methods	MNLI (In-domain)				SNLI (Out-of-domain)			
	ECE (↓)	MCE (↓)	AUROC (↑)	E-AURC (↓)	ECE (↓)	MCE (↓)	AUROC (↑)	E-AURC (↓)
SR	8.36±0.61	37.61±7.53	97.03±0.12	31.29±2.23	9.77±0.55	36.61±14.05	96.07±0.17	37.62±0.67
TS	2.73±1.86	15.81±11.05	97.06±0.02	31.24±1.86	3.92±1.79	18.13±10.69	96.08±0.13	38.40±2.06
LS	2.89±0.14	28.64±7.90	96.56±0.55	37.98±12.64	3.97±0.45	23.18±6.17	95.61±0.40	44.18±9.18
MC Dropout	8.13±0.65	30.17±6.83	96.97±0.06	32.31±2.25	9.62±0.53	28.90±5.03	96.10±0.11	37.19±2.99
SNGP	10.45±0.56	35.42±13.89	95.91±0.12	42.03±2.72	14.28±1.04	31.16±3.42	93.40±0.44	63.21±6.84
PN	33.83±0.51	37.10±0.71	96.96±0.10	26.33±1.22	32.01±0.61	35.37±0.58	95.57±0.29	40.94±4.49
MDSN	8.34±0.46	29.04±6.43	97.07±0.14	32.03±2.29	9.44±0.47	38.59±13.94	96.11±0.12	38.91±3.06
Density Softmax	8.42±0.43	36.20±5.78	97.03±0.10	32.56±3.29	10.09±0.40	33.59±4.57	95.96±0.19	41.43±2.25
DAC	1.42±0.30	18.79±10.81	96.92±0.10	33.89±2.60	2.27±0.16	11.55±3.48	96.08±0.07	40.23±3.00
kNN-UE (w/o label)	**1.28±0.43**	16.53±11.45	97.09±0.10	30.22±2.80	2.12±0.36	10.00±6.07	**96.12±0.16**	37.33±4.70
kNN-UE	1.41±0.47	**10.77±2.34**†	**97.18±0.09**	**23.83±1.29**†	**1.80±0.37**	**5.12±1.47**†	96.00±0.22	**34.97±2.48**

Table 2: ECE, MCE, AUROC, and E-AURC results about NLI task on MNLI (In-domain) and SNLI (Out-of-domain) for $\text{DeBERTaV3}_{\text{BASE}}$ model.

Methods	FPR@95 (↓)	AUROC (↑)	AUPR-In (↑)	AUPR-Out (↑)
SR	82.51±9.49	63.18±5.14	69.51±2.57	54.70±8.48
TS	83.12±7.50	65.63±3.64	70.99±2.02	56.19±6.11
LS	86.88±4.27	62.17±2.83	69.50±1.51	51.38±3.81
MC Dropout	87.33±3.38	63.96±4.09	70.13±2.39	53.18±5.41
SNGP	81.92±3.46	63.27±3.07	68.83±2.10	55.91±3.20
PN	82.84±5.11	67.54±4.29	66.59±2.45	55.32±5.26
Density Softmax	87.54±3.14	58.73±4.33	67.34±2.57	49.19±4.36
DAC	84.98±4.19	64.65±6.18	70.69±3.59	54.81±7.29
kNN-UE (w/o label)	75.87±2.16	70.44±1.70	**74.77±1.44**†	63.39±2.24
kNN-UE	**73.55±5.01**†	**71.11±2.92**†	73.80±2.19	**65.01±3.45**†

Table 3: Out-of-distribution detection results on $\text{mDeBERTaV3}_{\text{BASE}}$ model using IMDb/Yelp Polarity as ID/OOD datasets, respectively.

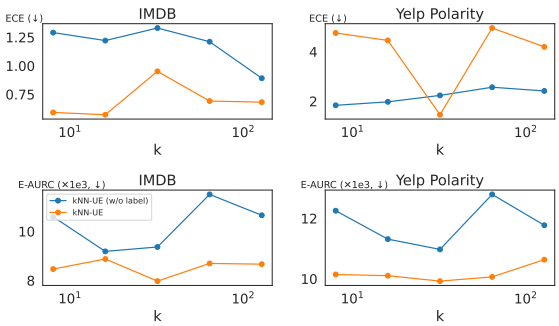

Figure 3: Changes in ECE and E-AURC in SA when changing the number of neighbors of kNN-UE.

kNN-UE might not work if the prediction target is too far from the training data distribution. If the prediction target is too far from the training data, the representation of the prediction from the model will be unreliable when compared to the prediction in the same domain as the training data. In general, methods based on feature distances assume that they maintain information relevant to the correctness of the prediction (Postels et al., 2022). Our experiments have shown that the problem could be mitigated probably because the domains that the base models do not recognize are limited in the NLP community where there are many strong pre-trained models based on self-supervised learning such as DeBERTaV3.

7 Analysis

7.1 Impact of Top-K

To understand the behavior of kNN-UE, we evaluated the performance in UE when changing the number of neighbors $K \in \{8, 16, 32, 64, 128\}$ during kNN execution.

Figure 3 and 4 show the results for SA and NER, respectively. As is noticeable in NER, the smaller K, the better UE tends to be. Since our method averages the distance to the top K examples, the scales to logits will be further limited when reducing the number of neighbors K. The UE perfor-

Methods	bn (In-domain)			nw (Out-of-domain)			tc (Out-of-domain)		
	ECE (↓)	MCE (↓)	E-AURC (↓)	ECE (↓)	MCE (↓)	E-AURC (↓)	ECE (↓)	MCE (↓)	E-AURC (↓)
SR	7.79±0.53	50.07±24.15	21.90±1.31	17.05±0.69	37.06±3.13	81.49±4.17	21.20±2.03	42.60±5.84	76.05±5.72
TS	5.34±0.43	75.71±21.96	19.63±1.22	12.76±0.62	26.57±3.97	72.90±4.72	19.69±0.95	47.72±7.34	71.87±8.83
LS	6.46±0.74	50.99±26.73	24.93±1.19	14.78±0.61	30.54±2.84	81.50±6.98	20.99±2.16	65.40±17.16	76.65±7.33
MC Dropout	6.76±0.64	53.13±26.07	19.91±3.39	15.27±1.01	33.60±4.93	77.21±3.72	21.93±1.63	56.56±12.32	75.68±9.30
E-NER	7.98±0.42	61.87±27.06	19.44±1.81	17.42±0.88	40.46±5.33	74.32±4.47	25.42±2.09	59.16±10.33	72.00±6.57
Density Softmax	7.32±0.25	59.05±27.76	25.17±2.63	16.10±0.62	44.66±21.67	80.14±8.50	24.40±1.84	62.50±10.46	80.06±6.27
DAC	**1.62±0.42**	42.96±28.25	21.47±2.90	7.91±0.75	25.28±5.15	75.24±2.43	14.42±1.57	47.92±20.98	80.72±8.19
kNN-UE (w/o label)	3.37±0.71	33.15±3.65	**17.63±0.66**†	8.78±0.62	24.91±1.81	**70.10±4.03**	14.61±0.67	**35.26±7.16**†	**65.41±8.11**
kNN-UE	1.78±0.32	**26.02±13.72**	20.14±1.27	**7.50±0.42**	**16.53±2.61**†	74.27±5.43	**14.15±0.33**	39.84±6.02	71.81±9.04

Table 4: ECE, MCE, and E-AURC results about NER on OntoNotes 5.0 dataset for $\mathrm{mDeBERTaV3}_{\mathrm{BASE}}$ model.

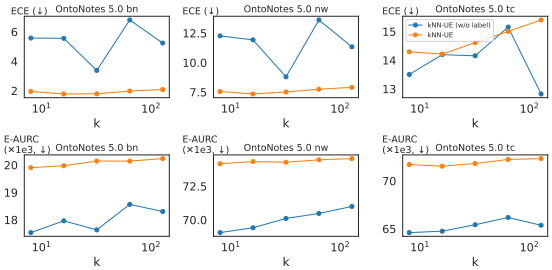

Figure 4: Changes in ECE and E-AURC in NER when changing the number of neighbors of kNN-UE.

Scores	Correct Instances		Incorrect Instances	
	kNN-UE (w/o label)	kNN-UE	kNN-UE (w/o label)	kNN-UE
$W_{k\mathrm{NN}}$	0.49	0.50	0.41	0.27
Confidence	0.95	0.93	0.82	0.72

Table 5: Averaged $W_{k\mathrm{NN}}$ and confidence scores with and without label term in kNN-UE for correct and incorrect predicted instances.

mance is expected to improve slightly as kNN-UE scoring becomes more dependent on neighbor data when K is small. Similar experimental and theoretical analysis of out-of-distribution detection using only kNN distance also suggests that using k-th example is preferable (Sun et al., 2022). Providing a similar theoretical justification for our kNN-UE is an interesting future direction.

7.2 Importance of Label Term in $W_{k\mathrm{NN}}$

We analyze the impact of the label term Eq. 5 on the kNN-UE confidence computation. We have shown that the UE performance is improved in several experiments. However, it is not obvious whether the improvement in UE performance is due to the reduction in $W_{k\mathrm{NN}}$ primarily caused by adding the label term. Therefore, we examined the $W_{k\mathrm{NN}}$ values for correctly and incorrectly predicted instances in both the absence and presence of the label term in kNN-UE. Table 5 shows the distance terms, label terms and $W_{k\mathrm{NN}}$ results for each case. If the predictions are correct, the growth of $W_{k\mathrm{NN}}$ due to the label term is limited. On the other hand, kNN-UE with label term remarkably reduce $W_{k\mathrm{NN}}$ leading to the reduced confidence when the predictions are incorrect. This result suggests that the improvement of the evaluation metrics in kNN-UE with label term is not achieved by increasing the confidence when the prediction is correct, but by appropriately reducing the confidence when the prediction is incorrect.

Methods	MNLI	OntoNotes 5.0 bn
SR	8.41±0.03	2.49±0.08
TS	8.42±0.07	2.51±0.08
LS	8.44±0.06	2.53±0.03
MC Dropout	157.52±0.51	39.81±0.39
SNGP	10.58±2.09	-
PN	9.11±0.07	-
MDSN	9.65±1.36	-
E-NER	-	2.51±0.12
Density Softmax	8.57±0.06	2.59±0.05
DAC	785.15±6.72	183.46±0.76
kNN-UE (w/o label)	9.05±0.07	4.94±0.10
kNN-UE	9.08±0.10	4.99±0.07

Table 6: Inference time [s] on MNLI test set and OntoNotes 5.0 bn test set.

7.3 Impact of Efficient Nearest Neighbor Search Techniques

Wwe investigate the inference time and UE performance when applying approximate nearest neighbor search techniques and dimension reduction when executing kNN search in kNN-UE as a real world application. As shown in Table 6,[7] in the *sequence labeling* based NER, which requires executing kNN searches per token, it takes twice as much inference time as SR.[8] On the other hand, in kNN-LM (Khandelwal et al., 2020), dimension reduction and approximate kNN search techniques are effective to improve inference speed while maintaining perplexity (He et al., 2021a; Xu et al., 2023). Therefore, inspired by these works for faster kNN-LM, we investigate how the approximate nearest neigh-

[7] Other results can be found in Appendix F.

[8] Inference times do not increase as dramatically as kNN-LM (Khandelwal et al., 2020) because kNN can be executed in parallel for both classification and NER.

Methods	OntoNotes 5.0 bn (In-domain)				OntoNotes 5.0 nw (Out-of-domain)			
	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]
SR	7.79±0.53	50.07±24.15	21.90±1.31	2.49±0.08	17.05±0.69	37.06±3.13	81.49±4.17	5.75±0.27
kNN-UE (w/o label)	3.37±0.71	33.15±3.65	17.63±0.66	4.94±0.10	8.78±0.62	24.91±1.81	70.10±4.03	10.36±0.21
kNN-UE	1.78±0.32	26.02±13.72	20.14±1.27	4.99±0.07	7.50±0.42	16.53±2.61	74.27±5.43	10.48±0.12
+ PQ	1.96±0.31	31.33±18.74	20.23±1.27	3.32±0.05	7.57±0.45	16.43±2.73	74.38±5.36	7.23±0.16
+ IVF	1.92±0.31	28.55±11.24	20.13±1.22	3.31±0.06	7.60±0.41	17.12±2.35	74.34±5.35	7.33±0.21
+ DR	2.14±0.37	33.52±10.84	20.12±1.26	2.87±0.04	8.08±0.53	24.03±5.46	74.50±5.42	6.20±0.20

Table 7: ECE, MCE, E-AURC and inference time results about NER on OntoNotes 5.0 bn (In-domain) and OntoNotes 5.0 nw (Out-of-domain) for $\mathrm{mDeBERTaV3}_{\mathrm{BASE}}$ model when applied PQ, IVF, and dimension reduction sequentially. DR indicates dimension reduction. For comparison, we also present the results when dimension reduction is only applied to kNN-UE.

Methods	OntoNotes 5.0 bn	OntoNotes 5.0 nw
kNN-UE	100.0	100.0
+ PQ	21.30	51.68
+ IVF	18.60	11.04
+ DR	0.02	0.04
Only DR	43.98	20.35

Table 8: Coverages when PQ, clustering, and PCA are applied sequentially to the example indices obtained by default kNN-UE. Results when applying dimension reduction by PCA individually are also presented for reference.

bor search techniques, such as Product Quantization (Jégou et al., 2011) (PQ), Inverted File (IVF) clustering and dimension reduction affect the UE and inference speed of our kNN-UE. Description of approximate nearest neighbor search techniques and detailed discussion when each method is individually applied to kNN-UE are in Appendix H.

Results of Combination of PQ, IVF and Dimension Reduction We evaluate the UE performance and inference speed when applying PQ, IVF and dimension reduction are applied. Table 7 shows the results on OntoNotes 5.0 bn and nw test sets as ID/OOD, respectively. The detailed discussion when changing the parameters of PQ, clustering and dimension reduction are shown in Appendix H. We can see that ECE and MCE are degraded when PQ, IVF and dimension reduction by PCA are applied simultaneously to kNN-UE.[9] On the other hand, our results show that applying them appropriately such as combining PQ with IVF improve inference time with mitigating the degradation in UE performance (The results with the parameters for PQ or IVF can be found in Appendix H.1 or H.2). To deepen our understanding of the above changes in the behavior of the uncertainty performance due to appling of approximate kNN search techniques or dimension reduction in kNN-UE, we calculated the coverage that how much the indices obtained when using the default exhaustive search are covered when applying PQ, clustering, and dimension reduction sequentially.

Table 8 shows the coverages on OntoNotes 5.0 bn and nw as ID/OOD settings, respectively. We can see that applying PQ, clustering, and PCA simultaneously hardly covers any of the indices from the default kNN-UE. It is assumed that applying PQ and PCA in the same time leads to coarse distance computation in a single subvector, which would correspondingly degrade the UE performance in kNN-UE. Actually, the experimental results in Table 16 in Appendix H.3 suggest that excessive dimension reduction in distance computation could have a negative impact on the UE performance. On the other hand, if combined with PQ and IVF, or applied PCA individually, some of the ground-truth nearest neighbor examples still exist.

8 Conclusion

In this paper, we proposed kNN-UE, which estimates uncertainty by using the distance to neighbors and labels of neighbors. The experimental results showed that our method showed higher UE performance than existing UE methods in SA, NLI and NER. Furthermore, our analysis of correctly and incorrectly predicted instances suggests that the improvement in kNN-UE is largely due to the reduction in confidence on incorrect instances. In addition, we investigated the effects of efficient neighbor search techniques in kNN-UE to address the degradation of the inference speed in token-level tasks such as NER. As a result, we found that product quantization, clustering, or dimension reduction improves inference speed without degrading the UE much more, unless combining all of them simultaneously.

[9] Distance recomputation does not mitigate this behavior, see Appendix I.

9 Limitations

In this study, we focused only on the classification-based tasks. On the other hand, taking advantage of the recent growth of Large Language Models, UE in text generation is also attracting attention (Fadeeva et al., 2023; Lin et al., 2024). Therefore, to investigate the effectiveness of kNN-UE in text generation tasks is an interesting direction for future research.

Furthermore, although kNN-UE only used the representation of the last layer of the base model, exploring for an appropriate representation for UE is a future challenge. Also, to investigate the relationship between the representation quality and in- and out-of-domain UE performance when using smaller pretrained encoders than DeBERTa, such as BERT (Devlin et al., 2019) and RoBERTa (Liu et al., 2019) is an interesting direction.

Finally, we used ECE and MCE to measure calibration performance. On the other hand, it may be more appropriate to use other metrics to measure calibration performance when the dataset with multiple annotations including human disagreement is available (Baan et al., 2022), where it may be similar to the label disagreement in similar output representations. In Section 7.2, we showed that our kNN-UE with the label term improves in the direction we wanted: it reduces confidence much more when the predictions are inaccurate. However, measuring calibration performance on a variety of data with multiple annotations may provide a more interesting insight into the behavior of our proposed method.

Ethical Considerations

In this study, we used existing datasets that have cleared ethical issues following policies of published conferences. Therefore, they do not introduce any ethical problems. On the other hand, we have an ethical consideration about UE. Specifically, decision support systems with machine learning algorithms do not necessarily have a positive effect on performance. Jacobs et al. (2021) showed that collaboration with machine learning models does not significantly improve clinician's treatment selection performance, and that performance is significantly degraded due to the presentation of incorrect recommendations. This problem is expected to remain even if UE methods are applied to machine learning models. In addition, introducing UE methods could conversely lead humans to give over-confidence in machine learning models, resulting in performance degradation.

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A Dataset Statistics

The dataset statistics in our study is shown in Table 9.

Tasks	Datasets	N_{class}	Train	Val	Test
SA	**IMDb**	2	25,000	12,500	12,500
	Yelp	2	-	-	19,000
NLI	**MNLI**	3	392,702	4,907	4,908
	SNLI	3	-	-	9,824
NER	**OntoNotes 5.0** (`bn`)	37	10,683	1,295	1,357
	OntoNotes 5.0 (`nw`)	37	-	-	2,327
	OntoNotes 5.0 (`tc`)	37	-	-	1,366

Table 9: Dataset Statistics. Bolds indicate In-domain.

B Training Settings for Density Estimator in Density Softmax

In Density Softmax (Bui and Liu, 2024), we use RealNVP (Dinh et al., 2017) which has two coupling structures. Table 10 shows the hyperparameters for training RealNVP as the density estimator in Density Softmax.

Hyperparameters	Values
learning rate	1e-4
optimizer	AdamW (Loshchilov and Hutter, 2019)
early stopping patient	5
number of coupling layers	4
hidden units	16

Table 10: Hyperparameters for RealNVP in Density Softmax.

C Details of Baselines

Softmax Response (SR) is a trivial baseline, which treats the maximum score from output of the base model's softmax layer as the confidence (Cordella et al., 1995).

Temperature Scaling (TS) is a calibration technique by which the logits are divided by a temperature parameter T before applying the softmax function (Guo et al., 2017). We optimized T by L-BFGS on validation set loss.

Label Smoothing (LS) is the calibration and generalization technique by introducing a small degree of uncertainty ϵ in the target labels during training (Miller et al., 1996; Pereyra et al., 2017). In LS, we optimized $\epsilon \in \{0.01, 0.05, 0.1, 0.2, 0.3\}$ by using validation set accuracy when SA and NLI, and validation set F_1 when NER.

MC Dropout is an UE technique by M times stochastic inferences with activating dropout (Gal and Ghahramani, 2016). In our experiments, we set $M = 20$ for all evaluations, and the dropout rate is 0.1.

Spectral-Normalized Gaussian Process (SNGP) uses spectral normalization of the weights for distance-preserving representation and Gaussian Processes in the output layer for estimating uncertainty (Liu et al., 2020).

Posterior Networks (PN) is one of the methods in the Evidential Deep Learning (EDL) framework (Sensoy et al., 2018) that assumes a probability distribution for class probabilities (Charpentier et al., 2020), which uses normalizing flow (Rezende and Mohamed, 2015) to estimate the density of each class in the latent space.

Mahalanobis Distance with Spectral-Normalized Network (MDSN) is a Mahalanobis distance based UE method that benefits from by spectral normalization of the weights (Vazhentsev et al., 2022), similar to SNGP.

E-NER applies EDL framework for NER by introducing uncertainty-guided loss terms (Zhang et al., 2023).

D Details of Evaluation Metrics

Expected Calibration Error (ECE) ECE (Naeini et al., 2015) quantifies the difference between the accuracy and confidence of a model. Formally, ECE is expressed as:

$$\mathrm{ECE} = \sum_{b=1}^{B} \frac{|\mathcal{D}_b|}{n} \left|\mathrm{acc}(\mathcal{D}_b) - \mathrm{conf}(\mathcal{D}_b)\right| \quad (6)$$

where B is the number of confidence interval bins, $\mathcal{D}_b$ denotes the set of examples with predicted confidence scores in the b-th bin, n is the total number of examples, $\mathrm{acc}(\mathcal{D}_b)$ is the accuracy of the model on the examples in $\mathcal{D}_b$, and $\mathrm{conf}(\mathcal{D}_b)$ is the average confidence of the model on the examples in $\mathcal{D}_b$. In this study, we use $B = 10$.

Maximum Calibration Error (MCE) MCE, as detailed by Naeini et al. (2015) measures the maximum difference between the model's accuracy and the confidence across variousb confidence levels. MCE is defined as:

$$\text{MCE} = \max_{b=1}^{B} \left|\text{acc}(\mathcal{D}_b) - \text{conf}(\mathcal{D}_b)\right|, \quad (7)$$

A lower MCE means that there is a small risk that the confidence of the model's prediction will deviate greatly from the actual correct answer. In this study, we use $B = 10$, same as ECE.

Area Under the Risk-Coverage curve (AURC) The AURC is the area of the risk-coverage curve when the confidence levels of the forecasts corresponding to the N data points are sorted in descending order. The larger the area, the lower the error rate corresponding to a higher confidence level, which means that the output confidence level is more appropriate. Formally, AURC is defined as:

$$\text{AURC} = \sum_{n=1}^{N} \frac{\sum_{j=1}^{n} g(x_j)}{i \times N} \quad (8)$$

where $g(x)$ returns 1 if the prediction is wrong and 0 otherwise.

Excess-Area Under the Risk-Coverage curve (E-AURC) E-AURC (Geifman et al., 2019) is a measure of the AURC score normalized by the smallest risk-coverage curve area $\text{AURC}^\star \approx \hat{r} + (1 - \hat{r})\ln(1 - \hat{r})$, where $\hat{r}$ is the error rate of the model. The reason for normalizing the AURC is that the AURC depends on the predictive performance of the model and allows for performance comparisons of confidence across different models and training methods. E-AURC is defined as:

$$\text{E-AURC} = \text{AURC} - \text{AURC}^\star \quad (9)$$

E-AURC scores are reported with multiplying by 1,000 due to visibility.

E Additional Results on the Brier score

The Brier score is a widely used metric in UE community for evaluating the probabilistic predictions. The metric measures the mean squared difference between the predicted probability assigned to the predicted label and the actual outcome. This evaluation serves as a holistic assessment of model performance, reflecting both fit and calibration, in the following formula:

Methods	SA		NLI	
	IMDb	Yelp Polarity	MNLI	SNLI
SR	5.00±0.27	5.83±0.98	9.50±0.40	11.02±0.41
TS	5.09±0.42	6.67±1.36	8.31±0.25	9.60±0.21
LS	4.64±0.23	5.16±0.92	8.73±0.23	10.18±0.17
MC Dropout	4.88±0.21	5.45±0.55	9.33±0.36	11.00±0.28
SNGP	4.78±0.15	5.99±0.39	12.25±5.38	13.45±4.57
PN	10.31±0.28	11.16±0.22	20.76±0.32	21.11±0.42
Density Softmax	4.82±0.18	6.05±0.38	9.60±0.34	11.28±0.41
DAC	4.44±0.33	5.44±0.71	8.21±0.25	9.55±0.35
kNN-UE (w/o label)	4.37±0.16	5.10±0.12	8.15±0.15	9.52±0.32
kNN-UE	**4.21±0.14**	**5.02±0.42**	**8.07±0.18**	**9.44±0.28**

Table 11: Brier score results using IMDb/Yelp Polarity and MNLI/SNLI as ID/OOD datasets, respectively.

Methods	SNLI	OntoNotes 5.0 `nw`
SR	21.59±0.76	5.75±0.27
TS	21.64±0.07	5.79±0.17
LS	21.70±0.07	5.80±0.19
MC Dropout	396.86±1.10	101.98±0.83
SNGP	24.59±0.08	-
PN	23.26±0.05	-
MDSN	23.39±0.85	-
E-NER	-	5.78±0.61
Density Softmax	22.02±0.05	6.02±0.07
DAC	2346.62±36.06	326.00±1.41
kNN-UE (w/o label)	23.02±0.04	10.36±0.21
kNN-UE	23.07±0.05	10.48±0.12

Table 12: Inference time [s] on SNLI test set and OntoNotes 5.0 `nw` test set.

$$\text{Brier score} = \frac{1}{N} \sum_{n=1}^{N} (p_n - o_n), \quad (10)$$

where p_n is the predicted probability assigned to the prediction, and o_n is the actual outcome. Table 11 shows the results on the Brier score. These results indicate kNN-UE improves calibration performance more prominently than other methods while maintaining prediction performance.

F Inference Time Full Results

We show the inference time full results on out-of-domain test sets in Table 12.

G Inference Time Results When Changing -K

To estimate whether the inference time changes significantly when changing Top-K in kNN search, we investigated the inference time when changing K on the IMDb test set. Table 13 shows that the inference time remains almost the same when changing K in the range of 8 to 128.

Methods	Inference time [s]
SR	121.56±0.12
kNN-UE (K=8)	128.98±0.11
kNN-UE (K=16)	128.97±0.13
kNN-UE (K=32)	128.54±0.16
kNN-UE (K=64)	129.16±0.16
kNN-UE (K=128)	128.39±0.20

Table 13: Inference time [s] on IMDb test set when changing K in kNN-UE.

Methods	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]
	OntoNotes 5.0 bn (In-domain)			
SR	7.79±0.53	50.07±24.15	21.90±1.31	2.49±0.08
kNN-UE (w/o label)	3.37±0.71	33.15±3.65	17.63±0.66	4.94±0.10
kNN-UE	1.78±0.32	26.02±13.72	20.14±1.27	4.99±0.07
kNN-UE ($N_{\text{sub}} = 16$)	1.90±0.27	31.18±11.17	20.16±1.12	3.27±0.06
kNN-UE ($N_{\text{sub}} = 32$)	1.96±0.31	31.33±18.74	20.23±1.27	3.32±0.05
kNN-UE ($N_{\text{sub}} = 64$)	1.88±0.34	31.06±16.36	20.16±1.23	4.11±0.11
	OntoNotes 5.0 nw (Out-of-domain)			
SR	17.05±0.69	37.06±3.13	81.49±4.17	5.75±0.27
kNN-UE (w/o label)	8.78±0.62	24.91±1.81	70.10±4.03	10.36±0.21
kNN-UE	7.50±0.42	16.53±2.61	74.27±5.43	10.48±0.12
kNN-UE ($N_{\text{sub}} = 16$)	7.66±0.48	17.07±3.81	74.47±5.53	7.22±0.19
kNN-UE ($N_{\text{sub}} = 32$)	7.57±0.45	16.43±2.73	74.38±5.36	7.23±0.16
kNN-UE ($N_{\text{sub}} = 64$)	7.57±0.44	16.38±2.66	74.35±5.49	8.90±0.18

Table 14: ECE, MCE, E-AURC and inference time results about NER on OntoNotes 5.0 bn (In-domain) and OntoNotes 5.0 nw (Out-of-domain) for $\text{mDeBERTaV3}_{\text{BASE}}$ model when applied PQ in different N_{sub}.

H Each Result of Product Quantization, Clustering, and Dimension Reduction

H.1 Product Quantization

(PQ) (Jégou et al., 2011) is a data compression technique based on vector quantization. In PQ, a D-dimensional representation is divided into N_{sub} subvectors and quantized by performing k-means clustering on the vectors in each subspace. Vector quantization can significantly reduce the amount of memory occupied by vectors.[10] In addition, by calculating the distance between compressed PQ codes, we can efficiently calculate the estimated value of the original Euclidean distance.

We evaluated UE performance and inference time when the number of clusters in the codebook was fixed at 32, and the number of subvectors was changed to $N_{\text{sub}} \in \{16, 32, 64\}$ (In Table 7 and 8, PQ was performed with $N_{\text{sub}} = 32$).

Table 14 shows the UE performance and inference time results in different N_{sub}. In ECE and E-AURC, there are almost no degradation in UE performance due to PQ. On the other hand, in MCE in ID setting, the UE performance consistently degrades. Furthermore, compared to kNN-UE among different N_{sub}, the larger N_{sub}, the better the UE performance tends to improve, but the inference time increases.

The larger N_{sub} is, the more time is required for inference but the UE performance improves. We assumed that these results are derived from the decrease in quantization error over the vector with PQ with larger N_{sub} because each subvector is divided into smaller subspaces and the quantization is performed for each subspace. On the other hand, an increase in N_{sub} requires additional distance computations etc., then more inference time.

H.2 Clustering

The original kNN-LM uses an inverted file index (IVF) technique that speeds up the search by dividing the representation into N_{list} clusters by k-means and searching for neighbors based on N_{probe} centroids. In this study, we evaluate the UE performance and inference speed when the number of clusters $N_{\text{list}} = 100$. In this study, we evaluate the UE performance and inference speed when the number of clusters $N_{\text{list}} = 100$ and applying PQ with $N_{\text{sub}} = 32$ are fixed and the number of cluster centroids to search changes$N_{\text{probe}} \in \{8, 16, 32, 64\}$ (In Table 7 and 8, IVF was performed with $N_{\text{probe}} = 32$).

Table 15 shows the performance of UE when changing N_{probe} in ID and OOD settings using OntoNotes 5.0. In ECE, scores are slightly reduced for ID, but only slightly worse for OOD; MCE also shows degradation for ID but little for OOD, and even improves when $N_{\text{probe}} = 8$; E-AURC shows almost no change in scores when N_{probe} is changed for both ID and OOD. In terms of inference time, the larger N_{probe}, the longer it takes. We derive the improvement in MCE when increasing N_{probe} in ID setting from the fact that more clusters are targeted, making it possible to cover ground-truth nearest neighbor examples. On the other hand, the tendency of slight decrease when increasing N_{probe} in OOD setting may comes from the reliability of the vector, similar to the discussion in Section 6.3.

In addition, Taken together with the results in Table 7 in Section 7.3, we can see that the degradation of the UE performance can be mitigated with improvement latency when applying PQ and IVF with lower N_{probe}, compared to applying PQ, IVF and PCA simultaneously.

[10] For example, raw datastore in kNN-UE is 636MB on OntoNotes 5.0 bn, but PQ reduces it to 10MB.

Methods	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]
	OntoNotes 5.0 bn (In-domain)			
SR	7.79±0.53	50.07±24.15	21.90±1.31	2.49±0.08
kNN-UE (w/o label)	3.37±0.71	33.15±3.65	17.63±0.66	4.94±0.10
kNN-UE	1.78±0.32	26.02±13.72	20.14±1.27	4.99±0.07
kNN-UE ($N_{\text{probe}} = 8$)	1.82±0.28	30.18±16.77	20.14±1.21	2.84±0.08
kNN-UE ($N_{\text{probe}} = 16$)	1.86±0.25	29.48±16.91	20.13±1.21	3.11±0.03
kNN-UE ($N_{\text{probe}} = 32$)	1.92±0.31	28.55±11.24	20.13±1.22	3.31±0.06
kNN-UE ($N_{\text{probe}} = 64$)	1.83±0.28	27.00±9.43	20.14±1.21	3.71±0.06
	OntoNotes 5.0 nw (Out-of-domain)			
SR	17.05±0.69	37.06±3.13	81.49±4.17	5.75±0.27
kNN-UE (w/o label)	8.78±0.62	24.91±1.81	70.10±4.03	10.36±0.21
kNN-UE	7.50±0.42	16.53±2.61	74.27±5.43	10.48±0.12
kNN-UE ($N_{\text{probe}} = 8$)	7.52±0.41	16.01±1.92	74.33±5.37	6.09±0.28
kNN-UE ($N_{\text{probe}} = 16$)	7.56±0.36	16.93±3.38	74.31±5.39	6.65±0.17
kNN-UE ($N_{\text{probe}} = 32$)	7.60±0.41	17.12±2.35	74.34±5.35	7.33±0.21
kNN-UE ($N_{\text{probe}} = 64$)	7.53±0.40	17.28±2.45	74.33±5.37	7.89±0.12

Table 15: ECE, MCE, E-AURC and inference time results about NER on OntoNotes 5.0 bn (In-domain) and OntoNotes 5.0 nw (Out-of-domain) for $\text{mDeBERTaV3}_{\text{BASE}}$ model when applied IVF in different N_{probe}.

Methods	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]
	OntoNotes 5.0 bn (In-domain)			
SR	7.79±0.53	50.07±24.15	21.90±1.31	2.49±0.08
kNN-UE (w/o label)	3.37±0.71	33.15±3.65	17.63±0.66	4.94±0.10
kNN-UE	1.78±0.32	26.02±13.72	20.14±1.27	4.99±0.07
kNN-UE ($D_{\text{pca}} = 64$)	1.89±0.37	31.01±14.35	20.06±1.25	3.24±0.08
kNN-UE ($D_{\text{pca}} = 128$)	1.80±0.36	27.85±13.80	20.13±1.29	3.41±0.10
kNN-UE ($D_{\text{pca}} = 256$)	1.80±0.40	26.23±12.61	20.13±1.28	3.85±0.06
	OntoNotes 5.0 nw (Out-of-domain)			
SR	17.05±0.69	37.06±3.13	81.49±4.17	5.75±0.27
kNN-UE (w/o label)	8.78±0.62	24.91±1.81	70.10±4.03	10.36±0.21
kNN-UE	7.50±0.42	16.53±2.61	74.27±5.43	10.48±0.12
kNN-UE ($D_{\text{pca}} = 64$)	7.48±0.41	16.20±2.75	74.33±5.49	7.37±0.26
kNN-UE ($D_{\text{pca}} = 128$)	7.54±0.45	16.42±2.73	74.30±5.44	7.75±0.24
kNN-UE ($D_{\text{pca}} = 256$)	7.56±0.43	16.13±2.59	74.26±5.40	8.51±0.46

Table 16: ECE, MCE, E-AURC and inference time results about NER on OntoNotes 5.0 bn (In-domain) and OntoNotes 5.0 nw (Out-of-domain) for $\text{mDeBERTaV3}_{\text{BASE}}$ model when applied PCA in different D_{pca}.

H.3 Dimension Reduction

In general, Transformer-based models such as PLM have high-dimensional token representations. In high-dimensional spaces, nearest neighbor search often suffer from the curse of dimensionality. To reduce this problem, we apply dimension reduction to kNN-UE similar to He et al. (2021a). In this study, we use Principal Component Analysis (PCA) as a dimension reduction algorithm to reduce the dimension of the datastore representations and the query representation D_{pca} (In Table 7 and 8, PCA was performed with $D_{\text{pca}} = 128$). As shown in Table 16, the UE performance depends on the number of target dimensions, and the performance degrades when $D_{\text{pca}} = 64$ or $D_{\text{pca}} = 128$. On the other hand, the performance in $D_{\text{pca}} = 256$ is almost the same as default kNN-UE. This suggests that excessive dimension reduction in distance computation to extract nearest examples by kNN search could have a negative impact on the UE performance.

Methods	ECE (↓)	MCE (↓)	E-AURC (↓)	time [s]
	OntoNotes 5.0 bn (In-domain)			
kNN-UE	1.78±0.32	26.02±13.72	20.14±1.27	4.99±0.07
kNN-UE (Approx.)	2.14±0.37	33.52±10.84	20.12±1.26	2.87±0.04
kNN-UE (Recomp.)	2.35±0.44	30.47±7.50	20.16±1.17	16.24±0.77
	OntoNotes 5.0 nw (Out-of-domain)			
kNN-UE	7.50±0.42	16.53±2.61	74.27±5.43	10.48±0.12
kNN-UE (Approx.)	8.08±0.53	24.03±5.46	74.50±5.42	6.20±0.20
kNN-UE (Recomp.)	8.30±0.51	25.67±5.26	74.58±5.53	34.22±0.78

Table 17: ECE, MCE, E-AURC and inference time results about NER on OntoNotes 5.0 bn (In-domain) and OntoNotes 5.0 nw (Out-of-domain) when applying distance recomputation in kNN-UE. "Approx." indicates using approximate distances, and "Recomp." indicates using exact distances by distance recomputation. Both "Approx." and "Recomp." are applied PQ with $N_{\text{sub}} = 32$, clustering with $N_{\text{probe}} = 32$ and dimension reduction with $D_{\text{pca}} = 128$.

I Distance Recomputation for kNN-UE

When using efficient kNN search techniques in Section 7.3, we use approximate distances to compute Eq. 4. Although we can get raw vectors by using the example indices obtained from approximate nearest neighbor search and compute accurate distance, in kNN-LM this has been shown to lead to performance gains and latency degradation (He et al., 2021a). We measure the UE performance and inference speed when PQ, clustering, and dimension reduction are applied simultaneously and re-computing accurate distances, reported in Table 17. These results show that the UE performance does not improve except for MCE in the ID setting, and the latency is about 5-7x slower when reading raw vectors from the datastore and re-computing distances. Moreover, these results suggest that exact distance computation for examples that are not actually nearest neighbors are not very effective in kNN-UE.

J Licenses of Datasets, Tools and Models

Datasets The IMDb movie dataset can be used for research purposes as described in https://developer.imdb.com/non-commercial-datasets/. Yelp Polarity dataset can be used for academic purposes as described in https://s3-media0.fl.yelpcdn.com/assets/srv0/engineering_pages/f64cb2d3efcc/assets/vendor/Dataset_User_Agreement.pdf. The MNLI dataset is licensed for research purposes as described in Williams et al. (2018). The SNLI dataset can be used for research purposes as described in https://nlp.stanford.edu/projects/snli/.

OntoNotes 5.0 dataset can be used for research purposes as described in https://catalog.ldc.upenn.edu/LDC2013T19.

Tools `transformers` is licensed by Apache-2.0. `faiss` is MIT-licensed.

Models $\mathrm{DeBERTaV3}_{\mathrm{BASE}}$ and $\mathrm{mDeBERTaV3}_{\mathrm{BASE}}$ from Huggingface model checkpoints are MIT-licensed.