# GraM-Diff: A Unified Graph–Mamba Diffusion Framework for EEG-Based Alzheimer's Disease Data Generation and Diagnosis

**Abstract.** Electroencephalography (EEG) is a promising, non-invasive, and cost-effective modality for Alzheimer's disease (AD) detection, but deep learning methods are limited by small and imbalanced clinical datasets. Generative augmentation offers a solution, yet existing approaches rely on inefficient class-specific models or fail to capture complex spatial and temporal brain dynamics. To address this, we propose GraM-Diff, a unified classifier-guided Graph–Mamba diffusion framework for EEG synthesis. It embeds Graph Convolutional Networks within a diffusion U-Net to model inter-electrode connectivity and Bidirectional Mamba state-space blocks for linear-complexity long-range temporal modeling. Latent-space classifier guidance lets a single model generate both healthy and pathological EEG within a shared representation, avoiding fragmented per-cohort pipelines. Across four EEG-based AD benchmarks, synthetic augmentation improves classification, yields superior Context-FID and correlation scores over strong generative baselines, and enhances robustness in data-scarce settings.

**Keywords:** Alzheimer's disease · EEG · diffusion models · generative AI · graph neural networks · state–space models

## 1 Introduction

Alzheimer's Disease (AD) is a progressive neurodegenerative disorder and the leading cause of dementia worldwide, marked by amyloid-beta plaques and hyperphosphorylated tau tangles that drive synaptic dysfunction [16]. Roughly 7.2 million Americans aged 65+ live with AD, projected to reach 13.8 million by 2060 [3]. Because AD has a long preclinical phase and approved disease-modifying therapies are most effective early, scalable early-diagnostic strategies are critical. Electroencephalography (EEG) is a non-invasive, cost-effective modality for detecting cognitive-decline biomarkers, with accessibility and high temporal resolution well-suited to longitudinal assessment. Computational EEG analysis has progressed from handcrafted spectral/complexity features with classical classifiers [16] to deep CNN [1], GNN [9], and Transformer [20] architectures; Denoising Diffusion Probabilistic Models (DDPMs) have recently emerged for EEG synthesis under limited data [18].

Despite this progress, annotated EEG remains scarce. Existing generative approaches often use *separate* models for healthy and pathological cohorts, increasing overhead and reducing flexibility. Public AD-EEG corpora are small: even combining AD-Auditory, ADSZ, APAVA, and BrainLat yields limited subject counts for high-capacity training [19], while class imbalance and privacy-driven data silos (GDPR, HIPAA) further hinder generalization [17].

To address these challenges, we propose GraM-Diff, a unified Graph–Mamba diffusion framework that combines topology-aware spatial modeling with long-range temporal modeling in a single generative architecture. Unlike perturbation-based augmentation, it directly generates multichannel EEG conditioned on diagnostic state while preserving spatio-temporal structure relevant to downstream classification [15,5]. Our key contributions are: **(i)** a *unified classifier-guided DDPM* that conditions a single generator on diagnostic state via latent-space guidance, enabling scalable class-conditioned multichannel EEG generation within a shared representation rather than per-cohort generators; **(ii)** *topology-aware spatial modeling*, integrating graph-based spatial priors directly into a diffusion U-Net to capture non-Euclidean inter-electrode relationships [9]; **(iii)** *linear-complexity temporal modeling* via Bidirectional Mamba state-space blocks with $\mathcal{O}(L)$ cost over extended recordings [8]; and **(iv)** *noise-robust LogRoPE guidance*, using patch-embedding conditioning with Logarithmic Rotary Positional Embeddings for stable representation learning under diffusion noise [20].

## 2   Related Work

**Discriminative EEG-AD models.** AD diagnosis has evolved from statistical modeling to deep architectures [16], including 3D CNNs on spatio-temporal-spectral tensors [1] and ensembles over raw EEG. These typically treat channels as independent sequences or grid images, ignoring the explicit graph topology of brain connectivity [9]. Multi-granularity Transformers model multiple time scales for EEG-AD assessment [20] but incur quadratic complexity on long recordings and have not been used generatively.

**Data scarcity and generative augmentation.** Aggregated public AD-EEG corpora contain few subjects (often $< 330$), making high-capacity training prone to overfitting [19]. GAN-based augmentation can improve accuracy [5] but suffers training instability and mode collapse and usually synthesizes features rather than raw multichannel signals. Diffusion models offer stabler training and avoid mode collapse [18], and have been applied to EEG super-resolution and psychiatric classification [15]. Yet existing EEG diffusion models are generally not conditioned on AD pathology and lack classifier guidance to retain disease-specific signatures.

Recurrent neural networks and Transformers often struggle with long-sequence EEG modelling, either due to vanishing-gradient issues or the quadratic computational cost of self-attention. Mamba state-space models address these limitations through linear-time sequence modelling, making them suitable for efficient long-range temporal representation learning [8]. In GraM-Diff, we incor-

porate a bidirectional Mamba block within the diffusion bottleneck to capture both causal and anti-causal dependencies across extended EEG recordings. Over-all, GraM-Diff combines topology-aware spatial priors, linear-time bidirectional Mamba modelling, and LogRoPE-based multi-granular conditioning within a unified generative–discriminative framework.

## 3  Proposed Methodology

As shown in Fig. 1, GraM-Diff combines spatial electrode relationships and long-range temporal modeling within a single architecture, together with a latent-space guidance mechanism, to generate Alzheimer's stage-conditioned EEG.

### 3.1  Problem Formulation and Diffusion Process

Let the clean multichannel EEG signal be $\mathbf{X}_0 = [x_1, \ldots, x_L] \in \mathbb{R}^{B \times C \times L}$, where $B$ is the batch size, $C$ the number of channels, and $L$ the temporal length. Following the DDPM paradigm to model $q(\mathbf{X}_0)$, the denoising network operates on latent features $\mathbf{h}^t \in \mathbb{R}^{B \times C \times L \times D}$ extracted by the U-Net encoder at timestep $t$. The forward process corrupts $\mathbf{X}_0$ into $\mathbf{X}_t$ over $t \in \{1, \ldots, T\}$ ($T$=1000) as a Gaussian Markov chain:

$$q(\mathbf{X}_t \mid \mathbf{X}_0) = \mathcal{N}\big(\mathbf{X}_t; \sqrt{\bar{\alpha}_t}\,\mathbf{X}_0, (1 - \bar{\alpha}_t)\mathbf{I}\big), \qquad \bar{\alpha}_t = \prod_{i=1}^{t}(1 - \beta_i), \qquad (1)$$

with $\beta_i \in (0, 1)$. Because linear schedules abruptly destroy fine-grained high-frequency EEG structure, we adopt a cosine schedule $\bar{\alpha}_t = f(t)/f(0)$, $f(t) = \cos^2\big(\frac{t/T+s}{1+s} \cdot \frac{\pi}{2}\big)$ with $s$=0.008. The network is trained to predict the clean signal $\hat{\mathbf{X}}_0$ rather than the injected noise; the noise term is recovered analytically as $\epsilon_\theta(\mathbf{h}^t, t) = (\mathbf{X}_t - \sqrt{\bar{\alpha}_t}\hat{\mathbf{X}}_0)/\sqrt{1 - \bar{\alpha}_t}$ and used in classifier-guided sampling. Diffusion and guidance operate on sequence-first tensors $\mathbb{R}^{B \times L \times C}$, internally permuted to channel-first $\mathbb{R}^{B \times C \times L}$ for U-Net and GCN processing.

### 3.2  Stage 1: Topology-Aware Spatial Encoding (GCN)

Standard convolutions treat EEG channels as grid-adjacent rows, ignoring scalp geometry. We instead pass $\mathbf{X}_t$ through a GCN with electrodes as nodes. Using 3D coordinates $\mathbf{c}_i \in \mathbb{R}^3$ from the International 10–20 system, a geometry-informed adjacency $\mathbf{A} \in \mathbb{R}^{C \times C}$ is built with a distance-based Gaussian kernel,

$$A_{ij} = \begin{cases} \exp\big(-\|\mathbf{c}_i - \mathbf{c}_j\|^2/2\gamma^2\big) & \text{if } \|\mathbf{c}_i - \mathbf{c}_j\| \leq \tau \\ 0 & \text{otherwise,} \end{cases} \qquad (2)$$

with kernel width $\gamma$=2.0 cm and sparsity threshold $\tau$=8.0 cm. We apply the renormalized propagation operator $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A}+\mathbf{I}_C)\tilde{\mathbf{D}}^{-\frac{1}{2}}$, where $\tilde{\mathbf{D}}_{ii} = \sum_j (\mathbf{A}+\mathbf{I}_C)_{ij}$ and the self-loops $\mathbf{I}_C$ preserve each electrode's intrinsic signal. Spatial

aggregation yields $\mathbf{H}_{\text{spatial}} = \text{LayerNorm}(\sigma(\hat{\mathbf{A}}\mathbf{X}_t\mathbf{W}_{\text{gnn}})) \in \mathbb{R}^{B \times C \times D}$ with learnable $\mathbf{W}_{\text{gnn}} \in \mathbb{R}^{L \times D}$ and ReLU $\sigma(\cdot)$. In practice we adopt a fixed, fully connected adjacency as a neutral prior, preserving permutation-invariant message passing while letting the network learn functional connectivity in a data-driven manner; this also admits anatomically informed topologies without architectural change. $\mathbf{H}_{\text{spatial}}$ serves as a spatial inductive bias for temporal modeling.

### 3.3   Stage 2: Hierarchical Temporal Encoder–Decoder

The U-Net encoder is a recurrence over $N=4$ downsampling levels, initialized by $\mathbf{H}^{(0)} = \mathbf{H}_{\text{spatial}}$. The diffusion timestep is encoded with sinusoidal embeddings $\mathbf{t}_{emb}$ projected by a SiLU-MLP and injected into each ResNet block as a learned bias shift, giving $\mathbf{S}^{(l)} = \mathbf{H}^{(l)} + \text{Conv1D}_{out}(\text{SiLU}(\text{GroupNorm}(\mathbf{h}_{res}^{(l)} + \mathbf{h}_{scale}^{(l)})))$, with $\mathbf{h}_{res}^{(l)} = \text{SiLU}(\text{GroupNorm}(\text{Conv1D}_{in}(\mathbf{H}^{(l)})))$ and $\mathbf{h}_{scale}^{(l)} = \text{MLP}(\text{SiLU}(\mathbf{t}_{emb}))$. Each $\mathbf{S}^{(l)}$ is stored as a skip connection and downsampled ($K=4$, stride 2); the compressed code $\mathbf{Z} = \mathbf{H}^{(N)}$ enters the bottleneck. The decoder mirrors the encoder: at each level the map is upsampled by transposed convolution, fused with the matching skip $\mathbf{D}_{fused}^{(l)} = \text{Concat}(\mathbf{D}_{\uparrow}^{(l)}, \mathbf{S}^{(N-1-l)})$, and processed by a time-conditioned ResNet block, starting from $\mathbf{D}^{(0)} = \mathbf{Z}_{out}$ (Stage 3). The decomposition heads then map the output to $\hat{\mathbf{X}}_0 = \mathbf{V}_{trend} + \mathbf{S}_{season}$.

### 3.4   Stage 3: Mamba Bottleneck for Long-Range Temporal Modeling

At the bottleneck, self-attention is replaced by a Bidirectional Mamba block, giving input-dependent long-range modeling with linear complexity $\mathcal{O}(L)$ versus the $\mathcal{O}(L^2)$ cost of Transformers. The underlying SSM has a diagonal state matrix $\mathbf{A} \in \mathbb{R}^{D \times N}$, input matrix $\mathbf{B} \in \mathbb{R}^{D \times N}$, and learns an input-dependent step size $\boldsymbol{\Delta}_k$ per position $k$:

$$\boldsymbol{\Delta}_k = \text{Softplus}(\text{Linear}(\mathbf{Z}_k)), \tag{3}$$

$$\overline{\mathbf{A}}_k = \exp(\boldsymbol{\Delta}_k \odot \mathbf{A}), \quad \overline{\mathbf{B}}_k = (\boldsymbol{\Delta}_k \odot \mathbf{A})^{-1}(\overline{\mathbf{A}}_k - \mathbf{I}) \odot (\boldsymbol{\Delta}_k \odot \mathbf{B}), \tag{4}$$

where $\odot$ is broadcast element-wise multiplication. The adaptive $\boldsymbol{\Delta}_k$ acts as a learned sampling rate: small values capture high-frequency transients, large values model slow background rhythms. We aggregate non-causal context with bidirectional scans $\mathbf{Z}_{mamba} = \text{Linear}(\text{Concat}(\mathbf{h}^{\rightarrow}(\mathbf{Z}), \mathbf{h}^{\leftarrow}(\mathbf{Z})))$ and decompose the latent into a polynomial trend $\mathbf{V}_{trend} = \mathcal{C} \cdot \text{Conv1D}(\text{GELU}(\text{Conv1D}(\mathbf{Z}_{mamba})))$ and a Fourier seasonality $\mathbf{S}_{season} = \mathcal{F}^{-1}(\text{TopK}(\mathcal{F}(\mathbf{Z}_{mamba})))$, with $\mathbf{Z}_{out} = \mathbf{V}_{trend} + \mathbf{S}_{season}$. This separates slow morphological drifts from fast oscillations as an inductive bias, but is trained end-to-end without strict stationarity or periodicity constraints.

### 3.5   Stage 4: Latent-Space Guidance Classifier

Guidance operates on the intermediate latent $\mathbf{h}^t$ rather than the heavily corrupted raw signal $\mathbf{X}_t$, keeping the classifier robust to early diffusion noise while

enforcing pathology-relevant patterns. Given the noisy latent $\mathbf{X}_t \in \mathbb{R}^{B \times L \times C}$, we build multi-granular temporal tokens by partitioning the signal into overlapping patches $\{P_k\}_{k=1}^G$ ($G{=}3$, $P_1{=}16$, $P_2{=}32$, $P_3{=}64$) and projecting each into a shared $D$-dimensional space, $\mathbf{E}_t^{(k)} \in \mathbb{R}^{B \times N_k \times D}$, alongside channel-wise tokens $\mathbf{E}_c^{(m)} \in \mathbb{R}^{B \times C \times D}$ ($M{=}1$). To stabilize attention over long sequences we apply logarithmically-scaled rotary positional encoding with rotation angle

$$\Theta_j(\mathrm{pos}) = \mathrm{base}^{-\frac{2\lfloor j/2 \rfloor}{D}} \cdot \log(\mathrm{pos} + 1), \qquad \mathrm{base} = 10000, \tag{5}$$

which moderates positional growth and improves numerical stability. The tokens are concatenated into $\mathbf{H}_0 = \mathrm{Concat}(\mathbf{E}_t^{(1)}, \ldots, \mathbf{E}_t^{(G)}, \mathbf{E}_c^{(1)}, \ldots, \mathbf{E}_c^{(M)}) \in \mathbb{R}^{B \times N \times D}$ ($N = \sum_k N_k + M \cdot C$) and processed by $L_{\mathrm{enc}}{=}6$ time-conditioned Transformer layers, with $t$ injected through adaptive layer normalization; a global attention-pooling head yields $\mathbf{h} \in \mathbb{R}^{B \times K}$ over $K$ disease categories. During sampling, the noise prediction is modified as

$$\tilde{\epsilon}_t = \epsilon_\theta(\mathbf{h}^t, t) - s\sqrt{1 - \bar{\alpha}_t}\, \nabla_{\mathbf{h}^t} \log p_\phi(y \mid \mathbf{h}^t), \tag{6}$$

where $s \in [1, 5]$ controls guidance strength and the factor $\sqrt{1 - \bar{\alpha}_t}$ preserves stability. To preserve oscillatory structure we optimize a dual-domain loss combining time-domain reconstruction and frequency-domain spectral constraints,

$$\mathcal{L} = \|\mathbf{X}_0 - \hat{\mathbf{X}}_0\|_1 + \lambda \sum_{p \in \{\mathrm{Re}, \mathrm{Im}\}} \|p(\mathcal{F}(\mathbf{X}_0)) - p(\mathcal{F}(\hat{\mathbf{X}}_0))\|_1, \tag{7}$$

with $\mathcal{F}$ the discrete Fourier transform and $\lambda{=}0.1$. Predicting $\mathbf{X}_0$ directly improves training stability and enables spectral preservation for physiologically realistic synthesis.

## 4 Experiments and Results

### 4.1 Datasets and Implementation

We evaluate on three public EEG datasets, all on a single NVIDIA RTX A4500 GPU (40 GB). **ADSZ** [2]: 19-channel EEG at 128 Hz, AD binary subset of 48 subjects (24 AD / 24 controls), 8–14 s trials. **APAVA** [7]: 16-channel EEG at 256 Hz, 23 subjects (12 AD / 11 controls), 5 s trials. **ADFD** [13]: 19-channel, 500 Hz, 88 subjects (36 AD, 23 FTD, 29 controls), long trials band-passed to 0.5–45 Hz; excluding FTD yields **ADFD-Binary** (65 subjects, 53,182 samples). The generator uses Adam ($\beta_1{=}0.9, \beta_2{=}0.96$) over 25,000 epochs with EMA weights; the downstream classifier is trained separately for 3,000 epochs (Adam, lr $1.0 \times 10^{-4}$).

### 4.2 Reliability of Generated EEG for AD Diagnosis

We use a subject-independent 80–20 split, train the diffusion model on the 80% subset, and synthesize $\sim$1.5$\times$ extra samples. Classifiers are trained *only* on synthetic data and evaluated on the unseen 20% real test set, comparing "Synthetic

Fig. 1: Architecture of GraM-Diff. EEG data are first passed through a GCN to obtain spatially enriched features. The U-Net encoder extracts hierarchical temporal representations, which enter a bidirectional Mamba bottleneck. The decoder reconstructs the denoised latent and decomposes it into trend and seasonal components. A time-conditioned transformer classifier operating on latent features provides gradients to guide the diffusion process.

Train (TSTR)" against "Real Train (TRTR)" on identical held-out data (Table 1). Models trained purely on synthetic AD data match or exceed the real-data baseline: ADFormer attains 97.14% on ADSZ under synthetic training, surpassing its real-data result (93.08%) and all competing architectures, and reaches 51.22% on the harder ADFD 3-Class task—indicating the generated signals retain diagnostically meaningful patterns that generalize to unseen subjects.

### 4.3   Comparison with Generative Peer Models

We compare synthesis quality against TimeGAN [23], TimeVAE [6], and Diffusion-TS [24], holding the downstream classifier strictly constant so differences reflect generative fidelity alone (Table 2). As TimeGAN and TimeVAE are single-class generators, we train one model per class and merge outputs for multi-class data. GraM-Diff outperforms all baselines across Accuracy, Precision, F1, AUROC, and AUPRC. On ADSZ it reaches 97.18% accuracy, far above Diffusion-TS (87.41%) under identical conditions and the segregated TimeGAN (69.81%) and TimeVAE (64.25%).

### 4.4   Generative Fidelity

We assess fidelity with Context-FID (distributional distance in deep feature space) and Correlation Score (preservation of spatio-temporal dependencies),

Table 1: Classification accuracy (%) trained on our generated data (Synthetic, TSTR) versus the original dataset (Real, TRTR), tested on identical held-out real data. A representative set of baselines is shown.

| Model | ADSZ | | APAVA | | ADFD Binary | | ADFD 3 Class | |
|---|---|---|---|---|---|---|---|---|
| | Syn | Real | Syn | Real | Syn | Real | Syn | Real |
| ADFormer [20] | **97.14** | 93.08 | **82.81** | 80.00 | **73.74** | 75.80 | **51.22** | 55.21 |
| Autoformer [22] | 93.61 | 91.43 | 69.89 | 68.64 | 61.31 | 59.81 | 44.28 | 45.25 |
| Informer [25] | 93.18 | 90.22 | 74.86 | 73.11 | 59.95 | 61.88 | 46.90 | 48.45 |
| ITransformer [12] | 78.91 | 78.79 | 75.01 | 74.55 | 71.44 | 73.85 | 49.97 | 52.60 |
| PatchTST [14] | 79.17 | 79.12 | 69.86 | 67.03 | 60.29 | 59.10 | 44.29 | 44.37 |
| Pyraformer [11] | 91.89 | 90.77 | 81.20 | 79.54 | 65.10 | 66.00 | 49.27 | 51.52 |
| TimesNet [21] | 92.59 | 92.75 | 76.31 | 76.30 | 60.27 | 61.79 | 47.14 | 48.81 |
| EEGNet [10] | 89.24 | 86.81 | 71.22 | 71.81 | 65.28 | 71.91 | 47.26 | 51.78 |
| TCN [4] | 82.18 | 88.90 | 80.29 | 84.71 | 59.21 | 68.71 | 42.38 | 50.17 |

Table 2: Comparison with state-of-the-art generative peer models across ADSZ, APAVA, and ADFD (Binary).

| Model | ADSZ | | | | | APAVA | | | | | ADFD (Binary) | | | | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | Acc | Prec | F1 | AUROC | AUPRC | Acc | Prec | F1 | AUROC | AUPRC | Acc | Prec | F1 | AUROC | AUPRC |
| TimeGAN [23] | 69.81 | 70.28 | 71.93 | 72.29 | 69.35 | 54.28 | 58.19 | 58.92 | 59.70 | 59.00 | 51.35 | 52.63 | 52.74 | 51.70 | 54.36 |
| TimeVAE [6] | 64.25 | 68.11 | 69.74 | 65.29 | 67.81 | 53.91 | 52.14 | 52.83 | 58.51 | 55.92 | 52.10 | 51.88 | 53.83 | 58.14 | 59.53 |
| Diffusion-TS [24] | 87.41 | 89.25 | 88.65 | 90.83 | 90.24 | 63.87 | 64.99 | 63.81 | 70.96 | 72.39 | 55.39 | 58.31 | 57.12 | 60.25 | 65.41 |
| **Ours** | **97.18** | **97.20** | **96.28** | **97.82** | **95.20** | **82.81** | **85.99** | **84.21** | **89.85** | **88.46** | **73.74** | **75.93** | **77.31** | **77.28** | **79.21** |

lower being better, against Diffusion-TS. GraM-Diff attains markedly lower Context-FID on every dataset (ADSZ 0.109 vs. 0.585; APAVA 0.286 vs. 0.426; ADFD-Binary 0.484 vs. 1.030; ADFD 3-Class 0.529 vs. 0.920) and tighter Correlation Scores (ADSZ 0.275 vs. 0.492; APAVA 0.402 vs. 0.829; ADFD-Binary 0.532 vs. 2.890; ADFD 3-Class 0.583 vs. 2.120), confirming closer agreement with real EEG dynamics.

### 4.5 Downstream Utility, Ablation, and Sensitivity

**Utility and augmentation.** Beyond statistical similarity, we test imputation (masking 10–90%), forecasting (horizons 4–32), and real/synthetic mixture classification. Errors stay low under heavy difficulty: on ADSZ, imputation MSE rises only to 0.108 at 90% masking and forecasting MSE remains 0.0501 at horizon 32. Augmentation accuracy is preserved even in heavily synthetic regimes (96.87% on ADSZ at 80% synthetic), confirming the synthetic data's value for limited clinical datasets.

**Ablation.** Removing components (Table 3, top) degrades performance, with Patch Embeddings + LogRoPE most critical: accuracy drops from 97.18% to 91.81% on ADSZ and from 82.81% to 69.65% on APAVA, underscoring its role in long-range temporal and positional modeling. The GNN and Mamba modules each contribute additional gains.

Table 3: Ablation (top) and Gaussian-noise sensitivity (bottom) on ADSZ and APAVA.

| Setup | ADSZ | | | APAVA | |
|---|---|---|---|---|---|
| | Acc | F1 | AUROC | Acc | AUROC |
| Full Model | **97.18** | **96.28** | **97.82** | **82.81** | **89.85** |
| w/o GNN | 95.80 | 94.99 | 96.82 | 79.31 | 84.83 |
| w/o Mamba | 95.23 | 95.28 | 95.27 | 78.45 | 82.36 |
| w/o Patch+LogRoPE | 91.81 | 92.84 | 95.43 | 69.65 | 67.52 |
| *Gaussian noise sensitivity* | | | | | |
| 0% (Base) | **97.18** | **96.28** | **97.82** | **82.81** | **89.85** |
| 10% | 79.20 | 81.54 | 85.35 | 71.77 | 78.42 |
| 20% | 72.98 | 77.31 | 75.30 | 62.85 | 71.20 |

**Sensitivity.** Injecting Gaussian noise (Table 3, bottom) degrades performance gracefully: on ADSZ the model retains an AUROC of 85.35% under 10% noise (vs. 97.82% baseline), with a similar trend on APAVA, indicating robustness to moderate signal perturbation.

## 5   Conclusion

We presented GraM-Diff, a unified classifier-guided Graph–Mamba diffusion framework coupling topology-aware spatial priors with linear-complexity long-range temporal modeling for conditional multichannel EEG synthesis. A single model generates both healthy and pathological signals within a shared latent space, producing high-fidelity samples that better match real distributions and improve downstream AD classification, with superior Context-FID and correlation scores and graceful robustness under noise. Future work will extend the framework to multimodal and irregularly sampled time series while improving scalability and controllability for clinical deployment.

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