

Unifying the Perspectives of NLP and Software Engineering: A Survey on Language Models for Code

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Abstract

In this work we systematically review the recent advancements in code processing with language models, covering 50+ models, 30+ evaluation tasks, 170+ datasets, and 700+ related works. We break down code processing models into general language models represented by the GPT family and specialized models that are specifically pretrained on code, often with tailored objectives. We discuss the relations and differences between these models, and highlight the historical transition of code modeling from statistical models and RNNs to pretrained Transformers and LLMs, which is exactly the same course that had been taken by NLP. We also discuss code-specific features such as AST, CFG, and unit tests, along with their application in training code language models, and identify key challenges and potential future directions in this domain.

1 Introduction

Language modeling has advanced remarkably in recent years with the advent of pretrained Transformers (Vaswani et al., 2017) such as BERT (Devlin et al., 2019) and GPT (Radford et al., 2018). As large language models (LLMs) scaled to hundreds of billions of parameters and started to display early signs of artificial general intelligence (Brown et al., 2020; Chowdhery et al., 2022; OpenAI, 2023), their applications have also transcended text processing. Pioneered by Codex (Chen et al., 2021b), LLMs have achieved impressive results in code processing, giving rise to commercial products such as GitHub Copilot¹ and open-source multi-billion code models such as StarCoder (Li et al., 2023h) and Code LLaMA (Rozière et al., 2023).

The application of pretrained Transformers in code processing, however, can be traced back to dates before decoder-only autoregressive models became dominant (Feng et al., 2020; Liu et al., 2020), and this domain is yet to witness a comprehensive review. In an attempt to bridge the gap between natural language processing (NLP) community and software engineering (SE) community on the topic of language model applications, we undertake a panoramic survey of language models for code in this work, covering 50+ models, 30+ downstream tasks, 170+ datasets, and 700 related works. We break down different categories of code language models, ranging from colossal models trained on general domains to tiny models trained specifically for code understanding or generation. We emphasize on the relations and differences between such models, and highlight the integration of code-specific features, such as abstract syntax trees or data flows, into language models, as well as the latest techniques adapted from NLP.

Related to our work, we are aware of several surveys on similar topics, with three works concurrent to us (Hou et al., 2023; Zheng et al., 2023b; She et al., 2023). These works, however, focus either on NLP side (Zan et al., 2023; Xu & Zhu, 2022) or SE side (Niu et al., 2023; Hou et al., 2023; Zheng et al., 2023b; She et al., 2023), and do not cover models, tasks, and challenges from the other side. For example, Zan et al. (2023) focus on LLMs for text-to-code generation, while giving little discussion of other evaluation tasks in software engineering community. Hou et al. (2023) and She et al. (2023), in contrast, comprehensively review works from SE venues such as ASE and ICSE, but cite only a handful of works from deep learning and NLP venues such as ACL, EMNLP, NeurIPS, and ICLR.

¹<https://github.com/features/copilot>

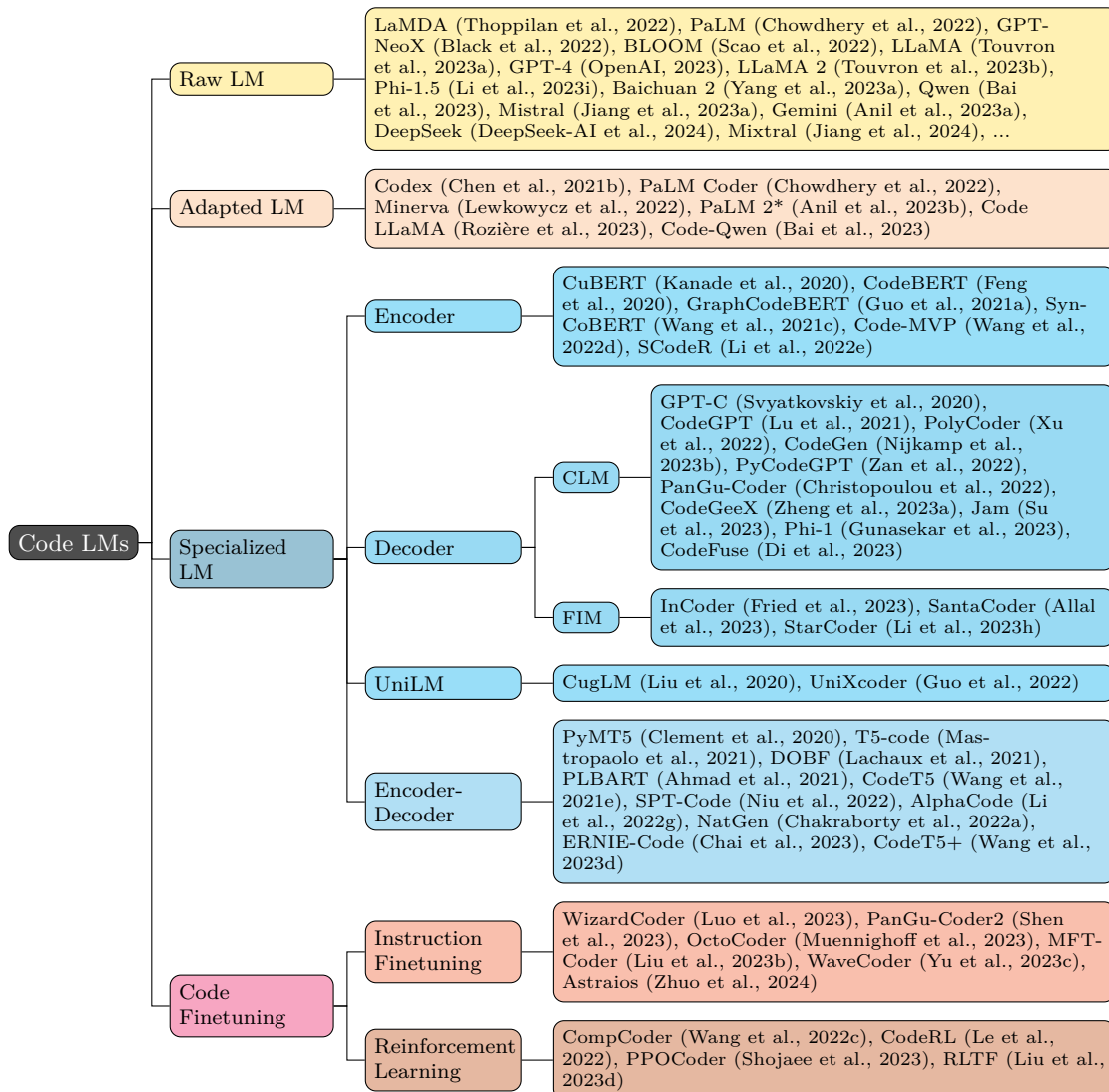


Figure 1: Our taxonomy of pretrained language models for code.

Thus, building on these works, we endeavor to unite the perspectives from both communities, and accentuate the integration between NLP and SE throughout the work. We make the key observation that advanced topics from language modeling have been recently introduced into code processing, including instruction tuning (Honovich et al., 2023; Xu et al., 2023a; Luo et al., 2023), infilling objectives (Tay et al., 2023b; Li et al., 2023h; Rozière et al., 2023), recontemplation of scaling laws (Hoffmann et al., 2022; Gunasekar et al., 2023; Li et al., 2023i), architectural improvements (Shazeer, 2019; Su et al., 2021; Dao et al., 2022), and autonomous agents (Qian et al., 2023; Hong et al., 2023), while in return SE requirements are providing real-world testbeds for these technologies and driving the development of LLMs forward into production. We believe a systematic review of these advancements would benefit both communities.

The rest of this work is organized following the taxonomy presented in Figure 1. In Section 2 we first contextualize the downstream tasks in code processing, highlighting the historical transition from various code understanding tasks to more practical text-to-code generation tasks. Then, in Section 3 we provide the preliminaries of language modeling and Transformer models, and in Section 4 we discuss the plethora of LLMs that have demonstrated coding ability. In Section 5 we review the specialized and often smaller models by their architecture, with special attention on the recent application of infilling objectives, instruction tuning,

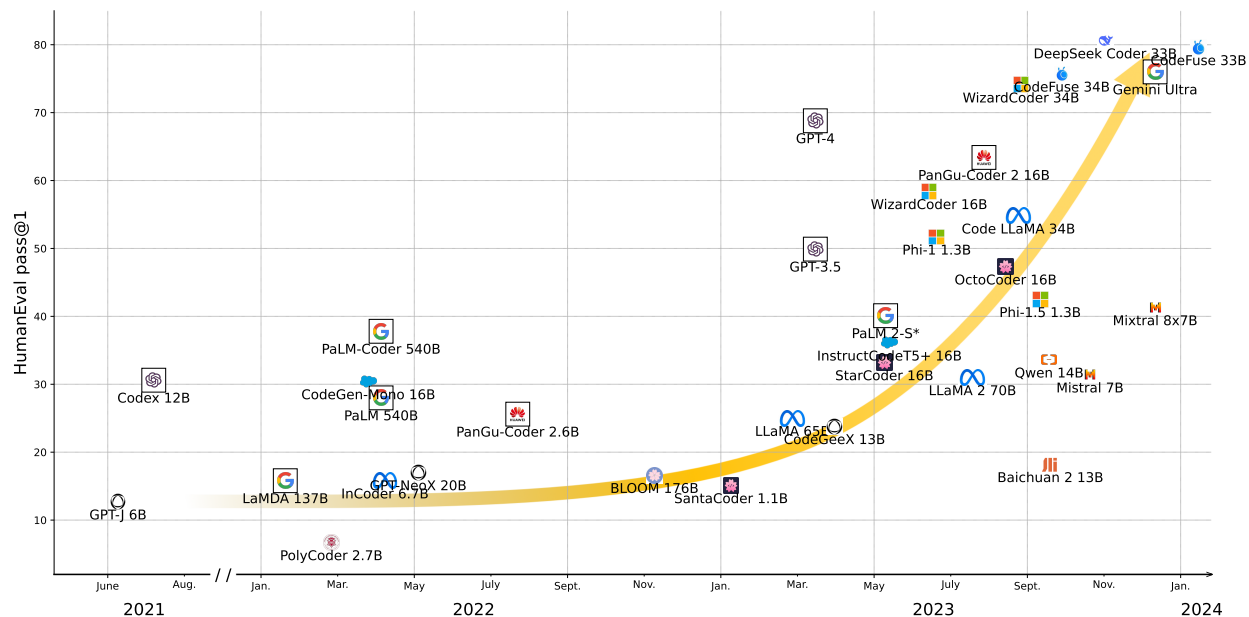


Figure 2: The timeline of code language models’ progress on HumanEval.

reinforcement learning, and engineering improvements. Then, in Section 6, we discuss unique features of code that are not available to natural languages but have been utilized to aid code processing. In Section 7, we review the most recent integration between LLMs and software development, before finally concluding this work in Section 8 and highlighting the current challenges in code processing.

2 Downstream Tasks in Code Processing

Over the past decade, various evaluation tasks have been proposed by the software engineering community to evaluate code models. CodeXGLUE (Lu et al., 2021) consolidates most of such tasks into a single benchmark covering code understanding tasks such as clone detection, defect detection, and sequence-to-sequence generation tasks such as code repair, code translation, program synthesis, and code summarization. After Chen et al. (2021b) introduced HumanEval and Codex, however, text-to-code synthesis was brought into the spotlight in the NLP community and has since become a standard task for evaluating LLMs (Figure 2). Accordingly, we first briefly introduce each of the traditional tasks and the application of pretrained language models in them in Section 2.1, and provide a comprehensive list of related works for each task. Then, we review the evaluation metrics in Section 2.2 and investigate program synthesis in more detail in Section 2.3. Lastly, we also discuss the latest trend of repository-level evaluation in Section 2.4. In Appendix A, we list benchmarks for each downstream task.

2.1 Downstream Tasks of Code Processing

Following the custom in software engineering, we categorize the evaluation tasks for code according to their input/output modality, and break down these tasks into five families: text-to-code, code-to-code, code-to-text, code-to-pattern, and text-to-text. We note that this taxonomy is interleaved with the understanding-generation dichotomy in NLP, since each category may contain both understanding and generation tasks, as discussed in Section 2.1.6.

2.1.1 Text-to-Code

Text-to-code tasks take text as input, and output code. Related methods are listed in Figure 3

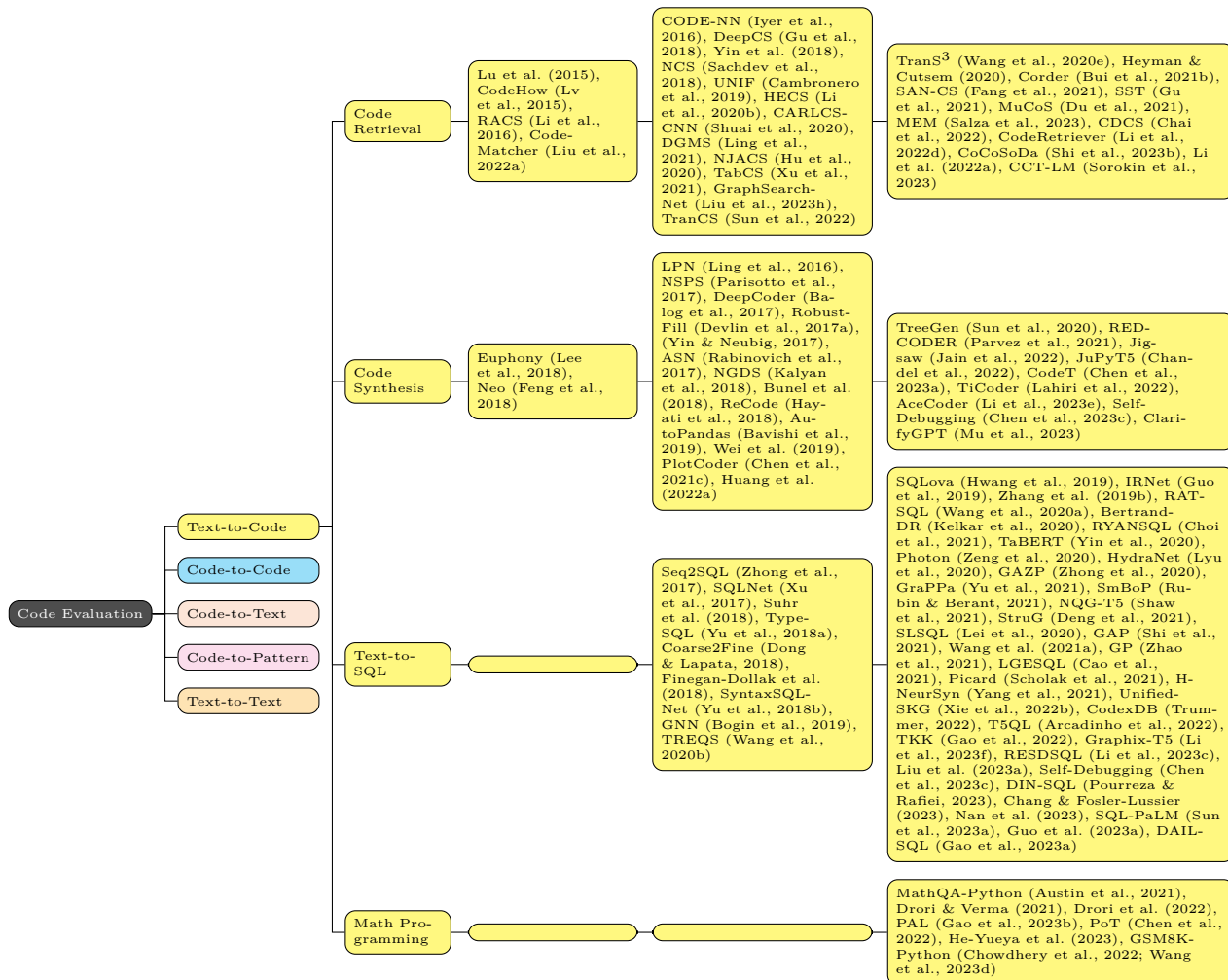


Figure 3: Evaluation tasks for code processing: models and methods for text-to-code tasks. For each task the first column is non-neural methods (mostly n-gram or TF-IDF based methods, but also including other heuristics based methods); the second column is non-Transformer neural methods; the third column is Transformer based methods. Pretrained code LMs such as CodeBERT, CodeGPT, and CodeT5 can be finetuned for multiple tasks, thus we omit their applications here to avoid cramming the page.

- *Code retrieval* aims to retrieve relevant code given natural language queries, or to mine parallel text-code pairs from an unannotated corpus. This task is usually performed by computing a similarity metric between the embedding of query and candidate code, and the contextual embeddings produced by bidirectional language models - such as BERT - has proven to be extremely helpful. Grazia & Pradel (2023) and Xie et al. (2023a) provide comprehensive reviews on this topic.

- *Code synthesis* aims to generate code (usually a function or a method) given a natural language description. This task can be viewed as an updated version of code retrieval using generative models instead of retrieval models. Statistical machine translation (SMT) and neural machine translation (NMT) models have been widely adopted for this task, often with enhanced decoders that leverage the unique grammatical rules of programming languages (Yin & Neubig, 2017; Rabinovich et al., 2017). Pretrained language models based on Transformer architecture, however, changed the game by directly generating the source code in the autoregressive language modeling style, even without task-specific finetuning (Chen et al., 2021b). We discuss this task in more detail in Section 2.3.

- *Text-to-SQL* is a special (and arguably easier) case of code synthesis, where the model is tasked to generate SQL commands from natural language queries. It has been a topic of special interest due to SQL’s structured nature (when compared with general-purpose languages such as Python and C) and wide application in data management. We refer to Kumar et al. (2022); Deng et al. (2022a); Qin et al. (2022a); Katsogiannis-Meimarakis & Koutrika (2023) for surveys on this topic.

- *Math programming* is also a special case of code synthesis, where a language model is required to solve mathematical reasoning problems via generating code that will be executed by external interpreters. This task abstracts the reasoning process from numerical calculations, and is thus of special interest in evaluating LLMs.

2.1.2 Code-to-Code

Code-to-code tasks take code as input, and output code. Related methods are listed in Figure 4 and 5

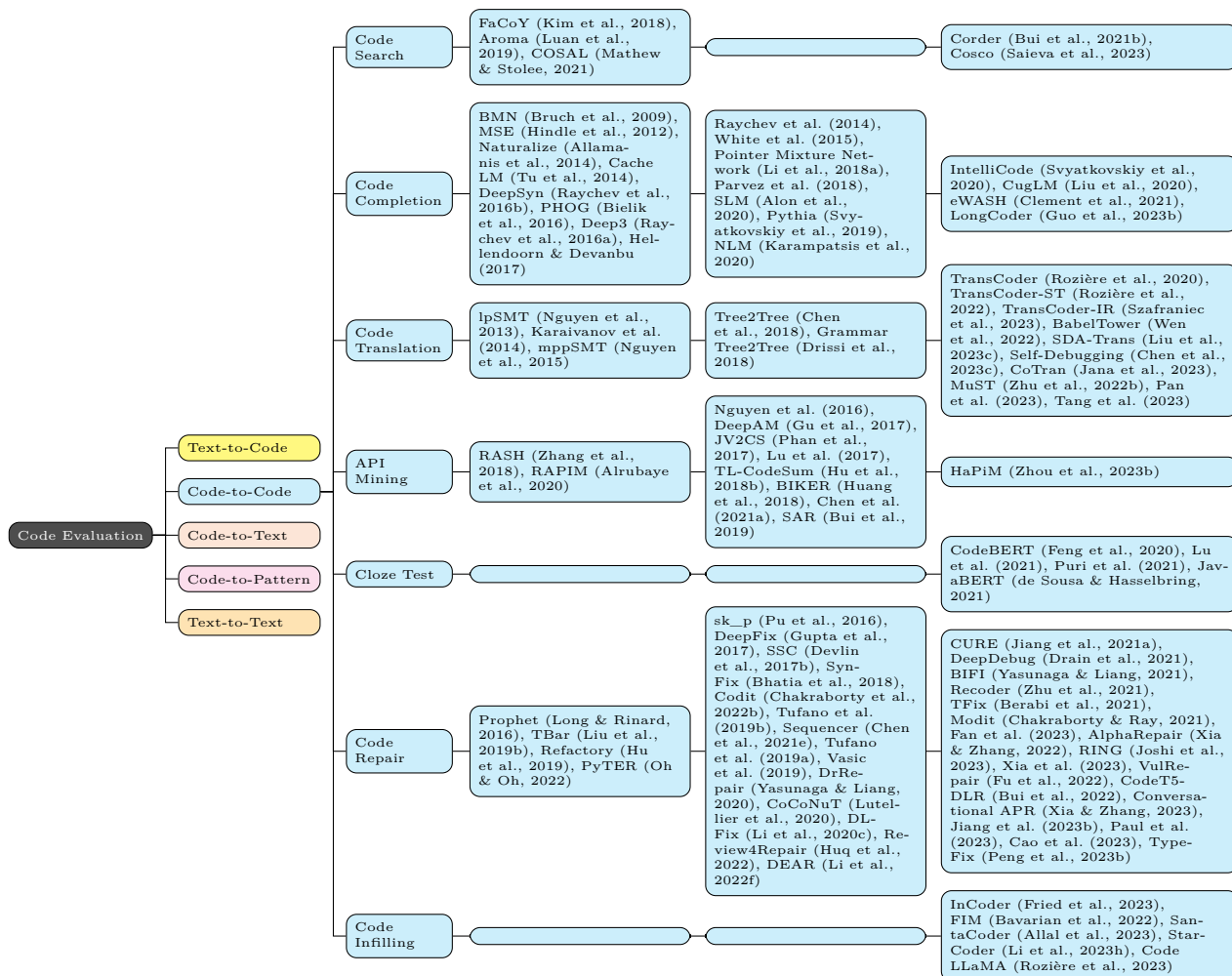


Figure 4: Evaluation tasks for code processing: models and methods for code-to-code tasks, part 1. For each task the first column is non-neural methods (mostly n-gram or TF-IDF based methods, but also including other heuristics based methods); the second column is non-Transformer neural methods; the third column is Transformer based methods. Pretrained code LMs such as CodeBERT, CodeGPT, and CodeT5 can be finetuned for multiple tasks, thus we omit their applications here to avoid cramming the page.

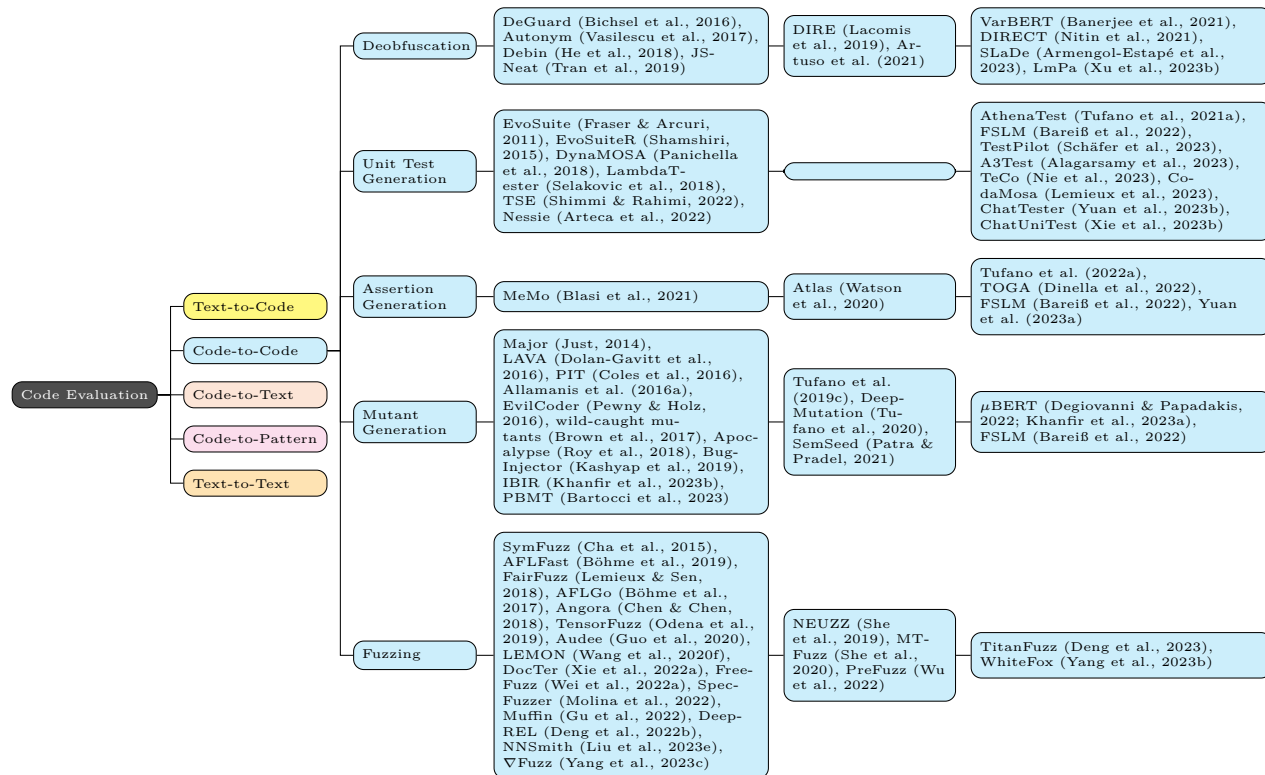


Figure 5: Evaluation tasks for code processing: models and methods for code-to-code tasks, part 2. For each task the first column is non-neural methods (mostly n-gram or TF-IDF based methods, but also including other heuristics based methods); the second column is non-Transformer neural methods; the third column is Transformer based methods. Pretrained code LMs such as CodeBERT, CodeGPT, and CodeT5 can be finetuned for multiple tasks, thus we omit their applications here to avoid cramming the page.

- *Code search* is a task similar to code retrieval, and differs from the later only in that the input is an existing code snippet, often in a different programming language from the target. Code search can be reformulated as finding clones of the query in the pool of targets, and is thus equivalent to clone detection to some extent.

- *Code completion* aims to complete a piece of code given its prefix, and remains to date one of the most popular applications of code language models in IDEs. This is essentially language modeling applied to code, and related technologies have been progressively introduced: n-gram, RNN, and Transformer. However, due to the structured nature of programming languages, many early works found grammar-aided statistical models to perform better (Bielik et al., 2016; Hellendoorn & Devanbu, 2017), and neural models only became dominant after 2018 (see Figure 4 for an intuitive overview.)

- *Code translation* aims to translate a piece of code (usually a function or method) into another programming language. The relation between code translation and cross-lingual code search is similar to the one between code synthesis and text-to-code retrieval, and SMT/MNT models have also been widely applied to this task. Code translation is an important technique in migrating old projects written in obsolete languages. However, we are yet to witness such applications, as the context window of even the most powerful language models are quite limited in the face of such projects. Malyala et al. (2023) provide a short survey on this task from the SE perspective.

- *API mining* refers to the process of finding similar APIs in different libraries, potentially in different programming languages. This task is closely related to *API migration* - a special case of code translation. API mining is traditionally tackled by computing similarity metrics between source and target APIs using information retrieval models, but as generative models become ever more capable, it is also worth exploring to directly generate the target API as a sequence-to-sequence task. Another closely related task is *idiom*

mining (Allamanis & Sutton, 2014), where the objective is to discover commonly used code patterns, which exposes the potential need of new APIs (Sivaraman et al., 2022).

- *Cloze test* is a recently proposed task for code understanding, after the rise of BERT-style pretraining. Due to the unique semantics of programming languages, several keywords are often selected for this test, such as `min` and `max` (Feng et al., 2020).

- *Code repair*, also known as bug fix, aims to fix a piece of buggy code. Like code translation, it is a traditional sequence-to-sequence generation task, and surveys are abundant on this topic (Gazzola et al., 2018; Monperrus, 2018; Zhong et al., 2022; Zhang et al., 2023c; Huang et al., 2023a). A generalization of code repair is *code edit* or *code change*, where the task is to model and predict code changes (such as Git commits), which are not necessarily about bug fixing.

- *Code infilling* is another recently proposed task, after fill-in-the-middle pretraining (Bavarian et al., 2022) became popular. It is a generalization of code completion, where not only the left context, but also the right context is given. However, it differs from cloze test in that the target of cloze test is only one token, while the target of code infilling can be an entire line or even multiple lines, which requires a decoder to generate autoregressively.

- *Obfuscation* refers to the process of renaming identifiers (e.g. variables, methods, and classes), for example to generic names like `var_1`, `var_2` or `x`, `y`. It is an important technique in virus detection, intellectual property protection, and code size reduction (Collberg & Thomborson, 2002; Murad et al., 2010; Vasilescu et al., 2017). *Deobfuscation* refers to the reverse process, where meaningful identifier names are recovered from obfuscated programs. Obfuscation can be easily achieved statically, but deobfuscation has been a subject of more interest in recent years. It plays a significant role in decompiling or reverse engineering, and has also been adopted as a pretraining objective for code language models (Lachaux et al., 2021; Ding et al., 2022a; Liu et al., 2022d).

- *Unit test generation* aims to generate unit tests for a given program. Prior to the rise of Codex and other code LLMs, almost all works in this area employed non-neural methods (see Figure 5). In the age of LLMs, however, this task is ever more important, as researches have shown that the current unit tests for evaluating LLMs’ program synthesis capability may be insufficient (Liu et al., 2023f).

- *Assertion generation* is a subtask of unit testing. Given a program and a partial unit test, this task aims to generate assertions (also known as *oracles* in software engineering) within the unit test. This task has generally went unnoticed by the NLP community, as the program synthesis task used for evaluating LLMs often concern standalone, competition-style methods, for which the simple assertion of the equality between program output and expected answer suffices.

- *Mutant generation* aims to generate mutants of a given program for the purpose of mutation testing, and relates closely to unit test generation and assertion generation. A mutant that is not detected by a given set of unit tests and assertions indicates that either additional test cases or better assertions are required (Fraser & Arcuri, 2011). Recently, masking out tokens in the source code and sampling them from the output of a masked language model has become a common method for this task. Ojdanic et al. (2021; 2023) give empirical comparisons between different mutation methods.

- *Fuzzing* is another software testing task, where the objective is to generate a large set of inputs covering as many corner cases as possible. While many recent works on fuzzing target deep learning libraries, few have utilized language models to conduct this process (see Figure 5).

2.1.3 Code-to-Text

Code-to-text tasks take code as input, and output text. Related methods are listed in Figure 6.

- *Code summarization*, also referred to as docstring generation, aims to generate a natural language description for a given piece of code (often a function or method). This is the opposite of code synthesis, and SMT/NMT techniques have been likewise applied. Zhang et al. (2022) provide a survey on this topic.

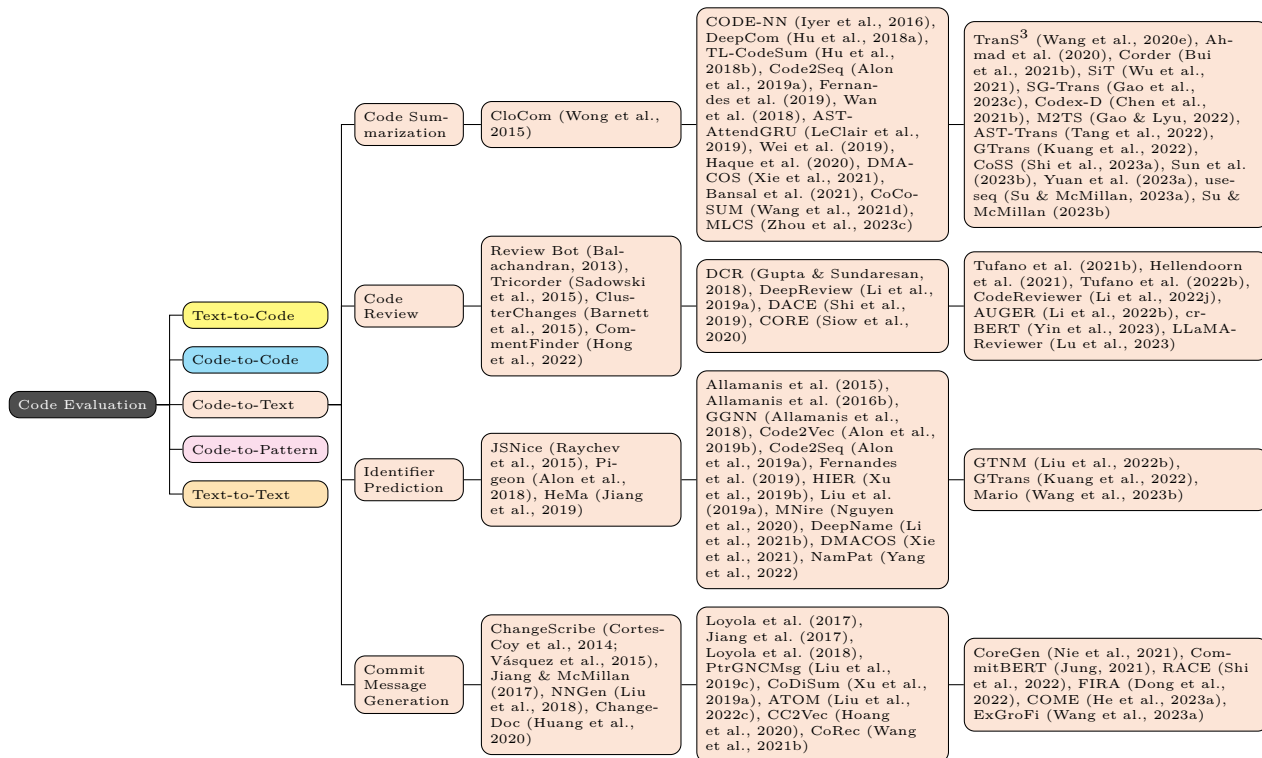


Figure 6: Evaluation tasks for code processing: code-to-text tasks. For each task the first column is non-neural methods (mostly n-gram or TF-IDF based methods, but also including other heuristics based methods); the second column is non-Transformer neural methods; the third column is Transformer based methods.

- *Code review* aims to automate the process of peer code review, and includes many subtasks, such as review necessity prediction, review comment generation, code refinement, and review decision prediction.

- *Identifier prediction* is the task of predicting identifier names in the code. As these names are deemed to contain important semantic information, this task has been utilized for code summarization (Allamanis et al., 2016b), as well as pretraining code models (Wang et al., 2021e; Niu et al., 2022). A special case of identifier prediction is *method name prediction*.

- *Commit message generation* aims to automatically generate commit messages for code changes. This task takes the code before and after change as input, and output the description for the change. This can be viewed as the dual task of program repair, as many code changes and their accompanying commit messages concern bug fixing. Tao et al. (2021) provide a survey on methods and datasets for this task up to 2021.

2.1.4 Code-to-Pattern

Code-to-pattern tasks conduct classification on code. Related methods are listed in Figure 7.

- *Type prediction* aims to predict the type of dynamic programming languages such as Python and JavaScript. It has been used as a pretraining objective for code language models (Wang et al., 2022d), where it is often simplified as a binary tagging task to predict which tokens in the code are identifiers (Wang et al., 2021c;e).

- *Defect detection* predicts whether the input code is buggy or not, and is a standard single-sentence classification task. Nong et al. (2023); Steenhoek et al. (2023); Bi et al. (2023); Harzevili et al. (2023) provide surveys on this task.

- *Clone detection* predicts whether or not two pieces of code are clones of each other. In software engineering there exist four types of code clones, and the most challenging type to identify is semantic clones, i.e.

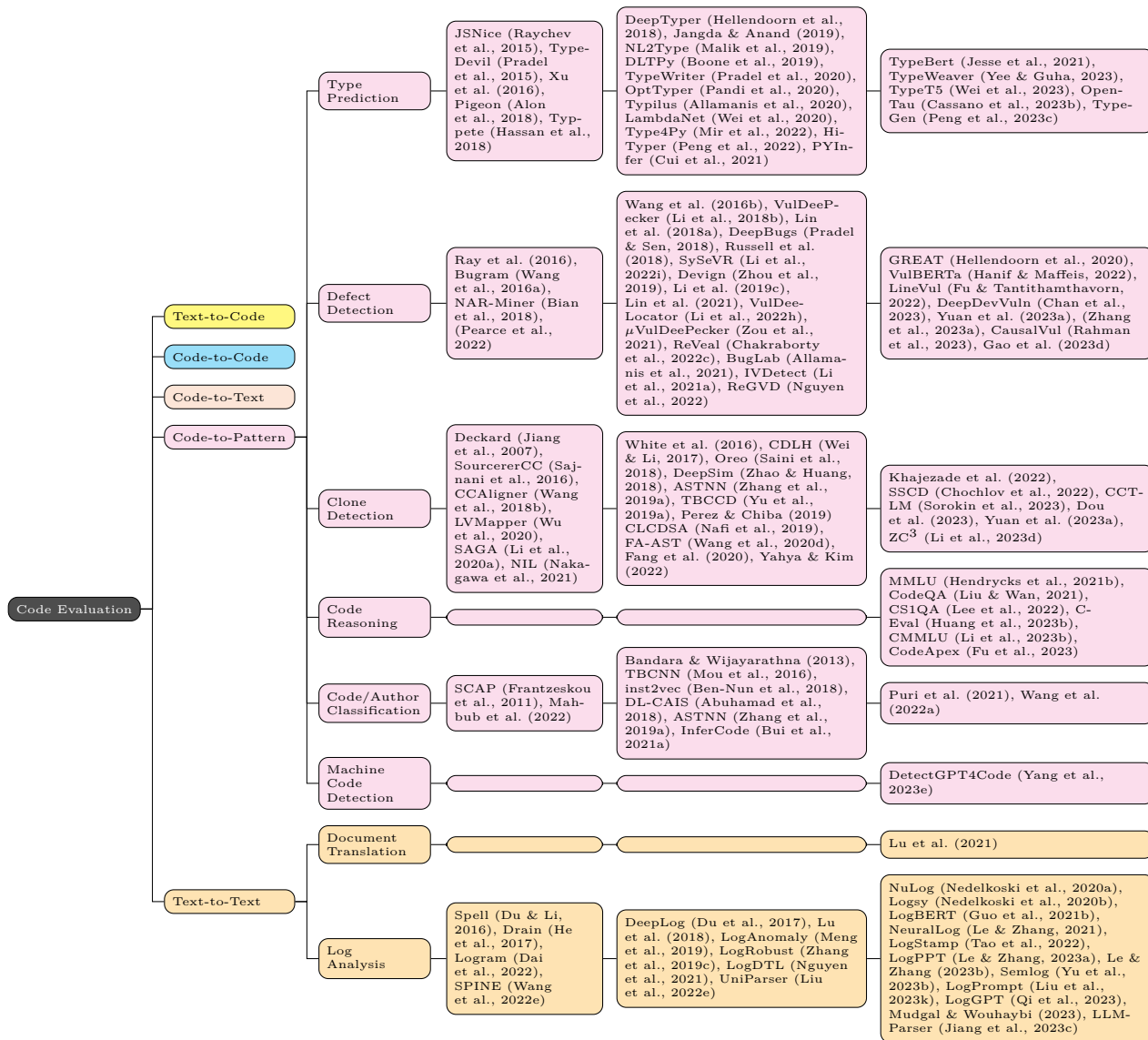


Figure 7: Evaluation tasks for code processing: code-to-pattern and text-to-text tasks. For each task the first column is non-neural methods (mostly n-gram or TF-IDF based methods, but also including other heuristics based methods); the second column is non-Transformer neural methods; the third column is Transformer based methods. We note that “method” differs from “target”. For example, Pearce et al. (2022) examine the code generated by GitHub Copilot for vulnerabilities, but the method they use is non-neural. Some tasks, such as code reasoning, are mainly proposed to evaluate LLMs, and we thus list benchmarks instead of methods.

syntactically dissimilar code that have the same functionality. As this task can be viewed as a two-sentence classification task, BERT-style language models have been widely applied to it. Svajlenko & Roy (2020) and Zhang & Sakurai (2021) provide comprehensive reviews on non-deep-learning based methods for this task.

- *Code reasoning* is a recently introduced task for evaluating LLMs, and often comes as a subset of general evaluation benchmarks such as MMLU (Hendrycks et al., 2021b). This task requires the model to reason about the code or algorithms, and answer related questions which are written in multiple-choice format or free-form QA format and may range from conceptual understanding to numerical calculation and complexity analysis.

- *Code classification* aims to predict the functionality of a piece of code within a predefined set of labels. A very similar task is *author identification*, which predicts the author of the input code. Both tasks are standard single-sentence classification tasks, and traditional machine learning methods have been widely adopted in them (Kalgutkar et al., 2019), while pretrained language models have seen almost no application.

- *Machine code detection* is another recently introduced task and aims to predict whether the input code is written by human or generated by machines. Detection of AI generated content (AIGC) has undergone thorough studies in general or specialized domains such as education (Mitchell et al., 2023; Liu et al., 2023j), but it is yet to be examined at scale on code.

2.1.5 Text-to-Text

Text-to-text tasks take text as input, and output text. Related methods are listed in Figure 7.

- *Document translation* is the automatic translation of code-related documents. Since models, datasets, and prompting strategies for machine translation are abundant in NLP (Vaswani et al., 2017; Goyal et al., 2022; He et al., 2023b), we do not go into detail about this task.

- *Log analysis* aims to analyze the system logs produced by software products, for example parsing logs into structured templates or finding anomalies from raw logs. Zhu et al. (2019) provide a survey on traditional methods for this task up to 2018, and Chen et al. (2021d) give an empirical comparison between neural network based methods. Zhang et al. (2023d) also cover more recent methods for log parsing, while Landauer et al. (2022) survey methods for anomaly detection in logs.

2.1.6 NLP Point-of-View

Unlike software engineering, evaluation tasks in NLP are generally categorized into understanding and generation. The former, represented by GLUE (Wang et al., 2018a) and SuperGLUE (Wang et al., 2019), emphasizes the comprehension of input text, and is typically formalized as classification, regression, sequence tagging, or span extraction. The later, on the other hand, involves autoregressive generation of text, such as machine translation and summarization.

Among the previously listed tasks, code synthesis, code translation, code repair, deobfuscation, unit test generation, assertion generation, mutant generation, code summarization, code review, identifier prediction, and commit message generation are sequence-to-sequence generation tasks. Formally, each instance of these tasks has a source sequence \mathbf{x} (e.g. a piece of source code) and a target sequence \mathbf{y} (e.g. its corresponding summarization), and the language model is tasked to maximize the conditional probability given by (5), where θ can be either a decoder-only model or an encoder-decoder model. In the former case, \mathbf{x} and \mathbf{y} are concatenated. In the later case, \mathbf{x} is processed by the encoder and \mathbf{y} is processed by the decoder.

Code completion and code infilling are also generation tasks, but differ from sequence-to-sequence tasks where the input and output are related by different sequences. In these two tasks, the target is a continuation or infill of the input. They correlate closely to the language modeling objectives given in Equation (3) and (5). Similarly, cloze test takes the same form as Equation (4) but is usually considered an understanding task, as its output is usually a single token and does not involve autoregressive generation.

Defect detection, clone detection, code classification, and author identification are sequence classification tasks. In these tasks, a set of labels \mathcal{Y} is defined over the input, and each instance is assigned a label $y \in \mathcal{Y}$ (e.g. for defect detection $\mathcal{Y} = \{0, 1\}$, while for author identification a possible \mathcal{Y} is $\{\text{Alice, Bob, John, others}\}$). The model is then tasked to maximize

$$p_{\theta}(y|\mathbf{x}). \tag{1}$$

Type prediction is a token classification task, also known as tagging. In this task, each token x_i is assigned a label $y_i \in \mathcal{Y}$, with an example \mathcal{Y} being $\{\text{int, float, string, bool, non-identifier, other}\}$. The model’s objective is to maximize

$$\prod_{i=1}^n p_{\theta}(y_i|\mathbf{x}). \tag{2}$$

The last two tasks - code retrieval and code search - also belong to understanding tasks. In these tasks, each source sequence \mathbf{x} is paired with a positive target sequence \mathbf{y} and a set of negative targets $\bar{\mathbf{y}} \in \{\mathbf{y}_1, \dots, \mathbf{y}_k\}$. The model’s task is to find a similarity metric s such that $s(\mathbf{x}, \mathbf{y})$ is larger than $s(\mathbf{x}, \bar{\mathbf{y}})$.

2.2 Evaluation Metrics

Of the tasks mentioned in Section 2.1, the understanding tasks are similar in form to natural language understanding tasks (Wang et al., 2018a; 2019) and evaluated likewise by metrics such as accuracy, F1 and Mean Reciprocal Rank (MRR), while short generation tasks such as identifier prediction is also evaluated by accuracy of exact matches. Code-to-text tasks are evaluated with common metrics for text generation such as BLEU (Papineni et al., 2002).

Evaluation of tasks involving code generation, on the other hand, is more complicated. Most early works evaluate syntactical correctness, i.e. the percentage of generations that can be successfully parsed. Chen et al. (2018) argue against such metrics and suggest reference match instead, which is the percentage of generations that are exactly the same as the references. Ren et al. (2020) propose CodeBLUE, a variant of BLEU that takes code syntax and semantics into account by evaluating the overlap of abstract syntax tree (AST) and data flow.

As code generation models became more capable over the years, however, these metrics based on content-overlap have been found to be inadequate (Rozière et al., 2020; Hendrycks et al., 2021a; Austin et al., 2021), since functionally equivalent snippets of code can differ dramatically in their lexical forms. Consequently, researchers have turned their attention to functional correctness. One popular example of such metrics is $\text{pass}@k$, proposed by Kulal et al. (2019) and refined by Chen et al. (2021b), which is an unbiased estimator of the model’s chance in passing all unit tests of a program with any of k generated samples. This metric can be generalized to $\text{pass}_n@k$ (Li et al., 2022g), which limits the number of model submissions to n but allows filtering by unit tests given in the input from k samples.

2.3 Program Synthesis

While dozens of evaluation tasks exist in software engineering, they have generally stayed out of the focus of the NLP community until very recently. The only exception is program synthesis, which has become a standard evaluation task for LLMs since the advent of HumanEval in 2021. Looking back at this task, we identify four changes in program synthesis over the years: shift of coding paradigms (from example-based to intention-based), generalization in languages (from domain-specific languages to general-purpose languages), simplification of model architectures (from grammar-guided decoders to general-purpose language models), and application of execution-based feedback.

Many of the early methods for program synthesis are example-based (Menon et al., 2013), which means they induce programs from input-output examples, often in domain-specific languages (DSLs) such as Flash-Fill (Devlin et al., 2017a) and Karel² (Bunel et al., 2018), as these languages are usually simple in syntax and structure.

As code generation models became more capable over the years, researchers started to pay attention to program synthesis in general-purpose programming languages as well. Hearthstone (Ling et al., 2016) and CONCODE (Iyer et al., 2018) are two of the early datasets, representing Python and Java respectively. Each example in Hearthstone is the description of a card in the game and its corresponding class implementation, while examples in CONCODE are simply Java methods paired with their natural-language documentation crawled from public GitHub repositories. Synthesizing programs from their corresponding natural language descriptions has since then become a standard practice in program synthesis, and has led to some of the most widely used benchmarks, such as HumanEval (Chen et al., 2021b), which has even been translated into multiple languages (Cassano et al., 2023a; Zheng et al., 2023a; Muennighoff et al., 2023). Some recent benchmarks use general-purpose languages but focus on specific domains, such as data science (Bavishi et al., 2019; Lai et al., 2023) or Jupyter notebooks (Agashe et al., 2019), while several math reasoning benchmarks

²FlashFill is used in Microsoft Excel for string transformation. Karel is a simple programming language for educational purpose.

have also been converted to programming tasks, including MathQA-Python (Amini et al., 2019; Austin et al., 2021) and GSM8K-Python (Cobbe et al., 2021; Chowdhery et al., 2022; Wang et al., 2023d).

Many early works argue that simply treating program synthesis as a text generation task does not utilize the underlying syntax of programming languages, and thus often use syntax-enhanced decoders to inject the target syntax as prior knowledge (Yin & Neubig, 2017). LLMs, however, have demonstrated that pretrained language models are capable of generating syntactically correct programs without loss of generality. Under this setting, researches start to *execute* the generated programs and provide feedback to the generation model to inject the prior knowledge of code instead. This has recently led to the popularity of *interactive coding*, which we discuss in more detail in Section 7.1.

2.4 Repository-Level Evaluation

Most evaluation tasks discussed in Section 2.1 are limited to a single file or even a single function, as cross-file code modeling poses challenges that are beyond the capability of most existing language models. Recently, however, position interpolation techniques (Chen et al., 2023b; Rozière et al., 2023; Peng et al., 2023a) have extended the context window of LLMs to hundreds of thousands of tokens, making it possible to contextualize the evaluation of code modeling within entire repositories. Several works (Shrivastava et al., 2023b; Ding et al., 2022b; Zhang et al., 2023b; Shrivastava et al., 2023a) have studied code completion leveraging repository-level context, and Liu et al. (2023i); Ding et al. (2023) propose RepoBench and CrossCodeEval respectively to evaluate such systems. More recently, Bairi et al. (2023) investigate the more challenging tasks of repository-level API migration and temporal editing, and Jimenez et al. (2023) introduce a corresponding benchmark, SWE-bench.

3 Language Modeling Preliminaries

As code is ultimately a subset of natural languages, language models have been extensively used to tackle the tasks listed in Section 2. Before diving into the language models themselves, we first briefly review the preliminaries of Transformer-based language modeling in this section following the common choices of training objectives, and also some implementation designs.

3.1 Causal Language Modeling

Unidirectional language models (also known as causal language models³) factor the probability of a sentence into the product of each token’s conditional probability with the chain rule. A piece of input text $\mathbf{x} = [x_1, x_2, \dots, x_n]$ consisting of n tokens is modeled as

$$P(\mathbf{x}) = \prod_{i=1}^n p_{\theta}(x_i | \mathbf{x}_{1:i-1}), \quad (3)$$

where $\mathbf{x}_{1:i-1}$ is a shorthand for tokens before x_i in the input, and θ is the parameters of the model. With Transformer decoders such as GPT (Radford et al., 2018; 2019; Brown et al., 2020) and LLaMA (Touvron et al., 2023a;b), the conditional probability in (3) is modeled by adding an attention mask to the attention matrix of each Transformer block, ensuring that x_i can only attend to previous tokens. During training, the cross entropy loss on all tokens in the input is calculated in parallel, while at inference time each new token is generated autoregressively. For further details about the Transformer architecture we refer to Vaswani et al. (2017).

3.2 Masked Language Modeling

Unlike causal language models, bidirectional language models are trained to acquire a better contextual representation of text rather than generating text autoregressively. In the vanilla Transformer, the encoder part is allowed to attend to a token’s left as well as right context for this purpose. BERT (Devlin

³The training objective of such language models is Causal Language Modeling (CLM), but also referred to as Next Token Prediction.

et al., 2019) takes one step further and pretrains only a Transformer encoder. A set \mathcal{M} of randomly chosen tokens in the input are replaced by a special token [MASK] to obtain a noisy input $\hat{\mathbf{x}}$, for example $[\text{CLS}], x_1, [\text{MASK}], x_3, [\text{MASK}], x_5, [\text{EOS}]$ ⁴, and the model is trained to recover the original tokens by maximizing

$$\prod_{m \in \mathcal{M}} p_{\theta}(m|\hat{\mathbf{x}}). \quad (4)$$

While this objective requires the model to have a deep understanding of the input text to reconstruct it, it suffers from low training efficiency, since only a small set of tokens (usually 15%) are masked (and thus “trained on”). To address this issue, Clark et al. (2020) propose ELECTRA, which is trained to discriminate whether or not each token in the input has been replaced by a BERT-like model instead, thereby computing loss on all input tokens.

3.3 Denoising Objectives

GPT-style causal LM and BERT-style bidirectional LM each has its own strengths and weaknesses. While GPT can be used for autoregressive generation, it lacks a bidirectional representation of input text, and is thus unsuitable for sequence-to-sequence (seq2seq) generation tasks such as translation and summarization. BERT, on the other hand, can produce bidirectional representations, but is pretrained only for mask filling, not generation.

The vanilla Transformer encoder-decoder architecture combines the respective advantages of GPT and BERT. T5 (Raffel et al., 2020) is such a model pretrained with *span corruption*, which can be regarded as a variant of MLM. During pretraining, spans of text in the input are replaced with sentinel tokens, which play the same role as [MASK] in BERT. The noisy input is first processed by the encoder with bidirectional attention, and the masked spans are then generated autoregressively by the decoder. Formally, if k spans are sampled for corruption in input \mathbf{x} , the noisy input $\hat{\mathbf{x}}$ is then constructed by replacing each span with a special token $\langle \text{extra_id_}i \rangle$, for $i = 1, 2, \dots, k$, and the target \mathbf{y} is constructed by concatenating all spans prepended with corresponding sentinels: $[\langle \text{extra_id_}1 \rangle, \text{span}_1, \dots, \langle \text{extra_id_}k \rangle, \text{span}_k]$. The model is then trained with a standard seq2seq objective, by maximizing

$$p_{\theta}(\mathbf{y}|\hat{\mathbf{x}}) = \prod_{i=1}^{n_y} p_{\theta}(y_i|\hat{\mathbf{x}}, \mathbf{y}_{1:i-1}). \quad (5)$$

Lester et al. (2021) show that models pretrained with such objectives can be adapted for autoregressive language modeling with extra pretraining using the prefix language modeling objective, i.e. splitting the text into two parts, processing the first part with encoder and generating the second part with decoder.

Tay et al. (2023b) argue that span corruption is also closely related to CLM, since one can mask out the whole input text as a single span and train the decoder to generate it autoregressively. Inspired by this relation, they propose UL2, which is the combination of many span corruption objectives that differ in corruption rate and span length. Applying it to both encoder-decoder models and decoder-only models, they find that encoder-decoder models perform better under the same computation budget constraint. Other researches have also found that such encoder-decoder models generally perform better than causal decoder-only models (Wang et al., 2022b; Soltan et al., 2022).

3.4 Auxiliary Objectives

Language modeling objectives, such as previously discussed CLM and MLM, mainly train the model to capture token-level information and are ineffective at modeling document structures. Thus, auxiliary objectives are often added to help the models learn such global information. BERT is pretrained with next sentence prediction (NSP) along with MLM, which is formulated as a binary classification task to predict whether two

⁴Both [CLS] and [EOS] are artificial tokens added to the input text. [CLS] is added at the beginning and its representation is used for sentence classification, while [EOS] indicates end of sentence. The original BERT also uses another special token [SEP], which is not in common use in LLMs, and we refer to Devlin et al. (2019) for details.

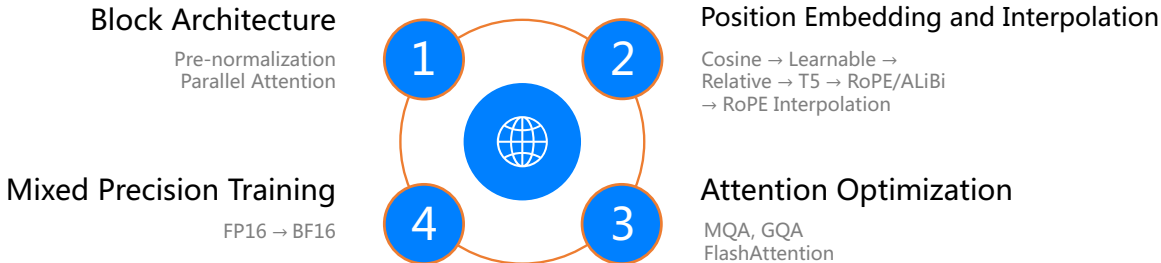


Figure 8: Major implementation changes in LLM over the past few years.

segments in the input are neighboring in the original corpus. Lan et al. (2020) propose a more challenging sentence-order prediction (SOP) task, where the negative samples are constructed by swapping the order of two neighboring sentences instead of sampling a random sentence from other documents.

Relatedly, Raffel et al. (2020) mix supervised downstream samples such as GLUE (Wang et al., 2018a) into T5’s pretraining dataset to conduct multi-task pretraining. However, it is worth noting that since they unify all tasks into a text-to-text format, the training objective is the same for their self-supervised pretraining and supervised downstream tasks, i.e. conditional generation of the target sequence.

3.5 Implementation Design

While most researches on pretraining language models have focused on designing novel training objectives, low-level implementation of the Transformer architecture itself is also being continuously improved over the years in pursuit of stability, performance, and efficiency, as shown in Figure 8.

The original Transformer block proposed by Vaswani et al. (2017) is formulated as

$$h = \text{LN}(\text{Attention}(x) + x), \tag{6}$$

$$y = \text{LN}(\text{FFN}(h) + h), \tag{7}$$

where x is the layer’s input; y is the layer’s output; “Attention” is the self-attention sublayer; “FFN” is the feed-forward sublayer, and “LN” is layer normalization (Ba et al., 2016).

GPT-2 (Radford et al., 2019) moves layer normalization to the input of each Transformer sub-block to stabilize training:

$$h = \text{Attention}(\text{LN}(x)) + x, \tag{8}$$

$$y = \text{FFN}(\text{LN}(h)) + h, \tag{9}$$

and such pre-norm has since become a standard practice in Transformer decoders.

GPT-J (Wang & Komatsuzaki, 2021) modifies the Transformer block to compute FFN sub-layer and self-attention sub-layer in parallel to increase computation throughput:

$$y = x + \text{FFN}(\text{LN}(x)) + \text{Attention}(\text{LN}(x)), \tag{10}$$

and Chowdhery et al. (2022) observes limited performance degradation when applying this design to larger models.

As self-attention alone cannot capture the position information of each input token, the vanilla Transformer adds a non-learnable vector that’s dependent on the absolute position in the input sequence to the embedding of each token, which is known as cosine position embedding. Later works such as GPT and BERT use learnable embeddings instead, while T5 adopts relative position embedding (Shaw et al., 2018), where the

information of relative position between query and key is injected in the computation of self-attention instead. A more recent scheme RoPE (Su et al., 2021) multiplies the keys and queries by a position-dependent rotation matrix, and is later shown to enable position interpolation for processing of longer sequences (Chen et al., 2023b; Rozière et al., 2023; Peng et al., 2023a). Alternatively, Press et al. (2022) propose ALiBi, which directly attenuates the attention scores according to the relative position between key and query. RoPE is popularized by its application in PaLM (Chowdhery et al., 2022) and GPT-NeoX (Black et al., 2022), while ALiBi is adopted by BLOOM (Scao et al., 2022). We refer to Zhao et al. (2023) for a survey on position embedding and interpolation in Transformers.

Apart from position embeddings, another issue in Transformer that has long troubled researchers is the fact that the complexity of self-attention scales quadratically with the input sequence length. Some works such as Reformer (Kitaev et al., 2020), Linformer (Wang et al., 2020c), Performer (Choromanski et al., 2021) and cosFormer (Qin et al., 2022b) use approximate attention to reduce this complexity, but they mostly come at the cost of degraded performance (Tay et al., 2023a; Lin et al., 2022). Other works tackle this issue from an engineering point-of-view. MQA (Shazeer, 2019) shares the same set of keys and values across all attention heads to optimize memory-to-arithmetic ratio and significantly improves inference speed at small costs of model performance. Its variant Grouped-Query Attention (GQA, Ainslie et al., 2023) takes a middle-ground approach by dividing attention heads into groups and sharing the same set of keys/values within each group. Orthogonally, Dao et al. (2022) introduce FlashAttention, which is an exact but improved implementation of self-attention that optimizes IO operations on the accelerating device via tiling to improve memory efficiency.

Another important technique for improving LLMs’ training efficiency is mixed precision training (Micikevicius et al., 2018), which stores model weights and activations in lower precision to save memory consumption. Early works use FP16 format for this low precision, while BF16 has now become more popular (Chowdhery et al., 2022; Scao et al., 2022), as it can represent the same range of floating point numbers as FP32, thus preventing numerical overflowing and underflowing during training.

4 General Language Models for Code

Since language models scaled to hundreds of billions of parameters (Brown et al., 2020; Chowdhery et al., 2022), many of them have demonstrated non-trivial coding capability, even if they are not specifically designed or trained for code. Pioneered by Codex, researchers have also found continual pretraining on code to significantly benefit language models’ performance on code⁵.

4.1 Off-the-Shelf Language Models

Large language models are often pretrained on trillions of tokens following the scaling laws (Kaplan et al., 2020; Hoffmann et al., 2022), and such an amount of text data is often a diverse composite with a non-negligible part of code. The Pile (Gao et al., 2021), for example, includes 95GB of code crawled from GitHub out of its 800GB raw dataset, while the multilingual pretraining dataset ROOTS (Laurençon et al., 2022) also contains 163GB of code spanning 13 programming languages in its 1.6TB compound. As two of the largest open-source pretraining datasets, they have supported many language models with coding ability. GPT-J (Wang & Komatsuzaki, 2021), for example, is reported by Chen et al. (2021b) to demonstrate non-trivial performance on HumanEval, while Scao et al. (2022) report similar results for GPT-NeoX (Black et al., 2022) and BLOOM. LLaMA (Touvron et al., 2023a), whose pretraining dataset includes 328GB code from GitHub, achieves 23.7 pass@1 performance on HumanEval, and its successor LLaMA 2 (Touvron et al., 2023b), achieves an even higher score of 29.9.

Closed-source models, on the other hand, perform generally better. LaMDA (Thoppilan et al., 2022) and PaLM (Chowdhery et al., 2022), whose pretraining dataset contains 12.5% and 5% code respectively, achieve 14.0 and 26.2 pass@1 performance on HumanEval, while GPT-4 (OpenAI, 2023) set a staggering record of

⁵While some works refer to this process as “finetuning on code”, it is still self-supervised in nature. Thus we choose to adopt the term “extra/additional/continual pretraining” in this work to avoid confusion with supervised in-task finetuning or instruction finetuning.

67.0 (and an early version is reported by Bubeck et al. (2023) to be 82) that until recently has remained higher than any specialized models pre-trained or instruction-finetuned for code.

More recently, the general trend has been to train smaller models with larger datasets, following the revised scaling law (Hoffmann et al., 2022). Baichuan 2 (Yang et al., 2023a), for example, is a 13B model trained on 2.6T tokens, while Qwen (Bai et al., 2023) is a 14B model trained on 3T tokens. They achieve 17.1 and 32.3 pass@1 on HumanEval, respectively. Li et al. (2023i), however, demonstrate that models as small as 1.3B can acquire coding capability that’s comparable to much larger models while also maintaining a reasonable performance on general text processing and even manifesting some emergent abilities (Wei et al., 2022c) such as chain-of-thought reasoning (Wei et al., 2022d). Their model, Phi-1.5, is trained on 21B tokens of textbook data generated by ChatGPT, and 100B tokens of filtered web data from Stack Overflow and Refined Web (Penedo et al., 2023), and attains 41.4 pass@1 performance on HumanEval.

Another rising trend is mixture-of-expert models (Lepikhin et al., 2021; Fedus et al., 2022; Du et al., 2022). Notably, Jiang et al. (2024) recently introduce Mixtral 8x7B, where only 13B parameters are activated for each token during inference, but achieving 40.2 on HumanEval and surpassing much larger dense models such as LLaMA 2. Similarly, Dai et al. (2024) present DeepSeekMoE, where only 2.8B parameters are activated in a 16B model, scoring 26.8 on HumanEval.

The exact performance of these models are presented in Table 1.

4.2 Language Models with Additional Pretraining on Code

Along with the seminal benchmark HumanEval, Chen et al. (2021b) kick-started the age of LLM for code with Codex, which are GPT-3 checkpoints pretrained on 100B additional code tokens and one of the earliest multi-billion models for code. Following their work, other researchers have also specialized their LLMs on code with additional pretraining. Chowdhery et al. (2022) train PaLM on 7.8B additional code tokens to obtain PaLM-Coder, setting new state-of-the-art on HumanEval and MBPP (Table 1) that are only broken later by its successor PaLM 2-S*, the smallest version of PaLM 2 (Anil et al., 2023b) further trained on an undisclosed amount of code. Similarly, Lewkowycz et al. (2022) train PaLM on 38.5B tokens of arXiv papers and mathematical content, while Rozière et al. (2023) train LLaMA 2 (Touvron et al., 2023b) on more than 500B code tokens to acquire Code LLaMA, whose performance on HumanEval surpasses all previous LMs except GPT-4 (Table 1). Liu et al. (2023b) further train Code LLaMA with multi-task finetuning (MFT) to introduce CodeFuse-CodeLLaMA, achieving 74.4 pass@1 on HumanEval and surpassing even the performance of GPT-4 published in OpenAI (2023).

Table 1: Pass@k performance of raw language models (top) and language models with extra training on code (bottom) on HumanEval (0-shot) and MBPP (3-shot), ordered chronologically. For Phi-1.5 we consider Phi-1.5-web version, and for Code LLaMA we consider its Python version. ¹ Chen et al. (2021b); ² Chowdhery et al. (2022); ³ Austin et al. (2021); ⁴ Scao et al. (2022); ⁵ Touvron et al. (2023a); ⁶ OpenAI (2023); ⁷ Bubeck et al. (2023); ⁸ Touvron et al. (2023b); ⁹ Li et al. (2023i); ¹⁰ Yang et al. (2023a); ¹¹ Bai et al. (2023); ¹² Jiang et al. (2023a); ¹³ Anil et al. (2023a); ¹⁴ DeepSeek-AI et al. (2024); ¹⁵ Jiang et al. (2024); ¹⁶ Dai et al. (2024); ¹⁷ Anil et al. (2023b); ¹⁸ Rozière et al. (2023).

	Size	HumanEval (0)		MBPP (3)	
		k=1	k=100	k=1	k=80
GPT-J ¹	6B	11.6	27.7		
LaMDA ²³	137B	14.0	47.3	14.8	62.4
PaLM ²	540B	26.2	76.2	36.8	75.0
GPT-NeoX ⁴	20B	15.4	41.2		
BLOOM ⁴	176B	15.5	55.5		
LLaMA ⁵	65B	23.7	79.3	37.7	76.8
GPT-4		67.0 ⁶ /82 ⁷			
LLaMA 2 ⁸	70B	29.9	89.0	45.0	81.5
Phi-1.5 ⁹	1.3B	41.4		43.5	
Baichuan 2 ¹⁰	13B	17.1		30.2	
Qwen ¹¹	14B	32.3		40.8	
Mistral ¹²	7B	30.5		47.5	
Gemini ¹³	Ultra	74.7			
DeepSeek ¹⁴	67B	42.7		57.4	
Mixtral ¹⁵	8x7B	40.2		60.7	
DeepSeekMoE ¹⁶	16B	26.8		39.2	
Codex ¹	12B	28.8	72.3		
PaLM-Coder ²	540B	36.0	88.4	47.0	80.8
PaLM 2-S* ¹⁷	S	37.6	88.4	50.0	86.8
Code LLaMA ¹⁸	34B	53.7	94.7	56.2	
Code-Qwen ¹¹	14B	45.1		51.4	

While almost all of these models are Transformer decoders pretrained with CLM, several architectural modifications have been introduced along the way, as we noted in Section 3.5. All these models use pre-norm, and GPT-J introduces parallel attention, which is later adopted by PaLM, GPT-NeoX, and Phi-1.5. PaLM introduces MQA and RoPE into LLMs, and RoPE is now employed by most language models, including GPT-NeoX, two generations of LLaMA, Qwen, and the 7B version of Baichuan 2. BLOOM and the 13B version of Baichuan 2, however, use ALiBi for position embeddings, while LLaMA 2 and Code LLaMA adopt GQA instead of MHA or MQA. In Section 5, we show that specialized models pretrained exclusively on code have also followed these advancements closely.

5 Specialized Language Models for Code

As pretrained Transformers such as GPT and BERT achieved remarkable success in natural language processing, such model architectures, learning paradigms, and training objectives were soon adopted by the software engineering community to produce specialized models for code understanding and generation. In this section, we first review common datasets used for pretraining code language models (Section 5.1), and then dive into the complex family of code LMs by their model architecture: encoder-only models (Section 5.2), encoder-decoder models (Section 5.3), decoder-only models (Section 5.4), UniLM (Section 5.5), and diffusion models (Section 5.6). Lastly, in Section 5.7 we also illustrate the current trend of applying more recent techniques in NLP, such as instruction tuning (Wei et al., 2022b; Sanh et al., 2022; Chung et al., 2022) and reinforcement learning (Ouyang et al., 2022) to code processing. An overview of these pretrained models are provided in Table 3.

5.1 Training Dataset for Code

While text data for pretraining language models are often crawled from the web and must undergo meticulous and often aggressive preprocessing (Raffel et al., 2020), code data come naturally as whole documents from public GitHub repositories. Even better, they come with readily available quality indicators such as the count of stars or forks (although Allal et al. (2023) suggest that star count correlates poorly with downstream performance). As a result, many large-scale code pretraining datasets have been introduced, including CodeSearchNet (Husain et al., 2019), CodeParrot (Tunstall et al., 2022), and the Stack (Kocetkov et al., 2022), totaling 20GB, 50GB and 3TB of code documents respectively (Table 2).

While these datasets are meant for training code models, it should be noted that code is ultimately a special form of natural language, as the vocabulary of most programming languages is a small subset of English. Besides, high-quality code is often interleaved with natural language comments or documentations, which also enables models to acquire certain knowledge of general text representation. In fact, of the 6.5M functions in CodeSearchNet, 2.3M are paired with natural language documentation, allowing models to train explicitly on such bimodal data.

Compared with natural language, another byproduct of scraping code from GitHub is commit histories, which consist of code before commit, code after commit, and a short message describing the commit, which can loosely serve as an instruction for language models. Muennighoff et al. (2023) utilize this feature and construct a 2GB dataset CommitPackFT containing 742K samples of instruction data for code, obviating the need of extensive human labor that’s required to construct natural language instructions (Sanh et al., 2022; Wang et al., 2022f).

Table 2: Statistics of several pretraining datasets for code models: size in bytes, number of files, and number of programming languages. In CodeSearchNet each file is a function. For Pile and ROOTS we only consider their code composite. ^a Husain et al. (2019); ^b Gao et al. (2021); ^c Biderman et al. (2022); ^d <https://huggingface.co/datasets/codeparrot/github-code>; ^e Kocetkov et al. (2022); ^f Laurençon et al. (2022).

Dataset	Size (GB)	Files (M)	# PL
CodeSearchNet ^a	20	6.5	6
The Pile ^{bc}	95	19	-
CodeParrot ^d	1K	115	30
The Stack ^e	3136	317	30
ROOTS ^f	163	15	13

Apart from bimodal training and instruction finetuning, another recent trend in constructing code dataset is synthesizing data with powerful models such as ChatGPT. While this method is originally proposed for generating instruction data in natural language (Wang et al., 2023c; Honovich et al., 2023), Gunasekar et al. (2023) take one step further and synthesize 1B tokens of Python textbooks and coding exercises to pretrain a 1.3B model, achieving state-of-the-art results on HumanEval that’s comparable to much larger models trained on significantly larger datasets.

Table 3: An overview of pretrained code language models’ architecture and training details: their base architecture, model size, vocabulary, context length, position embedding, training precision, attention type (MHA, MQA, or GQA), layer normalization type (post-norm or pre-norm), usage of FlashAttention, training initialization, objectives, dataset size (either in disk size, measured by GB/TB, or in number of tokens, measured by B/T), tokens seen during training, supported number of programming languages, and institute. We note that the number of training tokens does not count the training tokens of the model used for initialization, if any. The training objectives are: MLM (Masked Language Modeling), NSP (Next Sentence Prediction), RTD (Replaced Token Detection), IP (Identifier Prediction), CL (Contrastive Learning), SC (Span Corruption), DAE (Denosing Auto-Encoding), Text↔Code (text-to-code generation and code-to-text generation), MT (Machine Translation). Missing information (such as AlphaCode’s position embedding type) is left as blank.

Date	Model	Arch.	Size	Vocab	Context	PE	Precision	Atten. Type	Parallel Atten.	Pre-Norm	Flash Atten.	Init. from	Objectives	Dataset	Training	PL	Inst.
2019-12	CuBERT	BERT	350M	50K	1024	absolute	fp32	MHA				-	MLM + NSP	9.3B	93B	1	Google
2020-02	CodeBERT	RoBERTa	125M	50K	512	absolute	fp32	MHA				RoBERTa	MLM + RTD	20GB	105B	6	Microsoft
2020-09	GraphCodeBERT	RoBERTa	125M	50K	640	absolute	fp32	MHA				CodeBERT	MLM + Edge Prediction + Node Alignment	20GB	131B	6	Microsoft
2021-08	SynCoBERT	RoBERTa	125M	50K	512	absolute	fp32	MHA				CodeBERT	MLM + IP + AST Edge Prediction + CL	20GB	7B	6	Huawei
2021-10	DISCO	BERT	100M	20K	512	absolute	fp32	MHA				-	MLM + Node Type MLM + CL	1.8GB		2	Columbia & IBM
2022-05	Code-MVP	RoBERTa	125M	50K	512	absolute	fp32	MHA				GraphCodeBERT	MLM + Type Inference + CL	2GB	39B	1	Huawei
2022-10	SCoDeR	RoBERTa	125M	51K	1024	absolute	fp32	MHA				UniXcoder	CL	20GB		6	Microsoft
2020-05	GPT-C	GPT-2	374M	60K	1024	absolute		MHA		✓		-	CLM	11B	270B	4	Microsoft
2021-02	CodeGPT	GPT-2	124M	50K	1024	absolute	fp32	MHA		✓		GPT-2	CLM	2GB		1	Microsoft
2022-02	PolyCoder	GPT-NeoX	160M-2.7B	50K	2048	RoPE	fp32	MHA		✓		-	CLM	254GB	39B	12	CMU
2022-03	CodeGen-Multi(Mono)	GPT-J	350M-16.1B	50K	2048	RoPE	fp16	MHA	✓			-	CLM	1.6TB(1.8TB)/506B(577B)	1T(1.2T)	6(1)	Salesforce
2022-04	InCoder	GPT-3	6.7B	50K	2048	Cosine	fp32	MHA		✓		-	Causal Masking	204GB	52B	28	Meta
2022-06	PyCodeGPT	GPT-Neo	110M	32K	1024	absolute	fp32	MHA		✓		-	CLM	96GB	100B	1	Microsoft
2022-07	PanGu-Coder	PanGu- α	317M-2.6B	42K	1024	absolute		MHA		✓		-	CLM	147GB	230B	1	Huawei
2023-01	SantaCoder	GPT-2	1.1B	49K	2048	absolute	fp32	MQA		✓		-	FIM	268GB	236B	3	BigCode
2023-03	CodeGeeX	PanGu- α	13B	52K	2048	absolute	fp16	MHA		✓		-	CLM	158B	850B	23	Tsinghua
2023-05	StarCoder	GPT-2	15.5B	49K	8192	absolute	fp32	MQA		✓	✓	-	FIM	815GB	1T	86	BigCode
2023-05	Jam	GPT-2	350M	50K	256	absolute	bf16	MHA		✓		-	CLM	36GB/20B	9B	1	U. Notre Dame
2023-06	Phi-1	GPT-J	1.3B	51K	2048	RoPE	fp16	MHA	✓		✓	-	CLM	7B	53B	1	Microsoft
2023-10	CodeFuse	GPT-J	350M-13B	101K	4096	RoPE	fp16	MHA	✓	✓	✓	-	CLM	1.6TB / 1T		40+	Ant Group
2023-10	CodeShell	GPT-2	7B	70K	8192	RoPE	bf16	GQA		✓		-	CLM		500B		Peking U.
2020-10	PyMT5	GPT-2	374M	50K	1024+1024	absolute	fp16	MHA		✓		-	SC	27GB		1	Microsoft
2021-02	Mastropaolo et al.	T5	60M	32k	512+512	T5	bf16	MHA		✓		-	SC	1GB		1	USI
2021-02	DOBF		250M	50K	512+512	absolute	fp16	MHA				-	MLM + Deobfuscation	45GB		2	Meta
2021-03	PLBART	BART	140M	50K	1024+1024	absolute	fp32	MHA				-	DAE	655GB / 71B	210B	2	UCLA & Columbia
2021-09	CodeT5	T5	60M-220M	32K	512+256	T5	fp16	MHA		✓		-	SC + IP + Masked IP + Text↔Code	~25GB		8	Salesforce
2022-01	SPT-Code	BART	262M	80K	512+512	absolute	fp16	MHA				-	NSP + SC + Method Name Prediction	20GB		6	Nanjing U.
2022-02	AlphaCode		300M-41B	8K	1536+768		bf16	MQA				-	MLM + CLM	715GB	967B	13	DeepMind
2022-06	NatGen	T5	220M	32K	512+256	T5	fp16	MHA		✓		CodeT5	Naturalization	~26GB	14B	8	Columbia & UCD
2022-12	ERNIE-Code	mT5	580M	250K	1024+1024	T5	bf16	MHA		✓		mT5	SC + Text↔Code + MT		197B	6	Baidu
2023-05	CodeT5+	T5/GPT-3	220M-16B	50K	2048+2048	absolute	fp16	MHA	✓	✓		CodeGen-mono	SC + CLM + CL + Text↔Code	52B		9	Salesforce
2020-12	CugLM	BERT	51M	50K	128	absolute	fp32	MHA				-	MLM + NSP + CLM	8M	1.2B	2	Peking U.
2022-03	UniXcoder	RoBERTa	125M	51K	1024	absolute	fp32	MHA				-	MLM + CLM + SC + CL + Code2Text	20GB+	839B	6	Microsoft

5.2 Encoders

Pretrained Transformer encoders such as BERT (Devlin et al., 2019), RoBERTa (Liu et al., 2019d), and ELECTRA (Clark et al., 2020) have attained impressive results on natural language understanding tasks, and these methods were soon introduced into code processing after their advent. Kanade et al. (2020) replicate the training procedure of BERT on a code corpus to produce CuBERT, showcasing its superior performance over LSTM (Hochreiter & Schmidhuber, 1997) and non-pretrained Transformers. Feng et al. (2020), on the other hand, train CodeBERT with MLM and ELECTRA’s RTD on CodeSearchNet. They also utilize the explicit text-code pairs in CodeSearchNet, and use them respectively as the first and second segment in BERT’s input. When using CodeBERT to initialize the encoder part of a vanilla Transformer for sequence-to-sequence generation tasks such as code summarization, they observe a moderate performance gain over non-pretrained baselines.

Apart from these standard training objectives, many auxiliary objectives specifically designed for code have also been introduced. GraphCodeBERT (Guo et al., 2021a) and SynCoBERT (Wang et al., 2021c) both extract graphs from the source code (data flow graph and abstract syntax tree, respectively) and train the models to predict the typological relations between the nodes, while SynCoBERT and Code-MVP (Wang et al., 2022d) also add type inference to their pretraining stage in the form of tagging. Another common objective is contrastive learning: SynCoBERT and Code-MVP contrast between different views of the input (such as code, comment, AST, and transformed code), while DISCO (Ding et al., 2022a) constructs positive sample pairs by semantic-preserving transformations such as obfuscation, and negative pairs by injecting artificial bugs.

5.3 Encoder-Decoders

In NLP, pretrained Transformer encoder-decoders such as T5 (Raffel et al., 2020) and BART (Lewis et al., 2020) have also left a notable mark in the past few years’ advancement in language modeling. T5, for example, unifies all textual tasks into a sequence to sequence format and sets new records on GLUE (Wang et al., 2018a) and SuperGLUE (Wang et al., 2019). Compared with encoder-only models, encoder-decoders are naturally more powerful as they can be used for conditional text generation, while their encoder part can always be taken out to perform tasks that require an encoder-only architecture, such as regression (Tay et al., 2023b).

Inspired by these advantages of encoder-decoder architecture, many such models have been proposed for code processing. PyMT5 (Clement et al., 2020) and Mastropaolo et al. (2021) replicate the pretraining and multi-task finetuning process of T5 on code corpus, while Ahmad et al. (2021) introduce PLBART, a BART pretrained on 655GB combined data of Java, Python, and natural language. Lachaux et al. (2021) argue that MLM could be too easy a task for programming languages as identifier names often occur multiple times in a single context window, and propose a deobfuscation pretraining objective, where the model is trained to convert obfuscated code back to its original form. Related to this method, we note that meaningful variable names have also been found to have a positive impact on the code generation process of large language models (Chen et al., 2022).

Building on these early works, Wang et al. (2021e) propose CodeT5, which is pretrained alternatively with 1) T5’s original span corruption; 2) identifier tagging (where each token in the code input is tagged as either identifier or non-identifier); 3) masked identifier prediction (a special form of span corruption where all identifiers are masked); and 4) text-to-code & code-to-text generation. Its successor, CodeT5+ (Wang et al., 2023d), take inspiration from UL2 (Tay et al., 2023b) and introduce causal language modeling (CLM) into pretraining, along with additional contrastive objectives based on text-code matching.

AlphaCode (Li et al., 2022g) is also trained with multiple objectives, where the encoder is trained with MLM and the decoder is trained with CLM, with architecture modifications such as shallow-encoder & deep-decoder, multi-query attention (Shazeer, 2019), and being much larger than CodeT5 (up to 41B parameters). NatGen (Chakraborty et al., 2022a), on the other hand, is pretrained with a "naturalization" objective similar to deobfuscation: semantically equivalent but unnatural code is generated by predefined operations such as loop transformation, dead code injection, and variable renaming, and the model is pretrained to translate

these unnatural code back to its original form. We note that some of these models are built on previous works. For example, NatGen is initialized with CodeT5, while the largest version of CodeT5+ is initialized from a decoder-only model, CodeGen (Nijkamp et al., 2023b).

Apart from these general pretraining objectives, several works have also trained Transformer encoder-decoders with a focus on code translation, which is a natural application of Transformer models in code as the Transformer architecture was originally proposed by Vaswani et al. (2017) for machine translation (MT). However, unlike natural languages, where parallel corpus across two or more human languages exist in abundance, there is little parallel data for code. To tackle this issue, Rozière et al. (2020) propose Transcoder, which first pre-trains an encoder with XLM (Conneau & Lample, 2019), and then initializes a vanilla Transformer with this encoder and continue to pretrain it with Denoising Auto-Encoding (DAE, Lewis et al., 2020) and back translation (Sennrich et al., 2016), while its follow-up work (Szafraniec et al., 2023) also utilize language-independent intermediate representations to enhance this process, which we discuss in more detail in Section 6.

Apart from training data and objectives, these models mostly keep to the original architectures proposed by the NLP community, as shown in Table 3. Models based on BART, for example, use post-normalization and learnable absolute position embeddings, while those based on T5 use its simplified relative position embeddings and pre-normalization.

5.4 Decoders

After the monumental debut of GPT-3 (Brown et al., 2020) and the discovery of in-context learning, decoder-only Transformer models have become dominant in language modeling (Rae et al., 2021; Hoffmann et al., 2022; Chowdhery et al., 2022; Scao et al., 2022; Touvron et al., 2023a;b, *inter alia*). Many models similarly pretrained with CLM have also emerged in code processing, such as GPT-C (Svyatkovskiy et al., 2020), CodeGPT (Lu et al., 2021), PolyCoder (Xu et al., 2022), CodeGen (Nijkamp et al., 2023b), PyCodeGPT (Zan et al., 2022), Pangu-Coder (Christopoulou et al., 2022), CodeGeeX (Zheng et al., 2023a), Jam (Su et al., 2023), Phi-1 (Gunasekar et al., 2023), CodeFuse (Di et al., 2023), CodeShell⁶, and DeepSeek Coder (DeepSeek, 2023). Of these models, several alternative training objectives have been experimented with, such as MLM and Masked CLM⁷ in Pangu-Coder, but are found to underperform compared with CLM-only training. Zan et al. (2022) also propose continual training on sketches, where the model learns to first generate a sketch of a program and then the actual code. Notably, Gunasekar et al. (2023) present Phi-1, a 1.3B small model trained on a dataset of only 7B tokens consisting of 6B tokens from StackOverflow and 1B synthetic data generated by ChatGPT but achieving 50.6 pass@1 on HumanEval and 55.5 pass@1 on

Table 4: Pass@1 performance of pretrained code models (top), instruction finetuned code models (middle), in comparison with some of the best general language models (bottom), with models in each category ordered chronologically. The sources of these figures can be found in Section 5.3, Section 5.4, and Table 1.

Model	Size	HumanEval	MBPP
PolyCoder	2.7B	5.6	-
CodeGen-Mono	16.1B	29.3	35.3
InCoder	6.7B	15.2	19.4
PyCodeGPT	110M	8.3	-
Pangu-Coder	2.6B	23.8	23.0
SantaCoder	1.1B	14.0	35.0
CodeGeeX	13B	22.9	24.4
StarCoder	15.5B	33.6	52.7
CodeT5+	16B	30.9	-
Phi-1	1.3B	50.6	55.5
CodeFuse	13B	24.8	-
DeepSeek Coder	33B	56.1	66.0
InstructCodeT5+	16B	35.0	-
WizardCoder	15.5B	57.3	51.8
Pangu-Coder 2	15.5B	61.6	-
OctoCoder	15.5B	46.2	-
CodeFuse	34B	74.4	-
DeepSeek Coder-Instruct	33B	79.3	70.0
GPT-4	-	67.0/82	-
PaLM 2*	S	37.6	50.0
Code LLaMA	34B	53.7	56.2
Phi-1.5	1.3B	41.4	43.5

⁶<https://github.com/WisdomShell/codeshell>

⁷In their paper, MLM is conducted by replacing tokens in the input with `<mask>` and predicting it from only the left context, while Masked CLM is performed by adding a `<mask>` in the input and predicting the next token from it. Both tasks do not change the attention mask patterns of the model.

MBPP, comparable to much larger (both in model size and training data size) models such as Code LLaMA or PaLM 2.

Although Christopoulou et al. (2022) report denoising objectives to underperform in decoder-only models, there have been other works that successfully combine denoising or multi-task pretraining with decoder architecture. Incoder (Fried et al., 2023), SantaCoder (Allal et al., 2023), and StarCoder (Li et al., 2023h) are all trained with fill-in-the-middle (FIM) objective, also referred to as causal masking by Fried et al. (2023), which is essentially span corruption (Raffel et al., 2020) adopted to decoder-only architecture. One of the visible advantages of these infilling objectives is that they inject the models with the ability to fill in blanks in the middle of input code at inference time, while CLM allows only for autoregressive generation. As Table 4 shows, however, these objectives also lead to higher performance on downstream tasks when compared with CLM-only models such as CodeGen, although the exact benefits of infilling training remain controversial (Nijkamp et al., 2023a).

Observing Table 3, it is clear that decoder-only models for code have generally followed the practices in NLP more closely, when compared with other model architectures. All these models use pre-normalization, while MQA, RoPE, and parallel attention have also been adopted by several models. Notably, the three most recent models - StarCoder, Phi-1, and CodeFuse - also employ FlashAttention to improve model throughput.

5.5 UniLMs

Following UniLM (Dong et al., 2019) in NLP, several works in code processing have also pretrained this fourth family of Transformer models on code. CugLM (Liu et al., 2020) is trained with both CLM and MLM + NSP via alternating attention masks, while UniXcoder is trained with CLM, MLM, Span Corruption (in Prefix LM style) along with auxiliary objectives including contrastive learning and text-code mutual generation. Both two models, however, are relatively small in size, and whether or not this architecture is suitable for code processing is yet to be explored at scale.

5.6 Diffusion Models

Currently the Transformer architecture dominates text generation, but several works (Li et al., 2022c; Lin et al., 2023) have also adopted Diffusion Models (Ho et al., 2020) from computer vision for text generation. Recently CodeFusion (Singh et al., 2023) also introduces diffusion models into code modeling, and demonstrates that a 75M diffusion model can outperform StarCoder, CodeT5+, and GPT-3 on three code synthesis datasets.

5.7 Instruction Finetuning and Reinforcement Learning for Code

In natural language processing, training models on a diverse set of tasks with instruction prefix, known as instruction finetuning, has been shown to unlock the ability of cross-task generalization (Ouyang et al., 2022; Chung et al., 2022; Iyer et al., 2022). At first, these instruction data samples are manually compiled or crowd-sourced (Wei et al., 2022b; Sanh et al., 2022), but later researches find LLM-generated instructions to be sufficient (Wang et al., 2023c; Honovich et al., 2023).

Following these works in natural language, researchers from the code community have applied instruction tuning to their models as well. Wang et al. (2023d) finetune CodeT5+ with 20K instruction data generated by InstructGPT (Ouyang et al., 2022) to obtain InstructCodeT5+. WizardCoder (Luo et al., 2023) follows the methods of WizardLM (Xu et al., 2023a) to evolve 20K code Alpaca (Taori et al., 2023) samples into a 78K dataset and uses it to finetune StarCoder. Pangu-Coder 2 (Shen et al., 2023) also uses WizardLM’s Evol-Instruct to generate 68K instruction samples from 20K code Alpaca, but also introduces reinforcement learning via Rank Responses to align Test & Teacher Feedback (RRTF). OctoCoder (Muennighoff et al., 2023), on the other hand, takes a different path and uses Git commit histories as instruction data to finetune StarCoder and CodeGeeX2. More recently, CodeFuse (Liu et al., 2023b) also employs multitask-finetuning and explicitly introduces multiple downstream tasks into their instruction data. The performance of these instruction finetuned code models can also be found in Table 4.

In NLP, another technology closely related to instruction finetuning is reinforcement learning from human feedback (RLHF), which has played a significant role in aligning LLMs with human values (Ouyang et al., 2022; Bai et al., 2022). The merit of reinforcement learning is that it can incorporate non-differentiable reward signals into training, such as BLEU (Bahdanau et al., 2017) and human preference (Christiano et al., 2017), but the human feedback required in aligning LLMs often involves extensive labor on annotation. In comparison, applying reinforcement learning to code models has a natural advantage, as compilers can be used for automatically generating feedback for code samples produced by language models.

CodeRL (Le et al., 2022) is one such model, which defines four levels of rewards for each generated program (viz. compile error, runtime error, unit test failure, pass) as well as fine-grained token-level reward estimated by a critic model. The actor model, which is an extension of CodeT5, is then trained with REINFORCE algorithm (Williams, 1992). Similarly, CompCoder (Wang et al., 2022c) and PPOCoder (Shojaee et al., 2023) train CodeGPT and CodeT5 respectively with proximal policy optimization (Schulman et al., 2017), while RLTF (Liu et al., 2023d) proposes fine-grained feedback based on the error information and location provided by the compiler, as well as adaptive feedback that takes the ratio of passed test cases into account.

6 Code Features for Language Models

A major difference between programming languages and natural languages is that the former is artificially defined to be precise and unambiguous, and need to be compiled (or interpreted) without error before execution. This allows for a much larger flexibility in designing pretraining objectives on code, beside lexical manipulations such as CLM, MLM, and Span Corruption. A similar trend can be observed in the last years before neural networks were introduced into mainstream NLP literature (Sutskever et al., 2014; Bahdanau et al., 2015), when researchers in the MT community utilized alternative views of text such as syntactic features to improve the performance of SMT systems (Galley et al., 2006; Chiang, 2007). These features, however, are not universally applicable or even agreed upon, and often result in highly complicated systems (for example, the size of English part-of-speech tagging’s label set may range from dozens to hundreds).

Programming languages, however, fare much better in these aspects. Each mainstream programming language, such as C, Python, and Java, comes with readily available compiler toolkits that allow for easy and accurate extraction of semantic information such as Abstract Syntax Tree (AST), language-independent Intermediate Representation (IR), and auxiliary information such as type of each token and control/data flow graph (CFG/DFG). Thus, in the context of Transformer-based language modeling for code, many works have incorporated these features into their training procedure.

6.1 Abstract Syntax Tree and Intermediate Representation

AST is one of the most common intermediate results of the compiling process, where a program is parsed into a tree of operations and their operands. Before the popularization of Transformer in the code processing community, there had been works such as InferCode (Bui et al., 2021a) that processes these representations with special network architectures like Tree-Based CNN and conducts self-supervised pretraining by predicting subtrees.

TreeBERT (Jiang et al., 2021b) is one of the first attempts to take AST into the Transformer-based pretraining-finetuning framework. It’s a Transformer encoder-decoder pretrained with Tree MLM and Node Order Prediction, where the encoder takes a set of constituent paths in the AST as input (with each token being a path, which is the concatenation of its nodes’ representations) while the decoder takes the code as input. Tree MLM is then performed by masking certain nodes in a path representation and its corresponding code tokens in the decoder input, while Node Order Prediction is accomplished by swapping nodes in a path and predicting it with a [CLS] token similar to BERT.

The method used by TreeBERT, however, is complicated and does not scale well. Later works mostly opt to first process AST into a text sequence and treat it like a normal part of the input. Wang et al. (2021c), for example, process AST with depth-first traversal and concatenate it with code and comment, and then train SynCoBERT (which, unlike TreeBERT, is actually a BERT-like encoder-only model) with four objectives: 1) MLM; 2) identifier tagging; 3) AST edge prediction (predicting whether there exists an edge between

two AST nodes from the dot product of these nodes’ representations); and 4) contrastive learning over i) code and AST pairs, as well as ii) text and code-AST pairs. Similarly, SPT-Code (Niu et al., 2022), a Transformer encoder-decoder, takes the concatenation of code, sequentialized AST, and text as input, and is pretrained with 1) span corruption; 2) code-AST prediction (NSP with one segment being code and one segment being AST); and 3) method name generation, a special form of span corruption where a method name is masked. Different from other works, however, they do not take the docstrings as the text segment in their input, but instead concatenate all method names appearing in the code as a succinct natural language description. Likewise, UniXcoder (Guo et al., 2022) takes flattened AST instead of source code as its input during training.

In the compiling pipeline, AST is usually followed by language-independent intermediate representations, such as LLVM IR (Lattner & Adve, 2004). Such features’ independence from specific programming languages makes them suitable candidates for translation pivots, as is English in machine translation of low-resource natural languages (Leng et al., 2019). Szafraniec et al. (2023) take advantage of this characteristic and extend Transcoder (Rozière et al., 2020) with translation language modeling (Conneau & Lample, 2019) over code and IR, as well as IR generation from code. They also investigate other objectives such as IR decompilation (i.e. generating code from IR) and IR pivot (i.e. directly generating code in one language from the IR of another language), both showing promising results.

6.2 Control Flow and Data Flow

While AST and IR have proved to be useful information in certain tasks such as code translation, they are static by nature, just like the source code, and may fail to capture semantic properties of code that are only revealed at runtime (Wang & Su, 2020). Such semantics, however, are contained in dynamic features such as control flow and data flow. Similar to AST, specialized networks were used to process such information before the rise of pretrained Transformers, such as Message Passing Neural Network used by ProGraML (Cummins et al., 2021). Unlike AST, however, even after pretrained Transformers became dominant few works have looked in this direction.

GraphCodeBERT (Guo et al., 2021a) is one of such works, which creates special tokens and position embeddings for variables in the flow graph, and concatenates the variable sequence after text and source code to construct model input, with tailored attention masks on the code and variable segments: tokens from code segment and variable segment can attend to each other if and only if the variable is identified from the code token, and for tokens within the variable segment, v_i is allowed to attend to v_j if there is a direct edge from v_j to v_i in the dataflow. The model is then pretrained with MLM in combination with edge prediction and node alignment, both of which are accomplished by binary classification from the dot product of two tokens’ representations (one from code segment and one from variable segment for node alignment, and both from variable segment for edge prediction).

6.3 Type

Apart from AST, IR, and data flow, type information has also been used to aid language models in processing code. CugLM (Liu et al., 2020), for example, uses type information during finetuning to aid in the prediction of tokens for unidirectional MLM (i.e. MLM with unidirectional attention mask): the type of a masked token is first predicted from the final Transformer layer’s representation, and then the token itself is predicted based on both the hidden representation and predicted type. In contrast, both CodeT5 (Wang et al., 2021e) and SynCoBERT (Wang et al., 2021c) include identifier tagging in their pretraining objectives, which can be viewed as coarse-grained type prediction.

6.4 Program Transformation

As we have shown in Section 5.3, function-preserving program transformations have proven to be important techniques in pretraining code language models. Obfuscation is one instance of program transformation, and others include loop transformation (for-while), condition transformation (if-switch), dead code injection (e.g. `if True: pass`), and statement swapping. DOBF (Lachaux et al., 2021) and NatGen (Chakraborty et al.,

2022a) are two code language models pretrained to recover the original program from such transformations, while Wang et al. (2022a) also apply program transformations during the finetuning stage of language models to make them more robust to transformed test samples.

Notably, Wang et al. (2022d) integrate many of the aforementioned features into Code-MVP: source code, docstrings, AST, CFG, and transformed source code via identifier renaming, loop exchange, and dead code insertion. The model, initialized from GraphCodeBERT, is then trained with MLM, fine-grained type prediction, and contrastive learning across different views, such as text vs. code, code vs. AST, and code vs. CFG.

7 LLMs in Software Development

As language models set new records on software engineering benchmarks, software engineering technologies are also expanding the boundaries of language models in return, and have subsequently led them into real-world development cycles.

7.1 LLMs Extended with Coding Tools

Researches in the NLP community have shown that LLMs can learn to use external tools such as calculators, MT systems, and search engines (Thoppilan et al., 2022; Schick et al., 2023). As such, *interpreter* has been used to augment LLMs in complex reasoning tasks. PAL (Gao et al., 2023b) and PoT (Chen et al., 2022) both extend Codex with Python interpreters for numerical calculations, while ViperGPT (Surís et al., 2023) extends it further by calling vision APIs to extract information from visual input and answer related questions.

However, LLMs do not always produce code that can be interpreted and executed, and there has also been a line of works that explore the possibility of emulating the interpreter with LLMs themselves. Nye et al. (2021) trains LLMs to emulate the execution of programs by outputting program states at each step. More recently, Li et al. (2023a) propose Chain-of-Code, where a real interpreter executes the generated code until an error occurs, whereupon the LLM takes over to simulate execution.

Apart from alleviating the burden of numerical calculation in abstract reasoning tasks, *interpreter* also provides feedback on the process of code generation itself, together with unit tests. CodeT (Arteca et al., 2022) and TiCoder (Bareiß et al., 2022) use Codex to generate unit tests, which are run against generated code samples to improve the model’s performance on code synthesis. Similarly, TransCoder-ST (Rozière et al., 2022) augments TransCoder and DOBF with external unit tests for code translation, while InterCode (Yang et al., 2023d) explores interactive coding with execution feedback. In Section 5.7, we have also shown that the execution results on unit tests serve as natural supervision signals for reinforcement learning on code.

Notably, in March 2023 OpenAI also released an interpreter plugin for ChatGPT⁸, which can accept file inputs from users, generate code according to user instructions, and provide feedback via real-time execution. Zhou et al. (2023a) show that this feature allows GPT-4 to self-debug.

A topic closely related to tool using in LLM researches is *planning* as intelligent agents, which has been shown to enhance LLMs’ capability both theoretically and empirically (Feng et al., 2023). Ruan et al. (2023) find that LLMs can plan to solve complex tasks using external SQL generators and Python generators, while CodePlan (Bairi et al., 2023) demonstrates they can perform repository-level coding via adaptive planning.

Another stream of works use LLMs to create multi-agent systems for code generation, such as self-collaboration (Dong et al., 2023), ChatDev (Qian et al., 2023), and MetaGPT (Hong et al., 2023). In these frameworks, multiple LLMs are prompted to play distinct roles such as programmer, reviewer, and manager. These roles interact with each other, breakdown code generation into different phases (e.g. designing, coding, testing, and documenting), and collaborate to complete complex tasks.

⁸<https://openai.com/blog/chatgpt-plugins#code-interpreter>

7.2 LLMs Integrated into Software Development

With the increase in LLMs’ interactive coding capability, researchers have also started to integrate them into each and every process of software development.

Auto code completion is one of the earliest applications of language models in software development, as they require only the ability to predict the next token. Even before language models scaled to billions of parameters, there had been integration of completion systems such as Pythia (Svyatkovskiy et al., 2019) and IntelliCode (Svyatkovskiy et al., 2020) into popular IDEs.

Recently, however, the application of code language models have transcended simple code completion. GitHub Copilot is arguably one of the most popular AI code assistants, with diverse features including code generation, vulnerability detection, and license management⁹, while CodeFuse (Di et al., 2023) also integrates code generation, code translation, code commenting, and testcase generation into a single IDE extension. As code language models become larger, however, their client-side deployment and real-time performance also raise new challenges.

As LLMs continue to advance, building applications on top of them is also evolving into a consequential task itself. Many open-source frameworks for such applications have been released, including LangChain¹⁰, AutoGPT¹¹, and WorkGPT¹². These frameworks provide abstractions over language models for developers, and are actively revolutionizing the entire process of software development even as this survey is being finalized.

8 Conclusion and Challenges

In this work, we systematically reviewed the history of code processing with pretrained Transformer language models, and highlighted their relations and comparisons to models pretrained on general domains. The advancement in code modeling generally follows the history course of NLP, evolving from SMT models, to NMT models, and then to finetuning pretrained Transformers and lastly to few-shot application of LLMs and even autonomous agents in real-world production. Unlike natural languages, the nature of code makes it easy to extract auxiliary information from alternative views, and to utilize interpreter and unit tests for automatic feedback.

With these in mind, we identify several challenges in the current development of code modeling.

- **Comprehensive benchmarks to push code LLMs to the next stage.** The widely used HumanEval benchmark plays a key role in the evolution of Code LLMs. However, it is relatively small and its scoreboard has been manipulated to near perfect, which does not exactly reflect real-world behaviors. Many other benchmarks for Code LLMs have been proposed, but they are still not comprehensive enough to reflect production-level requirements. The community is eager for a new standard benchmark after HumanEval to further boost the progress of Code LLMs to the next stage.

- **Acquisition of high-quality data.** With Gunasekar et al. (2023) achieving SOTA performance with a 1.3B model trained on textbook data, we believe the selection of training data and utilization of synthetic data will be ever more prominent in the near future, for both self-supervised pretraining and supervised finetuning.

- **Integration of code features into language models.** As we noted in Section 6.2, CFG and DFG are yet to be employed at scale in code language modeling. The few works that do employ data flow make changes to the models’ attention masks, which severely limits their cross-task generalization and scaling ability. We believe the seamless integration of such features into textual input is worth researching in the future.

⁹<https://github.com/features/copilot>

¹⁰<https://www.langchain.com/>

¹¹<https://github.com/Significant-Gravitas/AutoGPT>

¹²<https://github.com/team-openpm/workgpt>

- **Application of LLMs in more code downstream tasks.** As we have pointed out in Section 2, current evaluation of LLMs’ coding capability is focused on program synthesis, and Figure 5 clearly shows that tasks related to software testing (viz. unit test generation, assertion generation, mutant generation, and fuzzing) and deobfuscation have seen few application of LLMs. Besides, since the context window of LLMs are currently quite limited, generation tasks such as program synthesis and code translation are yet to be applied beyond method level. In Section 2.4, we have listed several works on repository-level code completion and temporal editing, and we believe the application of LLMs in more repository-level tasks will become a hot research topic in the future.

- **Alternative model architectures and training objectives.** In Table 3, we have shown that many code language models are pretrained with auxiliary objectives specific to code, but these models all belong to the encoder-only or encoder-decoder family, while decoder-only models are yet to be augmented with alternative objectives. Also, as pioneered by Singh et al. (2023), we believe diffusion models will find its ground in code modeling in the future.

- **Building code LLM ecosystem for full-life-cycle of software development.** While the academia have witnessed an abundance of code models, most have been deployed in the coding stage as IDE plugins while neglecting other stages in the life-cycle of software development. In Section 7.2 we mentioned several inspiring examples, and we are hoping to see more applications of code LMs throughout the full life-cycle of software development, from requirement analysis to DevOps, eventually leading to full-scale ecosystems like those around PyTorch (Paszke et al., 2019) and Hugging Face¹³.

- **Safety and ethics issues related to code LLMs.** As language models grow in might, they also raise safety concerns including but not limited to data contamination, toxic or biased generation, personal information leak, and hallucinations. In software development, these models should be deployed with extra caution, as their generated code may contain security risks leading to catastrophic results. Pretraining data is also becoming a sensitive topic of ethics, and Kocetkov et al. (2022) take a meaningful step towards this issue by allowing developers to remove their code from the Stack. As synthetic training data becomes widespread, researchers should also proceed with caution about such practice, as the consequence of training AI models with AI generated data is yet to be investigated at scale.

With the presentation of this survey, we hope to provide a global view of language models’ application in software engineering and connect the researches from the two communities. We believe the current surge of LLMs will be ultimately transformed into real world applications, and lead humanity into a brighter future.

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A Benchmarks for Downstream Tasks

Table 5, 6, 7, 8, 9, 10 list benchmark datasets for code downstream tasks. For the size of these datasets, we use self-reported number whenever available.

Table 5: Benchmarks for text-to-SQL generation.

Task	Date	Benchmark	Source	Size
Text-to-SQL	1990	ATIS	Hemphill et al. (1990); Dahl et al. (1994)	11508
	1996	GeoQuery	Zelle & Mooney (1996)	877
	2000	Restaurants	Tang & Mooney (2000)	378
	2014-09	MAS	Li & Jagadish (2014)	196
	2017-02	Yelp	Yaghmazadeh et al. (2017)	128
	2017-02	IMDb	Yaghmazadeh et al. (2017)	131
	2017-04	Scholar	Iyer et al. (2017)	816
	2017-08	WikiSQL	Zhong et al. (2017)	80654
	2018-06	Advising	Finegan-Dollak et al. (2018)	4570
	2018-09	Spider	Yu et al. (2018c)	10181
	2019-06	SParC	Yu et al. (2019c)	12726
	2019-07	MIMICSQL	Wang et al. (2020b)	10000
	2019-09	CoSQL	Yu et al. (2019b)	15598
	2020-05	Criteria-to-SQL	Yu et al. (2020)	2003
	2020-10	Squall	Shi et al. (2020)	11276
	2020-10	Spider-Realistic	Deng et al. (2021)	508
	2021-06	Spider-Syn	Gan et al. (2021a)	8034
	2021-06	SEDE	Hazoom et al. (2021)	12023
	2021-06	KaggleDBQA	Lee et al. (2021)	400
	2021-09	Spider-DK	Gan et al. (2021b)	535
2022-05	Spider-SS	Gan et al. (2022)	8034	
2022-05	Spider-CG	Gan et al. (2022)	45599	
2023-05	BIRD	Li et al. (2023g)	12751	

Table 6: Benchmarks for program synthesis. JS is short for JavaScript. *Automatically mined/human-annotated. †These are 1749 prompts for 48 problems. ‡10538 prompts for 1420 methods. ◊Machine-generated/human-annotated prompts.

Task	Date	Benchmark	Source	Size	Language
Program Synthesis	2018-02	NL2Bash	Lin et al. (2018b)	9305	Bash
	2018-08	CONCODE	Iyer et al. (2018)	104K	Java
	2019-10	JuICe	Agashe et al. (2019)	*1.5M/3725	Python
	2021-05	APPS	Hendrycks et al. (2021a)	10000	Python
	2021-07	HumanEval	Chen et al. (2021b)	164	Python
	2021-08	MBPP	Austin et al. (2021)	974	Python
	2021-08	MathQA-Python	Austin et al. (2021)	23914	Python
	2021-08	PlotCoder	Chen et al. (2021c)	40797	Python
	2022-01	DSP	Chandel et al. (2022)	1119	Python
	2022-02	CodeContests	Li et al. (2022g)	13610	C++, Python, Java
	2022-03	MCoNaLa	Wang et al. (2023e)	896	Python
	2022-06	AixBench	Hao et al. (2022)	336	Java
	2022-10	MBXP	Athiwaratkun et al. (2023)	12.4K	13
	2022-10	Multilingual HumanEval	Athiwaratkun et al. (2023)	1.9K	12
	2022-10	MathQA-X	Athiwaratkun et al. (2023)	5.6K	Python, Java, JS
	2022-11	ExeDS	Huang et al. (2022b)	534	Python
	2022-11	DS-1000	Lai et al. (2023)	1000	Python
	2022-12	ODEX	Wang et al. (2022g)	945	Python
	2023-02	CoderEval	Yu et al. (2023a)	460	Python, Java
	2023-03	xCodeEval	Khan et al. (2023)	5.5M	11
	2023-03	HumanEval-X	Zheng et al. (2023a)	820	Python, C++, Java, JS, Go
	2023-06	StudentEval	Babe et al. (2023)	†1749	Python
	2023-06	DotPrompts	Agrawal et al. (2023)	‡10538	Java
	2023-09	CodeApex	Fu et al. (2023)	476	C++
	2023-09	VerilogEval	Liu et al. (2023g)	◊8645/156	Verilog
	2023-11	ML-Bench	Liu et al. (2023l)	10040	Bash
	2024-01	CRUXEval	Gu et al. (2024)	800	Python

Table 7: Benchmarks for code translation and program repair. JS is short for JavaScript. *These are pairwise sample counts. For example, HumanEval-X includes 164 programs, each implemented in 5 languages, totaling $164 \times (5 \times 4 / 2) = 1640$ translation pairs. †These are code change datasets, and only a subset therein concern bug-fixing.

Task	Date	Benchmark	Source	Size	Language
Code Translation	2020-06	GeeksforGeeks	Rozière et al. (2020)	1.4K	C++, Java, Python
	2021-02	CodeTrans	Lu et al. (2021)	11.8K	Java, C#
	2021-08	Avatar	Ahmad et al. (2023)	9515	Java, Python
	2022-06	CoST	Zhu et al. (2022b)	*132K	C++, Java, Python, C#, JS, PHP, C
	2022-06	XLCoST	Zhu et al. (2022a)	*567K	C++, Java, Python, C#, JS, PHP, C
	2023-03	xCodeEval	Khan et al. (2023)	*5.6M	11
	2023-03	HumanEval-X	Zheng et al. (2023a)	*1640	Python, C++, Java, JS, Go
	2023-08	G-TransEval	Jiao et al. (2023)	*4000	C++, Java, C#, JS, Python
	2023-10	CodeTransOcean	Yan et al. (2023)	270.5K	45
	Program Repair	2014-07	Defects4J	Just et al. (2014)	357
2015-12		ManyBugs	Goues et al. (2015)	185	C
2015-12		IntroClass	Goues et al. (2015)	998	C
2016-11		BugAID	Hanam et al. (2016)	105K	JS
2017-02		DeepFix	Gupta et al. (2017)	6971	C
2017-05		Codeflaws	Tan et al. (2017)	3902	C
2017-10		QuixBugs	Lin et al. (2017)	80	Java, Python
2018-05		Bugs.jar	Saha et al. (2018)	1158	Java
2018-12		BFP	Chakraborty et al. (2022b)	124K	Java
2019-01		Bears	Madeiral et al. (2019)	251	Java
2019-01		unnamed	Tufano et al. (2019a)	†21.8K	Java
2019-04		BugsJS	Gyimesi et al. (2019)	453	JS
2019-05		BugSwarm	Tomassi et al. (2019)	1827/1264	Java/Python
2019-05		CPatMiner	Nguyen et al. (2019)	†17K	Java
2019-05		ManySStuBs4J	Karampatsis & Sutton (2020)	154K	Java
2019-11		Refactory	Hu et al. (2019)	1783	Python
2020-07		CoCoNut	Lutellier et al. (2020)	24M	Java, JS, C, Python
2020-10		Review4Repair	Huq et al. (2022)	58021	Java
2020-11		BugsInPy	Widyasari et al. (2020)	493	Python
2021-07		TFix	Berabi et al. (2021)	105K	JS
2021-08		Megadiff	Monperrus et al. (2021)	†663K	Java
2022-01		SSB/TSSB	Richter & Wehrheim (2022)	9M/3M	Python
2022-10		FixJS	Csuvik & Vidács (2022)	324K	JS
2022-11		TypeBugs	Oh & Oh (2022)	93	Python
2023-03		xCodeEval	Khan et al. (2023)	4.7M	11
2023-04		RunBugRun	Prenner & Robbes (2023)	450K	C, C++, Java, Python, JS, Ruby, Go, PHP
2023-08	HumanEvalPack	Muennighoff et al. (2023)	984	Python, JS, Go, Java, C++, Rust	

Table 8: Benchmarks for code summarization, code completion, commit message generation, and defect/vulnerability detection. JS is short for JavaScript. *The task of code completion can be evaluated on any source code corpus, so we only list a few widely used benchmarks here. For cross-file code completion please refer to Table 10. †With/without verb-direct object filter.

Task	Date	Benchmark	Source	Size	Language
Code Summarization	2016-08	CODE-NN	Iyer et al. (2016)	66K/32K	C#/SQL
	2017-07	unnamed	Barone & Sennrich (2017)	150K	Python
	2018-05	DeepCom	Hu et al. (2018a)	588K	Java
	2018-07	TL-CodeSum	Hu et al. (2018b)	411K	Java
	2018-11	unnamed	Wan et al. (2018)	109K	Python
	2019-02	unnamed	LeClair et al. (2019)	2.1M	Java
	2019-09	CodeSearchNet	Husain et al. (2019)	2.3M	Go, JS, Python, PHP, Java, Ruby
	2023-08	HumanEvalPack	Muennighoff et al. (2023)	984	Python, JS, Go, Java, C++, Rust
*Code Completion	2013-05	GitHub Java Corpus	Allamanis & Sutton (2013)	2.1M	Java
	2016-10	Py150	Raychev et al. (2016a)	150K	Python
	2016-10	JS150	Raychev et al. (2016a)	150K	JS
	2023-06	LCC	Guo et al. (2023b)	360K	Python, Java, C#
Commit Message Generation	2017-03	unnamed	Jiang & McMillan (2017)	509K	Java
	2017-04	CommitGen	Loyola et al. (2017)	153K	Python, C++, Java, JS
	2017-08	CommitGen	Jiang et al. (2017)	†32K/75K	Java
	2018-09	NNGen	Liu et al. (2018)	27K	Java
	2019-05	PtrGNCMsg	Liu et al. (2019c)	64.9K	Java
	2019-08	CoDiSum	Xu et al. (2019a)	90.7K	Java
	2019-12	ATOM	Liu et al. (2022c)	160K	Java
	2021-05	CommitBERT	Jung (2021)	346K	Python, PHP, Go, Java, JS, Ruby
	2021-07	MCMD	Tao et al. (2021)	2.25M	Java, C#, C++, Python, JS
	2021-07	CoRec	Wang et al. (2021b)	107K	Java
	2023-07	ExGroFi	Wang et al. (2023a)	19263	Java
2023-08	CommitChronicle	Eliseeva et al. (2023)	10.7M	20	
Defect (Vulnerability) Detection	2018-01	CGD	Li et al. (2018b)	62K	C, C++
	2018-07	Draper VDISC	Russell et al. (2018)	12.8M	C, C++
	2018-07	SySeVR	Li et al. (2022i)	15591	C, C++
	2018-04	unnamed	Lin et al. (2018a)	32988	C, C++
	2019-02	unnamed	Ponta et al. (2019)	624	Java
	2019-09	Devign	Zhou et al. (2019)	48687	C
	2019-11	unnamed	Lin et al. (2021)	170K	C, C++
	2019-12	GREAT	Hellendoorn et al. (2020)	2.8M	Python
	2020-01	MVD	Zou et al. (2021)	182K	C, C++
	2020-02	unnamed	Lin et al. (2019)	1471	C
	2020-09	ReVeal	Chakraborty et al. (2022c)	18K	C
	2020-09	Big-Vul	Fan et al. (2020)	265K	C, C++
	2021-02	D2A	Zheng et al. (2021)	1.3M	C, C++
	2021-05	PyPIBugs	Allamanis et al. (2021)	2374	Python
	2021-07	CVEfixes	Bhandari et al. (2021)	5495	27
	2021-08	CrossVul	Nikitopoulos et al. (2021)	27476	40+
	2023-04	DiverseVul	Chen et al. (2023d)	349K	C, C++
	2023-06	VulnPatchPairs	Risse & Böhme (2023)	26K	C
	2023-11	VulBench	Gao et al. (2023d)	455	C

Table 9: Benchmarks for code retrieval, code reasoning, type inference, and clone detection/code search,. JS is short for JavaScript. *These benchmarks include a large number of automatically constructed samples, and a small set of human-annotated samples. †These are general-domain reasoning benchmarks, and only a subset therein concern programming, algorithms, and other topics related to computer science. ‡These are project counts (or, in the case of Cassano et al. (2023b), file counts). Yee & Guha (2023) propose to measure project-level type check rate instead of type prediction accuracy for TypeScript. ◊These are 21K/24K Java/Python methods for 576 programming problems.

Task	Date	Benchmark	Source	Size	Language
Code Retrieval	2018-03	StaQC	Yao et al. (2018)	268K	Python, SQL
	2018-05	DeepCS	Gu et al. (2018)	16M	Java
	2018-05	CoNaLa	Yin et al. (2018)	*600K/2.9K	Python
	2019-08	unnamed	Li et al. (2019b)	287	Java
	2019-09	CodeSearchNet	Husain et al. (2019)	*2.3M/99	Go, JS, Python, PHP, Java, Ruby
	2020-02	CosBench	Yan et al. (2020)	52	Java
	2020-08	SO-DS	Heyman & Cutsem (2020)	2.2K	Python
	2020-10	FB-Java	Ling et al. (2021)	249K	Java
	2021-02	AdvTest	Lu et al. (2021)	280K	Python
	2021-02	WebQueryTest	Lu et al. (2021)	1K	Python
	2021-05	CoSQA	Huang et al. (2021)	21K	Python
Code Reasoning	2020-09	MMLU	Hendrycks et al. (2021b)	†15908	Java/Python
	2021-09	CodeQA	Liu & Wan (2021)	120K/70K	
	2022-10	CS1QA	Lee et al. (2022)	9237	
	2023-05	C-Eval	Huang et al. (2023b)	†13948	
	2023-06	CMMLU	Li et al. (2023b)	†11528	
	2023-09	CodeApex	Fu et al. (2023)	250	
Type Inference	2019-12	TypeWriter OSS	Pradel et al. (2020)	208K	Python
	2020-04	Typilus	Allamanis et al. (2020)	252K	Python
	2020-04	LambdaNet	Wei et al. (2020)	‡300	TypeScript
	2021-04	ManyTypes4Py	Mir et al. (2021)	869K	Python
	2022-10	ManyTypes4TypeScript	Jesse & Devanbu (2022)	9.1M	TypeScript
	2023-02	TypeWeaver	Yee & Guha (2023)	‡513	TypeScript
	2023-03	BetterTypes4Py	Wei et al. (2023)	608K	Python
	2023-03	InferTypes4Py	Wei et al. (2023)	4.6K	Python
Clone Detection / Code Search	2023-05	OpenTau	Cassano et al. (2023b)	‡744	TypeScript
	2014-09	BigCloneBench	Svajlenko et al. (2014)	6M	Java
	2014-09	POJ-104	Mou et al. (2016)	52K	C, C++
	2019-05	unnamed	Perez & Chiba (2019)	◊21K/24K	Java/Python
2019-11	CLCDSA	Nafi et al. (2019)	78K	Java, C#, Python	

Table 10: Benchmarks for unit test/assertion generation, log parsing, and repository level coding. *LogHub (2023) is an annotated subset of LogHub (2018). †Line Completion/API Invocation Completion/Function Completion. ‡Retrieval/Completion/Pipeline. *File count. ◊Migration/Temporal Edit.

Task	Date	Benchmark	Source	Size	Language
Unit Test / Assertion Generation	2014-12	SF110	Fraser & Arcuri (2014)	24K	Java
	2020-09	Method2Test	Tufano et al. (2021a)	781K	Java
	2021-08	ConTest	Villmow et al. (2021)	365K	Java
Log Parsing	2018-11	LogHub (2018)	Zhu et al. (2019); He et al. (2020)	379M	
	2023-08	LogHub (2023)	Jiang et al. (2023d)	*50.4M	
Repository- Level Coding	2023-03	RepoEval	Zhang et al. (2023b)	†1600/1600/373	Python
	2023-06	RepoBench	Liu et al. (2023i)	‡890K/9M/43K	Python, Java
	2023-06	PragmaticCode	Agrawal et al. (2023)	*880	Java
	2023-06	Stack-Repo	Shrivastava et al. (2023a)	816K	Java
	2023-09	CodePlan	Bairi et al. (2023)	◊645/21	◊C#/Python
	2023-10	SWE-Bench	Jimenez et al. (2023)	2294	Python
	2023-10	CrossCodeEval	Ding et al. (2023)	9928	Python, Java, TypeScript, C#