000 001 002 003 CONLUX: CONCEPT-BASED LOCAL UNIFIED EXPLANATIONS

Anonymous authors

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ABSTRACT

With the rapid advancements of various machine learning models, there is a significant demand for model-agnostic explanation techniques, which can explain these models across different architectures. Mainstream model-agnostic explanation techniques generate local explanations based on basic features (e.g., words for text models and (super-)pixels for image models). However, these explanations often do not align with the decision-making processes of the target models and end-users, resulting in explanations that are unfaithful and difficult for users to understand. On the other hand, concept-based techniques provide explanations based on high-level features (e.g., topics for text models and objects for image models), but most are model-specific or require additional pre-defined external concept knowledge. To address this limitation, we propose ConLUX, a general framework to provide concept-based local explanations for any machine learning models. Our key insight is that we can automatically extract high-level concepts from large pre-trained models, and uniformly extend existing local model-agnostic techniques to provide unified concept-based explanations. We have instantiated ConLUX on four different types of explanation techniques: LIME, Kernel SHAP, Anchor, and LORE, and applied these techniques to text and image models. Our evaluation results demonstrate that 1) compared to the vanilla versions, ConLUX offers more faithful explanations and makes them more understandable to users, and 2) by offering multiple forms of explanations, ConLUX outperforms stateof-the-art concept-based explanation techniques specifically designed for text and image models, respectively.

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1 INTRODUCTION

035 036 037 038 039 040 041 042 As machine learning models become more complex and popular, it has become an emerging topic to explain the rationale behind their decisions. In particular, as the structure of machine learning models diversifies and evolves rapidly, and effective closed-source models (e.g., GPT-4 [\(Achiam et al.,](#page-10-0) [2023\)](#page-10-0) and Gemini [\(et al., 2024b\)](#page-10-1)) become more prevalent, model-agnostic explanation techniques show their appeal due to their adaptability to various models and tasks [\(Wang, 2024\)](#page-13-0). These techniques consider target models as black boxes, so they can explain any machine learning model without requiring any knowledge of the model's internal structure. This paper addresses the challenge of incorporating high-level concepts into local model-agnostic techniques to explain the decisionmaking processes of various machine learning models, including large language models (LLMs).

043 044 045 046 047 048 049 050 051 052 053 To faithfully explain the behavior of machine learning models, it is essential to provide explanations built from language components aligned with the decision process of the target models; to make explanations easy to understand, it is also crucial to provide explanations built from user-friendly language components [\(Poeta et al., 2023a\)](#page-12-0). Unfortunately, mainstream model-agnostic explanation techniques often fail to meet both requirements, as they provide explanations built from basic features (e.g., words for text models and (super-)pixels for image models) [\(Ribeiro et al., 2016;](#page-12-1) [Lundberg & Lee, 2017;](#page-11-0) [Ribeiro et al., 2018;](#page-12-2) [Guidotti et al., 2018\)](#page-11-1). In contrast, many concept-based techniques provide explanations based on high-level features (e.g., topics in texts and objects in images) [\(Poeta et al., 2023a\)](#page-12-0). These techniques either utilize the internal information of the target models like gradients, activations, and attention weights [\(Zhang et al., 2021b;](#page-13-1) [Yeh et al., 2020;](#page-13-2) [2019b;](#page-13-3) [Cunningham et al., 2023;](#page-10-2) [Ghorbani et al., 2019b;](#page-11-2) [Crabbe & van der Schaar, 2022;](#page-10-3) [Fel et al.,](#page-10-4) ´ [2023\)](#page-10-4), or pre-defined external knowledge [\(El Shawi, 2024;](#page-10-5) [Widmer et al., 2022\)](#page-13-4) to build high-level

069 070 071 072 Figure 1: Example explanation (a) is generated by LIME, demonstrating how each word in the input sentence contributes to the target model's prediction. The color intensity reflects the magnitude of the weight, with deeper hues indicating larger absolute values. Example explanation (b) is generated by ConLUX-augmented LIME, providing an explanation based on high-level concepts.

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075 076 077 078 concepts. This limits these techniques to specific types of models or tasks. Furthermore, while there are different forms of explanations (e.g. feature attributions, rules) for various purposes [\(Zhang](#page-13-5) [et al., 2021c\)](#page-13-5), existing concept-based explanations mainly focus only on attributions, which limits their fidelity and applicability.

079 080 081 082 083 084 085 086 087 088 089 090 091 To bridge this gap, we aim to elevate the explanations of various forms provided by existing modelagnostic techniques from feature-level to concept-level. As we focus on explaining the decisionmaking process of machine learning models to end-users, we put our emphasis on local explanations, which are more tractable for end-users. We find that existing local model-agnostic techniques all follow similar workflows, which allows us to introduce a unified way to elevate all these techniques from feature level to concept level. This transition necessitates automating the concept extraction process and establishing bidirectional mappings between concept representations and feature representations for given input data. Noticing that existing works have utilized large pre-trained models to extract concepts and represent input data at the concept level for specific tasks [\(Ludan et al.,](#page-11-3) [2023;](#page-11-3) [Sun et al., 2023\)](#page-12-3), we generalize these findings and further observe that large models also have the ability to map concept-level representations back to the feature-level. To this end, we propose ConLUX, a general framework that automatically incorporates high-level concepts into various existing local model-agnostic techniques for any machine learning models, and provides local explanations in various forms for diverse user needs.

092 093 094 095 We take three mainstream local model-agnostic techniques, LIME [\(Ribeiro et al., 2016\)](#page-12-1), Anchor [\(Ribeiro et al., 2018\)](#page-12-2), and LORE [\(Guidotti et al., 2018\)](#page-11-1) as examples to illustrate how ConLUX improves local model-agnostic explanations.

096 097 098 099 100 101 102 103 104 105 106 107 Figure [1](#page-1-0) shows a LIME explanation for a BERT-based sentiment analysis model on a movie review. The target model classifies the sentence as negative. LIME provides feature-level attributions, indicating how each word contributes to the model's prediction. In this case, LIME assigns high negative scores to the words "however" and "falls", which indicates that these words contribute much to the negative prediction. However, this explanation is unfaithful and hard to understand by end-users. For example, the word "however" is assigned a high negative score, but it functions as a conjunction and does not directly convey sentiment [\(Liu & Zhang, 2023\)](#page-11-4). Moreover, such confusing attributions, combined with an overwhelming amount of attribution information, complicate the explanation for end-users. ConLUX addresses these issues by elevating the explanation from feature-level to concept-level. ConLUX-agumented LIME extracts the main topics of the input sentence using GPT-4o, and then provides attribution-based explanations with these topics. From this explanation, users can easily understand that the negative prediction is mainly because the sentence mentions the movie's poor performance in "emotion impact" and "direction and script", while the part about "stunning visuals" and "passable plot" also expresses some positive sentiment. This ex-

- Figure 3: Example Anchors, LORE explanations and their ConLUX-augmented versions.
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136 137 138 planation faithfully reflects the decision process of the target model and is more understandable to end-users.

139 140 141 142 143 144 145 146 Similar issues exist in the explanation of image models. We use YOLOv8 [\(Jocher et al., 2023\)](#page-11-5) to perform an image classification task on ImageNet [\(Deng et al., 2009\)](#page-10-6) dataset. Figure [2](#page-2-0) shows a LIME explanation for an image classified as a *punching bag*. LIME attributes high importance to some fragmented superpixels. End-users can hardly understand why these parts are important for the model's prediction. ConLUX-augmented LIME provides explanations based on objects detected by Segment Anything Model (SAM) [\(Kirillov et al., 2023\)](#page-11-6), and attributes high importance to the punching bag itself and the kid in the image. This explanation is more faithful and understandable. End-users can easily realize that the model does not perform perfectly when classifying this image to a *punching bag*.

147 148 149 150 151 152 153 154 155 156 157 158 Figure [3](#page-2-1) shows the explanations generated by Anchor, LORE, and their ConLUX-augmented versions for an image classified as a *pickup*. Anchors provides rule-based sufficient conditions (referred to as *anchors*) for the target model's prediction. The vanilla anchor indicates that parts of the car and the background house guarantee the prediction as a *pickup*. With ConLUX, end-users can easily understand that the model classifies the image as a *pickup* exactly because it indeed detects the pickup truck in the image. LORE provides rule-based sufficient conditions and counterfactual explanations. Figure [3](#page-2-1) shows the counterfactual explanations, which show users how to change the model's prediction by modifying the input image. The vanilla LORE explanation indicates that if we mask a part of the grass, the background house and the whole side window of the truck will change the model's prediction to a *Half track*. In contrast, ConLUX-augmented LORE indicates that users can simply mask the pickup truck to change the model's prediction to a *Bison*, which is more user-friendly.

159 160 The preceding examples indicate that feature-level explanations are hard to understand by end-users. On the other hand, as high-level concepts align with the decision process of target models and users

161 better [\(Zhang et al., 2021a;](#page-13-6) [Ghorbani et al., 2019a;](#page-11-7) [Kim et al., 2018;](#page-11-8) [Sun et al., 2023\)](#page-12-3), ConLUX addresses this by providing concept-level explanations, and the examples demonstrate that ConLUX

162 163 164 165 166 167 makes explanations more understandable to end-users. Moreover, our empirical evaluation shows these concept-level explanations are also more faithful to the models. Finally, benefiting from the various types of explanations provided by existing local model-agnostic techniques, ConLUX can provide rich explanations including attributions, sufficient conditions, and counterfactuals, satisfying diverse user needs and offering a more comprehensive understanding of the target models. This fills the current gap in concept-based explanations, which lack forms beyond attributions.

168 169 170 171 172 173 174 175 To elevate the explanations provided by existing local model-agnostic techniques from feature-level to concept-level, we modify these techniques in a uniform and lightweight way based on their two commonalities: 1) these techniques use basic features as language components to build explanations; 2) these techniques use a perturbation model, which generates samples similar to the given input by changing some of its feature values, to capture the local behavior of the target model at the feature level. To this end, by only elevating the language components to high-level concepts and extending the perturbation model to generate samples by changing high-level concepts, ConLUX extends these techniques to provide concept-level explanations.

176 177 178 179 180 181 182 183 We evaluated ConLUX on explaining two sentiment analysis models (BERT, Llama 3.1[\(et al.,](#page-10-7) [2024a\)](#page-10-7)) and three image classification models(YOLOv8, Vision Transformer [\(Oquab et al., 2023;](#page-12-4) [Darcet et al., 2023\)](#page-10-8), and ResNet-50 [\(He et al., 2016\)](#page-11-9)). Our evaluation results demonstrate that ConLUX improves the fidelity of Anchors, LIME, LORE, and Kernel SHAP explanations by 82.21%, 48.59%, 149.93%, and 48.27% respectively, and by considering various forms of explanations together, ConLUX outperforms state-of-the-art concept-based explanation techniques specifically designed for text models (TBM [\(Ludan et al., 2023\)](#page-11-3)) and image models (EAC [\(Sun et al.,](#page-12-3) [2023\)](#page-12-3)), respectively.

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2 PRELIMINARIES

In this section, we introduce the background knowledge and notations used in this paper.

189 190 191 192 Machine Learning Models. We consider a machine learning model as a black-box function f that maps an input vector x to an output scalar $f(x)$. Formally, we let $f : \mathbb{X} \to \mathbb{R}$, where X is the input domain. For models that take fixed-dimension inputs, let $\mathbb{X} = \mathbb{R}^n$. For models capable of handling inputs of arbitrary dimensions, let $\mathbb{X} = \bigcup_{i=1}^{\infty} \mathbb{R}^i$. Let x_i denote the *i*-th feature value of x.

193 194 195 196 Local Model-Agnostic Explanation Techniques. A local model-agnostic explanation technique t takes a model f and an input x, and generates a local explanation $g_{f,x}$ to describe the behavior of f around x, i.e., $g_{f,x} := t(f,x)$. $g_{f,x}$ (g for short) is an expression formed with **predicates**. Each predicate p maps an input x to a binary value, i.e., $p : \mathbb{X} \to \{0, 1\}$, indicating whether x satisfies a specific condition.

199 200 As shown in Figure [4,](#page-4-0) existing local model-agnostic explanation techniques generate explanations following a similar workflow:

- 1. Producing Predicates: These techniques first generate a set of predicates $\mathbb P$ based on the input x .
- 2. Generating Samples: The underlying perturbation model t_{per} generates a set of samples \mathbb{X}_s^b in **predicate representations**, where each sample $\boldsymbol{z}^b \in \mathbb{X}_s^b$ is a binary vector in $\{0,1\}^d$ and z_i^b indicates whether the sample satisfies the *i*-th predicate in \mathbb{P} . The perturbation model then transforms the samples \mathbb{X}_s^b back to the original input space to get \mathbb{X}_s and $f(\mathbb{X}_s)$.
- 3. Learning Explanation: The underlying learning algorithm generates the local explanation $q_{f,x}$ consisting of predicates in P using X_s and $f(X_s)$.

210 211 212 213 Mainstream local model-agnostic explanation techniques like Anchors, LIME, LORE, and Kernel SHAP, all follow this workflow. They use the same kinds of predicate sets and perturbation models, and use different learning algorithms to generate explanations with different properties. In the following, we introduce the main components of the explanation techniques.

214 215 Predicate Sets. Given an input x , the corresponding predicate set $\mathbb P$ is defined as follows:

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\mathbb{P} = \{p_i | i \in [1, d]\},\
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Figure 4: The workflow of generating explanations by a local model-agnostic explanation technique.

233 234 235 236 237 238 239 240 where d is the number of predicates in \mathbb{P} , a hyperparameter set by users or according to the input data x. Each p_i is a **feature predicate** that constrains the value of a set of feature values in x, i.e. $p_i(z): \bigwedge_{j \in \mathbb{A}_i} 1_{\text{ran}(\boldsymbol{x},j)}(z_j)$, where \mathbb{A}_i is the set of indices of features that p_i constrains. Specifically, $\{A_1, A_2, ..., A_d\}$ forms a partition of $\{1, 2, ..., |x|\}$. Each $ran(x, j)$ is a set containing x_j , which is set according to the type of input data. For example, we can use ran $(x, j) = (x_i - \epsilon, x_j + \epsilon)$ for continuous values, and $\text{ran}(x, j) = \{x_j\}$ for categorical values. The predicate p_i is a conjunction of indicator functions, each of which checks if a sample z has a similar value to x_j (i.e., $z_j \in$ ran (\boldsymbol{x}, j)).

241 242 243 Predicate Representations. The predicate representation $z^b \in \{0,1\}^d$ of a sample z is a binary vector where $\mathbf{z}_i^b = p_i(\mathbf{z})$.

244 245 246 247 248 249 Perturbation Models. The perturbation model t_{per} first randomly selects $\mathbb{X}_s^b \subseteq \{0,1\}^d$ as the predicate representations of the samples. Then, it transforms \mathbb{X}_{s}^{b} back to the original input space to get \mathbb{X}_s . For each $z^b \in \mathbb{X}_s^b$, a predicate-to-feature mapping function $t_{p2f}: \{0,1\}^d \to \mathbb{X}$ transforms z^b to z as follows: if $z_i^b = 1$, then for each $j \in \mathbb{A}_i$, set $z_j = x_j$; otherwise, set each z_j to a masked value, or a random value sampled from $per(x, j)\ran(x, j)$, where $per(x, j)$ is a perturbation range with $per(\mathbf{x}, j) \supset \text{ran}(\mathbf{x}, j)$.

250 251 252 253 254 255 256 257 258 259 Learning Algorithms and Explanations. The learning algorithm learns an understandable expression g as an explanation. In Anchors, g is a conjunction of predicates that provides a sufficient condition for producing $f(x)$ as output, i.e., $f(z) = f(x)$ if $g(z) = 1$, and $g(z) = \bigwedge_{p \in \mathbb{Q}} p(z)$, where $\mathbb Q$ is selected by KL-LUCB algorithm [\(Kaufmann & Kalyanakrishnan, 2013\)](#page-11-10). In LIME and Kernel SHAP, $g(z) = \sum_{i=1}^{d} w_i p_i(z) + w_0$, where w_i is the weight of p_i , which is learned by their underlying regression algorithms. LORE first learns a decision tree with building systems like Yadt [\(Ruggieri, 2004\)](#page-12-5), then extracts a sufficient condition to obtain $f(x)$ and some counterfactual rules from the tree as explanations. The sufficient condition is similar to Anchors, while each of the counterfactual rules is in the form of $f(z) = y$ if $g(z) = 1$, where $y \neq f(x)$ and $g(z) = \bigwedge_{p \in \mathbb{Q}} p(z) \wedge \bigwedge_{p \in \mathbb{C}} \neg p(z)$, and $\mathbb Q$ and $\mathbb C$ are extracted from the decision tree.

260 261 262 263 264 265 266 267 An Example. For a text input *I love this movie so much*, these techniques can let each p_i constrains only one feature, and produce six predicates in the form of $p_i(z) := \mathbf{1}_{z_i = x_i}$. For another text input $z = I$ love this [MASK] so [MASK], the predicate representation of z is $p_1(z)$ $p_2(z)$ $p_3(z)$ $p_4(z)$ $p_5(z)$ $p_6(z) = 1 1 1 0 1 0$. The perturbation model will generate samples in predicate representation, then t_{p2f} will transform samples back to the origin input space. For example, a sample $0 \ 1 \ 0 \ 1 \ 1 \ 1$ is generated and t_{p2f} maps it to *[MASK] love [MASK] movie so much*. Consequently, these techniques will use the output of these samples and the samples' predicate presentation to learn an expression, and build the explanation with the predicates.

268 269 Limited by the predicate sets and perturbation models, existing local model-agnostic explanation techniques can only generate explanations based on the constraints of feature values, which limits their effectiveness in explaining the behavior of the model.

270 271 3 THE CONLUX FRAMEWORK

272 273 274 275 In this section, we propose ConLUX, a general framework to provide concept-based local explanations based on existing local model-agnostic explanation techniques without significantly changing their core components.

276 277 278 We introduce ConLUX in three steps: 1) defining concept-based local explanations and concept predicates, 2) showing the modifications to the explanation techniques, and 3) demonstrating the augmented workflow.

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- 3.1 CONCEPT-BASED LOCAL EXPLANATIONS

281 282 283 284 As we discussed in Section [2,](#page-3-0) though the form of the explanations varies, they are all built from predicates in P. Elevating the predicates to concept level is the key to providing concept-based explanations.

285 286 287 Definition of high-level concepts varies, as [Molnar](#page-12-6) [\(2020\)](#page-12-6) mentions, "A concept can be any abstraction, such as a color, an object, or even an idea." Here, to provide explanations that are easier to understand by end-users, we define a concept predicate as follows:

Definition 1 (Concept Predicate). *Given an input x, a concept predicate* p^c *is a function that maps* x to a binary value, i.e., $p^c : \mathbb{X} \to \{0,1\}$, and satisfies the following properties:

- 1. **Descriptive**: The concept predicate p^c can be concisely and intuitively described in natural *language.*
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2. **Human Evaluable**: The truth of $p^c(x)$ can be readily assessed by a human user.

The preceding two properties ensure that the concepts are easy to understand. Here, we provide two examples of concept predicates for text and image models in the following:

- Examples. For text models, we can define a concept predicate as follows:
	- Concept Name: Poor Visual Effects and Cinematography
	- Description: The input text mentioned that the visual effects and cinematography are lacking, failing to create an appealing aesthetic.

305 306 307 For image models, we use objects in an image to define a concept predicate. As shown in Figure [2,](#page-2-0) we can easily describe the concept predicate as "there is a punching bag in the image", "there is a kid in the image", etc.

308 We then define a concept-based local explanation as follows:

309 310 Definition 2 (Concept-Based Local Explanation). A concept-based local explanation $g_{f,x}^c$ is an *expression formed with concept predicates to describe the behavior of* f *around* x*.*

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312 313 314 315 316 317 As existing local explanation model-agnostic techniques provide various kinds of explanations like attributions, sufficient conditions, and counterfactuals, ConLUX can elevate all these explanations to concept level and provide users a unified interface to obtain various kinds of explanations with a single click. Additionally, We denote such a set of various kinds of explanations as a ConLUX unified explanation, which provides higher fidelity and offers a more comprehensive view than a single form of explanation.

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319 320 3.2 AUGMENTING EXPLANATION TECHNIQUES

321 322 323 As shown in Figure [4,](#page-4-0) to produce concept predicates, we should first extract high-level concepts based on the input x ; to provide explanations at concept level, we should replace the feature predicates in P with concept predicates; to capture the local behavior of the target model at concept level, we should extend the perturbation model to generate samples by changing high-level concepts.

324 325 326 327 328 Producing Concept Predicates. We use large pre-trained models to provide high-level concepts based on the input x and the target task. For text models, following the approach of [Ludan et al.](#page-11-3) [\(2023\)](#page-11-3), we provide GPT-3.5 with task-specific information, the given input, the corresponding output, and several in-context learning examples to generate candidate concepts. These concepts are then evaluated on the input x to construct the concept predicate set.

329 330 For image models, we refer to [Sun et al.](#page-12-3) [\(2023\)](#page-12-3) to use SAM to detect objects in the image.

331 332 Consequently, ConLUX defines concept predicates (denoted as p^c) using the extracted concepts, and replaces the feature predicates set $\mathbb P$ with the concept predicates set $\mathbb P^c$.

- **334 335 336 337 338 339 340 341 Performing Concept-Level Perturbation** The extended perturbation model t_{per}^c generates samples in concept-level representation and $t_{p2f}^c : \{0,1\}^{|p^c|} \to \mathbb{X}$ transforms the samples back to the original input space. Different from the t_{per} simply decides whether to mask a feature value, t_{per}^c changes high-level concepts at feature level, which is more complex. Therefore, t_{per}^c is usually a more sophisticated model. Here, for text models, we use Llama 3.1 to perform the concept-feature mapping; for image models, since each object is still a set of pixels, we can use the same transformation as t_{per} . As the effectiveness and faithfulness of the text perturbation are not straightforward, we conduct an experiment to demonstrate this, as detailed in Appendix [C.](#page-16-0)
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3.3 CONLUX-AUGMENTED WORKFLOW

345 346 347 348 349 The ConLUX augments the workflow in Figure [4](#page-4-0) as follows: it first extracts high-level concepts based on the input x and the target task, then follows a similar workflow as their vanilla versions, but replaces the predicate set $\mathbb P$ with $\mathbb P^c$ and the perturbation model t_{per} with t_{per}^c . Therefore, the ConLUX-augmented techniques can capture the local behavior of the target model at the concept level, and provide concept-based local explanations.

350 More details about the implementation of ConLUX can be found in Appendix [A.](#page-14-0)

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4 EMPIRICAL EVALUATION

355 356 357 358 359 360 361 362 363 In this section, we demonstrate the generality of ConLUX, its improvement of explanation fidelity, and the fidelity of ConLUX unified explanations by empirical evaluation. We show the generality of ConLUX by applying it to four mainstream local model-agnostic explanation techniques: Anchors, LIME, LORE, and Kernel SHAP (KSHAP for short), which provide three types of explanations: sufficient conditions, counterfactuals, and attributions. We apply them to explain various text and image models. We show the improvement of explanation fidelity by comparing the vanilla feature-level explanations with ConLUX-augmented the concept-based explanations. Moreover, we compare the fidelity of ConLUX unified explanations with two state-of-the-art concept-based explanation techniques: Textual Bottleneck Model (TBM) [\(Ludan et al., 2023\)](#page-11-3) for text models and Explain Any Concept (EAC) [\(Sun et al., 2023\)](#page-12-3) for image models.

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4.1 EXPERIMENTAL SETUP

367 368 We chose sentiment analysis as the target task for text models, and image classification as the target task for image models.

370 371 372 373 374 375 376 377 Sentiment Analysis. Sentiment analysis models take a text sequence as input and predict if the text is positive or negative, i.e. $f : \mathbb{X} \to \{0,1\}$, where $\mathbb{X} := \bigcup_{i=1}^{\infty} \mathbb{W}^i$ is the input domain, and W is the vocabulary set. We used a pre-trained BERT [\(Morris et al., 2020\)](#page-12-7) and Llama3.1 to predict the sentiment of 200 movie reviews from the Large Movie Review Dataset [\(Maas et al., 2011\)](#page-11-11), and explained the local behavior of the models around each input text. For vanilla techniques, we followed the settings described in Section [2.](#page-3-0) For ConLUX-augmented techniques, we set the number of concept predicates to 10, used GPT-3.5 [\(Brown et al., 2020\)](#page-10-9) to extract high-level concepts, and Llama3.1 to perform the predicate-to-feature mapping. For TBM, we applied it to explain the same 200 movie reviews with its default settings.

378 379 380 381 382 383 384 385 386 387 Image Classification. Image classification models take an image as input and predict the category of the image, i.e. $f : \mathbb{X} \to \{0, 1, ..., m\}$, where m is the number of categories, $\mathbb{X} := \mathbb{R}^{3 \times h \times w}$ is the input domain, with h and w being the height and width of the image. We used a pre-trained YOLOv8, Vision Transformer (ViT) [\(Oquab et al., 2023;](#page-12-4) [Darcet et al., 2023\)](#page-10-8), and ResNet-50 [\(He](#page-11-9) [et al., 2016\)](#page-11-9) to predict the category of 1000 images from the ImageNet dataset [\(Deng et al., 2009\)](#page-10-6), and explained the local behavior of the models around each input image. For vanilla techniques, we followed LIME to use Quickshift algorithm [\(Jiang et al., 2018\)](#page-11-12) to obtain the superpixels, and used these super-pixels as predicates. For ConLUX-augmented techniques, we used SAM [\(Kirillov et al.,](#page-11-6) [2023\)](#page-11-6) to detect objects in the images, and used these objects as predicates. For EAC, we applied it to explain the same 1000 images with its default settings.

388 389 390 391 To evaluate the fidelity of ConLUX unified explanations, as the combination of multiple forms of explanation provides more fidelity than a single form, we used the combination ConLUX-augmented KSHAP and LORE explanations as local surrogate models. Specifically, if an input is covered by LORE's rule, we use the LORE output; otherwise, we use the KSHAP explanation.

- **392** More details can be referred to Appendix [B.](#page-15-0)
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- **395** 4.2 FIDELITY EVALUATION

396 397 4.2.1 EVALUATION METRICS

398 399 400 Fidelity reflects how faithfully the explanations describe the target model. As these techniques provide explanations in different forms, we used different metrics to evaluate their fidelity.

401 402 403 404 405 406 407 408 Following the setup in the original papers of Anchors and LORE, we used coverage and precision as fidelity metrics (which are named differently in the LORE paper). Given a target model f, an input x, and a distribution D_x derived from the perturbation model, and the corresponding explanation g, we defined the coverage as $cov(x; f, g) = \mathbb{E}_{z \sim D_x}[g(z)]$, which indicates the proportion of inputs in the distribution that match the rule; we defined the precision as $\text{prec}(x; f, g) = \mathbb{E}_{z \sim D_x}[\mathbf{1}_{f(z)=y} | g(z)]$, where y is the consequence of the rules in g with $y = f(x)$ for factual rules and $y \neq f(x)$ for counterfactual rules. Precision indicates the proportion of covered inputs that g correctly predicts the model outputs.

409 410 411 412 413 414 As LIME and KSHAP are attribution-based local surrogate, we used *Area Over most relevant first perturbation curve* (AOPC) [\(Samek et al., 2016;](#page-12-8) [Modarressi et al., 2023\)](#page-12-9), and accuracy_a as fidelity metrics [\(Balagopalan et al., 2022;](#page-10-10) [Yeh et al., 2019a;](#page-13-7) [Ismail et al., 2021\)](#page-11-13). Given a target model f, an input x, its corresponding model output $y = f(x)$, their corresponding explanation g, and $x^{(k)}$ that is generated by masking the $k\%$ most important predicates in x, AOPC and accuracy_a are defined as follows:

- **415 416 417 418** • **AOPC:** Let $\text{AOPC}_k = \frac{1}{|\mathbb{T}|} \sum_{x}^{\mathbb{T}} p_f(y|x) - p_f(y|x^{(k)})$, where $p_f(y|x)$ is the probability of f to output y given the input x, and $\mathbb T$ is the set of all test inputs. AOPC_k indicates the average change of the model output when masking the $k\%$ most important predicates. A higher $AOPC_k$ indicates a better explanation. We calculate the AOPC curve by varying k from 0 to 100.
- **419 420 421** • Accuracy_a: Accuracy_a indicates the proportion of inputs among all $x^{(k)}$ that the target model gives the same output as the original input x, i.e. $\mathbb{E}(f(\mathbf{x}^{(k)}) = f(\mathbf{x}))$. Specifically, accuracy_a is different from the standard accuracy, and a lower accuracy^a indicates a better explanation.
- **422 423 424** Specifically, we only considered the predicates that positively contribute to $f(x)$, and we did not use AOPC when explaining Llama 3.1, as it does not directly provide the probability for each output token.

425 426 427 428 429 430 431 For TBM, EAC, and ConLUX unified explanations, considering that they can all serve as local surrogate models, i.e. $g : \mathbb{X} \to \mathbb{R}$, we defined the metrics as follows: Given a target model f, an input x, a perturbation distribution \mathbb{D}_x , and their corresponding explanation g, a performance metric L (e.g. accuracy, F1 score, MSE, etc.), we define the (in-)fidelity as $E_{z\sim\mathbb{D}_p}L(f(z), g(z))$, which indicates the performance of using q to approximate f . Here, we used the accuracy as the performance metric. Specifically, considering the complexity of the original task, we reduced the image classification task for local surrogates to predicting whether the target model f assigns the same classification to x' as it does to x.

Figure 5: AOPC upon masking the K% most important predicates. We use LIME, Kernel SHAP, and their ConLUX-augmented version to explain YOLOv8, ViT, and Resnet-50 on the image classification task and BERT on the sentiment analysis task.

Table 1: Average coverage and precision (higher are better) of Anchors, LORE, and their ConLUXaugmented versions (denoted as Anchors* and LORE*) on two sentiment analysis models and three image classification models.

Models	Coverage $(\%)$ \uparrow				Precision $(\%)$ \uparrow			
	Anchors	Anchors $*$	LORE	$LORE*$	Anchors	Anchors $*$	LORE	$LORE*$
Llama 3.1	4.9	22.5	2.3	21.3	81.2	94.2	64.3	76.9
BERT	5.3	24.4	3.2	20.3	78.2	91.0	65.3	79.4
YOLOv8	28.6	30.9	20.8	24.8	84.3	98.2	87.8	92.2
ViT	24.6	28.2	21.3	23.8	88.7	98.2	89.6	95.6
ResNet-50	28.0	30.5	20.1	29.7	89.3	99.4	85.8	92.6

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4.2.2 EVALUATION RESULTS

465 466 467 468 469 470 471 472 473 Table [1](#page-8-0) shows the fidelity of Anchors, LORE, and their ConLUX-augmented versions. ConLUX improves the average coverage of Anchors and LORE by 9.0% and 10.4%, and the average precision by 11.9% and 8.7%, respectively. Figure [5](#page-8-1) and Table [2](#page-9-0) show the fidelity of LIME, KSHAP, and their ConLUX-augmented versions. Figure [5](#page-8-1) shows the AOPC curve of LIME and KSHAP. Each AOPC curve of ConLUX-augmented versions is higher than the vanilla counterpart. Table [2](#page-9-0) shows the average AOPC and accuracya. ConLUX improves the average AOPC by 0.122 and 0.145, and decreases the average α cur α _N by 21.6% and 22.8%, for LIME and KSHAP, respectively. We do paired t-tests for each setup that only differs on whether to apply ConLUX, to show the statistical significance of the improvement. The p-value is all less than 0.01, which indicates with over 99% confidence the improvement is significant.

474 475 476 477 We also compared ConLUX unified explanations with two state-of-the-art concept-based taskspecific explanation techniques: TBM for text tasks and EAC for image tasks. Table [3](#page-9-1) shows the fidelity of TBM, EAC, and ConLUX unified explanations. ConLUX helps two classic local model-agnostic techniques to achieve 5.75% and 4.9% more accuracy than TBM and EAC.

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5 RELATED WORK

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482 483 Our work is related to model-agnostic explanation techniques and concept-based explanation techniques.

484 485 Model-agnostic explanation techniques consider target models as black boxes and provide explanations without requiring any knowledge of the model's internal structure. Existing Model-agnostic explanation techniques provide different types of explanations, such as feature importance [\(Lund-](#page-11-0)

Table 3: Average accuracy (higher accuracy is better) of TBM, EAC, and ConLUX unified explanations on two sentiment analysis models and three image classification models.

Methods	Accuracy $(\%)$ \uparrow							
	Llama 3.1		BERT YOLOv8 ViT		ResNet-50			
TBM	89.6	81.4						
EAC			56.6	53.4	57.7			
ConLUX	94.7	87.8	61.3	59.6	61.5			

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507 508 509 510 511 512 513 514 [berg & Lee, 2017;](#page-11-0) [Ribeiro et al., 2016;](#page-12-1) [Tan et al., 2023;](#page-12-10) [Shankaranarayana & Runje, 2019\)](#page-12-11), decision rules [\(Ribeiro et al., 2018;](#page-12-2) [Guidotti et al., 2018;](#page-11-1) [Dhurandhar et al., 2018\)](#page-10-11), counterfactuals [\(Wachter](#page-12-12) [et al., 2018;](#page-12-12) [Guidotti et al., 2018\)](#page-11-1), and visualizations [\(Goldstein et al., 2015;](#page-11-14) [Friedman, 2001;](#page-10-12) [Ap](#page-10-13)[ley & Zhu, 2020\)](#page-10-13). However, to our knowledge, all existing model-agnostic explanation techniques provide explanations at feature levels [\(Zhang et al., 2021c\)](#page-13-5). Basic feature-based explanations are usually worse in aligning with either the decision-making process of the model or end-users [\(Ghor](#page-11-7)[bani et al., 2019a;](#page-11-7) [Sun et al., 2023;](#page-12-3) [Kim et al., 2018\)](#page-11-8), which makes these explanations unfaithful and hard to understand.

515 516 517 518 519 520 521 522 523 524 525 526 527 Concept-based explanation techniques provide explanations in terms of high-level concepts, which align with the decision-making process of the model better and are more interpretable to end-users. To our knowledge, existing concept-based explanation techniques are all model-specific or taskspecific [\(Poeta et al., 2023b\)](#page-12-13). We categorize them into three groups: (1) techniques that extract concepts from the model's internal structure [\(Zhang et al., 2021b;](#page-13-1) [Yeh et al., 2020;](#page-13-2) [2019b;](#page-13-3) [Cun](#page-10-2)[ningham et al., 2023;](#page-10-2) [Ghorbani et al., 2019b;](#page-11-2) Crabbé & van der Schaar, 2022; [Fel et al., 2023\)](#page-10-4), which are limited to specific types of models, (2) techniques that use external knowledge to define concepts [\(El Shawi, 2024;](#page-10-5) [Widmer et al., 2022\)](#page-13-4), which are limited to specific types of tasks since their methods based on the knowledge for a specific task, and (3) techniques that use pre-trained models to extract concepts [\(Ludan et al., 2023;](#page-11-3) [Sun et al., 2023\)](#page-12-3). [Ludan et al.](#page-11-3) [\(2023\)](#page-11-3) propose TBM, which is a surrogate model specifically designed for text data, while [Sun et al.](#page-12-3) [\(2023\)](#page-12-3) propose EAC, which also utilizes internal information of the target model. Therefore, these techniques are only for specific types of tasks. In addition, these techniques mainly focus only on attributions which limits their use cases [\(Poeta et al., 2023b\)](#page-12-13).

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6 CONCLUSION

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532 533 534 535 536 537 538 539 We have proposed ConLUX, a general framework that automatically extracts high-level concepts and incorporates them into existing local model-agnostic explanation techniques to provide conceptbased explanations, which are more faithful and easier to understand by end-users. ConLUX offers unified explanations that combine attributions, sufficient conditions, and counterfactuals. This satisfies diverse user needs and fills the current gap in concept-based explanations, which lack forms beyond attributions. ConLUX achieves this by utilizing large pre-trained models to extract highlevel concepts, elevating language components from feature level to concept level, and extending perturbation models to sample in the concept space. We have instantiated ConLUX on Anchors, LIME, LORE, and Kernel SHAP, and provide unified explanations. We have constructed empirical evaluations to demonstrate the effectiveness of ConLUX.

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Then we use the Response Guides to produce local concepts.

810 811 A.2 CONCEPT-FEATURE MAPPING

B EXPERIMENT SETTINGS (CONTINUED)

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859 860 861 862 We experimented on two machines, one with an Intel i9-13900K CPU, 128 GiB RAM, and RTX 4090 GPU, and another with Intel(R) Xeon(R) Silver 4314 CPU, 256GiB RAM, and 4 RTX 4090 GPUs.

863 To measure the fidelity improvement brought by ConLUX, we keep all hyperparameters the same for both vanilla and augmented methods.

 For LIME and KSHAP, we set the number of sampled inputs to 1000 except for explaining Llama 3.1. For Anchors, we follow the default settings. For LORE, we set $ngen = 5$. For the LLama3.1 model, when applying it to the sentiment analysis task, we simply use the following prompt: From now on, you should act as a sentiment analysis neural network. You should classify the sentiment of a sentence into positive or negative. If the sentence is positive, you should reply 1. Otherwise, if it's negative, you should reply 0. There may be some words that are masked in the sentence, which are represented by \langle UNK \rangle . The input sentence may be empty, which is represented by \langle EMPTY \rangle . You will be given the sentences to be classified, and you should reply with the sentiment of the sentence by 1 or 0. There are two examples: Sentence: I am good Sentiment: Sentence: The movie is bad. Sentiment: Ω You must follow this format. Then I'll give you the sentence. Remember Your reply should be only 1 or 0. Do not contain any other content in your response. The input sentence may be empty. Sentence: {The given sentence} Sentiment:

C TEXT PERTURBATION FAITHFULNESS EXPERIMENT

 As demonstrated by [Ludan et al.](#page-11-3) [\(2023\)](#page-11-3), large language models (LLMs) can verify whether an instance satisfies a given concept. Building on this, we conduct an experiment to evaluate the consistency of LLM-based perturbations. Specifically, we use LLMs to assess whether the applied perturbations successfully alter the intended concept. For each sentence, we generate 100 random perturbations and verify if the concepts in the generated sentences align with the expected changes. Our results indicate that Llama3.1, the large model employed in our fidelity experiments, achieves concept-level perturbation accuracy exceeding 99

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