Mixture of Cluster-Conditional LoRA Experts for Vision-Language Instruction Tuning

Anonymous EMNLP submission

Abstract

 Instruction tuning of Large Vision-language Models (LVLMs) has revolutionized the devel- opment of versatile models with zero-shot gen- eralization across a wide range of downstream vision-language tasks. However, the diversity of training tasks of different sources and for- mats would lead to inevitable task conflicts, where different tasks conflict for the same set of model parameters, resulting in sub-optimal instruction-following abilities. To address that, we propose the Mixture of Cluster-conditional LoRA Experts (MoCLE), a novel Mixture of Experts (MoE) architecture designed to activate the task-customized model parameters based on the instruction clusters. A separate univer-016 sal expert is further incorporated to improve generalization capabilities of MoCLE for novel instructions. Extensive experiments on Instruct-**BLIP** and **LLaVA** demonstrate the effectiveness of MoCLE.

⁰²¹ 1 Introduction

 There has been a continuously increasing trend to develop intelligent assistants that can follow human instructions [\(Brown et al.,](#page-8-0) [2020;](#page-8-0) [OpenAI,](#page-9-0) [2022;](#page-9-0) [Chen et al.,](#page-8-1) [2023b\)](#page-8-1), with instruction tuning emerging as a notably effective approach. This method leverages large-scale well-formatted in- struction data to empower Large Language Mod- els (LLMs) to execute various human instructions, showcasing their ability to generalize across novel unseen tasks [\(Longpre et al.,](#page-9-1) [2023\)](#page-9-1). Likewise, ef- forts have been made to introduce similar capabil- ities to Large Vision-language Models (LVLMs) [\(Bai et al.,](#page-8-2) [2023;](#page-8-2) [Zhang et al.,](#page-10-0) [2023;](#page-10-0) [Ye et al.,](#page-10-1) [2023;](#page-10-1) [Chen et al.,](#page-8-3) [2023c,](#page-8-3)[a\)](#page-8-4), including LLaVA series [\(Liu](#page-9-2) [et al.,](#page-9-2) [2023b,](#page-9-2)[a\)](#page-9-3), MiniGPT-4 [\(Zhu et al.,](#page-10-2) [2023\)](#page-10-2) and InstructBLIP [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5).

038 It is observed that for both the LLMs [\(Sanh et al.,](#page-9-4) **039** [2021;](#page-9-4) [Wang et al.,](#page-10-3) [2022;](#page-10-3) [Chung et al.,](#page-8-6) [2022\)](#page-8-6) and **040** [L](#page-9-5)VLMs [\(Bai et al.,](#page-8-2) [2023;](#page-8-2) [Zhao et al.,](#page-10-4) [2023;](#page-10-4) [Li](#page-9-5)

Figure 1: Performance of the instruction-finetuned LVLMs on zero-shot tasks, where larger values indicate better performance. Only 2 out of 7 tasks benefit from instruction tuning from all the data, while the task experts show better performance on the other 5 tasks (*i.e*., Flickr 30K, GQA, HM, SciQA and IconQA).

[et al.,](#page-9-5) [2023b\)](#page-9-5), the ability to generalize to novel **041** unseen instructions necessitates multi-task instruc- **042** tion tuning, *i.e*., training on a diverse collection of **043** instruction-following tasks. However, the complex- **044** ity of various instruction tasks brings difficulties for **045** model fine-tuning. Specifically, [Wei et al.](#page-10-5) [\(2021\)](#page-10-5) **046** find that for certain model sizes, multi-task instruc- **047** tion tuning even fails to bring performance gains **048** for zero-shot tasks compared to the original models. **049** This is mainly attributed to the *negative transfer* **050** phenomenon [\(Zhang and Yang,](#page-10-6) [2017\)](#page-10-6) during multi- **051** task instruction tuning, where the model struggles **052** to optimize the losses of multiple conflicted tasks, **053** leading to sub-optimal performance. **054**

Similarly, tasks for vision-language instruction **055** tuning (*e.g*., visual question answering and im- **056** age captioning) focus on different perspectives of **057** LVLMs. This results in conflicts as most stud- **058** ies adopt sharing of all parameters. In our pre- **059** liminary study, we split the instruction data into **060** two *disjoint* subsets (*"cap"* for image captioning, **061** and *"vqa"* for visual question answering). We **062** then train InstructBLIP [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5) using **063**

 LoRA [\(Hu et al.,](#page-8-7) [2021\)](#page-8-7) on three data sets (*"cap"*, *"vqa"* and the full data *"full"*) to obtain three sets of parameters (*i.e*., task experts). Following the held-out evaluation protocol [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5), we evaluate these experts on the unseen datasets/tasks with the best expert. As shown in Figure [1,](#page-0-0) on 5 out of the 7 downstream tasks, the InstructBLIP instruction-tuned on all the data is outperformed by the task expert finetuned with only a subset of data. Among the 5 tasks, Flickr30k belongs to *"cap"*, and SciQA, GQA and IconQA belong to *"vqa"*. This shows that *instruction tuning on similar tasks brings positive transfer to downstream tasks, while training on the full data with dissimilar tasks can hurt generalization performance*.

079 The use of disjoint task experts above is a naïve solution to negative transfer, where we manually partition the training tasks and train each expert separately. However, it has several limitations: (1) The taxonomies such as *"vqa"* and *"cap"* require human expertise, and are difficult to scale as the number of tasks grows. (2) The ability to gener- alize to unseen tasks is inhibited, as we do not know which expert to choose for novel tasks, while some new tasks might benefit from multiple train- ing tasks (*e.g*., VSR and TextVQA as in Figure [1\)](#page-0-0). In this regard, specialization and generalization of LVLMs becomes a dilemma.

 This paper aims to develop an automatic and practical partition strategy and a network architec- ture that strikes a balance between specialization and generalization. In particular, we propose the *Mixture of Cluster-conditional LoRA Experts* (Mo- CLE) for vision-language instruction tuning. In this proposed framework, we first cluster instruc- tions of all the training data into several clusters via a pre-trained clustering model. In this way, similar tasks that can bring positive transfer to each other are automatically grouped into the same cluster, while different tasks that may cause conflict are separated (more justifications for the use of instruc- tion clusters are detailed in Sec. [3.2\)](#page-2-0). Then we construct several task experts, with each focusing on a specific cluster. Using the cluster as condi- tion, a router dispatches the input data to one of the specialized task experts and an universal expert that is shared among all data. As we activate a spe- cialized expert for a group of similar tasks, tasks that are less similar are learned via separate experts, mitigating task conflicts. Meanwhile, since the uni- versal expert trained on all tasks also contributes to the model outputs, we can enjoy generalization and specialization simultaneously. 116

We validate effectiveness of MoCLE on Instruct- **117** BLIP [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5) and LLaVA-1.5 [\(Liu et al.,](#page-9-3) **118** [2023a\)](#page-9-3) and observe remarkable performance gains **119** compared to dense models and other MoE base- **120** lines[\(Chen et al.,](#page-8-8) [2023d,](#page-8-8) [2024\)](#page-8-9). **121**

The main contributions of this work contain the **122** following three parts, **123**

- 1. We identify the negative transfer phenomenon **124** [\(Liu et al.,](#page-9-6) [2022b;](#page-9-6) [Zhili et al.,](#page-10-7) [2023\)](#page-10-7) as tasks **125** conflict during instruction tuning of LVLMs. **126**
- 2. We propose *Mixture of Cluster-conditional* **127** *LoRA Experts* (MoCLE), a novel parameter- **128** efficient finetuning framework suitable for the **129** vision-language instruction tuning, to mitigate **130** task conflicts and enjoy the benefits of huge **131** data training simultaneously. **132**
- 3. Our proposed MoCLE achieves remarkable **133** performance gains on held-in/out tasks com- **134** pared to dense models and other MoE base- **135** lines[\(Chen et al.,](#page-8-8) [2023d,](#page-8-8) [2024\)](#page-8-9). **136**

2 Related Work **¹³⁷**

2.1 Multi-Task Instruction Tuning **138**

Instruction tuning [\(Sanh et al.,](#page-9-4) [2021;](#page-9-4) [Wei et al.,](#page-10-5) **139** [2021\)](#page-10-5) fine-tunes a language model across tasks and **140** instruction templates to convey task intentions. Its **141** goal is to teach the model to understand relation- **142** ships between instructions and input/output pairs, 143 enabling generalization to unseen tasks with novel **144** instructions. Increasing the number of instructions **145** [\(Sanh et al.,](#page-9-4) [2021\)](#page-9-4), tasks [\(Wang et al.,](#page-10-3) [2022;](#page-10-3) [Chung](#page-8-6) **146** [et al.,](#page-8-6) [2022\)](#page-8-6), and data diversity [\(Zhou et al.,](#page-10-8) [2023\)](#page-10-8) **147** have shown to be effective in improving perfor- **148** mance. However, [Wei et al.](#page-10-5) [\(2021\)](#page-10-5) find that for **149** certain model sizes, instruction tuning fails to out- **150** perform untuned models on unseen tasks due to full **151** capacity utilization for learning task mixtures. Our **152** work addresses this in vision-language instruction **153** tuning using specialized experts. **154**

2.2 Mixture of Experts (MoE) **155**

[M](#page-8-11)oE models [\(Jacobs et al.,](#page-8-10) [1991;](#page-8-10) [Jordan and Ja-](#page-8-11) **156** [cobs,](#page-8-11) [1993;](#page-8-11) [Shazeer et al.,](#page-10-9) [2017\)](#page-10-9) are renowned for **157** their ability to increase model capacity through pa- **158** rameter expansion. Recent research integrates MoE **159** with adapters, exploring how pretrained adapters **160** can be effectively combined [\(Wu et al.,](#page-10-10) [2024b\)](#page-10-10), and **161** how they enhance performance in both few-shot **162**

Figure 2: Overall pipeline of MoCLE.

 [\(Huang et al.,](#page-8-12) [2023\)](#page-8-12) and zero-shot scenarios [\(Jang](#page-8-13) [et al.,](#page-8-13) [2023;](#page-8-13) [Muqeeth et al.,](#page-9-7) [2024\)](#page-9-7). Another line of research [\(Chen et al.,](#page-8-9) [2024;](#page-8-9) [Wu et al.,](#page-10-11) [2024a;](#page-10-11) [Luo et al.,](#page-9-8) [2024;](#page-9-8) [Zadouri et al.,](#page-10-12) [2023;](#page-10-12) [Chen et al.,](#page-8-8) [2023d\)](#page-8-8) focuses on augmenting model capacity in a parameter-efficient manner. However, these ap- proaches do not explicitly incorporate task/domain priors during the routing process, which might be limited when handling task conflicts. Two con- current studies [\(Liu et al.,](#page-9-9) [2024;](#page-9-9) [Li et al.,](#page-9-10) [2024\)](#page-9-10) incorporate domain information for expert routing. Unlike our approach, however, they do not address zero-shot generalization to unseen tasks.

¹⁷⁶ 3 Methodology

 In this section, we start with the formulation of LVLM instruction tuning and an analysis of the limitations of task experts. We then introduce the proposed MoCLE. The overall framework is shown in Figure [2.](#page-2-1)

182 3.1 Problem Formulation

 Suppose that there is a set of datasets that are di- vided into held-in and held-out datasets [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5). A large vision-language model is first fine- tuned on the held-in dataset, and then evaluated on the held-out dataset in a zero-shot manner. To unify and diversify input-output formats and promotes 189 instruction tuning, several task templates ${T_i}$ are designed to wrap the raw inputs, which is a pair 191 of text X_{txt} and image X_{img} from the dataset. For example, "*Given the image, answer the question with no more than three words.* {Question}" is a template for visual question answering tasks. The **instruction is defined as** $I \equiv T_i(X_{\text{txt}})$ that wraps text inputs using the template.

3.2 Clustering Data by Instructions **197**

The purposes of partitioning the training data are **198** two-fold. First, we hope to train a task expert with **199** a collection of similar tasks so as to avoid task **200** conflicts. Second, we expect novel tasks to be **201** automatically assigned to the proper experts based **202** on their cluster without manual intervention. **203**

To achieve these goals, we conduct clustering on **204** the instructions as they serve as the foundation for **205** identifying different tasks. Formally, let $\mathcal{E}(\cdot)$ be a 206 pre-trained sentence encoder, and $\mathbf{e}_i = \mathcal{E}(I_i)$ be the 207 sentence representation of an instruction I_i . We use 208 the k-means clustering algorithm to group all in- **209** structions in the training datasets into K clusters by 210 iteratively minimizing $\sum_{j=1}^{K} \sum_{\mathbf{e}_i \in S_j} ||\mathbf{e}_i - \mathbf{c}_j||^2$ where S_j is the set of instructions assigned to the 212 jth cluster, and c_j is the centroid of the jth clus- **213** ter. In each k-means clustering iteration, each in- **214** struction is assigned to the nearest centroid with **215** all centroids updated as the average of instruction **216** representations in the corresponding cluster. **217**

, **211**

3.3 Mixture of Cluster-Conditional LoRA **218** Experts **219**

In addition to considerations at the data level, we **220** also suggest an architectural design to tackle the is- **221** sue of negative transfer. We propose the Mixture of **222** Cluster-conditional LoRA Experts (MoCLE) that **223** learns to activate the LoRA expert at each layer **224** given the cluster of the data. Specifically, let E **225** as be the number of experts. We introduce a gate **226** vector $\mathbf{G} \in \mathbb{R}^E$. Given an input \mathbf{x}_i , **G** determines 227 the experts to which the input is routed. The gate **228** vector is obtained as: **229**

$$
\mathbf{G} = \text{top}_k \left(\text{softmax} \left(\frac{1}{\tau} \left(\mathbf{W}_{\text{gate}} \mathbf{C}_{[\mathbf{x}_i]} + \boldsymbol{\epsilon} \right) \right) \right), \tag{1}
$$

231 where $\text{top}_k(\cdot)$ keeps the k largest entries unchanged 232 and sets the others to zero. $C_{[x]}$, which is shared among all layers, is the learnable embedding of the cluster that x belongs to. This is the key for the model to choose proper task experts for the input data. To endow the clustering embedding with task information, we initialize it to be the centroid of the corresponding cluster. Moreover, **W**_{gate} is the trainable weights of the linear gate, which is learned at each layer where the MoE block is inserted, $\epsilon \sim N(0, \frac{1}{F})$ 241 is inserted, $\epsilon \sim N(0, \frac{1}{E})$ is a noise term that adds randomness to the expert choosing process (and en- courages MoCLE to explore multiple combinations 244 of experts during training^{[1](#page-3-0)}), and τ is a temperature 245 hyperparameter. The output y_i is then computed as the sum of weighted outputs of the experts, and the original LLM linear layer [\(Hu et al.,](#page-8-7) [2021\)](#page-8-7) on **the input** x_i **, as:**

$$
\mathbf{y}_i = \sum_{e=1}^E G_e \mathbf{W}_e \mathbf{x}_i + \mathbf{W}_0 \mathbf{x}_i, \tag{2}
$$

250 where W_0 is the pre-trained linear layer of LVLM, W^e is the linear projection weight of the eth LoRA expert, and G^e (the eth entry in G) indicates the contribution of the eth expert.

254 3.4 Universal Expert

 As will be shown in Sec. [4.4.1,](#page-5-0) the formulation in Sec. [3.3](#page-2-2) still hurts the generalization ability of the entire model, due to the fact that instruction-tuned models generalize to unseen tasks via training on extensive instructions [\(Wei et al.,](#page-10-5) [2021\)](#page-10-5), while in our formulation, each expert sees fewer instructions than the original dense model.

 To alleviate this problem, we propose an *univer- sal expert* that learns from all training data. Specif- ically, we fix the number of activated experts to 1 265 (*i.e.*, k in Eq. [1](#page-2-3) equals 1) and define G_{max} as the maximum element in G. Then the output for all the experts is expressed as:

$$
\mathbf{y}_{i} = \left(\sum_{e=1}^{E} G_e \mathbf{W}_e + (1 - G_{\text{max}}) \mathbf{W}_u\right) \mathbf{x}_{i} + \mathbf{W}_0 \mathbf{x}_{i}.
$$

(3)

 in which we additionally train an universal expert parameterized by Wu. Different from the task experts that are activated only for specific model in- puts, the universal expert is activated for all inputs. The final output is a weighted sum of outputs from

one of the experts and the universal expert plus the **274** original LVLM's output. Consequently, the task **275** expert learns distinct skills for certain tasks while **276** the universal expert masters holistic understanding **277** of the training corpus. The synergy between them **278** offers both specialization and generalization for the **279** LVLMs with MoCLE. **280**

4 Experiment 281

In this section, we conduct an assessment of Mo- **282** CLE across multiple downstream tasks in a zero- **283** shot setting. We first detail the experimental set- **284** tings and implementation details, which are fol- **285** lowed by a description of the datasets and instruc- **286** tions employed, along with the outcomes of our **287** evaluations. Lastly, we present an ablation study **288** and visualizations of clustering and routing results. **289**

4.1 Implementation Details **290**

We evaluate the effectiveness of MoCLE on two **291** LVLMs: InstructBLIP [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5) and **292** LLaVA-1.5 [\(Liu et al.,](#page-9-3) [2023a\)](#page-9-3). Specifically, we **293** compare the performance between the LVMs with **294** and without MoCLE. The detailed configuration of **295** MoCLE on these LVLMs are presented in Table **296** [1.](#page-4-0) In addition, we encode all the instructions of **297** different datasets using the all-MiniLM-L6-v2 vari- **298** [a](#page-9-11)nt of the Sentence Transformer model [\(Reimers](#page-9-11) **299** [and Gurevych,](#page-9-11) [2019\)](#page-9-11) and cluster their embeddings 300 via k-means clustering algorithm. More training **301** details can be found in Appendix [A.](#page-11-0) **302**

4.2 Settings 303

For InstructBLIP, we follow [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5) for 304 the choice of training datasets. However, these **305** datasets only focus on a single domain: natural **306** images. To validate the effectiveness of MoCLE 307 on multiple domains, for LLaVA-1.5, in addition to **308** its original training data LLaVA-665K [\(Liu et al.,](#page-9-3) **309** [2023a\)](#page-9-3) which focus on natural image domain, we **310** include datasets from multiple domains, *i.e*., geo- **311** metric tasks: Geo170k [\(Gao et al.,](#page-8-14) [2023\)](#page-8-14), medi- **312** cal tasks: VQA-RAD [\(Lau et al.,](#page-9-12) [2018\)](#page-9-12), SLAKE **313** [\(Liu et al.,](#page-9-13) [2021\)](#page-9-13) and PathVQA [\(He et al.,](#page-8-15) [2020\)](#page-8-15). **314** More details on the training and evaluation datasets **315** are provided in Appendix [C.](#page-11-1) Note that during **316** [e](#page-10-13)valuation, we report the CIDEr score [\(Vedantam](#page-10-13) **317** [et al.,](#page-10-13) [2015\)](#page-10-13) for Flickr30K, the iVQA accuracy **318** for iVQA, AUC score for HatefulMemes, Mean **319** Reciprocal Rank (MRR) for Visual Dialog, the **320** perception/perception+cognition score for MME **321**

¹We do not apply load balancing during training as we found it might distort task specialization.

Models	LLM	Expert Params.	$#$ Experts	# Clusters		Rank Temperature	Trainable Params.
InstructBLIP	Vicuna-7B	q proj, v proj	$4 + 1$ (universal)	64		0.05	O-Former, LoRAs
$LLaVA-1.5$	Vicuna-1.5-7B	up_proj , down_proj $4 + 1$ (universal)			128	0.1	MLP connector, LoRAs

Table 1: Architecture details of MoCLE on different LVLMs. Note that experts are added to each layer of the transformer.

Models			GQA VSR IQA Visdial MME POPE			A-OKVQA OKVQA VQAv2 Direct MC (test) (test-dev)	
$InstructBLIP (7B) 48.6 60.8 43.4 46.3 1202.9 77.6 58.8 73.8$						57.0	77.4
$+$ MoCLE	49.3	64.7 46.3		46.9 1222.6 82.1	61.5 78.2	59.8	78.9

Table 2: Zero-shot results (InstructBLIP) on the held-out datasets, *i.e*., GQA, VSR, IconQA (IQA), Visdial, MME, POPE and evaluation on held-in datasets, *i.e*., A-OKVQA, OKVQA, VQAv2. Here Direct and MC denote directly answering and multiple choices. Best results are marked in bold.

Models	Flickr 30K	\mathbf{VQA}^T HM \mathbf{SQA}			OA	MSVD MSRVTT _{iVQA} OΑ	
InstructBLIP $(7B)$ 81.3		53.9	65.3 62.0		41.4	23.0	51.3
$+$ MoCLE	81.9	57.1		65.6 63.9	42.6	24.4	53.2

Table 3: **Zero-shot results (InstructBLIP) on the held-out datasets.** Here, VQA^T, HM and SQA denote TextVQA, HatefulMemes and ScienceQA, respectively.

Methods	Train Data	MME	MMB	SOA	GeoOA	VOA-RAD		SLAKE		PathVOA	
						Open	Closed	Open	Closed	Open	Closed
	LLaVA-665k	1804	65.89	67.67	$\overline{}$	٠					-
Single LoRA	Geo170k			٠	57.82	۰					$\overline{}$
	Med. Mix		$\overline{}$	-	٠	53.90	84.19	86.05	85.58	38.07	91.77
Single LoRA	All	1794	64.69	66.78	57.56	46.89	77.94	84.61	82.45	35.56	90.71
MoCLE	All	1838	66.07	67.38	60.21	53.59	81.98	83.29	85.10	35.21	91.65

Table 4: Evaluation results of LLaVA-1.5-7B, where MMB denotes MMBench.

 (InstructBLIP/LLaVA) and F1 score for the adver- sarial split of POPE. For all other datasets, we re- port the top-1 accuracy (%). Task templates for evaluation can be found in Appendix [D.](#page-11-2)

326 4.3 Evaluation Results

 InstructBLIP Tables [2](#page-4-1) and [3](#page-4-2) show the results on multiple held-out/in vision-language tasks. The proposed MoCLE shows considerable performance improvement over the original LVLM. Specifically, on held-out datasets such as IconQA, Visual Spa- tial Reasoning (VSR), TextVQA and ScienceQA datasets, we obtain an absolute performance gain of 2.9%, 3.9%, 3.2%, and 1.9%, respectively. On held- in datasets, an absolute improvement of 4.4%, 2.8% and 1.5% can be observed on A-OKVQA (MC), OKVQA and VQAv2, respectively. This indicates that the proposed MoCLE facilitates generalization to unseen tasks and can effectively alleviate task conflicts during multi-task learning

341 LLaVA-1.5 Similar to the preliminary results in **342** Figure [1,](#page-0-0) we consider a *Single-LoRA* baseline **343** where a single set of LoRAs are trained on natural images (LLaVA-665k), geometric (Geo170K), **344** medical (Med. Mix) and a mixture of all tasks (All). **345** As can be seen, due to task conflicts, the model 346 trained on all tasks shows inferior results compared **347** to those trained on only one task. However, Mo- **348** CLE is able to reduce this gap on medical tasks **349** and even offer better performance on natural im- **350** age (MME, MMB) and geometric tasks (GeoQA) **351** compared to the model trained on one task. This **352** shows that MoCLE is effective with the presence **353** of multiple-domain datasets. **354**

4.4 Ablation Studies **355**

In this section, we first ablate the effectiveness of **356** the main components (i.e., Cluster MoE and univer- **357** sal expert) in the proposed MoCLE. Then we con- **358** duct a thorough analysis to study how the proposed **359** MoCLE responds to changes in hyper-parameters **360** (*e.g*., temperature and the number of clusters and **361** task experts). Notice that we use InstructBLIP **362** for all ablations and we report the evaluation re- **363** sults on Flickr30K (Flickr), Hateful Memes (HM), **364** ScienceQA (SQA), IconQA (IQA), Visual Spatial 365

			LoRA($r=8$) $r=64$ Cluster MoE Uni. Expert LoRA # Params. Flickr HM SQA IQA VSR VQA ^T Avg.						
(a)			4.19M		81.3 65.1 57.4 44.2 62.8			49.4	60.0
(b)			33.55M		81.5 65.2 62.0	43.9 62.6		49.0	60.7
(c)			16.78M	81.9	65.4 63.3	, 46.1	58.9	54.9	61.8
(d)			20.97M	81.9	65.6 63.9	46.3 64.7		57.1	63.3

Table 5: Comparison of individual components of the MoCLE framework in zero-shot vision-language tasks. Default settings are marked in gray .

366 **Reasoning (VSR) and TextVQA (VQA^T).**

367 4.4.1 Effects of Different Components

368 We start from MoCLE and remove its key compo-**369** nent one-by-one to analyze their effect.

 Universal expert. Table [5](#page-5-1) shows the ablation re- sults when varying different components of Mo- CLE. By comparing rows (d) and (c), we notice that a sharp performance drop in VSR and TextVQA tasks when the universal expert is removed. This is due to that instruction-tuned model generalizes to unseen tasks by training on many instructions, while in our case, each expert sees fewer instruc- tions than the dense model. For example, task TextVQA with instruction "*OCR tokens: {}, Ques- tion: {}. Short answer:*" needs not only VQA ability but also optical character recognition (OCR) skills, which are learned jointly from VQA data formatted as "*Question: {}. Short answer:*" and TextCaps data formatted as "*OCR tokens: {}. Write a description for the photo*". Thus, universal expert is necessary to maintain generalization ability.

 Cluster MoE. Comparing rows (c) and (a), we observe performance drop on SOA, IOA, and VOA^T when cluster MoE is not used, which indicates it can alleviate task conflicts within a single set of LoRAs between different tasks.

388

 LoRA rank. As can be seen from rows (c), (b) and (a), naïvely increasing the LoRA ranks from 8 to 64 only leads to a small average performance improvement of 0.7%, and thus cannot address task conflicts. Instead, promoting task specialization via clustering achieves notable improvement with fewer additional parameter (×4 in Cluster MoE 399 versus $\times 8$ when increasing the rank to 64).

400 4.4.2 Universal Expert vs. Top-2 Experts

 To ablate the proposed universal expert, we remove it and activate one more existing expert. *i.e*., top-2 gating. We report their performance in Table [6.](#page-5-2) The top-2 MoE model yields inferior results com- pared to MoCLE and it even performs worse than the MoCLE variant without the universal expert reported in Table [5.](#page-5-1) This can be explained by the

			Flickr HM SQA IQA VSR VQA ^T Avg.	
Universal 81.9 65.6 63.9 46.3 64.7 57.1 63.3 $Top-2$			82.0 64.7 61.9 45.5 56.3 52.0 60.4	

Table 6: Ablation study on the universal expert by comparing with either (i) a universal expert that is activated all the time or (ii) expert with the second largest logit, in addition to the top-1 expert.

Table 7: Ablation study on routing inputs based on different input conditions.

intensified conflicts when task experts are shared **408** via top-2 gating because now each expert need to **409** learn common feature with other experts. However, **410** as the universal expert is shared all the time espe- **411** cially for this purpose, it frees task experts from **412** this duty and thus alleviates the conflicts. **413** 4.4.3 Gating Strategies **414**

We compare the proposed cluster-conditioned gat- **415** ing strategy with existing MoLE methods in Table **416** [7.](#page-5-3) Note that MoLE denotes the mixture of LoRA **417** experts by applying MoE to LoRA. Some of these **418** methods adopt different configurations, *e.g*., # ex- **419** perts, expert params. and ranks. For fair compari- **420** son, we follow the first row of Table [1](#page-4-0) except that **421** universal expert is not enabled in this experiment. **422** Token/Sentence-MoLE. The former obtains the **423** routing decision based on the hidden representa- **424** tions of each token (adopted by [\(Chen et al.,](#page-8-9) [2024\)](#page-8-9)) **425** and the later on the average representations of the **426** instruction tokens while excluding the visual to- **427** kens. (adopted by [\(Chen et al.,](#page-8-8) [2023d\)](#page-8-8)). Both of **428** these methods give inferior results on the evalua- **429** tion tasks. We speculate that this is because (1) a **430** sparse expert learns less data than its dense coun- **431** terpart, leading to lack of task generalization, (2) **432** similar tasks are not grouped together by the same **433** expert, resulting in task conflicts within that expert, **434** which can be verified by the routing visualization **435** in Figure [6,](#page-7-0) where samples in the same dataset are **436**

Figure 3: Ablation study on the number of clusters, experts and gate temperature. The x-axes of the first and last figures are log-scaled. The y-axes are the average performance of Flickr, HM, SQA, IQA, VSR and VQA^T.

437 routed to multiple experts instead of a dedicated **438** one.

 Dataset-MoLE is a special case of MoCLE as it treats each dataset as a cluster while MoCLE lever- ages k-means to achieve this. It closely resembles to the dataset expert proposed in [\(Jang et al.,](#page-8-13) [2023\)](#page-8-13) except that we assign clusters for a sentence by its distance to cluster centers while they count, to this sentence, the number of closest reference sentences belonging to each dataset. Further, for fair com- parison, we only use 4 experts but they allocate an expert for each dataset. We observe inferior results compared to the proposed cluster routing. This results from the fact that Dataset-MoLE is less flexible as it can only assign a dataset to one cluster. However, in practice, we observe multiple tasks in a dataset which should be assigned to different clusters. (*e.g*., *llava_150k* contains reasoning, con- versations and captioning, which are assigned to different clusters/experts as in Figure [5](#page-7-1) and [6a\)](#page-7-0).

457 4.4.4 Number of Clusters

 The number of clusters K controls the granularity of task specialization. A very small K would result in many different tasks to be processed by the same expert, and can increase the chance of task conflicts. As shown in Figure [3,](#page-6-0) when we cluster the inputs into 4 groups, the resulting model performs poorly on the evaluation tasks. However, as we increase the number of clusters to 16 and 64, we observe considerable performance gains. However, a K too large (256) introduces unnecessary complexity to the routing process (*e.g*., a paraphrased instruction gets routed to different experts). So we use 64 clusters by default.

471 4.4.5 Temperature

 In the proposed MoCLE, the temperature plays an important role in controlling the contribution of the universal expert. Specifically, as shown in Eq. [\(1\)](#page-2-3), τ controls the sharpness of the gate distribution, while the output of the universal expert is **476** weighted by $1 - G_{\text{max}}$. Therefore, as τ decreases, 477 Gmax increases, and finally the contribution of the **⁴⁷⁸** universal expert decreases. As shown in Figure [3,](#page-6-0) **479** the results are consistent with our understandings. **480** When τ is either too small (0.01) or large (0.2) can 481 lead to inferior results. The temperatures of 0.05 **482** and 0.1 seem to achieve a balance between spe- **483** cialization and generalization of the model. In the **484** experiments, we use temperature of 0.05 as default. **485**

4.4.6 Number of Task Experts **486**

As demonstrated in Figure [3,](#page-6-0) more task experts usu- **487** ally provides with stronger capacity. Specifically, **488** when only 2 task experts are employed, we observe **489** inferior overall results. This model has similar **490** capacity to the single LoRA model in Sec. [4.4.1,](#page-5-0) **491** where only one LoRA encounters difficulties in 492 fitting a diverse set of tasks. When the number of **493** task experts is increased to 4, the performance gets **494** improved. When the number of task experts be- **495** comes 8, it behaves similarly to the 4-expert case, **496** which indicates that the benefit of increasing capac- 497 ity converges as we use more task experts. Hence, **498** we use 4 task experts as the default setting. **499**

4.5 Visualizations **500**

4.5.1 Clustering 501

We first show the justification to represent the train- **502** ing data via their instructions. Specifically, for **503** each dataset, we sample 100 examples and encode **504** their instructions with the all-MiniLM-L6-v2 vari- **505** [a](#page-9-11)nt of the Sentence Transformer model [\(Reimers](#page-9-11) **506** [and Gurevych,](#page-9-11) [2019\)](#page-9-11). We then visualize the data **507** [i](#page-10-14)n Figure [4](#page-7-2) via t-SNE [\(Van der Maaten and Hin-](#page-10-14) **508** [ton,](#page-10-14) [2008\)](#page-10-14). As can be seen, (1) Samples from the **509** same task are grouped together. For example, all 510 visual question generation (VQG, triangle markers) **511** data reside on the left part of the figure. (2) Sam- **512** ples from similar tasks are close to each other, *e.g*., **513**

7

Figure 4: T-SNE visualization of the instruction encoding. Different colors correspond to different datasets, while the shape of the markers indicates the task category defined manually.

Figure 5: Clustering assignment of the training datasets when $K = 64$. The labels on the y-axis indicate the names of the datasets. The x-axis denotes the cluster index to which the subsets are assigned.

 coco_cap and *textcaps* both belong to the image captioning (CAP, small dots) task and stay close to each other at the lower right of the figure. Simi- larly, both visual question answering (VQA, cross markers) and conversation (CONV, y-shape) data involve answering user questions, which lie in the middle part of the figure, suggesting that instruc-tions are good representatives of training data.

 We then cluster all the instructions of the ex- amples in the training data into 64 groups using k-means clustering. Figure [5](#page-7-1) shows the cluster as- signment of the training data. Here, each row in the heatmap denotes a subset of a dataset. The subset is obtained by applying the task template (Sec. [3.1\)](#page-2-4) on the samples of the dataset. We ob- serve the following: (1) Different subsets of the same datasets are assigned to similar clusters. For example, *aok_vqa*, *coco_vqa*, and *ok_vqa* are in the first several clusters. (2) Datasets of similar tasks are assigned to common clusters. For example,

Figure 6: Routing decisions of one LoRA mixture for MoCLE and Sentence-MoLE. The setup of the vertical axis is similar to Figure [5](#page-7-1) except that we also include the held-out tasks. They are separated by a dotted line on the vertical axis. The horizontal axis corresponds to the index of the LoRA experts.

llava_150k including *llava_detail*, *llava_reason* **534** and *llava_conversation* and a series of VQA tasks **535** share the first several clusters as they are to answer **536** questions. These justify the use of clustering on **537** task instructions as an automatic partition strategy **538** for training datasets. **539**

4.5.2 Routing Results **540**

Figure [6](#page-7-0) visualizes the routing decisions of the 541 proposed MoCLE and Sentence-MoLE. We obtain **542** both results from one mixture of LoRA, *i.e*., one **543** linear module in a layer. The routing results are **544** aggregated by the subset of datasets similar to Fig- **545** ure [5.](#page-7-1) As can be seen from Figure [6a,](#page-7-0) MoCLE can **546** achieve task-level routing for the inputs. For exam- **547** ple, datasets from *VQA* and *VQG* tasks are handled **548** by expert 0 and 3, respectively. Instead, routing pat- **549** tern of Sentence-MoLE in Figure [6b](#page-7-0) reveals little **550** correlations between datasets and experts. That is, **551** different datasets obtain similar routing decisions, **552** and thus still suffer from task conflicts. **553**

5 Conclusions **⁵⁵⁴**

In this paper, we first show through extensive exper- **555** iments that task conflicts exist in vision language **556** instruction tuning. To address this, we propose **557** the Mixture of Cluster-conditional LoRA Experts **558** (MoCLE), a novel MoE architecture designed to ac- **559** tivate the task-customized model parameters based **560** on the instruction clusters. In addition, we achieve **561** task specialization and generalization in MoCLE si- **562** multaneously via a separate universal expert. Com- **563** prehensive evaluations of MoCLE on both held- **564** out/in tasks show the effectiveness of MoCLE. **565**

⁵⁶⁶ 6 Limitations

567 Although effective, we mainly focus on task con-**568** flicts among text-based conversation tasks in this

569 paper, while the support of our MoCLE for more **570** complicated visual perception tasks is appealing,

571 which has shown more severe task conflicts with **572** the conversation tasks [\(Zhu et al.,](#page-10-15) [2022\)](#page-10-15).

- **⁵⁷³** References **574** Jinze Bai, Shuai Bai, Shusheng Yang, Shijie Wang,
- **575** Sinan Tan, Peng Wang, Junyang Lin, Chang Zhou, **576** and Jingren Zhou. 2023. Qwen-vl: A frontier large **577** vision-language model with versatile abilities. *arXiv*
- **578** *preprint arXiv:2308.12966*. **579** Tom Brown, Benjamin Mann, Nick Ryder, Melanie
- **580** Subbiah, Jared D Kaplan, Prafulla Dhariwal, Arvind **581** Neelakantan, Pranav Shyam, Girish Sastry, Amanda
- **582** Askell, et al. 2020. Language models are few-shot

583 learners. In *NeurIPS*.

- **584** Jiaqi Chen, Jianheng Tang, Jinghui Qin, Xiaodan Liang, **585** Lingbo Liu, Eric P Xing, and Liang Lin. 2021. **586** Geoqa: A geometric question answering benchmark
- **587** towards multimodal numerical reasoning. *arXiv* **588** *preprint arXiv:2105.14517*.
- **589** Jun Chen, Deyao Zhu, Xiaoqian Shen, Xiang Li, Zechun

590 Liu, Pengchuan Zhang, Raghuraman Krishnamoor-**591** thi, Vikas Chandra, Yunyang Xiong, and Mohamed

592 Elhoseiny. 2023a. Minigpt-v2: large language model **593** as a unified interface for vision-language multi-task **594** learning. *arXiv preprint arXiv:2310.09478*.

595 Kai Chen, Chunwei Wang, Kuo Yang, Jianhua Han, **596** Lanqing Hong, Fei Mi, Hang Xu, Zhengying Liu,

597 Wenyong Huang, Zhenguo Li, et al. 2023b. Gain-**598** ing wisdom from setbacks: Aligning large lan-**599** guage models via mistake analysis. *arXiv preprint*

600 *arXiv:2310.10477*. **601** Lin Chen, Jisong Li, Xiaoyi Dong, Pan Zhang, Con-

602 ghui He, Jiaqi Wang, Feng Zhao, and Dahua

603 Lin. 2023c. Sharegpt4v: Improving large multi-**604** modal models with better captions. *arXiv preprint*

605 *arXiv:2311.12793*.

606 Shaoxiang Chen, Zequn Jie, and Lin Ma. 2024. Llava-**607** mole: Sparse mixture of lora experts for mitigating

608 data conflicts in instruction finetuning mllms. *arXiv* **609** *preprint arXiv:2401.16160*.

610 Zeren Chen, Ziqin Wang, Zhen Wang, Huayang Liu, **611** Zhenfei Yin, Si Liu, Lu Sheng, Wanli Ouyang,

612 Yu Qiao, and Jing Shao. 2023d. Octavius: Mitigating **613** task interference in mllms via moe. *arXiv preprint*

615 Zeren Chen, Ziqin Wang, Zhen Wang, Huayang Liu,

614 *arXiv:2311.02684*.

616 Zhenfei Yin, Si Liu, Lu Sheng, Wanli Ouyang, **617** Yu Qiao, and Jing Shao. 2023e. Octavius: Mitigating task interference in mllms via moe. *arXiv preprint* **618** *arXiv:2311.02684*. **619**

- Hyung Won Chung, Le Hou, Shayne Longpre, Barret **620** Zoph, Yi Tay, William Fedus, Yunxuan Li, Xuezhi **621** Wang, Mostafa Dehghani, Siddhartha Brahma, et al. **622** 2022. Scaling instruction-finetuned language models. **623** *arXiv preprint arXiv:2210.11416*. **624**
- Wenliang Dai, Junnan Li, Dongxu Li, Anthony **625** Meng Huat Tiong, Junqi Zhao, Weisheng Wang, **626** Boyang Albert Li, Pascale Fung, and Steven C. H. **627** Hoi. 2023. Instructblip: Towards general-purpose **628** vision-language models with instruction tuning. **629** *arXiv preprint arxiv:2305.06500*. **630**
- Chaoyou Fu, Peixian Chen, Yunhang Shen, Yulei Qin, **631** Mengdan Zhang, Xu Lin, Zhenyu Qiu, Wei Lin, Jin- **632** rui Yang, Xiawu Zheng, et al. 2023. Mme: A compre- **633** hensive evaluation benchmark for multimodal large 634

language models. *arXiv preprint arXiv:2306.13394*. 635 language models. *arXiv preprint arXiv:2306.13394*. **635**
- Jiahui Gao, Renjie Pi, Jipeng Zhang, Jiacheng Ye, Wan- **636** jun Zhong, Yufei Wang, Lanqing Hong, Jianhua Han, **637** Hang Xu, Zhenguo Li, and Lingpeng Kong. 2023. [G-](https://arxiv.org/abs/2312.11370) **638** [llava: Solving geometric problem with multi-modal](https://arxiv.org/abs/2312.11370) **639** [large language model.](https://arxiv.org/abs/2312.11370) *Preprint*, arXiv:2312.11370. **640**
- Yash Goyal, Tejas Khot, Douglas Summers-Stay, Dhruv **641** Batra, and Devi Parikh. 2017. Making the v in vqa **642** matter: Elevating the role of image understanding in **643** visual question answering. In *CVPR*. **644**
- Xuehai He, Yichen Zhang, Luntian Mou, Eric Xing, and **645** Pengtao Xie. 2020. Pathvqa: 30000+ questions for **646** medical visual question answering. *arXiv preprint* **647** *arXiv:2003.10286*. **648**
- J. Edward Hu, Yelong Shen, Phillip Wallis, Zeyuan **649** Allen-Zhu, Yuanzhi Li, Shean Wang, and Weizhu **650** Chen. 2021. Lora: Low-rank adaptation of large **651** language models. *arXiv preprint arxiv:2106.09685*. **652**
- Chengsong Huang, Qian Liu, Bill Yuchen Lin, Tianyu **653** Pang, Chao Du, and Min Lin. 2023. Lorahub: Effi- **654** cient cross-task generalization via dynamic lora com- **655** position. *arXiv preprint arXiv:2307.13269*. **656**
- Drew A Hudson and Christopher D Manning. 2019. **657** Gqa: A new dataset for real-world visual reasoning **658** and compositional question answering. In *CVPR*. **659**
- Robert A. Jacobs, Michael I. Jordan, Steven J. Nowlan, **660** and Geoffrey E. Hinton. 1991. Adaptive mixtures of **661** local experts. In *Neural Computation*. **662**
- Joel Jang, Seungone Kim, Seonghyeon Ye, Doyoung **663** Kim, Lajanugen Logeswaran, Moontae Lee, Kyung- **664** jae Lee, and Minjoon Seo. 2023. [Exploring the bene-](https://api.semanticscholar.org/CorpusID:256627673) **665** [fits of training expert language models over instruc-](https://api.semanticscholar.org/CorpusID:256627673) **666** [tion tuning.](https://api.semanticscholar.org/CorpusID:256627673) In *International Conference on Machine* **667** *Learning*. **668**
- Michael I. Jordan and Robert A. Jacobs. 1993. Hierar- **669** chical mixtures of experts and the em algorithm. In **670** *Neural Computation*. **671**

9

- **672** Douwe Kiela, Hamed Firooz, Aravind Mohan, Vedanuj **673** Goswami, Amanpreet Singh, Pratik Ringshia, and **674** Davide Testuggine. 2020. The hateful memes chal-**675** lenge: Detecting hate speech in multimodal memes. **676** In *NeurIPS*.
- **677** Diederik P Kingma and Jimmy Ba. 2014. Adam: A **678** method for stochastic optimization. *arXiv preprint* **679** *arXiv:1412.6980*.
- **680** Jason Lau, Soumya Gayen, Asma Ben Abacha, and **681** Dina Demner-Fushman. 2018. [A dataset of clini-](https://doi.org/10.1038/sdata.2018.251)**682** [cally generated visual questions and answers about](https://doi.org/10.1038/sdata.2018.251) **683** [radiology images.](https://doi.org/10.1038/sdata.2018.251) *Scientific Data*, 5:180251.
- **684** Dengchun Li, Yingzi Ma, Naizheng Wang, Zhiyuan **685** Cheng, Lei Duan, Jie Zuo, Cal Yang, and Mingjie **686** Tang. 2024. Mixlora: Enhancing large language **687** models fine-tuning with lora based mixture of experts. **688** *arXiv preprint arXiv:2404.15159*.
- **689** Junnan Li, Dongxu Li, Silvio Savarese, and Steven C. H. **690** Hoi. 2023a. Blip-2: Bootstrapping language-image **691** pre-training with frozen image encoders and large **692** language models. *arxiv preprint arxiv:2301.12597*.
- **693** Lei Li, Yuwei Yin, Shicheng Li, Liang Chen, Peiyi **694** Wang, Shuhuai Ren, Mukai Li, Yazheng Yang, **695** Jingjing Xu, Xu Sun, Lingpeng Kong, and Qi Liu. **696** 2023b. M3it: A large-scale dataset towards multi-**697** modal multilingual instruction tuning. *arxiv preprint* **698** *arxiv:2306.04387*.
- **699** Yifan Li, Yifan Du, Kun Zhou, Jinpeng Wang, **700** Wayne Xin Zhao, and Ji-Rong Wen. 2023c. Eval-**701** uating object hallucination in large vision-language **702** models. *arXiv preprint arXiv:2305.10355*.
- **703** Tsung-Yi Lin, Michael Maire, Serge Belongie, James **704** Hays, Pietro Perona, Deva Ramanan, Piotr Dollár, **705** and C Lawrence Zitnick. 2014. Microsoft coco: **706** Common objects in context. In *ECCV*.
- **707** Bo Liu, Li-Ming Zhan, Li Xu, Lin Ma, Yan Yang, and **708** Xiao-Ming Wu. 2021. Slake: A semantically-labeled **709** knowledge-enhanced dataset for medical visual ques-**710** tion answering. In *2021 IEEE 18th International* **711** *Symposium on Biomedical Imaging (ISBI)*, pages **712** 1650–1654. IEEE.
- **713** Fangyu Liu, Guy Edward Toh Emerson, and Nigel Col-**714** lier. 2022a. Visual spatial reasoning. In *TACL*.
- **715** Haotian Liu, Chunyuan Li, Yuheng Li, and Yong Jae **716** Lee. 2023a. Improved baselines with visual instruc-**717** tion tuning. *arXiv preprint arXiv:2310.03744*.
- **718** Haotian Liu, Chunyuan Li, Qingyang Wu, and Yong Jae **719** Lee. 2023b. Visual instruction tuning. *arxiv preprint* **720** *arxiv:2304.08485*.
- **721** Yijiang Liu, Rongyu Zhang, Huanrui Yang, Kurt **722** Keutzer, Yuan Du, Li Du, and Shanghang Zhang. **723** 2024. Intuition-aware mixture-of-rank-1-experts **724** for parameter efficient finetuning. *arXiv preprint* **725** *arXiv:2404.08985*.
- Yuan Liu, Haodong Duan, Yuanhan Zhang, Bo Li, **726** Songyang Zhang, Wangbo Zhao, Yike Yuan, Jiaqi **727** Wang, Conghui He, Ziwei Liu, et al. 2023c. Mm- **728** bench: Is your multi-modal model an all-around **729** player? *arXiv preprint arXiv:2307.06281*. **730**
- Zhili Liu, Jianhua Han, Kai Chen, Lanqing Hong, Hang **731** Xu, Chunjing Xu, and Zhenguo Li. 2022b. Task- **732** customized self-supervised pre-training with scalable **733** dynamic routing. In *AAAI*. **734**
- Shayne Longpre, Le Hou, Tu Vu, Albert Webson, **735** Hyung Won Chung, Yi Tay, Denny Zhou, Quoc V **736** Le, Barret Zoph, Jason Wei, et al. 2023. The flan **737** collection: Designing data and methods for effective **738** instruction tuning. *arXiv preprint arXiv:2301.13688*. **739**
- Pan Lu, Swaroop Mishra, Tony Xia, Liang Qiu, Kai-Wei **740** Chang, Song-Chun Zhu, Oyvind Tafjord, Peter Clark, **741** and A. Kalyan. 2022. Learn to explain: Multimodal **742** reasoning via thought chains for science question 743
answering. *arxiv preprint arxiv*:2209.09513. answering. *arxiv preprint arxiv:2209.09513*. **744**
- Pan Lu, Liang Qiu, Jiaqi Chen, Tony Xia, Yizhou Zhao, **745** Wei Zhang, Zhou Yu, Xiaodan Liang, and Song-Chun **746** Zhu. 2021. Iconqa: A new benchmark for abstract di- **747** agram understanding and visual language reasoning. **748** *arxiv preprint arxiv:2110.13214*. **749**
- Tongxu Luo, Jiahe Lei, Fangyu Lei, Weihao Liu, Shizhu **750** He, Jun Zhao, and Kang Liu. 2024. Moelora: **751** Contrastive learning guided mixture of experts on **752** parameter-efficient fine-tuning for large language **753** models. *arXiv preprint arXiv:2402.12851*. **754**
- Kenneth Marino, Mohammad Rastegari, Ali Farhadi, **755** and Roozbeh Mottaghi. 2019. Ok-vqa: A visual **756** question answering benchmark requiring external **757** knowledge. In *CVPR*. **758**
- Anand Mishra, Shashank Shekhar, Ajeet Kumar Singh, **759** and Anirban Chakraborty. 2019. Ocr-vqa: Visual **760** question answering by reading text in images. In **761** *ICDAR*. **762**
- Mohammed Muqeeth, Haokun Liu, Yufan Liu, and **763** Colin Raffel. 2024. Learning to route among spe- **764** cialized experts for zero-shot generalization. *arXiv* **765** *preprint arXiv:2402.05859*. **766**
- OpenAI. 2022. Introducing chatgpt. *Technical Report*. **767**
- Nils Reimers and Iryna Gurevych. 2019. Sentence-bert: **768** Sentence embeddings using siamese bert-networks. 769 *arXiv preprint arXiv:1908.10084*. **770**
- Victor Sanh, Albert Webson, Colin Raffel, Stephen H **771** Bach, Lintang Sutawika, Zaid Alyafeai, Antoine **772** Chaffin, Arnaud Stiegler, Teven Le Scao, Arun **773** Raja, et al. 2021. Multitask prompted training en- **774** ables zero-shot task generalization. *arXiv preprint* **775** *arXiv:2110.08207*. **776**
- Dustin Schwenk, Apoorv Khandelwal, Christopher **777** Clark, Kenneth Marino, and Roozbeh Mottaghi. 2022. **778** A-okvqa: A benchmark for visual question answer- **779** ing using world knowledge. In *ECCV*. **780**
-
-
-
-
-

-
-
-

- Noam M. Shazeer, Azalia Mirhoseini, Krzysztof Maziarz, Andy Davis, Quoc V. Le, Geoffrey E. Hin- ton, and Jeff Dean. 2017. Outrageously large neu- ral networks: The sparsely-gated mixture-of-experts layer. *arxiv preprint arxiv:1701.06538*.
- Oleksii Sidorov, Ronghang Hu, Marcus Rohrbach, and Amanpreet Singh. 2020. Textcaps: a dataset for image captioning with reading comprehension. In *ECCV*.
- Amanpreet Singh, Vivek Natarajan, Meet Shah, Yu Jiang, Xinlei Chen, Dhruv Batra, Devi Parikh, and Marcus Rohrbach. 2019. Towards vqa models that can read. In *CVPR*.
- Laurens Van der Maaten and Geoffrey Hinton. 2008. Visualizing data using t-sne. In *JMLR*.
- Ramakrishna Vedantam, C Lawrence Zitnick, and Devi Parikh. 2015. Cider: Consensus-based image de-scription evaluation. In *CVPR*.
- Yizhong Wang, Swaroop Mishra, Pegah Alipoor- molabashi, Yeganeh Kordi, Amirreza Mirzaei, Anjana Arunkumar, Arjun Ashok, Arut Selvan Dhanasekaran, Atharva Naik, David Stap, et al. 2022. Super-naturalinstructions: Generalization via declar- ative instructions on 1600+ nlp tasks. *arXiv preprint arXiv:2204.07705*.
- Jason Wei, Maarten Bosma, Vincent Y Zhao, Kelvin Guu, Adams Wei Yu, Brian Lester, Nan Du, An- drew M Dai, and Quoc V Le. 2021. Finetuned lan- guage models are zero-shot learners. *arXiv preprint arXiv:2109.01652*.
- Haoyuan Wu, Haisheng Zheng, and Bei Yu. 2024a. Parameter-efficient sparsity crafting from dense to mixture-of-experts for instruction tuning on general tasks. *arXiv preprint arXiv:2401.02731*.
- Xun Wu, Shaohan Huang, and Furu Wei. 2024b. Mixture of lora experts. *arXiv preprint arXiv:2404.13628*.
- Dejing Xu, Zhou Zhao, Jun Xiao, Fei Wu, Hanwang Zhang, Xiangnan He, and Yueting Zhuang. 2017. Video question answering via gradually refined atten- tion over appearance and motion. In *ACM Multime-dia*.
- Antoine Yang, Antoine Miech, Josef Sivic, Ivan Laptev, and Cordelia Schmid. 2021. Just ask: Learning to answer questions from millions of narrated videos. In *ICCV*.
- Qinghao Ye, Haiyang Xu, Jiabo Ye, Ming Yan, Haowei Liu, Qi Qian, Ji Zhang, Fei Huang, and Jingren Zhou. 2023. mplug-owl2: Revolutionizing multi-modal large language model with modality collaboration. *arXiv preprint arXiv:2311.04257*.
- Peter Young, Alice Lai, Micah Hodosh, and J. Hock- enmaier. 2014. From image descriptions to visual denotations: New similarity metrics for semantic in-ference over event descriptions. In *TACL*.
- Ted Zadouri, A. Ustun, Arash Ahmadian, Beyza Ermics, **836** Acyr Locatelli, and Sara Hooker. 2023. Pushing **837** mixture of experts to the limit: Extremely parameter **838** efficient moe for instruction tuning. *arxiv preprint* **839** *arxiv:2309.05444*. **840**
- Pan Zhang, Xiaoyi Dong Bin Wang, Yuhang Cao, Chao **841** Xu, Linke Ouyang, Zhiyuan Zhao, Shuangrui Ding, **842** Songyang Zhang, Haodong Duan, Hang Yan, et al. **843** 2023. Internlm-xcomposer: A vision-language large **844** model for advanced text-image comprehension and **845** composition. *arXiv preprint arXiv:2309.15112*. **846**
- Yu Zhang and Qiang Yang. 2017. A survey on multi- **847** task learning. In *TKDE*. **848**
- Bo Zhao, Boya Wu, and Tiejun Huang. 2023. Svit: **849** Scaling up visual instruction tuning. *arxiv preprint* **850** *arxiv:2307.04087*. **851**
- LIU Zhili, Kai Chen, Jianhua Han, HONG Lanqing, **852** Hang Xu, Zhenguo Li, and James Kwok. 2023. Task-customized masked autoencoder via mixture **854** of cluster-conditional experts. In *ICLR*. **855**
- Chunting Zhou, Pengfei Liu, Puxin Xu, Srini Iyer, Jiao **856** Sun, Yuning Mao, Xuezhe Ma, Avia Efrat, Ping Yu, **857** Lili Yu, et al. 2023. Lima: Less is more for alignment. **858** *arXiv preprint arXiv:2305.11206*. **859**
- Deyao Zhu, Jun Chen, Xiaoqian Shen, Xiang Li, and **860** Mohamed Elhoseiny. 2023. Minigpt-4: Enhancing **861** vision-language understanding with advanced large **862** language models. *arXiv preprint arxiv:2304.10592*. **863**
- Jinguo Zhu, Xizhou Zhu, Wenhai Wang, Xiaohua Wang, **864** Hongsheng Li, Xiaogang Wang, and Jifeng Dai. 2022. **865** Uni-perceiver-moe: Learning sparse generalist mod- **866** els with conditional moes. In *NeurIPS*. **867**

868 **A** Training Details

869 A.1 InstructBLIP

 Following [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5), we adopt the same training configurations for the mentioned models such as the proposed MoCLE, the reproduced In- structBLIP (7B) and the task experts in Sec. [1.](#page-0-1) We train those models with a maximum of 60K steps and a batch size of 128. The AdamW optimizer **[\(Kingma and Ba,](#page-9-14) [2014\)](#page-9-14) is used, with** β_1 **as 0.9,** β_2 as 0.999, and a weight decay as 0.05. We apply a linear warmup of the learning rate during the initial **1000 steps, increasing from 10⁻⁸ to 10⁻⁵, followed** by a cosine decay with a minimum learning rate of **881** 0.

882 A.2 LLaVA-1.5

 We follow [\(Liu et al.,](#page-9-3) [2023a\)](#page-9-3) for the training config- uration. Specifically, for LLaVA-150K[\(Liu et al.,](#page-9-3) [2023a\)](#page-9-3), Geo170K[\(Gao et al.,](#page-8-14) [2023\)](#page-8-14) and Med. Mix, *[i](#page-9-13).e*., VQA-RAD[\(Lau et al.,](#page-9-12) [2018\)](#page-9-12), SLAKE[\(Liu](#page-9-13) [et al.,](#page-9-13) [2021\)](#page-9-13) and Path-VQA[\(He et al.,](#page-8-15) [2020\)](#page-8-15), we train the model for 1, 2 and 9 epochs, respectively. When training on all of these datasets, we copy each dataset k times (k is the number of epochs it is trained independently) and merge them into a single dataset. For each training job, we use a batch size of 128, weight decay of 0 and learning 894 rate of $1e - 4$, which is warmed up from 0 during the initial 3% steps and followed by a cosine decay with a minimum learning rate of 0.

897 **B** Weights of the Universal Experts

 During training, if some training data obtains a very large weight on a task expert, such data tend to be very specific and might be less beneficial to other tasks. Hence, they get less weight on the universal expert. On the contrary, less specific (a.k.a, more general) data benefit more to other tasks and obtain larger weight on the universal expert. Therefore, the complementarity between the task experts and universal expert achieves good generalization in **907** MoCLE.

 Figure [7](#page-11-3) shows the average activation weights of the universal experts for different datasets during training. ocr_vqa obtains the lowest weight on the universal expert during training. Indeed, ocr_vqa includes samples that require the model to answer questions such as "What is the title of this book?" and "Who is the author of this book?". Ques- tions like these have little overlap with the ones in other datasets. However, we observe much higher

weights for ok_vqa, ok_vqg, aok_vqa, aok_vqg, **917** llava_*, and coco_vqa. This is consistent with our **918** previous observation in Sec. [4.5](#page-6-1) that VQA abilities **919** are fundamental in LVLM. **920**

Figure 7: Weights of the universal expert for different datasets. Colors indicate different datasets.

C Data **⁹²¹**

We list the training and evaluation data for Instruct- **922** BLIP and LLaVA-1.5 in Table [8.](#page-12-0) **923**

C.1 Dataset Abbreviation **924**

For InstructBLIP, we further show in Table [9](#page-12-1) (1) 925 the abbreviation used in Sec. [4.5](#page-6-1) for each dataset **926** and (2) their manually defined task category. As **927** shown in Table [9,](#page-12-1) we use 13 datasets in total. Here **928** multiple datasets might be associated with the same **929** data sources because these sources are formatted **930** by different groups of task templates (see Appendix **931** [D\)](#page-11-2). For LLaVA-150K [\(Liu et al.,](#page-9-2) [2023b\)](#page-9-2), we do **932** not apply any task template as it has been well **933** formatted. **934**

D Task Templates **⁹³⁵**

For InstructBLIP, we use the same set of task tem- **936** plates following [\(Dai et al.,](#page-8-5) [2023\)](#page-8-5) for instruction **937** tuning and held-in/out evaluation. Please refer to **938** Tables [10](#page-13-0) and [11](#page-13-1) for training and evaluation tem- **939** plates **940**

E Case Studies **941**

In this section, we present several case studies with **942** MoCLE. First, we study its conversation abilities **943** via a range of tasks, including object counting, **944** optical character recognition (OCR), and image **945** introduction. Then we showcase some example **946** instructions sampled from different clusters. **947**

Models	Training datasets	Evaluation Datasets
		Flickr30K (Young et al., 2014), GQA (Hudson and Manning, 2019)
	Web CapFilt (Li et al., 2023a)	VSR (Liu et al., 2022a), IconQA (Lu et al., 2021)
InstructBLIP	A-OKVOA (Schwenk et al., 2022)	TextVQA (Singh et al., 2019), Hateful Memes (Kiela et al., 2020)
	TextCaps (Sidorov et al., 2020), VQAv2(Goyal et al., 2017)	ScienceOA (Lu et al., 2022), MSVD-OA (Xu et al., 2017)
	OKVQA (Marino et al., 2019), COCO (Lin et al., 2014)	MSRVTT-QA (Xu et al., 2017), iVQA (Yang et al., 2021)
	OCRVQA (Mishra et al., 2019), LLaVA-150K (Liu et al., 2023b)	MME (Fu et al., 2023), POPE (Li et al., 2023c)
		OKVQA*, A-OKVQA*, VQAv2*
	LLaVA-665K (Liu et al., $2023a$)	MME, MMBench(Liu et al., 2023c), ScienceOA
$LLaVA-1.5$	Geo170K (Gao et al., 2023), VOA-RAD (Lau et al., 2018)	GeoOA* (Chen et al., 2021), VOA-RAD*
	SLAKE (Liu et al., 2021), PathVOA (He et al., 2020)	SLAKE*, PathVOA*

Table 8: Datasets used for training and evaluation. *: the train split of this dataset is used during instruction tuning.

Datasets	Data Source	Task Template Group
aok_vqa	A-OKVQA	VOAMC
aok_vqg	A-OKVOA	VOG
coco_cap	COCO	CAP
coco_vqa	VOAv ₂	VOA
coco_vqg	VOA _v 2	VOG
ocrvqa	OCR-VOA	VOA
ok_vqa	OKVQA	VOA
ok_vqg	OKVOA	VOA
textcaps	TextCaps	OCRCAPS
capfilt	Web CapFilt	CAP
llava conversation	LLaVA-150K	
llava detail	LLaVA-150K	
llava reason	LLaVA-150K	

Table 9: Abbreviation and manually defined task categories for the training datasets of InstructBLIP.

948 E.1 Conversations

 In Table [12,](#page-14-0) we instruct the model to conduct a very difficult object counting task. The correct answer for this question is 63, which is quite hard for existing LVLMs. InstructBLIP fails to give the correct answers, while with MoCLE, InstructBLIP can respond the user query in a much more proper **955** manner.

 In Table [13,](#page-14-1) the model is queried to recognize the character in the image. InstructBLIP performs not so well on this query possibly because OCR-related tasks conflict with other tasks during training. With MoCLE, the model can give correct results.

 In Table [14,](#page-14-2) we ask the model to introduce a famous person in the image. InstructBLIP gives a blunt response to the user query and does not follow the instruction of "introduction". This might be due to the conflict between image caption and conversation tasks. In the training data, there are a large portion of image caption data that require the model to give a brief description to the image, while the user query in this example expects a detailed introduction to Albert Einstein. With MoCLE, the user query is identified and routed to the correct expert that is specialized at such a conversation task, thus, the model outputs a desired response.

Similarly, in Table [15,](#page-14-3) we ask the model to de- **974** scribe the image in a detailed manner. InstructBLIP **975** still mistakes this query as an image caption task **976** and gives very short caption to this image. Instead, **977** with MoCLE, the model correctly understands the **978** "in details" in the instruction and provides sufficient **979** details. 980

E.2 Sample Instructions in Clusters **981**

In Table [16,](#page-15-0) we showcase some sample instructions **982** assigned to different clusters. Though all the in- **983** structions in the 4 selected clusters belong to VQA- **984** related tasks, they focus on various perspectives **985** such as food, pet, men, and counting, justifying the **986** usage of a large number of instruction clusters. **987**

Table 10: Task templates used during training. For OCRCAPS, we insert "OCR tokens:{}" before the template of CAP. For VQAMC (*i.e*., multiple choice VQA), we append "Options: (a) option 1 (b) option2, . . ." after the question and before the answer.

Table 11: Task templates used during evaluation.

Model responses to counting-related queries.

Table 12: Model responses to counting-related queries.

Model responses when asked to introduce a famous person.

Table 14: Model responses to introduce a celebrity.

Model responses when queried to give detailed image descriptions.

Table 15: Model responses to give detailed image description.

Table 16: Sampled instructions from different clusters.