MULTI-VIEW ENCODERS FOR PERFORMANCE PREDICTION IN LLM-BASED AGENTIC WORKFLOWS

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ABSTRACT

Large language models (LLMs) have demonstrated remarkable capabilities across diverse tasks, but optimizing LLM-based agentic systems remains challenging due to the vast search space of agent configurations, prompting strategies, and communication patterns. Existing approaches often rely on heuristic-based tuning or exhaustive evaluation, which can be computationally expensive and suboptimal. This paper proposes **Agentic Predictor**, a lightweight predictor for efficient agentic workflow evaluation. Agentic Predictor is equipped with a *multi-view workflow encoding* technique that leverages multi-view representation learning of agentic systems by incorporating code architecture, textual prompts, and interaction graph features. To achieve high predictive accuracy while significantly reducing the number of required workflow evaluations for training a predictor, Agentic Predictor employs *cross-domain unsupervised pretraining*. By learning to approximate task success rates, Agentic Predictor enables fast and accurate selection of optimal agentic workflow configurations for a given task, significantly reducing the need for expensive trial-and-error evaluations. Experiments on a carefully curated benchmark spanning three domains show that our predictor outperforms state-of-the-art methods in both predictive accuracy and workflow utility, highlighting the potential of performance predictors in streamlining the design of LLM-based agentic workflows.

1 INTRODUCTION

Large language models (LLMs) have catalyzed the development of agentic systems capable of executing complex, multi-step tasks autonomously (Hong et al., 2024; Wu et al., 2024; Xi et al., 2024; Mialon et al., 2024). These systems, often constructed through meticulous manual engineering, integrate components such as Chain-of-Thought reasoning, tool invocation, and memory management to enable sophisticated behaviors for orchestrating intricate workflows (Xi et al., 2025; Ke et al., 2025; Gridach et al., 2025; Plaat et al., 2025). However, the handcrafted nature of these systems imposes limitations on scalability, adaptability, and rapid deployment across diverse domains.

To address these limitations, recent trends have shifted towards automated design methods for agentic systems (Hu et al., 2025a; Shang et al., 2025; Zhang et al., 2025a; Zhuge et al., 2024; Liu et al., 2024b; Hu et al., 2025b; Yuan et al., 2025). Automated methods typically employ search algorithms to discover optimal workflow configurations by systematically exploring a vast design space. Instead of relying on human intuition, these approaches generally involve iterations of candidate generation, evaluation, and refinement. While promising, these methods exhibit significant drawbacks, chiefly the high computational costs associated with the extensive validation steps needed during the exploration and evaluation phases of the search. Each candidate configuration must undergo rigorous evaluation, often through expensive, repeated interactions with LLM APIs, rendering the search prohibitively costly and time-consuming.

In this paper, we argue that purely search-based automated design methods are inherently inefficient and propose a predictive approach to significantly accelerate workflow evaluation. Specifically, we advocate for a predictor-based framework that can rapidly estimate the performance of candidate agentic workflows, similar to performance predictors in neural architecture search (White et al., 2021), thereby reducing the need for extensive validation.

As depicted in Figure 1, instead of fully evaluating every candidate, a predictive model can estimate the quality and viability of agentic workflows, thus guiding the search process far more efficiently. By reducing costly ground-truth executions or environment interactions during the search process, prediction-based approaches promise significant improvements in both search efficiency and solution quality. However, building a high-quality predictor for agentic workflows introduces two fundamental challenges.

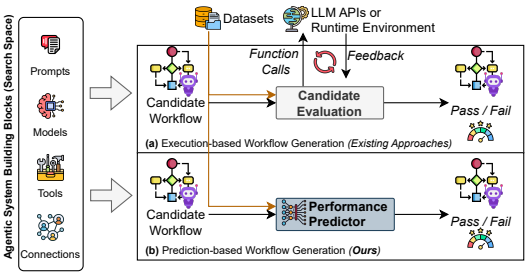

Figure 1: Comparison between (a) execution-based and (b) prediction-based candidate evaluation for agentic workflow generation. Execution-based methods rely on costly runtime or LLM calls, while our prediction-based approach offers faster, scalable evaluation via a learned predictor.

Workflow Heterogeneity. Agentic workflows exhibit considerable heterogeneity; subtle variations in configuration can lead to dramatically different performances. Specifically, workflows can vary widely in communication structure, prompting strategies, tool invocation patterns, and reasoning styles, making it challenging to learn a unified predictive model. Moreover, agentic systems differ significantly across tasks, domains, and toolsets, resulting in diverse and complex workflow configurations that are difficult to model uniformly (Xu et al., 2024; Qiao et al., 2025).

Scarcity of Labeled Data. The availability of labeled data for training effective prediction models is severely limited due to the prohibitive cost of generating performance labels through exhaustive validation. Constructing a large, diverse set of labeled workflows with known execution outcomes is particularly expensive, creating a data bottleneck for supervised learning approaches. Moreover, gathering large-scale, high-quality labels for agentic workflows (e.g., success rates and execution outcomes) is often infeasible, further limiting the amount of supervised training data available for learning accurate predictors.

To tackle these challenges, we present **Agentic Predictor**, a multi-view encoder framework for performance prediction in LLM-based agentic workflows. To address workflow heterogeneity, Agentic Predictor uses *multi-view workflow encoders* that jointly model complementary signals—structural (e.g., agent topology), behavioral (e.g., tool usage), and semantic (e.g., prompts)—capturing the diverse, task-dependent characteristics of workflow configurations. To mitigate label scarcity, we introduce *cross-domain unsupervised pretraining*, denoted Agentic Predictor+, which leverages abundant unlabeled workflows from related domains. We pretrain the multi-view encoders with contrastive and reconstruction objectives, then fine-tune on limited labeled data, yielding robust and transferable representations for prediction. The **main contributions** of this paper are as follows.

- We devise novel multi-view encoders and cross-domain unsupervised pretraining that jointly capture the heterogeneous facets of LLM-based agentic workflows, yielding higher predictive performance, better generalization, and effective predictor training under limited labels.
- We introduce Agentic Predictor, unifying these components for the underexplored problem of performance prediction in heterogeneous, label-scarce LLM-based agentic workflows, thereby reducing trial-and-error costs and accelerating development.
- We empirically demonstrate that Agentic Predictor yields substantial improvements of up to **12.12%** in prediction accuracy and **15.16%** in utility metrics over strong baselines across three domains.

2 Related Work

Automated Generation of Agentic Workflows. Recent advancements (Xi et al., 2025; Ke et al., 2025; Gridach et al., 2025; Plaat et al., 2025) in agentic workflows have led to the development of various frameworks aimed at enhancing multi-agent collaboration for complex tasks (Guo et al., 2024; Trirat et al., 2025; Niu et al., 2025; Trirat & Lee, 2025). MetaGPT (Hong et al., 2024) and ChatDev (Qian et al., 2024) use predefined multi-agent structures to address coding challenges, while AgentVerse (Chen et al., 2024) introduces iterative collaboration where agents discuss, execute, and evaluate tasks. LLM-Debate (Du et al., 2024) employs multiple expert agents that engage in debates over several rounds to derive final answers. However, these systems often rely on static configurations, which limits their adaptability to diverse queries across different tasks and domains.

To optimize agentic workflows, GPTSwarm (Zhuge et al., 2024) and G-Designer (Zhang et al., 2024) apply variants of the REINFORCE algorithm to optimize workflow structures represented as directed acyclic graphs (DAGs), while DyLAN (Liu et al., 2024b) dynamically selects agents based on task requirements. ADAS (Hu et al., 2025a) and AFlow (Zhang et al., 2025a) further leverage powerful LLMs (e.g., Claude-3.5-Sonnet and GPT-4) to iteratively generate task-specific multi-agent systems. Similarly, AgentSquare (Shang et al., 2025) proposes a modular design space for automatic LLM agent search, enhancing adaptability to novel tasks. Despite their effectiveness, these methods typically require numerous LLM calls, resulting in significant computational and financial overheads, making them less practical for real-world applications.

Table 1: Comparison between ours and existing frameworks for prediction-based workflow generation.

Framework	Multi-View Representation	Unsupervised Pretraining	Lightweight Predictor	Search Agnostic
MAS-GPT (Ye et al., 2025)	×	×	×	×
FLORA-Bench (Zhang et al., 2025b)	×	×	✓	✓
Agentic Predictor *(Ours)*	✓	✓	✓	✓

Rather than manually designing a fixed workflow (Qian et al., 2024; Chen et al., 2024; Du et al., 2024) or paying repeated inference costs to synthesize one per query (Zhuge et al., 2024; Liu et al., 2024b), Agentic Predictor presents a lightweight performance predictor to rapidly estimate the quality of candidate agentic workflows, enabling broad exploration without exhaustive evaluations. Among recent efforts, FLORA-Bench (Zhang et al., 2025b) advocates GNN-based predictors and releases a benchmark that models workflows as a single-view graph where prompts are node features. A complementary direction, MAS-GPT (Ye et al., 2025), fine-tunes LLMs to directly generate workflows in a single call. **In contrast to these directions**, Agentic Predictor differs in three respects: *representation* (multi-view encoding of agent topology, code, and system prompts vs. single-view graphs), *learning* (cross-domain unsupervised pretraining to mitigate label scarcity, rather than no pretraining recipe or supervised LLM fine-tuning), and *efficiency* (a compact predictor for fast evaluation without repeated LLM calls). Table 1 summarizes these distinctions.

Performance Predictors for NAS. Neural architecture search (NAS) has spurred the development of performance predictors that aim to reduce the significant computational cost of evaluating candidate architectures. PRE-NAS (Peng et al., 2022) employs a predictor-assisted evolutionary strategy to estimate model performance, thereby alleviating the need for exhaustive training. BRP-NAS (Dudziak et al., 2020) integrates graph convolutional networks to forecast hardware-aware performance metrics, improving the practicality of NAS under resource constraints. CAP (Ji et al., 2024) introduces a context-aware neural predictor, leveraging self-supervised learning to generate expressive and generalizable representations of architectures, thus enabling more effective search space exploration. FlowerFormer (Hwang et al., 2024) advances architecture encoding through a flow-aware graph transformer, yielding improved prediction accuracy. A unifying trend among these methods is the emphasis on learning more *informative representations* to guide the search process. Building on this insight, we propose the Agentic Predictor framework, which approaches performance prediction from a *representation-centric* perspective. By incorporating multi-view representations conditioned on workflow configurations, Agentic Predictor facilitates accurate performance estimation and efficient exploration of the agentic workflow space.

3 Methodology: Agentic Predictor

3.1 Problem Formulation

Let an agentic workflow be denoted as $\mathcal{W} = \{\mathcal{V}, \mathcal{E}, \mathcal{P}, \mathcal{C}\}$, where $\mathcal{V} = \{v_i\}_{i=1}^{N}$ represents the set of N agents, $\mathcal{E}$ denotes the set of edges defining the connections between agents, and $\mathcal{P} = \{p_i\}_{i=1}^{N}$ denotes the system prompts for each agent i. $\mathcal{C}$ represents the complete code specifying the logic and structure of the workflow. Thus, the workflow $\mathcal{W}$ is represented as a directed acyclic graph (DAG).

Given a task description T, the workflow $\mathcal{W}$ autonomously executes agents in topological order, where the i-th agent receives the task description T along with the outputs y from its predecessor agents. Formally, the input to agent i is defined as $\mathcal{X}_i = \{T\} \cup \{y_j : v_j \in \mathcal{N}_i^{(\text{in})}\}$, where $\mathcal{N}_i^{(\text{in})}$ denotes the set of predecessor agents of agent i, and y_j is the output of agent j. The output y_i of agent i is generated by querying an LLM: $y_i = \text{LLM}(\mathcal{X}_i, p_i)$. After executing all agents, the final response of the agentic workflow is defined as $r = f_{\text{LLM}}(\mathcal{W}, T)$, where f_{LLM} represents the overall execution process of the given LLM. Generally, this process is repeated for the evaluation of r, which incurs significant computational and financial overhead.

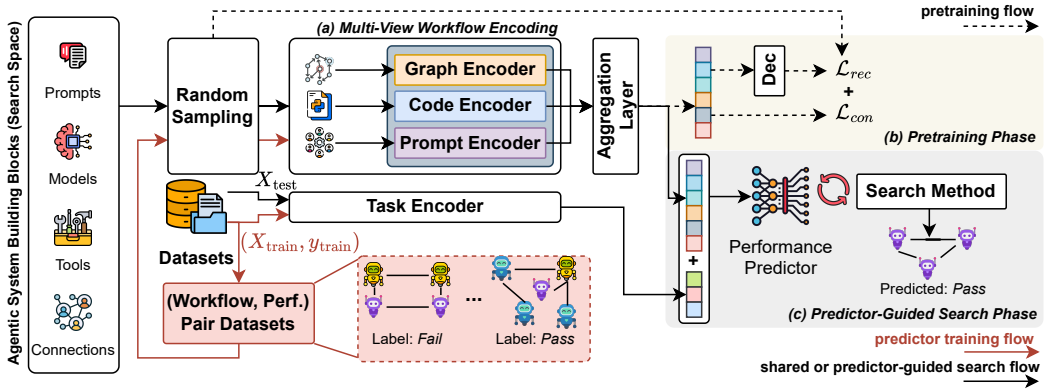

Figure 2: Overview of our Agentic Predictor framework. A **(a) multi-view workflow encoder** is designed to encode a set of agentic workflows from graph, code, and prompt aspects into unified representations, which serve as features for training the predictor. In the **(b) pretraining phase**, the encoder learns these representations on unlabeled workflows spanning diverse tasks and domains, using cross-domain unsupervised pretraining objectives. In the **(c) predictor-guided search phase**, a performance predictor is trained on a small (workflow configuration, performance) dataset to classify configurations as pass or fail, and subsequently guides the search toward promising configurations.

In contrast, this paper aims to design a predictive model $\mathcal{M}$ that efficiently estimates the final performance of an agentic workflow $\mathcal{W}$ on a given task description T, without requiring costly LLM invocations. Therefore, we treat the workflow $\mathcal{W}$ and task description T as inputs to the predictor $\mathcal{M}$, which outputs the estimated performance $\hat{e}$. Formally, $\hat{e} = \mathcal{M}_\Theta(\mathcal{W}, T)$, where Θ denotes the learnable parameters of the performance predictor.

Learning Objective. Given the workflow $\mathcal{W}$, task description (or query) T, and performance predictor $\mathcal{M}_\Theta$ parameterized by Θ, we aim to find the optimal Θ that minimizes the error between the estimated performance $\hat{e}$ and the ground-truth performance e. Formally, we solve

$$\min_{\Theta} \mathbb{E}_{(\mathcal{W},T)}[\mathcal{L}(e, \hat{e})], \tag{1}$$

where $\mathcal{L}(\cdot, \cdot)$ is a loss function that quantifies the discrepancy between the ground truth and the predicted performance. $\mathcal{L}$ can be either the cross-entropy loss or the mean squared error loss, depending on whether the prediction task is formulated as a classification or regression problem.

3.2 Framework Overview

We present an overview of our Agentic Predictor framework in Figure 2. First, the multi-view workflow encoder integrates key aspects of an agentic workflow—graph structures $(\mathcal{V}, \mathcal{E})$, code implementations $\mathcal{C}$, and system prompts $\mathcal{P}$—into a unified representation $\mathcal{F}$. Integration is achieved via modality-specific encoders followed by an aggregation layer that consolidates features across modalities. Second, when labeled instances are scarce, we refine these representations with unsupervised objectives, reconstruction and contrastive learning, to improve generalization and adaptability across diverse tasks and configurations. Third, a dedicated performance predictor $\mathcal{M}_\Theta$ is trained on a labeled set (often small) comprising workflow configurations $\mathcal{W}$, task descriptions T, and observed performance outcomes e. Finally, with the trained predictor, we perform a predictor-guided search that efficiently ranks and selects promising workflow configurations without incurring expensive LLM calls. Because Agentic Predictor is search-agnostic, we deliberately do not commit to a specific search algorithm within the framework.

3.3 Multi-View Workflow Encoding

Motivated by recent findings in the NAS literature (White et al., 2020; Akhauri & Abdelfattah, 2024; Trirat & Lee, 2024), which show that architecture representations strongly influence predictor performance, we argue for expressive, comprehensive representations tailored to agentic workflows. Because agentic workflows differ fundamentally from traditional neural architectures, conventional

graph-based encodings alone are insufficient. Although DAGs naturally capture explicit inter-agent communication and dependencies, they omit crucial implicit signals such as tool-usage patterns, code structure, computational complexity, and the nuanced semantics present in agent prompts. To address these limitations, we propose a multi-view encoding scheme that integrates complementary representations at multiple granularities, with each view capturing distinct yet essential aspects of LLM-based agentic workflows.

- **Graph View** explicitly models structural dependencies and direct interactions among agents, emphasizing inter-agent communication channels. We denote the graph view as $\mathcal{G} = (\mathcal{V}, \mathcal{E})$.
- **Code View** implicitly encodes program-level semantics, control and logical sequence, computational complexity, and patterns of tool usage inherent in workflow implementations $\mathcal{C}$.
- **Prompt View** provides semantic embeddings that capture agent roles, behavioral specifications, and broader contextual guidance embedded within system and instruction prompts $\mathcal{P}$.

Our rationale for adopting this multi-view framework is that aggregating heterogeneous information sources reduces representation bias, thereby improving both robustness and predictive accuracy.

3.3.1 Encoder Networks

We now detail the components of our proposed multi-view workflow encoding method for performance prediction in agentic workflows using neural networks. Let $\mathrm{Enc}(\cdot)$ denote an encoder function that maps a candidate workflow—composed of $(\mathcal{G}, \mathcal{C}, \mathcal{P})$—into d-dimensional Euclidean space, i.e., $\mathrm{Enc}(\cdot) : (\mathcal{G}, \mathcal{C}, \mathcal{P}) \to \mathbb{R}^d$. Given the heterogeneous nature of workflow configurations, we design three specialized encoder networks, each responsible for learning a representation corresponding to a distinct view. These view-specific representations are then aggregated into a shared latent space, denoted by $\mathbf{Z} = \mathrm{Enc}(\mathcal{G}, \mathcal{C}, \mathcal{P})$, where $\mathbf{Z} \in \mathbb{R}^d$. This continuous latent representation is used to train the performance predictor $\mathcal{M}_\Theta$ (see §3.5). The individual encoders for each view are integrated into a unified architecture as described below.

Graph Encoder. Following Zhang et al. (2025b), we employ graph neural network (GNN) layers to encode graph-based representations. The workflow is modeled as a DAG in which each edge encodes a unidirectional message channel. Rather than relying on a single graph, we adopt a *multi-graph* approach that integrates node features from multiple views, including agent-specific definitions and function-call implementations at each agent node. Concretely, we first obtain view-specific node embeddings $\mathbf{H}_{\text{prompt}} = \mathrm{GNN}(\mathcal{G}_{\text{prompt}})$, $\mathbf{H}_{\text{code}} = \mathrm{GNN}(\mathcal{G}_{\text{code}})$, and $\mathbf{H}_{\text{operator}} = \mathrm{GNN}(\mathcal{G}_{\text{operator}})$ in $\mathbb{R}^{N \times d}$, stack them along a view dimension to form $\mathbf{X} \in \mathbb{R}^{N \times V \times d}$ with $V = 3$, and apply a cross-view self-attention block with residual connection and layer normalization $\hat{\mathbf{X}} = \mathrm{LN}(\mathrm{MHA}(\mathbf{X}, \mathbf{X}, \mathbf{X}) + \mathbf{X})$, where MHA is multi-head attention applied across views for each node (the sequence axis is the view axis; topology is unchanged). Next, a view-attention pooling module computes per-node attention weights with a L-layer multi-layer perceptron (MLP) and $\tanh$ nonlinearity, followed by a softmax over views, and produces a weighted sum across views $\mathbf{H} = \mathrm{ViewAttnPool}(\hat{\mathbf{X}}) \in \mathbb{R}^{N \times d}$. Finally, a graph readout G_{pool} aggregates node embeddings into a single graph representation, $\mathbf{Z}_\mathcal{G} = G_{\text{pool}}(\mathbf{H}) = G_{\text{pool}}(\mathrm{ViewAttnPool}(\mathrm{CrossGraphAttn}(\mathbf{X})))$, which preserves edge directionality from the upstream GNN while capturing cross-view contextual dependencies at the node level before graph-level summarization. Here, $\mathrm{CrossGraphAttn}$ enriches each node with multi-view contextual dependencies, while $\mathrm{ViewAttnPool}$ highlights which views are most informative.

Code Encoder. To model code semantics, we adopt workflow-level embeddings. We use an L-layer MLP to extract latent semantic features, enabling the model to learn intricate computational logic and tool interactions at a global level. The code representation is computed as $\mathbf{Z}_\mathcal{C} = \mathrm{MLP}_\mathcal{C}(\mathcal{C})$.

Prompt Encoder. Unlike FLOW-GNN (Zhang et al., 2025b), which encodes agent prompts as node-level features, we use another L-layer MLP to encode the *entire* workflow instruction prompts holistically. This approach captures role descriptions, behavioral intents, and global context—resulting in richer and more semantically informed representations. The prompt encoding is $\mathbf{Z}_\mathcal{P} = \mathrm{MLP}_\mathcal{P}(\mathcal{P})$.

Aggregation Layer. The representations from the graph, code, and prompt encoders—$\mathbf{Z}_\mathcal{G}$, $\mathbf{Z}_\mathcal{C}$, and $\mathbf{Z}_\mathcal{P}$—are concatenated and passed through a final MLP layer. This aggregation mechanism adaptively integrates information across all views, enabling the model to emphasize the most contextually relevant aspects. The final output of the encoder $\mathrm{Enc}(\cdot)$ is computed as $\mathbf{Z} = \mathrm{MLP}([\mathbf{Z}_\mathcal{G}, \mathbf{Z}_\mathcal{C}, \mathbf{Z}_\mathcal{P}])$.

These encoders learn not only from different workflow perspectives but also at varying levels of granularity, specifically, at the graph level for agent interactions, the code level for logical structures, and the prompt level for agent-specific instructions.

3.3.2 DECODER NETWORKS

The decoder is a generative module that reconstructs $\hat{\mathcal{G}}$, $\hat{\mathcal{C}}$, and $\hat{\mathcal{P}}$ from the latent variables $\mathbf{Z}$ to encourage learning generalizable representations of agentic workflows. It consists of a stack of MLP layers. For simplicity, the decoder outputs the modality-specific *input embedding* vectors of $\mathcal{G}$, $\mathcal{C}$, and $\mathcal{P}$. Accordingly, we parameterize $\mathrm{Dec}(\cdot)$ with an MLP and define $\hat{\mathcal{G}} = \mathrm{MLP}(\mathbf{Z}_{\mathcal{G}})$, $\hat{\mathcal{C}} = \mathrm{MLP}(\mathbf{Z}_{\mathcal{C}})$, and $\hat{\mathcal{P}} = \mathrm{MLP}(\mathbf{Z}_{\mathcal{P}})$. This decoder is used only during pretraining for self-supervised reconstruction of modality-specific embeddings from $\mathbf{Z}$ and is not part of the encoding path at inference time.

3.4 CROSS-DOMAIN UNSUPERVISED PRETRAINING

In real-world scenarios, labeled performance data for agentic workflows are scarce due to costly evaluation. To enable data-efficient training without label leakage, we *optionally* adopt a two-phase strategy. Rather than directly supervising the encoder with performance labels, we first perform cross-domain unsupervised pretraining to obtain rich and generalizable workflow representations $\mathbf{Z}$. No performance labels (e.g., success/failure) are used in this stage. The resulting representations improve sample efficiency for downstream prediction, in line with observations in NAS (White et al., 2020; Yan et al., 2020; 2021; Akhauri & Abdelfattah, 2024; Trirat & Lee, 2024). When sufficiently many labels are available, direct supervised learning of the predictor remains feasible.

Multi-Task Pretraining. We train the multi-view encoder on M unlabeled workflow configurations by minimizing a combined loss comprising reconstruction and contrastive objectives: $\mathcal{L}_{rec} = \frac{1}{M}\sum_{i=1}^{M} \|\mathcal{G}_i - \hat{\mathcal{G}}_i\|^2 + \|\mathcal{C}_i - \hat{\mathcal{C}}_i\|^2 + \|\mathcal{P}_i - \hat{\mathcal{P}}_i\|^2$ and $\mathcal{L}_{con} = \frac{1}{M}\sum_{i=1}^{M} -\log \frac{\exp(\mathrm{sim}(\mathbf{Z}_i, \mathbf{Z}_j^+)/\tau)}{\sum_{k=1}^{M} \exp(\mathrm{sim}(\mathbf{Z}_i, \mathbf{Z}_k)/\tau)}$. Here, $\mathcal{G}_i, \mathcal{C}_i, \mathcal{P}_i$ denote the input graph, code, and prompt embeddings, respectively, while $\hat{\cdot}$ denotes reconstructions via modality-specific decoders. Notably, the graph branch reconstructs its own embedding target with a stop-gradient, whereas code and prompt/text are reconstructed in input space. The contrastive loss is instantiated *cross-modally* with in-batch sampling. For each configuration i, positives $(\mathbf{Z}_i, \mathbf{Z}_j^+)$ are the index-aligned embeddings of the configuration across two different views (e.g., $\mathcal{G}_i$ with $\mathcal{C}_i$), while negatives are all other configurations within the batch. We symmetrize the objective by swapping anchor/target and average it over the three view pairs $(\mathcal{G}, \mathcal{C})$, $(\mathcal{G}, \mathcal{P})$, and $(\mathcal{C}, \mathcal{P})$. This learning objective encourages the encoder to capture structure- and content-aware signals without observing performance outcomes. Thus, the total loss function is $\mathcal{L}_{enc} = \mathcal{L}_{rec} + \mathcal{L}_{con}$.

3.5 PERFORMANCE PREDICTOR

Following the unsupervised pretraining of the multi-view encoder, we introduce a lightweight performance predictor to guide exploration of the large agentic workflow space. This phase enables efficient identification of high-performing configurations with minimal supervision, using only a small set of labeled workflow–performance pairs. As shown in Figure 2(c), our predictor operates on learned workflow embeddings, enriched with task-specific context, to form a joint representation $\mathcal{F}$ used for performance prediction and downstream search.

Task Encoder. To capture task-specific characteristics, we incorporate a Task Encoder that generates high-level semantic embeddings from natural-language task descriptions. These embeddings, derived from pretrained language models (e.g., T5 or BERT), provide global context that helps differentiate tasks with similar surface form but distinct functional requirements. The task embedding is concatenated with the multi-view workflow representation, forming $\mathcal{F} = [\mathbf{Z}, \mathbf{T}]$, where $\mathbf{Z}$ is the encoded workflow and $\mathbf{T}$ is the task embedding. For workflow content itself (prompts and code), we pair this with lightweight, domain-specific encoders within the multi-view backbone to balance representational capacity with efficiency. This separation of modalities followed by fusion captures complementary compositional and contextual signals and supports generalization across heterogeneous tasks with varying operational goals and constraints.

The performance predictor is a lightweight prediction head $\mathcal{M}_\Theta$ (e.g., an MLP) trained on a limited set of labeled data $(X_{\text{train}}, y_{\text{train}})$, where each X_{train} corresponds to $\mathcal{F}$ and y_{train} is the

performance label (e.g., binary success/failure or a scalar score). We instantiate the objective to match the label type. For binary labels, we use a binary cross-entropy loss, i.e., $\mathcal{L}_{\text{pred}} = -\frac{1}{N}\sum_{i=1}^{N}[e_i \log \hat{e}_i + (1-e_i)\log(1-\hat{e}_i)]$, where $\hat{e}_i$ is the predicted success probability. For numeric labels, we can use mean squared error, i.e., $\mathcal{L}_{\text{pred}} = \frac{1}{N}\sum_{i=1}^{N}(s_i - \hat{s}_i)^2$. By operating on semantically rich pretrained embeddings, the predictor attains strong accuracy in the low-data regime, enabling label-efficient search.

Integration with Workflow Optimization. With the trained predictor in place, we can perform predictor-guided search to efficiently explore the workflow configuration space. Rather than evaluating each configuration via full execution, we embed candidates into their joint representations $\mathcal{F}$ and score them using the predictor. The top-scoring candidates are selected for evaluation. This substantially reduces computational cost by focusing on the most promising regions of the search space. A simple yet effective instantiation of this strategy uses random search to sample K workflow candidates from the full configuration space, and then ranks them using the learned predictor. We select the top-k configurations, averaged across samples in the benchmark, for evaluation. This predictor-as-ranker setup transforms random search into a label-efficient guided procedure without requiring complex heuristics. Since our main contribution is the performance predictor rather than the optimization algorithm, we focus evaluation on prediction accuracy and ranking quality (i.e., workflow utility) in the following section. Additional results on workflow optimization appear in §B.6.

4 Experiments

We conduct a comprehensive evaluation of the proposed Agentic Predictor framework from multiple perspectives, guided by the following questions: **(Q1)** How does Agentic Predictor perform as a predictor of agentic workflow performance compared to relevant baselines? **(Q2)** How do different design choices and configurations of Agentic Predictor affect its predictive accuracy? **(Q3)** Is the pretraining phase helpful for maintaining prediction quality under varying numbers of labels?

4.1 Setup

Benchmarks. To evaluate performance predictors for agentic workflows, we use FLORA-Bench (Zhang et al., 2025b), the only publicly available benchmark (to the best of our knowledge) that enumerates diverse workflows across multiple domains and LLM backbones. It spans five datasets covering three core areas: code generation (HumanEval (Chen et al., 2021), MBPP (Austin et al., 2021)), mathematical problem solving (GSM8K (Cobbe et al., 2021), MATH (Hendrycks et al., 2021b)), and general reasoning (MMLU (Hendrycks et al., 2021a)). Table 2 summarizes the benchmark. We emphasize structural and procedural diversity over raw difficulty; even for datasets often considered solved by prompting (e.g., GSM8K), predicting success across workflow variants remains nontrivial. For each dataset, we randomly split instances into training (80%), validation (10%), and test (10%) sets.

Table 2: Summary of benchmark statistics.

Domains	Code Generation (GD/AF)	Math (GD/AF)	Reasoning (GD/AF)
# workflows	739 / 38	300 / 42	189 / 30
Avg. # nodes	5.96 / 6.11	6.06 / 5.49	5.97 / 6.58
# tasks	233 / 233	782 / 782	2,400 / 2,400
# samples	30,683 / 7,362	12,561 / 4,059	453,600 / 72,000

Evaluation Metrics. To ensure a fair and consistent comparison, we strictly adhere to the official evaluation protocols specified by the benchmark.

- **Accuracy** quantifies how well a model predicts agentic workflow performance. It is defined as $accuracy = \frac{1}{|\mathcal{D}^{\text{test}}|}\sum_{i}^{|\mathcal{D}^{\text{test}}|}\mathbf{1}(\hat{e}_i = e_i)$, where $|\mathcal{D}^{\text{test}}|$ is the size of the test split, and $\hat{e}_i$ and e_i denote the predicted and ground-truth performance, respectively. $\mathbf{1}(\cdot)$ is the indicator function, which returns 1 if $\hat{e}_i = e_i$, and 0 otherwise.
- **Utility** evaluates the consistency between the workflow rankings predicted by the model and the ground-truth rankings, emphasizing the model's ability to determine the relative order of different workflows. First, we calculate the ground-truth and predicted success rates of a workflow $\mathcal{W}_i$ by averaging e and $\hat{e}$ across all tasks in $\mathcal{D}^{\text{test}}$. Then, we rank the workflows and extract the top-k workflows according to the respective scores, resulting in two ordered sets: $\mathcal{H} = \{\mathcal{W}_i\}_{i=1}^{k}$ and $\hat{\mathcal{H}} = \{\mathcal{W}'_i\}_{i=1}^{k}$. Formally, $utility = \frac{1}{k}\sum_{i=1}^{k}\mathbf{1}(\mathcal{W}'_i \in \mathcal{H})$.

Table 3: Performance comparison between Agentic Predictor and baseline methods. The best and second-best results are highlighted in **bold** and underlined, respectively.

Domain	CodeGD		CodeAF		MathGD		MathAF		ReasonGD		ReasonAF		Average	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
MLP	83.88	76.16	78.02	73.94	63.22	64.13	73.73	69.64	71.54	62.41	78.45	88.48	74.81	72.46
GCN	84.23	79.31	84.35	72.73	64.12	63.03	76.19	66.52	72.22	59.18	87.12	**91.82**	78.04	72.10
GAT	85.14	79.50	84.49	76.46	64.84	62.32	76.44	66.51	72.16	59.44	87.07	89.40	78.36	72.27
GCN-II	83.81	78.45	83.72	77.75	63.56	66.02	75.04	64.33	72.29	59.10	87.28	89.92	77.62	72.60
Graph Transformer	85.24	80.20	84.71	74.09	63.25	64.97	75.45	66.48	72.26	60.92	86.93	90.60	77.97	72.88
Dir-GNN	84.85	79.81	83.45	76.08	63.01	64.68	76.11	67.97	74.25	62.64	86.66	90.07	78.05	73.54
One For All	83.74	75.93	81.05	73.42	63.17	66.65	75.21	69.08	72.29	60.35	82.52	87.64	76.33	72.18
Agentic Predictor	**85.33**	**81.42**	**85.62**	**80.08**	**66.20**	**67.88**	**79.56**	**74.08**	**75.13**	**63.06**	**87.96**	91.47	**79.97**	**76.33**
% Improvement (Up to)	1.90%	7.23%	9.74%	10.11%	5.06%	8.92%	7.91%	15.16%	5.02%	6.70%	12.12%	4.37%	6.90%	5.87%

Baselines. Since there is no direct baseline method specifically designed for performance prediction in agentic systems, we adopt comparison baselines from the benchmark paper. Some of these methods have previously been used as performance predictors for NAS (White et al., 2021). The selected baselines include one naive **MLP** and several strong graph-based models: **GCN** (Kipf & Welling, 2017), **GAT** (Veličković et al., 2018), **GCN-II** (Chen et al., 2020), **Graph Transformer** (Shi et al., 2021), **Dir-GNN** (Rossi et al., 2024) and **One For All** (Liu et al., 2024a).

Implementation Details. For all methods, we follow the same setup as suggested by Zhang et al. (2025b). Specifically, we use a 2-layer backbone with a hidden dimension of 512, set dropout to 0.5, and use a batch size of 512. Models are optimized with the Adam optimizer (Kingma & Ba, 2014) using a learning rate of 1×10^{-4} and weight decay of 5×10^{-4}. Training is conducted for 200 epochs on a single NVIDIA A100-SXM4-80GB GPU, and the best checkpoint is selected by the highest accuracy on the validation subset. Our framework is encoder-agnostic by design. To isolate the contribution of our multi-view formulation and avoid confounding factors, we deliberately use the same text encoder `all-MiniLM-L6-v2` (Wang et al., 2020) as in FLORA-Bench (Zhang et al., 2025b). In addition, we use `CodeRankEmbed` (Suresh et al., 2025) for code embeddings.

4.2 Main Results

We report all experimental results for agentic workflow performance prediction averaged from three runs on different random seeds in the same dataset.

Prediction Accuracy (Q1). We report averaged performance scores in Table 3. Our proposed framework, Agentic Predictor, consistently outperforms all baseline methods across the three task domains. In terms of accuracy, Agentic Predictor achieves top results in each domain—85.62%, 79.56%, and 87.96%, respectively—resulting in the highest overall average accuracy of 79.97%. This reflects an improvement of up to 6.90% over the comparison baselines. Utility scores exhibit a similar trend. Agentic Predictor attains the highest utility in code generation (81.42%) and math problem solving (74.08%), and a near-best score in reasoning tasks (91.47%), second only to GCN (91.82%). On average, it achieves the highest utility score of 76.33%, marking an improvement of up to 5.87% over the baselines. These results validate that Agentic Predictor not only enhances predictive accuracy but also improves downstream utility in diverse agentic workflows, demonstrating its robustness and generalizability across task types. The consistent performance gains underscore the benefits of leveraging multi-view encoding across heterogeneous agentic workflows.

4.3 Additional Analyses

Ablation Study (Q2). To substantiate our contributions on specific design of multi-view workflow encoding in Agentic Predictor, we conduct ablation study on two main components using the AFlow subset: multi-view encoder and multi-graph encoding techniques. According to the results in Table 4 and Table 5, we find that incorporating all three input views—code, graph, and text—results in the best overall performance across all tasks. Specifically, the full model configuration achieves the highest average accuracy (84.38%) and utility (81.88%), underscoring the complementary value of each modality. Notably, the removal of any single view leads to a consistent drop in performance, demonstrating the synergistic role of multimodal inputs in prediction capabilities of Agentic Predictor.

Furthermore, results in Table 5 reveal the significance of multi-graph encoding. When multiple graphs are used instead of a single graph, the model shows a clear performance improvement, particularly in code generation (accuracy improves from 82.58% to 84.44%) and reasoning tasks (utility rises from

Table 4: Results of ablation study on different input view variations.

Variations			Code Generation		Math Problem		Common Reasoning		Average	
Code	Graph	Text	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
✓			82.04	75.66	75.70	68.52	83.19	**91.51**	80.31	78.56
	✓		84.44	77.22	79.14	67.99	87.00	91.03	83.53	78.75
		✓	79.87	70.34	76.60	68.45	68.06	71.04	74.84	69.94
✓	✓		83.72	73.97	75.86	70.18	86.88	86.14	82.15	76.76
✓		✓	82.27	77.28	76.03	66.66	54.17	53.21	70.82	65.72
	✓	✓	82.45	74.64	75.70	67.83	69.47	70.55	75.87	71.01
✓	✓	✓	**85.62**	**80.08**	**79.56**	**74.08**	**87.96**	91.47	**84.38**	**81.88**

Table 5: Results of ablation study on different input graph variations.

Variations		Code Generation		Math Problem		Commong Reasoning		Average	
Single View	Multi View	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
✓		82.58	**78.52**	78.57	67.51	86.95	90.14	82.70	78.72
	✓	**84.44**	77.22	**79.14**	**67.99**	**87.00**	**91.03**	**83.53**	**78.75**

90.14% to 91.03%). This supports our hypothesis that different graph perspectives enrich structural context and lead to more robust representations. Together, these findings validate the architectural choices in Agentic Predictor, demonstrating that both multi-view and multi-graph designs are integral to its superior performance.

Effects of Pretraining Phase (Q3). Since acquiring a large amount of ground-truth labels from agentic workflows is expensive, we examine whether cross-domain unsupervised pretraining (denoted as Agentic Predictor+) benefits settings where labeled instances are limited. We vary the label ratio from 0.1 to 0.5, selecting labeled samples from the training split of all datasets in the benchmark. We pretrain the proposed multi-view encoder with a batch size of 32 for 20 epochs. On average, the results shown in Figure 3 indicate that Agentic Predictor+ consistently outperforms all baseline models across all label ratios, demonstrating the effectiveness of our unsupervised pretraining strategy. The gains are especially pronounced in low-label regimes: at a 0.1 label ratio, Agentic Predictor+ maintains an accuracy above 73%, while other models drop closer to 70%. These findings underscore the importance of leveraging cross-domain structure through pretraining for generalizable workflow performance prediction, especially when direct supervision is limited.

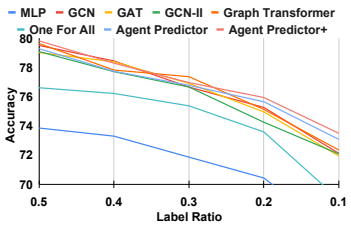

Figure 3: Accuracy comparison between Agentic Predictor and the baselines across varying label ratios.

More experimental results on different LLM backbones, various GNN backbones, LLM classifier comparison, and out-of-distribution test are reported in Tables 6 7, 8, 9, 10 and 11, respectively. An additional evaluation of performance predictors used as a reward function for agentic workflow optimization, and case study findings are also provided in §B.6 and §C.

5 Conclusions

This paper introduces Agentic Predictor, a novel framework for efficient prediction of agentic workflow performance that leverages a multi-view predictive approach. By integrating multi-view graph structures, code semantics, and prompt embeddings into a unified representation, Agentic Predictor captures the diverse characteristics of agentic systems. Moreover, it employs cross-domain unsupervised pretraining to mitigate the challenge of limited labeled data, thereby enhancing generalization across varied tasks. Through comprehensive experiments spanning three domains, Agentic Predictor consistently outperforms strong baselines in predictive accuracy and workflow utility.

Limitations and Future Work. While Agentic Predictor exhibits strong performance, it has certain limitations. The current predictor focuses on binary success metrics, constrained by the available benchmark, which may overlook more nuanced aspects of workflow behavior. Additionally, adapting to highly specialized domains may still require some labeled data. Future work includes expanding to multi-objective optimization (e.g., balancing accuracy and cost), incorporating richer views such as temporal traces and user feedback, and exploring human-in-the-loop workflows for real-time refinement. These directions aim to make Agentic Predictor more generalizable and interactive in complex, real-world settings.

Reproducibility Statement

We facilitate reproducibility by providing an anonymous repository with all source code at https://anonymous.4open.science/r/agent-predictor. Algorithm 1 provides the complete pseudocode of the proposed framework. For experimental consistency, the random seed for each run is 2^r, where r is the running index starting from 0.

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A Pseudocode of Agentic Predictor

We present the pseudocode of the proposed Agentic Predictor framework in Algorithm 1 below.

Algorithm 1 Overall Procedure of Agentic Predictor

Initialization: Multi-View Encoder $\mathrm{Enc}(\cdot)$ and Performance Predictor Model $\mathcal{M}_\Theta$
Input: User Instruction (or Task Description) $T \in \mathcal{T}$ and Training Data D^{train}

▷ Cross-Domain Unsupervised Pretraining (§3.4, *Optional*)
Sample M unlabeled workflows $\mathcal{W}_1, \mathcal{W}_2, ..., \mathcal{W}_M$ from multiple domains
for each $\mathcal{W}_i = (\mathcal{G}_i, \mathcal{C}_i, \mathcal{P}_i)$ **do**
  $\mathbf{Z}_i \leftarrow \mathrm{Enc}(\mathcal{G}_i, \mathcal{C}_i, \mathcal{P}_i)$ ▷ Encode multiview graph, code, and prompts
  $(\hat{\mathcal{G}}_i, \hat{\mathcal{C}}_i, \hat{\mathcal{P}}_i) \leftarrow \mathrm{Dec}(\mathbf{Z}_i)$ ▷ Decode reconstructions
end for
$\mathcal{L}_{enc} = \mathcal{L}_{rec} + \mathcal{L}_{con}$ ▷ Minimize total pretraining loss
▷ Training Performance Predictor (§3.5)
Obtain (small) labeled dataset $\{(\mathcal{W}_j, T_j, e_j)\}_{j=1}^{N}$ from D^{train}
for each $(\mathcal{W}_j, T_j)$ **do**
  $\mathbf{Z}_j \leftarrow \mathrm{Enc}(\mathcal{W}_j)$ ▷ Encode workflow
  $\mathbf{T}_j \leftarrow \mathrm{TaskEncoder}(T_j)$ ▷ Encode task description
  $\mathcal{F}_j \leftarrow \mathrm{MLP}([\mathbf{Z}_j, \mathbf{T}_j])$ ▷ Form joint representation
  $\hat{e}_j \leftarrow \mathcal{M}_\Theta(\mathcal{F}_j)$ ▷ Predict performance
end for
Train $\mathcal{M}_\Theta$ using binary cross-entropy loss $\mathcal{L}_{pred}(e_j, \hat{e}_j)$, where $\{e_j\}_{j=1}^{N}$
▷ Predictor-Guided Candidate Ranking
Sample K candidate workflows $\{\mathcal{W}_k\}_{k=1}^{K}$
for each $\mathcal{W}_k$ **do**
  $\mathbf{Z}_k \leftarrow \mathrm{Enc}(\mathcal{W}_k)$ ▷ Encode workflow
  $\mathcal{F}_k \leftarrow \mathrm{MLP}([\mathbf{Z}_k, \mathbf{T}])$ ▷ Encode task
  $\hat{e}_k \leftarrow \mathcal{M}_\Theta(\mathcal{F}_k)$ ▷ Predict score
end for
Rank all $\{\mathcal{W}_k\}$ by predicted scores $\hat{e}_k$
return top-k ranked workflows for final evaluation

B Additional Experimental Results

This section provides complementary studies that further characterize our approach: robustness when the agent-controller LLM backbone varies (§B.1); an ablation over multiple GNN backbones (§B.2); a comparison to few-shot LLM predictors (§B.3); and out-of-distribution (OOD) generalization evaluations (§B.4).

B.1 Performance on Different LLM Backbones

As show in Table 6, we assess whether predictor performance is robust when the agentic workflows are driven by different LLMs. Concretely, we replicate our evaluation while swapping the controller LLM among GPT-4o-mini, DeepSeek, Qwen 7B, and Mistral 7B, holding the training data construction, multi-view encoder, and evaluation protocol fixed. Except for the Mistral 7B case, Agentic Predictor exhibits stable performance and preserves the relative ranking of workflows across these backbones, indicating that it captures structural and behavioral regularities of agentic programs rather than idiosyncrasies of any single LLM.

B.2 Performance on Different GNN Backbones

Our main experiments use a 2-layer GCN (hidden size 512) following the standard setup in FLORA-Bench (Zhang et al., 2025b), enabling a controlled comparison to baseline predictors. To test architecture sensitivity, we conduct an ablation over five diverse GNN backbones—GCN, GAT, GCN-II, Graph Transformer, and Dir-GNN—while keeping the prompt and code views fixed. As

Table 6: Results on different backbones driven agentic workflows.

Domain	GPT-4o-mini		DeepSeek		Qwen 7B		Mistral 7B	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
MLP	83.88	76.16	85.89	71.72	84.25	80.52	89.23	85.07
GCN	82.94	80.40	86.56	75.69	86.71	84.48	92.58	88.48
GAT	83.03	80.25	84.42	75.18	86.98	84.26	92.62	88.72
GCN-II	82.81	79.48	84.34	75.68	85.17	82.71	90.94	85.89
Graph Transformer	83.42	79.83	86.34	73.06	86.76	84.65	**92.80**	**88.87**
Dir-GNN	84.85	79.81	85.38	71.27	86.36	84.50	91.87	88.47
One For All	81.24	71.92	84.73	73.23	84.51	80.42	89.13	85.06
Agentic Predictor	**85.33**	**81.42**	**88.39**	**76.64**	**86.99**	**85.02**	92.33	88.69

Table 7: Results on different GNN backbones of Agentic Predictor.

	Code Generation		Math Problem		Common Reasoning		Average	
GNN Backbone	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
GCN	85.62	80.08	79.56	74.08	87.96	91.47	84.38	81.88
GAT	83.74	73.11	75.86	67.03	86.95	87.20	82.19	75.78
GCN-II	84.71	73.83	76.68	68.41	86.76	86.04	82.72	76.09
Graph Transformer	83.22	78.17	76.64	70.03	86.88	89.50	82.25	79.23
Dir-GNN	84.62	79.64	80.26	75.03	87.93	94.77	84.27	83.15

presented in Table 7 All backbones yield comparable predictive accuracy and replicate the same trends, reinforcing that the performance improvements stem from the multi-view encoding and pretraining rather than a specific GNN design. These results support the architecture-agnostic nature of the Agentic Predictor.

B.3 Comparison with LLM Predictors

We compare against few-shot, prompt-based LLM classifiers implemented with a standardized LLM-PP–style template (Jawahar et al., 2023) with 5-shot and temperature set to 0 using GPT-4.1, Claude 4 Sonnet, and Gemini 2.5 Flash. The results in Table 8 are consistent with prior findings on FLORA-Bench (Zhang et al., 2025b) (which evaluated DeepSeek-v3), these prompted LLMs underperform even a simple MLP predictor and substantially trail our graph-based approach. A likely reason is that prompted LLM classifiers do not exploit the structured execution patterns and tool-usage dynamics present in agentic workflows. Beyond accuracy, prompted LLM inference incurs a per-sample monetary and latency cost, whereas our predictor amortizes cost at training time. In our setup, generating predictions for up to 1,000 samples per task with LLM prompting required approximately $300, implying considerably higher expense at full-benchmark scale. By contrast, the learned predictor scales to large candidate sets with constant per-sample computational cost at inference. Overall, while few-shot LLMs provide a useful baseline, they are less effective and less economical for large-scale agent search.

B.4 Out-of-Distribution (OOD) Generalization Performance

We study two factors that enable OOD robustness. First, the multi-view encoder jointly represents workflows via graph, code, and prompt views, all of which are architecture-agnostic. This design allows unseen agents and tools to be incorporated as long as their implementations and textual descriptions are available; the graph encoder embeds novel entities through structural and attribute signals without relying on fixed IDs. Second, cross-domain unsupervised pretraining over diverse unlabeled workflows equips the encoder with priors over common structural and behavioral motifs (e.g., tool invocation patterns and reasoning flows), improving robustness to unseen configurations.

Regarding evaluation, we perform two levels of OOD generalization. *Cross-system generalization:* train on one agentic framework (e.g., AFlow (Zhang et al., 2025a)) and test on another (e.g., G-Designer (Zhang et al., 2024)), following RQ3 in FLORA-Bench (Zhang et al., 2025b). *Unseen task generalization:* train on one set of downstream tasks (e.g., math) and test on disjoint tasks (e.g., coding) not observed during training. As presented in Table 9, Table 10 and Table 11, across both settings, Agentic Predictor maintains strong performance and preserves relative workflow rankings, indicating that it generalizes beyond in-distribution memorization.

Table 8: Comparison between Agentic Predictor and LLM-based few-show classification.

Domain	Code Generation		Math Problem		Common Reasoning		Avg.	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
GPT-4.1 (∼$59)	62.42	57.00	67.08	52.97	59.10	66.79	62.86	58.92
Claude 4 Sonnet (∼$202)	56.72	51.65	64.62	57.32	44.50	41.25	55.28	50.07
Gemini 2.5 Flash (∼$21)	60.52	58.94	51.60	55.21	59.20	63.17	57.10	59.11
Agentic Predictor	**84.40**	**78.84**	**80.10**	**77.61**	**90.40**	**87.67**	**84.97**	**81.37**

Table 9: Results when train on AFlow and test on G-Designer

Domain	Code Generation		Math Problem		Common Reasoning		Average	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
GCN	56.76	54.29	49.64	51.92	61.37	54.13	55.92	53.45
GAT	57.25	56.05	48.29	48.71	57.03	53.12	54.19	52.63
GCN-II	64.16	62.67	48.85	50.56	65.55	52.76	59.52	55.33
Graph Transformer	60.83	58.39	47.73	46.65	55.88	48.87	54.81	51.30
One For All	58.97	53.25	50.60	51.02	63.84	55.22	57.80	53.16
Agentic Predictor	65.02	64.91	53.62	52.83	67.51	57.74	62.05	58.49

B.5 Effects of Pretraining Phase (Full Results)

Since acquiring a large amount of ground-truth labels from agentic workflows is expensive, we examine whether cross-domain unsupervised pretraining (denoted as Agentic Predictor+) benefits settings where labeled instances are limited. We vary the label ratio from 0.1 to 0.5, selecting labeled samples from the training split of all datasets in the benchmark. We pretrain the proposed multi-view encoder with a batch size of 32 for 20 epochs.

Following the average results in the main text, we provide a comprehensive comparison of accuracy (top row) and utility (bottom row) across three task domains—code generation, math problems, and reasoning—under varying label ratios from 0.5 to 0.1 (Figure 4).

Across all settings, our proposed framework, Agentic Predictor, and its pretrained variant, Agentic Predictor+, consistently outperform baseline models, especially in low-resource scenarios. In the code generation domain (Figures 4a, 4e), Agentic Predictor+ achieves superior accuracy and notably higher utility as the label ratio decreases, outperforming all graph-based and non-graph baselines. Similarly, for math problems (Figures 4b, 4f), Agentic Predictor+ maintains a stable accuracy even as labeled data diminishes, while significantly improving utility, indicating better performance in label-scarce conditions. In reasoning tasks (Figures 4c, 4g), although accuracy deltas narrow between models, Agentic Predictor+ sustains strong utility across all label ratios, highlighting its robustness in generalization. When averaged across domains (Figures 4d, 4h), Agentic Predictor+ shows clear advantages in both metrics under limited supervision. The utility improvements are particularly prominent, suggesting that our pretrained encoder captures transferable representations that enhance decision-making, even when fine-tuning data is sparse. These findings validate the efficacy of the unsupervised pretraining phase and highlight the importance of cross-domain datasets for pretraining.

B.6 Workflow Optimization Results

In the main experiments, we demonstrate the feasibility and robustness of predicting agentic workflow performance. However, it remains an open question whether such predictions can effectively contribute to improving efficiency and to what extent they may introduce performance degradation in agentic workflows. To investigate this, we evaluate **(Q4)** *whether using Agentic Predictor as a predictor enhances the optimization of agentic workflows compared to alternative baselines*. Specifically, we measure the performance improvement (or loss) incurred when using performance predictors.

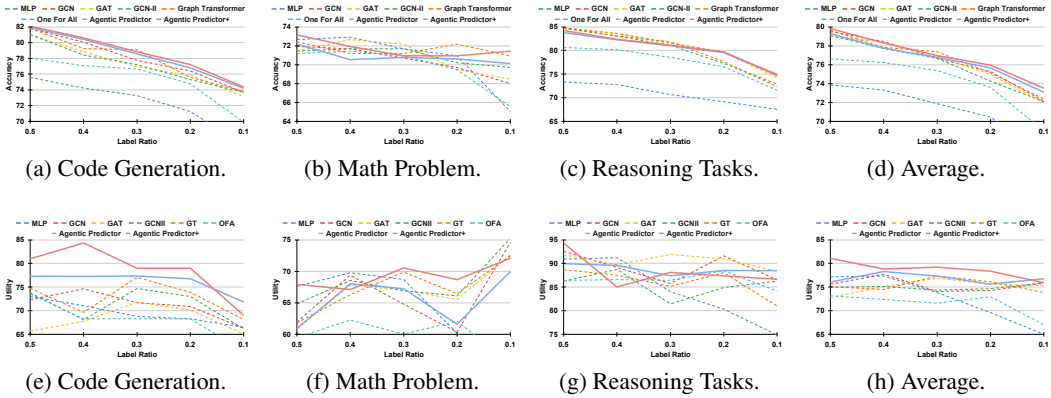
To ensure a fair comparison, we adopt the same experimental setup as Zhang et al. (2025b), which provides a unified platform for optimizing agentic workflows and evaluating their performance. During the optimization process on each benchmark, a predictor is used to estimate the performance of candidate agentic workflows. These predicted performance values are treated as rewards to guide the optimization. Upon completion of the optimization, the quality of the resulting workflows is assessed based on their accuracy score on held-out test tasks.

Table 10: Results when train on G-Designer and test on AFlow

Domain	Code Generation		Math Problem		Common Reasoning		Average	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
GCN	58.21	57.33	67.57	54.63	57.51	53.37	61.10	55.11
GAT	59.29	59.68	66.34	52.70	56.07	50.38	60.57	54.25
GCN-II	58.75	61.17	67.32	52.96	55.93	52.19	60.67	55.44
Graph Transformer	60.52	61.44	58.97	57.49	56.50	54.86	58.66	57.93
One For All	62.01	54.57	58.72	61.23	59.40	54.17	60.04	56.66
Agentic Predictor	60.94	59.75	69.11	63.02	58.56	56.73	62.87	59.83

Table 11: Results on cross-domain OOD test.

Domain	Code-Math		Code-Reason		Math-Reason		Math-Code		Reason-Code		Reason-Math		Average	
Model	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility	Accuracy	Utility
GCN	48.89	54.07	52.61	53.29	49.38	46.69	50.07	48.75	32.56	50.53	33.42	50.57	44.49	50.65
GAT	45.95	49.42	53.71	57.90	46.83	38.90	51.02	47.40	33.79	52.62	33.42	51.10	44.12	49.56
GCN-II	56.02	44.49	53.44	45.93	50.38	47.36	39.48	51.55	38.13	51.35	36.61	57.93	45.68	49.77
Graph Transformer	47.67	56.18	53.71	57.95	47.90	43.63	54.00	56.20	60.92	52.37	41.77	52.91	51.00	53.21
One For All	36.61	61.11	50.33	39.82	44.92	45.88	65.40	56.24	63.36	50.60	38.08	45.27	49.78	49.82
Agentic Predictor	57.17	61.03	54.22	62.99	53.86	61.75	59.88	60.25	61.60	54.52	62.90	52.69	58.27	58.87



(a) Code Generation. (b) Math Problem. (c) Reasoning Tasks. (d) Average.

(e) Code Generation. (f) Math Problem. (g) Reasoning Tasks. (h) Average.

Figure 4: Comparison of accuracy (upper) and utility (lower) between Agentic Predictor and the baselines across varying label ratios.

We compare Agentic Predictor against four baselines: (1) the **ground truth** baseline, which directly evaluates agentic workflows to obtain ground-truth performance scores (as done in the original AFlow (Zhang et al., 2025a)); (2) two strong GNN-based predictors **GCN** and **GAT**; and (3) a **random** baseline, which assigns random performance scores as rewards. This experiment is conducted across five benchmarks: MATH, GSM8K, MBPP, HumanEval, and MMLU.

As in Table 12, Agentic Predictor consistently outperforms the random, GCN, and GAT baselines, achieving an average accuracy score of **74.43%**, significantly higher than random (62.56%), GCN (68.42%), and GAT (71.00%). Notably, as a predictor incurs zero search cost compared to the ground-truth's cost of $39.83, this result underscores the effectiveness and efficiency of Agentic Predictor as a reliable predictor for optimizing agentic workflows. Note that the search cost is 0 because the predictors do not incur any LLM inference cost.

B.7 Transferability

Considering that the MMLU benchmark encompasses various reasoning tasks, we further investigate the transferability of predictors trained on MMLU datasets to determine whether they can be used to optimize similar reasoning tasks, specifically DROP (Dua et al., 2019) and HotpotQA (Yang et al., 2018). As reported in Table 12, the workflow optimized using Agentic Predictor achieves competitive performance on these tasks: 86.25% on DROP and 13.37% on HotpotQA, demonstrating notable transferability. While performance on HotpotQA is lower than the baselines, the results remain broadly comparable, indicating that the workflows optimized via Agentic Predictor maintain

Table 12: Workflow optimization performance based on the selected workflow across different methods.

Methods	Math Problems		Code Generation		Reasoning			Average	
	MATH	GSM8K	MBPP	HumanEval	MMLU	DROP	HotpotQA	Score	Search Cost ($)
Ground Truth (AFlow)	87.38	94.53	73.22	97.20	83.10	84.25	69.94	84.23	39.83
Random	78.40	75.23	67.84	76.34	42.87	80.42	16.86	62.56	0.00
GCN	79.22	86.16	68.23	97.46	46.43	82.33	19.14	68.42	0.00
GAT	80.11	86.22	**68.62**	97.71	57.00	85.83	**21.47**	71.00	0.00
Agentic Predictor	**81.89**	**92.65**	68.42	**98.73**	**79.70**	**86.25**	13.37	**74.43**	0.00

substantial effectiveness when transferred to closely related reasoning tasks. This highlights the practical potential of Agentic Predictor for broader applicability in workflow optimization scenarios.

C Case Study

This section presents qualitative results from the workflow optimization process using Agentic Predictor as the reward function across three domains.

C.1 Code Generation

The code generation workflow on the HumanEval dataset demonstrates that the initial solution generation step often required subsequent refinement through explicit review and revision cycles. By systematically reviewing the initially generated code, and conditionally revising based on feedback from automated tests, the workflow substantially improved the final solution's correctness. This iterative approach effectively balanced computational cost and performance, resulting in solutions that were consistently more robust and accurate compared to single-step generations.

Workflow for Code Generation (HumanEval)

```
from typing import Literal
import workspace.HumanEval.workflows.template.operator as operator
import workspace.HumanEval.workflows.round_19.prompt as prompt_custom
from metagpt.provider.llm_provider_registry import create_llm_instance
from metagpt.utils.cost_manager import CostManager

DatasetType = Literal["HumanEval", "MBPP", "GSM8K", "MATH", "HotpotQA", "DROP", "MMLU"]

class Workflow:
    def __init__(
        self,
        name: str,
        llm_config,
        dataset: DatasetType,
    ) -> None:
        self.name = name
        self.dataset = dataset
        self.llm = create_llm_instance(llm_config)
        self.llm.cost_manager = CostManager()
        self.custom = operator.Custom(self.llm)
        self.custom_code_generate = operator.CustomCodeGenerate(self.llm)
        self.test = operator.Test(self.llm)

    async def __call__(self, problem: str, entry_point: str):
        """
        Implementation of the workflow
        1. Generate initial solution using custom_code_generate.
        2. Review the solution using custom operator.
        3. Test the solution; if test fails, revise using custom operator and retest.
        """
        # Step 1: Generate initial solution
        initial_solution = await self.custom_code_generate(problem=problem, entry_point=
            entry_point, instruction="")

        # Step 2: Review the solution to improve quality
```

```
    reviewed = await self.custom(input=initial_solution['response'], instruction=
        prompt_custom.REVIEW_PROMPT)

    # Step 3: Test the reviewed solution
    test_result = await self.test(problem=problem, solution=reviewed['response'],
        entry_point=entry_point)

    # If test fails, revise solution based on test feedback and retest once
    if not test_result['result']:
        revised = await self.custom(input=reviewed['response'] + "\n" + test_result['
            solution'], instruction=prompt_custom.REVISE_PROMPT)
        test_result = await self.test(problem=problem, solution=revised['response'],
            entry_point=entry_point)
        final_solution = revised['response'] if test_result['result'] else reviewed['
            response']
    else:
        final_solution = reviewed['response']

    return final_solution, self.llm.cost_manager.total_cost
```

C.2 MATH PROBLEM

In addressing mathematical problems using the MATH dataset, the workflow leverages an ensemble strategy by producing multiple candidate solutions, subsequently selecting the most consistent one via a self-consistency ensemble step. The selected solution was then further refined through an additional review process. This combined ensemble and review mechanism significantly enhanced solution quality, highlighting the value of ensemble techniques in solving complex mathematical reasoning tasks, while maintaining a controlled computational budget.

Workflow for Math Problem (MATH)

```
from typing import Literal
import workspace.MATH.workflows.template.operator as operator
import workspace.MATH.workflows.round_88.prompt as prompt_custom
from metagpt.provider.llm_provider_registry import create_llm_instance
from metagpt.utils.cost_manager import CostManager

DatasetType = Literal["HumanEval", "MBPP", "GSM8K", "MATH", "HotpotQA", "DROP", "MMLU"]

class Workflow:
    def __init__(
        self,
        name: str,
        llm_config,
        dataset: DatasetType,
    ) -> None:
        self.name = name
        self.dataset = dataset
        self.llm = create_llm_instance(llm_config)
        self.llm.cost_manager = CostManager()
        self.custom = operator.Custom(self.llm)
        self.sc_ensemble = operator.ScEnsemble(self.llm)

    async def __call__(self, problem: str):
        """
        Implementation of the workflow with ensemble and review step
        """
        # Generate multiple candidate solutions using custom operator with different
            instructions
        candidates = []
        for i in range(3):
            response = await self.custom(input=problem, instruction=prompt_custom.SOLVE_PROMPT
                + f" Attempt {i+1}.")
            candidates.append(response['response'])

        # Use self-consistency ensemble to select the best solution
        ensemble_result = await self.sc_ensemble(solutions=candidates, problem=problem)
        best_solution = ensemble_result['response']

        # Review and refine the best solution
        review_response = await self.custom(input=problem + "\nSolution to review:\n" +
            best_solution, instruction=prompt_custom.REVIEW_PROMPT)
        final_solution = review_response['response']
```

```
        return final_solution, self.llm.cost_manager.total_cost
```

C.3 Reasoning Task

For reasoning tasks on the MMLU dataset, the workflow combines multiple generation techniques, including custom-generated solutions with varying prompts and answers produced by specialized answer-generation operators, to diversify initial candidate answers. The self-consistency ensemble step effectively selected the most consistent candidate, which was subsequently subjected to rigorous review and format verification steps. This meticulous process, which included conditional regeneration and revision to ensure strict adherence to specified answer formats, proved highly effective in enhancing both accuracy and reliability of the final responses.

Workflow for Reasoning Task (MMLU)

```
from typing import Literal
import workspace.MMLU.workflows.template.operator as operator
import workspace.MMLU.workflows.round_19.prompt as prompt_custom
from metagpt.provider.llm_provider_registry import create_llm_instance
from metagpt.utils.cost_manager import CostManager

DatasetType = Literal["HumanEval", "MBPP", "GSM8K", "MATH", "HotpotQA", "DROP", "MMLU"]

class Workflow:
    def __init__(
        self,
        name: str,
        llm_config,
        dataset: DatasetType,
    ) -> None:
        self.name = name
        self.dataset = dataset
        self.llm = create_llm_instance(llm_config)
        self.llm.cost_manager = CostManager()
        self.custom = operator.Custom(self.llm)
        self.answer_generate = operator.AnswerGenerate(self.llm)
        self.sc_ensemble = operator.ScEnsemble(self.llm)

    async def __call__(self, problem: str):
        """
        Implementation of the workflow with multiple custom answers, multiple AnswerGenerate
            answers, ensemble, review, and revision
        """
        # Step 1: Generate multiple candidate answers using custom operator with a concise
            prompt
        custom_answers = []
        for _ in range(2):
            custom_response = await self.custom(input=problem, instruction=prompt_custom.
                CUSTOM_PROMPT)
            custom_answer = custom_response['response']
            custom_answers.append(custom_answer)
        # Add 1 answer with diversity prompt to increase answer variety
        custom_diverse_response = await self.custom(input=problem, instruction=prompt_custom.
            CUSTOM_DIVERSE_PROMPT)
        custom_answers.append(custom_diverse_response['response'])

        # Step 2: Generate multiple candidate answers using AnswerGenerate operator to
            increase diversity
        answergen_answers = []
        for _ in range(2):
            answergen_response = await self.answer_generate(input=problem)
            answergen_answer = answergen_response['answer']
            answergen_answers.append(answergen_answer)

        # Step 3: Ensemble all candidate answers to select the most consistent answer
        all_answers = custom_answers + answergen_answers
        ensemble_response = await self.sc_ensemble(solutions=all_answers)
        ensemble_answer = ensemble_response['response']

        # Step 4: Review the ensemble answer to ensure format and correctness
        review_input = problem + "\nAnswer: " + ensemble_answer
```

```
    review_response = await self.custom(input=review_input, instruction=prompt_custom.
        REVIEW_PROMPT)
    reviewed_answer = review_response['response']

    # Step 5: If reviewed answer is not in correct format, regenerate with a stricter
        prompt
    if not reviewed_answer.startswith("Answer: Option "):
       strict_regen_input = problem + "\nPlease provide the final answer strictly in the
           format 'Answer: Option X'."
       strict_regen_response = await self.custom(input=strict_regen_input, instruction=
           prompt_custom.STRICT_REGEN_PROMPT)
       reviewed_answer = strict_regen_response['response']

    # Step 6: Revision step to refine the reviewed answer for strict format adherence
    revision_input = problem + "\nAnswer: " + reviewed_answer
    revision_response = await self.custom(input=revision_input, instruction=prompt_custom.
        REVISION_PROMPT)
    final_answer = revision_response['response']

    return final_answer, self.llm.cost_manager.total_cost
```