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# Model Merging Enables In-Context Learning for Bioacoustics Foundation Models

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## Abstract

1 General-purpose foundation models capable of generalizing across species and  
2 tasks represent a promising new frontier in bioacoustics, with NATURELM-AUDIO  
3 being one of the most prominent examples. While its domain-specific finetun-  
4 ing yields strong performance on bioacoustic benchmarks, we observe that it also  
5 introduces trade-offs in instruction-following flexibility. For instance, NATURELM-  
6 AUDIO achieves high accuracy when prompted for either the common or scientific  
7 name individually, but its accuracy drops significantly when both are requested  
8 in a single prompt. These effects limit zero- and few-shot generalization to novel  
9 tasks. We address this by applying a simple model merging strategy that interpo-  
10 lates NATURELM-AUDIO with its base language model, recovering instruction-  
11 following capabilities with minimal loss of domain expertise. Finally, we show that  
12 this enables effective few-shot in-context learning, a key capability for real-world  
13 scenarios where labeled data for new species or environments are scarce.

## 14 1 Introduction

15 Bioacoustics, the study of sound production, transmission, and perception in animals, is a critical  
16 tool for understanding biodiversity, monitoring ecosystems, and informing conservation efforts [26,  
17 24, 27]. Recent advances in machine learning (ML) have transformed the field, enabling automated  
18 detection, classification, and analysis of acoustic events at unprecedented scales [44].

19 Early work in ML for bioacoustics typically relied on *species-specific models*, trained and optimized  
20 for a single species and task [1]. However, as in other domains of ML, there is now a shift towards  
21 *general-purpose foundation models* that can support a broad range of downstream species and/or  
22 tasks with minimal retraining [23, 12, 15, 36, 37, 46]. One of the most prominent examples of  
23 this trend is NATURELM-AUDIO [38], the first bioacoustics audio–language model, designed for  
24 zero-shot generalization to unseen tasks via text-based prompting.

25 In this paper, we examine the capabilities of NATURELM-AUDIO as a *general* foundation model  
26 for bioacoustics. Despite its strong performance on tasks and prompts closely matching its training  
27 distribution, we find that its intense domain-specific finetuning has led to a severe reduction in  
28 the *instruction-following capabilities* of its base model (LLAMA-3.1-8B-INSTRUCT), a trade-off  
29 commonly observed in other specialized models [54]. This limits its ability to generalize in zero- or  
30 few-shot settings to new tasks. We show that *model merging* with the base model can help restore  
31 these capabilities, achieving a balance between domain-specific knowledge and general instruction-  
32 following. Finally, we demonstrate that this restoration enables NATURELM-AUDIO to perform  
33 *few-shot in-context learning*, a scenario of particular importance in bioacoustics where practitioners  
34 often have only a handful of labeled examples for new species, habitats, or acoustic conditions.

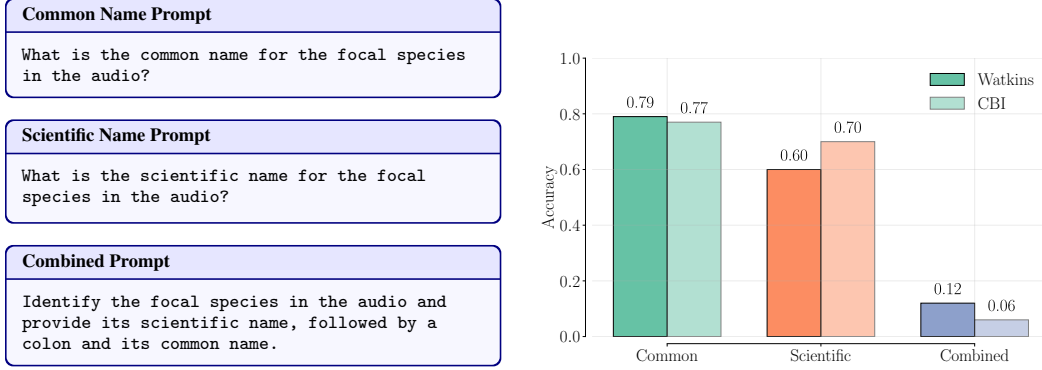


Figure 1: NATURELM-AUDIO classification accuracy for different prompts on WATKINS and CBI.

<b>id aecd4535-ebef-438d-811b-1ffb7be5c22e</b> GT: <i>Odobenus rosmarus</i> : Walrus Common: <b>Walrus</b> Scientific: <b><i>Odobenus rosmarus</i></b> Combined: <b><i>Odobenus rosmarus</i> - male courtship ...</b>	<b>id 4cbdd583-23c6-408d-aea5-3719dc6d9654</b> GT: <i>Lagenodelphis hosei</i> : Frasers Dolphin Common: <b>Fraser's Dolphin</b> Scientific: <b><i>Lagenodelphis hosei</i></b> Combined: <b><i>Lagenodelphis hosei</i></b>
<b>id 185c974a-d905-475c-8fc0-0cbab1e383b9</b> GT: <i>Eubalaena australis</i> : Southern Right Whale Common: <b>Fin- Finback Whale</b> Scientific: <b><i>Balaenoptera physalus</i></b> Combined: <b><i>Balaenoptera physalus</i>: 52 Hz Pulses</b>	<b>id 4186fc55-0ac2-4f44-9026-009f239fcf96</b> GT: <i>Stenella clymene</i> : Clymene Dolphin Common: <b>Clymene Dolphin</b> Scientific: <b><i>Stenella clymene</i></b> Combined: <b><i>Stenella clymene</i>: Clymene Dolphin</b>

Figure 2: Example model predictions for the common name, scientific name, and combined-name prompts, compared to ground truth. Correct predictions in **green**, incorrect in **red**.

## 2 Problem Analysis

NATURELM-AUDIO is a LoRA [18] finetuning of LLAMA-3.1-8B-INSTRUCT [13] on ~2M steps of audio-text pairs, predominantly bioacoustics but also music and human sounds. While the original evaluation shows that the model follows training-like instructions well, such as predicting either the common or the scientific name of the focal species in an audio in isolation, we find that requesting both in a single prompt often leads to a substantial drop in accuracy. Figure 1 shows the exact prompts and corresponding accuracies on WATKINS and CBI, two species-classification datasets from the BEANS benchmark [16] covering marine mammals and birds, respectively. On both datasets, the model performs slightly better on common names than on scientific names, yet achieves high accuracy (60–80%) in both cases. However, when prompted for both names jointly, accuracy falls to 6–12%.

The examples in Figure 2 illustrate typical failure modes. In the top left, the model outputs correct common and scientific names individually, but under the combined prompt it drifts into behavioural description (“male courtship behavior”), possibly reflecting its exposure to captioning-style data during training [38]. In the bottom left, it misidentifies the species in all cases, yet common and scientific predictions remain mutually consistent; in the combined case it again appends unrelated context (“52 Hz pulses”). In the top right, correct individual predictions degrade to only the scientific name under the combined prompt. In the bottom right, all three prompts succeed.

We additionally experiment with the ZF-INDIV dataset originally used in [38] to evaluate zero-shot task generalization (see Appendix B.2) and observe a similar pattern: NATURELM-AUDIO shows reduced robustness to even mild prompt variations. This behaviour is consistent with the effects of extensive domain-specific finetuning observed in other specialized LLMs, where overfitting to training prompt formats can narrow instruction-following flexibility and limit generalization [54].

### 3 Method

Section 2 shows that NATURELM-AUDIO has lost its instruction following capabilities in favor of task-specific ones acquired during finetuning. We recover these ones through model merging.

**Model Merging** Model merging aims to ensemble different models without incurring in additional inference or storage costs [2, 11, 49, 5]. While the non-linear nature of neural networks prevents from taking the weighted average of the models in general [48], this aggregation is well behaved when the two models exhibit linear mode connectivity [9], *i.e.* can be connected via a linear path over which the loss does not significantly increase. In this case, the merged model  $\Theta^{(\text{merge})}$  can be obtained from the endpoint models  $\Theta^{(1)}, \Theta^{(2)}$  simply as  $\Theta^{(\text{merge})} = (1 - \alpha)\Theta^{(1)} + \alpha\Theta^{(2)}$ , where  $\alpha \in [0, 1]$  is a scaling parameter controlling the contribution of each model. Consistent with previous findings [48, 32, 9], we observe that linear interpolation remains effective along the finetuning trajectory, suggesting that linear mode connectivity holds when (part of) the optimization path is shared.

**Merging NATURELM-AUDIO with its base model** We merge LLAMA-3.1-8B-INSTRUCT with its finetuning NATURELM-AUDIO to combine the instruction following abilities of the former and the task-specific performance of the latter. In particular, being NATURELM-AUDIO a LoRa [18] finetuning, linearly interpolating between the base and the finetuned is equivalent to changing the multiplicative factor  $\alpha$  in LoRa: Given the weight matrix  $\mathbf{W}_{\text{base}}$  of the base model for some layer, LoRA updates it as  $\mathbf{W}_{\text{ft}} = \mathbf{W}_{\text{base}} + \mathbf{A}\mathbf{B}$ , where  $\mathbf{A}$  and  $\mathbf{B}$  are two low-rank learnable matrices; thus

$$(1 - \alpha)\mathbf{W}_{\text{base}} + \alpha\mathbf{W}_{\text{ft}} = (1 - \alpha)\mathbf{W}_{\text{base}} + \alpha(\mathbf{W}_{\text{base}} + \mathbf{A}\mathbf{B}) \quad (1)$$

$$= \mathbf{W}_{\text{base}} - \alpha\mathbf{W}_{\text{base}} + \alpha\mathbf{W}_{\text{base}} + \alpha\mathbf{A}\mathbf{B} = \mathbf{W}_{\text{base}} + \alpha\mathbf{A}\mathbf{B}. \quad (2)$$

This shows that we can interpolate between the base and the finetuned model simply by varying  $\alpha$ .

### 4 Results

**Combined Instruction-Following Task** We evaluate the merged model over a range of interpolation coefficients  $\alpha$ , using the three prompt variants in Figure 1. The  $y$ -axis in Figure 3 reports the accuracy on the *combined* prompt, while the  $x$ -axis shows the mean accuracy on the *training-like* prompts (common name and scientific name individually). For the combined prompt, intermediate interpolation values substantially outperform both extremes. Specifically, rescaling from  $\alpha = 1$  (NATURELM-AUDIO) to  $\alpha \approx 0.7$  increases combined-task accuracy from 6%  $\rightarrow$  45% on Watkins and 12%  $\rightarrow$  63% on CBI, reflecting a restoration of instruction-following capabilities degraded in the finetuned model. However, setting  $\alpha$  too low ( $\alpha < 0.5$ ) sharply reduces accuracy on combined prompts due to a loss of domain-specific audio knowledge from the finetuning stage.

The observed behaviour highlights  $\alpha$  as a controllable *capability trade-off parameter*. At  $\alpha = 1$ , the model fully retains its domain adaptation but suffers in compositional instruction following. At  $\alpha = 0$ , it maximizes general instruction-following behaviour inherited from the base model, but discards most bioacoustic specialization. The monotonic decline in  $x$ -axis accuracy with decreasing  $\alpha$  further confirms that domain-task performance and instruction-following ability are in tension.

**In-Context Learning Task** We next assess the merged model on a more challenging *one-shot in-context learning* task, where a single example for each class is provided directly in the prompt. We use the UNSEEN-CMN-FAMILY split from the BEANS-ZERO benchmark, the most difficult “unseen species” scenario evaluated in [38]. In this setting, no species from the same taxonomic family as those in the test set are present in training, and the goal is to predict the *common name* of the focal species. In the original paper, NATURELM-AUDIO performs extremely poorly when evaluated zero-shot on this challenging split (0.035 accuracy).

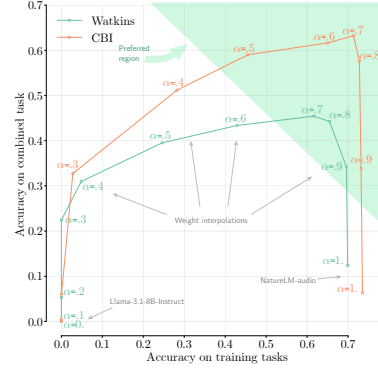


Figure 3: Accuracy on the combined prompt (y-axis) from Figure 1 versus the mean accuracy on the individual common- and scientific-name prompts (x-axis) when varying  $\alpha$ .

In-Context Learning Prompt	
Identify the common name for the focal species in the audio. Output exactly one of: Dall's Porpoise, Spotted Elachura	
Audio:	[high-pitched clicks and whistles]
Label:	Dall's Porpoise
Audio:	[bird-like chirping and trilling]
Label:	Spotted Elachura
Audio:	<Audio><AudioHere></Audio>
Label:	

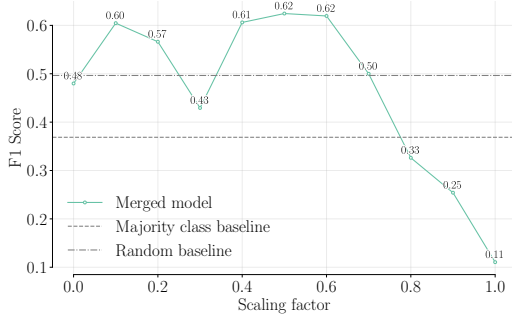


Figure 4: F1-score for 1-shot in-context classification on UNSEEN-CMN-FAMILY when varying  $\alpha$ .

106 Ideally, the in-context examples would include *audio tokens* from the encoded waveforms. For  
 107 simplicity, we instead provide a short textual description of each audio clip. To further simplify  
 108 evaluation, we restrict to the two most frequent classes, reducing the task to binary classification.

109 We show the prompt and results in Figure 4. The original NATURELM-AUDIO ( $\alpha = 1$ ) reaches an  
 110 F1-score of just 0.11, performing *worse than random guessing* and often producing labels outside the  
 111 provided ones, indicating a failure in instruction following. In contrast, the merged model achieves  
 112 F1-scores above 0.6 for  $\alpha \in [0.4, 0.6]$ . These results show that model merging can *restore in-context*  
 113 *learning*, enabling bioacoustic models to adapt quickly to new tasks with few labeled examples.

## 114 5 Related Work

115 **Catastrophic forgetting in multi-modal finetuning** Catastrophic forgetting is a well-known  
 116 challenge when fine-tuning large language models [39]. A common training-time mitigation is to  
 117 freeze the LLM and update only the projection layer that maps visual or audio features into the text  
 118 embedding space, often with fewer fine-tuning steps [54] or using PEFT methods [55, 34]. In contrast,  
 119 post-training approaches aim to restore forgotten skills in already fine-tuned models [57, 35].

120 **Model merging** Model merging provides an efficient alternative to ensembling, producing a single  
 121 model combining multiple models' capabilities without increasing inference cost. Early work,  
 122 inspired by linear mode connectivity [9, 11, 30, 8], focused on aligning independently trained models,  
 123 often by solving a neuron permutation problem [2, 22, 5, 40, 41, 14, 31, 17]. Closer to our work,  
 124 Wortsman et al. [48] produce robust finetuned models by linearly interpolating them with their base  
 125 model, while Ilharco et al. [20] use interpolations to improve specific tasks without waiving others.

## 126 6 Conclusions

127 We investigated the instruction-following limitations of NATURELM-AUDIO and found that even  
 128 small changes in prompt structure can significantly degrade performance, reducing its utility as  
 129 a general-purpose model. To address this, we applied a lightweight model-merging strategy that  
 130 interpolates the finetuned NATURELM-AUDIO with its base model. Intermediate interpolation  
 131 weights restore much of the lost instruction-following capability while preserving most domain-  
 132 specific accuracy. This recovery further enables few-shot in-context learning, a critical feature in  
 133 bioacoustics where only a few labeled examples are often available. In our experiments,  $\alpha \approx 0.6$   
 134 provided a strong balance between instruction following and domain expertise, though the optimal  
 135 value remains task- and dataset-dependent.

136 **Limitations and Future Work** Our current evaluation of in-context learning is limited in scope. In  
 137 future work, we plan to incorporate raw audio tokens directly into prompts and extend the evaluation to  
 138 multiple datasets and many-class settings. Convex weight interpolation may not be optimal, we intend  
 139 to explore alternative strategies for restoring instruction-following abilities, including more advanced  
 140 model-merging methods (e.g. evolutionary merging [3, 29], subspace-based merging [10, 25, 42])  
 141 and activation-steering techniques [4, 43]. We believe these directions will further enhance the  
 142 adaptability of bioacoustic foundation models, especially in real-world, low-resource scenarios.

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## A Extended related work

**Foundation Models in Bioacoustics** Recent advances have introduced large-scale bioacoustic foundation models designed for cross-species and cross-task generalization. NATURELM-AUDIO [38] integrates a self-supervised audio encoder with a LLaMA-based language decoder. BIOLINGUAL [37] adapts CLAP-style audio–text contrastive learning to bioacoustics, while audio-only models such as BIRDMAE [36], AVES [15] and PERCH 2.0 [46] pretrain large models on extensive birdsong or multi-taxa datasets to produce broadly transferable acoustic features. Although these models surpass species-specific baselines, they remain susceptible to domain shifts and catastrophic forgetting, limiting their robustness in real-world deployment.

**Mode connectivity and model merging** Mode connectivity investigates the weight configurations that define local minima. Frankle et al. [9] examines the linear mode connectivity of models trained for only a few epochs from the same initialization, linking this phenomenon to the lottery ticket hypothesis. Relaxing the shared-initialization requirement, Entezari et al. [8] argues that, after resolving neuron permutations, all trained models may reside in a single connected basin. Model merging pursues a different goal: combining multiple models into one that inherits their capabilities without the cost and complexity of ensembling. In this direction, Singh and Jaggi [40] introduced an optimal-transport–based weight-matching method, while Git Re-Basin [2] proposes optimizing a linear assignment problem (LAP) for each layer. More recently, REPAIR [22] shows that substantial gains in the performance of interpolated models can come from renormalizing activations, while  $C^2M^3$  [5] proposes matching and merging many models jointly through cycle-consistent permutations. When the models to merge are fine-tuned from a shared backbone, task-vector-based methods are most effective [21, 50, 53, 28, 48, 7, 47, 56, 10, 33, 29, 19, 6, 42, 51, 45]. These involve taking the parameter-level difference between the finetuned model and its pretrained base, termed a task vector. Improvements can be obtained by optimizing task-vector combinations [52], mitigating sign disagreement [50], randomly dropping updates [53], or applying evolutionary methods [3, 29]. Finally, techniques employing layer-wise task vectors [42, 10, 25] obtain state-of-the-art results by leveraging layer-level structures through SVD of the parameter differences.

## B Additional Experiments

### B.1 Combined Instruction Following Task

### B.2 Zero-Shot Generalization Task

In Robinson et al. [38], zero-shot generalization was evaluated on the ZF-INDIV dataset, part of the BEANS-ZERO benchmark [38], which tests the ability to infer the number of zebra finch individuals in an audio recording. This task was not included in the model’s training set.

With the original prompt from Robinson et al. [38] (Figure 6), NATURELM-AUDIO achieves 0.66 accuracy (random baseline: 0.5), indicating partial generalization to this unseen task. However, reversing the order of the class names in the prompt or removing explicit class labels, asking instead for the number of birds, reduces accuracy to 0.52, essentially random performance.

These observations suggest that the higher-than-random performance reported in Robinson et al. [38] may be sensitive to prompt formulation. While the original result remains valid for the tested prompt,



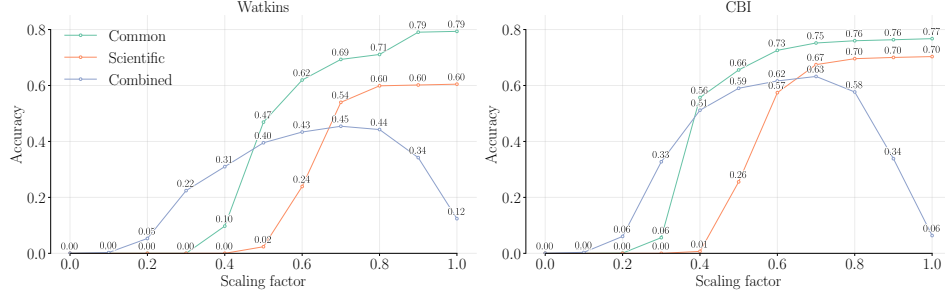


Figure 5: Accuracy on the common name, scientific name, and combined prompts from ??, as a function of the rescaling parameter  $\alpha$ .

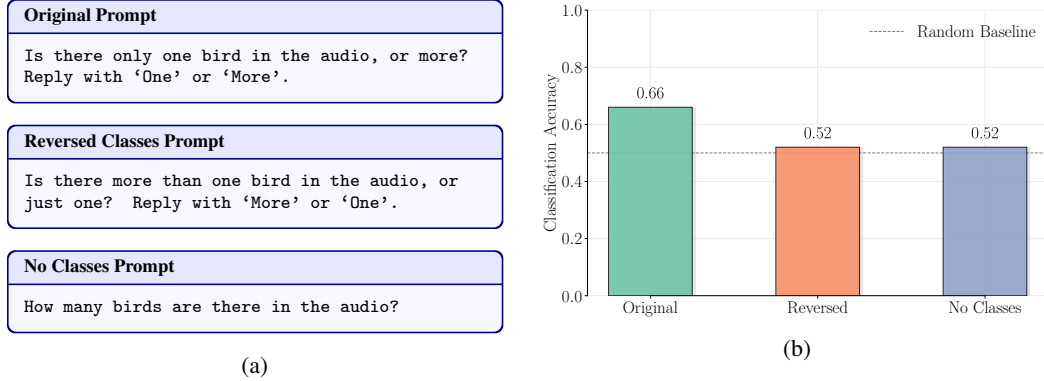


Figure 6: **Classification accuracy for different prompt types on ZF-INDIV.** (a) Exact wording of the three evaluated prompts. (b) Accuracy of NATURELM-AUDIO on ZF-INDIV. Accuracy is above random for the original prompt from Robinson et al. [38], but drops to near-random when the prompt is slightly reworded.

our findings indicate that performance may not fully reflect broad zero-shot generalization, but could instead be partly influenced by prompt-specific biases.

### B.2.1 Few-Shot In-Context Learning

**Experimental Details** To mitigate position bias, we randomly permute the order of the few-shot examples in the prompt for each evaluation sample. This randomization is applied independently for every sample, ensuring that any spurious correlations between class position and prediction might be minimized. As previously noted, the two species used in the experiment, Spotted Elachura (*Elachura formosa*) and Dall’s Porpoise (*Phocoenoides dalli*), were selected for being the most frequent classes in the UNSEEN-CMN-FAMILY dataset, with 73 and 53 samples respectively.

Following [38], we evaluate classification accuracy by first extracting the model’s free-form output, then computing the Levenshtein distance between this output and each possible target class name (in this case, the two species’ common names). The class with the smallest distance is selected, and the prediction is considered correct if this distance is less than a threshold  $t$  (set to  $t = 5$  in our experiments).

### B.2.2 Compute Resources

All experiments were conducted on a single NVIDIA A100 GPU (40 GB), using 8 CPU cores and 32 GBs of RAM, requiring, for storage, 300 GB of disk space.

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