

MetAL: A Novel Meta Active Learning Approach for Morphophonological Processing

Anonymous ACL submission

Abstract

In morphologically complex languages like Arabic, developing a morphophonological processing system poses significant challenges. While deep learning models have shown success in this task, these models heavily rely on the size of the annotated data. However, creating large datasets, especially for low-resource languages such as different Arabic dialects, is very time-consuming, hard, and expensive. Furthermore, not all annotated data contribute beneficial information for training models. To address these issues, active learning tries to guide the learning algorithm to choose informative samples for annotation. Despite the limited research on applying active learning to morphophonological processing, this paper introduces a novel combination of meta and active learning approaches for tackling this task. To the best of our knowledge, there is no research that focuses on the combination of these approaches. The experimental results conducted on Egyptian Arabic demonstrate that achieving similar performance as the state-of-the-art model on the entire dataset is possible with only approximately 23% of annotated data. Notably, our proposed method outperforms existing successful deep active learning methods.

1 Introduction

During the last few years, morphological inflection processing (Narasimhan et al., 2015; Kirov and Cotterell, 2018; Belth et al., 2021) has received a great deal of attention. This task has gained significant attention in the NLP community (Halabi, 2016; Khalifa et al., 2020; Alhafni et al., 2020) and has recently been the focus of several shared tasks (Cotterell et al., 2018; Vylomova et al., 2020; Batsuren et al., 2022). Neural seq2seq models achieved impressive precision, particularly when accessing extensive training datasets (Cotterell et al., 2018). Nonetheless, when trained with limited data, these neural models exhibit low performance, often for

languages with complex morphological structures. However, having enough annotated data is challenging, costly, and time-intensive. In addition, all annotated data do not contain useful information for enhancing the quality of the learning algorithm.

In this paper, we have introduced a novel meta active learning (MetAL) approach to reduce the amount of labeled data required for the Egyptian Arabic morphophonological processing. Morphophonological processing takes a sequence of morphs and applies morphophonological processes to obtain the surface form. It is an important component of inflection. In our experiments, we have selected an efficient transformer model for character-level transduction tasks (Wu et al., 2021) as our baseline model. We have used the pool-based active learning method with maximum entropy criterion for selecting uncertain samples. By combining meta and active learning methods, we have achieved similar results as supervised learning with only 23% of the training dataset, which is a SOTA result in this area. Our approach also surpasses currently effective deep active learning (DAL) techniques, especially in scenarios where a small amount of annotated data is involved. To the best of our knowledge, our work is the first application of a MetAL approach in the morphophonological processing task. It should be noted that our proposed method is not specific to Arabic, and it can be also applied to other languages.

2 Previous Work

There has been extensive non-neural network research focused on Arabic morphological modeling, which includes morphophonological processing (Habash and Rambow, 2006; Graff et al., 2009; Habash et al., 2022). Recently, with the popularity of neural networks, various studies of DL models based on character-level neural transducers using transformers and RNNs approaches have been in-

081 introduced (Wu et al., 2021; Dankers et al., 2021; 130
082 Yang et al., 2022; Wehrli et al., 2022). 131

083 DAL has recently been used in various sub-fields 132
084 of NLP such as NER (Prabhu et al., 2019; Liu 133
085 et al., 2020) and machine translation (Liu et al., 134
086 2018; Zhao et al., 2020). In the morphological 135
087 inflection task, Muradoglu and Hulden (2022) pre- 136
088 sented a novel DAL technique using word-level 137
089 entropy for lemma inflection in different languages. 138
090 Mirbostani et al. (2023) introduced another DAL 139
091 approach that utilizes character-level entropy. This 140
092 method achieved superior performance compared 141
093 to previous techniques. 142

094 In recent years, meta-learning has found suc- 143
095 cessful applications in various NLP domains such 144
096 as machine translation (Gu et al., 2018), NER (Ma 145
097 et al., 2022), and semantic parsing (Langedijk et al., 146
098 2022). It aims to address the challenge of quickly 147
099 adapting to new training data. Common meta- 148
100 learning techniques can be classified into three 149
101 groups: black-box adaptation (Santoro et al., 2016), 150
102 optimization (Finn et al., 2017), and metric learning 151
103 (Snell et al., 2017). Kann et al. (2020) introduced 152
104 a meta-learning-based approach for cross-lingual 153
105 transfer learning in the morphological inflection 154
106 task using the MAML algorithm (Finn et al., 2017). 155

107 3 Problem Definition and Dataset 156

108 In this paper, we focus on morphophonological 157
109 processing, in which a model receives an underly- 158
110 ing representation (UR) of a word and generate its 159
111 surface form (SF), i.e., spoken form. We use the 160
112 morphophonology dataset of Khalifa et al. (2022), 161
113 which consists of (UR, SF) pairs for Egyptian Ara- 162
114 bic and is derived from the ECAL dataset (Kilany 163
115 et al., 2002). The UR includes segmentation in- 164
116 formation, using # to indicate word boundaries, 165
117 – for prefixes, and = for suffixes. The dataset’s 166
118 split into TRAIN, DEV, and EVAL is based on the 167
119 ECAL’s split. Since in ECAL, the split is based 168
120 on running texts, some words may appear in mul- 169
121 tiple splits. To address this, Khalifa et al. (2022) 170
122 also created DEV-OOV and EVAL-OOV subsets 171
123 by including only words that do not overlap with 172
124 TRAIN. Some samples of (UR, SF) pairs and the 173
125 dataset’s statistics are shown in appendix section. 174

126 4 Proposed Method 175

127 4.1 Baseline Network 176

128 We performed various experiments to choose the 177
129 best baseline model for our MetAL experiments, 178

and chose Wu et al. (2021)’s transformer-based 130
model. It has outperformed existing RNN-based 131
seq2seq models and achieved SOTA results on our 132
target dataset. 133

134 4.2 Meta Learning Method 134

135 Given the limited resources of character-level 136
137 datasets for morphophonological processing tasks, 137
138 an optimization-based meta-learning algorithm is 138
139 a practical method to achieve high accuracies with 139
140 small datasets and few training iterations. Accord- 140
141 ingly, we have adopted MAML (Finn et al., 2017), 141
142 a general optimization algorithm compatible with 142
143 gradient descent, in our method. The primary as- 143
144 sumption is that our neural transducer model, f_θ , 144
145 is parameterized by θ , and its loss function, \mathcal{L} , is 145
146 minimized using a gradient-based learning tech- 146
147 nique. The model is trained over multiple tasks, 147
148 \mathcal{T}_i , sampled from a distribution over tasks $p(\mathcal{T})$ to 148
149 which the model should be adapted. 149

150 In our problem, each task has an associated 150
151 dataset containing pairs of (UR, SF) for words. It 151
152 is split into two subsets: *support* and *query*. The 152
153 support set (i.e., the training set) is a labeled sub- 153
154 set used for adaptation of the meta-learning model 154
155 through learning the initial parameters. The query 155
156 set (i.e., the test set) is the complement of the 156
157 support set used for evaluating the model’s per- 157
158 formance on new, unseen data points. Furthermore, 158
159 it indicates how well the model generalizes over 159
160 the tasks not seen in the meta-training phase. 160

161 Model adaptation is the process of quickly learn- 161
162 ing and adjusting the initial parameters to a task us- 162
163 ing a small number of samples. Equation (1) com- 163
164 puts adapted parameters of the model, f_θ , over a 164
165 single task, \mathcal{T}_i , using one adaptation iteration (i.e., 165
 $N_{\text{adapt}} = 1$). 165

$$166 \theta'_i = \theta - \alpha \nabla_{\theta} \mathcal{L}_{\mathcal{T}_i}(f_\theta) \quad (1) \quad 166$$

167 In the given equation, α is the step size, which 167
168 can be a fixed or a learned hyperparameter. 168

169 Applying multiple gradient updates on the meta- 169
170 learning model creates a trade-off between param- 170
171 eter refinement and adaptation speed. Therefore, 171
172 choosing a suitable N_{adapt} depends on the complex- 172
173 ity of the task, as more resources and training time 173
174 is required to reach a thorough adaptation. 174

175 The optimal parameters of the model for better 175
176 performance of $f_{\theta'_i}$ in terms of θ , adapted over 176
177 multiple tasks sampled from $p(\mathcal{T})$, are computed 177
178 using Equation (2). 178

$$\theta^* = \arg \min_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta'_i}) \quad (2)$$

This method significantly improves the fine-tuning of the model, with one or more adaptation iterations (i.e., $N_{\text{adapt}} \geq 1$) on a new task from the same distribution.

Given the adapted parameters over each task, θ'_i , the optimization of the model across all the sampled tasks, \mathcal{T}_i , is performed by updating the model parameters, θ , using Equation (3):

$$\theta \leftarrow \theta - \beta \nabla_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta'_i}) \quad (3)$$

where β is the meta step size.

4.3 Meta Active Learning (MetAL) Method

In our approach, we have combined the principles of meta-learning, described in Section 4.2, and active learning (AL) to improve the accuracy of the baseline model on our problem. The meta-learning model shares the knowledge learned from previous tasks of the same distribution with the new tasks that are generated based on the most informative instances in each AL training cycle. In our algorithm, we have used the pool-based AL method integrated with the maximum entropy criterion for selecting uncertain samples in each training cycle.

The MetAL method initiates the training procedure by random sampling, without replacement, of a portion (around 10%) of a pool dataset, \mathcal{U} . In our case, \mathcal{U} initially contains 13,170 unannotated samples. In the next step, these randomly selected samples are annotated and divided into two subsets: *tuning* and *training*. A tuning subset, \mathcal{V} , is a dataset (500 samples in our experiments) used for validating the trained models. A training subset, \mathcal{D} , is an augmented dataset (900 samples in our experiments) used for training the model in the initial cycle according to the meta-learning method. In subsequent training cycles, \mathcal{V} remains constant; however, \mathcal{D} is increased by δ ($=250$) number of samples selected from the remaining samples of \mathcal{U} based on their maximum entropy values.

For a given sample from \mathcal{U} , Equation (4) computes the entropy value of a word, w , in terms of its characters' logits, \mathbf{c} , predicted by the most performant model trained in the previous AL cycle.

$$H(w) = \max_{\mathbf{c} \in w} \left(- \sum_{i=1}^N p_i(\mathbf{c}) \log p_i(\mathbf{c}) \right) \quad (4)$$

$p_i(\mathbf{c})$ is the probability value of the i^{th} character in an N -sized \mathbf{c} and is calculated using the softmax function, $e^{c_i} / \sum_{i=1}^N e^{c_i}$. Given that the model's predicted characters with the lowest confidence value have the highest entropy, the entropy of a word, $H(w)$, corresponds to the maximum value of all the entropy values associated with its respective characters.

A MetAL training cycle encompasses a meta-learning method with $N_{\mathcal{T}}$ number of tasks. The training dataset, \mathcal{D} , is randomly divided into $N_{\mathcal{T}}$ equal subsets, \mathcal{D}_i . Each task, \mathcal{T}_i , has an associated \mathcal{D}_i , and during meta-learning iterations, undertakes a meta-training and a meta-testing phase. The \mathcal{D}_i is split into a support set, \mathcal{S}_i , and a query set, \mathcal{Q}_i , to be used in those phases, respectively.

K_s sample batches are selected sequentially from \mathcal{S}_i for meta-learning model adaptation during meta-training. This phase helps the model acquire knowledge and adaptability across current tasks and learn to generalize for the next tasks by updating the meta-learning model's parameters using Equations (1) and (2). The meta-testing phase involves exposing the model to the query set for parameters optimization across all tasks, given the adapted parameters over each task. K_q shots of sample batches are randomly chosen from \mathcal{Q}_i for fine-tuning the model using Equation (3).

5 Experimental Results

We evaluated our proposed MetAL method by training the baseline model with MetAL, DAL, and random training (i.e., passive learning) over 5 runs, with each run utilizing a randomly chosen tuning set based on different seed values, and evaluating on EVAL, EVAL-OOV, DEV, and DEV-OOV datasets. Figure 1 shows the mean and standard deviation (SD) of the model's performance on the morphophonological processing task in terms of accuracy for each training cycle. It reflects the average outcome across all 5 runs. During our analysis, no significant loss discrepancy between the training and tuning sets has been observed, and both the mean and SD of the results display relatively minimal variations. The details regarding the hyper-parameters and variables employed in our experiments and the supplementary experiments are presented in Appendices B and C.

As shown in Figure 1, the curve corresponding to our proposed MetAL method displays a shape that tends towards an asymptote. It demonstrates a

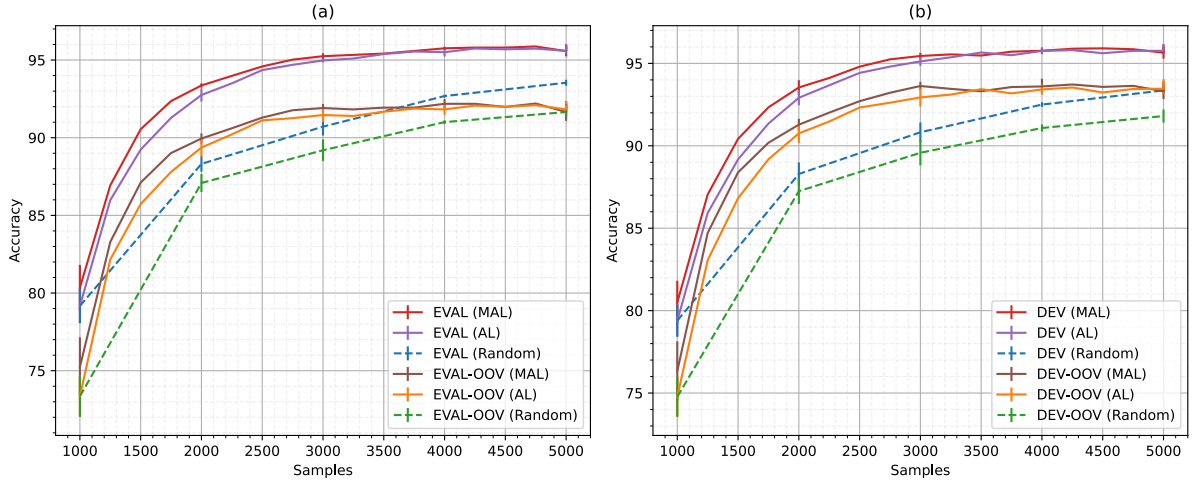


Figure 1: Morphophonological processing task: The mean and standard deviation of the baseline model’s accuracy trained using MetAL, DAL, and random training methods, and evaluated on (a) EVAL, EVAL-OOV, (b) DEV, and DEV-OOV datasets

considerably accelerated growth in contrast to the DAL and random curves and initiates with a higher level of accuracy, outperforming both alternative training methods.

By achieving optimal accuracy with only approximately 3,000 samples (i.e., about 23% of the training set) on EVAL-OOV and DEV-OOV, and only around 4,000 samples (i.e., about 30% of the training set) on EVAL and DEV, our method demonstrates its capacity to actively elicit a small set of informative samples from the pool for labeling and effectively adapt to these samples with few shots, showing strong performance on out-of-vocabulary datasets of the same distribution. Hence, it reveals that this method excels over DAL on small-scale datasets. In contrast, the random learner relies on whole training set to reach its best accuracy level.

The SD of our MetAL method (over the experimental results using 5 runs) has a consistent decrease in each subsequent training cycle, in addition to being lower compared to that of the DAL and random training methods. This can be attributed to the effective utilization of data enabled by the rapid adaptation to new tasks in meta-learning, increasing the model’s robustness, reducing the impact of variations in the training set, and resulting in a lower SD. In contrast, DAL focuses on selecting informative instances, which may not directly address data variability.

Adopting the meta-learning method to go over multiple tasks during each training iteration, the model has developed the capacity to generalize its gained experience from sampled tasks to im-

prove over unseen samples of the same distribution. In our approach, exposing the model to a few shots of informative data points extracted from a small-sized AL training cycle dataset, \mathcal{D} , greatly reduces the required annotation and accelerates the model’s training process compared to employing DAL method alone.

6 Conclusion

We have introduced the meta active learning algorithm, a combination of meta and active learning approaches, using the morphophonological processing task for Egyptian Arabic dialect as a sample task. The results of our experiment demonstrate that achieving similar accuracy as the SOTA model on the entire dataset is possible with only 23% of the total training dataset, which outperforms existing successful deep active learning methods, especially on lower amounts of annotated data.

Our method has been designed to be language and model agnostic. We hypothesize that by concentrating on Arabic, a language renowned for its morphological intricacies, our approach’s efficacy will extend to diverse languages. As our prospective research topics, we suggest addressing the intricacies of templatic morphology, a substantial source of complexity within Arabic, in addition to analyzing the application of our method to train other baseline models, generate datasets for low-resource Arabic dialects and other languages, and incorporate alternative uncertainty criteria.

336 Limitations

337 Our work, like many deep learning algorithms, re-
338 lies on GPU resources. In common learning prob-
339 lems, models are trained once on training datasets,
340 tuned on the development sets, and then ready for
341 inference. However, the training process involves
342 conducting multiple iterations whenever new infor-
343 mative samples from the pool are annotated and
344 added to the training set throughout AL cycles. As
345 the augmented training set grows, the demand for
346 GPU resources increases.

347 Furthermore, there is a trade-off between the
348 adaptation speed and the generalization perfor-
349 mance during the meta-learning phase. Additional
350 adaptation iterations and support shots are required
351 for broader task generalization in meta-learning,
352 increasing GPU resource demand. However, the
353 requirement for GPU resources is not specifically
354 tied to our proposed method but rather stems from
355 the inherent nature of active learning and meta-
356 learning methods.

357 Our algorithm is language and model agnostic;
358 however, it has only been evaluated on the Egyptian
359 Arabic dialect. Therefore, further research
360 is needed to examine the accuracy of the model
361 across other languages and dialects using different
362 learning models.

363 It is worth mentioning that the proposed method
364 exhibits the potential to achieve higher accuracy
365 with increased hyperparameter values. Unfortu-
366 nately, due to hardware limitations, we were unable
367 to perform the experiments to validate this.

368 Ethics Statement

369 This study is primarily focused on fundamental
370 research and is not related to a specific applica-
371 tion. We do not anticipate any ethical concerns aris-
372 ing from the algorithms and technologies proposed
373 in this work. This research has utilized datasets
374 and open-source libraries that have been previously
375 published and publicly accessible.

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A Dataset

For the purpose of this paper, our concentration lies on the intricate Arabic morphophonological processing task, given its substantial complexity and variation among the dialects. Accordingly, we have used the annotated Egyptian Arabic morphophonology dataset introduced by Khalifa et al. (2020) to assess our proposed method on a low-resource language with a high degree of morphological complexity. The dataset contains pairs of (UR, SF) split into TRAIN, DEV, and EVAL subsets, based on the ECAL’s splits introduced by Kilany et al. (2002), in addition to EVAL-OOV and DEV-OOV subsets, specific to this dataset. Two samples of (UR, SF) pairs along with the sizes of different splits of the dataset used in our task are shown in Tables A.1 and A.2.

UR	SF
#qAl=li=hum#	#qalluhum#
#bi-t-Akl=I#	#bitakli#

Table A.1: Two samples of (UR, SF) pairs of the dataset.

	TRAIN	DEV	EVAL
All	13,170	5,180	6,974
OOV	-	2,189	2,271

Table A.2: The sizes of different splits of the dataset.

Owing to the dataset’s comprehensive annotations, we undertook our experiments using a simulation-based active learning approach. As outlined in Section 4.3, during each MetAL cycle, we deliberately select K_s samples as the support set from the pool of annotated training samples, sequentially presenting it to the model. Conversely, the query set, containing K_q samples, is formed from the complementary set of the support set and is introduced to the model in a randomized manner.

B Experimental Setup

We performed a series of experiments involving various successful approaches, including the Neural Transducer by Wu et al. (2021), and Cluzh by Wehrli et al. (2022). As a result, we selected the character-level neural transducer (i.e., Wu et al. (2021) system) as our baseline model. This choice stems from its standing as a SOTA transformer-based model, outperforming existing RNN-based seq2seq models and showcasing successful outcomes across the entirety of the Ara-

bic morphophonological processing dataset. The model is a compact transformer consisting of 4 encoder-decoder layers, 4 self-attention heads, an embedding dimension of 256, and a hidden size of 1024 for the feed-forward layer. The model has 7.37M parameters, excluding embeddings and the pre-softmax linear layer.

The optimal values for the hyper-parameters of our experiments are listed in Table B.1. We conducted multiple experiments with different values to analyze the performance of our proposed MetAL method. The mean and standard deviation of the results in terms of accuracy for each training cycle is reported in Figure 1.

Parameter	Value
\mathcal{D} (initial) samples	900
\mathcal{V} samples	500
δ samples	250
Support Feeding Methodology	rotation
Query Feeding Methodology	random
Uncertainty criterion	entropy
Training batch size (BS)	100
Evaluation batch size	6
α learning rate	0.001
β learning rate	0.0001
Dropout	0.3
$N_{\mathcal{T}}$	4
K_s	8
K_q	8
N_{adapt}	1

Table B.1: The optimal hyper-parameter values of the experiments.

We have used PyTorch, NumPy, Pandas, and Matplotlib software packages to implement the proposed algorithm. The experiments were performed on a hardware comprising an Intel Core i7-8700K CPU with 6 cores running at 3.70GHz speed, a GeForce GTX 1080 GPU with 8GB of VRAM, and 64GB of RAM. Each MetAL training cycle needs a minimum of 7.92GB of GPU memory and 4.86GB of RAM.

C Supplementary Experiments

In addition to showcasing the most optimal hyper-parameter values in the paper, as shown in Table B.1, we conducted a thorough study to illustrate the importance of the hyper-parameters and components of our proposed MetAL approach. We tuned essential hyper-parameters such as the number of

626 tasks (N_T), support shots (K_s), query shots (K_q),
627 adaptation iterations (N_{adapt}), training batch size
628 (BS), and feeding methodology for passing batched
629 samples to the model (FM). For instance, the exam-
630 ples demonstrated in Table C.1 outline our model’s
631 performance on the tune set. We conducted five
632 experiments in which we employed different seed
633 values to randomly select tuning sets, and the re-
634 sults represent the average outcome derived from
635 all five experiments.

$N_{\mathcal{T}}$	K_s	K_q	N_{adapt}	BS	Support FM	Query FM	Epochs	Accuracy
1	1	1	1	100	random	random	667	44.08%
4	1	1	1	100	random	random	559	89.45%
4	2	2	1	100	random	random	650	91.90%
4	6	2	1	100	random	random	980	93.02%
4	6	6	1	100	random	random	680	94.71%
4	6	6	1	400	random	random	700	95.14%
4	6	6	1	100	rotation	random	760	95.37%

Table C.1: The effects of different hyperparameters on the accuracy of the model on the tune set.