

# Waste-Bench: A Comprehensive Benchmark for Evaluating VLLMs in Cluttered Environments

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## Abstract

Recent advancements in Large Language Models (LLMs) have paved the way for Vision Large Language Models (VLLMs) capable of performing a wide range of visual understanding tasks. While LLMs have demonstrated impressive performance on standard natural images, their capabilities have not been thoroughly explored in cluttered datasets where there is complex environment having deformed shaped objects. In this work, we introduce a novel dataset specifically designed for waste classification in real-world scenarios, characterized by complex environments and deformed shaped objects. Along with this dataset, we present an in-depth evaluation approach to rigorously assess the robustness and accuracy of VLLMs. The introduced dataset and comprehensive analysis provide valuable insights into the performance of VLLMs under challenging conditions. Our findings highlight the critical need for further advancements in VLLM’s robustness to perform better in complex environments. The dataset and code for our experiments will be made publicly available.

## 1 Introduction

In recent years, Large Language Models (LLMs) (Chung et al., 2024; Achiam et al., 2023; Touvron et al., 2023) have demonstrated exceptional abilities to comprehend, reason, and generate text across a wide range of open-ended tasks. Notably, PaLM 2 (Anil et al., 2023) excels in common-sense reasoning, multilingual capabilities, and advanced coding, while Falcon (Penedo et al., 2023) shows excellent performance in multiple Natural Language Processing(NLP) tasks. This success of LLMs is attributed to their superior performance on various tasks (Qin et al., 2023; Devlin et al., 2019).

Building on the advancements of LLMs, Vision-Language Models (VLLMs) have emerged, leveraging aligned image-text data from web imagery

and manual annotations to facilitate effective self-supervised vision-language modeling, including caption generation (Vinyals et al., 2015; Chou et al., 2020). This progress is exemplified by models like multimodal GPT-4 (Achiam et al., 2023; Liu et al., 2023) and open-source initiatives such as LLaVA (Liu et al., 2024). These VLLMs, developed through generative pretraining and instruction-tuning, excel in zero-shot task completion across a variety of user-oriented multimodal tasks. Their advanced capabilities are paving the way for the development of versatile multimodal conversational assistants with extensive applications in real-world scenarios (Hu et al., 2023). Vision Large Language Models (VLLMs) (Zhu et al., 2024; Shao et al., 2023; Yu et al., 2023) have demonstrated remarkable capabilities in engaging with visual content, offering a wide range of potential applications. While several benchmarks have been suggested to evaluate these capabilities, there are still challenges and opportunities for further development in this field (Yu et al., 2023; Shi et al., 2023). Notably, domains such as waste classification and segregation for improved recycling, reducing material generation, and minimizing environmental impact present significant opportunities. These advancements can lead to a substantial positive impact on environmental sustainability.

Motivated by the wide-scale applications of Vision Large Language Models (VLLMs) and the lack of comprehensive benchmarking efforts for complex visual environments, especially for waste, we present a new benchmark, Waste-Bench, to thoroughly assess the performance of VLLMs. As shown in Figure 3, Waste-Bench evaluates VLLMs on key aspects of single and multi-class recognition, robustness, and reasoning in visual tasks. It encompasses scenarios that closely mimic real-world conditions, including cluttered waste images with deformed objects. Waste-Bench is an open-ended visual QA and classification benchmark focusing



Figure 1: Examples illustrating the challenges faced by models in interpreting cluttered scenes. The model struggles with recognizing shapes, counting objects, comparing material sizes, and identifying deformed and unrecognized objects. The cluttered environment and deformed shapes significantly impact the model’s accuracy across different scenarios, as revealed by the specific questions accompanying each image.

on waste recycling. The performance of VLLMs on the Waste-Bench benchmark reveals that these models struggle to accurately comprehend complex visual environments and identify objects, particularly in cluttered scenes and when dealing with deformed shapes, counting tasks, and other challenging aspects as given in Figure 1. Extensive quantitative and qualitative analyses using the Waste-Bench benchmark provide important insights into these VLLMs based on their failure cases and individual performances across diverse visual scenarios. As illustrated in Figure 1, these shortcomings highlight the need for improved robustness and reasoning capabilities in VLLMs to better handle the intricacies of real-world environments. Our main contributions can be highlighted as below:

- We present Waste-Bench, a comprehensive benchmark designed to assess the robustness and reasoning capabilities of Vision Large Language Models (VLLMs) in waste classification, reflecting the complexities of real-world applications.
- We comprehensively evaluate a range of VLLMs, including both open-source and closed-source models. Our evaluation reveals that most models exhibit significant performance challenges, highlighting their limited

reasoning capabilities in cluttered scenes with deformed shaped objects.

- We extensively analyze VLLMs on the Waste-Bench benchmark, focusing on scenarios where models struggle, such as identifying deformed shapes, navigating cluttered scenes, and performing counting tasks. Our findings provide insights to enhance future human-centric AI systems’ robustness and reasoning for waste classification and management.

## 2 Related Work

**Vision Large Language Models(VLLMs)** (Zhu et al., 2024; Shao et al., 2023) have demonstrated remarkable capabilities in engaging with visual content, offering a wide range of potential applications. Notable models in this domain include Qwen (Bai et al., 2023), which has consistently demonstrated superior performance across various downstream tasks. LLaVA (Liu et al., 2024) and CogVLM (Wang et al., 2023) have shown robust capabilities in integrating vision and language, enabling them to excel in multimodal tasks. MiniGPT-4 and InstructBLIP (Zhu et al., 2024; Dai et al., 2024) further enhance these capabilities by leveraging generative pretraining and instruction-tuning to achieve strong zero-shot task completion. Additionally, Gemini-Pro (Reid et al., 2024) exemplifies

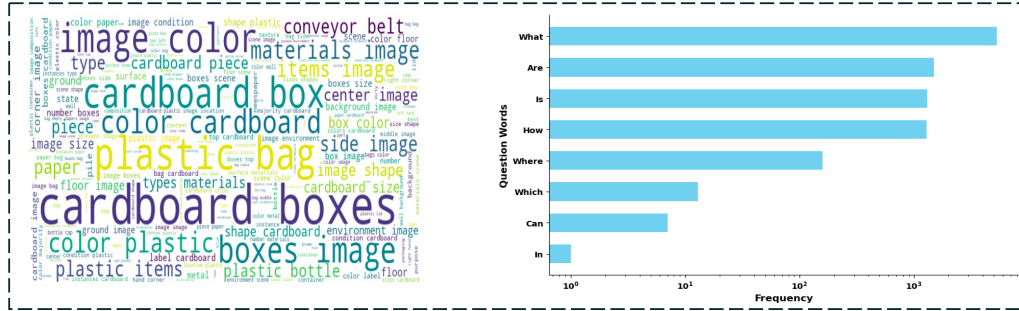


Figure 2: Waste-Bench Overview. Left: Illustration of the most frequent keywords in the answer set of the Waste-Bench benchmark. Right: Frequency distribution of question types.

state-of-the-art performance with its advanced reasoning and interaction capabilities, paving the way for the development of versatile multimodal conversational assistants. All these models perform extremely well on wide range of image understanding tasks like caption generation, visual question answering and so on. These models accept both visual and textual inputs and generate textual responses. From an architectural perspective, Vision Large Language Models (VLLMs) typically combine pre-trained vision backbones (Fang et al., 2023) with large language models (Touvron et al., 2023; Zheng et al., 2023) using connector modules such as MLP adapters, Q-former (Dai et al., 2024), and gated attention (Alayrac et al., 2022).

**Benchmarking VLLMs** With the growing number of VLLMs emerging in the research community, several benchmarks have been proposed to evaluate and quantify these models for benchmarking and analysis purposes. Notable benchmarks in this domain include SEED-Bench (Li et al., 2023b), which evaluates the visual capabilities of both image and video LMMs across multiple dimensions, and MV-Bench (Li et al., 2023a), which curates challenging tasks to evaluate the spatial and temporal understanding of VLLMs. While these benchmarks provide effective insights into model performance, they primarily focus on general visual comprehension metrics.

Additionally, LVLM-eHub (Xu et al., 2023) offers an interactive model comparison platform through image-related queries, allowing for a more dynamic evaluation of VLLMs. OwlEval (Zhou et al., 2023) and MM-Vet (Zhang et al., 2024) further underscore comprehensive Vision-Language(VL) skills by introducing evaluation metrics that transcend mere model hierarchies. MME (Chen et al., 2022) also stands out by providing

a multi-modal evaluation framework that assesses the integration of vision and language capabilities. These benchmarks contribute to a more holistic understanding of VLLM performance in various complex and realistic scenarios.

In contrast, Waste-Bench is a comprehensive benchmark designed to assess the robustness and reasoning capabilities of VLLMs in waste classification. The Waste-Bench benchmark includes scenarios with cluttered images and deformed objects to simulate real-world conditions. It aims to thoroughly evaluate the performance of VLLMs in challenging visual environments, providing a more rigorous assessment than existing benchmarks.

### 3 Waste-Bench

In this work, our objective is to develop a comprehensive benchmark to evaluate the robustness and reasoning capabilities of Vision Large Language Models (VLLMs) in various complex and cluttered visual environments, spanning diverse scenarios. To achieve this, we introduce Waste-Bench. Initially, we offer a holistic overview of Waste-Bench and outline the diversity of questions it contains. Following this, we detail the creation process of Waste-Bench in Section 3.2. Performance evaluation including experiments and results are given in Section 4.

#### 3.1 Waste-Bench Dataset

Waste-Bench encompasses 11 different question categories and 9,520 high-quality open-ended question-answer (QA) pairs, spanning 952 high-quality images with an average of 10 questions per image. These questions cover diverse categories related to real-world waste classification scenarios, including individual classification of waste classes, multi-class classification, shapes of objects, and

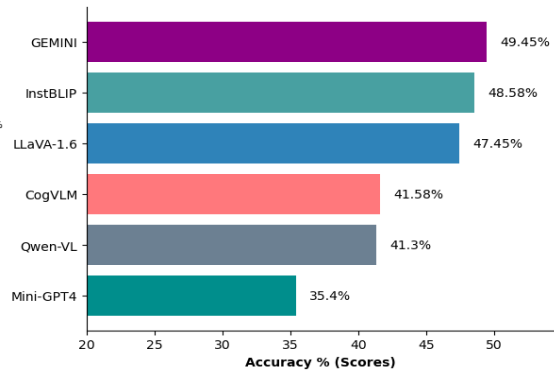
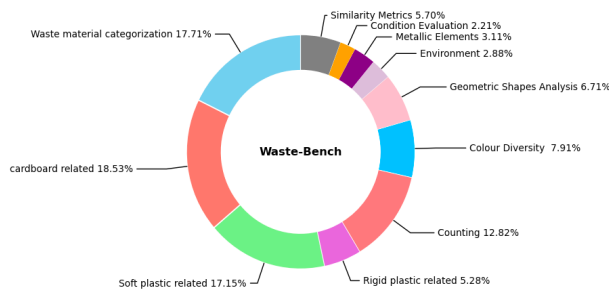


Figure 3: Left: Waste-Bench comprises of 11 diverse complex question categories encompassing a variety of waste images context. Right: Overall performance of VLLMs across the images.

211 colors. This comprehensive dataset is designed to  
 212 rigorously test the capabilities of Vision Large Lan-  
 213 guage Models (VLLMs) in handling complex and  
 214 cluttered visual environments. In Figure 2 (right),  
 215 we present the distribution of different question  
 216 types in Waste-Bench, aimed at evaluating model  
 217 robustness related to classification categories. Fig-  
 218 ure 2 (left) shows a word cloud of frequent key-  
 219 words in the answer set, emphasizing objects and  
 220 attributes relevant to waste classification.

### 221 3.1.1 Waste-Bench Different Question Types

222 To assess the robustness and reasoning capabilities  
 223 of Vision Large Language Models (VLLMs) in the  
 224 Waste-Bench benchmark, we ensure it contains var-  
 225 ious question types to encompass a wide range of  
 226 real-world complex and cluttered visual environ-  
 227 ments within each image. Below, we provide a  
 228 detailed definition of the Waste-Bench as given in  
 229 Figure 3.

- 230 • **Single Class Classification (Cardboard, Metal,**  
 231 **Soft Plastic, Rigid Plastic):** This category in-  
 232 cludes questions that require the model to  
 233 classify individual waste items into one of  
 234 the specified single classes. The questions  
 235 aim to determine whether the model can ac-  
 236 curately identify and distinguish between dif-  
 237 ferent types of materials commonly found in  
 238 waste.
- 239 • **Multiclass Categorization:** In this category,  
 240 the models are challenged with images con-  
 241 taining multiple deformed waste items that  
 242 need to be classified into more than one cat-  
 243 egory. The goal is to assess the model’s abil-  
 244 ity to handle complex scenes where multiple  
 245 waste types are present and need to be accu-  
 246 rately categorized.

- 247 • **Counting:** This category involves tasks where  
 248 the model must count the number of specific  
 249 items or categories within an image. For  
 250 example, counting the number of cardboard  
 251 pieces or the number of recyclable items in  
 252 a cluttered environment. The questions are  
 253 designed to evaluate the model’s precision in  
 254 quantifying objects in a scene.
- 255 • **Color Diversity:** This question type tests the  
 256 model’s ability to distinguish and identify  
 257 items based on color. Tasks in this category  
 258 include identifying objects of a specific color  
 259 or categorizing items by color diversity. It as-  
 260 sesses the model’s capability to utilize color  
 261 as a key feature in classification.
- 262 • **Geometric Shape Analysis:** This category of  
 263 questions focuses on the model’s ability to re-  
 264 cognize and categorize objects based on their  
 265 geometric shapes. Questions involve identify-  
 266 ing items with specific shapes, such as cylin-  
 267 drical, circular or rectangular objects, which  
 268 are common in waste sorting processes.
- 269 • **Complex and Cluttered Environment:** This  
 270 category includes questions to evaluate the  
 271 model’s performance in recognizing and rea-  
 272 soning about the environment in which waste  
 273 is found. Model evaluates whether waste is  
 274 in an indoor or outdoor setting. It includes  
 275 questions that require comprehensive image  
 276 analysis.
- 277 • **Condition Evaluation:** In this category, the  
 278 model must evaluate the condition of waste  
 279 items. This includes assessing whether items  
 280 are intact, twisted, clean or dirty. The ques-  
 281 tions are designed to test the model’s ability

- 282 to make nuanced judgments about the state of  
283 objects.
- 284 • **Similarity Metric:** These questions require the  
285 model to compare and determine the similarity  
286 between different waste items. For example,  
287 identifying items that belong to the same cate-  
288 gory or have similar features. It assesses the  
289 model’s ability to draw comparisons and make  
290 associations based on visual features, robust-  
291 ness in recognizing objects in challenging set-  
292 tings, and adaptability to varying conditions.
  - 293 • **Combined Classification and Counting:** This  
294 category merges classification and counting  
295 tasks, requiring the model to not only clas-  
296 sify multiple items in a scene but also provide  
297 accurate counts for each category. This com-  
298 bined approach tests the model’s capability to  
299 perform multiple reasoning tasks simultane-  
300 ously.

301 These question types present in our dataset help  
302 to rigorously test the capabilities of VLLMs in  
303 handling the intricacies of waste classification in  
304 complex and cluttered environments.

### 305 3.2 Building Waste Bench Benchmark

306 After defining the waste dataset question cate-  
307 gories, we now proceed to building the Waste-  
308 Bench benchmark, which consists of four steps.  
309 Each step is presented in detail below, and can be  
310 visually explored in Figure 4.

311 **Stage 1: Data Collection and Annotation.** We  
312 thoroughly reviewed various datasets to find those  
313 that represent waste images within cluttered en-  
314 vironments. We meticulously pre-processed the  
315 metadata provided with the images to ensure ac-  
316 curate representation of the categories assigned to  
317 each image. The test dataset contains 952 images.  
318 Following the image collection process, we utilized  
319 the Gemini-Vision model to generate high-quality  
320 captions for these images. These captions were  
321 subsequently verified by experienced human an-  
322 notators. We adhered to stringent annotation and  
323 verification instructions to ensure a robust and reli-  
324 able set of captions. The prompt used for generat-  
325 ing captions is provided in Figure 4. Personalized  
326 annotation guidelines were used for each image  
327 category to ensure accuracy.

328 **Stage 2: Question-Answer Generation** The first  
329 challenge is to select an evaluation setting to assess

VLLMs. Inspired by human interaction in day-to-  
day life, we aim to simulate a similar style of in-  
teraction with VLLMs by curating open-ended QA  
pairs to evaluate these models for robustness and  
reasoning. We feed detailed ground-truth image  
captions to GPT-3.5, which are utilized to generate  
open-ended questions covering both reasoning and  
robustness aspects. With VLLMs being increas-  
ingly integrated into waste management systems,  
it’s crucial to validate their ability to accurately  
analyze and respond to questions about waste ob-  
jects in cluttered environments. In evaluating the  
capabilities of VLLMs, our goal is to determine  
whether these models can understand the input im-  
age not only by analyzing spatial content and rec-  
ognizing classes but also by comprehending the  
underlying rationale behind the depicted waste ob-  
jects and their relationships with the surrounding  
context. This involves creating questions that go  
beyond simple image comprehension and require  
the model to engage in complex logical inference  
and contextual understanding. Specifically, we cre-  
ate question types that test the model’s ability to  
classify objects based on recognition, color, shape,  
single class, multiclass, condition, and other rele-  
vant aspects in complex, cluttered settings. It was  
particularly challenging to ensure that the models  
not only correctly analyzed the images but also  
responded accurately and appropriately to the ques-  
tions posed. Example prompts used as instructions  
to LLMs for curating QA pairs are provided in Fig-  
ure 4.

362 **Stage 3: QA Pairs Filtration** After generating QA  
363 pairs, a manual filtration step is employed, with  
364 human assistance to verify each generated QA pair.  
365 Therefore, an exhaustive filtering process is con-  
366 ducted which involves QA rectification and remov-  
367 ing those samples which are not relevant to the  
368 image or evaluation type. This process results in  
369 a final set of 9552 high-quality QA pairs for the  
370 Waste-Bench benchmark.

371 **Stage 4: Evaluation Procedure** Previous methods  
372 in the literature have explored using LLM mod-  
373 els as judges for quantifying results in open-ended  
374 QA benchmarks. We adopt a similar approach and  
375 instruct LLMs to act as evaluators to assess the  
376 correctness of predicted responses from VLLMs  
377 compared to ground-truth answers. We generate  
378 open-ended predictions from VLLMs by providing  
379 image-question pairs as inputs and then present the  
380 model predictions and their corresponding ground-  
381 truth responses to the LLM Judge alongside the

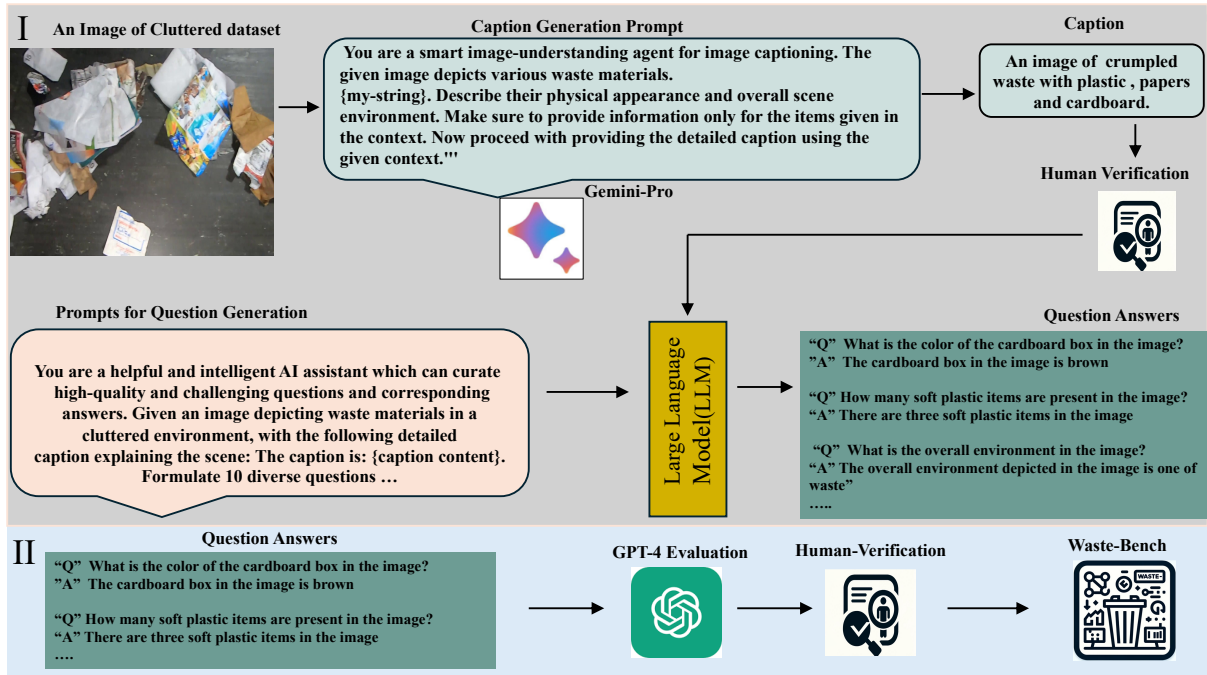


Figure 4: Step I: Gemini-Pro generates detailed captions for images of waste, which are then verified by human annotators. Step II: Nearly 10k diverse questions are generated from these captions, evaluated by GPT-4, and verified by humans.

evaluation prompt. The Judge determines whether the prediction is correct or incorrect through a binary judgment, assigns a score from 1 to 5 representing the quality of the prediction, and provides reasoning to explain its decision. The evaluation prompt used in our case is shown in Figure 5.

```

"role": "system",
"content": "You are an intelligent chatbot designed for evaluating the correctness of AI assistant predictions for question-answer pairs. "
"Your task is to compare the predicted answer with the ground-truth answer and determine if the predicted answer is correct or not. Here's how you can accomplish the task:"
"-----"
"##INSTRUCTIONS:"
"- Focus on the correctness and accuracy of the predicted answer with the ground truth.\n"
"- Consider predictions with less specific details as correct evaluation, unless such details are explicitly asked in the question.\n"
},
{
"role": "user",
"content": "please evaluate the following question-answer pair:\n\n"
"Question: {question}\n"
"Ground truth correct Answer: {ground truth}\n"
"Predicted Answer: {predicted}\n\n"
"Provide your evaluation as a correct/incorrect prediction along with the score where the score is an integer value between 0 (fully wrong) and 5 (fully correct). The middle score provides the percentage of correctness."
"Please generate the response in the form of a Python dictionary string with keys 'predicted', 'score' and 'reason', where the value of 'predicted' is a string of 'correct' or 'incorrect', the value of 'score' is in INTEGER, not STRING, and value of 'reason' should provide the reason behind the decision."
"Only provide the Python dictionary string."
"For example, your response should look like this: {'predicted': 'correct', 'score': 4.8, 'reason': 'reason'}."

```

Figure 5: The prompt is designed to enable the Language Model to act as an evaluation judge, assessing and scoring the performance of VLLMs. It categorizes responses as accurate or not and assigns a score from 1 to 5 based on the correctness and quality of the prediction. Additionally, it also provides the reasoning.

## 4 Performance Evaluation on Waste-Bench

Both open-source and closed-source models are explored and selected for the evaluation. We evaluate six models in total where among the open-source models, we evaluate five recent VLLMs, including InstructBLIP, LLaVA-1.6, CogVLM, Qwen-VL, and MiniGPT-4. For evaluating closed-source models, we use Gemini-Pro.

### 4.1 Main Experiments on Waste-Bench

In Table 1, we present the evaluation results of various Vision Large Language Models (VLLMs) across accuracy metrics on the Waste-Bench dataset. We analyse these results and present several key findings.

**Open Source VLLMs Struggle on Waste Bench having cluttered environment** : All open-source VLLMs find it challenging to perform well and thus show inferior performance when evaluated on the Waste-Bench dataset, particularly in cluttered scenes. Additionally cluttered scenes filled with deformed shaped objects make the task more competitive. Interestingly, the performance of models like LLaVA-1.6, and InstructBLIP is relatively higher compared to models such as Qwen-VL and MiniGPT-4. For instance, Gemini achieves an ac-

Model	Versions	LLM	Accuracy	Score
Gemini	Gemini-1.0 Pro	Proprietary LLM	49.45	3.09
LLaVA	LLaVA-1.6	Vicuna-7B	47.45	3.06
Qwen-VL	Qwen-VL-Chat	Qwen-7B	41.30	2.60
MiniGPT-4	MiniGPT-4	Vicuna-7B	36.40	2.53
CogVLM	Cogvlm-chat-v1.1	Vicuna-7B	41.58	2.81
InstructBLIP	BLIP-2_Vicuna_Instruct	Vicuna-7B	48.58	3.03

Table 1: Evaluation results of various VLLMs across different accuracy metrics. We present results for both open-source and closed-source models, providing a comprehensive assessment of their performance.

414 accuracy of 49.45% with a score of 3.09, however  
415 MiniGPT-4 suffers severely with these particularly  
416 challenging conditions and thus under perform. Ta-  
417 ble 1 results show Accuracy of the response and  
418 the score of the models where total score is 5.

#### 419 **Closed Source Model Perform Competitively on** 420 **Waste-Bench:**

421 As shown in Table 1, the Gemini model sur-  
422 passes the performance of open-source models  
423 and achieves high gains compared to other mod-  
424 els. However, it still remains at the lower end of  
425 performance for this type of dataset, with an accu-  
426 racy below 50%. GEMINI handles cluttered scenes  
427 with deformed shaped objects, better than others,  
428 indicating a more sophisticated understanding of  
429 complex visual contents. In handling cluttered con-  
430 ditions with mixed and deshpaed objects, Gem-  
431 ini maintains a performance with an accuracy of  
432 49.45% and a score of 3.09.

433 **Comparison Across Models:** As evident from Ta-  
434 ble 1, among the models evaluated, Gemini consis-  
435 tently outperforms others with the highest accuracy  
436 of 49.45%. This is followed closely by InstBLIP  
437 with an accuracy of 48.58% and 42.29%, respec-  
438 tively. On the other hand, models like MiniGPT-4  
439 and Qwen-VL show lower performance metrics,  
440 with MiniGPT-4 having the lowest scores 36.40%.

## 441 **4.2 Key Highlights and Qualitative Results**

442 Based on the evaluation of Vision Large Language  
443 Models (VLLMs) on the Waste-Bench benchmark,  
444 several key insights have emerged that provide valu-  
445 able guidance for future development. This analy-  
446 sis focuses on the models’ performance under dif-  
447 ferent conditions, highlighting their strengths and  
448 areas needing improvement. Models show weak  
449 reasoning capabilities, often failing to accurately  
450 identify objects and understand contexts in clut-  
451 tered environments. For instance, cluttered scenes  
452 lead to frequent classifications, such as confusing

453 different types of plastics or failing to recognize  
454 partially obscured objects, thus ignoring the pres-  
455 ence of the objects in the image. Few samples are  
456 shown in the Figure 6 for reference.

457 **Issues in Real-World Waste Classification:** Mod-  
458 els which shows super performance on organized  
459 exhibit less promising results on Waste-Bench es-  
460 pecially in counting irregular shaped objects and  
461 and many a times predicting the colour wrong be-  
462 cause of clutter and presence of one object on top of  
463 the other. Figure 6 second row shows the question  
464 asked about color of the plastic bag and as transpar-  
465 ent plastic is present on top of cardboard it seems  
466 as pink so model predicts it as pink. Most mod-  
467 els are trained on datasets that lack the complexity  
468 of real-world waste scenarios. This training bias  
469 results in poor generalization to the diverse condi-  
470 tions of Waste-Bench. Enhanced training strategies,  
471 including diverse and realistic samples, are needed  
472 to improve robustness.

473 **Recognition and Counting Challenge:** Models  
474 generally struggle with recognizing and classifying  
475 objects across all classes in cluttered environments.  
476 They often face significant challenges with soft  
477 plastics, which exhibit a wider range of shapes,  
478 sizes, and levels of transparency, complicating ob-  
479 ject enumeration. As illustrated in Figure 6, ques-  
480 tions related to the shape and color of soft plastics  
481 are frequently answered incorrectly by the models.  
482 This discrepancy highlights the difficulties models  
483 encounter in accurately identifying and classify-  
484 ing objects in cluttered environments. Addition-  
485 ally, models often struggle with partially occluded  
486 objects or objects that are very small, sometimes  
487 failing to recognize them entirely. However, mod-  
488 els perform slightly better on cardboard due to its  
489 distinctive features. Cardboard typically exhibits  
490 consistent visual features such as texture, color,  
491 and edges, which facilitate easier recognition and  
492 classification. These features are less susceptible to



Figure 6: Qualitative results illustrating models struggling with identifying shapes, colors, and recognizing rare classes within cluttered scenes, indicating areas for further investigation and improvement.

the effects of clutter compared to the more varied appearances of soft plastics. Cardboard items are often larger and more easily distinguishable, simplifying the counting process. Thus, while there are overall challenges, the models show a relatively better performance with cardboard due to its distinct and consistent visual features.

**Classifying Visually Similar Objects:** The models often struggle with accurately predicting similar objects due to the complexity and clutter in the scenes. For instance, in the case of identifying hard plastic, the models frequently confuse it with soft plastic. In cluttered scenes, soft and hard plastics may overlap or be partially obscured, further complicating the classification task. Even small amounts of noise in the images can distort the visual features that the models rely on to differentiate between soft and hard plastics. This added complexity degrades the model’s performance and increases the likelihood of misclassification. As illustrated in Figure 1, the image in the center shows an example where the model confused soft plastic and hard plastic, classifying both as plastic. This response is highlighted by the model’s answer to Question 3.

**Challenges in Rare Class Recognition:** Models often struggle with accurately recognizing and classifying less frequent categories within cluttered scenes, especially when these objects are deformed. This difficulty is particularly evident in the case of

metals, a class with a small number of instances in the images. As illustrated in fig:evaluation (bottom row), the models frequently miss minor details or fail to identify metals, indicating a need for better handling.

**Challenges with Noise and Enhanced Lighting:** While not the main focus of our paper, we observed that introducing noise or enhanced lighting conditions in images exacerbates performance issues in some models. For instance, some models suffer a significant drop in accuracy with noise, highlighting their vulnerability, whereas others demonstrate better noise-handling capabilities. These findings suggest the importance of considering environmental factors in future evaluations.

## 5 Conclusion

In this paper, we evaluated various VLLMs in complex environments with deformed objects, revealing significant weaknesses in identifying shapes, colors, and locations. We introduced the Waste-Bench benchmark, featuring multiple categories to enable comprehensive validation of these models. The Waste-Bench benchmark provides a robust framework for assessing VLLMs in challenging conditions, aiding in the development of more resilient and accurate models for real-world applications like waste segregation and autonomous waste management.



**Limitations** Our study though comprehensive has some limitations. The scope of our evaluation was limited to a specific set of cluttered environments, which may not fully represent the variety of real-world scenarios. Additionally, the models were tested under controlled conditions, and their performance in more dynamic and unpredictable settings remains to be explored. We tested models on a variety of questions to ensure robust testing for our evaluation purposes, accuracy and score were calculated and seemed sufficient, showcasing the robustness of our approach. Incorporating additional evaluation methods in future work could provide an even more comprehensive understanding. Despite these limitations, our findings offer valuable insights and a strong foundation for advancing research in this area.

**Ethics Statement** We constructed this dataset based on images given in zwaste-f dataset (Bashkirova et al., 2022). We constructed this dataset based on images provided in the Zerowaste-F dataset (Bashkirova et al., 2022). This dataset includes various images of waste in cluttered environments to simulate real-world conditions. Some images contain identifiable objects, but we ensured that no personal identification details are included. When used properly, our image and annotation dataset provides significant value for evaluating waste classification models.

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