

WILT: A MULTI-TURN, MEMORIZATION-ROBUST INDUCTIVE LOGIC BENCHMARK FOR LLMs

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ABSTRACT

While large language models (LLMs) have shown impressive capabilities across a wide range of domains, they still encounter significant challenges in reasoning tasks that require gathering evidence over multiple turns and drawing logical conclusions from this evidence. These challenges present significant obstacles for LLM chat user interfaces, which rely on multi-turn interactions to facilitate effective collaboration. This limitation leads to real-world issues; for example, service chatbots must gather necessary information from customers over multiple turns to diagnose and resolve problems effectively. Despite the multi-turn nature of many real-world LLM use cases, most existing benchmarks rely on carefully curated single-turn tests, which often blur the line between memorization and genuine reasoning. To address this, we introduce the **Wason Inductive Logic Test (WILT)**, a simple yet challenging multi-turn reasoning benchmark designed to resist memorization. WILT is inspired by the Wason 2-4-6 task (Wason, 1960), where participants must infer a basic boolean function involving three variables (e.g., $x < y < z$) by proposing test cases (such as (2, 4, 6)). In WILT, each test starts from a clean slate, with only the initial instructions provided, preventing models from relying on pre-learned responses. Over several turns, models must interact with the environment by suggesting test cases to narrow the possible hypotheses and ultimately infer the hidden function based on the outcomes. Our findings reveal that LLMs struggle with this task, exhibiting distinct strengths and weaknesses: some are better at narrowing down the hypothesis space by proposing valuable test cases, while others are more adept at deducing the hidden function from observed cases. Despite these variations, the best-performing model achieves only 28% accuracy, highlighting a significant gap in LLM performance on complex multi-turn reasoning tasks.

1 INTRODUCTION

Large language models (LLMs) powered by the transformer architecture (Vaswani, 2017) have enabled a new computing paradigm driven by natural language. These models are increasingly integrated into day-to-day life beyond the machine learning research space, where they help many people with common tasks. These models interact with users through *multi-turn conversations*, a capability of next-token-prediction models bolstered via instruction-tuning (Mishra et al., 2021) and alignment post-training phases (Ouyang et al., 2022). Despite their impressive single-turn performance, LLMs often falter in scenarios requiring multi-turn reasoning and evidence gathering.

The reasoning capability of LLMs, particularly in multi-turn scenarios, is of substantial interest. A commonly reported failure pattern for LLMs is the “doom loop”, where after an initially unsatisfactory response, the model repeatedly responds with a near-identical message to one of its earlier messages, providing minimal utility. For example, in code generation tasks like the example shown in Figure 1, a model may repeatedly reply with code blocks identical to ones it has already seen or produced, which impairs its subsequent usefulness. Strong multi-turn performance can be thought of as collecting evidence over multiple steps to reduce the hypothesis space of the model’s possible responses to only include useful ones: an important capability which remains critical beyond the first turn even in everyday LLM use cases.

054 Measuring the performance of LLMs has been challenging for the research community. Existing
 055 benchmarks overwhelmingly focus on single-turn interactions (Hendrycks et al., 2020; 2021), and
 056 are often subject to memorization or overfitting (Goodhart, 1984; Recht et al., 2019). As a result, dif-
 057 ficult benchmarks often keep a held-out, publicly unavailable test set to accurately evaluate models
 058 (Chollet, 2019). While some multi-turn benchmarks have emerged to attempt to measure phenom-
 059 ena like the “doom loop” (McLaughlin, 2024), none so far have done so for multi-turn, multi-step
 060 inductive reasoning.

061 To bridge this gap, we introduce the **Wason Inductive Logic Test (WILT)**, a multi-turn benchmark
 062 designed to assess LLMs’ ability to gather evidence and reason across multiple turns. Inspired by the
 063 Wason 2-4-6 task (Wason, 1960), WILT requires models to propose test cases (e.g. (2, 4, 6)), observe
 064 the results (True or False), and iteratively narrow down the hypothesis space in order to deduce a
 065 hidden rule (e.g. $x < y < z$). Since the task always begins from an identical starting state, it cannot
 066 simply be solved by memorizing the answer to a prompt and forces the model to use multiple turns
 067 to gather evidence. Therefore, WILT explicitly tests for two important capabilities in an LLM: (1)
 068 whether the model can efficiently narrow down the hypothesis space of possible solutions by posing
 069 the right test cases over multiple turns, and (2) whether the model can recommend a simple and
 070 meaningful solution to the problem after accumulating evidence. While we find that LLMs struggle
 071 on this task overall, we find that some of them are better on one of aforementioned sub-tasks than
 072 the other. This knowledge can be useful for practitioners when choosing which models to deploy
 073 for real world use cases.

074 In this work, we make the following contributions:

- 075 1. **Introducing WILT** - We introduce a multi-turn inductive logic benchmark that cannot be
 076 solved in a single turn. This requires a model to gather information, reflect upon what it
 077 observes, and make decisions when sufficient evidence is gathered, mirroring real-world
 078 tasks like debugging code or reasoning over time.
- 079 2. **Evaluating LLMs** - We show that state-of-the-art LLMs struggle significantly on this task,
 080 with the best model achieving only 28% accuracy. This highlights a significant deficiency
 081 in multi-turn performance of top-performing LLMs, suggesting that strong single-turn per-
 082 formance may not always transfer to multi-turn settings.
- 083 3. **Further Analysis** - We perform several experiments analyzing hypothesis space reduction,
 084 response complexity, and the performance of models when provided test cases from a dif-
 085 ferent model. We demonstrate that models have varied strengths and weaknesses on this
 086 task, and that combining models together in a multi-turn setting may increase performance
 087 compared to using a single strong model.

089 2 WILT

091 The Wason Inductive Logic Test (WILT) is a benchmark for LLM reasoning inspired by the Wason
 092 2-4-6 task (Wason, 1960). Models begin with the instruction that they must uncover the hidden rule,
 093 and may pose up to 30 test cases of that rule. For example, they can pose the tuple (2, 4, 6) and the
 094 test will respond with “True, 29 Attempts Remaining.”

095 All hidden rules take three numbers and return a boolean. These rules are simple and non-stochastic,
 096 so there is no additional value to posing the same test multiple times. Valid inputs include any float
 097 or integer that can be typed in three or fewer characters, excluding signs and the decimal point (e.g.
 098 -999, 1.23, 5). The hidden rules are written as Python lambda functions. After a maximum of thirty
 099 tries (or any turn before then), the model may make one attempt to guess the function, after which
 100 the test will terminate. The model must return a Python lambda function that is the same as or
 101 equivalent¹ to the hidden rule in order to receive full points.

102 WILT is conceptually simple, but very challenging. Humans are able to identify simple rules despite
 103 the infinitely large hypothesis space, the unbounded difficulty of a hidden function, and the impos-
 104 sibility of verifying the correctness of your response (Tweney et al., 1980; Tukey, 1986). Without
 105 effective priors for what constitutes a “simple” or “reasonable” answer, it becomes trivial to con-
 106 struct an arbitrary counterexample to a current hypothesis. For example, consider the canonical

107 ¹For example, $x - y = z$ is equivalent to $y + z = x$

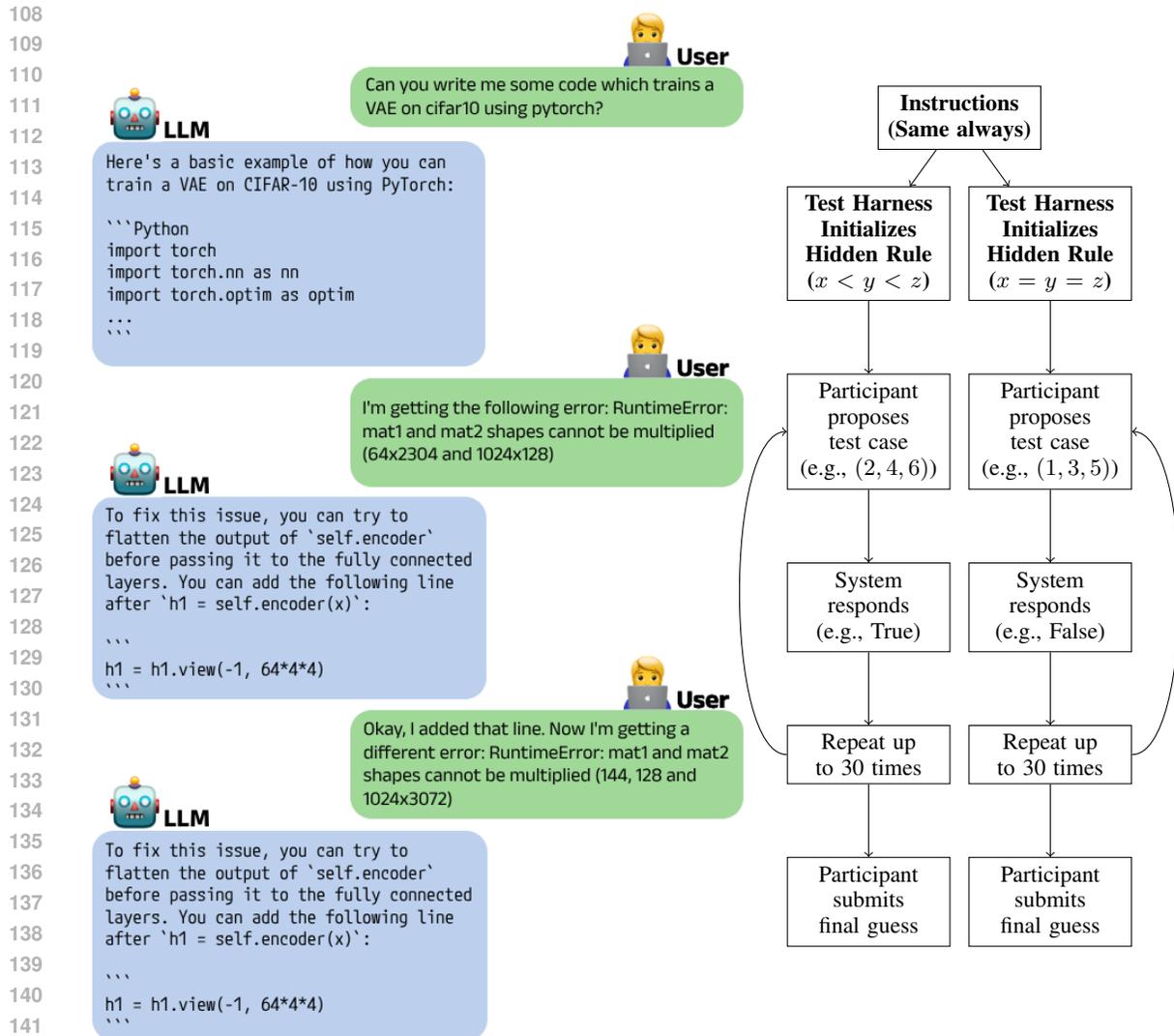


Figure 1: Left: Abbreviated example of the “doom loop” phenomenon observed in appendix C.1. The model returns an unsatisfactory response on an early turn, and devolves into repeating the same suggestions in subsequent turns. Right: Overview of the WILT task. For each test, the test harness initializes a hidden rule, and participants propose up to 30 test cases for each hidden rule before making a final guess.

Wason task rule of $x < y < z$. This rule has very high overlap with the much more arbitrary rule $(x < y < z) \wedge (x \neq 12)$.

The WILT benchmark therefore tests a few high-value behaviors of interest:

1. **Multi-Turn Capability:** Participants that fall into doom loops are punished by virtue of having less useful information with which to infer the hidden rule.
2. **Hypothesis Space Reduction:** Participants are rewarded for proposing test cases that effectively narrow down the possible rules, despite that hypothesis space being infinitely large.
3. **Susceptibility to Confirmation Bias:** Participants who are more prone to “confirming their hypothesis” rather than seeking falsification will perform poorly upon this task.
4. **Inductive Reasoning:** Proposing good test cases is a useful test of inductive reasoning and the ability to generalize from a number of specific examples.

- 162 5. **Deductive Reasoning:** Proposing sensible functions after observing many test cases is
 163 a useful test of deductive reasoning. Success in this task involves identifying a specific
 164 function that accurately fits a set of examples.
- 165 6. **Occam’s Razor:** Participants are rewarded for finding the simplest explanation fitting the
 166 examples.

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168 We release two test suites: a *lite split*, with 10 very easy tests and a canonical *full split* with 50
 169 moderately difficult tests². Future work will extend this to include a procedurally generated split for
 170 additional robustness to overfitting. We find that the lite split quickly produces a roughly similar
 171 ordering to the full split, but we report results upon the full split for the remainder of this work.
 172 Please see Appendix A.4 for further details.

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174 3 RELATED WORK

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176 Compared to other reasoning benchmarks, WILT stands out as both highly multi-turn focused and
 177 unusually robust to memorization. In contrast to other benchmarks, WILT requires models to *in-*
 178 *teract with an environment* by proposing their own test cases to uncover a hidden function without
 179 relying on pre-provided examples. This setup reduces the risk of overfitting, as each test begins with
 180 the same initial instructions, and the model must generate and interpret its own data.

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182 3.1 REASONING BENCHMARKS

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184 There are a wide variety of reasoning benchmarks used to evaluate large language models. Some
 185 very notable among these are MATH (Hendrycks et al., 2021), GSM8K (Cobbe et al., 2021), Com-
 186 monsenseQA (Talmor et al., 2018), StrategyQA (Geva et al., 2021), BIG-BENCH (Srivastava et al.,
 187 2022), SciBench (Wang et al., 2023b), SVAMP (Patel et al., 2021), ARC-AGI (Chollet, 2019),
 188 MMLU (Hendrycks et al., 2020), GPQA (Rein et al., 2023), and HumanEval (Chen et al., 2021).
 189 These benchmarks are the standard for measuring LLM reasoning capabilities, but are overwhelm-
 190 ingly carefully chosen single-turn problems which aim to meaningfully separate the performance
 191 of different models on reasoning-like outputs such as math, code, or logic puzzles. However, these
 192 benchmarks are subject to train-on-test leakage, even if efforts are made to decontaminate the dataset
 193 (Yang et al., 2023), and the majority are explicitly single-turn tests. Our benchmark directly mea-
 194 sures the model’s ability to navigate multi-turn scenarios, and does not require careful hiding of a
 test set to prevent misleading results.

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196 With respect to reasoning about simple functions, a benchmark that stands out as similar to ours
 197 is CRUXEval (Gu et al., 2024), which assembles a list of 800 simple Python functions and input-
 198 output pairs, and evaluates language models on their ability to predict input from output and output
 199 from input. Our work could be seen as a multi-turn, more difficult extension of this work – one
 200 where the function is replaced with a black box, where helpful and informative input-output pairs
 201 are not provided but instead need to be searched for by the language model, and where the objective
 is to infer the hidden function rather than the input or output.

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203 3.2 MULTI-TURN BENCHMARKS

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205 There are a handful of multi-turn benchmarks used to evaluate LLMs. PlanBench (Valmeekam et al.,
 206 2022) is one prominent benchmark which attempts to measure the ability of LLMs to navigate plan-
 207 ning problems. This is a class of problems which are solved easily by classical planning algorithms
 208 such as STRIPS (Fikes & Nilsson, 1971), and like our benchmark poses a significant challenge to
 209 LLMs. PlanBench is a primarily multi-step, single-turn benchmark with a multi-turn component
 210 (i.e. replanning based on unexpected events), which contrasts with our benchmark’s more direct
 211 multi-turn focus. This can be observed in the o1 models performing comparatively well on Plan-
 212 Bench (Valmeekam et al., 2024), since scaling inference time compute within a single turn would
 be expected to improve performance substantially.

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214 Closest to ours is Aidan-bench (McLaughlin, 2024), which directly measures the cosine similar-
 215 ity between multi-turn responses. This represents a more pure measurement of the doom loop

²We will release the code for this benchmark with the final release of the full paper.

Table 1: Model Accuracy Comparison

Model	Accuracy	Approx. Correct	Avg. Guesses	Avg. Repeats
Claude 3.5 Sonnet (Anthropic, 2024a)	14/50	10/50	16.38	0.54
o1-mini 2024-09-12 (OpenAI, 2024c)	13/50	8/50	12.1	0.06
o1-preview 2024-09-12 (OpenAI, 2024c)	12/50	6/50	8.12³	0.06
chatgpt-4o-latest (OpenAI, 2024a)	11/50	7/50	14.22	0.76
Mistral Large 2 (Mistral AI, 2024a)	11/50	5/50	26.56	2.84
GPT-4o 2024-08-06 (OpenAI, 2024a)	9/50	6/50	15.26	0.52
Llama 3.1 405B (Dubey et al., 2024)	8/50	9/50	12.21	0.60
Gemini 1.5 Flash 0827 (Google, 2024)	7/50	4/50	14.04	2.16
Llama 3.1 70B (Dubey et al., 2024)	7/50	2/50	15.18	1.48
Deepseek-v2.5-chat (Liu et al., 2024)	6/50	5/50	27.22	9.78
GPT-4o-mini (OpenAI, 2024b)	6/50	2/50	20.36	1.08
Gemini 1.5 Pro (Google, 2024)	5/50	6/50	16.78	0.82
Gemini 1.5 Flash (Google, 2024)	5/50	6/50	16.5	2.46
Deepseek-v2-coder (Zhu et al., 2024)	5/50	5/50	21.82	6.70
Deepseek-v2-chat (Liu et al., 2024)	3/50	3/50	25.32	6.68
Llama 3.1 8b (Dubey et al., 2024)	3/50	0/50	26.18	4.46
Open Mistral Nemo (Mistral AI, 2024b)	2/50	3/50	27.34	8.00
Claude 3 Haiku (Anthropic, 2024b)	1/50	1/50	6.76	0.22
Gemini 1.5 Flash 8b 0827 (Google, 2024)	0/50	2/50	26.76	7.72
Gemma 2 9B (Team et al., 2024)	0/50	2/50	8.82	1.40

phenomenon. In our benchmark, rather than directly measuring the doom loops, we are instead measuring how often those doom loops lead to failures of reasoning. We see similar surprising performances in our benchmark compared to Aidan-bench (e.g. Mistral Large’s noteworthy ability at multi-turn), but with an ordering more tied to capabilities (e.g. Sonnet’s superior performance, see Table 1).

3.3 HYPOTHESIS SPACE REDUCTION

Hypothesis space representation is a commonly used framing in inductive logic tasks for LLMs. In Wang et al. (2023a), the authors show a technique called *hypothesis search* where the model will propose hypotheses in natural language and then implement these hypotheses as Python programs. This technique was shown to improve performance on ARC-AGI (Chollet, 2019), but a similar approach could be used along with chain-of-thought (Wei et al., 2022) for WILT as well.

4 EXPERIMENTS

4.1 WILT FULL SPLIT RESULTS

We evaluated several state-of-the-art LLMs on the full split of the WILT task. Experimental details can be found in Appendix A.1. Our results for this test can be found in Table 1. Claude 3.5 Sonnet narrowly performs the best on this task, with OpenAI’s o1 models close behind despite using fewer guesses.

In Table 1, we include a column *approximately correct*, measuring the number of rules in which the model was able to correctly identify some critical behavior of the rule, but returned a rule with failing edge cases³. For example, guessing $(x < y < z)$ instead of $(x \leq y \leq z)$ is approximately correct. We include this column to highlight models that are more willing to guess immediately instead of uncovering edge cases by default (e.g. Llama 3.1 405B). In these cases, we could see potentially

³We bold results for this column only if the models are also high performing. For example, Claude 3 Haiku uses fewer guesses than o1-preview, but this is because it is failing to make use of its available turns to uncover the behavior of the hidden rule, not because it efficiently solves the task.

improved performance through explicitly instructing the model to use more guesses. Examples of common failure patterns can be found in Appendix B.

In addition, we find that LLMs (particularly smaller ones) will frequently repeat tests they have already used, sometimes dozens of times, often with the same provided reasoning. We therefore also provide a column *average repeats* which counts the average number of proposed tests which were already tested for that rule. Further discussion on test novelty can be found in Appendix A.2.

In our experiments, we show that LLMs struggle substantially with this task. We show that despite the test’s relative simplicity, most models struggle substantially both to propose good tests and to infer a rule based on available evidence. Specifically, their propensity to repeat test cases, propose useless test cases, and guess very unlikely rules harms their performance on this task substantially. The varying performance in a multi-turn setting represents a previously unappreciated dimension of measuring reasoning capability in LLMs. There is much work in language modeling for code-based agents (Cognition AI, 2024; Yang et al., 2024a) and LLM-driven unit testing (Yang et al., 2024b), and the difficulty of LLMs to explore edge cases effectively across multiple turns has substantial implications on those applications.

As in the original Wason 2-4-6 task, we find a common failure mode to be confirmation bias – a participant will identify a plausible hypothesis and continue to propose tests that attempt to *confirm* it (see Appendix B.3). Stronger models will more explicitly attempt to *falsify* these hypotheses instead. For example, a model that observes the rule is always true when the values are all equal should attempt to test a rule like $x \leq y \leq z$, rather than submitting more cases where the three values are equal.

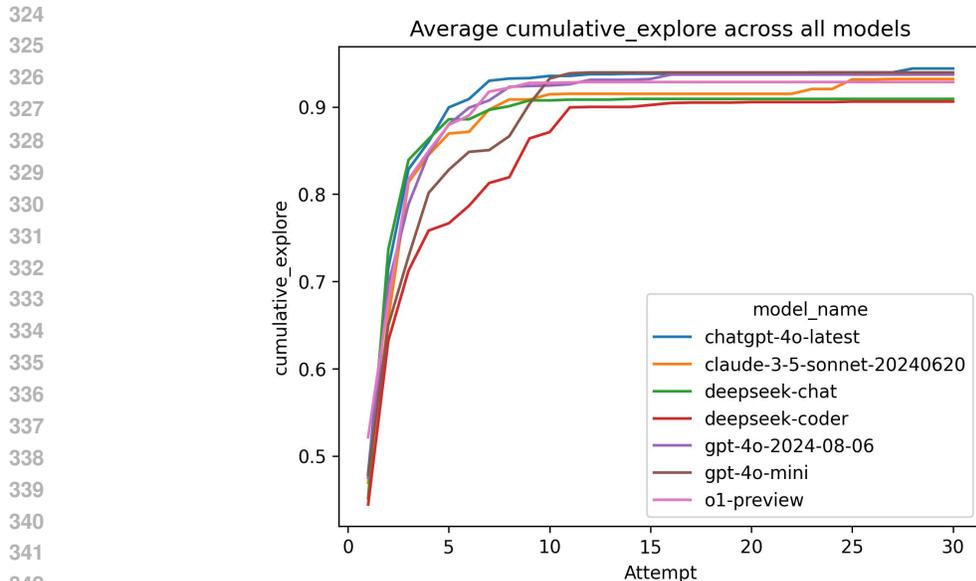
We show some varying behavior among top performing models, which highlights the multifaceted ways which a model can succeed on a multi-turn task. Claude 3.5 Sonnet performs quite well on WILT, outperforming models like o1-mini and o1-preview which tend to win on adjacent single-turn benchmarks. On most turns, WILT is a setting which removes many of the advantages of a model which has scaled up inference-time compute; each turn requires only a moderate amount of consideration, compared to other single-turn benchmarks which are *multi-step*, *single turn* and thereby reward the model substantially for long and elaborate chains of thought. o1-mini and o1-preview show astonishingly low test case reuse, and much lower than average guess count compared to Sonnet 3.5 despite comparable performance, pointing to their strong deductive reasoning skills and recollection of the previous steps in a conversation. However, they ultimately underperform due to gathering less evidence compared to Sonnet 3.5, which is a *multi-turn capabilities failure* despite *not* being a failure on any turn in particular. Put another way, Sonnet 3.5 seems better at understanding that it will be able to leverage future tests, and that its multi-turn performance shines “between” turns rather than during them.

In this vein, Mistral Large stands out as having surprisingly strong performance in multi-turn, despite its novelty metrics being below average. That is, it tends to respond with many operators (see Table 2), repeat many more tests than other similar-performing models, and responds with messages with worse novelty metrics as reported in Table 3 and Figure 5. However, it tends to use most of its available resources, accrue evidence with new tests deep into the conversation, and ultimately deduce the rule very well for a model of its size. The strong result observed from Mistral Large points towards a *multi-turn capabilities success* despite numerous *single-turn failures*, and reveals a previously underappreciated ability of this model.

4.2 HYPOTHESIS SPACE REDUCTION

To compare the LLMs’ ability to efficiently reason about the task, we estimate how effectively each model reduces the hypothesis space (Wang et al., 2023a). At best, an LLM should always propose a triplet that eliminates as many untested hypotheses as possible. At worst, a model repeatedly proposes a triplet confirming previously covered hypotheses. For example, an LLM that has already guessed (2, 4, 6) retreads much of the same hypothesis space by guessing (4, 6, 8) rather than (0.01, -1, 100).

To represent that hypothesis space, we randomly generate 2000 lambda functions that encompass a wide range of potential hypotheses. For example, we randomly generate lambdas having to do with: ordering ($x < y < z$), equality ($x = y \neq z$), arithmetic relations ($x + y = z$), parity



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Figure 2: Models can succeed upon this task by reducing the hypothesis space quickly or providing useful tests for many turns. We show that models with strong reasoning capabilities can narrow the space quickly, but weaker multi-turn capability harms their ability to get value out of later tests.

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($x \leq 10, y \leq 5, z \leq 100$), etc. When an LLM proposes a triplet, we cross off any lambdas that do not match the observed behavior of the hidden rule. Figure 2 illustrates the rate at which different models reduce the hypothesis space over successive turns. Models with worse reasoning spend more attempts to clear less of the hypothesis space, with some models using all of their attempts and yet failing to propose useful tests once some visible behavior is latched onto. For a model with strong reasoning capabilities, we would expect that they would not repeatedly propose test cases that cover previously matched lambdas. Models like deepseek-v2-chat show strong hypothesis space reduction within the first few turns, but struggle to cover the entire space even after 30 turns, leading to suboptimal performance on the full split. In contrast, models like gpt-4o-mini show weaker performance in the first few turns, but are able to cover a greater range of the hypothesis space by better leveraging later turns. It’s important to remember that narrowing the hypothesis space is only one aspect of the challenge; making an accurate final guess after proposing tests is equally crucial for strong overall performance on WILT.

361 4.3 EVALUATING FUNCTION INVERSION CAPABILITY

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To succeed at the WILT task, models must succeed at both gathering evidence (hypothesis reduction) and drawing logical conclusions from evidence (function inversion). To distinguish a model’s ability to do one or the other, we perform an experiment where models attempt to guess the rule using tests from another model. Rather than asking the model to gather evidence, we directly provide it all the reasoning-stripped⁴ input-output pairs generated by another model for the same rule, and ask the model to guess the rule in a single turn. Without the original reasoning and subsequent observation before and after each test case, we expect most models to underperform relative to the full test even when provided their own cases. Likewise, we expect models stronger at single-turn to perform better in this experiment relative to other models subject to the same evidence. Our results can be found in Figure 3.

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This reveals some notably varied capabilities among the top performing models. While Claude Sonnet 3.5 was the narrowly highest performing model on the full test, this experiment reveals important context for why that may be. We see that it performs better than most other models subject to the same evidence, but proposes test cases that are generally slightly less useful for other models

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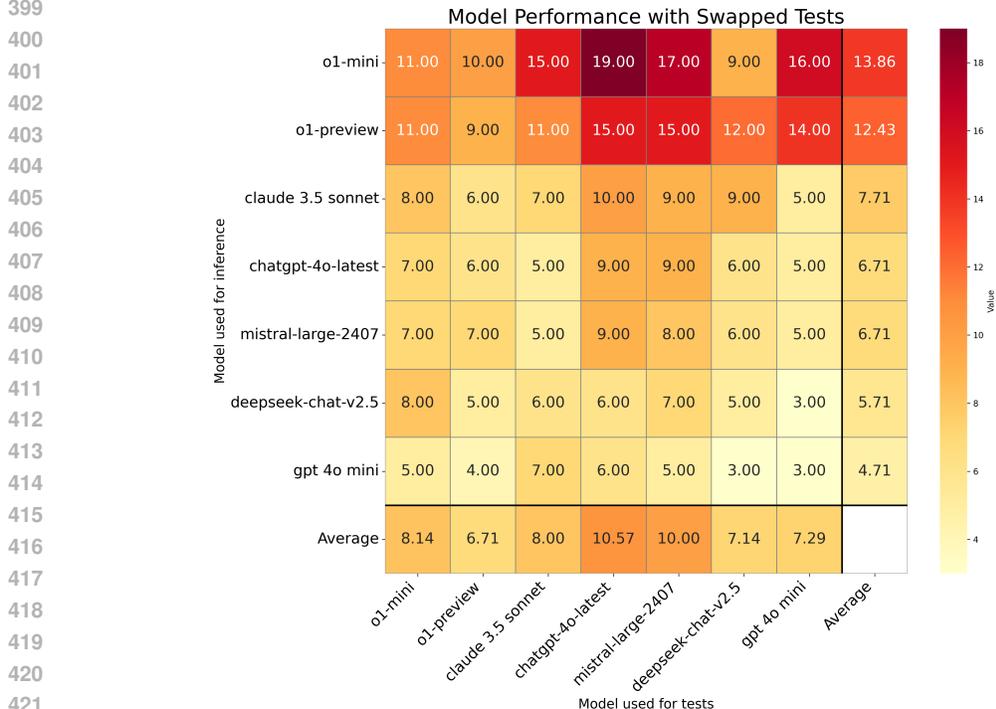
⁴We strip reasoning to avoid conflating confirmation bias in the attached reasoning, rather than just the accumulated evidence.

378 without the attached justifications. Likewise, without its own reasoning for each case, Sonnet’s
 379 performance degraded substantially more than other models in the same setting, suggesting a larger
 380 component of its success was its reasoning, compared to the test cases alone.

381 o1-mini shows highly superior single-turn capability in this test, but notably performs relatively less
 382 well when provided its own tests rather than the tests of another high-performing model. When
 383 paired with cases from chatgpt-4o-latest, it successfully guessed 19 of the 50 rules, far surpassing
 384 the best-performing single model in the full test.
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386 Despite having many repeated tests and messages which were generally similar to each other (see
 387 Tables 1 and 3), we see that Mistral Large performs well with other models’ tests and provides a
 388 corpus of tests useful to other models. We note its comparable performance to chatgpt-4o-latest both
 389 along the rows (model’s performance with other model’s test cases) and columns (performance of
 390 other models with the model’s test cases), reinforcing its strong performance in the full test.

391 Critically, we show that models have non-identical strengths and weaknesses, and that success on
 392 the full WILT task depends on strong performance on a few key metrics of interest. Even without the
 393 attached reasoning for test cases, composing the test case generation of one model and the function
 394 inversion of another model very often outperforms using a single strong model for both subtasks.
 395 This has some notable implications for future LLM applications: in Wang et al. (2024) it was shown
 396 that several language models coordinated by an aggregator LLM could outperform strong single
 397 models. Future work could explore coordinating models for both single-turn and multi-turn oriented
 398 tasks, potentially leading to improved performance.



423 Figure 3: Models have varying success when using test cases proposed by other models. o1-mini
 424 stands out as having much stronger single-turn reasoning in this experiment, but it performs poorly
 425 with its own tests.
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427 **4.4 RESPONSE COMPLEXITY**

428 To determine how well the models employ Occam’s Razor, we explore different metrics to gauge
 429 whether the models find the simplest rule that covers the examples. From existing Bayesian models
 430 of cognition (Tenenbaum, 1999; Tenenbaum & Griffiths, 2001), the *size principle* uses hypothesis
 431 size as a measure of simplicity. In these Bayesian models, hypothesis size is calculated as the number

of values that match the hypothesis. Calculating hypothesis size in this manner is only possible when the test values are within a limited countable range. In our case, the possible test values are infinite, requiring some alternative metrics to gauge hypothesis size. We use three metrics:

1. **Number of Operators:** We count the number of operators used in the rule expression.
2. **Response Length:** We calculate the string length of the rule expression. The longer the length, the more complex it is likely to be. As longer outputs tend to be arbitrarily preferred by automatic evaluators (Dubois et al., 2024), it is particularly important to measure the brevity of the response for cases where simplicity is desired.
3. **Set Inclusion:** We generate a grid of integer-float tuples and apply them to guessed and actual rules to generate sets of tuples returning “True”. If the set of the guessed rule is a subset or superset of the actual rule, we then calculate their set size ratio. A ratio of 1 is ideal, > 1 suggests a less complex guess, and < 1 a more complex one.

Table 2 shows the complexity metrics of the LLMs. Many LLMs with high accuracy such as Claude 3.5 Sonnet, chatgpt-4o-latest, and Mistral Large have long response lengths. However, o1-preview has a short response length and few operators, despite its high performance on the task. The differences in response length and number of operators is most clearly seen in the incorrect answers. For example, if the correct rule is `lambda x, y, z: (x * y * z) % 2 == 1`, Claude 3.5 Sonnet’s guess is `lambda x,y,z: all(n > 0 and int(n)== n and (n & (n-1))== 0)and (n % 3 == 0 or n == 1)for n in [x,y,z])`, which is more convoluted than o1-preview’s guess of `lambda x, y, z: abs(x)== 1 and abs(y)== 1 and abs(z)== 1`. Combined with its low number of average guesses made before making the final guess, o1-preview appears to follow Occam’s Razor very closely compared to most of the other high-performing models with longer response lengths. For the set inclusion ratio, the best models tend to cluster around an intermediate value of 2-4.

Table 2: Response Complexity (Median)

Model	Num Operators	Response Length	Set Inclusion
Claude 3.5 Sonnet	3	34.5	0.08
o1-mini 2024-09-12	3	29.0	0.79
o1-preview-2024-09-12	2	25	0.01
chatgpt-4o-latest	5	39	1.0
Mistral Large 2	5	39	1.0
GPT-4o 2024-08-06	4.5	39	0.34
Llama 3.1 405B	2	30	0.52
Gemini 1.5 Flash 0827	4	35.5	0.00
Llama 3.1 70B	2	25	1.00
Deepseek-v2.5-chat	3	29	0.27
GPT-4o-mini	5	39.5	0.05
Gemini 1.5 Pro	3	38	0.27
Gemini 1.5 Flash	3	28	0.06
Deepseek-v2-coder	5	39	0.88
Deepseek-v2-chat	2	28	0.00
Llama 3.1 8b	2	23	0.05
Open Mistral Nemo	5	46	1.00
Claude 3 Haiku	5	31	0.49
Gemini 1.5 Flash 8b 0827	3	29	0.02
Gemma 2 9B	5	38	0.52

In addition, Figure 4 shows the median number of operators used by a model when given another model’s test cases, as in Section 4.3. This can be used to estimate the model’s bias toward guessing a simpler rule. o1-preview, for example, tends to use fewer operators than the other models subject to the same evidence. This also highlights potential discrepancies in the complexity resulting from a model’s test cases and the complexity of its final guesses. When models use test cases generated by DeepSeek Chat v2.5, they tend to use fewer operators, likely because the test cases

are fully encompassed by simple rules like $\lambda x, y, z: \text{False}$. Conversely, when given other models' tests, DeepSeek Chat v2.5 responds with a high level of complexity compared to other models. Its guesses often overfit a complicated rule to the test cases (e.g., it guesses a rule of $\lambda x, y, z: y == x \text{ or } y == z \text{ or } y == (x + z) / 2$ when given the following true test cases for even numbers: $(2.0, 2.0, 2.0)$, $(2.0, 2.0, 4.0)$, $(-2.0, 4.0, 6.0)$, $(0.0, 2.0, 4.0)$, $(2.2, 4.0, 6.0)$, $(2.0, 4.0, 6.0)$.)

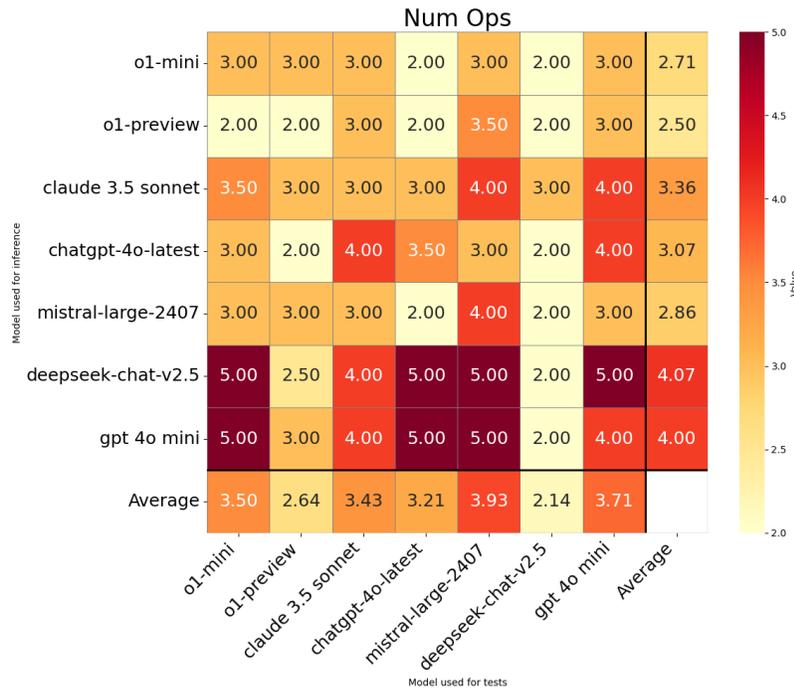


Figure 4: The median number of operators provides a window into guessed rules being more or less complicated compared to guesses provided by other models. More metrics for response complexity in test-case swap scenarios can be found in Appendix A.3.

5 CONCLUSION

In this work, we highlight the importance of the multi-turn setting for understanding the performance of large language models in everyday use cases. We introduced a new benchmark which attempts to measure performance in this common setting, and show its difficulty even for state-of-the-art LLMs. With the models exhibiting non-overlapping strengths, the resulting performance of these models on the WILT task provides useful context for what types of tasks they would be useful for, beyond simply suggesting the top-performing model is the best one to use for all applications.

Our benchmark identifies a critical way that typical benchmarks differ from day-to-day use of LLMs: whereas effective multi-turn collaboration often requires asking clarifying questions, performing experiments, and gathering new evidence, typical benchmarks are overwhelmingly designed to be solved immediately. This may, in turn, create an implicit incentive for models to end conversations as quickly as possible, even where that may be ineffective or inappropriate.

With this work, we aim to provide a benchmark that measures a model's capacity for exploring an environment and reasoning based on its own decisions across multiple turns. We believe that this paradigm offers a more direct measurement of reasoning capability compared to other benchmarks. Likewise, we believe an explicit focus on multi-turn reasoning capability more directly shines a light upon the most common uses of LLMs.

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682 A APPENDIX / SUPPLEMENTAL MATERIAL

683 A.1 EXPERIMENTAL DETAILS

684 A.1.1 MODEL CONFIGURATIONS

685 Models are accessed when possible with default configurations and settings provided by their re-
686 spective proprietary APIs (i.e. Anthropic, OpenAI, Mistral, DeepSeek, and Vertex APIs). Llama 3.1
687 models are run via the Amazon Bedrock API. Gemma 2 9b and llama 3 70B are run via the Groq
688 API Abts et al. (2022).

689 A.1.2 PROMPTS

690 All models begin from the same initial prompt.

691 You are an AI tasked with discovering a hidden rule that takes three numbers
692 as input and returns a boolean. These numbers can be any float or integer number
693 that can be typed in 3 or fewer digits, not including signs and decimal characters
694 (e.g. -11.3 is a valid value). In each response, you will provide your step-by-step
695 reasoning for your future plans on this task, and then you will take one of two
696 actions:

1. Provide a single test case to observe the output of a rule (e.g. “Test Case: `((1, 2, 3))`” which corresponds to $x=1, y=2, z=3$. You may only propose one test case at a time.
2. Provide a final “guess” in the form of a python lambda function (e.g. “Final Guess: `lambda x,y,z: x < y < z`”). You only get to select this action one time, so don’t use it unless you are confident or are forced to.

You will have up to 30 attempts at test cases, and you will have exactly one attempt at guessing the final function. Make sure all of the tests you provide are unique from other ones you have already tried – the functions are all deterministic, and will be the same every time. You should prioritize getting the rule as correct as possible, since an incorrect answer will get no points. You should therefore not guess the function unless you are quite confident, or if you are very close to running out of attempts.

You must return your responses in the format laid out above at the very bottom of your message. For example, if you want to submit a test case, you must conclude with the string “Test Case: `((x, y, z))`”, where x,y,z are replaced with your guesses. If you want to submit a final guess, you must conclude with the string “Final Guess: `<function>`” where `<function>` is replaced with a python lambda function. Do not include any comments or additional text on the same lines as these two things.

Make sure to include your reasoning for your tests – what you are testing for, why you selected that test, etc.

Responses by the models are pulled out via regular expressions matching the formatting in the prompt. We find that after controlling for various formatting eccentricities (python blocks, mark-down, bold characters, etc) that all listed models are capable of providing test cases in this format.

A.1.3 VERIFYING EQUIVALENT FUNCTIONS

To verify two provided lambda functions are equivalent, we generate a large number of test cases and ensure the provided rules match on all outputs. Specifically, we create three sets of cases:

1. **Integer Grid Cases** - We construct a $40 \times 40 \times 40$ grid of integer triplets from -20 to 20, inclusive, leading to 64,000 triplet cases.
2. **Random Uniform Cases** - We construct a list of 10,000 uniformly random float triplets from -200 to 200, inclusive.
3. **Special Cases** - We hand-design a small set of test cases to ensure all hidden rules in the full split are adequately tested.

We mark a rule as incorrect if any test cases generated above show different behavior between the hidden rule and the guessed rule, and mark it correct otherwise.

A.2 TEST CASE NOVELTY

Test case novelty is an interesting second order metric for success upon the WILT task. Broadly speaking, models that reuse fewer tests are rewarded with more information for which to solve the task. Models that very rarely re-propose a test tend to perform very well upon WILT, but the inverse is not necessarily true – models that loop tests often still arrive at the right answer.

Repeated tests are useful for bifurcating the types of failures on WILT – one being the doom loop phenomenon, and the other being reasoning capability conditioned upon some available evidence. One hypothesis for the observed behavior is that certain models are primarily oriented towards single-turn scenarios, and that one type of failure need not imply the other. DeepSeek Chat v2.5, for example, demonstrates strong initial hypothesis space reduction compared to other models, which allows it notably better performance on WILT compared to other models with similar repeat counts (e.g. open-mistral-nemo). Strong single-turn performance and deductive reasoning capabilities can help salvage performance from a model that demonstrates difficulty with multi-turn inductive logic.

Table 3: Model Novelty Metrics

Model	Repeats	Avg. Novelty	Avg. Min. Novelty
claude-3.5-sonnet-20240620	27	0.22	0.08
o1-mini-2024-09-12	3	0.24	0.09
o1-preview-2024-09-12	3	0.28	0.11
chatgpt-4o-latest	38	0.21	0.10
mistral-large-2407	142	0.13	0.04
gpt-4o-2024-08-06	26	0.22	0.11
llama3.1 405B	30	0.20	0.06
gemini-1.5-flash-exp-0827	108	0.19	0.08
llama3-70b	74	0.19	0.06
deepseek-chat-v2.5	489	0.09	0.02
gpt-4o-mini	54	0.19	0.10
gemini-1.5-pro	41	0.26	0.13
gemini-1.5-flash	123	0.19	0.08
deepseek-coder	334	0.11	0.03
deepseek-chat-v2	335	0.10	0.03
llama-3.1-8b	223	0.13	0.01
open-mistral-nemo	400	0.12	0.02
claude-3-haiku-20240307	11	0.29	0.11
gemini-1.5-flash-8b-exp-0827	386	0.14	0.05
gemma2-9b-it	70	0.34	0.18

Following Aidan-bench (McLaughlin, 2024), we provide Table 3, containing additional novelty metrics. These include:

1. *Average novelty* - which reports the average cosine similarity between each message’s gpt-3 embeddings and the closest previous message within the same test.
2. *Average minimum novelty* - which reports the average *minimum* cosine similarity between each message’s gpt-3 embeddings and the closest previous message within the same test.

These capture an additional dimension of “test novelty” and “message novelty”, where models may propose the same tests for different reasons, or repeat previously generated messages verbatim. We bold results which are best within the class of high performing models. We note that models that propose fewer tests before guessing (e.g. o1-preview, o1-mini) should see lower values for all of these compared to models that tend to use many tests before guessing (e.g. mistral-large) even for otherwise equally performing models. We also show the average novelty by turn in Figure 5, which captures the model’s novelty scores across turns.

A.3 RESPONSE COMPLEXITY IN TEST SWAP EXPERIMENTS

In figure 6 we show the set inclusion ratios in the case where a model is provided another model’s test cases. That is, we show whether an error in the final guess of a model is likely to be smaller / less than one (e.g. $x < y < z$ instead of $x \leq y \leq z$), or larger / greater than one (e.g. $x > 0$ instead of $x > 0 \wedge x < 5$). This seems more test-case dependent than other complexity benchmarks, where tests provided by certain models seem to lead to smaller hypotheses.

Figure 7 shows the length of the string used to guess the rule by each model, which is comparatively more consistent for a model. We find this to be fairly consistent across settings, with most models hovering near 45.

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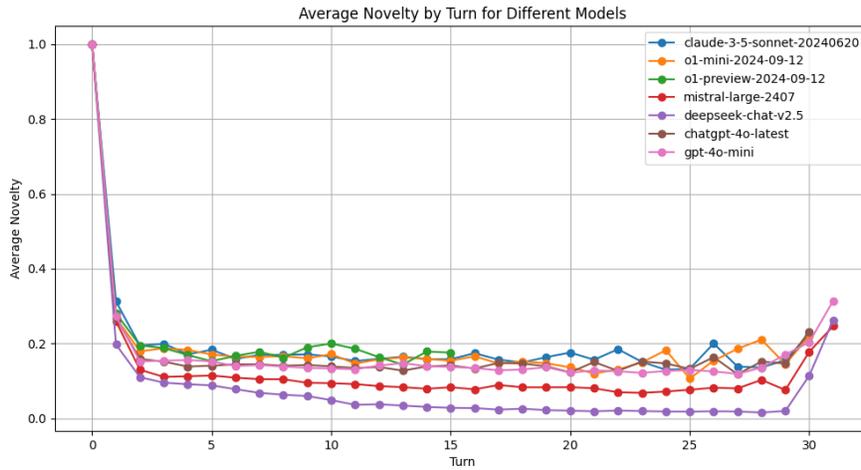


Figure 5: Cosine similarity by turn for selected models. Models have a higher novelty score near the end, since the final guess is often much different from previous messages, which are all proposed test cases.

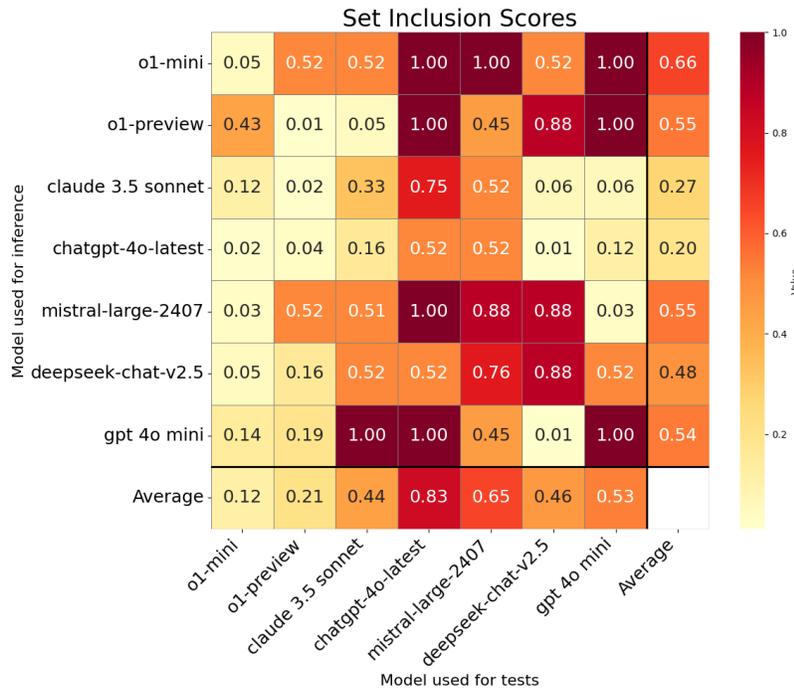


Figure 6: Set inclusion ratios will differ in the same model when provided another model’s tests, and models provided the same tests have different set inclusion behaviors.

A.4 SELECTED LITE SPLIT RESULTS

Table 4 contains selected results for the *lite split*. We show this much easier split produces a similar ordering, suggesting that the bulk of the separation in our benchmark lies in the easier tests.

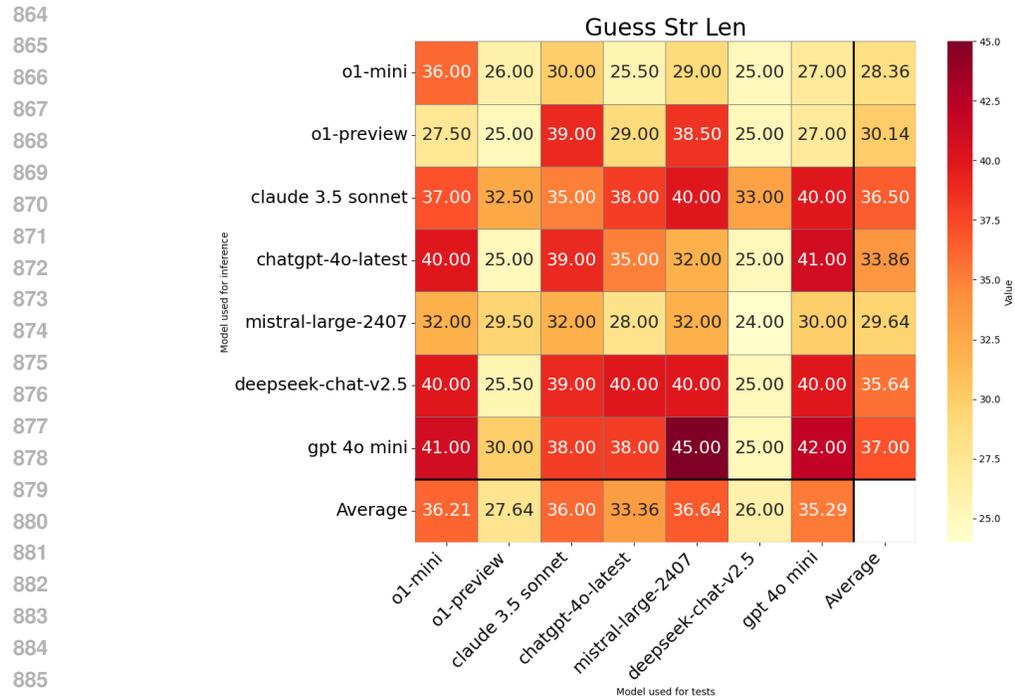


Figure 7: Models tend to have fairly consistent guess string lengths, with some exceptions.

Table 4: Lite Split Metrics

Model	Accuracy	Avg. Guesses
Claude-3.5-Sonnet	8/10	13.68
GPT-4-Turbo	7/10	12.47
GPT-4o	6/10	13.86
DeepSeek-V2-Coder	6/10	23.46
Llama 3 70B	4/10	15.64
DeepSeek-V2-Chat	2/10	24.82
Llama 3 8B	1/10	24.0
GPT-3.5-Turbo	1/10	2.9

903 A.5 TEST DESCRIPTIONS

904 Table 5 contains the functions found in the *lite split* of WILT. Table 6 contains the functions found
 905 in the *full split* of WILT. These are implemented as Python lambda functions.

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Table 5: Lite Split: Complete Set of Tests

Test ID	Description
1	$x > y > z$
2	$x < y < z$
3	$x \geq y \geq z$
4	$x \leq y \leq z$
5	$x = y = z$
6	$x \neq y \wedge y \neq z \wedge x \neq z$
7	$x < 0 \wedge y < 0 \wedge z < 0$
8	$x + y = z$
9	$x \cdot y = z$
10	$x < y \wedge y > z$

B FAILURE CASE EXAMPLES

B.1 DOOM LOOP WITHOUT REASONING FAILURE

Table 7 shows an example of a model (Deepseek-Chat-v2.5) entering a doom loop during the test proposal phase, but where that doom loop does not constitute a reasoning failure. Reasoning has been removed for brevity.

B.2 APPROXIMATELY CORRECT

Table 8 shows an example of o1-mini getting a very difficult test case (co-primality) approximately correct, failing only because it adds an additional arbitrary constraint upon the magnitude of the values despite no such constraint existing. Reasoning has been removed for brevity.

B.3 CONFIRMATION BIAS

Table 9 shows an example of o1-preview failing a relatively easy test case ($x \geq y \geq z$) due to a confirmation bias error. The model uses only 9 test cases and correctly identifies that the rule returns true when all three are equal, but submits five test cases confirming that and none exploring other rules which are true when three items are equal. Reasoning has been removed for brevity.

B.4 SAME TEST FOR NEW REASON

Table 10 shows an example of Claude Sonnet 3.5 repeating a test, where it will mistakenly generate the same test for a different stated reason. We see the model notice it has repeated a test only after it has already submitted the test. Other tests have been removed for brevity.

Table 6: Full Split: Complete Set of Tests

Test ID	Description
Easy Tests	
1	$x > y > z$
2	$x < y < z$
3	$x \geq y \geq z$
4	$x \leq y \leq z$
5	$x < z < y$
6	$x \leq z \leq y$
7	$z < x < y$
8	$z \leq x \leq y$
9	$x = y = z$
10	$x \neq y \wedge y \neq z \wedge x \neq z$
11	$x < 0 \wedge y < 0 \wedge z < 0$
12	$x > 0 \wedge y > 0 \wedge z > 0$
13	$x \bmod 2 = 0 \wedge y \bmod 2 = 0 \wedge z \bmod 2 = 0$
14	$x \bmod 2 \neq 0 \wedge y \bmod 2 \neq 0 \wedge z \bmod 2 \neq 0$
Medium Tests	
15	$x + y = z$
16	$x \cdot y = z$
17	$x + z = y$
18	$x \cdot z = y$
19	$y + z = x$
20	$y \cdot z = x$
21	$\max(x, y, z) = x$
22	$\max(x, y, z) = y$
23	$\max(x, y, z) = z$
24	$\min(x, y, z) = x$
25	$\min(x, y, z) = y$
26	$\min(x, y, z) = z$
27	$x + y + z = 0$
28	$x \cdot y \cdot z = 0$
29	$(x + y + z) \bmod 2 = 0$
30	$(x + y + z) \bmod 2 = 1$
31	$(x \cdot y \cdot z) \bmod 2 = 0$
32	$(x \cdot y \cdot z) \bmod 2 = 1$
33	$(x + y)/2 = z$
34	$-5 \leq x, y, z \leq 5$
35	$-10 \leq x, y, z \leq 10$
36	$-5 \leq x, y, z \leq 0$
37	$0 \leq x, y, z \leq 5$
38	$-2 \leq x, y, z \leq 2$
39	$-20 \leq x, y, z \leq 20$
Very Hard Tests	
40	$x^2 + y^2 = z^2$
41	$x^2 + z^2 = y^2$
42	$y^2 + z^2 = x^2$
43	$[x] \& [y] = [z]$ (bitwise AND)
44	$[x] \mid [y] = [z]$ (bitwise OR)
45	$[x] \oplus [y] = [z]$ (bitwise XOR)
46	$x, y, z \in \mathbb{Z} \wedge \gcd(x, y) = \gcd(y, z) = \gcd(z, x) = 1$
47	$\sqrt{[x]^2} = [x] \wedge \sqrt{[y]^2} = [y] \wedge \sqrt{[z]^2} = [z]$
48	$0 < x \bmod 1 \wedge 0 < y \bmod 1 \wedge 0 < z \bmod 1$
49	$0 < x \bmod 1 < y \bmod 1 < z \bmod 1 < 1$
50	$x < y < z \wedge 0 < z - x \leq 1$

Table 7: DeepSeek-v2.5 Enters a doom loop but still arrives at the correct answer

Turn	Assistant	Harness
1	Test Case: (1, 1, 1)	(1.0, 1.0, 1.0): True.
2	Test Case: (1, 2, 3)	(1.0, 2.0, 3.0): True.
3	Test Case: (3, 2, 1)	(3.0, 2.0, 1.0): True.
4	Test Case: (2, 1, 3)	(2.0, 1.0, 3.0): True.
5	Test Case: (-1, -2, -3)	(-1.0, -2.0, -3.0): False.
6	Test Case: (-1, 2, -3)	(-1.0, 2.0, -3.0): False.
7	Test Case: (0, 1, 2)	(0.0, 1.0, 2.0): False.
8	Test Case: (2, 3, 1)	(2.0, 3.0, 1.0): True.
9	Test Case: (0, 1, 1)	(0.0, 1.0, 1.0): False.
10	Test Case: (0.001, 1, 1)	(0.001, 1.0, 1.0): True.
11	Test Case: (-0.001, 1, 1)	(-0.001, 1.0, 1.0): False.
12	Test Case: (999, 1, 1)	(999.0, 1.0, 1.0): True.
13	Test Case: (-999, 1, 1)	(-999.0, 1.0, 1.0): False.
14	Test Case: (0.0001, 1, 1)	(0.0001, 1.0, 1.0): True.
15	Test Case: (-0.0001, 1, 1)	(-0.0001, 1.0, 1.0): False.
16	Test Case: (999.999, 1, 1)	(999.999, 1.0, 1.0): True.
17	Test Case: (-999.999, 1, 1)	(-999.999, 1.0, 1.0): False.
18	Test Case: (0.0001, 999.999, 1)	(0.0001, 999.999, 1.0): True.
19	Test Case: (-0.0001, 999.999, 1)	(-0.0001, 999.999, 1.0): False.
20	Test Case: (0.0001, -999.999, 1)	(0.0001, -999.999, 1.0): False.
21	Test Case: (0.0001, 999.999, -0.0001)	(0.0001, 999.999, -0.0001): False.
22	Test Case: (0.0001, 999.999, -999.999)	(0.0001, 999.999, -999.999): False.
23	Test Case: (0.0001, 999.999, 0.0001)	(0.0001, 999.999, 0.0001): True.
24	Test Case: (0.0001, 0.0001, 999.999)	(0.0001, 0.0001, 999.999): True.
25	Test Case: (999.999, 0.0001, 0.0001)	(999.999, 0.0001, 0.0001): True.
26	Test Case: (0.0001, 999.999, 0.0001)	(0.0001, 999.999, 0.0001): True.
27	Test Case: (0.0001, 0.0001, 999.999)	(0.0001, 0.0001, 999.999): True.
28	Test Case: (999.999, 0.0001, 0.0001)	(999.999, 0.0001, 0.0001): True.
29	Test Case: (0.0001, 999.999, 0.0001)	(0.0001, 999.999, 0.0001): True.
30	Test Case: (0.0001, 0.0001, 999.999)	(0.0001, 0.0001, 999.999): True.
31	Final Guess: lambda x, y, z: $x > 0$ and $y > 0$ and $z > 0$	Congratulations! Your guess is correct.

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Table 8: o1-mini nearly gets the coprimality case correct, but adds bounds for no concrete reason.

Turn	Assistant	Harness
1	Test Case: (1, 2, 3)	(1.0, 2.0, 3.0): True.
2	Test Case: (3, 2, 1)	(3.0, 2.0, 1.0): True.
3	Test Case: (1, 1, 1)	(1.0, 1.0, 1.0): True.
4	Test Case: (-1, 2, 3)	(-1.0, 2.0, 3.0): True.
5	Test Case: (-1, -2, -3)	(-1.0, -2.0, -3.0): True.
6	Test Case: (0, 0, 0)	(0.0, 0.0, 0.0): False.
7	Test Case: (0, 1, 2)	(0.0, 1.0, 2.0): False.
8	Test Case: (1.5, 2.5, 3.5)	(1.5, 2.5, 3.5): False.
9	Test Case: (1, 2, 3.0)	(1.0, 2.0, 3.0): True.
10	Test Case: (1, 2, 3.1)	(1.0, 2.0, 3.1): False.
11	Test Case: (1, 2, -3)	(1.0, 2.0, -3.0): True.
12	Test Case: (10, -20, 30)	(10.0, -20.0, 30.0): False.
13	Test Case: (4, 5, 6)	(4.0, 5.0, 6.0): False.
14	Test Case: (-2, -1, 3)	(-2.0, -1.0, 3.0): True.
15	Test Case: (3, 3, 4)	(3.0, 3.0, 4.0): False.
16	Test Case: (1, -1, 2)	(1.0, -1.0, 2.0): True.
17	Test Case: (-3, 3, -2)	(-3.0, 3.0, -2.0): False.
18	Test Case: (2, -2, 2)	(2.0, -2.0, 2.0): False.
19	Test Case: (-1, 2, -2)	(-1.0, 2.0, -2.0): False.
20	Test Case: (1, 3, 2)	(1.0, 3.0, 2.0): True.
21	Test Case: (1, 2, 2)	(1.0, 2.0, 2.0): False.
22	Test Case: (-1, -2, 3)	(-1.0, -2.0, 3.0): True.
23	Test Case: (2, 3, -1)	(2.0, 3.0, -1.0): True.
24	Final Guess: λ x, y, z: all(isinstance(n, int) and $n \neq 0$ and $-3 \leq n \leq 3$ for n in [x, y, z]) and math.gcd(x, y) == 1 and math.gcd(x, z) == 1 and math.gcd(y, z) == 1	Sorry, that's not the correct rule.

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Table 9: o1-preview fails early on an easy test case despite having a wealth of remaining tests, because it latched on to an early behavior and sought to confirm it rather than falsify it.

Turn	Assistant	Harness
1	Test Case: (2, 3, 6)	(2.0, 3.0, 6.0): False.
2	Test Case: (2, 3, 5)	(2.0, 3.0, 5.0): False.
3	Test Case: (1, 1, 1)	(1.0, 1.0, 1.0): True.
4	Test Case: (2, 2, 2)	(2.0, 2.0, 2.0): True.
5	Test Case: (1, 1, 2)	(1.0, 1.0, 2.0): False.
6	Test Case: (-1, -1, -1)	(-1.0, -1.0, -1.0): True.
7	Test Case: (1.5, 1.5, 1.5)	(1.5, 1.5, 1.5): True.
8	Test Case: (0, 0, 0)	(0.0, 0.0, 0.0): True.
9	Test Case: (1, 2, 3)	(1.0, 2.0, 3.0): False.
10	Final Guess: lambda x, y, z: x == y == z	Sorry, that's not the correct rule.

Table 10: Claude Sonnet 3.5 double submits (2, 3, 5) to test $x + y = z$ and $all(isprime(n))$

Turn	Assistant	Harness
1-5
6	Still False. Let's try a different approach and consider some mathematical relationships. Reasoning for the next test: 1. Let's test if the rule involves a simple arithmetic relationship. 2. We'll use numbers where the third is the sum of the first two. 3. We'll use small integers for clarity. Test Case: (2, 3, 5)	(2.0, 3.0, 5.0): False.
7-8
9	We're still not getting a True result. Let's try a different approach and consider some number theory concepts. Reasoning for the next test: 1. Let's test if the rule involves prime numbers. 2. We'll use three consecutive prime numbers. 3. This will also test if there's a special relationship with consecutive numbers that are not simply ascending. Test Case: (2, 3, 5)	(2.0, 3.0, 5.0): False.
10	We've already tested (2, 3, 5) before, and it's still False. Let's try a different number theory concept...	...

1188 C FULL CONVERSATION EXAMPLES

1189

1190 C.1 DOOM LOOP ON CODING TASK

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1192 Below we provide a full example of a "doom loop" interacting with an LLM in a multi-turn con-
 1193 versation in a real world coding task. We use llama 3 8b to generate code for a pytorch variational
 1194 autoencoder, and after 2 turns of debugging it repeats an already mentioned suggestion.

1195

1196 **### User:**

1197

Can you write me some code which trains a VAE on cifar10 using pytorch?

1198

1199 **### Llama3-8b-8192:**

1200

Here's a basic example of how you can train a Variational Autoencoder (VAE) on
 1201 CIFAR-10 using PyTorch:

1202

```

1202 ```Python
1203 import torch
1204 import torch.nn as nn
1205 import torch.optim as optim
1206 from torchvision import datasets, transforms
1207 from torch.utils.data import DataLoader
1208 import numpy as np
1209
1210 # Define the VAE model
1211 class VAE(nn.Module):
1212     def __init__(self):
1213         super(VAE, self).__init__()
1214         self.encoder = nn.Sequential(
1215             nn.Conv2d(3, 32, kernel_size=3),
1216             nn.ReLU(),
1217             nn.MaxPool2d(2, 2),
1218             nn.Conv2d(32, 64, kernel_size=3),
1219             nn.ReLU(),
1220             nn.MaxPool2d(2, 2),
1221             nn.Flatten()
1222         )
1223         self.fc1 = nn.Linear(64*4*4, 128)
1224         self.fc2 = nn.Linear(128, 128)
1225         self.fc3 = nn.Linear(128, 64*4*4)
1226         self.fc4 = nn.Linear(64*4*4, 3*32*32)
1227
1228     def reparameterize(self, mu, logvar):
1229         std = torch.exp(0.5*logvar)
1230         eps = torch.randn_like(std)
1231         return mu + eps*std
1232
1233     def encode(self, x):
1234         h1 = self.encoder(x)
1235         h2 = torch.relu(self.fc1(h1))
1236         h3 = torch.relu(self.fc2(h2))
1237         mu = self.fc3(h3)
1238         logvar = self.fc4(h3)
1239         return mu, logvar
1240
1241     def decode(self, z):
1242         h1 = torch.relu(self.fc4(z))
1243         h2 = torch.relu(self.fc3(h1))
1244         h3 = torch.relu(self.fc2(h2))
1245         h4 = torch.relu(self.fc1(h3))

```

```

1242         return torch.sigmoid(self.fc4(h4))
1243
1244     def forward(self, x):
1245         mu, logvar = self.encode(x)
1246         z = self.reparameterize(mu, logvar)
1247         return self.decode(z), mu, logvar
1248
1249     # Define the loss function
1250     def loss_function(recon_x, x, mu, logvar):
1251         BCE = nn.functional.binary_cross_entropy(recon_x,
1252         ↪ x.view(-1, 3*32*32), reduction='sum')
1253         KLD = 0.5 * torch.sum(1 + logvar - mu.pow(2) -
1254         ↪ logvar.exp())
1255         return BCE + KLD
1256
1257     # Load the CIFAR-10 dataset
1258     transform = transforms.Compose([transforms.ToTensor()])
1259     trainset = datasets.CIFAR10(root='./data', train=True,
1260     ↪ download=True, transform=transform)
1261     trainloader = DataLoader(trainset, batch_size=64,
1262     ↪ shuffle=True)
1263
1264     testset = datasets.CIFAR10(root='./data', train=False,
1265     ↪ download=True, transform=transform)
1266     testloader = DataLoader(testset, batch_size=64,
1267     ↪ shuffle=False)
1268
1269     # Initialize the VAE model and the optimizer
1270     vae = VAE()
1271     optimizer = optim.Adam(vae.parameters(), lr=0.001)
1272
1273     # Train the VAE
1274     for epoch in range(100):
1275         for i, (x, _) in enumerate(trainloader):
1276             x = x.to(device)
1277             optimizer.zero_grad()
1278             recon_x, mu, logvar = vae(x)
1279             loss = loss_function(recon_x, x, mu, logvar)
1280             loss.backward()
1281             optimizer.step()
1282             if i % 100 == 0:
1283                 print('Epoch: %d, Batch: %d, Loss: %.3f' %
1284                 ↪ (epoch+1, i+1, loss.item()))
1285
1286     # Test the VAE
1287     test_loss = 0
1288     with torch.no_grad():
1289         for x, _ in testloader:
1290             x = x.to(device)
1291             recon_x, mu, logvar = vae(x)
1292             loss = loss_function(recon_x, x, mu, logvar)
1293             test_loss += loss.item()
1294     test_loss /= len(testloader)
1295     print('Test Loss: %.3f' % test_loss)

```

This code defines a VAE model, loads the CIFAR-10 dataset, and trains the model using the Adam optimizer. The loss function is the sum of the binary cross-entropy

1296 loss and the Kullback-Leibler divergence. The model is trained for 100 epochs,
 1297 and the test loss is printed after each epoch.

1298 Note that you need to install the ‘torchvision’ package to use the CIFAR-10
 1299 dataset. You can install it using ‘pip install torchvision’. Also, you need
 1300 to specify the device (GPU or CPU) where you want to run the model.
 1301 You can do this by adding ‘device = torch.device('cuda' if
 1302 torch.cuda.is_available() else 'cpu')’ before the training loop.

1303

1304 **### User:**

1305 I’m getting the following error trying to run this code:

1306 RuntimeError Traceback (most recent call last)
 1307 <ipython-input-3-471d3f454439> in <cell line: 70>()
 1308 72 x = x.to(device)
 1309 73 optimizer.zero_grad()
 1310 --> 74 recon_x, mu, logvar = vae(x)
 1311 75 loss = loss_function(recon_x, x,
 1312 mu, logvar)
 1313 76 loss.backward()
 1314
 1315 6 frames
 1316 in forward(self, input)
 1317 115
 1318 116 def forward(self, input: Tensor) -> Tensor:
 1319 --> 117 return F.linear(input, self.weight,
 1320 ↪ self.bias)
 1321 118
 1322 119 def extra_repr(self) -> str:
 1323
 1324 RuntimeError: mat1 and mat2 shapes cannot be multiplied
 1325 ↪ (64x2304 and 1024x128)

1326 **### llama3-8b-8192:**

1327 The error message indicates that there is a mismatch between the shapes of the
 1328 input and the weights in one of the fully connected layers in your VAE model.
 1329 The error message specifically says that the shapes are 64x2304 and 1024x128,
 1330 which means that the input has a shape of (64, 2304) and the weights have a shape
 1331 of (1024, 128).

1332 The issue is likely due to the fact that the input to the fully connected layer is
 1333 not what you expect. In the ‘encode’ method of your VAE model, you have the
 1334 following lines:
 1335 ...
 1336 h1 = self.encoder(x)
 1337 h2 = torch.relu(self.fc1(h1))
 1338 h3 = torch.relu(self.fc2(h2))
 1339 mu = self.fc3(h3)
 1340 logvar = self.fc4(h3)
 1341 ...

1342 The ‘h3’ tensor has a shape of (64, 128) because ‘self.fc2’ is a fully con-
 1343 nected layer with 128 output units. However, ‘self.fc3’ and ‘self.fc4’ are
 1344 also fully connected layers, and they are expecting an input with a shape of
 1345 (batch_size, 128) where batch_size is the number of samples in the
 1346 batch.

1347 In your case, the batch size is 64, so the input to ‘self.fc3’ and ‘self.fc4’ should be
 1348 (64, 128), not (64, 128) as it is now.

1349 To fix this issue, you can try to flatten the output of ‘self.encoder’ before passing
 it to the fully connected layers. You can do this by adding the following line after
 ‘h1 = self.encoder(x)’:

```

1350     ...
1351     h1 = h1.view(-1, 64*4*4)
1352     ...

```

1353 This will flatten the output of ‘self.encoder’ into a tensor with a shape of
 1354 (batch_size, 64*4*4), which should be compatible with the weights of
 1355 ‘self.fc1’, ‘self.fc2’, ‘self.fc3’, and ‘self.fc4’.
 1356

1357 **### User:**

1358 Okay, I added that line. Now I’m getting a similar error with different values:
 1359 RuntimeError: mat1 and mat2 shapes cannot be
 1360 multiplied (144x128 and 1024x3072)
 1361

1362 **### llama3-8b-8192:**

1363 The error message indicates that there is a mismatch between the shapes of the
 1364 input and the weights in one of the fully connected layers in your VAE model.
 1365

1366 The error message specifically says that the shapes are 144x128 and 1024x3072,
 1367 which means that the input has a shape of (144, 128) and the weights have a shape
 1368 of (1024, 3072).

1369 The issue is likely due to the fact that the input to the fully connected layer is
 1370 not what you expect. In the ‘encode’ method of your VAE model, you have the
 1371 following lines:

```

1372     ...
1373     h1 = self.encoder(x)
1374     h2 = torch.relu(self.fc1(h1))
1375     h3 = torch.relu(self.fc2(h2))
1376     mu = self.fc3(h3)
1377     logvar = self.fc4(h3)
1378     ...

```

1379 The ‘h3’ tensor has a shape of (64, 128) because ‘self.fc2’ is a fully con-
 1380 nected layer with 128 output units. However, ‘self.fc3’ and ‘self.fc4’ are
 1381 also fully connected layers, and they are expecting an input with a shape of
 1382 (batch_size, 128) where batch_size is the number of samples in the
 1383 batch.

1384 In your case, the batch size is 64, so the input to ‘self.fc3’ and ‘self.fc4’ should be
 1385 (64, 128), not (64, 128) as it is now.

1386 To fix this issue, you can try to flatten the output of ‘self.encoder’ before passing
 1387 it to the fully connected layers. You can do this by adding the following line after
 1388 ‘h1 = self.encoder(x)’:

```

1389     ...
1390     h1 = h1.view(-1, 128)
1391     ...

```

1392 This will flatten the output of ‘self.encoder’ into a tensor with a shape of
 1393 (batch_size, 128), which should be compatible with the weights of
 1394 ‘self.fc1’, ‘self.fc2’, ‘self.fc3’, and ‘self.fc4’.

1395 However, the error message also mentions that the input has a shape of 144x128,
 1396 which is not compatible with the weights of the fully connected layer. This sug-
 1397 gests that there may be an issue with the architecture of your VAE model.

1398 To fix this issue, you can try to adjust the architecture of your VAE model to ensure
 1399 that the input to the fully connected layers is compatible with the weights.
 1400
 1401
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