000 001 002 003 004 005 006 ARE CLASSIFICATION ROBUSTNESS AND EXPLA-NATION ROBUSTNESS REALLY STRONGLY CORRE-LATED? AN ANALYSIS THROUGH INPUT LOSS LAND-SCAPE

Anonymous authors

Paper under double-blind review

ABSTRACT

This paper looks into the critical area of deep learning robustness and challenges the common belief that classification robustness and explanation robustness in image classification systems are inherently correlated. Through a novel evaluation approach leveraging clustering for efficient assessment of explanation robustness, we demonstrate that enhancing explanation robustness does not necessarily flatten the input loss landscape with respect to explanation loss - contrary to flattened loss landscapes indicating better classification robustness. To further investigate this contradiction, a training method designed to adjust the loss landscape with respect to explanation loss is proposed. Through the new training method, we uncover that although such adjustments can impact the robustness of explanations, they do not have an influence on the robustness of classification. These findings not only challenge the previous assumption of a strong correlation between the two forms of robustness but also pave new pathways for understanding the relationship between loss landscape and explanation loss. Codes are provided in the supplement.

1 INTRODUCTION

032 033 034 035 036 037 038 039 040 In deep learning, the robustness of image classification systems against adversarial instances has emerged as an important area of research. These systems, integral to modern artificial intelligence, frequently encounter scenarios where adversarial instances—subtly altered images designed to deceive algorithms—pose significant challenges. At the heart of this challenge lie two critical concepts: classification robustness and explanation robustness. Classification robustness refers to a model's ability to maintain accuracy under adversarial attacks [\(Szegedy et al.,](#page-12-0) [2013;](#page-12-0) [Madry et al.,](#page-11-0) 2017), while explanation robustness pertains to the consistency of the model's interpretative outputs in such adversarial scenarios [\(Dombrowski et al.,](#page-10-0) [2019;](#page-10-0) [Huang et al.,](#page-11-1) [2023\)](#page-11-1). Traditionally, there's been a prevailing conclusion within the research community [\(Boopathy et al.,](#page-10-1) [2020;](#page-10-1) [Huang et al.,](#page-11-1) [2023\)](#page-11-1):

041

042 043 *Conclusion: Classification robustness and explanation robustness are strongly correlated: Increasing classification robustness can increase explanation robustness and vice versa.*

044 045 046 047 This paper, however, unveils a finding that disrupts this conventional belief: a contradiction in the assumed correlation between classification robustness and explanation robustness. This revelation not only challenges established assumptions but also opens new avenues for understanding and improving the resilience of deep learning models.

048 049 050 051 052 053 Adversarial attacks on classification aim at deceiving image classification models by introducing perturbations to benign images [\(Szegedy et al.,](#page-12-0) [2013\)](#page-12-0). To defend against adversarial examples, adversarial training (AT) [\(Madry et al.,](#page-11-0) [2017;](#page-11-0) [Goodfellow et al.,](#page-11-2) [2014\)](#page-11-2) is one of the most effective approaches which explicitly augments the training process to enhance a model's inherent robustness against adversarial samples for classification. Classification robustness typically is referred as the classification accuracy under adversarial attacks, and AT methods are effective in improving the classification robustness of a deep learning model.

075

103 104 105

(a) Example of adversarial attack on explanation. on CIFAR-10 shows that the adversarially trained The explanation maps of original image can be models have much flatter landscapes. Adversarial manipulated to the target explanation. tween normal and adversarially trained models training can increase classification robustness.

071 072 073 074 Figure 1: (a) Illustration of an adversarial attack on explanation, demonstrating the manipulation of explanation maps from the original image to achieve a target, resulting in explanation loss (b) A visualization of input loss landscape w.r.t classification loss, comparing a normal-trained model to an adversarial-trained model.

076 077 078 079 080 081 Explanation maps [\(Baehrens et al.,](#page-10-2) [2010\)](#page-10-2), also known as saliency maps, are proposed to explain deep learning methods by feature importance. However, explanation maps are themselves also vulnerable to adversarial attacks [\(Dombrowski et al.,](#page-10-0) [2019;](#page-10-0) [Ghorbani et al.,](#page-10-3) [2019\)](#page-10-3). For example, in Fig. [1a,](#page-1-0) by making small visual changes to the input sample which hardly influences the network's output, the explanations can be arbitrarily manipulated [\(Dombrowski et al.,](#page-10-0) [2019\)](#page-10-0). Explanation robustness is referred as the error between victim explanation under adversarial attacks on the input and targeted explanation.

082 083 084 085 086 087 To better understand robustness, one important way is to explore the input loss landscape (Li $\&$ [Spratling,](#page-11-3) [2023\)](#page-11-3). Existing work has found out that *a flat input loss landscape w.r.t classification loss indicates better classification robustness* [\(Xie et al.,](#page-13-0) [2020;](#page-13-0) [Li & Spratling,](#page-11-3) [2023\)](#page-11-3), as shown in Fig. [1b.](#page-1-0) To visualize the input loss landscape, we add the random perturbation to the inputs with magnitude α (detailed method in Section [4\)](#page-4-0). The results in Fig. [1b](#page-1-0) show that models with higher classification robustness have a flatter input loss landscape w.r.t classification loss.

Then a natural question comes up for explanation robustness:

Q: Does increasing explanation robustness of a model also flatten input loss landscape w.r.t explanation loss?

We visualize the input loss landscape w.r.t explanation loss in Fig. [4](#page-5-0) using models with different levels of explanation robustness and find that, surprisingly, *increasing the explanation robustness does not flatten the input loss landscape w.r.t explanation loss*. Specifically, to obtain models with different levels of explanation robustness, we consider utilizing adversarial training methods that allow us to control the emphasis on classification robustness $(Zhang et al., 2019)$ $(Zhang et al., 2019)$ $(Zhang et al., 2019)$ since previous works have proven that increasing classification robustness can also increase explanation robustness.

099 100 101 102 The previous observation that increasing the explanation robustness does not flatten the input loss landscape w.r.t explanation loss is strange compared with increasing classification robustness could flatten the input loss landscape w.r.t classification loss. To further explore this observation, we ask the previous question in a reverse way:

Q: Does flattening the input loss landscape w.r.t explanation loss not increase the robustness of explanations as well?

106 107 The answer to this question is, flattening the input loss landscape w.r.t explanation loss will decrease the explanation robustness. Specifically, we propose a new loss function to flatten the loss landscape w.r.t explanation loss. The results show that adding the loss will decrease the explanation robustness

108 109 110 111 but not change the classification robustness measured by adversarial accuracy. This observation, indicating that influencing explanation robustness does not impact classification robustness, challenges the previous conclusion: the correlation between explanation robustness and classification robustness may not hold.

Overall, we summarize our contributions as follows:

- We propose a sampling method based on cluster methods that can choose representative pairs to evaluate explanation robustness more efficiently.
- We use TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1) to control the classification robustness and explanation robustness and visualize the input loss landscape w.r.t explanation loss to find that increasing the explanation robustness by increasing the classification robustness does not flatten the input loss landscape.
	- We propose a new training method that flattens the input loss landscape w.r.t explanation loss. The training results show that explanation robustness may **not** be strongly correlated to classification robustness.

124 2 RELATED WORK

125

126 127 128 129 130 131 132 133 134 135 136 137 Adversarial Attack and Adversarial Training (AT) It has been proven that convolutional neural networks (CNNs) are vulnerable to the adversarial examples [\(Szegedy et al.,](#page-12-0) [2013;](#page-12-0) [Goodfellow et al.,](#page-11-2) [2014;](#page-11-2) [Carlini & Wagner,](#page-10-4) [2017\)](#page-10-4). Noise that is imperceptible to humans, when added to the original inputs, can lead to the misclassification of models. Projected Gradient Descent (PGD) [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0) is one of the most popular methods that generate such a noise or evaluate models' classification robustness by calculating accuracy under its attack. Many methods have been introduced to defend against adversarial attacks including knowledge distillation [\(Papernot et al.,](#page-12-1) [2016\)](#page-12-1), quantization [\(Xu et al.,](#page-13-2) [2017;](#page-13-2) [Lin et al.,](#page-11-4) [2019\)](#page-11-4) and noise purification [\(Song et al.,](#page-12-2) [2017;](#page-12-2) [Carlini et al.,](#page-10-5) [2022\)](#page-10-5). However, these preprocessing methods do not involve a training process and may be vulnerable to adaptive attack [\(Athalye et al.,](#page-10-6) [2018\)](#page-10-6). Goodfellow et al. [\(Goodfellow et al.,](#page-11-2) [2014\)](#page-11-2) first introduced adversarial training (AT), which trains a model from scratch with adversarial samples. Adversarial Training (AT) proved its performance including adversarial competitions [\(Madry et al.,](#page-11-0) [2017;](#page-11-0) [Brendel et al.,](#page-10-7) [2020\)](#page-10-7). In our paper, we also focus on classification robustness increased by AT.

138 139 140 141 142 143 144 145 146 Many works tend to increase the performance of AT through external datasets [\(Hendrycks et al.,](#page-11-5) [2019;](#page-11-5) [Carmon et al.,](#page-10-8) [2019;](#page-10-8) [Wang et al.,](#page-12-3) [2023\)](#page-12-3), metric learning [\(Pang et al.,](#page-11-6) [2019\)](#page-11-6), self-supervised learning [\(Chen et al.,](#page-10-10) [2020a\)](#page-10-9), ensemble learning (Tramèr et al., [2017\)](#page-12-4), label smoothing (Chen et al., [2020b\)](#page-10-10) and Taylor Expansion [\(Jin et al.,](#page-11-7) [2023\)](#page-11-7). Wu et al. [\(Wu et al.,](#page-13-3) [2020\)](#page-13-3) found that obtaining a flat loss landscape can help increase classification robustness, which inspired the ideas in this paper. There is also a line of work that attempts to accelerate AT. For example, Shafahi et al. [\(Shafahi](#page-12-5) [et al.,](#page-12-5) [2019\)](#page-12-5) reused calculated adversarial noises, Liu et al. [\(Liu et al.,](#page-11-8) [2021\)](#page-11-8) introduced single-step training. In this paper, we mainly consider the Madry adversarial training [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0) and TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1).

147 148 149 150 151 152 153 154 155 156 157 158 159 Explanation Robustness Saliency maps [\(Simonyan et al.,](#page-12-6) [2013;](#page-12-6) [Shrikumar et al.,](#page-12-7) [2017;](#page-12-7) [Bach et al.,](#page-10-11) [2015;](#page-10-11) [Selvaraju et al.,](#page-12-8) [2016\)](#page-12-8) are widely used to explain image-related tasks in deep learning, and our focus is on the robustness of these explanations. However, similar to an adversarial attack, it is possible to find an adversarial noise on original images so that it can easily manipulate the saliency maps without changing classification results in both white-box [\(Dombrowski et al.,](#page-10-0) [2019;](#page-10-0) [Ghorbani et al.,](#page-10-3) [2019;](#page-10-3) [Heo et al.,](#page-11-9) [2019;](#page-11-9) [Slack et al.,](#page-12-9) [2020\)](#page-12-9) and black-box settings [\(Tamam et al.,](#page-12-10) [2022\)](#page-12-10). Zhang et al. [\(Zhang et al.,](#page-13-4) [2020\)](#page-13-4) further introduced a new method that can attack both saliency maps and classification results. In order to evaluate the explanation robustness, Wicker et al. [\(Wicker et al.,](#page-12-11) [2022\)](#page-12-11) introduced the max-sensitivity and average-sensitivity of saliency maps. Alvarez et al. [\(Alvarez-Melis & Jaakkola,](#page-10-12) [2018\)](#page-10-12) estimated explanation robustness by the Local Lipschitz of interpretation while Tamam et al. [\(Tamam et al.,](#page-12-10) [2022\)](#page-12-10) directly used attack loss to evaluate explanation robustness. In this paper, we use attack loss based on the proposed cluster method to evaluate explanation robustness.

160 161 Several works have also aimed to improve explanation robustness. Chen et al. [\(Chen et al.,](#page-10-13) [2019\)](#page-10-13) introduced a regularization term during training to make the explanation more robust. Boopathy et al. [\(Boopathy et al.,](#page-10-1) [2020\)](#page-10-1) improved the performance by training with noisy labels. Tang et al. [\(Tang](#page-12-12)

3 METHODS

195

197 198 199

201

203

196 200 202 In the previous section, we observe a strange situation where increasing the explanation robustness does not flatten the input loss landscape w.r.t explanation robustness. To further explore, we consider this situation in a reverse way: *How Does flattening the input loss landscape w.r.t explanation loss influence the robustness of explanations?* In this section, we propose a new training algorithm to flatten the input loss landscape w.r.t explanation robustness. To explicitly guide the training with flattening input loss landscape w.r.t explanation robustness, we decide to add an extra loss:

 $\mathcal{L}_{f} = ||I(x + \zeta) - I(x) ||,$ (1)

204 205 206 207 208 209 210 where ζ is a noise randomly sampled from a standard Gaussian distribution and I is the explanation method. We use randomly sampled noise within a standard training framework instead of the min-max training framework used in the previous flatness-aware methods [\(Wu et al.,](#page-13-3) [2020\)](#page-13-3) because flat training methods based on AT [\(Wu et al.,](#page-13-3) [2020\)](#page-13-3) typically use an untargeted setting while off-theshelf explanation adversarial attacks must be executed in a target setting. A victim image and a target image are required for the explanation of adversarial attacks [\(Tamam et al.,](#page-12-10) [2022;](#page-12-10) [Dombrowski et al.,](#page-10-0) [2019\)](#page-10-0). Besides, calculating ζ through a targeted setting may increase the training time and increase the probability that the model is overfitting to the chosen pairs.

211 212 213 214 It is important to note that the new loss function \mathcal{L}_f can be incorporated into any training framework, including Madry adversarial training [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0), TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1), and normal training. We will mainly focus on Madry adversarial training plus the new training loss:

$$
\mathcal{L} = \mathcal{L}_{sc}(f(x_{adv}), y) + \lambda \mathcal{L}_f. \tag{2}
$$

254 255

257

Algorithm 1 Separate Explanation Robustness with PGD (SEP)

method as SEP_{pos} when λ is positive, and as SEP_{neg} when λ is negative. We summarize our algorithm in Algorithm [1.](#page-4-1) We also visualize the comparison of saliency maps from models trained with different algorithms to provide how our methods influence the saliency maps in Fig. [2.](#page-3-1)

4 LOSS LANDSCAPE VISUALIZATION

In this section, we discuss our strategy for obtaining models with varying levels of explanation robustness and detail our method for visualizing the input loss landscape. Research has shown a correlation between increased classification robustness and enhanced explanation robustness [\(Huang et al.,](#page-11-1) [2023\)](#page-11-1). To achieve models with different classification robustness levels, we use TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1), which offers detailed control over classification robustness compared to methods like Madry adversarial training [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0).

Background of TRADES TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1) is an adversarial training technique that balances classification and adversarial robustness using the loss function:

$$
L_{Tra} = L_{sc}(f(x), y) + \alpha L_{adv}(f(x), f(x_{adv})),
$$
\n(3)

where $f(x)$ is the model output, L_{sc} is the standard classification loss, x_{adv} is an adversarial example, and L_{adv} computes the KL divergence between original and adversarial representations. The parameter α controls the importance of classification robustness, allowing precise regulation of robustness levels.

251 252 253 Explanation Loss The objective, used to guide adversarial attacks on explanations, is defined to find a small noise ϵ as:

$$
\epsilon = \arg\min \|I(x_v + \epsilon) - I(x_t)\|,\qquad(4)
$$

256 258 where I represents the explanation method, x_t are target images, and x_v are victim images. We formally define explanation loss as follows.

259 260 Definition 1 (Explanation Loss). $\mathcal{L}_e(x_v+\epsilon, x_t)$ = $||I(x_v + \epsilon) - I(x_t)||.$

261 262 263 264 265 To prevent ϵ from being too large, additional classification loss is used to ensure manipulated images yield the same classification results [\(Dom](#page-10-0)[browski et al.,](#page-10-0) [2019;](#page-10-0) [Tamam et al.,](#page-12-10) [2022\)](#page-12-10).

266 267 268 269 Explanation Robustness Evaluation To measure explanation robustness, we propose using a representative subset of test images, chosen via clustering. Clustering aims that intra-cluster pairs share similar explanations. We cluster images based on

Figure 3: The explanations from different clusters generated by our clustering method on CIFAR10. The two images with different labels in the same cluster share a similar explanation while they both show a different explanation with the image from another cluster. The results show that our method can choose the most representative images w.r.t explanation.

270 271 272 273 274 the output from the last layer before the classification layer of a pre-trained ResNet18 [\(He et al.,](#page-11-10) 2016) using k-means [\(Lloyd,](#page-11-11) [1982\)](#page-11-11) with $k = 10$ by the guidance of elbow method. Visualizations of saliency maps show that images from the same cluster have similar explanations (see Fig. [3\)](#page-4-2). We also report the explanation loss for intra-cluster and inter-cluster pairs to show that our clustering method indeed makes intra-cluster pairs share similar explanations quantitatively in Appendix [C.](#page-16-0)

275 276 277 278 279 280 281 282 283 284 285 286 287 We select 15 images from each cluster to form a subset \mathcal{D}_e of the test set, containing 150 images and 22,350 (150×149) pairs. We report the mean explanation loss for all pairs in \mathcal{D}_e using a white-box attack method [\(Dom](#page-10-0)[browski et al.,](#page-10-0) [2019\)](#page-10-0) to evaluate explanation robustness in the rest of the paper. We also report the explanation loss at attack starts (Expl at Start) and loss at attack ends (Expl at End) to provide a comprehensive analysis of both robustness and flatness. A higher explanation loss indicates better explanation robustness because the model is harder to attack.

Table 1: Comparison of classification robustness and explanation robustness of models trained with TRADES and different α on CIFAR10. Within a certain range, using the TRADES training method and increasing the value of α can not only improve the classification robustness but also improve the explanation robustness.

288 Analysis In Table [1,](#page-5-1) we provide an evalua-

289 290 291 292 tion of classification robustness and explanation robustness for models trained with TRADES and different α on CIFAR10. From Table [1,](#page-5-1) it is easy to see that, with the increase of α , both the classification and explanation robustness of the model increase. Therefore, we obtain models with different explanation robustness.

293 294 295 296 297 298 299 Visualization After getting the models with different explanation robustness, the next step is to visualize input loss landscape w.r.t explanation loss. We visualize the input loss landscape by plotting the change of explanation loss when we add a random noise d to the victim image x_v with different magnitude γ :

$$
f(\gamma) = \mathcal{L}_e(x_v + \gamma \mathbf{d}, x_t), \quad (5)
$$

303 304 305 306 307 308 309 310 where d is sampled from a standard Gaussian distribution. We provide the mean explanation loss for all pairs in the subset we build, with the results displayed in Fig. [4.](#page-5-0) We can see that the adversarially trained models have better explanation robustness because of the high initial explanation loss instead of a flat loss landscape. We also visualize compared with normal training and Madry adversarial

5 EXPERIMENTAL RESULTS

Figure 4: Input Loss landscape w.r.t explanation loss for models trained with different with different α in TRADES. The loss landscape does not show a clear difference between models that vary in explanation robustness because the loss change remains the same.

311 312 313 314 315 316 317 training (MAT) in Appendix Fig. [7,](#page-15-0) and it shows similar results: increasing explanation robustness will not flatten the input loss landscape w.r.t explanation loss. Previous work on classification robustness [\(Xie et al.,](#page-13-0) [2020;](#page-13-0) [Li & Spratling,](#page-11-3) [2023\)](#page-11-3) has proven that a model with good classification robustness has a flat loss landscape w.r.t classification loss. However, different from the conclusions drawn in classification robustness, adversarially trained models don't exhibit a flat loss landscape w.r.t explanation loss. This phenomenon motivates us to propose the method in the following section to flatten the input loss landscape w.r.t explanation robustness.

318

300 301 302

319

320

321

322 323 In this section, we conduct verification experiments on multiple datasets and models to effectively demonstrate the ability of our proposed method to differentiate explanatory robustness from classification robustness.

324 325 326 327 328 329 330 331 Table 2: Performance of models trained with ConvNet and ResNet18 on various datasets is evaluated using four training methods, w.r.t. explanation loss at start, at end, and adversarial accuracy. Higher explanation loss at end indicates better explanation robustness; higher adversarial accuracy denotes better classification robustness. Explanation loss at start is also included to show our method's influence on explanation robustness. The **best** performance in explanation and classification robustness and the worst performance in explanation robustness are highlighted. There is no positive correlation between explanation and classification robustness achieved through SEP_{pos} and SEP_{neg} training methods, compared to MAT.

354 355

356

5.1 EXPERIMENTAL SETTINGS

357 358 359 360 361 362 Datasets To thoroughly demonstrate the impact of our proposed training method and the resulting conclusions, we conduct model training on five publicly available datasets for experiments: CIFAR10 [\(Krizhevsky et al.,](#page-11-12) [2009\)](#page-11-12), CIFAR100 [\(Krizhevsky et al.,](#page-11-12) [2009\)](#page-11-12), MNIST [\(LeCun et al.,](#page-11-13) [1989\)](#page-11-13), Fashion MNIST [\(Xiao et al.,](#page-13-5) [2017\)](#page-13-5), and TinyImageNet [\(Le & Yang,](#page-11-14) [2015\)](#page-11-14). Their detailed descriptions can be found in Appendix [A.](#page-14-0) We also consider using ImageNet [\(Deng et al.,](#page-10-14) [2009\)](#page-10-14) and the experiment results for ImageNet can be found in Appendix [E.3.](#page-17-0)

363 364 365 366 367 368 369 370 Model Architecture In addition to utilizing diverse datasets, we have also designed four distinct models for training on these datasets, further reinforcing our conclusions. We conduct exper-iments on ConvNet, ResNet [\(He et al.,](#page-11-10) [2016\)](#page-13-6), Wide ResNet [\(Zagoruyko & Komodakis,](#page-13-6) 2016) and MoblieNetV2 [\(Howard et al.,](#page-11-15) [2017;](#page-11-15) [Sandler et al.,](#page-12-15) [2018\)](#page-12-15). The ConvNet model consists of three convolutional layers and one fully connected layer from Gidaris et al. [\(Gidaris & Komodakis,](#page-10-15) [2018\)](#page-10-15). For ResNet and Wide ResNet, we use a standard ResNet18 and Wide-ResNet-28, respectively. We also adjust the ResNet, Wide ResNet, and MoblieNetV2 so that they can fit into all datasets we use. All four models employ the softplus [\(Zheng et al.,](#page-13-7) [2015\)](#page-13-7) activation function because it is better for the explanation attack method we use [\(Dombrowski et al.,](#page-10-0) [2019\)](#page-10-0).

371 372 373 374 Explanation Methods We mainly use: Gradient [\(Baehrens et al.,](#page-10-2) [2010\)](#page-10-2), Gradient \times Input[\(Shrikumar et al.,](#page-12-7) [2017\)](#page-12-7), Guided Backpropagation[\(Springenberg et al.,](#page-12-16) [2014\)](#page-12-16),Deep Lift [\(Shriku](#page-12-7)[mar et al.,](#page-12-7) [2017\)](#page-12-7) and Integrated Gradients [\(Sundararajan et al.,](#page-12-17) [2017\)](#page-12-17). We use Captum [\(Kokhlikyan](#page-11-16) [et al.,](#page-11-16) [2020\)](#page-11-16) for all explanation methods.

375 376 377 Training Methods We mainly consider 2 baselines: i) normal training (Normal), ii) Madry adversarial training (MAT) [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0). As mentioned in the Section [3,](#page-3-2) we explore two types of proposed method: SEP_{pos} and SEP_{neg} . In the rest of this paper, unless specified, we will use $\lambda = 50000$ for SEP_{pos} and $\lambda = -3000$ for SEP_{neg}.

378 379 380 381 382 383 Table 3: Performance of different explanation methods (Gradient and Guide Propagation) in the training phase is evaluated w.r.t. explanation loss at start, at end, and adversarial accuracy on CI-FAR10. Higher explanation loss at end indicates better explanation robustness, while higher adversarial accuracy denotes better classification robustness. The best and worst performances in explanation robustness and classification robustness are highlighted. Under various explanation methods, SEP_{pos} shows a lower explanation loss compared to SEP_{neg} , with similar adversarial accuracy.

Hyperparameters For all experiments, we train our models 25 epochs with 64 as the batch size. We also consider different training epochs and our conclusion remains the same in Appendix [E.5.](#page-18-0) To accelerate the training process, we use Adam [\(Kingma & Ba,](#page-11-17) [2014\)](#page-11-17) as the optimizer. We list the detailed hyperparameters for CIFAR10 in the Appendix Table [8.](#page-16-1) We use the standard settings in adversarial training [\(Pang et al.,](#page-11-18) [2020\)](#page-11-18), with $\epsilon = 8/255$ in PGD for RGB images and $\epsilon = 0.3$ for grayscale images, and steps in PGD are set to 10 for all experiments.

400 401 402 403 404 405 Metrics As mentioned in Section [4,](#page-4-0) we measure explanation robustness using the explanation loss at the end (after attack). A higher explanation loss indicates a worse attack and thus better explanation robustness. We also report the explanation loss at the start (before attack) to show the influence of our method on the explanation loss landscape. For classification robustness, we report adversarial accuracy, with higher values indicating better robustness. Additionally, we include clean accuracy to ensure the models function normally in non-adversarial settings.

5.2 SEPARATING EXPLANATION AND CLASSIFICATION ROBUSTNESS

We conducted a series of experiments involving multiple models and datasets on Gradient \times Input and results are shown in Table [2](#page-6-0) for ConvNet and ResNet18. We have the following observations:

- On one hand, SEP_{pos} , SEP_{neg} , and MAT have very similar adversarial accuracy, indicating their classification robustness is similar in all datasets and models. On the other hand, SEP_{pos} shows the weakest explanation robustness by having the lowest explanation loss at end. Similarly, SEP_{neg} shows the strongest explanation robustness. These results show that *there is no inherent relationship between explanation robustness and classification robustness*. The different performance w.r.t. explanation loss at end for SEP_{pos} and SEP_{neg} is mainly induced by the difference in explanation loss at start, which is influenced by our training method by setting different λ .
	- In the setting of CIFAR10 and ResNet18, increasing the explanation robustness by SEP_{neo} hurts the clean accuracy while it still does not change classification robustness. This observation further validates our argument: classification robustness and explanation robustness may not be strongly correlated. We provide the results for W-ResNet and MoblieNetV2 in the Appendix Table [6](#page-14-1) and the results show a very similar conclusion to the results of ConvNet and ResNet.
- **423 424 425**

426

5.3 INFLUENCE OF DIFFERENT EXPLANATION METHODS IN TRAINING PHASE

427 428 429 430 431 In the previous experiment, we demonstrated that our methods achieve similar classification robustness while exhibiting significantly different explanation robustness under the Gradient × Input explanation method. To further investigate whether this conclusion holds for different explanation methods, we trained models using Gradient and Guide Propagation. The results are based on CI-FAR10 and are summarized in Table [5](#page-9-0) with more datasets and more explanation methods including Deep Lift and Integrated Gradients can be found in Appendix [E.4.](#page-17-1) Our observations are as follows:

Figure 5: Performance of varying explanation methods in the testing phase, w.r.t. explanation loss at start, at end, and adversarial accuracy. Models are trained with Gradient x Input and tested on different explanation methods. All models are trained on CIFAR10. Even if the explanation methods during training and testing are different, SEP_{pos} shows a lower explanation loss compared to SEP_{neq} , while they have similar adversarial accuracy.

Figure 6: The test results of the model trained using the TRADE training method with CIFAR10, combined with our approach, are presented. The findings indicate that when we apply our method to TRADE, an alternative adversarial training method distinct from MAT, we can still deduce that classification robustness and explanation robustness are not inherently interconnected. This outcome demonstrates the universal applicability of our proposed method.

- Our methods achieve similar classification robustness under various explanation methods, yet they exhibit notably different explanation robustness. In most cases, SEP_{pos} shows lower explanation loss compared to SEP_{neg} , despite similar adversarial accuracy.
- Compared to MAT, our method SEP_{pos} shows comparable adversarial accuracy, indicating similar classification robustness, but it demonstrates distinct explanation loss characteristics. This suggests that explanation robustness and classification robustness may not be strongly correlated.
- 5.4 INFLUENCE OF DIFFERENT EXPLANATION METHODS IN TESTING PHASE

 In the previous experiments, the same explanation methods were used during both training and testing. To test if our findings hold when using different explanation methods during testing, in this experiment, we use the same model trained with Gradient \times Input (thus the classification robustness is the same for different testing phases), but change two different explanation methods (Gradient and Guide Propagation) in the testing phase. The results on CIFAR10 are shown in Fig. [5,](#page-8-0) where the detailed value of this experiment can be found in Appendix Table [9.](#page-17-2) While with the same classification robustness (as shown in Table [2,](#page-6-0) under adversarial accuracy in CIFAR10), there is a huge difference between SEP_{pos} and SEP_{neg} w.r.t the explanation losses (both at the start and the end). This indicates even with different explanation methods in the testing phase, the explanation robustness still does not show strong correlations with adversarial robustness.

- 5.5 INFLUENCE OF DIFFERENT ADVERSARIAL TRAINING METHODS
- All previous experiments utilized MAT [\(Madry et al.,](#page-11-0) [2017\)](#page-11-0) as the default adversarial training method. To assess the generalizability of our approach across different adversarial training methods, we employed TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1) in this experiment. Results in Fig. [6](#page-8-1) (details in

486 487 488 Appendix Table [10\)](#page-17-3) indicate that our SEP method impacts explanation robustness without altering classification robustness, suggesting a weak correlation between the two robustnesses.

489 5.6 PARAMETER SENSITIVITY ANALYSIS

490

491 492 493 494 In this section, we examine how different regularization weights λ affect the results (more results in the Appendix). We trained ConvNet networks on CIFAR10 with various λ values. Testing results are presented in Table [4.](#page-9-1) We observe that the choice of λ influences both the exploration rate at start and end. When λ is greater than 10^4 or less than $-3 * 10^3$, the explanation loss changes intensely.

Table 4: The evaluation of the ConvNet trained on CIFAR10 under different λ conditions reveals that the relationship between explanation and classification robustness is not positively correlated when an appropriate λ is selected during model training.

Table 5: Performance of different explanation methods (Gradient and Guide Propagation) in the training phase is evaluated w.r.t. explanation loss at start, at end, and adversarial accuracy on CI-FAR10. Higher explanation loss at end indicates better explanation robustness, while higher adversarial accuracy denotes better classification robustness. The best and worst performances in explanation robustness and classification robustness are highlighted. Under various explanation methods, SEP_{pos} shows a lower explanation loss compared to SEP_{neg} , with similar adversarial accuracy.

6 CONCLUSION

524 525 526 527 528 529 530 531 532 533 534 535 536 In summary, our study challenges the previous conclusion that explanation robustness and classification robustness are strongly correlated. Using TRADES [\(Zhang et al.,](#page-13-1) [2019\)](#page-13-1) to control explanation robustness by adjusting classification robustness, we found that increasing explanation robustness does not necessarily lead to a flatter input loss landscape for explanation loss. This contrasts with the observation that enhancing classification robustness results in a flatter input loss landscape for classification robustness. We introduce a novel algorithm to flatten the input loss landscape for explanation loss, addressing this contradiction. Our results show that our algorithm effectively improves explanation robustness without changing classification robustness, indicating a potential lack of strong correlation between the two. Our results reveal the importance of considering and optimizing both aspects separately to ensure the overall reliability and trustworthiness of AI systems in sensitive areas such as healthcare. For our future works, we hope to dive into two different robustness to understand why adversarial training can increase explanation robustness and what might be the inner difference between two robustness to understand more about the inner mechanism of adversarial attacks and explanations.

537

538

540 541 REFERENCES

547

- **542 543** David Alvarez-Melis and Tommi S Jaakkola. On the robustness of interpretability methods. *arXiv preprint arXiv:1806.08049*, 2018. [3](#page-2-0)
- **544 545 546** Anish Athalye, Nicholas Carlini, and David Wagner. Obfuscated gradients give a false sense of security: Circumventing defenses to adversarial examples. In *International conference on machine learning*, pp. 274–283. PMLR, 2018. [3](#page-2-0)
- **548 549 550** Sebastian Bach, Alexander Binder, Grégoire Montavon, Frederick Klauschen, Klaus-Robert Müller, and Wojciech Samek. On pixel-wise explanations for non-linear classifier decisions by layer-wise relevance propagation. *PloS one*, 10(7):e0130140, 2015. [3](#page-2-0)
- **551 552 553** David Baehrens, Timon Schroeter, Stefan Harmeling, Motoaki Kawanabe, Katja Hansen, and Klaus-Robert Müller. How to explain individual classification decisions. *The Journal of Machine Learning Research*, 11:1803–1831, 2010. [2,](#page-1-1) [7](#page-6-1)
- **554 555 556 557** Akhilan Boopathy, Sijia Liu, Gaoyuan Zhang, Cynthia Liu, Pin-Yu Chen, Shiyu Chang, and Luca Daniel. Proper network interpretability helps adversarial robustness in classification. In *International Conference on Machine Learning*, pp. 1014–1023. PMLR, 2020. [1,](#page-0-0) [3,](#page-2-0) [4](#page-3-3)
- **558 559 560 561** Wieland Brendel, Jonas Rauber, Alexey Kurakin, Nicolas Papernot, Behar Veliqi, Sharada P Mohanty, Florian Laurent, Marcel Salathé, Matthias Bethge, Yaodong Yu, et al. Adversarial vision challenge. In *The NeurIPS'18 Competition: From Machine Learning to Intelligent Conversations*, pp. 129–153. Springer, 2020. [3](#page-2-0)
- **562 563** Nicholas Carlini and David Wagner. Towards evaluating the robustness of neural networks. In *2017 ieee symposium on security and privacy (sp)*, pp. 39–57. Ieee, 2017. [3](#page-2-0)
	- Nicholas Carlini, Florian Tramer, Krishnamurthy Dj Dvijotham, Leslie Rice, Mingjie Sun, and J Zico Kolter. (certified!!) adversarial robustness for free! *arXiv preprint arXiv:2206.10550*, 2022. [3](#page-2-0)
- **568 569 570** Yair Carmon, Aditi Raghunathan, Ludwig Schmidt, John C Duchi, and Percy S Liang. Unlabeled data improves adversarial robustness. *Advances in neural information processing systems*, 32, 2019. [3](#page-2-0)
- **571 572 573** Jiefeng Chen, Xi Wu, Vaibhav Rastogi, Yingyu Liang, and Somesh Jha. Robust attribution regularization. *Advances in Neural Information Processing Systems*, 32, 2019. [3](#page-2-0)
- **574 575 576 577** Kejiang Chen, Yuefeng Chen, Hang Zhou, Xiaofeng Mao, Yuhong Li, Yuan He, Hui Xue, Weiming Zhang, and Nenghai Yu. Self-supervised adversarial training. In *ICASSP 2020-2020 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)*, pp. 2218–2222. IEEE, 2020a. [3](#page-2-0)
- **578 579 580** Tianlong Chen, Zhenyu Zhang, Sijia Liu, Shiyu Chang, and Zhangyang Wang. Robust overfitting may be mitigated by properly learned smoothening. In *International Conference on Learning Representations*, 2020b. [3](#page-2-0)
	- Jia Deng, Wei Dong, Richard Socher, Li-Jia Li, Kai Li, and Li Fei-Fei. Imagenet: A large-scale hierarchical image database. In *2009 IEEE conference on computer vision and pattern recognition*, pp. 248–255. Ieee, 2009. [7,](#page-6-1) [15](#page-14-2)
- **585 586 587** Ann-Kathrin Dombrowski, Maximillian Alber, Christopher Anders, Marcel Ackermann, Klaus-Robert Müller, and Pan Kessel. Explanations can be manipulated and geometry is to blame. *Advances in neural information processing systems*, 32, 2019. [1,](#page-0-0) [2,](#page-1-1) [3,](#page-2-0) [4,](#page-3-3) [5,](#page-4-3) [6,](#page-5-2) [7](#page-6-1)
- **588 589 590 591** Amirata Ghorbani, Abubakar Abid, and James Zou. Interpretation of neural networks is fragile. In *Proceedings of the AAAI conference on artificial intelligence*, volume 33, pp. 3681–3688, 2019. [2,](#page-1-1) [3](#page-2-0)
- **592 593** Spyros Gidaris and Nikos Komodakis. Dynamic few-shot visual learning without forgetting. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 4367–4375, 2018. [7](#page-6-1)

612

632 633 634

- **594 595 596** Ian J Goodfellow, Jonathon Shlens, and Christian Szegedy. Explaining and harnessing adversarial examples. *arXiv preprint arXiv:1412.6572*, 2014. [1,](#page-0-0) [3](#page-2-0)
- **597 598 599** Kaiming He, Xiangyu Zhang, Shaoqing Ren, and Jian Sun. Deep residual learning for image recognition. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 770–778, 2016. [6,](#page-5-2) [7](#page-6-1)
- **600 601 602** Dan Hendrycks, Kimin Lee, and Mantas Mazeika. Using pre-training can improve model robustness and uncertainty. In *International conference on machine learning*, pp. 2712–2721. PMLR, 2019. [3](#page-2-0)
	- Juyeon Heo, Sunghwan Joo, and Taesup Moon. Fooling neural network interpretations via adversarial model manipulation. *Advances in neural information processing systems*, 32, 2019. [3](#page-2-0)
- **606 607 608** Andrew G Howard, Menglong Zhu, Bo Chen, Dmitry Kalenichenko, Weijun Wang, Tobias Weyand, Marco Andreetto, and Hartwig Adam. Mobilenets: Efficient convolutional neural networks for mobile vision applications. *arXiv preprint arXiv:1704.04861*, 2017. [7](#page-6-1)
- **609 610 611** Wei Huang, Xingyu Zhao, Gaojie Jin, and Xiaowei Huang. Safari: Versatile and efficient evaluations for robustness of interpretability. In *Proceedings of the IEEE/CVF International Conference on Computer Vision*, pp. 1988–1998, 2023. [1,](#page-0-0) [4,](#page-3-3) [5](#page-4-3)
- **613 614 615** Gaojie Jin, Xinping Yi, Dengyu Wu, Ronghui Mu, and Xiaowei Huang. Randomized adversarial training via taylor expansion. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 16447–16457, 2023. [3](#page-2-0)
- **616 617** Diederik P Kingma and Jimmy Ba. Adam: A method for stochastic optimization. *arXiv preprint arXiv:1412.6980*, 2014. [8](#page-7-0)
- **618 619 620 621 622** Narine Kokhlikyan, Vivek Miglani, Miguel Martin, Edward Wang, Bilal Alsallakh, Jonathan Reynolds, Alexander Melnikov, Natalia Kliushkina, Carlos Araya, Siqi Yan, et al. Captum: A unified and generic model interpretability library for pytorch. *arXiv preprint arXiv:2009.07896*, 2020. [7](#page-6-1)
- **623 624** Alex Krizhevsky, Geoffrey Hinton, et al. Learning multiple layers of features from tiny images. 2009. [7,](#page-6-1) [15](#page-14-2)
- **625 626** Ya Le and Xuan Yang. Tiny imagenet visual recognition challenge. *CS 231N*, 7(7):3, 2015. [7,](#page-6-1) [15](#page-14-2)
- **627 628 629** Yann LeCun, Bernhard Boser, John S Denker, Donnie Henderson, Richard E Howard, Wayne Hubbard, and Lawrence D Jackel. Backpropagation applied to handwritten zip code recognition. *Neural computation*, 1(4):541–551, 1989. [7,](#page-6-1) [15](#page-14-2)
- **630 631** Lin Li and Michael Spratling. Understanding and combating robust overfitting via input loss landscape analysis and regularization. *Pattern Recognition*, 136:109229, 2023. [2,](#page-1-1) [6](#page-5-2)
	- Ji Lin, Chuang Gan, and Song Han. Defensive quantization: When efficiency meets robustness. *arXiv preprint arXiv:1904.08444*, 2019. [3](#page-2-0)
- **635 636 637** Guanxiong Liu, Issa Khalil, and Abdallah Khreishah. Using single-step adversarial training to defend iterative adversarial examples. In *Proceedings of the Eleventh ACM Conference on Data and Application Security and Privacy*, pp. 17–27, 2021. [3](#page-2-0)
	- Stuart Lloyd. Least squares quantization in pcm. *IEEE transactions on information theory*, 28(2): 129–137, 1982. [6](#page-5-2)
- **641 642 643** Aleksander Madry, Aleksandar Makelov, Ludwig Schmidt, Dimitris Tsipras, and Adrian Vladu. Towards deep learning models resistant to adversarial attacks. *arXiv preprint arXiv:1706.06083*, 2017. [1,](#page-0-0) [3,](#page-2-0) [4,](#page-3-3) [5,](#page-4-3) [7,](#page-6-1) [9](#page-8-2)
- **644 645 646** Tianyu Pang, Kun Xu, Yinpeng Dong, Chao Du, Ning Chen, and Jun Zhu. Rethinking softmax cross-entropy loss for adversarial robustness. *arXiv preprint arXiv:1905.10626*, 2019. [3](#page-2-0)
- **647** Tianyu Pang, Xiao Yang, Yinpeng Dong, Hang Su, and Jun Zhu. Bag of tricks for adversarial training. *arXiv preprint arXiv:2010.00467*, 2020. [8](#page-7-0)

671

680

683

- **648 649 650** Nicolas Papernot, Patrick McDaniel, Xi Wu, Somesh Jha, and Ananthram Swami. Distillation as a defense to adversarial perturbations against deep neural networks. In *2016 IEEE symposium on security and privacy (SP)*, pp. 582–597. IEEE, 2016. [3](#page-2-0)
- **652 653 654** Mark Sandler, Andrew Howard, Menglong Zhu, Andrey Zhmoginov, and Liang-Chieh Chen. Mobilenetv2: Inverted residuals and linear bottlenecks. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 4510–4520, 2018. [7](#page-6-1)
- **655 656** Ramprasaath R Selvaraju, Abhishek Das, Ramakrishna Vedantam, Michael Cogswell, Devi Parikh, and Dhruv Batra. Grad-cam: Why did you say that? *arXiv preprint arXiv:1611.07450*, 2016. [3](#page-2-0)
	- Ali Shafahi, Mahyar Najibi, Mohammad Amin Ghiasi, Zheng Xu, John Dickerson, Christoph Studer, Larry S Davis, Gavin Taylor, and Tom Goldstein. Adversarial training for free! *Advances in Neural Information Processing Systems*, 32, 2019. [3](#page-2-0)
- **661 662 663** Avanti Shrikumar, Peyton Greenside, and Anshul Kundaje. Learning important features through propagating activation differences. In *International conference on machine learning*, pp. 3145– 3153. PMLR, 2017. [3,](#page-2-0) [7](#page-6-1)
	- Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman. Deep inside convolutional networks: Visualising image classification models and saliency maps. *arXiv preprint arXiv:1312.6034*, 2013. [3](#page-2-0)
- **668 669 670** Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman. Deep inside convolutional networks: Visualising image classification models and saliency maps. arxiv 2013. *arXiv preprint arXiv:1312.6034*, 2019. [4](#page-3-3)
- **672 673 674** Dylan Slack, Sophie Hilgard, Emily Jia, Sameer Singh, and Himabindu Lakkaraju. Fooling lime and shap: Adversarial attacks on post hoc explanation methods. In *Proceedings of the AAAI/ACM Conference on AI, Ethics, and Society*, pp. 180–186, 2020. [3](#page-2-0)
- **675 676 677** Yang Song, Taesup Kim, Sebastian Nowozin, Stefano Ermon, and Nate Kushman. Pixeldefend: Leveraging generative models to understand and defend against adversarial examples. *arXiv preprint arXiv:1710.10766*, 2017. [3](#page-2-0)
- **678 679** Jost Tobias Springenberg, Alexey Dosovitskiy, Thomas Brox, and Martin Riedmiller. Striving for simplicity: The all convolutional net. *arXiv preprint arXiv:1412.6806*, 2014. [7](#page-6-1)
- **681 682** Mukund Sundararajan, Ankur Taly, and Qiqi Yan. Axiomatic attribution for deep networks. In *International conference on machine learning*, pp. 3319–3328. PMLR, 2017. [7](#page-6-1)
- **684 685 686** Christian Szegedy, Wojciech Zaremba, Ilya Sutskever, Joan Bruna, Dumitru Erhan, Ian Goodfellow, and Rob Fergus. Intriguing properties of neural networks. *arXiv preprint arXiv:1312.6199*, 2013. [1,](#page-0-0) [3](#page-2-0)
- **687 688** Snir Vitrack Tamam, Raz Lapid, and Moshe Sipper. Foiling explanations in deep neural networks. *arXiv preprint arXiv:2211.14860*, 2022. [3,](#page-2-0) [4,](#page-3-3) [5](#page-4-3)
- **690 691** Ruixiang Tang, Ninghao Liu, Fan Yang, Na Zou, and Xia Hu. Defense against explanation manipulation. *Frontiers in big Data*, 5:704203, 2022. [3,](#page-2-0) [4](#page-3-3)
- **692 693 694** Florian Tramer, Alexey Kurakin, Nicolas Papernot, Ian Goodfellow, Dan Boneh, and Patrick Mc- ` Daniel. Ensemble adversarial training: Attacks and defenses. *arXiv preprint arXiv:1705.07204*, 2017. [3](#page-2-0)
- **695 696 697** Zekai Wang, Tianyu Pang, Chao Du, Min Lin, Weiwei Liu, and Shuicheng Yan. Better diffusion models further improve adversarial training. *arXiv preprint arXiv:2302.04638*, 2023. [3](#page-2-0)
- **698 699 700** Zifan Wang, Matt Fredrikson, and Anupam Datta. Robust models are more interpretable because attributions look normal. *arXiv preprint arXiv:2103.11257*, 2021. [4](#page-3-3)
- **701** Matthew Wicker, Juyeon Heo, Luca Costabello, and Adrian Weller. Robust explanation constraints for neural networks. *arXiv preprint arXiv:2212.08507*, 2022. [3](#page-2-0)

756 757 758 759 760 761 Table 6: Test results of models trained by Wide ResNet network and MobileNet network on various data sets according to four training methods. The results presented indicate that the performance of models trained using the Wide ResNet network and MobileNet network on different datasets suggests that there is no positive correlation between the model's explanation robustness and classification robustness achieved through the SEP_{pos} and SEP_{neg} training methods, as compared to the MAT training method.

A CODE AND DATA

This is our open source code link: [open source code.](https://anonymous.4open.science/r/seperate_two_robustness-D231/README.md)

We conduct model training on five publicly available datasets for experiments:

- CIFAR10 [Krizhevsky et al.](#page-11-12) [\(2009\)](#page-11-12): consisting of 60k 32×32 color images in 10 classes including 50k training and 10k test images.
- CIFAR100 [Krizhevsky et al.](#page-11-12) [\(2009\)](#page-11-12): containing the same images as CIFAR10 but has a more refined label with 100 categories.
- **MNIST** [LeCun et al.](#page-11-13) [\(1989\)](#page-11-13): containing 60k training samples and 10k test samples from 10 digit classes. Each digit is a 28×28 grayscale image.
- Fashion MNIST [Xiao et al.](#page-13-5) [\(2017\)](#page-13-5): consisting of 60k training samples and $10k$ test samples from 10 classes. Each sample is a 28×28 grayscale image in a clothes category.
- TinyImageNet [Le & Yang](#page-11-14) [\(2015\)](#page-11-14): it is a subset of ImageNet [Deng et al.](#page-10-14) [\(2009\)](#page-10-14) with 64x64 pixels and 200 categories

B MORE VISUALIZATION RESULTS

809

771 772 773

Firstly, we visualize the input loss landscape w.r.t explanation loss using a normal trained model and model trained with Madry adversarial training in Fig. [7.](#page-15-0) The results show that increasing the explanation robustness does not flatten the input loss landscape. Besides, we also visualize more saliency maps with more explanation methods with images from different clusters in Fig. [8.](#page-15-1) They all prove that we can choose the most representative saliency maps.

Figure 8: Explanation of images from different clusters. The results show that images from the same cluster that even have different labels still have similar saliency maps on various explanation methods. Besides, images with the same label from different clusters still have different explanations. These results show that our method can sample the most representative subset of explanations.

C EXPLANATION LOSS FOR INTRA-CLUSTER AND INTER-CLUSTER PAIRS

In the paper, we use Fig. 2&.8 to show the images within the same cluster share similar explanations qualitatively. Here, Table [7](#page-16-2) shows the quantitative results of *explanation loss at start* for the intra-cluster and inter-cluster on ResNet18. We will add more results and demonstrations in the final version.

Table 7: Explanation loss at start of intra and inter clusters. The smaller explanation loss in the intra-cluster shows that images in the same cluster have similar explanations.

D DETAILED HYPERPARAMETER

In this section, we provide the detailed hyperparameter for our CIFAR10 dataset in Table [8.](#page-16-1)

Table 8: Comparison of explanation loss for intra-cluster sample and inter-cluster sample on CI-FAR10. The results show that our cluster method indeed the cluster images with similar explanations.

894 895 896

E MORE EXPERIMENTAL RESULTS

E.1 EXPERIMENTS ON W-RESNET AND MOBILENET

We list the main results using Gradient X Inputs as training and testing explanation methods for W-ResNet and MobileNetV2 in Table [6.](#page-14-1) We have the following observations:

- Once again, the adversarial accuracy for MAT, SEP_{pos} , and SEP_{neg} is similar in most scenarios for W-ResNet and MobileNet, while SEP_{pos} always has a smaller explanation loss compared with MAT, and SEP_{neq} always has a larger explanation loss compared with MAT. These results show that influencing explanation robustness does not necessarily change classification robustness.
- For W-ResNet and MobileNet, the adversarial accuracy for CIFAR100 fluctuates. For MobileNet and CIFAR100, compared with MAT, SEP_{pos} increases classification robustness while SEP_{neg} decreases it. However, this observation also indicates that the positive correlation between explanation robustness and classification robustness might not be true since SEP_{pos} decreases explanation robustness while increasing classification robustness.

914 915 E.2 DETAILED VALUES FOR TRANSFERABLITY EXPERIMENTS

916 917 The detailed values for Transferablity experiments can be found in Table [9](#page-17-2) and the detailed values for experiments using TRADES for our method can be found in Table [10.](#page-17-3) The analysis of these results can be found in the main paper.

918 919 920 921 922 Table 9: Test results for transferability of explanation robustness. Models are trained with Gradient x Input and tested on different explanation methods.All models are trained on CIFAR10. Even if the interpretation methods during training and testing are different, comparing the training results of our proposed method with the AT training method of the corresponding configuration in Table [2,](#page-6-0) we can still draw our previous conclusions, which also shows that our conclusions are transferable.

928 929 930

> Table 10: The test results of the model trained using the TRADE training method, combined with our approach. The findings indicate that when we apply our method to TRADE, an alternative adversarial training method distinct from MAT, we can still deduce that classification robustness and interpretation robustness are not inherently interconnected.

E.3 EXPERIMENTS ON IMAGENET

Here, we present our experiments on ImageNet with ResNet18 in Table [11.](#page-17-4) We can find that the conclusion of ImageNet experiments is the same as the main paper: Increasing or decreasing explanation robustness will not necessarily influence the classification robustness.

Table 11: Experiments for ImageNet on ResNet18. The results are aligned with the conclusion made in the main paper.

E.4 MORE EXPERIMENTS ON DIFFERENT EXPLANATION METHODS

968 969 970 971 We provide more results for FashionMnist and TinyImageNet on ConvNet and ResNet using Guide Propagation as the explanation method in Table [15.](#page-19-0) We also provide the experimental results for DeepLift and Integrated Gradients in Table [12.](#page-18-1) The results show a similar conclusion in the main text, where it is possible to influence the explanation robustness without changing adversarial robustness, which demonstrates that our conclusion works in general for different explanation methods.

972 973 974 975 976 977 Table 12: Performance of using DeepLift and Intergrated Gradients as explanation methods with ConvNet. Higher explanation loss at end indicates better explanation robustness, while higher adversarial accuracy denotes better classification robustness. The best and worst performances in explanation robustness and classification robustness are highlighted. Under various explanation methods, SEP_{pos} shows a lower explanation loss compared to SEP_{neg} , with similar adversarial accuracy.

996

E.5 MORE PARAMETER SENSITIVITY STUDIES

997 998 999 1000 1001 1002 Training Epochs We conducted experiments on the ConvNet network using the CIFAR10 dataset to show that our chosen training epoch is reasonable. The results, as presented in Table [13,](#page-18-2) indicate that the model's performance undergoes only marginal changes after 25 rounds for ConvNet, despite the epoch count continuing to increase. Choosing 25 epochs does not hurt the reliability of our argument. Besides, the results also support our conclusion. With the increase of training epochs, the classification robustness still increases while the explanation robustness actually decreases.

1003 1004 1005 1006 1007 Table 13: The test results of ConvNet network at different training epochs on the CIFAR10 data set.The findings indicate that as we increase the number of training epochs from 25, there is only marginal improvement in the model's performance for ConvNet. Therefore, we have decided to select 25 epochs as the final number of training epochs for all our models. This choice will not impact our final conclusions, while also allowing for faster training speed.

1011 1012 1013

1008 1009 1010

1014 1015 1016 Table 14: The results of ResNet18 with different training epochs on CIFAR10. The results show that with increasing training epochs, the accuracy of ResNet18 on CIFAR10 keeps increasing while our conclusion remains the same.

1023 1024

-
-
-
-
-
-
-

-
-
-

 Table 15: Performance of using Guide Propagation in the training phase with Fashion-MNIST and TinyImageNet. Higher explanation loss at end indicates better explanation robustness, while higher adversarial accuracy denotes better classification robustness. The best and worst performances in explanation robustness and classification robustness are highlighted. Under various explanation methods, SEP_{pos} shows a lower explanation loss compared to SEP_{neg} , with similar adversarial accuracy.

1052										
		ConvNet					ResNet18			
1053	FMNIST									
1054	Method	Expl at Start (10^{-7})	Expl at End	Clean Acc $(\%)$	Adv Acc $(\%)$	Expl at Start	Expl at End	Clean Acc $(\%)$	Adv Acc $(\%)$	
	Normal	30.932	18.451	92.79	0.00	66.131	29.110	91.57	0.00	
1055	MAT	97.726	72.402	62.85	73.98	608.486	467.815	79.22	67.10	
	SEP_{pos}	48.368	34.672	78.46	67.28	97.703	78.354	77.55	62.09	
1056	SEP_{neq}	542.540	425.948	65.07	77.17	4219.351	3839.408	80.11	72.21	
	TinyImageNet									
1057	Method	Expl at Start (10^{-7})	Expl at End	Clean Acc $(\%)$	Adv Acc	Expl at Start	Expl at End	Clean Acc $(\%)$	Adv Acc $(\%)$	
1058	Normal	0.559	0.281	28.71	0.00	0.617	0.216	28.34	0.00	
	MAT	1.356	0.787	25.13	9.55	2.577	1.411	26.33	10.81	
1059	SEP_{pos}	0.983	0.625	25.16	5.97	1.767	1.226	28 68	11.47	
	SEP_{neq}	1.566	0.977	24.89	4.99	3.403	1.761	26.79	11.23	
1060										