

Diffusion-NAT: Self-Prompting Discrete Diffusion for Non-Autoregressive Text Generation

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Abstract

Recently, continuous diffusion models (CDM) have been introduced into non-autoregressive (NAR) text-to-text generation. However, the discrete nature of text increases the difficulty of CDM to generate coherent and fluent texts, and also causes the incompatibility problem between CDM and advanced NLP techniques, especially the popular pre-trained language models (PLMs). To solve it, we propose Diffusion-NAT, which introduces discrete diffusion models (DDM) into NAR text-to-text generation and integrates BART to improve the performance. By revising the decoding process of BART and the typical settings of DDM, we unify the inference process of BART and the denoising process of DDM into the same NAR masked tokens recovering task. In this way, DDM can rely on BART to perform denoising, which can benefit from both the rich pre-learned knowledge of BART and the iterative refining paradigm of DDM. Besides, we also propose the iterative self-prompting strategy to further improve the generation quality. Experimental results on 7 datasets show that our approach can outperform competitive NAR methods, and even surpass autoregressive methods. Our code and data will be publicly released.

1 Introduction

Text-to-text generation (Sutskever et al., 2014; Vaswani et al., 2017) is an essential task in natural language processing, which aims to generate human-like texts satisfying the task demand. To efficiently generate high-quality texts, non-autoregressive (NAR) models (Gu et al., 2018; Lee et al., 2018) are widely explored for text-to-text generation by predicting all tokens in the target text simultaneously, having a lower inference latency.

Despite the efficiency, the generation accuracy of NAR models generally underperform autoregressive (AR) models with the token-by-token generation, since parallel token prediction cannot effectively capture the dependency among the to-

Model	Type	PLMs	Cost	NAR	T2T
D3PM	Dis.	×	Low	✓	×
Diffusion-LM	Con.	×	Low	✓	×
SED	Con.	×	Low	✓	×
SSD-LM	Con.	✓	High	✓	×
DiffusionBERT	Dis.	✓	High	✓	×
LD4LG	Con.	✓	Low	×	×
DiffuSeq	Con.	×	Low	✓	✓
SeqDiffuSeq	Con.	×	Low	✓	✓
GENIE	Con.	×	High	✓	✓
Difformer	Con.	×	Low	✓	✓
Ours	Dis.	✓	Low	✓	✓

Table 1: A comparison of existing diffusion methods for text generation. **Dis.** and **Con.** refer to discrete and continuous diffusion. **PLMs**, **Cost**, **NAR** and **T2T** denote using PLMs, Training Cost, Non-AutoRegressive model and Text-to-Text generation, respectively.

kens. To enhance the generation quality, a variety of techniques have been proposed for NAR models, with either improved architectures (Qian et al., 2021) or training methods (Qi et al., 2021). More recently, inspired by the success of diffusion models in computer vision (Ho et al., 2020; Dhariwal and Nichol, 2021), they have been introduced to improve NAR models for text-to-text generation (Chen et al., 2023; Floto et al., 2023; Lyu et al., 2023; Mahabadi et al., 2023). As shown in Table 1, these studies typically adopt the continuous diffusion method on the latent space of token embeddings in the NAR manner, and iteratively refine all the target token embeddings via a parameterized denoising process.

However, these attempts are highly limited by the discrete nature of text, and thus it is necessary to incorporate special strategies to adapt continuous diffusion models for text generation. Typically, they rely on an additional rounding step (Li et al., 2022b) to map the generated embeddings into tokens, and add corresponding loss during training. However, the added step and training loss would burden the diffusion models, causing them hungry for more training steps and data to

capture the mapping relation between input and output. Although large-scale pre-trained language models (PLMs) (Devlin et al., 2019; Lewis et al., 2020) seem to be a promising solution to alleviate this hunger problem, due to the large model discrepancy, it is difficult to use existing PLMs for improving the text generation models when integrating with continuous diffusion models, even leading to performance degradation (Li et al., 2022b).

To address these issues, we aim to develop a more effective approach to integrating diffusion models and PLMs for NAR text-to-text generation. Instead of using continuous diffusion, we utilize discrete diffusion (Austin et al., 2021; Gu et al., 2022) for text generation, which performs denoising on discrete states (e.g., vocabulary) to recover the original tokens. It is more suitable for modeling discrete text data, making it feasible to develop more *unified and compatible* solutions to integrate diffusion models and well-trained PLMs for improving NAR text generation. However, both discrete diffusion models and PLMs neither naturally fit with each other nor the NAR text-to-text generation manner, making it hard to directly combine them for improving the NAR generation quality.

In this paper, we propose **Diffusion-NAT**, a self-prompting discrete diffusion model using PLMs for NAR text-to-text generation. The core contribution lies in that we unify the *inference process* of PLMs and *denoising process* of discrete diffusion models into the same **masked token recovering task** in the NAR manner. In this way, PLMs can play the role of the parameterized denoiser in discrete diffusion models, hence we can combine the merits of both diffusion models (*using iterative refining generation*) and PLMs (*with rich semantic knowledge*) for improving NAR text generation. Specifically, we select the Seq2Seq PLM, BART (Lewis et al., 2020) as our backbone by revising its decoding process into the NAR masked tokens recovering task. Then, we adjust the typical discrete diffusion method to better fit the PLM by adding mask tokens as noise, revising the learning objective and removing the time step embeddings. Further, as our approach performs the denoising process fully based on the PLM, we devise an iterative self-prompting strategy to guide the PLM performing multi-turn deliberation and refinement on the intermediate generated results, to enhance the quality of the final output.

To demonstrate the effectiveness of our approach, we conduct extensive experiments on seven

text-to-text generation datasets. Experimental results show that our approach can outperform competitive NAR text generation methods, e.g., improving the best NAR models by +2.48 BLEU-2 on PersonaChat, +4.33 Distinct-2 on DailyDialog. Our approach even surpasses state-of-the-art autoregressive PLMs, e.g., Ours (62.68) v.s. BART (49.59) on BLEU-2 in DailyDialog, and Our (44.2) v.s. BART (38.3) on ROUGE-L in MSNews. Besides, our approach also supports DDIM (Song et al., 2021a) for fast inference, which also provides a way to trade off the time cost and the generation quality during inference. By setting proper diffusion steps (e.g., 100 and 2), our approach can outperform competitive AR and NAR models with similar inference latency, respectively.

2 Related Work

Non-Autoregressive Text Generation. Compared with autoregressive (AR) methods (Lewis et al., 2020) that need to predict the target text in a token-by-token manner, Non-autoregressive (NAR) methods can generate all tokens in parallel, which can greatly reduce the inference latency (Gu et al., 2018; Ghazvininejad et al., 2019). However, in this way, NAT methods can not fully capture the dependency relations among tokens during decoding, leading to the sacrifice of accuracy. To address it, existing works adopt several training and inference strategies to improve the performance of NAR methods, e.g., knowledge distillation (Zhou et al., 2020), glancing sampling (Qian et al., 2021), iterative decoding (Geng et al., 2021) and large-scale pre-training (Qi et al., 2021; Li et al., 2022a). In this work, we introduce the discrete diffusion model into NAR text generation, narrowing the performance gap with AR methods.

PLMs for Text Generation. Pre-trained language models (PLMs) have shown remarkable performance in generating human-like texts (Li et al., 2021). After pre-training, most existing PLMs (Raffel et al., 2020) are fine-tuned following the AR paradigm for text generation. In this way, they either reformulate generation tasks into the language model format (e.g., GPT (Radford et al., 2019)), or leverage the sequence-to-sequence manner to generate the text using an autoregressive decoder (e.g., BART (Lewis et al., 2020)). However, as these PLMs only focus on fine-tuning under the AR paradigm, they can not be directly used for NAR text generation. Recently, BANG (Qi

et al., 2021) and ELMER (Li et al., 2022a) rely on large-scale pre-training for improving the NAR text generation. Considering the pre-training cost, we aim to efficiently adapt BART into an effective NAR model with diffusion models.

Diffusion Models for Text Generation. Diffusion models (DM) (Ho et al., 2020; Song et al., 2021b) are a class of latent variable models that can progressively denoise a random Gaussian noise into a data example. Existing DMs can be roughly categorized into continuous diffusion models (Ho et al., 2020; Tang et al., 2023a; Nikolaidou et al., 2023) and discrete diffusion models (Austin et al., 2021; Zheng et al., 2023; Qian et al., 2022), which perform diffusion on continuous signals and discrete states, respectively. Recently, DMs have been utilized for text generation and have demonstrated superiority in controllable text generation tasks (Tang et al., 2023b; Li et al., 2022b). For text-to-text generation tasks, existing works generally follow the continuous diffusion paradigm, and improve the performance by refining the model architecture (Yuan et al., 2022), adding regularization (Gao et al., 2022) and large-scale pre-training (Lin et al., 2022). In this work, we introduce discrete diffusion models into text-to-text generation tasks, and utilize a PLM to improve it.

3 Preliminary

Problem Statement. This work focuses on text-to-text generation tasks using non-autoregressive (NAR) models. Generally, text-to-text generation tasks (Sutskever et al., 2014; Vaswani et al., 2017) (e.g., dialog and summarization) can be formulated as modeling the conditional probability $P(Y|C)$, where $C = \{c_1, c_2, \dots, c_m\}$ and $Y = \{y_1, y_2, \dots, y_n\}$ denote the input text and output text respectively, both consisting of a sequence of tokens from a vocabulary \mathcal{V} .

Different from AR models with the left-to-right token-by-token generation manner, NAR models (Gu et al., 2018; Lee et al., 2018) predict all tokens of the output text Y simultaneously, where each token y_i is predicted only based on the input text C . Thus, the conditional probability can be factorized as

$$P(Y|C) = \prod_{i=1}^n P(y_i|C), \quad (1)$$

Diffusion Models. Diffusion models (DM) (Ho et al., 2020; Song et al., 2021b) sample an exam-

ple from a data distribution $p(x)$ by gradually denoising a random noise. Typically, starting from a noise x_T , the denoising process (also so-called reverse process) can be regarded as a Markov process, where the noises at $T-1, T-2, \dots, 0$ steps are progressively predicted and removed to obtain the latent variables x_{T-1}, x_{T-2}, \dots , until reaching the final sample x_0 . Conversely, given the sample x_0 , we can generate x_1, x_2, \dots, x_T as a Markov chain, denoted as the *forward process*:

$$q(x_t|x_{t-1}) = \mathcal{N}(\sqrt{1 - \beta_t}x_{t-1}, \beta_t\mathbf{I}), \quad (2)$$

where $\beta_t \in (0, 1)$ is the pre-defined scaling of noise variance at the t -th step. Given the above forward process as prior, DMs are trained to reverse it following the denoising process for recovering x_0 , where each step is parameterized as:

$$p(x_{t-1}|x_t) = \mathcal{N}(\mu_\theta(x_t, t), \Sigma_\theta(x_t, t)), \quad (3)$$

where $\mu_\theta(\cdot)$ and $\Sigma_\theta(\cdot)$ can be implemented by a U-Net (Ronneberger et al., 2015) or Transformer (Vaswani et al., 2017), and time step embeddings are adopted to represent t .

Discrete Diffusion Models. Discrete diffusion models (Austin et al., 2021; Gu et al., 2022) perform the forward and denoising processes in discrete random variables with K categories, where $K = |\mathcal{V}|$ for text data. For a sentence, x_0 is the vector consisting of the indexes of its contained tokens, and the forward process of adding noise is

$$q(x_t|x_{t-1}) = v^\top(x_t)\mathbf{Q}_t v(x_{t-1}), \quad (4)$$

where $v(x_t)$ maps each token index from x_t into K -dimension one-hot vector, \mathbf{Q}_t is the probability transition matrix and $[\mathbf{Q}_t]_{i,j}$ denotes the probability of the token i to be replaced by the token j . In this way, according to Bayes' theorem, the denoising process $q(x_{t-1}|x_t, x_0)$ can be deduced as:

$$q(x_{t-1}|x_t, x_0) = \frac{(v^\top(x_t)\mathbf{Q}_t v(x_{t-1}))(v^\top(x_{t-1})\bar{\mathbf{Q}}_{t-1} v(x_0))}{v^\top(x_t)\bar{\mathbf{Q}}_t v(x_0)} \quad (5)$$

where $\bar{\mathbf{Q}}_t = \mathbf{Q}_1\mathbf{Q}_2 \dots \mathbf{Q}_t$. Based on the above prior, we can use a parameterized model $p_\theta(x_{t-1}|x_t, t)$ to learn the denoising process.

4 Approach

In this section, we introduce Diffusion-NAT, an effective approach to integrating the discrete diffusion model and the Seq2Seq PLM BART, for improving NAR text-to-text generation. The overview of our approach is shown in Figure 1.

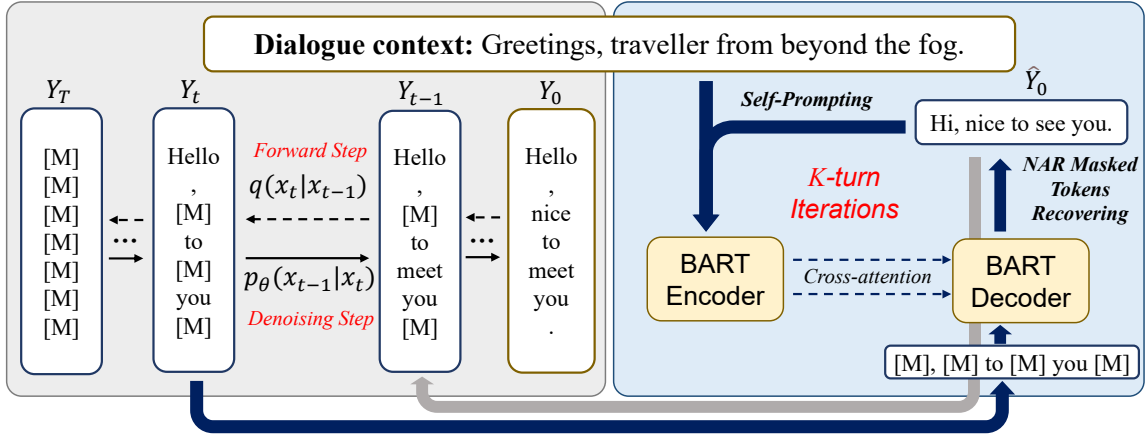


Figure 1: The overview of our Diffusion-NAT. We show an example that generates a response in the t -th step using K -turn self-prompting. The given dialog context and the K -turn prompt (*i.e.*, estimated \hat{Y}_0) are fed into BART encoder, and the response in the t -th Y_t is fed into BART decoder for estimating the original tokens.

262 4.1 Overview

263 Since discrete diffusion models (DDM) and BART
 264 adopt different ways for training (*i.e.*, noise pre-
 265 diction and masked text infilling respectively), it
 266 is hard to directly integrate both for NAR text-
 267 to-text generation. Our solution is to regard the
 268 mask token [MASK] of BART as the *noise* in DDM,
 269 and incorporate an absorbing state [MASK] into the
 270 Markov transition matrices. In this way, the for-
 271 ward process of DDM gradually replaces all the
 272 tokens by [MASK], and the denoising process can
 273 be reformulated as a *NAR Masked Tokens Recover-*
 274 *ing (NMTR)* task:

$$275 f_{\text{NMTR}}([M], \dots, [M]) = \{y_1, \dots, y_n\}, \quad (6)$$

276 where [M] denotes the [MASK] token of BART. To
 277 apply this framework for NAR text generation, we
 278 further make adaptations for BART and DDM. For
 279 BART, its pre-training task of masked text infilling
 280 is similar to the above objective except that it is in
 281 a NAR manner, and thus we revise the decoding
 282 process of BART to support the NAR inference
 283 in Section 4.2. For DDM, we learn to predict the
 284 original tokens instead of noise and remove the
 285 time step embeddings in Section 4.3, for better
 286 adaptation to BART. In this way, we can unify
 287 the inference process of BART and the denoising
 288 process of discrete diffusion models with the same
 289 formulation of *NAR masked tokens recovering*.

290 With this unified formulation, DDM can fully
 291 rely on BART to conduct the denoising process,
 292 with no need for additional parameters or specific
 293 training. In this way, the generated results based
 294 on BART can be iteratively refined via the denois-

295 ing process, leading to improved generation text.
 296 Since BART is employed as the backbone of our
 297 approach, we can naturally leverage advanced tech-
 298 niques of PLMs to improve the diffusion process,
 299 *e.g.*, prompt learning (Liu et al., 2021b). Thus,
 300 we propose the iterative self-prompting strategy to
 301 perform multi-turn deliberation and refinement on
 302 the intermediate generated results in Section 4.4,
 303 further enhancing the quality of the output.

304 4.2 Adapting BART for NAR Generation

305 Since BART utilizes a token-by-token autoregres-
 306 sive mechanism for decoding, this part discusses
 307 how to revise its decoding process to fit the NAR
 308 generation framework.

309 **BART.** BART (Lewis et al., 2020) is a Seq2Seq
 310 PLM that has been widely used on various text-to-
 311 text generation tasks. It adopts the encoder-decoder
 312 Transformer architecture. Given the input text C ,
 313 the encoder produces its representation vectors \mathbf{E} ,
 314 and the decoder performs cross-attention with \mathbf{E}
 315 to inject the condition from the input text. Dur-
 316 ing pre-training, the masked text infilling task is
 317 mainly adopted to learn the model parameters on a
 318 large-scale corpus, aiming to recover the masked
 319 span from the input text. During inference, using a
 320 special start token as the initial input of the decoder,
 321 the output text will be generated token by token.

322 **Revised NAR Decoding Process.** In the denois-
 323 ing process of our approach, BART is employed to
 324 recover the masked tokens from the noised target
 325 text at each time step. Thus, we revise the decoding
 326 process of BART into the NAR manner that can

recover all masked tokens simultaneously. Concretely, at the t -step, given the condition text C and the noised target text Y_t containing [MASK] tokens, we feed them into the encoder and decoder of BART respectively, and simultaneously recover all the [MASK] tokens into the target tokens as:

$$\text{BART}(\{y_1^{(t)} \cdots [M]\}, C) = \{y_1^{(t-1)} \cdots y_n^{(t-1)}\}, \quad (7)$$

where $y_1^{(t)}$ is the token of the first position at the t -th step. In this way, the decoding process follows the unified formulation in Eq. 6. Thus, we can employ BART in the denoising process by leveraging its pre-learned knowledge and generation capacity.

4.3 Adapting DDM for NAR Generation

In this part, we discuss how to adapt the discrete diffusion model (DDM) to NAR masked tokens recovering for text generation.

Markov Transition Matrices with [MASK]. As introduced in Section 3, discrete diffusion models rely on the probability transition matrix \mathbf{Q}_t to perform the forward and denoising processes over the state space. To align DDM with the NAR decoding process of BART (Section 4.2), we incorporate the [MASK] token as the absorbing state of the Markov transition matrices. Concretely, at the t -th step of the forward process, if token i is not the [MASK] token, it has the probabilities of α_t and γ_t being unchanged and replaced by the [MASK] token respectively, leaving the probability of $\beta_t = 1 - \alpha_t - \gamma_t$ transiting to other tokens in \mathcal{V} as:

$$[\mathbf{Q}_t]_{i,j} = \begin{cases} \alpha_t, & \text{if } j = i, \\ \gamma_t, & \text{if } j = [\text{M}], \\ 1 - \alpha_t - \gamma_t, & \text{otherwise,} \end{cases} \quad (8)$$

where α_t and γ_t are determined by the pre-defined noise schedule, *e.g.*, cosine schedule (Nichol and Dhariwal, 2021). While, if token i is the [MASK] token, it will be unchanged. Based on such a forward process, all tokens in the output text would become [MASK] after a sufficient number of steps, corresponding to the all-[MASK] input in Eq. 6. In the denoising process, we adopt BART to gradually recover the all-[MASK] sequence into output text in the NAR manner, where each denoising step is equivalent to the decoding of BART in Section 4.2.

Training with NAR Masked Tokens Recovering. During training, existing diffusion models mostly learn to predict the noise in the current time step.

However, such training objective is not consistent with PLMs. Inspired by existing works (Li et al., 2022b; Gong et al., 2022), we predict all the original tokens $Y_0 = \{y_1^{(0)}, \dots, y_n^{(0)}\}$ using BART in the NAR manner at each time step as:

$$\text{BART}(\{y_1^{(t)} \cdots [M]\}, C) = \{y_1^{(0)} \cdots y_n^{(0)}\}. \quad (9)$$

As Y_t usually contains several [MASK] tokens, the above process can be regarded as recovering all the masked tokens into the original ones, which is actually similar to the pre-training objective of BART. In this way, the training objective is formulated as:

$$\mathcal{L}_Y = - \sum_{i=1}^n \log p_{\theta}(y_i^{(0)} | Y_t, C) \quad (10)$$

where Y_t denotes the intermediate recovered text in the t -th step. During inference, given Y_t , our model first estimates \hat{Y}_0 , and then adds the $(t - 1)$ -step noise into it for producing Y_{t-1} . The above process will iterate for multiple steps, until the final results of Y_0 are obtained.

Removing Time Step Embeddings. As another difference in architecture, diffusion models typically incorporate time step embeddings to represent the time information (Ho et al., 2020; Song et al., 2021a), while BART has never set up corresponding time step embeddings. To reduce such discrepancy, we directly remove the time step embeddings from our diffusion process, so as to adapt DDM to reusing the whole architecture and all pre-trained parameters of BART. Actually, as the discrete diffusion process is to progressively recover the all-[MASK] sequence, the PLM can directly acquire the time information by counting the number of [MASK] tokens. Further, by removing the time step embeddings, our diffusion approach can better integrate with other improvement techniques, *e.g.*, DDIM method (Song et al., 2021a) with the non-Markov process for fast inference.

4.4 Iterative Self-Prompting

In a typical denoising process, the denoising network relies on the condition C and Y_t to estimate \hat{Y}_0 . However, at early steps, [MASK] tokens generally occupy the majority of Y_t , causing the estimation to be more difficult. To reduce the inference difficulty at an early stage, we propose the iterative self-prompting strategy that endows our model with deliberation capacity via prefixed prompts.

Training with Self-Prompting. Inspired by the self-conditioning strategy (Chen et al., 2022), our self-prompting strategy focuses on improving the quality of \hat{Y}_0 through multi-round checking and revision. Concretely, given Y_t and C , we first utilize the PLM to produce the estimated \hat{Y}_0 . Then, as \hat{Y}_0 and C are two sequences of tokens, we regard \hat{Y}_0 as the prompt of the PLM and prefix it with C to compose the new input condition $C' = [\hat{Y}_0; C]$. Next, the new condition C' and Y_t are further fed into the encoder and decoder of the PLM respectively, where cross-attention in the decoder is employed to generate \hat{Y}_0 by considering the previous estimation. During training, with a certain probability (e.g., 50%), we do not use the self-prompting strategy and only optimize the model parameter using Eq. 10. When integrated with this strategy, we first produce \hat{Y}_0 and then construct C' for self-prompting, where the training objective becomes:

$$\mathcal{L}_Y = - \sum_{i=1}^n \log p_{\theta}(y_i^{(0)} | Y_t, \hat{Y}_0, C). \quad (11)$$

Inference with Iterative Self-Prompting. To obtain a well-estimated \hat{Y}_0 , we repeat the following self-prompting process for K times: we first estimate the original tokens $\hat{Y}_0 = \{\hat{y}_1^{(0)}, \dots, \hat{y}_n^{(0)}\}$ based on the constructed new condition C' and then utilize it to replace the original prompt within C' . Each iterative process can be denoted as:

$$\text{BART}(\{y_1^{(t)} \dots y_n^{(t)}\}, \{\hat{y}_1^{(0)} \dots \hat{y}_n^{(0)}\}, C) = \{y_1^{(0)} \dots y_n^{(0)}\}. \quad (12)$$

In this way, by setting proper hyper-parameter K , we can balance the accuracy of the estimated \hat{Y}_0 and the time cost during inference. Note that such a manner also supports the explicit control in the intermediate prompts for guiding the generation, e.g., correcting grammar errors in \hat{Y}_0 . We leave it as our future work.

5 Experiments

5.1 Experimental Settings

More details about the datasets, evaluation metrics, baselines, and implementations are shown in Appendix A, B, C and D, respectively.

5.2 Experimental Results

Dialog Generation. As shown in Table 2, for the coherence metrics (i.e., BLEU-1/2), the performance order of aforementioned baselines in the two dialog generation datasets is mostly consistently as:

AR models > Semi-NAR models > NAR models. It indicates that AR models are more capable of generating coherent and fluent responses than NAR ones. A major reason is that AR models can better capture the dependency of tokens. Whereas, for the diversity metrics, AR models mostly underperform NAR models. The reason may be that AR models are easy to overfit into the frequently co-occurring tokens (e.g., I am OK.) in the training data, causing the “safe response” problem. Besides, the NAR methods using pre-training techniques (i.e., BANG and ELMER) can better balance the coherence and diversity metrics, and greatly outperform other NAR models. It demonstrates the effectiveness of large-scale pre-training in improving the NAR generation performance.

Finally, Diffusion-NAT mostly outperforms Semi-NAR and NAR models on all metrics. Different from these baselines, our approach is based on the discrete diffusion model that can iteratively refine the generated results using a PLM BART. As we have adapted them to better fit with each other by a set of revisions, we can combine the merits of the rich knowledge from BART and the iterative refining mechanism of the diffusion model. In this way, we can improve both the coherence and diversity of the generated responses. Furthermore, our approach outperforms AR models in the average value of all metrics, e.g., Ours (27.90) VS. BART (23.54) in PersonaChat. The reason is that our approach achieves much higher values in the Distinct-1,2 metrics. It shows the effectiveness of our approach for generating diverse responses.

Text Summarization and Question Generation.

As shown in Table 3 and Table 4, AR models outperform NAR models in a large margin. The reason is that the two types of tasks mainly require the model to accurately generate proper texts, which is more suitable for AR models due to their superiority in capturing the token dependency. Despite this, our approach mostly outperforms all the NAR and Semi-NAR methods, and even surpasses AR models on part of datasets (e.g., MSNews). It is because our approach can effectively combine the merits of the PLM that has pre-learned rich semantic knowledge and the diffusion models that can iteratively refine the produced results, leading to higher-quality generated texts.

Conversational Question Answering. The conversational question answering task is to evaluate

Type	Models	PersonaChat					DailyDialog				
		B-1↑	B-2↑	D-1↑	D-2↑	Overall↑	B-1↑	B-2↑	D-1↑	D-2↑	Overall↑
AR	Transformer	41.56	32.95	0.30	0.80	18.90	45.95	40.60	0.91	4.68	23.04
	MASS	41.06	35.75	1.40	6.90	21.28	51.77	45.09	3.99	23.38	31.06
	ProphetNet	46.00	38.40	1.30	7.30	23.25	-	-	-	-	-
	BART	47.60	39.36	1.10	6.10	23.54	56.18	49.59	5.04	27.72	34.63
Semi-NAR	InsT	12.63	9.43	0.10	0.30	5.62	-	-	-	-	-
	iNAT	41.17	32.13	0.10	1.10	18.63	-	-	-	-	-
	LevT	24.89	18.94	0.10	0.60	11.13	-	-	-	-	-
	CMLM	<u>44.38</u>	<u>35.18</u>	0.10	0.80	20.12	-	-	-	-	-
	BANG	39.82	30.72	1.90	14.20	<u>21.66</u>	41.47	35.71	1.76	13.98	23.23
NAR	NAT	31.53	24.17	0.10	0.80	14.15	-	-	-	-	-
	iNAT	30.56	23.38	0.10	0.70	13.69	-	-	-	-	-
	CMLM	31.44	24.06	0.10	0.60	14.05	-	-	-	-	-
	LevT	26.92	20.47	0.00	0.40	11.95	-	-	-	-	-
	BANG	31.11	23.90	2.50	22.70	20.05	35.50	30.15	1.90	15.13	20.67
	ELMER	31.45	23.99	3.66	<u>24.96</u>	21.02	68.32	61.14	5.30	35.64	42.60
Diffusion	Ours	44.55	37.66	<u>3.19</u>	26.20	27.90	68.79	62.68	6.67	39.97	44.53

Table 2: The comparison between our approach and baselines on two dialog generation tasks. B-1/2 and D-1/2 denote BLEU-1/2 and Distinct-1/2. **Bold** and underline fonts denote the best and second best methods within NAR and Semi-NAR models, respectively. The baseline results on PersonaChat are collected from (Li et al., 2022a).

both the generative capacity and the world knowledge of the model. As shown in Table 4, our approach also performs well in this task, even slightly outperforming the AR model BART by 0.8 on F1 metric. A possible reason is that our approach can make use of the pre-learned world knowledge from BART. Besides, as our model can also leverage the iterative refining paradigm of the diffusion model, it may also fix the wrong answers in the generated text, leading to more accurate answers.

Human Evaluation. In addition to the automatic metrics, human evaluation is also critical for text generation. Considering the expensive annotation cost, we only focus on the dialog generation task and compare our approach with two best-performing baselines, *i.e.*, BART and ELMER. Following existing works (Li et al., 2022a), we randomly select 500 examples from the test set of the PersonaChat dataset, and invite three annotators to evaluate the quality of the generated responses from the two baselines and ours from the perspectives of Fluency, Informativeness and Relevance. The scoring range is from 1 to 5. As shown in Table 5, we can see that the AR method BART performs better on the Fluency and Relevance metrics while the NAR method ELMER performs well on informativeness. Such results show a similar tendency as the automatic metrics, and indicate the different superiority of AR and NAR models. As a comparison, our approach can well balance the

three metrics, with the comparable performance on Fluency as BART and the best performance on Informativeness. It shows the great potentiality of discrete diffusion models with PLMs in NAR text-to-text generation tasks.

Inference Latency. By using DDIM (Song et al., 2021a) or other acceleration strategies, we can also reduce the inference latency of our approach. To verify it, we test the inference latency and performance of our approach using different diffusion steps by using DDIM, and compare them with two best-performing NAR and AR baselines (*i.e.*, ELMER and BART) on PersonaChat dataset. The above experiments are conducted on a NVIDIA 3090-24G GPU with a batch size of 1. As shown in Table 10, we can see that our approach can provide a way to trade off the time cost and the generation quality during inference. By setting proper diffusion steps (100 and 2), our approach can outperform BART and ELMER on average with similar inference latency, respectively.

6 Conclusion

In this paper, we proposed Diffusion-NAT, a self-prompting discrete diffusion model (DDM) using a PLM BART for non-autoregressive (NAR) text generation. In our approach, we unified the inference process of BART and the denoising process of DDM into the same masked tokens recovering task, to combine the merits of both the rich pre-

Type	Models	XSUM			SQuAD v1.1		
		ROUGE-1↑	ROUGE-2↑	ROUGE-L↑	ROUGE-L↑	BLEU-4↑	METEOR↑
AR	Transformer	30.66	10.80	24.48	29.43	4.61	9.86
	MASS	39.70	17.24	31.91	49.48	20.16	24.41
	ProphetNet	39.89	17.12	32.07	48.00	19.58	23.94
	BART	38.79	16.16	30.61	42.55	17.08	23.19
Semi-NAR	InsT	17.65	5.18	16.05	29.98	2.34	8.15
	iNAT	26.95	6.88	22.43	32.34	3.16	9.18
	LevT	25.33	7.40	21.48	30.81	2.68	9.40
	CMLM	29.12	7.70	23.04	29.60	3.89	9.70
	BANG	34.71	11.71	29.16	47.39	17.62	<u>21.69</u>
NAR	NAT	24.04	3.88	20.32	31.51	2.46	8.86
	iNAT	24.02	3.99	20.36	32.44	2.33	8.84
	CMLM	23.82	3.60	20.15	31.58	2.51	8.85
	LevT	24.75	4.18	20.87	31.38	2.27	9.14
	BANG	32.59	8.98	27.41	44.07	12.75	18.99
	ELMER	<u>38.30</u>	<u>14.17</u>	<u>29.92</u>	40.22	13.49	20.08
Diffusion	GENIE	29.3	8.3	21.9	-	-	-
	AR-DIFFUSION	32.2	10.6	25.2	-	-	-
	Ours	38.84	15.30	30.88	<u>46.64</u>	<u>16.19</u>	21.99

Table 3: The comparison between different methods on XSUM and SQuAD v1.1 datasets. **Bold** and underline fonts denote the best and second best methods within NAR and Semi-NAR models, respectively. The baseline results are collected from (Qi et al., 2021) and (Li et al., 2022a).

Models	MSNews			MSQG			CoQA
	ROUGE-1↑	ROUGE-2↑	ROUGE-L↑	ROUGE-L↑	BLEU-4↑	METEOR↑	F1↑
LSTM	30.0	14.6	27.7	25.3	3.5	14.1	15.1
Transformer	33.0	15.4	30.0	29.3	5.1	16.6	15.7
BART	41.8	23.1	38.3	38.1	10.2	22.1	64.6
BANG	32.7	<u>16.1</u>	30.3	<u>33.1</u>	11.0	18.4	31.4
ELMER	<u>35.6</u>	<u>16.1</u>	<u>32.5</u>	26.6	5.00	15.7	<u>63.1</u>
Ours	46.8	31.6	44.2	33.3	<u>6.6</u>	19.3	65.4

Table 4: The comparison between different methods on MSNews, MSQG and CoQA datasets. **Bold** and underline fonts denote the best and second best methods within NAR models, respectively.

Models	PersonaChat		
	Fluency	Informativeness	Relevance
BART	4.32	4.31	3.47
ELMER	3.88	4.49	2.90
Ours	4.29	4.57	3.19

Table 5: Human evaluation scores of different methods about the generated responses on PersonaChat.

	ELMER	Diffusion-NAT			BART
Steps	-	2	20	100	-
Latency	13.8ms	19.1ms	76.4ms	267.5ms	253.6ms
BLEU-2	23.99	30.82	36.19	37.66	39.36
Dist-2	24.96	23.68	26.93	26.20	6.10

Table 6: Performance and inference latency changes of two baselines and our approach w.r.t. the diffusion steps using DDIM during inference on PersonaChat dataset.

570 learned knowledge of BART and the iterative refin-
571 ing paradigm of DDM. Concretely, we revised the
572 decoding process of BART into the NAR manner,
573 and adapted the typical settings of DDM to better
574 fit with BART, including Markov transition ma-
575 trix, training objective and time step embeddings.
576 Besides, we devised an iterative self-prompting
577 strategy to guide the PLM to deliberate and refine
578 the intermediate generated results, to further im-

579 prove the quality of final produced texts. Extensive
580 experiments on seven datasets have shown that our
581 approach can outperform competitive NAR and
582 Semi-NAR models, and even surpass AR models.

583 In future work, we will investigate more effective
584 and efficient way to combine LLMs and DDM for
585 NAR text generation, *e.g.*, prompt learning.

586 Limitations

587 This work is to investigate discrete diffusion mod-
588 els with pre-trained language models for non-
589 autoregressive text-to-text generation. An impor-
590 tant limitation is the relatively higher inference
591 latency of diffusion models. In this work, we have
592 adopted DDIM to accelerate the inference process
593 by reducing the diffusion steps, and we also con-
594 duct experiments to investigate the performance
595 changes w.r.t. different steps in Appendix H. We
596 can see that fewer steps using DDIM would lead to
597 the performance degradation. Fortunately, there are
598 several recent works that have shown effectiveness
599 in solving this problem (Lu et al., 2022). As these
600 methods are general to all diffusion models, they
601 may be able to be utilized in our approach. Besides,
602 as we have adopted a PLM, BART in our approach,
603 it may present biases learned from the pre-training
604 corpus in the generated texts.

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Task	Datasets	#Train	#Valid	#Test
Dialog	DailyDialog	76,052	7,069	6,740
	PersonaChat	122,499	14,602	14,056
Sum.	XSUM	204,045	11,332	11,334
	MSNews	136,082	7,496	7,562
QG	MSQG	198,058	11,008	11,022
	SQUAD v1.1	75,722	10,570	11,877
CQA	CoQA	108,647	3,935	4,048

Table 7: Statistics of the datasets, where **Dialog**, **Sum.**, **QG** and **CQA** denote Dialog Generation, Text Summarization, Question Generation and Conversational Question Answering, respectively.

A Details of Datasets 945

We conduct experiments on seven datasets, corresponding to four representative text generation tasks. The statistics of these datasets are shown in table 7. 946 947 948 949

- **Dialog Generation** aims to predict responses according to the dialog history. We select **DailyDialog** (Li et al., 2017) and **PersonaChat** (Zhang et al., 2018) datasets. 950 951 952 953
- **Text Summarization** is to summarize the document into a sentence. We choose **XSUM** (Narayan et al., 2018) and **MSNews** (Liu et al., 2021a), two news summarization datasets. 954 955 956 957
- **Question Generation** aims to generate questions based on given passages and answers. We use **MSQG** (Liu et al., 2021a) and **SQUAD v1.1** (Rajpurkar et al., 2016) datasets. 958 959 960 961
- **Conversational Question Answering** is to answer the question based on a conversation. We select **CoQA** (Reddy et al., 2019) dataset. 962 963 964

B Details of Evaluation Metrics. 965

Following existing works (Li et al., 2022a; Qi et al., 2021), we employ corresponding metrics to evaluate model performances on different tasks. 966 967 968

- For dialog generation, we adopt BLEU-1/2 (Papineni et al., 2002) to measure the coherence between the generated and real responses based on the co-occurrence ratio of n -grams, and Distinct-1/2 (Li et al., 2016) to measure the n -gram diversity of the generated texts. 969 970 971 972 973 974 975
- For text summarization, we utilize ROUGE-1/2/L (Lin, 2004) to compute the overlapping ratio of n -grams between the generated and 976 977 978

ground-truth summarizations for estimating the quality.

- For question generation, we use ROUGE-L, BLEU-4 and METEOR (Banerjee and Lavie, 2005) to assess the generation consistency.
- For conversational question answering, we adopt F1-Score (Rajpurkar et al., 2016) to measure the prediction accuracy.

C Details of Baselines

We mainly compare our Diffusion-NAT with a variety of Semi-NAR and NAR models. **NAT** (Gu et al., 2018), **iNAT** (Lee et al., 2018), **InsT** (Stern et al., 2019), **CMLM** (Ghazvininejad et al., 2019) and **LevT** (Gu et al., 2019) are five Transformer-based NAR models with special generation strategies, *i.e.*, iterative refinement, conditional masked language modeling and insertion-deletion operation. **BANG** (Qi et al., 2021) and **ELMER** (Li et al., 2022a) adopt the pre-training technique based on Transformer to further improve the NAR generation performance. Note that InsT, iNAT, LevT, CMLM and BANG also support the semi-NAR manner that can rely on partially generated results for improving the inference. We also compare our approach with two recently proposed diffusion-based methods, *i.e.*, **GENIE** (Lin et al., 2022) and **AR-DIFFUSION** (Wu et al., 2023), which incorporate the pre-training strategy and auto-regressive decoding to improve the generation performance of continuous diffusion models.

We also compare our approach with AR models which have shown better accuracy than NAR ones. **LSTM** (Hochreiter and Schmidhuber, 1997) and **Transformer** (Vaswani et al., 2017) are two classic Seq2Seq models. **MASS** (Song et al., 2019), **BART** (Lewis et al., 2020) and **ProphetNet** (Qi et al., 2020) are PLMs specially for text generation and we use their base version for fair comparison.

D Implementation Details

For all baselines, we use the source code provided by their authors, and all hyper-parameters are set following the suggestions from the original paper. For our Diffusion-NAT, we use the checkpoint of BART-base with 110M parameters for initialization, and do not add any other parameters. We use the linear noise schedule (Ho et al., 2020) for the diffusion process. During training, the diffusion step is set to 1000. During inference, we utilize

Models	PersonaChat			
	B-1	B-2	D-1	D-2
ELMER	31.11	23.99	3.66	24.96
Ours	44.55	37.66	3.19	26.20
-w/o self-prompting	43.93	37.19	2.62	22.22
-w/o PLM	41.39	35.33	1.74	17.31
+Time step Embedding	40.03	33.80	1.75	16.80
BART=>RoBERTa	38.07	32.17	2.99	18.32

Table 8: Ablation study on PersonaChat dataset.

Models	PersonaChat		XSUM			SQuAD	
	B-1	B-2	R-L	R-L	MT		
DiffuSeq	37.79	32.50	20.29	29.29	12.57		
Ours	44.55	37.66	30.88	46.64	21.99		

Table 9: Performance comparison of continuous diffusion method DiffuSeq (Gong et al., 2022) and our approach on PersonaChat, XSUM and SQuAD datasets.

DDIM (Song et al., 2021a) for fast sampling and reduce the diffusion step into 100. The number of self-prompting turns is set to 2. We use AdamW as the optimizer, and set learning rate to 5e-5. We set the training step for XSUM and SQuAD v1.1 to 120k, and 80k for other datasets. The batch size is set to 512. All experiments are conducted on 8 NVIDIA Tesla V100 GPUs. The training process of each task requires less than 24 hours.

E Ablation and Variation Study

Our Diffusion-NAT includes several key designs, *i.e.*, the usage of BART, self-prompting strategy, removing time step embeddings. Here, we conduct the ablation and variation study on our approach to verify their effectiveness. Concretely, we propose four variations of our approach as shown in Table 8, where **-w/o self-prompting** and **-w/o PLM** refer to the variations removing the corresponding component, **+Time step Embeddings** and **BART=>RoBERTa** are the variations that add the time step embeddings as continuous diffusion methods (Li et al., 2021) and replaces BART by RoBERTa in our approach, respectively. We can see that all the variations underperform our approach, it demonstrates the effectiveness of the above designs. Among them, we can see that adding time step embeddings cause the performance degrading a lot. The reason is that the additional embeddings may disturb the original semantic representations of BART.

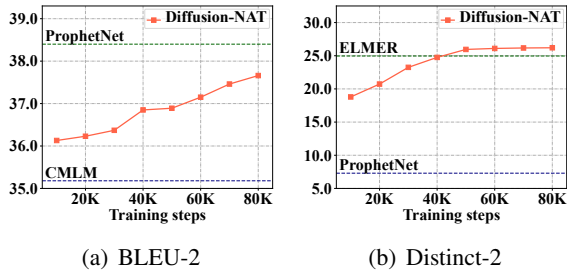


Figure 2: Performance changes of our approach w.r.t. the training steps on PersonaChat dataset.

F Discrete Diffusion V.S. Continuous Diffusion

For the NAR text-to-text generation, existing works (Gong et al., 2022) also have incorporated the continuous diffusion method. In this part, we aim to compare our approach with a recently proposed work, DiffuSeq (Gong et al., 2022) that performs continuous diffusion on the latent space of token embeddings and leverages the KNN rounding step to map the embeddings into discrete tokens. We conduct the experiments on PersonaChat, XSUM and SQuAD datasets. As shown in Table 9, we can see that our approach outperforms DiffuSeq in all metrics by a large margin. It shows the effectiveness of our proposed method that utilizes the discrete diffusion method in NAR text-to-text generation tasks. Besides, compared with DiffuSeq, our approach can also benefit from the PLM BART, which also helps generate higher-quality texts.

G Performance w.r.t. Training Steps

As our approach adopts the pre-trained BART for parameters initialization, it is also helpful to faster and better convergence. To verify it, we report the BLEU-2 and Distinct-2 performance changes of our approach w.r.t. the training steps during training. As show in Figure 2, we observe that with the increasing of training steps, the performance of our approach is consistently improving, gradually approaching or surpassing competitive models. It shows the stabilization of our convergence process. Besides, for BLEU-2, with just 10k training steps, our approach can outperform competitive Semi-NAR model CMLM. The reason may be that BART provides a good starting point of the training process, making our approach converge faster.

PersonaChat						
Diff. Steps	2	10	20	100	200	1000
BLEU-2	30.82	35.88	36.19	37.66	37.63	37.65
Distinct-2	23.68	27.54	26.93	26.20	26.35	26.39

Table 10: Performance changes w.r.t. the diffusion steps (abbreviated as Diff. Steps) on PersonaChat dataset.

PersonaChat						
SP Turns	0	1	2	3	4	5
BLEU-2	35.00	36.50	37.66	37.69	37.77	37.77
Distinct-2	26.01	26.22	26.20	26.34	26.29	26.30

Table 11: Performance changes w.r.t. the self-prompting turns (abbreviated as SP Turns) on PersonaChat dataset.

H Hyper-parameter Tuning.

Our approach also requires some parameters to tune, *i.e.*, the diffusion steps during decoding and the turns of self-prompting. Generally, more diffusion steps and self-prompting turns would lead to better performance but larger inference latency, hence we can tune their values to balance the inference time cost and quality. In this part, we conduct experiments on the PersonaChat dataset to validate it. As shown in Table 10 and Table 11, we can see that more diffusion steps and more self-prompting turns are able to improve the model performance, while the improvement seems to be saturated after a certain number, *i.e.*, 100 for diffusion steps and 2 for self-prompting turns. Such results can provide a reference for tuning the two hyper-parameters to match the requirement of model performance and inference latency. Besides, we can see that with very few diffusion steps (*e.g.*, 2 steps), our approach can also achieve a decent performance on BLEU-2 and Distinct-2. It demonstrates the potentiality of further reducing the inference latency in our approach.

I Case Study

To provide the qualitative analysis on our approach, we show two generated examples on the PersonaChat dataset in Table 12. We can see that with the help of BART and the diffusion model, our approach can generate relevant and informative responses based on the given dialog context. Besides, the left example shows that our approach is able to generate interesting phrases such as “as healthy as american lifestyle”, which makes the response

Personal Profile	i enjoy cross stitch and quilting. my father served in our military in the war. i am proud to be an american. i am what people call a baby boomer. my parents were proud immigrants to america.	my father was a police officer. my favorite band is nirvana. i like running. i work at pet smart. i am a musician.
Context	hello, how is your day going hi. my day is good. i am hanging out with both of my sons. cool, sounds like fun. just as much fun as cross stitch and quilts i love those crafts! right now i am into my aquarium filled with exotic fish. i am what you would call a baby boomer, explains the quilting passion you might like my collection of decorations. they are 50s vintage! sure, it would bring back old memories. especially when my dad served in the military that is awesome. what do you eat for breakfast? mine is granola every day. oatmeal fan over here. my parents were immigrants, they raised me on oats everyday. that is very healthy. i like it. do you eat fish?	hey. want to chat? i am just listening to my favorite music, nirvana. i was just reading a biography. i love those. i work too much overtime at pet smart to read. what do you do? i just got out of college.
Real Response	yes i do eat fish. i love it	what did you study. i work at pet smart but really like music.
Ours	fish is almost as healthy as american lifestyle, love fish too	i am a musician. and i play music all the time.

Table 12: Examples of generated responses on PersonaChat by our approach.

more humorous and also well reflects the speaker's personal characteristics.

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