
AliO: Output Alignment Matters in Long-Term Time Series Forecasting

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Abstract

Long-term Time Series Forecasting (LTSF) tasks, which leverage the current data sequence as input to predict the future sequence, have become increasingly crucial in real-world applications such as weather forecasting and planning of electricity consumption. However, state-of-the-art LTSF models often fail to achieve prediction output alignment for the same timestamps across lagged input sequences. Instead, these models exhibit low output alignment, resulting in fluctuation in prediction outputs for the same timestamps, undermining the model’s reliability. To address this, we propose AliO (Align Outputs), a novel approach designed to improve the output alignment of LTSF models by reducing the discrepancies between prediction outputs for the same timestamps in both the time and frequency domains. To measure output alignment, we introduce a new metric, TAM (Time Alignment Metric), which quantifies the alignment between prediction outputs, whereas existing metrics such as MSE only capture the distance between prediction outputs and ground truths. Experimental results show that AliO effectively improves the output alignment, i.e., up to 58.2% in TAM, while maintaining or enhancing the forecasting performance (up to 27.5%). This improved output alignment increases the reliability of the LTSF models, making them more applicable in real-world scenarios. The code implementation is on the GitHub repository³.

1 Introduction

The task of long-term time series forecasting (LTSF) is essential in various fields such as prediction of electricity demand [13], weather forecasting [37], health data [20], and so on. Recently, deep neural network models [40, 30, 33, 43] have shown strong performance in predicting long-term time series

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³<https://github.com/eai-lab/AliO>

based on historical information, which typically aim to minimize the error between the prediction output and the ground-truth sequence as a regression task. However, in real-world applications, merely minimizing the prediction error in LTSF is insufficient. It is equally important to ensure that the forecasting model generates consistent (aligned) prediction outputs for overlapping timestamps across lagged input sequences. For example, Fig. 1 illustrates a scenario in which a trained forecasting model predicts future electricity usage in two instances: (1) for the period from April to November (Prediction 1, purple), using input data from January to March, and (2) for the period from May to December (Prediction 2, yellow), using input data from February to April, where the forecasting periods overlap between May and November. A reliable model should provide consistent predictions for these overlapping months, regardless of the partially differing input sequences. If the model produces inconsistent predictions on the electricity usage for the same timestamps (i.e., May to November) between two input sequences, it could result in significant time and financial costs for rescheduling budget allocation and undermine the reliability of the predictions.

We refer to this phenomenon as the *output alignment* problem, which has not been adequately acknowledged and addressed by existing LTSF studies [25, 7, 18], despite its significance and substantial impact on real-world applications. To the best of our knowledge, state-of-the-art LTSF models [37, 33, 30] often fail to maintain the prediction output consistency, and none of existing works has explicitly recognized or attempted to address this inconsistency in LTSF tasks.

In this paper, we present *AliO (Align Outputs)*, a novel method designed to enhance output alignment in LTSF models. For the first time, AliO enables LTSF models to produce consistent predictions for overlapping timestamps across lagged input sequences. By aligning predictions for overlapping timestamps through the minimization of discrepancies in both time and frequency domains, AliO improves output consistency even when input sequences lagged. AliO achieves this by directing the model’s predictions toward the ground-truth sequences while simultaneously minimizing discrepancies across multiple predictions obtained from a set of lagged input sequences. It allows AliO to integrate seamlessly with the model’s forecasting objectives, such as regression loss (e.g., MSE), without adding implementation complexity or requiring modifications to the model. As a result, AliO enhances the reliability of forecasts by improving output alignment (consistency), while maintaining or even improving overall forecasting performance.

This represents a significant advancement over existing methods [37, 40] that focus solely on minimizing the forecasting objective without considering prediction output alignment.

To quantify output alignment, which represents the consistency of a model’s predictions across lagged input sequences, we propose a new metric, Time Alignment Metric (TAM). TAM quantitatively assesses the model’s output alignment by measuring discrepancies between predictions for overlapping timestamps for multiple input sequences. To the best of our knowledge, the proposed TAM is the first metric designed to measure the output alignment.

We experiment with AliO on representative LTSF tasks, including ETT{h1, h2, m1, m2}, Electricity (ECL), Traffic, Weather, and ILI dataset [37], using various state-of-the-art LTSF models such as CycleNet [27], GPT4S [43], iTransformer [30], PatchTST [33], TimesNet [36], DLinear [40] and Autoformer [37]. The evaluation results demonstrate that AliO effectively aligns predictions over overlapping timestamps, i.e., improving TAM up to 58.2%, while maintaining or enhancing

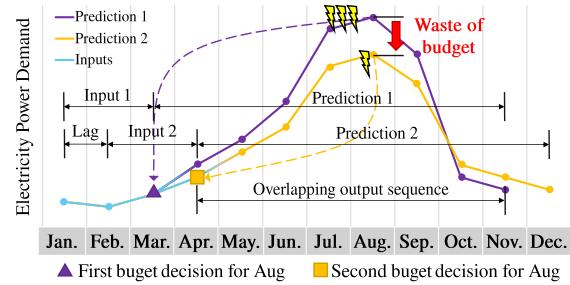


Figure 1: An example of low output alignment between two predictions on future electricity usages: (1) Prediction 1 (purple) forecast spanning from Apr to Nov and (2) Prediction 2 (yellow) forecast spanning from May to Dec. These two predictions are generated from two partially overlapping input sequences—(1) one from Jan to Mar (Input 1), and (2) the other from Feb to Apr (Input 2). The inconsistency between these two prediction outputs over the same timestamps (i.e., May to Nov) leads to differing budget allocation plannings for electricity power consumption in Aug, resulting in time and financial waste due to rescheduling resource allocation.

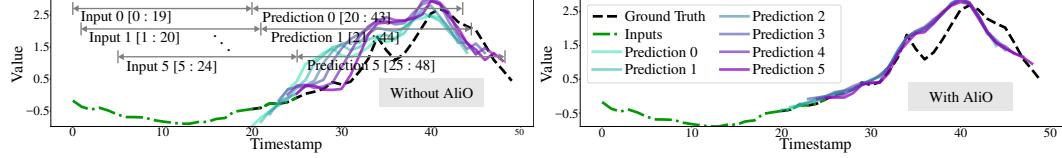


Figure 2: (**Left**) Six prediction outputs from the DLinear [40] model trained with regression loss (MSE) only, forecasting a length-24 sequence for ILI data [37], where six input sequences (green dotted line) are lagged one timestamp apart. (**Right**) Six predicted sequences from DLinear trained with AliO, under the same conditions. The predicted sequences exhibit improved output alignment, showing a closer match to the ground truth for all six predictions, which significantly reduces the prediction shifts observed when using regression loss alone.

forecasting regression accuracy up to 17.4% measured in MSE. The detailed descriptions on additional datasets and experimental configurations are provided in Secs. G to I.

2 Motivation

A system with low prediction consistency leads to user distrust and increased costs. For instance, studies on the consistency of weather forecasts have reported cases where consistent forecasts lead to greater trust in the system, whereas inconsistent forecasts result in user distrust [5, 31, 4]. Furthermore, according to research in non-weather domains, consumers tend to perceive consistency among multiple estimates from the same system as a signal of skill [11, 5, 3]. The inconsistency in predictions necessitates replanning, which consumes unnecessary organizational time. The resulting resource reallocation leads to the investment of more resources, contrary to the original goal of Rolling forecasting, which aims for resource savings [16, 14]. This can be described as an additional sunk cost [35], as frequent fluctuations in predictions can induce irrational decision-making and result in lost opportunity costs [35, 6].

While modern Long-Term Times Series Forecasting (LTSF) models demonstrate high accuracy, research on the aforementioned consistency has been insufficient. Consequently, we examined the consistency of existing models through rolling forecasting on representative LTSF datasets. The left panel of Fig. 2 shows the prediction results of DLinear [37] on the ILI dataset [37] using only regression loss (MSE), revealing a significant lack of consistency. In contrast, the right panel, where AliO is applied, shows that consistency is improved while accuracy is maintained. As can be seen in Sec. I, this is a phenomenon observed across other models and datasets.

Although both consistency and accuracy are crucial for addressing users' psychological and economic concerns, our experiments revealed that while modern LTSF models achieve high accuracy, they fall short in terms of consistency. AliO, as a loss function used in conjunction with regression loss, aims to achieve two goals: maintaining the high accuracy of existing LTSF models while improving their prediction consistency. Furthermore, to quantify consistency, we propose the Time Alignment Metric (TAM). Regression metrics such as MSE, MAE, and DTW [34] represent accuracy, which is the distance between predictions and ground truth. Therefore, they have limitations in measuring consistency, which is a measure of performance between predictions. Complementing this, TAM measures the distance between predictions, serving as an indicator that represents consistency.

Through Sec. 5 and Sec. I, we show that AliO successfully achieves the dual goals of maintaining/improving the high accuracy of existing models and enhancing consistency. Additionally, in ??, we experimentally verify the relationship between the inconsistency value (TAM) of existing models and the MSE improvement in models trained with AliO. To the best of our knowledge, this is the first study to address the improvement of consistency in LTSF.

3 Time alignment metric (TAM)

We first define the concept of output alignment and then introduce Time Alignment Metric (TAM), which enables a quantitative assessment of output alignment.

Definition 3.1. (Output Alignment) *Output alignment* refers to the property wherein the prediction outputs of a model, derived from a set of lagged input sequences, exhibit consistent alignment, characterized by uniform patterns across overlapping timestamps in the prediction outputs.

For instance, as illustrated in Fig. 2, the six prediction outputs for the overlapping timestamps (i.e., from 25 to 43) in the left figure demonstrate a lower degree of output alignment. Conversely, the six prediction outputs in the right figure exhibit similar and consistent patterns, demonstrating a high degree of output alignment. To quantify the output alignment (Theorem 3.1) in model predictions, we propose Time Alignment Metric (TAM). We begin by defining the necessary concepts, including lagged input and output sequences, and overlapping output sequences, as provided below.

Definition 3.2. (Input and Output Sequence) Given a time-series sequence $\mathbf{X} \in \mathbb{R}^{c \times d}$, where c is the input channel, and d is the length of the sequence, respectively, the n -th *input sequence* $\mathbf{X}^n \in \mathbb{R}^{c \times d'}$ of the length $d' \leq d$ is defined as the segment $\mathbf{X}_{s:s+d'-1}$, where s is the starting timestamp, and $s + d' - 1$ is the ending timestamp.

Then, taking $\mathbf{X}^n \in \mathbb{R}^{c \times d'}$ as input, $f(\mathbf{X}^n; \theta) = \mathbf{Y}^n \in \mathbb{R}^{c' \times h}$ is defined as the prediction *output sequence* of the length h provided by the forecasting model f , where c' is the output channel, and θ is the model parameter. Having the input sequence \mathbf{X}^n and the corresponding output sequence \mathbf{Y}^n of the model f , the lagged input and output sequences, \mathbf{X}^{n+1} and \mathbf{Y}^{n+1} , are derived by shifting their timestamps by the lag parameter l , as described below.

Definition 3.3. (Lagged Input and Output Sequence) Given the n -th input sequence $\mathbf{X}^n \in \mathbb{R}^{c \times d'}$ of the segment $\mathbf{X}_{s:s+d'-1}$, the sequence $\mathbf{X}^{n+1} \in \mathbb{R}^{c \times d'}$ of the segment $\mathbf{X}_{s+l:s+d'+l-1}$ is defined as the *lagged input sequence* of \mathbf{X}^n with l being the lag parameter.

Then, given the lagged input sequence $\mathbf{X}^{n+1} \in \mathbb{R}^{c \times d'}$, the prediction output of the length h , $f(\mathbf{X}^{n+1}; \theta) = \mathbf{Y}^{n+1} \in \mathbb{R}^{c' \times h}$, is defined as the model f 's *lagged output sequence*. From \mathbf{Y}^n and \mathbf{Y}^{n+1} , the overlapping output sequences \mathbf{P}^n and \mathbf{P}^{n+1} are derived to compute TAM, as follows.

Definition 3.4. (Overlapping Output Sequence) Given two output sequences $\mathbf{Y}^n \in \mathbb{R}^{c' \times h}$ and $\mathbf{Y}^{n+1} \in \mathbb{R}^{c' \times h}$ of the model f generated from \mathbf{X}^n and \mathbf{X}^{n+1} as input, respectively, $\mathbf{P}^n \in \mathbb{R}^{c' \times h'}$ and $\mathbf{P}^{n+1} \in \mathbb{R}^{c' \times h'}$ are defined as the *overlapping output sequences* between \mathbf{Y}^n and \mathbf{Y}^{n+1} , whose segments are given by $\mathbf{Y}_{1:l:h}^n$ and $\mathbf{Y}_{1:h-l}^{n+1}$, respectively, where $h' = h - l$ is the overlapping length.

From these, Time Alignment Metric (TAM) is defined to quantify output alignment by evaluating the consistency between overlapping output sequences \mathbf{P}^n and \mathbf{P}^{n+1} , as follows.

Definition 3.5. (TAM; Time Alignment Metric) Given N overlapping output sequences $\mathbf{P}^n \in \mathbb{R}^{c' \times h'}$ for $n = 1, 2, \dots, N$, where the input and output sequences, \mathbf{X}^{n+1} and \mathbf{Y}^{n+1} , are offset from \mathbf{X}^n and \mathbf{Y}^n by the lag l , TAM_N (*Time Alignment Metric*) is calculated as the average of the MAE values between all pairs of $\{\mathbf{P}^n, \mathbf{P}^m\}$, which is given by:

$$TAM_N \triangleq \frac{(N-1)N}{2} \sum_{n=1}^{N-1} \sum_{m=n+1}^N \frac{|\mathbf{P}^n - \mathbf{P}^m|_1}{h'} \quad (1)$$

TAM offers a distinct advantage over traditional forecasting regression metrics, such as the MSE or MAE between model outputs and ground truth, which only measure forecasting performance and fail to capture prediction fluctuations across different predictions. Unlike these metrics, TAM evaluates the distances between overlapping predictions, allowing for an assessment of how predictions evolve over time. For instance, regression metrics do not determine whether overlapping predictions remain consistent or exhibit smooth transitions, making it challenging to assess data-model robustness. In contrast, TAM computes the distance between overlapping predictions, providing a robust measure of data-model consistency. A lower TAM value reflects improved alignment and data-model robustness.

4 Improving output alignment (AliO)

To enhance the output alignment of LTSF models, we propose AliO (Align Outputs), which minimizes the discrepancy between overlapping predictions (Theorem 3.4). AliO is designed to simultaneously

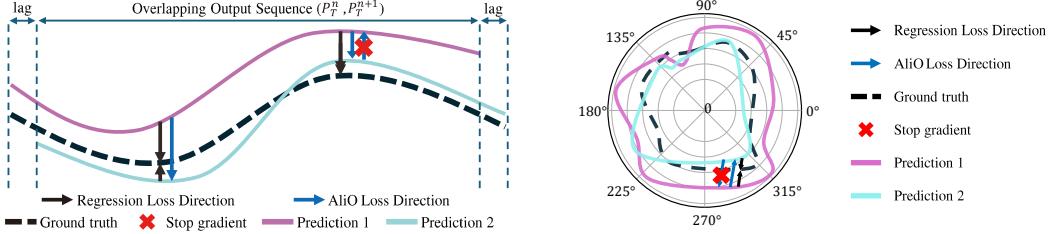


Figure 3: **Output alignments in both time and frequency domains.** (Left) In the time domain, AliO minimizes the difference between two predictions in the overlapping timestamps, i.e., \mathbf{P}_T^n and \mathbf{P}_T^{n+1} (T means time domain). To preserve the regression loss direction while improving the output alignment, the regression pulling (Sec. 4.2) is applied through the stop-gradient operation to each time point, ensuring that the overall loss is calculated in the direction towards the ground truth. (Right) In the frequency domain, AliO aligns both the phase and amplitude components of \mathbf{P}_F^n and \mathbf{P}_F^{n+1} (the transformed frequency domain of \mathbf{P}_T^n and \mathbf{P}_T^{n+1}), applied with the stop-gradient operation. The figure is represented in polar coordinates, where the angle indicates the phase, and the distance from the center point corresponds to the amplitude

achieve two key objectives: (1) improving output alignment by reducing discrepancies between the overlapping predictions, and (2) maintaining the model’s forecasting regression performance by aligning the model’s prediction outputs with the ground truths. The two objectives are achieved through the technique that we call regression pulling with the stop-gradient operation, which ensures that the forecasting regression loss remains unaffected while improving output alignment simultaneously.

Given two overlapping predictions, $\mathbf{P}^n = f(\mathbf{X}^n; \boldsymbol{\theta})_{1+l:h}$ and $\mathbf{P}^{n+1} = f(\mathbf{X}^{n+1}; \boldsymbol{\theta})_{1:h-l}$ defined in Theorem 3.4, AliO aligns these predictions such that $\mathbf{P}^n \simeq \mathbf{P}^{n+1}$ for $n = 1, 2, \dots, N$ by minimizing the following objective with respect to the model f ’s parameter $\boldsymbol{\theta}$, as:

$$\min_{\boldsymbol{\theta}} D(f(\mathbf{X}^n; \boldsymbol{\theta})_{1+l:h}, f(\mathbf{X}^{n+1}; \boldsymbol{\theta})_{1:h-l}) \quad (2)$$

where D denotes a distance function and subscripts denote the segment ranges of the model f ’s prediction output sequences, i.e., $1+l:h$ and $1:h-l$ correspond to the same timestamps for \mathbf{X}^n and \mathbf{X}^{n+1} , respectively. Eq. (2) can be easily extended to handle non-consecutive overlapping output sequences, enabling its application to TAM (Theorem 3.5). AliO aligns the overlapping predictions \mathbf{P}^n and \mathbf{P}^{n+1} in both time and frequency domains, as illustrated in Fig. 3 with further details provided in the following subsections. The algorithmic procedure of AliO is summarized in Alg. 1.

4.1 Time domain alignment

To enhance the temporal alignment, AliO aligns the overlapping predictions, \mathbf{P}_T^n and \mathbf{P}_T^m for $n, m = 1, 2, \dots, N$, in the time domain, where the subscript T denotes the time domain. This alignment can be achieved using a distance function, D_T , such as MSE or Dynamic Time Warping (DTW) [34]. The computed distance is back-propagated to encourage the model f to produce overlapping predictions that align with each other. However, solely aligning the overlapping predictions by minimizing the time domain alignment loss $\mathcal{L}_T = D_T(\mathbf{P}_T^n, \mathbf{P}_T^m)$ may lead to both prediction outputs deviating from the ground truth, degrading the forecasting regression performance of the model f .

4.2 Regression pulling (RegPull)

To maintain forecasting regression performance while aligning predictions, we propose *Regression Pulling (RegPull)*, which identifies which prediction output points of \mathbf{P}_T^n and \mathbf{P}_T^m are relatively further from the ground truth than the other at the same timestamp, indicated by the index variable idx_T , as shown on line (1) in Alg. 1. By applying the stop-gradient operation, denoted as $sg(\cdot)$, to the prediction output points farther from the ground truth, the time domain alignment loss \mathcal{L}_T pulls these distant points closer to the ground truth, aligning its optimization direction with that of the forecasting regression loss and reinforcing to minimize the regression loss. Consequently, regression pulling

Algorithm 1 The procedure of AliO. \odot denotes element-wise multiplication. $FFT(\cdot, \cdot, \cdot)$ returns the frequency domain representation of each signal sequences, $sg(\cdot)$ is stop-gradient operator.

Input: The number of predictions N , consecutive predictions \mathbf{Y}^n with at time lag of l , and their ground truth $\hat{\mathbf{Y}}^n$, where $n \in [1, N]$, and distance function D_T and D_F for the time and frequency domain, respectively. The subscript T and F denotes the time and frequency domain, respectively.

Output: The time domain alignment loss \mathcal{L}_T and frequency domain alignment loss \mathcal{L}_F .

Initialize $\mathcal{L}_t = 0$, $\mathcal{L}_f = 0$, $count = 0$

for $n = 1$ **to** $N - 1$ **do**

for $m = n + 1$ **to** N **do**

$gap = |m - n| \times l$

$(\mathbf{P}_T^n, \mathbf{P}_T^m, \mathbf{GT}_T) = (\mathbf{Y}_{gap}^n, \mathbf{Y}_{gap}^m, \hat{\mathbf{Y}}_{gap}^n)$

$idx_T = \text{Index}(|\mathbf{P}_T^n - \mathbf{GT}_T| > |\mathbf{P}_T^m - \mathbf{GT}_T|)$

$\mathcal{L}_t = \mathcal{L}_t + D_T(\mathbf{P}_{T,i \in idx_T}^n, sg(\mathbf{P}_{T,i \in idx_T}^n)) + D_T(sg(\mathbf{P}_{T,i \notin idx_T}^n), \mathbf{P}_{T,i \notin idx_T}^m)$ [RegPull] (1)

$(\mathbf{P}_F^n, \mathbf{P}_F^m, \mathbf{GT}_F) = FFT(\mathbf{P}_T^n, \mathbf{P}_T^m, \mathbf{GT}_T)$ (2)

$idx_F = \text{Index}(|\mathbf{P}_F^n - \mathbf{GT}_F| > |\mathbf{P}_F^m - \mathbf{GT}_F|)$ (3)

$\mathcal{L}_f = \mathcal{L}_f + D_F(\mathbf{P}_{F,i \in idx_F}^n, sg(\mathbf{P}_{F,i \in idx_F}^n)) + D_F(sg(\mathbf{P}_{F,i \notin idx_F}^n), \mathbf{P}_{F,i \notin idx_F}^m)$ [RegPull] (4)

$count = count + 1$ (5)

end for

end for

$(\mathcal{L}_T, \mathcal{L}_F) = (\mathcal{L}_t / count, \mathcal{L}_f / count)$

Return: \mathcal{L}_T and \mathcal{L}_F

effectively reduces the misalignment between prediction outputs with the forecasting regression performance being unaffected, inducing overall predictions closely aligned with the ground truths.

For each prediction output point $i \in [1, h']$ in Alg. 1, $D_T(\mathbf{P}_{T,i \in idx_T}^n, sg(\mathbf{P}_{T,i \in idx_T}^n))$ on line (2) encourages the prediction \mathbf{P}_T^n to move closer to the prediction \mathbf{P}_T^m . On the other hand, $D_T(sg(\mathbf{P}_{T,i \notin idx_T}^n), \mathbf{P}_{T,i \notin idx_T}^m)$ on the same line (2) promotes the alignment of \mathbf{P}_T^m towards \mathbf{P}_T^n . The direction of alignment is determined by the index variable, idx_T . These two distance values are combined into the time domain alignment loss \mathcal{L}_T , which is expressed as:

$$\mathcal{L}_T = D_T(\mathbf{P}_{T,i \in idx_T}^n, sg(\mathbf{P}_{T,i \in idx_T}^n)) + D_T(sg(\mathbf{P}_{T,i \notin idx_T}^n), \mathbf{P}_{T,i \notin idx_T}^m) \quad (3)$$

Consequently, Eq. (3) aligns the direction of the time domain alignment loss \mathcal{L}_T with the forecasting regression loss while improving output alignment. The regression pulling can also be applied in the same way to the frequency domain; Fig. 3 shows a visual illustration of output alignment in the time (left) and frequency domain (right) using regression pulling (red cross marks).

4.3 Frequency domain alignment

In addition to the time domain alignment, we propose frequency domain alignment as a complementary approach that supports and enhances time-domain alignment by aligning overlapping predictions in the frequency representation. It promotes the alignment of both the phase and the amplitude components, improving overall consistency in the time domain.

As shown in Alg. 1, the time domain overlapping predictions, \mathbf{P}_T^n and \mathbf{P}_T^m , along with the ground truths \mathbf{GT}_T , are first transformed into frequency domain representations, resulting in \mathbf{P}_F^n , \mathbf{P}_F^m , and \mathbf{GT}_F on line (3), where the subscript F denotes the frequency domain. Subsequently, the index variable idx_F is determined by identifying output points further from \mathbf{GT}_F between \mathbf{P}_F^n and \mathbf{P}_F^m on line (4). The distance function D_F is then applied with regression pulling to facilitate alignment in the frequency domain on lines (5) in the same manner to the time domain. From this, the frequency domain alignment loss \mathcal{L}_F is obtained as:

$$\mathcal{L}_F = D_F(\mathbf{P}_{F,i \in idx_F}^n, sg(\mathbf{P}_{F,i \in idx_F}^n)) + D_F(sg(\mathbf{P}_{F,i \notin idx_F}^n), \mathbf{P}_{F,i \notin idx_F}^m) \quad (4)$$

We use MSE (mean squared error) as the main distance function for the frequency domain alignment, i.e., $D_F = \|\mathbf{P}_F^n - \mathbf{P}_F^m\|_2^2 / h'$. The following Theorem 4.1 demonstrates that applying MSE in the frequency domain facilitates phase alignment between prediction outputs.

Theorem 4.1. *Given two frequency domain prediction vectors, \mathbf{p}_F^n and \mathbf{p}_F^m in $\mathbb{C}^{h'}$, where \mathbb{C} means the set of complex numbers, minimizing their MSE, $\|\mathbf{p}_F^n - \mathbf{p}_F^m\|_2^2$, results in a reduction of the difference*

in the phase components, $\angle \mathbf{p}_F^n$ and $\angle \mathbf{p}_F^m$, as shown below (the proof is provided in Sec. B.1):

$$\frac{1}{h'} \|\mathbf{p}_F^n - \mathbf{p}_F^m\|_2^2 \rightarrow 0 \implies |\angle \mathbf{p}_F^n - \angle \mathbf{p}_F^m| \rightarrow 0 \quad (5)$$

Fig. 3 (Right) shows a polar-coordinate depiction of frequency alignment conducted through Eq. (5) in the frequency domain. Theorem 4.2 shows that minimizing MSE, i.e., $D_F = \|\mathbf{P}_F^n - \mathbf{P}_F^m\|_2^2$, also reduces the differences in amplitude once the phase components $\angle \mathbf{P}_F^n$ and $\angle \mathbf{P}_F^m$ have been aligned.

Theorem 4.2. *Once the phases of two frequency domain prediction vectors, \mathbf{p}_F^n and \mathbf{p}_F^m in $\mathbb{C}^{h'}$, are aligned, i.e., $\angle \mathbf{p}_F^n \simeq \angle \mathbf{p}_F^m$, the minimization of MSE between the two prediction outputs, $\|\mathbf{p}_F^n - \mathbf{p}_F^m\|_2^2$, leads to a reduction in the amplitude difference, as shown below (the proof is provided in Sec. B.2):*

$$\frac{1}{h'} \|\mathbf{p}_F^n - \mathbf{p}_F^m\|_2^2 \rightarrow 0 \implies |\mathbf{p}_F^n| - |\mathbf{p}_F^m| \rightarrow 0 \quad (6)$$

4.4 AliO loss

By combining the time \mathcal{L}_T in Eq. (3) and frequency domain alignment loss \mathcal{L}_F in Eq. (4), we derive the AliO loss, \mathcal{L}_{AliO} , which is incorporated with the forecasting regression loss, \mathcal{L}_{reg} as shown below, where λ_T and λ_F control the extent of alignment in the time and frequency domain, respectively.

$$\mathcal{L}_{AliO} = \lambda_T \mathcal{L}_T + \lambda_F \mathcal{L}_F \quad \therefore \mathcal{L}_{total} = \mathcal{L}_{reg} + \mathcal{L}_{AliO} \quad (7)$$

5 Experiment

We evaluate AliO on representative LTSF models and datasets. In model training, MSE is employed as the regression loss. The model performance is assessed using both MSE and TAM_N for output alignment evaluation, with $N = 2$. To reproduce experimental results of baselines and ensure a fair evaluation, we follow the same hyper-parameters presented in each model papers [37, 27, 40, 43, 30, 33, 36]. For AliO, we set $N = 2$ and $l = 1$, covering a wide prediction range. The search space for λ_T and λ_F are $\{1.0, 2.0, 5.0\}$ and $\{0.0, 0.5, 1.0, 2.0\}$, respectively, and we report the best results in the main results. All results are reported as the average performance across all prediction lengths. Detailed descriptions of the experiment and results are provided in Secs. G to I.

Models. We apply AliO to various LTSF architectures, experimenting it with a diverse range of LTSF approaches, categorized into four groups: (1) Transformer-based models, i.e., Autoformer [37], PatchTST [33], and iTransformer [30], (2) Linear-based models, i.e., DLinear [40] and CycleNet [27], (3) CNN-based models, i.e., TimesNet [36], and (4) LLM-based models, i.e., GPT4TS [43].

Datasets. On the main text of the paper, we report results on representative LTSF datasets, i.e., Electricity (ECL) [13], ETT {h1, h2, m1, and m2} [42], Traffic, [37], Weather [37], and National-Illness (ILI) dataset [37]. The experiments results on full datasets can be found in Sec. I.

Context Length Following the official settings for each model, we set the context length to 336 for PatchTST and DLinear, and 96 for the other models. For the ILI dataset specifically, the context lengths were set to 104 for PatchTST and DLinear, and 36 for TimesNet.

Prediction Length Furthermore, as per the official settings, the prediction lengths were set to $\{96, 192, 336, 720\}$ for most datasets. The exceptions were the PEMS-related datasets with $\{12, 24, 48, 96\}$, the ILI dataset with $\{24, 36, 48, 60\}$, and the Autoformer model on the ETT datasets, for which we used $\{24, 48, 168, 336, 720\}$.

5.1 Output alignment and forecasting performance

Tab. 1 summarizes the performance of LTSF models on seven datasets (excluding ILI) for multivariate LTSF tasks, comparing baselines (without AliO) and AliO-integrated models in terms of MSE and TAM. As shown in the table, integrating AliO with the regression loss substantially improves alignment performance (TAM), achieving gains of up to 70.5% for CycleNet, 45.8% for GPT4TS, 45.8% for iTransformer, 36.8% for PatchTST, 45.6% for TimesNet, 64.0% for DLinear, and 39.0% for Autoformer. Simultaneously, forecasting performance (MSE) also improves by up to 11.5%. As summarized in Tab. 2, for the ILI dataset exhibiting insufficient initial output alignment, AliO achieves up to a 17.4% higher MSE improvement compared to other benchmarks.

Table 1: The forecasting and alignment performance, measured by MSE and TAM_2 , respectively, are compared between the baseline (MSE only) and AliO, with best results indicated in **bold**. The results are averaged over three random seeds and prediction lengths. The more metrics (MAE, MAPE, and RMSE) with standard deviations are provided in Sec. I.

Models	CycleNet		GPT4TS		iTransformer		PatchTST		TimesNet		DLinear		Autoformer		
Metric	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	
ECL	baseline	0.171	0.016	0.167	0.036	0.176	0.050	0.162	0.037	0.196	0.040	0.166	0.013	0.229	0.041
	AliO	0.170	0.014	0.167	0.025	0.172	0.031	0.161	0.024	0.191	0.028	0.166	0.010	0.221	0.036
ETTh1	baseline	0.432	0.044	0.424	0.056	0.455	0.088	0.418	0.076	0.476	0.05	0.422	0.025	0.477	0.05
	AliO	0.429	0.013	0.417	0.039	0.438	0.052	0.415	0.048	0.468	0.032	0.419	0.014	0.444	0.046
ETTh2	baseline	0.385	0.047	0.363	0.048	0.382	0.074	0.341	0.061	0.416	0.079	0.449	0.054	0.401	0.041
	AliO	0.381	0.025	0.354	0.033	0.377	0.052	0.341	0.050	0.402	0.043	0.446	0.033	0.377	0.025
ETTm1	baseline	0.386	0.032	0.351	0.044	0.407	0.060	0.352	0.050	0.412	0.045	0.358	0.024	0.488	0.070
	AliO	0.383	0.014	0.346	0.031	0.396	0.033	0.349	0.032	0.398	0.026	0.354	0.010	0.448	0.053
ETTm2	baseline	0.272	0.027	0.270	0.042	0.292	0.048	0.257	0.059	0.296	0.036	0.289	0.037	0.271	0.052
	AliO	0.271	0.019	0.265	0.028	0.289	0.026	0.255	0.039	0.295	0.022	0.268	0.020	0.254	0.032
Traffic	baseline	0.487	0.021	0.411	0.059	0.422	0.061	0.389	0.041	0.626	0.040	0.436	0.025	0.634	0.048
	AliO	0.481	0.008	0.405	0.032	0.423	0.044	0.388	0.027	0.554	0.030	0.434	0.009	0.624	0.045
Weather	baseline	0.255	0.010	0.227	0.024	0.260	0.024	0.229	0.018	0.262	0.018	0.245	0.007	0.342	0.056
	AliO	0.255	0.008	0.225	0.011	0.259	0.017	0.228	0.012	0.262	0.014	0.244	0.005	0.311	0.042

5.2 How AliO maintains or improves regression performance

Tab. 2 shows AliO’s effectiveness in improving both forecasting accuracy and alignment performance on the ILI dataset [37], which exhibits poor output alignment in the absence of AliO. The proposed regression pulling enhances model training by analyzing prediction distances at each timestamp, adaptively strengthening the effect of regression loss to align predictions with each other and ground truth. On ILI, which exhibits poor initial alignment, AliO achieves 17.4% MSE and 58.1% TAM improvement. Conversely, datasets with better initial alignment, presented in Tab. 1, achieve comparatively smaller MSE improvements. Figs. 4 and 13 shows this trend; higher initial TAM (poor alignment) correlates with greater MSE gains, demonstrating AliO’s efficacy in suboptimal alignment conditions.

Figs. 2 and 5 visualize DLinear predictions on the ILI dataset. The left figures (without AliO) exhibit prediction shifts [18] in both time (Fig. 2) and frequency (Fig. 5) domains, reflected in high TAM values. In contrast, the right figures (with AliO) show improved alignment in both domains, which reduces TAM value and enhances regression performance (MSE).

Table 2: The forecasting regression and alignment performance on ILI [37], measured in MSE, and TAM_2 , are compared between the baseline (without AliO) and AliO. The best results are highlighted in **bold**. For robust evaluation, we conduct experiments with three random seeds. Results are rounded to three decimal places for simplicity.

Models	GPT4TS		PatchTST		TimesNet		DLinear	
Metric	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2	MSE	TAM_2
base	1.898	0.117	1.813	0.110	2.176	0.322	2.247	0.152
AliO	1.755	0.098	1.497	0.046	1.963	0.258	2.187	0.119

5.3 Hyper-parameter Analysis

Time and Frequency Domain Coefficients. AliO utilizes the two coefficients, λ_T and λ_F in Eq. (7), to balance the regression performance and output alignment by adjusting the alignment strengths over the time and frequency domains, respectively. To evaluate AliO with respect to these two coefficients, we provide Fig. 6, which presents heatmaps of the normalized MSE and TAM for various coefficient values. The x-axis represents λ_F in $\{0.0, 0.5, 1.0, 2.0\}$, and the y-axis corresponds to λ_T in $\{1.0, 2.0, 5.0\}$. The left heatmap shows normalized MSE, where the maximum MSE in each dataset is scaled to 1.0 and the minimum to 0, followed by averaging across all models. The right heatmap presents normalized TAM in the same manner. Additional results are in Sec. F.

As AliO is designed to enhance alignment, a clear trend is observed in TAM where increasing the time domain alignment coefficient λ_T from 1.0 to 5.0 leads to a consistent improvement. Interestingly, the normalized MSE also shows a general improvement as λ_T increases, suggesting that the regression pulling effectively aligns the directions of the AliO loss with those of the regression loss. The influence of the frequency domain alignment coefficient λ_F is less pronounced compared to the time

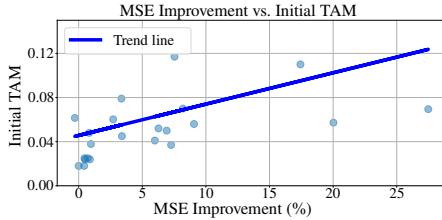


Figure 4: The relationship between initial TAM and MSE improvement (%). The correlation coefficient is 0.33, indicating a positive trend; when the initial alignment is poor (i.e., higher TAM values), the MSE improvement tends to be greater. For more detailed information, please check Sec. E.

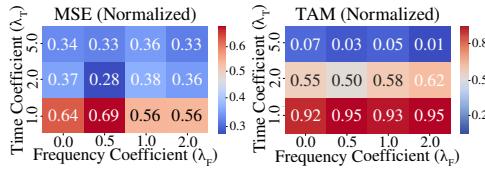


Figure 6: Comparison of the normalized MSE (left) and TAM (right) over different settings of λ_T and λ_F . The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{1.0, 2.0, 5.0\}$). Increasing λ_T consistently improves TAM performance, while λ_F shows its impact depending on the value of λ_T . Blue represents better performance.

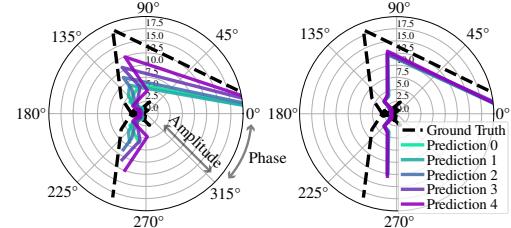


Figure 5: (Left) The frequency domain of five predictions in polar coordinates from DLinear [40] trained with regression loss, forecasting the ILI dataset. (Right) Five phases from the same setup, with AliO applied. AliO effectively aligns both the phase and amplitude of the model’s predictions in the frequency domain.

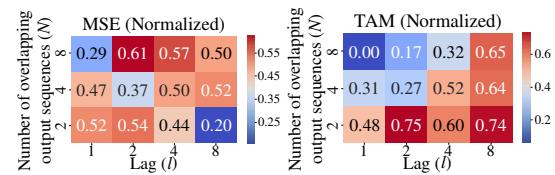


Figure 7: Comparison of the normalized MSE (left) and TAM (right) over different settings of the overlapping predictions N and the lag l . The x-axis represents the lag l , and the y-axis represents the number of overlapping predictions N . Increasing N improves TAM, while increasing l degrades the performance. No distinct tendencies are observed regarding MSE. Blue represents better performance.

coefficient λ_T . However, in cases where λ_T alone cannot improve performance, λ_F shows its impact on both the MSE and TAM metrics, as exemplified by values of 0.28 and 0.50, respectively. This demonstrates the significance of the frequency domain alignment to overcome limitations in the time domain alignment, indicating that both phase and amplitude contribute to performance enhancements.

Number of Overlapping Output Sequences and Lag Size. We investigate how the model’s MSE and TAM vary with different numbers of overlapping output sequences N and the lag l . Fig. 7 shows the normalized MSE and TAM with a range between 0 and 1.0. TAM is improved as the lag decreases, which can be attributed to an increased length of overlapping timestamps at smaller lag value. This allows AliO to align longer overlapping sequence effectively. Additionally, the model performance improves as N increases. As shown in Alg. 1, a higher N enables AliO to align predictions from distant timestamps, significantly enhancing TAM. In contrast, no clear trend is observed for MSE, since the window size increases as both N and l grow. Prior studies [12, 2, 17, 32] suggest that large window sizes can cause overfitting, whereas an optimal window size leads to better performance. As shown in Fig. 7, when both N and l are large, MSE tends to increase, indicating degraded performance. Conversely, lower MSE values (0.29, 0.37, 0.20) are observed along the diagonal elements, representing proper window sizes, such as $(l, N) = (1, 8), (2, 4), (8, 2)$, which indicates that balanced combinations of l and N yield better performance.

6 Related works

To the best of our knowledge, no prior work has adequately identified the output alignment problem and provided a solution for it, as AliO proposed in this paper.

Data-Model Robustness. While existing research [30] primarily focuses on model initialization robustness, i.e., the consistency of model performance across randomly initialized weights [30], the output alignment emphasizes data-model robustness. This aspect underscores the model’s ability

to produce consistent prediction outputs for lagged input sequences. The data-model robustness is equally critical for practical applications as discussed in this paper and can be quantified using the proposed TAM, which can be enhanced through the proposed time and frequency domain alignment. We anticipate this aspect of LTSF study will inspire further active research in the field.

Contrastive Learning. Contrastive learning [41, 8, 1, 9, 38, 22] employ pretraining strategies that encourage augmented positive pairs to be closely aligned in the representation space. However, they differ from AliO in several key aspects. First, they operate in the representation space rather than in the output space where AliO functions. Second, they minimize the distance between whole vectors rather than focusing on overlapping timestamps. Third, they do not incorporate regression-aware algorithms like regression pulling. These differences highlight the distinctive approach of AliO in output alignment, operating independently of existing methods and can thus be integrated with them.

7 Limitations and discussions

On Volatile Datasets. TAM is a metric designed to assess the output alignment of LTSF models. However, its application should be approached with caution on highly volatile datasets that fall outside the typical scope of LTSF tasks, as model predictions may experience considerable volatility. Nevertheless, as demonstrated in Sec. I, the results on the Exchange Rate dataset [37], which is influenced by abrupt external shocks, suggest that TAM retains potential applicability even in volatile settings. Designing more robust metrics for inherently volatile data is our next research objective.

Distance Functions. AliO improves regression performance under high initial TAM conditions (a low degree of output alignment). This is likely attributable to its use of MSE as the distance function, which is consistent with the regression loss employed during model training. To further enhance performance, alternative distance functions such as [25, 29, 15, 7], which capture different characteristics of time series data (e.g., shape), may serve as promising directions for future exploration.

8 Conclusion

In this paper, we investigate the output alignment problem, which can commonly arise in LTSF tasks and propose Time Alignment Metric (TAM) as a quantitative measure for this problem. To solve the output alignment problem, we propose AliO (Output Alignment) applied in both time and frequency domains. AliO achieves up to 27.5% improvement in MSE across various LTSF models and datasets, and up to 58.2% improvement in TAM, effectively addressing the output alignment problem.

Acknowledgment

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A Exemplar illustrations on importance of output alignment

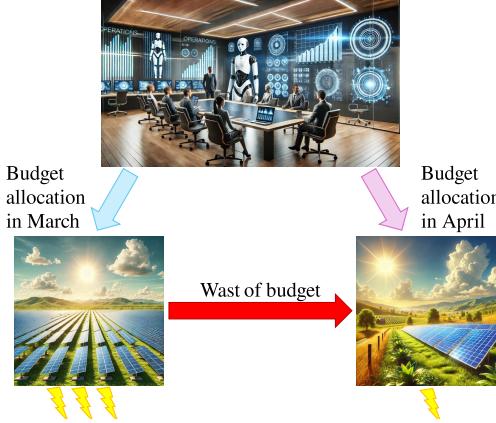


Figure 8: A simple example illustrating the importance of *output alignment* in electricity power demand forecasting. The two predictions differ, causing confusion among people, and they realize that the budget allocated in March was a waste.

B Proof

B.1 Proof of Theorem 4.1

Proof. Rewriting the equation on the left side of the theorem, we can express it from the perspective of individual elements:

$$\frac{|\mathbf{p}_F^1 - \mathbf{p}_F^2|_2^2}{h'} = \frac{1}{h'} \sum_i^{h'} |\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 \quad (8)$$

The squared magnitude of the difference between two complex numbers $\mathbf{p}_{F,i}^1$ and $\mathbf{p}_{F,i}^2$ are given as follows:

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = (\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2)(\overline{\mathbf{p}_{F,i}^1} - \overline{\mathbf{p}_{F,i}^2}) \quad (9)$$

Where $\overline{\mathbf{p}_{F,i}^1}$ and $\overline{\mathbf{p}_{F,i}^2}$ are the complex conjugate of $\mathbf{p}_{F,i}^1$ and $\mathbf{p}_{F,i}^2$. Now, expressing $\mathbf{p}_{F,i}^1$ and $\mathbf{p}_{F,i}^2$ including the complex conjugate in polar form:

$$\mathbf{p}_{F,i}^1 = |\mathbf{p}_{F,i}^1| e^{j\theta_{\mathbf{p}_{F,i}^1}}, \quad \mathbf{p}_{F,i}^2 = |\mathbf{p}_{F,i}^2| e^{j\theta_{\mathbf{p}_{F,i}^2}} \quad (10)$$

$$\overline{\mathbf{p}_{F,i}^1} = |\mathbf{p}_{F,i}^1| e^{-j\theta_{\mathbf{p}_{F,i}^1}}, \quad \overline{\mathbf{p}_{F,i}^2} = |\mathbf{p}_{F,i}^2| e^{-j\theta_{\mathbf{p}_{F,i}^2}} \quad (11)$$

where $j = \sqrt{-1}$ and θ is the angle (phase) for the corresponding complex number. We substitute into the expression and simplify the expression:

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = (|\mathbf{p}_{F,i}^1| e^{j\theta_{\mathbf{p}_{F,i}^1}} - |\mathbf{p}_{F,i}^2| e^{j\theta_{\mathbf{p}_{F,i}^2}})(|\mathbf{p}_{F,i}^1| e^{-j\theta_{\mathbf{p}_{F,i}^1}} - |\mathbf{p}_{F,i}^2| e^{-j\theta_{\mathbf{p}_{F,i}^2}}) \quad (12)$$

$$= |\mathbf{p}_{F,i}^1|^2 + |\mathbf{p}_{F,i}^2|^2 - |\mathbf{p}_{F,i}^1||\mathbf{p}_{F,i}^2|(e^{j(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2})} + e^{-j(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2})}) \quad (13)$$

Using Euler's formula $e^{j\theta} = \cos(\theta) + j\sin(\theta)$ [10], we can convert the exponential expressions to trigonometric expressions:

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = |\mathbf{p}_{F,i}^1|^2 + |\mathbf{p}_{F,i}^2|^2 - |\mathbf{p}_{F,i}^1||\mathbf{p}_{F,i}^2|\{\cos(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2}) + j\sin(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2})\} \quad (14)$$

$$+ \cos(-(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2})) + j\sin(-(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2}))\} \quad (15)$$

$$= |\mathbf{p}_{F,i}^1|^2 + |\mathbf{p}_{F,i}^2|^2 - 2|\mathbf{p}_{F,i}^1||\mathbf{p}_{F,i}^2|\cos(\theta_{\mathbf{p}_{F,i}^1} - \theta_{\mathbf{p}_{F,i}^2}) \quad (16)$$

Utilizing the angle (phase) notation \angle , we can express the equation as:

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = |\mathbf{p}_{F,i}^1|^2 + |\mathbf{p}_{F,i}^2|^2 - 2|\mathbf{p}_{F,i}^1||\mathbf{p}_{F,i}^2|\cos(\angle\mathbf{p}_{F,i}^1 - \angle\mathbf{p}_{F,i}^2) \quad (17)$$

Reducing the final equation implies increasing the cosine term, which in turn signifies aligning the two phases, since one of predictions is constant by stop-gradient $sg(\cdot)$ operator in Alg. 1.

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 \rightarrow 0 \implies \cos(\angle \mathbf{p}_{F,i}^1 - \angle \mathbf{p}_{F,i}^2) \rightarrow 1 \quad (18)$$

$$\cos(\angle \mathbf{p}_{F,i}^1 - \angle \mathbf{p}_{F,i}^2) \rightarrow 1 \implies |\angle \mathbf{p}_F^1 - \angle \mathbf{p}_F^2| \rightarrow 0 \quad (19)$$

$$\therefore |\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 \rightarrow 0 \implies |\angle \mathbf{p}_F^1 - \angle \mathbf{p}_F^2| \rightarrow 0 \quad (20)$$

□

B.2 Proof of Theorem 4.2

Proof. Since the two phases, i.e., $\angle \mathbf{p}_{F,i}^1$ and $\angle \mathbf{p}_{F,i}^2$, are aligned, the Eq. (17) in Sec. B.1 is modified as follows:

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = |\mathbf{p}_{F,i}^1|^2 + |\mathbf{p}_{F,i}^2|^2 - 2|\mathbf{p}_{F,i}^1||\mathbf{p}_{F,i}^2| \quad (21)$$

By factoring, it can be expressed in the following perfect square form.

$$|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2 = (|\mathbf{p}_{F,i}^1|^2 - |\mathbf{p}_{F,i}^2|^2)^2 \quad (22)$$

Since one of predictions is constant by stop-gradient $sg(\cdot)$ operator in Alg. 1, minimizing $|\mathbf{p}_{F,i}^1 - \mathbf{p}_{F,i}^2|^2$ leads to a reduction in the amplitude difference □

C Visualization of alignment

In this section, we visualize the model’s prediction outputs and alignment differences when trained solely with regression loss versus with both regression loss and AliO. Each figure is arranged in a 2×2 grid: the top row shows results using regression loss alone, while the bottom row presents results incorporating AliO; the left column illustrates the time domain, and the right column displays the frequency domain visualized in a polar coordinate system, where the azimuth angle represents the phase and the radial distance from the origin corresponds to the amplitude. Overlapping timestamps of prediction outputs for five lagged inputs are shown, with the ground truth indicated by black dashed lines. Figs. 9 to 12 show the results from DLinear [40], PatchTST [33], TimesNet [36], and iTransformer [30].

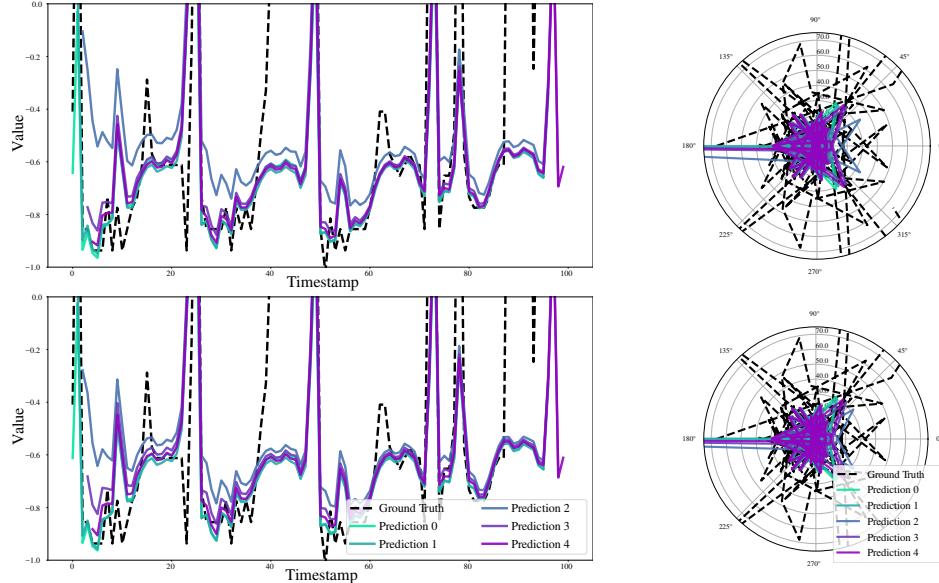


Figure 9: **Visualization:** **Upper** shows the prediction of DLinear [40] using only the regression loss on the ECL dataset [13], while **Bottom** shows the result under the same conditions when AliO is also applied. It is observed that AliO improves alignment performance for overlapping timestamps.

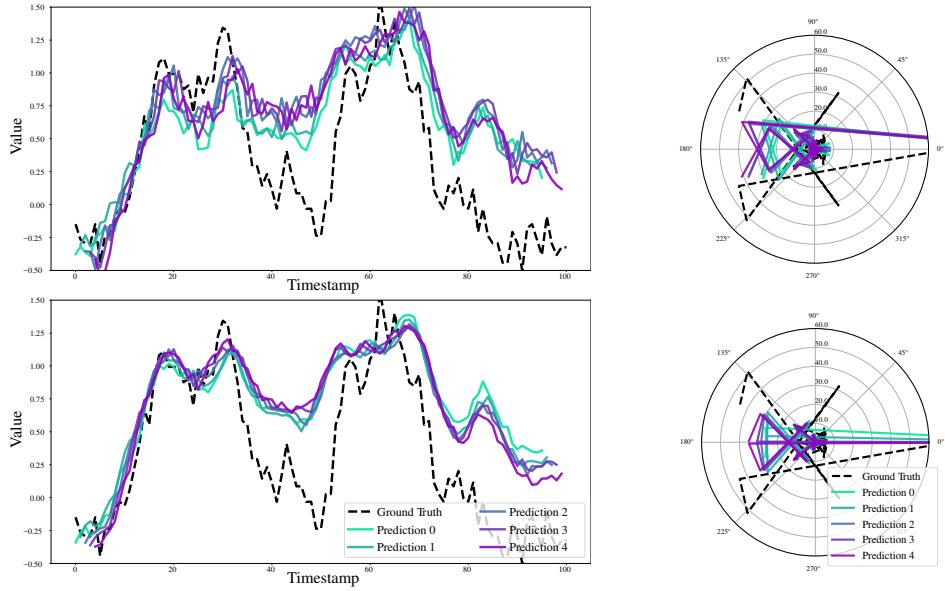


Figure 10: **Visualization:** **Upper** shows the prediction of PatchTST [33] using only the regression loss on the ETTm1 dataset [42], while **Bottom** shows the result under the same conditions when AliO is also applied. It is observed that AliO improves alignment performance for overlapping timestamps.

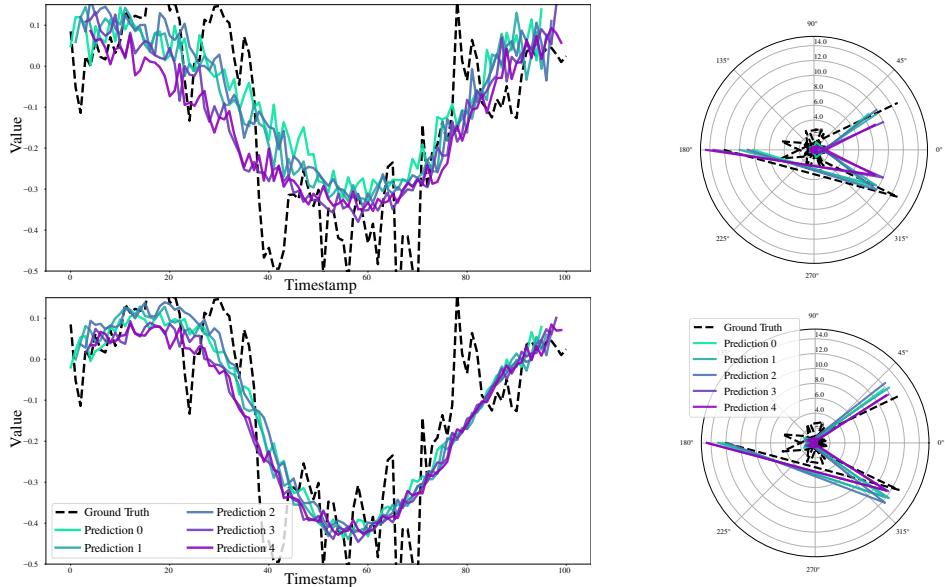


Figure 11: **Visualization:** **Upper** shows the prediction of TimesNet [36] using only the regression loss on the ETTm2 dataset [42], while **Bottom** shows the result under the same conditions when AliO is also applied. It is observed that AliO improves alignment performance for overlapping timestamps.

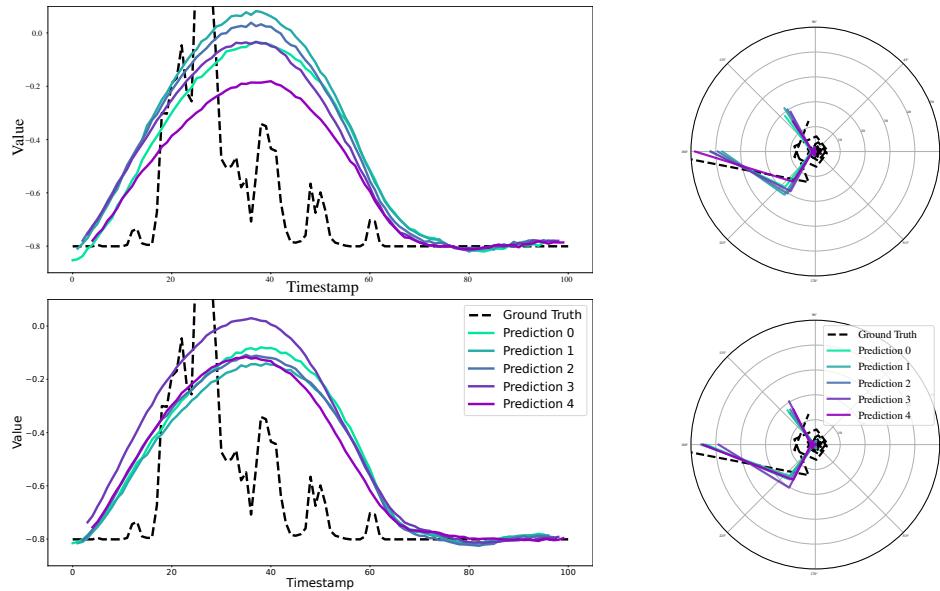


Figure 12: **Visualization:** **Upper** shows the prediction of iTTransformer [30] using only the regression loss on the Solar dataset [24], while **Bottom** shows the result under the same conditions when AliO is also applied. It is observed that AliO improves alignment performance for overlapping timestamps.

D On sudden event

This section expands on the sudden events mentioned in Sec. 7.

Definition D.1. The sudden event refers to an anomalous data point in the input sequence that can be interpreted as out-of-distribution (OOD), causing perturbations in the output sequence. Such event occur when input-level perturbations lead to unpredictable output patterns.

These scenarios deviate from the core objective of Long-term Time Series Forecasting (LTSF), which focuses on predictable sequences. Instead, they align more closely with:

- Domain Adaptation [19]
- Anomaly Detection [39]
- Test-Time Adaptation [21]

The TAM metric is specifically designed for LTSF tasks with predictable, stable output sequences (i.e., non-perturbed scenarios). In contexts involving sudden events or OOD (out-of-distribution) data, the inherent assumptions of TAM—particularly its reliance on sequence stability—may not hold, necessitating cautious application. However, if a sudden event includes precursor signals (i.e., detectable input patterns) and the model can sufficiently predict the output sequence using this information, TAM remains valid even under such conditions.

E Initial TAM vs. MSE improvement

Fig. 4 may be difficult to interpret as there is no explicit distinction between models and datasets. In this section [Fig. 13], to facilitate easier interpretation, models are represented by different shapes and datasets are represented by different colors.

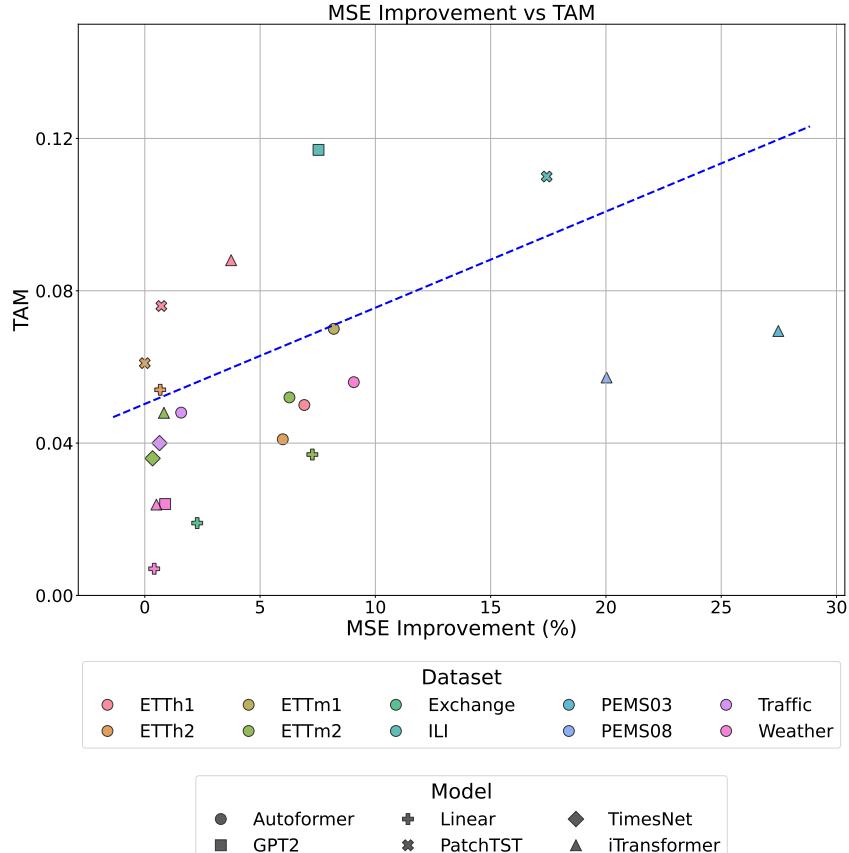


Figure 13: The relationship between initial TAM and MSE improvement (%).

F Zero coefficient of time domain alignment (λ_T)

By default, AliO operates in the time domain, so scenarios where the time-scaling coefficient is zero were excluded from the main context. However, we conducted experiments on CycleNet [27], iTransformer [30], TimesNet [36] under conditions with a zero time-scaling coefficient. The results, shown in Figs. 14 to 25, are normalized between 0 and 1. Since the condition ($\lambda_T = 0, \lambda_F = 0$) implies that AliO is not used, so it is empty. As demonstrated in Fig. 6 increasing λ_T consistently improves TAM performance. When it comes to MSE performance, there's a general trend for it to improve as the coefficient increases, similar to what's seen with TAM (I'm assuming this refers to a specific model or method you're using). However, in some environments, the coefficient can become excessively large, dominating the regression loss and causing performance to degrade. Despite this, our experiments confirmed that an appropriate, non-zero coefficient leads to improved performance. The tables show the results where the lag is 1 and the number of sequences is 2 (default).

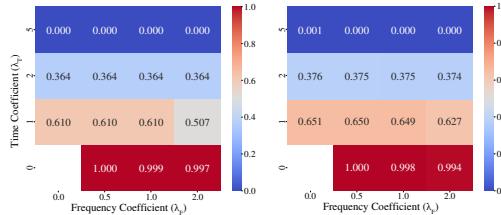


Figure 14: Comparison of the normalized MSE (**left**) and TAM (**right**) of CycleNet trained on ETTm1 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

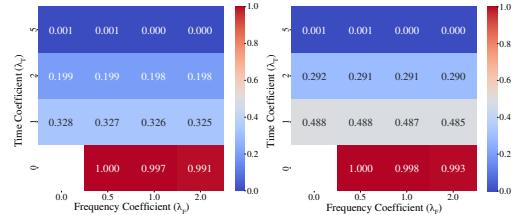


Figure 15: Comparison of the normalized MSE (**left**) and TAM (**right**) of CycleNet trained on ETTm2 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

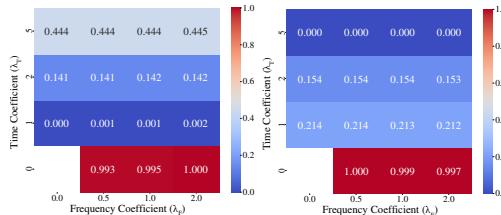


Figure 16: Comparison of the normalized MSE (**left**) and TAM (**right**) of CycleNet trained on Traffic dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

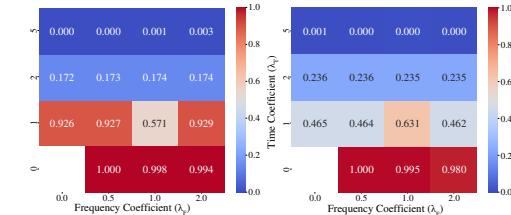


Figure 17: Comparison of the normalized MSE (**left**) and TAM (**right**) of iTransformer trained on ETTh1 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

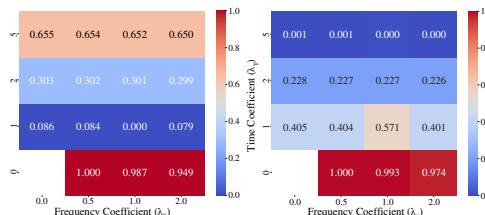


Figure 18: Comparison of the normalized MSE (**left**) and TAM (**right**) of iTransformer trained on ETTh2 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

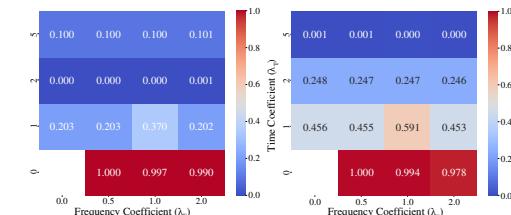


Figure 19: Comparison of the normalized MSE (**left**) and TAM (**right**) of iTransformer trained on ETTm1 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

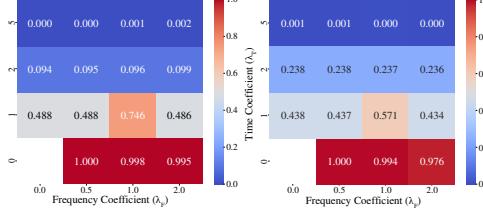


Figure 20: Comparison of the normalized MSE (left) and TAM (right) of iTransformer trained on ETTm2 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

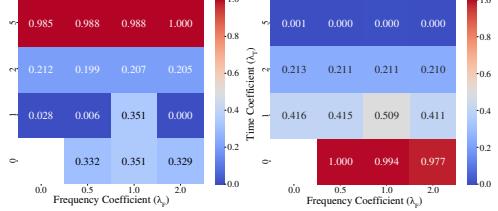


Figure 21: Comparison of the normalized MSE (left) and TAM (right) of iTransformer trained on Traffic dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

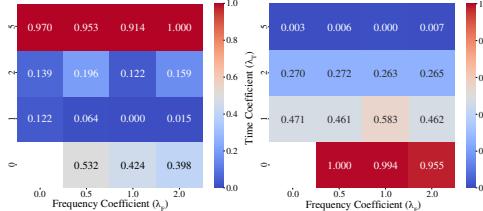


Figure 22: Comparison of the normalized MSE (left) and TAM (right) of iTransformer trained on Weather dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

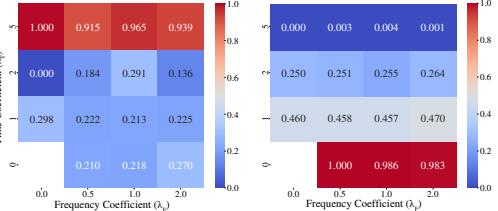


Figure 23: Comparison of the normalized MSE (left) and TAM (right) of TimesNet trained on ETTh1 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

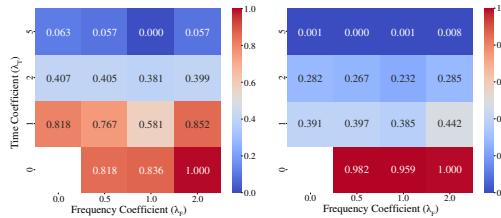


Figure 24: Comparison of the normalized MSE (left) and TAM (right) of TimesNet trained on ETTm1 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

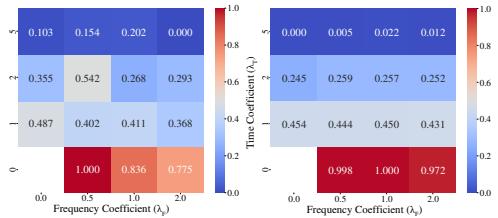


Figure 25: Comparison of the normalized MSE (left) and TAM (right) of TimesNet trained on ETTm2 dataset. The x-axis represents λ_F ($\{0.0, 0.5, 1.0, 2.0\}$), and the y-axis represents λ_T ($\{0.0, 1.0, 2.0, 5.0\}$).

G Dataset explanation

We provide a brief description of each dataset used in our experiments, as referenced in Secs. 5 and I.

- **Electricity transformer temperature (ETT)** [42]: This dataset consists of two years of data collected from two counties in China. It is divided into four subsets: ETTh1 and ETTh2 (sampled hourly), and ETTm1 and ETTm2 (sampled every 15 minutes). Each record contains six power load features and one target variable representing the oil temperature.
- **Exchange** [37]: Contains daily exchange rates from eight countries, spanning from 1990 to 2016.
- **Electricity (ECL)** [13]: Comprises electric power consumption data sampled every minute over four years for a single household.

- **ILI** (<https://github.com/thuml/Autoformer>): Weekly records from 2002 to 2021, provided by the US Centers for Disease Control and Prevention, representing the number of influenza-like illness patients.
- **PEMS**: Contains traffic information measured at 5-minute intervals on California highways. The subsets PEMS03, PEMS04, PEMS07, and PEMS08 correspond to different regions and time spans, with varying numbers of sensors [28].
- **Solar-Energy** [24]: Includes solar energy production data from 137 plants in 2006, measured at 10-minute intervals.
- **Traffic** [37]: Consists of hourly traffic congestion data collected by 862 sensors on San Francisco freeways from January 2015 to December 2016.

To ensure fair performance evaluation, we adopted the sequence length, prediction length, and label length settings used in recent LTSF models, such as Autoformer [37], DLinear [40], PatchTST [33], TimesNet [36], iTransformer [30], GPT4TS [43], CycleNet [27]. Following previous works [37, 30, 28]. Tab. 3 shows the descriptions of datasets including the number of variate in each dataset, prediction length, dataset size, sampling frequency, and domain. Since the official Autoformer implementation provides the results in different prediction length (24, 48, 168, 336, 720), we follow their implementation and show the results on Sec. I.

Table 3: Descriptions of datasets. # of vars means the number of variate in each dataset.

Dataset	# of vars	Prediction Length	Dataset size (Train / Validation / Test)	Frequency	Domain
ETTh1	7	24, 48, 168, 336, 720 (Autoformer) 96, 192, 336, 720 (other models)	8545 / 2881 / 2881	Hourly	Temperature
ETTh2	7	24, 48, 168, 336, 720 (Autoformer) 96, 192, 336, 720 (other models)	8545 / 2881 / 2881	Hourly	Temperature
ETTm1	7	24, 48, 168, 336, 720 (Autoformer) 96, 192, 336, 720 (other models)	34465 / 11521 / 11521	15 min	Temperature
ETTm2	7	24, 48, 168, 336, 720 (Autoformer) 96, 192, 336, 720 (other models)	34465 / 11521 / 11521	15 min	Temperature
Weather	21	96, 192, 336, 720	36792 / 5271 / 10540	10 min	Weather
Electricity (ECL)	321	96, 192, 336, 720	18317 / 2633 / 5261	Hourly	Electricity
Traffic	862	96, 192, 336, 720	12185 / 1757 / 3509	Hourly	Transportation
ILI	7	24, 36, 48, 60	617 / 74 / 170	Weekly	Health
Exchange Rate (Exchange)	8	96, 192, 336, 720	5120 / 665 / 1422	Daily	Economy
Solar	137	96, 192, 336, 720	36601 / 5161 / 10417	10 min	Energy
PEMS03	358	12, 24, 48, 96	15617 / 5135 / 5135	5 min	Transportation
PEMS04	307	12, 24, 48, 96	10172 / 3375 / 3375	5 min	Transportation
PEMS07	883	12, 24, 48, 96	16911 / 5622 / 5622	5 min	Transportation
PEMS08	170	12, 24, 48, 96	10690 / 3548 / 3548	5 min	Transportation

H Experiment configurations

To ensure fair model evaluation, we utilized the official GitHub codes provided by six benchmark models: Autoformer [37], DLinear [40], PatchTST [33], TimesNet [36], iTransformer [30], GPT4TS [43], CycleNet [27]. For all experiments, we adopted the same prediction length, label length, and sequence length as the official implementations, and maintained the original architecture of each model.

Context lengths. According to the papers [37, 40, 33, 36, 30, 43, 27], the used context lengths are followed by:

- CycleNet, Autoformer, iTransformer: 96
- TimesNet: 96 (36 for the ILI dataset)
- PatchTST, DLinear: 336 (104 for the ILI dataset)

Prediction lengths. We primarily used prediction lengths of $\{96, 192, 336, 720\}$. For the ILI dataset (<https://github.com/thuml/Autoformer>), we followed prior works and used $\{24, 36, 48, 60\}$. As an exception, for the ETT{h1, h2, m1, m2} datasets, we followed the Autoformer paper and used $\{24, 48, 168, 336, 720\}$ (for Autoformer) and $\{96, 192, 336, 720\}$ (for other models).

Optimization. The optimizer and scheduler were used under the same conditions as specified in the official codes for each model.

Our method. For our method (AliO), the hyperparameters—the number of samples N in Alg. 1 and lag l in Alg. 1—were set to their default values of 2 and 1, respectively. The Mean Squared Error (MSE) function was used as the distance function for both the time and frequency domains. The coefficients for the time domain (λ_T) and frequency domain (λ_F) were selected from the ranges $\{1.0, 2.0, 5.0\}$ and $\{0.0, 0.5, 1.0, 2.0\}$, respectively (default values are $\lambda_T = 1$ and $\lambda_F = 0$ since the frequency domain is optional). Additionally, the AWL [26] technique was employed to automatically tune these coefficients and report the best performance.

Evaluation. We used Mean Squared Error (MSE) as our baseline loss function and reported forecasting performance using MSE, Mean Absolute Error (MAE), Mean Absolute Percentage Error (MAPE), Root Mean Squared Error (RMSE), and TAM. For all these metrics, lower values indicate better performance.

Robustness. To ensure robust results, we used three random seeds (2023, 2024, 2025) for initialization and report the standard deviation using \pm . All experiments were conducted on NVIDIA RTX 3090 and A6000 GPUs. We conducted all experiments using the same GPU when comparing the baseline and AliO under the same conditions.

Training hyper-parameters. We used the same learning rate, batch size, and epoch as the official implementation of each model for reproducibility and fair comparison. The implementation code for each model is as follows.

- Autoformer: <https://github.com/thuml/Autoformer>
- DLinear: <https://github.com/vivva/DLinear>
- PatchTST: <https://github.com/yuqinie98/PatchTST>
- TimesNet: <https://github.com/thuml/TimesNet>
- iTransformer: <https://github.com/thuml/iTransformer>
- GPT4TS: <https://github.com/DAMO-DI-ML/NeurIPS2023-One-Fits-All>
- CycleNet: <https://github.com/ACAT-SCUT/CycleNet>

We followed the implementation code listed above (GitHub) and used the same learning rate, batch size, and number of epochs as shown in Tabs. 4 to 11. The optimizer we used is Adam [23].

Table 4: Learning rate and batch size of Autoformer used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	Exchange	Traffic	Weather
Learning rate	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001
batch size	32	32	32	32	32	32	32	32
Epoch	10	10	10	10	10	10	3	10

Table 5: Learning rate and batch size of DLinear used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	Exchange	ILI	Traffic	Weather
Learning rate	0.001	0.0001	0.05	0.0001	0.001 0.01	0.0005 0.005	0.05	0.05	0.0001
batch size	16	8	32	8	32	8 32	32	16	16
Epoch	10	10	10	10	10	10	10	10	10

Table 6: Learning rate and batch size of PatchTST used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	ILI	Traffic	Weather
Learning rate	0.0001	0.0001	0.0001	0.0001	0.0001	0.0025	0.0001	0.0001
batch size	32	128	128	128	128	16	6	128
Epoch	100	100	100	100	100	100	100	100

Table 7: Learning rate and batch size of TimesNet used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	ILI	Exchange	Traffic	Weather
Learning rate	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001
batch size	32	32	32	32	32	32	32	16	32
Epoch	10	10	10	10	10	10	10	10	10

Table 8: Learning rate and batch size of iTransformer used in each datasets (excluding PEMS and Solar).

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	ILI	Exchange	Traffic	Weather
Learning rate	0.0005	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.001	0.0001
batch size	16	32	32	32	32	32	32	16	32
Epoch	10	10	10	10	10	10	10	10	10

Table 9: Learning rate and batch size of iTransformer used in each datasets (including PEMS and Solar).

Dataset	PEMS03	PEMS04	PEMS07	PEMS08	Solar
Learning rate	0.001	0.0005	0.001	0.0001 0.001	0.0005
batch size	32	32	32 16	32 16	32
Epoch	10	10	10	10	10

Table 10: Learning rate and batch size of GPT4TS used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	ILI	Traffic	Weather
Learning rate	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.001	0.0001
batch size	512	256	256	256	256	16	256	512
Epoch	10	10	10	10	10	10	10	10

Table 11: Learning rate and batch size of CycleNet used in each datasets.

Dataset	ECL	ETTh1	ETTh2	ETTm1	ETTm2	Traffic	Weather	Solar
Learning rate	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001	0.0001
batch size	128	128	128	128	128	128	128	128
Epoch	30	30	30	30	30	30	30	30

I Full experimental results

This section presents the comprehensive results of each Long-Term Series Forecasting (LTSF) models, Autoformer [37] (Tabs. 12 and 13), DLinear [40] (Tabs. 14 and 15), PatchTST [33] (Tabs. 16 and 17), TimesNet [36] (Tabs. 18 and 19), iTransformer [30] (Tabs. 20 to 22), GPT4TS [43] (Tabs. 23 and 24), and CycleNet [27] (Tabs. 25 and 26). The evaluation metrics include Mean Squared Error (MSE), Temporal Alignment Metric (TAM), Mean Absolute Error (MAE), Mean Absolute Percentage Error (MAPE), and Root Mean Squared Error (RMSE). The \pm symbol denotes the standard deviation across multiple seeds (we used three random seeds for robust experiment). AVG represents the average value across all prediction lengths, with the best performance highlighted in **bold**.

Table 12: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETM1, ETM2, Exchange, Traffic, and Weather datasets and Autoformer [37]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thumul/Autoformer>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 6.98%, TAM: 24.24%, MAE: 3.38%, MAPE: 3.76%, and RMSE: 3.12%. The maximum improvement of AliO over the baseline is MSE: 27.90%, TAM: 81.18%, MAE: 15.17%, MAPE: 15.42%, and RMSE: 8.58%. Exchange, Traffic, and Weather are in Tab. 13.

Models	Autoformer						AliO					
	Method	MSE \downarrow	Baseline		MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow		MAE \downarrow	MAPE \downarrow	RMSE \downarrow
Metric	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	
ECL	96	0.204 \pm 0.008	0.035 \pm 0.002	0.319 \pm 0.008	3.398 \pm 0.230	0.452 \pm 0.009	0.193\pm0.003	0.029\pm0.001	0.308 \pm 0.003	3.296 \pm 0.132	0.440 \pm 0.004	
	192	0.219 \pm 0.005	0.042 \pm 0.002	0.329 \pm 0.003	3.416 \pm 0.185	0.468 \pm 0.005	0.215\pm0.003	0.038\pm0.004	0.324 \pm 0.004	3.402 \pm 0.091	0.464 \pm 0.004	
	336	0.232 \pm 0.004	0.040 \pm 0.004	0.340 \pm 0.004	3.466 \pm 0.224	0.481 \pm 0.004	0.223\pm0.007	0.034\pm0.004	0.331 \pm 0.005	3.350 \pm 0.136	0.472 \pm 0.007	
	720	0.260 \pm 0.013	0.046 \pm 0.007	0.362 \pm 0.009	3.501 \pm 0.118	0.509 \pm 0.013	0.253\pm0.008	0.042\pm0.002	0.356 \pm 0.006	3.404 \pm 0.035	0.503 \pm 0.008	
	AVG	0.229 \pm 0.018	0.041 \pm 0.003	0.337 \pm 0.015	3.445 \pm 0.036	0.478 \pm 0.019	0.221\pm0.019	0.036\pm0.004	0.330 \pm 0.015	3.363 \pm 0.040	0.469 \pm 0.020	
ETTh1	24	0.408 \pm 0.008	0.063 \pm 0.005	0.427 \pm 0.002	10.853 \pm 0.413	0.639 \pm 0.006	0.373\pm0.008	0.051\pm0.002	0.416 \pm 0.007	10.747 \pm 0.477	0.611 \pm 0.007	
	48	0.408 \pm 0.014	0.048 \pm 0.004	0.431 \pm 0.008	11.632 \pm 0.477	0.639 \pm 0.011	0.395\pm0.024	0.037\pm0.002	0.420 \pm 0.012	10.889 \pm 0.175	0.628 \pm 0.019	
	168	0.502 \pm 0.028	0.051 \pm 0.012	0.482 \pm 0.016	11.810 \pm 0.142	0.708 \pm 0.020	0.445\pm0.014	0.036\pm0.005	0.451 \pm 0.010	11.573 \pm 0.593	0.667 \pm 0.011	
	336	0.517 \pm 0.013	0.039\pm0.003	0.491 \pm 0.006	11.786\pm0.326	0.719 \pm 0.009	0.484\pm0.013	0.048 \pm 0.002	0.479\pm0.008	11.957 \pm 0.223	0.696\pm0.009	
	720	0.549 \pm 0.016	0.047\pm0.002	0.527 \pm 0.008	12.533\pm0.659	0.741 \pm 0.011	0.521\pm0.009	0.057 \pm 0.009	0.516\pm0.010	13.217 \pm 1.015	0.722\pm0.007	
ETTh2	AVG	0.477 \pm 0.053	0.050 \pm 0.007	0.472 \pm 0.034	11.723 \pm 0.488	0.689 \pm 0.039	0.444\pm0.050	0.046\pm0.008	0.456\pm0.034	11.677\pm0.811	0.665\pm0.038	
	24	0.280 \pm 0.009	0.054 \pm 0.004	0.356 \pm 0.006	1.524 \pm 0.038	0.529 \pm 0.008	0.265\pm0.003	0.034\pm0.003	0.340 \pm 0.003	1.392\pm0.028	0.515\pm0.003	
	48	0.335 \pm 0.029	0.051 \pm 0.009	0.390 \pm 0.021	1.624 \pm 0.067	0.578 \pm 0.025	0.301\pm0.009	0.025\pm0.002	0.360 \pm 0.006	1.422 \pm 0.054	0.549 \pm 0.008	
	168	0.442 \pm 0.008	0.044 \pm 0.009	0.448 \pm 0.009	1.868 \pm 0.150	0.665 \pm 0.006	0.421\pm0.008	0.027\pm0.002	0.427 \pm 0.005	1.580 \pm 0.084	0.649 \pm 0.006	
	336	0.479 \pm 0.012	0.031 \pm 0.012	0.482 \pm 0.012	2.003 \pm 0.194	0.692 \pm 0.009	0.448\pm0.002	0.018\pm0.004	0.455 \pm 0.002	1.749 \pm 0.020	0.669 \pm 0.001	
ETM1	720	0.470 \pm 0.022	0.025 \pm 0.005	0.483 \pm 0.013	2.273 \pm 0.166	0.685 \pm 0.016	0.450\pm0.005	0.020 \pm 0.000	0.466 \pm 0.003	2.044 \pm 0.024	0.670 \pm 0.004	
	AVG	0.491 \pm 0.072	0.041 \pm 0.010	0.433 \pm 0.046	1.858 \pm 0.245	0.630 \pm 0.059	0.377\pm0.071	0.025\pm0.005	0.410 \pm 0.046	1.637 \pm 0.219	0.610 \pm 0.060	
	24	0.377 \pm 0.015	0.092 \pm 0.003	0.415 \pm 0.005	2.563 \pm 0.005	0.614 \pm 0.012	0.351\pm0.023	0.084\pm0.001	0.394 \pm 0.011	2.455\pm0.019	0.592\pm0.019	
	48	0.447 \pm 0.048	0.079 \pm 0.014	0.452 \pm 0.017	2.789 \pm 0.130	0.668 \pm 0.035	0.381\pm0.002	0.053\pm0.001	0.412 \pm 0.003	2.458\pm0.074	0.617 \pm 0.001	
	96	0.493 \pm 0.054	0.074 \pm 0.010	0.478 \pm 0.019	2.834 \pm 0.081	0.701 \pm 0.038	0.440\pm0.029	0.055\pm0.006	0.445 \pm 0.012	2.579 \pm 0.078	0.663 \pm 0.022	
ETM2	288	0.579 \pm 0.030	0.070 \pm 0.013	0.513 \pm 0.012	2.851 \pm 0.060	0.760 \pm 0.020	0.515\pm0.003	0.041\pm0.002	0.479 \pm 0.004	2.604 \pm 0.049	0.718 \pm 0.002	
	672	0.544\pm0.013	0.036 \pm 0.001	0.501 \pm 0.005	2.788 \pm 0.062	0.737\pm0.009	0.554 \pm 0.013	0.031\pm0.002	0.501 \pm 0.009	2.728 \pm 0.044	0.744 \pm 0.009	
	AVG	0.488 \pm 0.065	0.070 \pm 0.017	0.472 \pm 0.032	2.765 \pm 0.095	0.696 \pm 0.047	0.448\pm0.070	0.053\pm0.016	0.446 \pm 0.036	2.565 \pm 0.093	0.667\pm0.053	
	24	0.161 \pm 0.013	0.078 \pm 0.010	0.268 \pm 0.010	1.081 \pm 0.039	0.401 \pm 0.016	0.148\pm0.005	0.057\pm0.005	0.259 \pm 0.005	1.054 \pm 0.041	0.385\pm0.007	
	48	0.217 \pm 0.012	0.080 \pm 0.005	0.308 \pm 0.009	1.196 \pm 0.046	0.466 \pm 0.013	0.182\pm0.006	0.041\pm0.009	0.279 \pm 0.007	1.094 \pm 0.033	0.426\pm0.007	
ETTm2	96	0.252 \pm 0.029	0.058 \pm 0.008	0.324 \pm 0.015	1.302 \pm 0.024	0.502 \pm 0.028	0.217\pm0.003	0.030\pm0.006	0.298 \pm 0.004	1.158 \pm 0.019	0.466\pm0.003	
	288	0.319 \pm 0.005	0.027 \pm 0.004	0.362 \pm 0.003	1.407 \pm 0.029	0.565 \pm 0.005	0.313\pm0.001	0.019\pm0.005	0.354 \pm 0.001	1.307 \pm 0.013	0.559\pm0.001	
	672	0.408\pm0.002	0.017 \pm 0.003	0.410 \pm 0.001	1.577 \pm 0.014	0.639\pm0.001	0.409 \pm 0.003	0.012 \pm 0.004	0.409 \pm 0.002	1.538 \pm 0.047	0.640 \pm 0.002	
	AVG	0.271 \pm 0.078	0.052 \pm 0.024	0.334 \pm 0.044	1.313 \pm 0.156	0.514 \pm 0.075	0.254\pm0.087	0.032\pm0.015	0.320 \pm 0.050	1.230 \pm 0.161	0.495\pm0.084	

Table 13: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETM1, ETM2, Exchange, Traffic, and Weather datasets and Autoformer [37]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thumt/Autoformer>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 6.98%, TAM: 24.24%, MAE: 3.38%, MAPE: 3.76%, and RMSE: 3.12%. The maximum improvement of AliO over the baseline is MSE: 27.90%, TAM: 81.18%, MAE: 15.17%, MAPE: 15.42%, and RMSE: 8.58%. ECL, ETTh1, ETTh2, ETM1, and ETM2 are in Tab. 12.

Models	Method	Baseline						Autoformer			
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	
Exchange	96	0.155 \pm 0.012	0.031 \pm 0.016	0.286 \pm 0.011	1.700 \pm 0.053	0.394 \pm 0.015	0.139\pm0.005	0.018\pm0.007	0.270\pm0.005	1.648\pm0.010	0.373\pm0.007
	192	0.284 \pm 0.017	0.014\pm0.004	0.389 \pm 0.009	2.345 \pm 0.025	0.532 \pm 0.016	0.275\pm0.012	0.015 \pm 0.008	0.379\pm0.009	2.338\pm0.025	0.525\pm0.011
	336	0.447 \pm 0.041	0.020 \pm 0.007	0.496 \pm 0.023	3.403 \pm 0.130	0.668 \pm 0.031	0.436\pm0.012	0.011\pm0.000	0.488\pm0.007	3.369\pm0.002	0.660\pm0.009
	720	1.110 \pm 0.035	0.037 \pm 0.044	0.814\pm0.022	6.640 \pm 0.123	1.053 \pm 0.017	0.800\pm0.011	0.007\pm0.002	1.079 \pm 0.022	6.627\pm0.094	1.039 \pm 0.011
	AVG	0.499 \pm 0.329	0.025 \pm 0.008	0.496\pm0.177	3.522 \pm 1.699	0.662 \pm 0.220	0.413\pm0.221	0.013\pm0.004	0.554 \pm 0.280	3.495\pm1.707	0.649 \pm 0.221
Traffic	96	0.637 \pm 0.018	0.051 \pm 0.005	0.400 \pm 0.014	4.222 \pm 0.261	0.798 \pm 0.011	0.613\pm0.009	0.041\pm0.003	0.375\pm0.002	3.782\pm0.014	0.783\pm0.006
	192	0.626 \pm 0.009	0.055 \pm 0.006	0.389 \pm 0.006	4.104\pm0.090	0.791 \pm 0.006	0.621\pm0.008	0.051\pm0.005	0.386 \pm 0.006	4.130 \pm 0.079	0.788 \pm 0.005
	336	0.623 \pm 0.006	0.042\pm0.002	0.386 \pm 0.005	4.207\pm0.091	0.789 \pm 0.004	0.614\pm0.003	0.048 \pm 0.006	0.379\pm0.003	4.313 \pm 0.167	0.784 \pm 0.002
	720	0.651 \pm 0.010	0.045 \pm 0.004	0.398 \pm 0.006	4.326 \pm 0.033	0.807 \pm 0.006	0.648\pm0.005	0.039 \pm 0.001	0.386 \pm 0.003	3.970\pm0.063	0.805 \pm 0.003
	AVG	0.634 \pm 0.010	0.048 \pm 0.005	0.393 \pm 0.005	4.215 \pm 0.070	0.796 \pm 0.006	0.624\pm0.013	0.045\pm0.004	0.382 \pm 0.004	4.049\pm0.175	0.790 \pm 0.008
Weather	96	0.269 \pm 0.032	0.069 \pm 0.011	0.340 \pm 0.023	13.016\pm1.557	0.518 \pm 0.031	0.224\pm0.009	0.051\pm0.003	0.288 \pm 0.011	13.076 \pm 0.455	0.474\pm0.010
	192	0.298 \pm 0.013	0.055 \pm 0.003	0.356 \pm 0.008	14.001\pm0.960	0.546 \pm 0.012	0.282\pm0.007	0.043\pm0.005	0.332 \pm 0.006	15.517 \pm 0.589	0.531\pm0.007
	336	0.367 \pm 0.026	0.046 \pm 0.006	0.398 \pm 0.020	13.587\pm2.218	0.606 \pm 0.021	0.338\pm0.011	0.045\pm0.014	0.368 \pm 0.008	14.002 \pm 0.378	0.581\pm0.010
	720	0.434 \pm 0.014	0.056 \pm 0.004	0.441 \pm 0.013	11.666\pm0.645	0.659 \pm 0.011	0.401\pm0.005	0.027\pm0.007	0.410 \pm 0.040	12.468 \pm 0.723	0.633\pm0.004
	AVG	0.342 \pm 0.057	0.056 \pm 0.007	0.384 \pm 0.035	13.068\pm0.788	0.582 \pm 0.049	0.311\pm0.058	0.042\pm0.008	0.350 \pm 0.040	13.766 \pm 1.028	0.555\pm0.053

Table 14: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETThm1, ETThm2, Exchange, ILI, Traffix, and Weather datasets and DLinear [40]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/vivva/DLinear>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 5.62%, TAM: 36.21%, MAE: -3.82%, MAPE: 2.25%, and RMSE: 0.79%. The maximum improvement of AliO over the baseline is MSE: 36.07%, TAM: 77.73%, MAE: 8.21%, MAPE: 15.19%, and RMSE: 5.61%. Exchange ILI Traffic Weather are in Tab. 15.

Models	Method	Baseline						AliO					
		Metric	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	
ECL	96	0.140±0.000	0.017±0.000	0.237±0.000	2.149±0.005	0.374±0.000	0.140±0.000	0.013±0.000	0.237±0.000	2.149±0.003	0.374±0.000	0.374±0.000	
	192	0.153±0.000	0.013±0.000	0.250±0.000	2.300±0.003	0.391±0.000	0.153±0.000	0.010±0.000	0.250±0.000	2.301±0.001	0.391±0.000	0.391±0.000	
	336	0.169±0.000	0.011±0.000	0.268±0.000	2.283±0.004	0.411±0.000	0.169±0.000	0.008±0.000	0.267±0.000	2.283±0.001	0.411±0.000	0.411±0.000	
	720	0.204±0.000	0.011±0.001	0.301±0.000	2.457±0.002	0.451±0.000	0.203±0.000	0.008±0.001	0.300±0.000	2.451±0.004	0.451±0.000	0.451±0.000	
	AVG	0.166±0.021	0.013±0.002	0.264±0.021	2.297±0.098	0.407±0.026	0.166±0.021	0.010±0.002	0.264±0.021	2.296±0.096	0.407±0.026	0.407±0.026	
ETTh1	96	0.371±0.000	0.028±0.001	0.395±0.001	8.691±0.011	0.609±0.000	0.369±0.000	0.019±0.000	0.392±0.000	8.743±0.003	0.608±0.000	0.608±0.000	
	192	0.408±0.002	0.028±0.002	0.419±0.002	8.481±0.081	0.638±0.002	0.404±0.000	0.015±0.000	0.413±0.000	8.496±0.006	0.635±0.000	0.635±0.000	
	336	0.435±0.002	0.024±0.005	0.439±0.003	8.545±0.053	0.660±0.001	0.432±0.000	0.013±0.000	0.435±0.000	8.489±0.001	0.658±0.000	0.658±0.000	
	720	0.474±0.001	0.022±0.003	0.493±0.001	9.459±0.056	0.689±0.001	0.469±0.000	0.010±0.000	0.488±0.000	9.429±0.001	0.685±0.000	0.685±0.000	
	AVG	0.422±0.034	0.025±0.003	0.436±0.032	8.794±0.350	0.649±0.026	0.419±0.033	0.014±0.003	0.432±0.032	8.789±0.343	0.646±0.025	0.646±0.025	
ETTh2	96	0.291±0.003	0.069±0.016	0.354±0.002	1.359±0.048	0.539±0.003	0.290±0.006	0.046±0.010	0.353±0.006	1.321±0.028	0.538±0.006	0.538±0.006	
	192	0.381±0.008	0.049±0.005	0.416±0.006	1.369±0.007	0.617±0.007	0.369±0.007	0.023±0.004	0.405±0.006	1.376±0.022	0.607±0.006	0.607±0.006	
	336	0.438±0.011	0.039±0.001	0.456±0.007	1.494±0.008	0.662±0.008	0.454±0.009	0.009	0.505±0.027	0.465±0.004	1.497±0.041	0.674±0.007	
	720	0.687±0.044	0.057±0.020	0.586±0.018	1.605±0.033	0.828±0.026	0.672±0.025	0.013±0.002	0.577±0.013	1.544±0.019	0.820±0.015	0.820±0.015	
	AVG	0.449±0.131	0.054±0.010	0.453±0.076	1.457±0.090	0.662±0.095	0.446±0.128	0.033±0.014	0.450±0.075	1.434±0.080	0.660±0.093	0.660±0.093	
ETThm1	96	0.300±0.001	0.031±0.002	0.344±0.001	2.021±0.011	0.548±0.001	0.296±0.000	0.014±0.000	0.338±0.000	1.983±0.001	0.544±0.000	0.544±0.000	
	192	0.338±0.000	0.026±0.001	0.369±0.001	2.079±0.008	0.581±0.000	0.333±0.000	0.010±0.000	0.361±0.000	2.068±0.001	0.577±0.000	0.577±0.000	
	336	0.369±0.000	0.020±0.001	0.386±0.001	2.131±0.008	0.608±0.000	0.367±0.000	0.008±0.000	0.382±0.000	2.124±0.001	0.606±0.000	0.606±0.000	
	720	0.427±0.000	0.019±0.001	0.442±0.001	2.240±0.018	0.653±0.000	0.422±0.000	0.006±0.000	0.416±0.000	2.237±0.001	0.650±0.000	0.650±0.000	
	AVG	0.358±0.041	0.024±0.004	0.380±0.025	2.118±0.072	0.597±0.034	0.354±0.042	0.010±0.002	0.374±0.025	2.103±0.082	0.594±0.035	0.594±0.035	
ETThm2	96	0.171±0.002	0.034±0.002	0.265±0.004	1.047±0.009	0.413±0.002	0.166±0.001	0.018±0.001	0.258±0.001	1.056±0.003	0.407±0.001	0.407±0.001	
	192	0.233±0.004	0.031±0.004	0.312±0.007	1.153±0.024	0.483±0.004	0.229±0.002	0.015±0.001	0.307±0.002	1.162±0.005	0.478±0.002	0.478±0.002	
	336	0.311±0.022	0.053±0.023	0.366±0.017	1.325±0.085	0.557±0.019	0.284±0.005	0.026±0.007	0.344±0.004	1.274±0.018	0.533±0.005	0.533±0.005	
	720	0.443±0.012	0.030±0.003	0.453±0.008	1.315±0.019	0.665±0.009	0.394±0.004	0.020±0.005	0.415±0.003	1.384±0.007	0.628±0.003	0.628±0.003	
	AVG	0.289±0.091	0.037±0.009	0.349±0.062	1.210±0.104	0.530±0.083	0.268±0.075	0.020±0.004	0.331±0.051	1.219±0.110	0.512±0.072	0.512±0.072	

Table 15: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Exchange, ILI, Traffix, and Weather datasets and DLinear [40]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/vivva/DLinear>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 5.62%, TAM: 36.21%, MAE: -3.82%, MAPE: 2.25%, and RMSE: 0.79%. The maximum improvement of AliO over the baseline is MSE: 36.07%, TAM: 77.73%, MAE: 8.21%, MAPE: 15.19%, and RMSE: 5.61%. ECL, ETTh1, ETTh2, ETTm1, and ETTm2 are in Tab. 14.

Models	Method	DLinear						AliO			
		Metric	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow
Exchange	96	0.086 \pm 0.006	0.017 \pm 0.000	0.208 \pm 0.008	1.198 \pm 0.036	0.293 \pm 0.010	0.078\pm0.000	0.015\pm0.000	0.201\pm0.000	1.120\pm0.001	0.280\pm0.000
	192	0.160 \pm 0.002	0.015 \pm 0.001	0.295 \pm 0.002	1.584\pm0.033	0.400 \pm 0.003	0.157\pm0.002	0.014\pm0.001	0.291 \pm 0.019	0.396 \pm 0.002	
	336	0.330 \pm 0.032	0.012\pm0.005	0.434 \pm 0.016	2.120\pm0.139	0.574 \pm 0.028	0.320\pm0.034	0.012 \pm 0.003	0.425 \pm 0.022	2.222 \pm 0.207	
	720	0.833 \pm 0.129	0.033\pm0.017	0.689 \pm 0.050	2.298 \pm 0.441	0.910 \pm 0.072	0.822\pm0.135	0.054 \pm 0.033	0.679 \pm 0.051	2.186\pm0.258	
	AVG	0.352 \pm 0.260	0.019\pm0.007	0.407 \pm 0.163	1.800 \pm 0.390	0.544 \pm 0.209	0.344\pm0.259	0.024 \pm 0.016	0.399 \pm 0.161	1.781\pm0.407	
	24	2.335 \pm 0.149	0.196 \pm 0.039	1.078 \pm 0.060	4.052 \pm 0.445	1.527 \pm 0.049	2.229\pm0.019	0.131\pm0.003	1.036\pm0.005	3.689\pm0.059	
ILI	36	2.072\pm0.026	0.144\pm0.009	1.018\pm0.012	2.497\pm0.075	1.439\pm0.009	0.2076 \pm 0.036	0.153 \pm 0.063	1.024 \pm 0.005	2.507 \pm 0.190	
	48	2.269 \pm 0.077	0.136 \pm 0.020	1.091 \pm 0.032	2.685 \pm 0.249	1.506 \pm 0.026	2.161\pm0.016	0.078\pm0.003	1.049\pm0.003	2.278\pm0.016	
	60	2.315 \pm 0.022	0.132 \pm 0.028	1.088 \pm 0.006	2.542 \pm 0.176	1.521 \pm 0.007	2.280\pm0.080	0.112 \pm 0.021	1.078\pm0.019	2.412\pm0.050	
	AVG	2.247 \pm 0.093	0.152 \pm 0.023	1.069 \pm 0.027	2.944 \pm 0.576	1.498 \pm 0.031	2.187\pm0.069	0.119 \pm 0.025	1.047\pm0.018	2.721\pm0.505	
	96	0.412 \pm 0.001	0.024 \pm 0.001	0.286\pm0.001	3.123 \pm 0.030	0.642\pm0.001	0.269\pm0.000	0.007\pm0.000	0.426 \pm 0.000	2.749\pm0.000	
	192	0.424 \pm 0.000	0.026 \pm 0.003	0.291\pm0.000	3.073 \pm 0.018	0.651\pm0.000	0.276\pm0.000	0.007\pm0.002	0.430 \pm 0.000	2.718\pm0.006	
Traffic	336	0.438 \pm 0.001	0.023 \pm 0.000	0.299\pm0.001	3.047 \pm 0.008	0.662\pm0.000	0.282\pm0.000	0.006\pm0.002	0.440 \pm 0.000	2.690\pm0.006	
	720	0.468 \pm 0.001	0.026 \pm 0.004	0.319\pm0.001	3.139 \pm 0.022	0.684 \pm 0.001	0.299\pm0.000	0.009\pm0.002	0.466 \pm 0.000	2.769\pm0.005	
	AVG	0.436 \pm 0.019	0.025 \pm 0.001	0.299\pm0.011	3.095 \pm 0.033	0.660\pm0.014	0.282\pm0.010	0.007\pm0.001	0.441 \pm 0.014	2.731\pm0.027	
	96	0.175\pm0.001	0.009 \pm 0.001	0.237 \pm 0.003	10.585\pm0.247	0.419\pm0.001	0.175 \pm 0.001	0.007\pm0.000	0.236\pm0.002	10.679 \pm 0.122	
	192	0.216\pm0.001	0.007 \pm 0.000	0.275 \pm 0.001	10.767\pm0.080	0.465\pm0.001	0.217 \pm 0.000	0.005\pm0.000	0.273\pm0.000	10.893 \pm 0.009	
	AVG	0.245 \pm 0.050	0.007 \pm 0.001	0.299 \pm 0.043	10.993\pm0.380	0.492 \pm 0.051	0.244\pm0.049	0.005\pm0.001	0.295\pm0.041	11.184 \pm 0.424	
Weather	96	0.175\pm0.001	0.009 \pm 0.001	0.237 \pm 0.003	10.585\pm0.247	0.419\pm0.001	0.175 \pm 0.001	0.007\pm0.000	0.236\pm0.002	10.679 \pm 0.122	
	192	0.216\pm0.001	0.007 \pm 0.000	0.275 \pm 0.001	10.767\pm0.080	0.465\pm0.001	0.217 \pm 0.000	0.005\pm0.000	0.273\pm0.000	10.893 \pm 0.009	
	336	0.264 \pm 0.002	0.007 \pm 0.000	0.316 \pm 0.003	11.698\pm0.232	0.513 \pm 0.002	0.262\pm0.000	0.004\pm0.000	0.310 \pm 0.005	0.511\pm0.000	
	720	0.326 \pm 0.001	0.006 \pm 0.000	0.367 \pm 0.002	10.920\pm0.188	0.571 \pm 0.001	0.324\pm0.000	0.003\pm0.000	0.362 \pm 0.000	11.236 \pm 0.009	
	AVG	0.326 \pm 0.019	0.025 \pm 0.001	0.299 \pm 0.001	10.993\pm0.380	0.492 \pm 0.051	0.244\pm0.049	0.005\pm0.001	0.295\pm0.041	11.184 \pm 0.424	

Table 16: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETM1, ETM2, ILI, Traffix, and Weather datasets and PatchTST [33]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/yuguinie98/PatchTST>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 2.58%, TAM: 35.69%, MAE: 2.42%, MAPE: 4.40%, and RMSE: 1.34%. The maximum improvement of AliO over the baseline is MSE: 20.93%, TAM: 60.37%, MAE: 14.44%, MAPE: 29.81%, and RMSE: 11.01%. ILI, Traffic, and Weather are in Tab. 17.

Models	Method	Baseline						AliO			
		Metric	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow
ECL	96	0.130\pm0.000	0.030 \pm 0.000	0.223 \pm 0.000	2.332 \pm 0.034	0.360\pm0.000	0.130 \pm 0.000	0.016\pm0.000	0.221\pm0.000	2.276\pm0.006	0.361 \pm 0.000
	192	0.149 \pm 0.001	0.032 \pm 0.002	0.241 \pm 0.001	2.488 \pm 0.040	0.386 \pm 0.001	0.148\pm0.001	0.021\pm0.000	0.238\pm0.000	2.462\pm0.004	0.385\pm0.001
	336	0.166 \pm 0.000	0.037 \pm 0.001	0.260 \pm 0.001	2.493 \pm 0.008	0.408 \pm 0.001	0.165\pm0.001	0.028\pm0.001	0.257\pm0.000	2.468\pm0.008	0.406 \pm 0.001
	720	0.203 \pm 0.001	0.049 \pm 0.002	0.293 \pm 0.001	2.583 \pm 0.027	0.451 \pm 0.001	0.202 \pm 0.001	0.030 \pm 0.000	0.289 \pm 0.001	2.554 \pm 0.012	0.449 \pm 0.001
	AVG	0.162 \pm 0.024	0.037 \pm 0.007	0.254 \pm 0.023	2.474 \pm 0.081	0.401 \pm 0.030	0.161\pm0.024	0.024\pm0.005	0.251\pm0.023	2.440\pm0.091	0.400 \pm 0.029
ETTh1	96	0.379 \pm 0.000	0.065 \pm 0.002	0.401 \pm 0.000	9.413 \pm 0.032	0.616 \pm 0.000	0.378\pm0.001	0.053\pm0.002	0.401\pm0.001	9.358\pm0.026	0.615\pm0.001
	192	0.412 \pm 0.000	0.063 \pm 0.002	0.420 \pm 0.000	9.490 \pm 0.037	0.642 \pm 0.000	0.411\pm0.000	0.050\pm0.002	0.419\pm0.000	9.454\pm0.027	0.641\pm0.000
	336	0.435 \pm 0.002	0.072 \pm 0.007	0.436 \pm 0.001	9.524 \pm 0.066	0.659 \pm 0.001	0.432\pm0.001	0.045\pm0.002	0.434\pm0.000	9.425\pm0.038	0.657\pm0.000
	720	0.448 \pm 0.003	0.103 \pm 0.013	0.465 \pm 0.002	10.184 \pm 0.163	0.669 \pm 0.002	0.439\pm0.003	0.042\pm0.005	0.461\pm0.002	9.896\pm0.092	0.663\pm0.002
	AVG	0.418 \pm 0.023	0.076 \pm 0.014	0.431 \pm 0.021	9.653 \pm 0.277	0.646 \pm 0.018	0.415\pm0.021	0.048\pm0.004	0.429\pm0.020	9.533\pm0.190	0.644\pm0.017
ETTh2	96	0.276 \pm 0.000	0.067 \pm 0.001	0.338 \pm 0.000	1.378 \pm 0.002	0.525 \pm 0.000	0.275\pm0.000	0.055\pm0.001	0.337\pm0.000	1.368\pm0.003	0.525\pm0.000
	192	0.336\pm0.000	0.062 \pm 0.001	0.378 \pm 0.000	1.510 \pm 0.003	0.580\pm0.000	0.337 \pm 0.000	0.051\pm0.001	0.377\pm0.001	1.495\pm0.024	0.580 \pm 0.000
	336	0.361 \pm 0.000	0.060 \pm 0.002	0.401 \pm 0.001	1.700 \pm 0.011	0.601 \pm 0.000	0.360\pm0.000	0.048\pm0.002	0.399\pm0.002	1.672\pm0.027	0.600\pm0.000
	720	0.391\pm0.000	0.055 \pm 0.002	0.429 \pm 0.000	2.013 \pm 0.003	0.625\pm0.000	0.391 \pm 0.001	0.044\pm0.002	0.429\pm0.001	2.010 \pm 0.003	0.625 \pm 0.001
	AVG	0.341 \pm 0.038	0.061 \pm 0.004	0.387 \pm 0.030	1.650 \pm 0.214	0.583 \pm 0.033	0.341\pm0.038	0.050\pm0.004	0.386\pm0.030	1.636 \pm 0.216	0.583\pm0.033
ETM1	96	0.290 \pm 0.001	0.052 \pm 0.001	0.342 \pm 0.001	2.175 \pm 0.015	0.538 \pm 0.001	0.285\pm0.001	0.029\pm0.000	0.334\pm0.001	2.102\pm0.015	0.534\pm0.001
	192	0.334 \pm 0.002	0.049 \pm 0.001	0.370 \pm 0.002	2.302 \pm 0.014	0.578 \pm 0.002	0.329\pm0.002	0.035\pm0.001	0.364\pm0.001	2.241\pm0.001	0.574\pm0.001
	336	0.366\pm0.001	0.049 \pm 0.001	0.391 \pm 0.001	2.350 \pm 0.014	0.605\pm0.001	0.367 \pm 0.002	0.026\pm0.000	0.386\pm0.001	2.284\pm0.008	0.606 \pm 0.002
	720	0.418 \pm 0.005	0.052 \pm 0.002	0.423 \pm 0.004	2.452\pm0.026	0.646 \pm 0.004	0.415\pm0.002	0.037\pm0.001	0.419\pm0.001	2.459 \pm 0.016	0.644\pm0.001
	AVG	0.352 \pm 0.042	0.050 \pm 0.001	0.382 \pm 0.026	2.320 \pm 0.089	0.592 \pm 0.035	0.349\pm0.043	0.032\pm0.004	0.376\pm0.028	2.271\pm0.114	0.589\pm0.036
ETM2	96	0.164 \pm 0.001	0.051 \pm 0.001	0.252 \pm 0.000	1.057 \pm 0.004	0.405 \pm 0.001	0.162\pm0.000	0.036\pm0.001	0.251\pm0.000	1.053\pm0.001	0.403\pm0.000
	192	0.220 \pm 0.000	0.059 \pm 0.002	0.292 \pm 0.001	1.194\pm0.004	0.469 \pm 0.000	0.218\pm0.001	0.033\pm0.001	0.289\pm0.001	1.194 \pm 0.006	0.467 \pm 0.001
	336	0.275 \pm 0.001	0.063 \pm 0.000	0.329 \pm 0.000	1.318 \pm 0.001	0.525 \pm 0.001	0.274\pm0.000	0.045\pm0.001	0.327\pm0.000	1.316\pm0.003	0.523 \pm 0.000
	720	0.368 \pm 0.002	0.063 \pm 0.002	0.384 \pm 0.001	1.478\pm0.003	0.606 \pm 0.001	0.366\pm0.001	0.044\pm0.000	0.383\pm0.001	1.480 \pm 0.002	0.605\pm0.001
	AVG	0.257 \pm 0.067	0.059 \pm 0.004	0.314 \pm 0.043	1.262 \pm 0.139	0.501 \pm 0.066	0.255\pm0.067	0.039\pm0.005	0.312\pm0.044	1.261\pm0.141	0.500 \pm 0.067

Table 17: Full results of the proposed AliO method on the ECL, ETTm1, ETTm2, ILI, Traffix, and Weather datasets and PatchTST [33]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/yuqinie98/PatchTST>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 2.58%, TAM: 35.69%, MAE: 2.42%, MAPE: 4.40%, and RMSE: 1.34%. The maximum improvement of AliO over the baseline is MSE: 20.93%, TAM: 60.37%, MAE: 14.44%, MAPE: 29.81%, and RMSE: 11.01%. ECL, ETTm1, ETTm2, ETTm1, and ETTm2 are in Tab. 16.

Models	Method	PatchTST						AliO		
		Baseline			PatchTST			MAE \downarrow	MAPE \downarrow	RMSE \downarrow
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MSE \downarrow	RMSE \downarrow				
ILI	24	2.132 \pm 0.179	0.128 \pm 0.015	0.917 \pm 0.064	4.121 \pm 0.100	1.459 \pm 0.062	1.686\pm0.053	0.811\pm0.003	3.004\pm0.048	1.298\pm0.020
	36	1.559 \pm 0.045	0.106 \pm 0.017	0.830 \pm 0.013	2.305 \pm 0.216	1.248 \pm 0.018	1.391\pm0.047	0.944\pm0.002	0.767\pm0.004	1.751\pm0.077
	48	1.736 \pm 0.078	0.099 \pm 0.009	0.900 \pm 0.021	2.306 \pm 0.099	1.317 \pm 0.030	1.431\pm0.109	0.942\pm0.001	0.774\pm0.034	1.682\pm0.049
	60	1.824 \pm 0.140	0.107 \pm 0.005	0.923 \pm 0.046	2.476 \pm 0.098	1.349 \pm 0.053	1.479\pm0.097	0.942\pm0.002	0.790\pm0.034	1.738\pm0.096
	AVG	1.813 \pm 0.186	0.110 \pm 0.010	0.893 \pm 0.033	2.802 \pm 0.684	1.343 \pm 0.068	1.497\pm0.101	0.946\pm0.005	0.785\pm0.015	2.044\pm0.497
Traffic	96	0.358 \pm 0.000	0.040 \pm 0.000	0.245 \pm 0.000	2.553 \pm 0.018	0.598 \pm 0.000	0.357\pm0.000	0.229\pm0.001	0.242\pm0.000	2.472\pm0.005
	192	0.378\pm0.001	0.039 \pm 0.000	0.254 \pm 0.000	2.570 \pm 0.022	0.615\pm0.001	0.378 \pm 0.000	0.222 \pm 0.000	0.248 \pm 0.000	2.482 \pm 0.001
	336	0.391 \pm 0.001	0.040 \pm 0.001	0.262 \pm 0.001	2.620 \pm 0.004	0.626 \pm 0.001	0.390\pm0.001	0.227\pm0.001	0.257\pm0.001	2.542\pm0.003
	720	0.431 \pm 0.000	0.044 \pm 0.001	0.285 \pm 0.000	2.845 \pm 0.018	0.657 \pm 0.000	0.427\pm0.001	0.229\pm0.000	0.278\pm0.000	2.707\pm0.017
	AVG	0.390 \pm 0.024	0.041 \pm 0.002	0.262 \pm 0.013	2.647 \pm 0.105	0.624 \pm 0.019	0.388\pm0.023	0.227\pm0.003	0.256\pm0.012	2.551\pm0.084
Weather	96	0.152 \pm 0.002	0.020 \pm 0.000	0.201 \pm 0.003	11.697\pm0.303	0.390 \pm 0.003	0.151\pm0.000	0.155\pm0.000	0.197\pm0.000	11.913 \pm 0.090
	192	0.196 \pm 0.001	0.018 \pm 0.001	0.242 \pm 0.001	13.084\pm0.650	0.443 \pm 0.002	0.196\pm0.001	0.113\pm0.000	0.240\pm0.001	13.325 \pm 0.405
	336	0.247 \pm 0.000	0.017 \pm 0.000	0.282 \pm 0.000	14.374 \pm 0.254	0.497 \pm 0.000	0.246\pm0.000	0.112\pm0.000	0.279\pm0.001	14.242\pm0.366
	720	0.320\pm0.001	0.016 \pm 0.000	0.334 \pm 0.001	13.976\pm0.119	0.566\pm0.000	0.321 \pm 0.000	0.097\pm0.000	0.329\pm0.000	14.243\pm0.026
	AVG	0.229 \pm 0.056	0.018 \pm 0.001	0.265 \pm 0.044	13.283\pm0.919	0.474 \pm 0.058	0.228\pm0.056	0.012\pm0.003	0.261\pm0.044	13.431 \pm 0.853

Table 18: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETM1, ETM2, Exchange, Traffic, ILI, and Weather datasets and TimesNet [36]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thuml/TimesNet>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 3.42%, TAM: 33.36%, MAE: 1.81%, MAPE: 4.01%, and RMSE: 1.76%. The maximum improvement of AliO over the baseline is MSE: 29.03%, TAM: 51.96%, MAE: 9.34%, MAPE: 23.09%, and RMSE: 16.56%. Exchange, Traffic, ILI, and Weather are in Tab. 19.

Models	TimesNet						AliO					
	Method	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	
ECL	96	0.168 \pm 0.001	0.038 \pm 0.001	0.271 \pm 0.001	2.666 \pm 0.048	0.409 \pm 0.001	0.166\pm0.001	0.269\pm0.001	0.263\pm0.001	2.563\pm0.067	0.408\pm0.001	
	192	0.186 \pm 0.001	0.038 \pm 0.002	0.288 \pm 0.002	2.787 \pm 0.097	0.431 \pm 0.001	0.183\pm0.001	0.233\pm0.000	0.284\pm0.001	2.712\pm0.013	0.428\pm0.002	
	336	0.202 \pm 0.005	0.041 \pm 0.002	0.302 \pm 0.003	2.944\pm0.075	0.449 \pm 0.006	0.196\pm0.001	0.205\pm0.001	0.297\pm0.002	2.944 \pm 0.091	0.443\pm0.002	
	720	0.228 \pm 0.012	0.044 \pm 0.005	0.322 \pm 0.011	2.883\pm0.092	0.477 \pm 0.013	0.219\pm0.002	0.339\pm0.003	0.313\pm0.001	2.933 \pm 0.027	0.468\pm0.002	
ETTh1	AVG	0.196 \pm 0.020	0.040 \pm 0.002	0.296 \pm 0.017	2.820 \pm 0.094	0.442 \pm 0.022	0.191\pm0.017	0.028\pm0.006	0.291\pm0.014	2.788\pm0.143	0.436\pm0.020	
	96	0.409\pm0.010	0.055 \pm 0.001	0.425\pm0.006	10.015\pm0.311	0.640\pm0.008	0.410 \pm 0.010	0.045\pm0.001	0.426 \pm 0.006	10.036 \pm 0.280	0.641 \pm 0.008	
	192	0.469 \pm 0.006	0.054 \pm 0.003	0.460 \pm 0.004	10.999 \pm 0.070	0.685 \pm 0.004	0.461\pm0.005	0.030\pm0.002	0.455\pm0.001	10.429 \pm 0.286	0.679\pm0.003	
	336	0.507 \pm 0.013	0.046 \pm 0.003	0.478 \pm 0.008	10.926 \pm 0.266	0.712 \pm 0.009	0.497\pm0.003	0.027\pm0.001	0.472\pm0.002	10.342 \pm 0.156	0.705\pm0.002	
ETTh2	720	0.521 \pm 0.006	0.046 \pm 0.003	0.497 \pm 0.003	10.981 \pm 0.954	0.722 \pm 0.004	0.502\pm0.007	0.027\pm0.001	0.487\pm0.003	10.451\pm0.332	0.708\pm0.005	
	AVG	0.476 \pm 0.039	0.050 \pm 0.004	0.465 \pm 0.024	10.730 \pm 0.370	0.689 \pm 0.029	0.468\pm0.033	0.032\pm0.007	0.460\pm0.020	10.314 \pm 0.148	0.683\pm0.024	
	96	0.328 \pm 0.014	0.067 \pm 0.006	0.370 \pm 0.010	1.607 \pm 0.053	0.573 \pm 0.012	0.318\pm0.003	0.041\pm0.006	0.362\pm0.002	1.500\pm0.021	0.564\pm0.003	
	192	0.429 \pm 0.030	0.089 \pm 0.034	0.424 \pm 0.019	1.646 \pm 0.069	0.655 \pm 0.023	0.398\pm0.011	0.044\pm0.002	0.408\pm0.005	1.626\pm0.040	0.631\pm0.008	
ETM1	336	0.452 \pm 0.013	0.085 \pm 0.023	0.453 \pm 0.009	1.826\pm0.034	0.672 \pm 0.010	0.448\pm0.002	0.051\pm0.003	0.447\pm0.002	1.839 \pm 0.052	0.669\pm0.001	
	720	0.454 \pm 0.006	0.075 \pm 0.025	0.463 \pm 0.006	2.177 \pm 0.158	0.673 \pm 0.005	0.446\pm0.016	0.036\pm0.005	0.459\pm0.010	2.064\pm0.132	0.668\pm0.012	
	AVG	0.416 \pm 0.046	0.079 \pm 0.008	0.428 \pm 0.032	1.814 \pm 0.201	0.643 \pm 0.037	0.402\pm0.047	0.043\pm0.005	0.419\pm0.034	1.757\pm0.192	0.633\pm0.038	
	96	0.334 \pm 0.005	0.052 \pm 0.001	0.374 \pm 0.003	2.366 \pm 0.011	0.578 \pm 0.004	0.328\pm0.005	0.029\pm0.001	0.368\pm0.002	2.308\pm0.045	0.572\pm0.004	
ETM2	192	0.386 \pm 0.000	0.045 \pm 0.001	0.399 \pm 0.001	2.478 \pm 0.070	0.622 \pm 0.000	0.381\pm0.001	0.033\pm0.002	0.397\pm0.001	2.458\pm0.045	0.618\pm0.001	
	336	0.429 \pm 0.007	0.044 \pm 0.002	0.427 \pm 0.003	2.593 \pm 0.091	0.655 \pm 0.005	0.409\pm0.003	0.022\pm0.001	0.417\pm0.001	2.483\pm0.014	0.640\pm0.003	
	720	0.499 \pm 0.004	0.042 \pm 0.002	0.465 \pm 0.003	2.801 \pm 0.051	0.706 \pm 0.003	0.475\pm0.001	0.020\pm0.001	0.452\pm0.002	2.686\pm0.023	0.689\pm0.001	
	AVG	0.412 \pm 0.054	0.045 \pm 0.003	0.416 \pm 0.030	2.560 \pm 0.144	0.640 \pm 0.042	0.398\pm0.048	0.026\pm0.005	0.409\pm0.027	2.484\pm0.121	0.630\pm0.038	
ETTh2	96	0.186 \pm 0.000	0.040 \pm 0.002	0.266 \pm 0.001	1.181 \pm 0.013	0.431 \pm 0.000	0.186\pm0.002	0.030\pm0.002	0.265\pm0.001	1.155\pm0.026	0.431\pm0.002	
	192	0.255 \pm 0.002	0.037 \pm 0.001	0.308 \pm 0.002	1.290\pm0.020	0.505 \pm 0.002	0.253\pm0.001	0.020\pm0.001	0.307\pm0.002	1.292 \pm 0.036	0.503\pm0.001	
	336	0.315\pm0.003	0.033 \pm 0.003	0.345\pm0.001	1.351 \pm 0.017	0.561\pm0.003	0.317 \pm 0.004	0.020 \pm 0.002	0.348 \pm 0.002	1.335\pm0.015	0.563 \pm 0.003	
	720	0.430 \pm 0.001	0.034 \pm 0.004	0.410 \pm 0.001	1.584 \pm 0.039	0.656 \pm 0.001	0.423\pm0.001	0.017 \pm 0.001	0.406 \pm 0.000	1.545 \pm 0.021	0.650 \pm 0.000	
ETM2	AVG	0.296 \pm 0.080	0.036 \pm 0.003	0.332 \pm 0.047	1.352 \pm 0.132	0.538 \pm 0.073	0.295\pm0.078	0.022\pm0.005	0.331\pm0.047	1.332 \pm 0.125	0.537\pm0.072	

Table 19: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Exchange, Traffic, ILI, and Weather datasets and TimesNet [36]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thumt/TimesNet>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 3.42%, TAM: 33.36%, MAE: 1.81%, MAPE: 4.01%, and RMSE: 1.76%. The maximum improvement of AliO over the baseline is MSE: 29.03%, TAM: 51.96%, MAE: 9.34%, MAPE: 23.09%, and RMSE: 16.56%. ECL, ETTh1, ETTh2, ETTm1, and ETTm2 are in Tab. 18.

Models	Method	TimesNet						AliO			
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	
Exchange	96	0.112 \pm 0.001	0.038 \pm 0.004	0.241 \pm 0.001	1.405 \pm 0.100	0.334 \pm 0.002	0.105\pm0.002	0.023\pm0.001	0.232\pm0.001	1.300\pm0.041	0.324\pm0.003
	192	0.217 \pm 0.008	0.036 \pm 0.004	0.337 \pm 0.005	1.951\pm0.061	0.466 \pm 0.009	0.207\pm0.002	0.020\pm0.000	0.330\pm0.001	2.002 \pm 0.054	0.455\pm0.003
	336	0.366 \pm 0.008	0.031 \pm 0.003	0.440 \pm 0.006	3.197\pm0.076	0.605 \pm 0.007	0.364\pm0.005	0.029\pm0.004	0.439\pm0.004	3.249 \pm 0.070	0.603\pm0.004
	720	0.964 \pm 0.025	0.033 \pm 0.005	0.746 \pm 0.012	6.519 \pm 0.188	0.982 \pm 0.013	0.944 \pm 0.034	0.024 \pm 0.004	0.740 \pm 0.015	6.473\pm0.189	0.972 \pm 0.017
	AVG	0.415 \pm 0.295	0.035 \pm 0.003	0.441 \pm 0.170	3.268 \pm 1.777	0.597 \pm 0.217	0.405\pm0.290	0.024\pm0.003	0.435\pm0.171	3.256 \pm 1.775	0.588\pm0.217
	96	0.593 \pm 0.007	0.042 \pm 0.001	0.313 \pm 0.002	2.957\pm0.073	0.770 \pm 0.004	0.589\pm0.003	0.028\pm0.001	0.310\pm0.001	2.798\pm0.051	0.767\pm0.002
Traffic	192	0.618 \pm 0.005	0.041 \pm 0.004	0.325 \pm 0.004	3.115 \pm 0.107	0.786 \pm 0.003	0.614 \pm 0.003	0.025 \pm 0.001	0.320 \pm 0.001	2.882 \pm 0.053	0.783 \pm 0.002
	336	0.631 \pm 0.008	0.041 \pm 0.005	0.334 \pm 0.006	3.420 \pm 0.219	0.794 \pm 0.005	0.448\pm0.128	0.026 \pm 0.001	0.303 \pm 0.018	2.712 \pm 0.320	0.663 \pm 0.092
	720	0.661 \pm 0.002	0.035 \pm 0.002	0.347 \pm 0.001	3.477 \pm 0.016	0.813 \pm 0.001	0.653\pm0.002	0.032 \pm 0.005	0.344 \pm 0.002	3.456 \pm 0.094	0.808 \pm 0.001
	AVG	0.626 \pm 0.022	0.040 \pm 0.003	0.330 \pm 0.011	3.242 \pm 0.192	0.791 \pm 0.014	0.576\pm0.069	0.028 \pm 0.003	0.319 \pm 0.014	2.962 \pm 0.261	0.755 \pm 0.050
	24	2.759 \pm 0.839	0.371 \pm 0.026	0.972 \pm 0.077	4.452 \pm 0.551	1.643 \pm 0.246	2.239\pm0.347	0.256\pm0.011	0.924 \pm 0.045	3.424 \pm 0.129	1.492 \pm 0.114
	36	1.949 \pm 0.033	0.330 \pm 0.031	0.919 \pm 0.006	2.976 \pm 0.224	1.396 \pm 0.012	1.734\pm0.025	0.262 \pm 0.027	0.846 \pm 0.007	2.508 \pm 0.167	1.317 \pm 0.010
ILI	48	1.976 \pm 0.112	0.305 \pm 0.030	0.896 \pm 0.029	2.906 \pm 0.050	1.405 \pm 0.040	1.911\pm0.033	0.263\pm0.016	0.862\pm0.015	2.686 \pm 0.047	1.382\pm0.012
	60	2.002 \pm 0.098	0.289 \pm 0.006	0.919 \pm 0.033	3.060 \pm 0.179	1.414 \pm 0.035	1.970\pm0.054	0.251\pm0.021	0.899 \pm 0.002	2.779 \pm 0.123	1.403\pm0.019
	AVG	2.171 \pm 0.304	0.324 \pm 0.028	0.926 \pm 0.025	3.348 \pm 0.572	1.465 \pm 0.092	1.963\pm0.162	0.258\pm0.004	0.883 \pm 0.027	2.849 \pm 0.309	1.399\pm0.056
	96	0.174\pm0.003	0.021 \pm 0.001	0.223 \pm 0.002	11.767 \pm 0.301	0.417\pm0.004	0.174 \pm 0.003	0.017\pm0.000	0.223\pm0.001	11.659\pm0.718	0.417 \pm 0.003
	192	0.231\pm0.005	0.017 \pm 0.002	0.271\pm0.004	14.158 \pm 0.953	0.481\pm0.006	0.237 \pm 0.007	0.014 \pm 0.001	0.276 \pm 0.006	13.831\pm0.810	0.487 \pm 0.007
	336	0.285 \pm 0.002	0.020 \pm 0.002	0.307 \pm 0.001	13.782\pm0.351	0.534 \pm 0.002	0.280\pm0.001	0.011 \pm 0.001	0.302\pm0.000	13.819 \pm 0.139	0.529\pm0.001
Weather	720	0.359 \pm 0.001	0.015 \pm 0.001	0.353 \pm 0.002	14.045\pm0.438	0.599 \pm 0.001	0.358\pm0.001	0.012 \pm 0.001	0.353 \pm 0.001	14.367 \pm 0.365	0.599\pm0.001
	AVG	0.262\pm0.061	0.018 \pm 0.002	0.289 \pm 0.043	13.438 \pm 0.871	0.508\pm0.060	0.262 \pm 0.060	0.014 \pm 0.002	0.289 \pm 0.042	13.419\pm0.930	0.508 \pm 0.059

Table 20: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETM1, ETM2, Solar, PEMSO3, PEMSO4, PEMSO7, PEMSO8, Exchange, Traffic, and Weather datasets and iTransformer [30]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thumt/iTransformer>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 6.59%, TAM: 28.04%, MAE: 5.41%, MAPE: 0.46%, and RMSE: 3.85%. The maximum improvement of AliO over the baseline is MSE: 88.52%, TAM: 60.37%, MAE: 73.75%, MAPE: 18.04%, and RMSE: 66.10%. Solar, PEMSO3, PEMSO4, PEMSO7, and PEMSO8 are in Tab. 21. Exchange, Traffic, and Weather are in Tab. 22.

Models	Method	Baseline						AliO			
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow
ECL	96	0.148 \pm 0.000	0.046 \pm 0.000	0.240 \pm 0.000	2.525 \pm 0.030	0.385 \pm 0.000	0.147\pm0.000	0.034\pm0.000	0.238\pm0.000	2.512\pm0.018	0.383\pm0.000
	192	0.165 \pm 0.001	0.042 \pm 0.000	0.256 \pm 0.001	2.732 \pm 0.033	0.406 \pm 0.001	0.160\pm0.000	0.031\pm0.000	0.250\pm0.000	2.671\pm0.023	0.400\pm0.000
	336	0.180 \pm 0.001	0.049 \pm 0.001	0.273 \pm 0.001	2.736\pm0.005	0.424 \pm 0.001	0.175\pm0.001	0.036\pm0.001	0.267\pm0.000	2.802\pm0.025	0.418\pm0.001
	720	0.211 \pm 0.000	0.063 \pm 0.000	0.301 \pm 0.000	3.068\pm0.024	0.459 \pm 0.000	0.207\pm0.001	0.025\pm0.001	0.294\pm0.001	3.073\pm0.032	0.455\pm0.001
	AVG	0.176 \pm 0.021	0.050 \pm 0.007	0.267 \pm 0.020	2.765 \pm 0.174	0.418 \pm 0.024	0.172\pm0.020	0.031\pm0.004	0.262\pm0.019	2.764\pm0.184	0.414\pm0.024
ETTh1	96	0.386 \pm 0.001	0.083 \pm 0.001	0.404 \pm 0.001	10.066 \pm 0.052	0.621 \pm 0.001	0.380\pm0.000	0.057\pm0.000	0.397\pm0.000	9.673\pm0.026	0.616\pm0.000
	192	0.443 \pm 0.001	0.083 \pm 0.001	0.437 \pm 0.001	9.867 \pm 0.093	0.666 \pm 0.001	0.431\pm0.000	0.064\pm0.001	0.428\pm0.000	9.624\pm0.060	0.657\pm0.000
	336	0.487 \pm 0.003	0.089 \pm 0.002	0.459 \pm 0.002	10.520 \pm 0.334	0.698 \pm 0.002	0.471\pm0.001	0.038\pm0.000	0.445\pm0.001	10.034\pm0.076	0.686\pm0.001
	720	0.506 \pm 0.007	0.098 \pm 0.001	0.492 \pm 0.003	11.807 \pm 0.649	0.711 \pm 0.005	0.471\pm0.008	0.048\pm0.002	0.469\pm0.004	11.258\pm0.051	0.687\pm0.006
	AVG	0.455 \pm 0.041	0.088 \pm 0.005	0.448 \pm 0.029	10.565 \pm 0.676	0.674 \pm 0.031	0.438\pm0.034	0.052\pm0.009	0.435\pm0.023	10.147\pm0.591	0.661\pm0.026
ETTh2	96	0.300 \pm 0.001	0.080 \pm 0.002	0.350 \pm 0.001	1.469 \pm 0.010	0.548 \pm 0.001	0.300\pm0.000	0.045\pm0.001	0.348\pm0.000	1.422\pm0.004	0.548\pm0.000
	192	0.378 \pm 0.000	0.076 \pm 0.001	0.398 \pm 0.001	1.596 \pm 0.014	0.615 \pm 0.000	0.375\pm0.001	0.058\pm0.002	0.396\pm0.000	1.560\pm0.006	0.612\pm0.001
	336	0.421 \pm 0.002	0.073 \pm 0.002	0.431 \pm 0.001	1.775 \pm 0.008	0.649 \pm 0.001	0.413\pm0.001	0.055\pm0.003	0.427\pm0.001	1.712\pm0.002	0.643\pm0.001
	720	0.429 \pm 0.001	0.069 \pm 0.002	0.447 \pm 0.000	2.018 \pm 0.012	0.655 \pm 0.001	0.419\pm0.002	0.050\pm0.002	0.441\pm0.001	1.981\pm0.024	0.647\pm0.001
	AVG	0.382 \pm 0.046	0.074 \pm 0.003	0.406 \pm 0.033	1.714 \pm 0.184	0.617 \pm 0.038	0.377\pm0.042	0.052\pm0.005	0.403\pm0.032	1.669\pm0.186	0.613\pm0.036
ETM1	96	0.343 \pm 0.003	0.067 \pm 0.001	0.377 \pm 0.001	2.354 \pm 0.012	0.586 \pm 0.002	0.330\pm0.001	0.037\pm0.000	0.361\pm0.000	2.142\pm0.005	0.575\pm0.001
	192	0.380 \pm 0.002	0.060 \pm 0.001	0.394 \pm 0.001	2.383 \pm 0.013	0.617 \pm 0.001	0.375\pm0.001	0.031\pm0.000	0.383\pm0.001	2.203\pm0.011	0.612\pm0.001
	336	0.418 \pm 0.000	0.058 \pm 0.001	0.418 \pm 0.000	2.443 \pm 0.006	0.647 \pm 0.000	0.408\pm0.001	0.037\pm0.000	0.406\pm0.000	2.302\pm0.005	0.639\pm0.001
	720	0.488 \pm 0.001	0.056 \pm 0.001	0.457 \pm 0.001	2.670 \pm 0.012	0.699 \pm 0.001	0.472\pm0.001	0.026\pm0.000	0.441\pm0.001	2.451\pm0.005	0.687\pm0.001
	AVG	0.407 \pm 0.048	0.060 \pm 0.004	0.412 \pm 0.027	2.462 \pm 0.111	0.637 \pm 0.037	0.396\pm0.046	0.033\pm0.004	0.398\pm0.026	2.275\pm0.104	0.628\pm0.037
ETTm2	96	0.185 \pm 0.001	0.050 \pm 0.001	0.270 \pm 0.001	1.169 \pm 0.009	0.430 \pm 0.001	0.184\pm0.000	0.038\pm0.000	0.267\pm0.000	1.160\pm0.002	0.428\pm0.000
	192	0.254 \pm 0.000	0.050 \pm 0.001	0.314 \pm 0.001	1.302 \pm 0.018	0.504 \pm 0.000	0.250\pm0.001	0.025\pm0.000	0.310\pm0.001	1.287\pm0.005	0.500\pm0.001
	336	0.315 \pm 0.004	0.049 \pm 0.006	0.352 \pm 0.003	1.411 \pm 0.005	0.562 \pm 0.004	0.312\pm0.001	0.022\pm0.000	0.348\pm0.001	1.399\pm0.003	0.559\pm0.001
	720	0.413 \pm 0.001	0.044 \pm 0.003	0.407 \pm 0.001	1.615 \pm 0.006	0.643 \pm 0.001	0.411\pm0.001	0.019\pm0.000	0.404\pm0.001	1.594\pm0.009	0.641\pm0.001
	AVG	0.292 \pm 0.075	0.048 \pm 0.002	0.336 \pm 0.045	1.374 \pm 0.146	0.534 \pm 0.070	0.289\pm0.075	0.026\pm0.007	0.332\pm0.045	1.360\pm0.142	0.532\pm0.070

Table 21: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Solar, PEMs03, PEMs04, PEMs07, PEMs08, Exchange, Traffix, and Weather datasets and iTransformer [30]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thumli/iTransformer>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 6.59%, TAM: 28.04%, MAE: 5.41%, MAPE: 0.46%, and RMSE: 3.85%. The maximum improvement of AliO over the baseline is MSE: 88.52%, TAM: 60.37%, MAE: 73.75%, MAPE: 18.04%, and RMSE: 66.10%. ECL, ETTh1, ETTh2, ETTm1, and ETTm2 are in Tab. 20. Exchange, Traffix, and Weather are in Tab. 22

Models	Method	Baseline						AliO			
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow
Solar	96	0.206 \pm 0.002	0.038 \pm 0.002	0.237 \pm 0.002	1.846 \pm 0.033	0.454 \pm 0.002	0.192\pm0.002	0.021\pm0.001	0.217\pm0.002	1.843\pm0.035	0.438\pm0.002
	192	0.237 \pm 0.001	0.040 \pm 0.000	0.263 \pm 0.001	1.976\pm0.014	0.487 \pm 0.001	0.225\pm0.001	0.020\pm0.000	0.241\pm0.001	1.980 \pm 0.008	0.474\pm0.001
	336	0.250 \pm 0.001	0.038 \pm 0.001	0.275 \pm 0.001	2.011\pm0.011	0.500 \pm 0.001	0.242\pm0.001	0.019\pm0.000	0.257\pm0.000	2.017 \pm 0.011	0.492\pm0.001
	720	0.251 \pm 0.000	0.035 \pm 0.000	0.275 \pm 0.000	2.066\pm0.025	0.501 \pm 0.000	0.247\pm0.001	0.016\pm0.000	0.261\pm0.000	2.092 \pm 0.012	0.497\pm0.001
	AVG	0.236 \pm 0.016	0.038 \pm 0.002	0.263 \pm 0.014	1.975\pm0.072	0.485 \pm 0.017	0.227\pm0.019	0.019\pm0.002	0.244\pm0.015	1.983 \pm 0.081	0.475\pm0.021
	12	0.069\pm0.000	0.048 \pm 0.000	0.175\pm0.001	1.417\pm0.006	0.263\pm0.001	0.069 \pm 0.000	0.028\pm0.000	0.175 \pm 0.000	1.424 \pm 0.006	0.263 \pm 0.000
PEMS03	24	0.098 \pm 0.001	0.052 \pm 0.000	0.209 \pm 0.001	1.671 \pm 0.011	0.313 \pm 0.001	0.098\pm0.000	0.041\pm0.000	0.209\pm0.000	1.663\pm0.006	0.313\pm0.001
	48	0.163 \pm 0.001	0.061 \pm 0.001	0.274 \pm 0.001	2.022 \pm 0.009	0.404 \pm 0.001	0.162\pm0.001	0.047\pm0.000	0.273\pm0.001	2.000\pm0.015	0.402\pm0.001
	96	0.918 \pm 0.310	0.117 \pm 0.026	0.720 \pm 0.127	3.747 \pm 0.531	0.944 \pm 0.162	0.576\pm0.044	0.080\pm0.009	0.575\pm0.028	3.383\pm0.266	0.759\pm0.029
	AVG	0.312 \pm 0.314	0.069 \pm 0.025	0.345 \pm 0.196	2.214 \pm 0.814	0.481 \pm 0.243	0.226 \pm 0.183	0.049 \pm 0.017	0.308 \pm 0.141	2.117 \pm 0.679	0.434 \pm 0.173
	12	0.081\pm0.000	0.042 \pm 0.000	0.188\pm0.000	1.283\pm0.007	0.284\pm0.000	0.082 \pm 0.000	0.033\pm0.000	0.190 \pm 0.001	1.294 \pm 0.013	0.286 \pm 0.000
	24	0.100\pm0.000	0.041 \pm 0.000	0.212\pm0.000	1.512\pm0.019	0.316\pm0.000	0.101 \pm 0.000	0.031\pm0.000	0.213 \pm 0.000	1.521 \pm 0.009	0.317 \pm 0.001
PEMS04	48	0.134 \pm 0.002	0.041 \pm 0.000	0.248 \pm 0.002	1.782 \pm 0.029	0.366 \pm 0.002	0.131\pm0.001	0.029\pm0.000	0.245\pm0.001	1.771\pm0.017	0.362\pm0.002
	96	0.169 \pm 0.001	0.041 \pm 0.000	0.280 \pm 0.000	2.090 \pm 0.015	0.411 \pm 0.001	0.166\pm0.002	0.028\pm0.000	0.277\pm0.002	2.081\pm0.008	0.407\pm0.003
	AVG	0.121 \pm 0.030	0.041 \pm 0.001	0.232 \pm 0.031	1.667\pm0.270	0.344 \pm 0.043	0.120\pm0.028	0.030\pm0.002	0.231\pm0.030	1.667 \pm 0.262	0.343\pm0.041
	12	0.067\pm0.000	0.044 \pm 0.000	0.164\pm0.001	1.670\pm0.003	0.258\pm0.000	0.070 \pm 0.001	0.036\pm0.001	0.168 \pm 0.001	1.706 \pm 0.017	0.264 \pm 0.001
	24	0.087\pm0.000	0.042 \pm 0.000	0.190\pm0.001	1.898\pm0.019	0.295\pm0.001	0.090 \pm 0.001	0.035\pm0.000	0.193 \pm 0.001	1.943 \pm 0.028	0.300 \pm 0.001
	48	0.995 \pm 0.054	0.020\pm0.019	0.832 \pm 0.032	1.540\pm0.702	0.997 \pm 0.027	0.114\pm0.001	0.031 \pm 0.001	0.218\pm0.002	2.158 \pm 0.017	0.338\pm0.002
PEMS07	96	1.172 \pm 0.189	0.021\pm0.023	0.895 \pm 0.050	2.412\pm1.881	1.079 \pm 0.085	0.402\pm0.161	0.052 \pm 0.017	0.435\pm0.089	4.015 \pm 0.667	0.623\pm0.121
	AVG	0.580 \pm 0.454	0.031\pm0.010	0.520 \pm 0.308	1.880\pm0.298	0.657 \pm 0.342	0.169\pm0.121	0.038 \pm 0.007	0.254\pm0.095	2.455 \pm 0.818	0.381\pm0.127
	12	0.088\pm0.001	0.053 \pm 0.000	0.193\pm0.001	1.637\pm0.004	0.297\pm0.001	0.089 \pm 0.000	0.046\pm0.000	0.138\pm0.000	0.193 \pm 0.000	0.298 \pm 0.001
	24	0.138 \pm 0.000	0.059 \pm 0.000	0.243 \pm 0.001	2.074\pm0.005	0.371 \pm 0.001	0.241\pm0.001	0.051\pm0.000	0.242\pm0.000	2.076 \pm 0.011	0.371\pm0.001
	48	0.247 \pm 0.010	0.052 \pm 0.001	0.287 \pm 0.006	2.242 \pm 0.070	0.497 \pm 0.010	0.232\pm0.003	0.037\pm0.001	0.271\pm0.002	2.085\pm0.038	0.481\pm0.003
	96	0.452 \pm 0.020	0.065 \pm 0.005	0.431 \pm 0.013	2.921 \pm 0.217	0.672 \pm 0.015	0.282\pm0.003	0.030\pm0.001	0.312\pm0.002	2.394\pm0.052	0.531\pm0.003
PEMS08	AVG	0.231 \pm 0.125	0.057 \pm 0.005	0.288 \pm 0.079	2.219 \pm 0.413	0.459 \pm 0.127	0.185\pm0.068	0.041\pm0.007	0.255\pm0.039	2.050\pm0.239	0.420\pm0.082

Table 22: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Solar, PEMSO3, PEMSO4, PEMSO7, PEMSO8, Exchange, Traffic, and Weather datasets and Transformer [30]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/thuml/iTransformer>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 6.59%, TAM: 28.04%, MAE: 5.41%, MAPE: 0.46%, and RMSE: 3.85%. The maximum improvement of AliO over the baseline is MSE: 88.52%, TAM: 60.37%, MAE: 73.75%, MAPE: 18.04%, and RMSE: 66.10%. ECL, ETTh1, ETTh2, ETTm1, and ETTm2 are in Tab. 20. Solar, PEMSO3, PEMSO4, PEMSO7, and PEMSO8 are in Tab. 21.

Models	Metric	Baseline						iTransformer			
		Method	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow
Exchange	96	0.086 \pm 0.001	0.035 \pm 0.001	0.206 \pm 0.001	1.287 \pm 0.007	0.294 \pm 0.001	0.086\pm0.000	0.030\pm0.000	0.205\pm0.001	1.280\pm0.006	0.293\pm0.001
	192	0.179 \pm 0.001	0.037 \pm 0.000	0.302 \pm 0.001	1.926 \pm 0.011	0.423 \pm 0.001	0.178\pm0.001	0.031\pm0.000	0.300\pm0.001	1.895\pm0.003	0.421\pm0.001
	336	0.335 \pm 0.003	0.042 \pm 0.000	0.420 \pm 0.002	2.952 \pm 0.014	0.579 \pm 0.003	0.331\pm0.002	0.032\pm0.001	0.417\pm0.001	2.914\pm0.013	0.576\pm0.001
	720	0.865 \pm 0.006	0.038 \pm 0.002	0.702 \pm 0.003	6.170 \pm 0.019	0.930 \pm 0.003	0.857\pm0.006	0.031\pm0.002	0.699\pm0.002	6.150\pm0.021	0.926\pm0.003
	AVG	0.366 \pm 0.270	0.038 \pm 0.002	0.408 \pm 0.166	3.084 \pm 1.680	0.557 \pm 0.213	0.363\pm0.267	0.031\pm0.001	0.405\pm0.166	3.060\pm1.679	0.554\pm0.212
Traffic	96	0.394 \pm 0.001	0.066 \pm 0.001	0.269 \pm 0.001	2.897 \pm 0.005	0.628 \pm 0.001	0.393\pm0.001	0.049\pm0.000	0.264\pm0.000	2.723\pm0.010	0.627\pm0.001
	192	0.413 \pm 0.001	0.061 \pm 0.000	0.277 \pm 0.000	2.948 \pm 0.011	0.643 \pm 0.001	0.412\pm0.000	0.043\pm0.000	0.271\pm0.000	2.757\pm0.011	0.642\pm0.000
	336	0.425\pm0.001	0.059 \pm 0.000	0.283 \pm 0.001	2.947 \pm 0.021	0.652\pm0.001	0.428 \pm 0.000	0.041\pm0.000	0.278\pm0.000	2.788\pm0.009	0.654\pm0.000
	720	0.457\pm0.002	0.060 \pm 0.000	0.300 \pm 0.001	3.108 \pm 0.034	0.676\pm0.001	0.460 \pm 0.000	0.041\pm0.000	0.296\pm0.000	2.889\pm0.008	0.678\pm0.000
	AVG	0.422\pm0.020	0.061 \pm 0.002	0.282 \pm 0.010	2.975 \pm 0.071	0.649\pm0.016	0.423 \pm 0.022	0.044\pm0.003	0.277\pm0.011	2.789\pm0.055	0.650 \pm 0.017
Weather	96	0.176 \pm 0.002	0.024 \pm 0.001	0.216 \pm 0.002	16.182 \pm 0.603	0.420 \pm 0.002	0.175\pm0.000	0.021\pm0.000	0.215\pm0.000	14.334\pm0.300	0.418\pm0.000
	192	0.225 \pm 0.001	0.024 \pm 0.002	0.257 \pm 0.001	16.029 \pm 0.036	0.474 \pm 0.001	0.223\pm0.000	0.019\pm0.000	0.257\pm0.000	15.938\pm0.131	0.473\pm0.000
	336	0.282 \pm 0.001	0.024 \pm 0.000	0.299 \pm 0.001	15.771 \pm 0.132	0.531 \pm 0.001	0.281\pm0.001	0.016\pm0.000	0.298\pm0.000	15.376\pm0.069	0.530\pm0.001
	720	0.359 \pm 0.001	0.023 \pm 0.001	0.350 \pm 0.001	15.409\pm0.151	0.599 \pm 0.001	0.357\pm0.000	0.013\pm0.000	0.347\pm0.000	15.819 \pm 0.052	0.597\pm0.000
	AVG	0.260 \pm 0.061	0.024 \pm 0.000	0.281 \pm 0.045	15.848 \pm 0.262	0.506 \pm 0.059	0.259\pm0.061	0.017\pm0.003	0.279\pm0.044	15.367\pm0.565	0.505 \pm 0.060

Table 23: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, ILI, Traffix, and Weather datasets and GPT4TS [43]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/DAMO-DI-ML/NearIPS2023-One-Fits-All>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 2.27%, TAM: 32.13%, MAE: 2.43%, MAPE: 1.56%, and RMSE: 1.14%. The maximum improvement of AliO over the baseline is MSE: 11.54%, TAM: 62.06%, MAE: 10.98%, MAPE: 8.16%, and RMSE: 5.93%. ILI, Traffix, and Weather are in Tab. 24.

Models	GPT4TS						AliO				
	Method	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	
ETTh1	96	0.380 \pm 0.003	0.060 \pm 0.001	0.401 \pm 0.001	9.556\pm0.065	0.616 \pm 0.002	0.374\pm0.003	0.034\pm0.001	0.393\pm0.001	9.675 \pm 0.079	0.612\pm0.002
	192	0.418 \pm 0.001	0.051 \pm 0.001	0.419 \pm 0.003	9.502\pm0.101	0.646 \pm 0.001	0.412\pm0.002	0.037\pm0.001	0.416\pm0.001	9.532 \pm 0.276	0.642\pm0.001
	336	0.441 \pm 0.007	0.054 \pm 0.004	0.435 \pm 0.004	9.507\pm0.157	0.664 \pm 0.006	0.431\pm0.004	0.031 \pm 0.000	0.427 \pm 0.003	9.519 \pm 0.180	0.656 \pm 0.003
	720	0.458 \pm 0.006	0.058 \pm 0.005	0.465 \pm 0.003	10.152\pm0.159	0.677 \pm 0.004	0.452\pm0.009	0.053 \pm 0.002	0.456 \pm 0.004	10.804 \pm 0.153	0.672\pm0.007
AVG	96	0.292 \pm 0.003	0.053 \pm 0.003	0.353 \pm 0.001	1.377 \pm 0.031	0.540 \pm 0.002	0.288\pm0.003	0.041 \pm 0.001	0.348 \pm 0.004	1.352\pm0.023	0.537\pm0.003
	192	0.368 \pm 0.008	0.054 \pm 0.006	0.400 \pm 0.004	1.484 \pm 0.017	0.606 \pm 0.006	0.351\pm0.001	0.033 \pm 0.002	0.388 \pm 0.001	1.470 \pm 0.024	0.592 \pm 0.001
	336	0.376 \pm 0.003	0.041 \pm 0.002	0.414 \pm 0.002	1.674 \pm 0.030	0.613 \pm 0.002	0.373\pm0.002	0.029 \pm 0.001	0.409 \pm 0.002	1.622 \pm 0.025	0.611 \pm 0.001
	720	0.414 \pm 0.004	0.042 \pm 0.003	0.449 \pm 0.005	2.051 \pm 0.056	0.644 \pm 0.003	0.404\pm0.002	0.027 \pm 0.002	0.441 \pm 0.002	1.981 \pm 0.017	0.635 \pm 0.002
AVG	96	0.363 \pm 0.040	0.048 \pm 0.005	0.404 \pm 0.031	1.646 \pm 0.230	0.601 \pm 0.034	0.354\pm0.038	0.033 \pm 0.005	0.396 \pm 0.030	1.606 \pm 0.212	0.594 \pm 0.032
	192	0.292 \pm 0.002	0.047 \pm 0.001	0.347 \pm 0.002	2.184 \pm 0.033	0.540 \pm 0.002	0.286\pm0.001	0.036 \pm 0.000	0.340 \pm 0.001	2.136 \pm 0.011	0.535\pm0.001
	336	0.330 \pm 0.001	0.043 \pm 0.002	0.369 \pm 0.001	2.241 \pm 0.011	0.575 \pm 0.001	0.325\pm0.001	0.029 \pm 0.000	0.362 \pm 0.001	2.220 \pm 0.004	0.570 \pm 0.001
	720	0.418 \pm 0.001	0.043 \pm 0.001	0.423 \pm 0.001	2.506 \pm 0.031	0.646 \pm 0.001	0.414\pm0.001	0.033 \pm 0.001	0.418 \pm 0.001	2.469 \pm 0.009	0.643 \pm 0.001
ETTh2	96	0.351 \pm 0.041	0.044 \pm 0.002	0.383 \pm 0.025	2.320 \pm 0.110	0.592 \pm 0.035	0.346\pm0.042	0.031 \pm 0.003	0.376 \pm 0.026	2.283 \pm 0.110	0.587 \pm 0.036
	192	0.233 \pm 0.002	0.039 \pm 0.002	0.259 \pm 0.002	1.096 \pm 0.010	0.412 \pm 0.002	0.168\pm0.000	0.033 \pm 0.001	0.257 \pm 0.000	0.179 \pm 0.003	0.410\pm0.001
	336	0.233 \pm 0.004	0.042 \pm 0.003	0.305 \pm 0.003	1.224 \pm 0.020	0.483 \pm 0.004	0.225\pm0.000	0.025 \pm 0.001	0.297 \pm 0.001	1.199 \pm 0.012	0.474\pm0.001
	720	0.297 \pm 0.009	0.048 \pm 0.007	0.348 \pm 0.005	1.363 \pm 0.011	0.545 \pm 0.008	0.284\pm0.003	0.026 \pm 0.001	0.337 \pm 0.002	1.323 \pm 0.016	0.533\pm0.002
ETTm2	96	0.382\pm0.006	0.041 \pm 0.003	0.401 \pm 0.005	1.552 \pm 0.034	0.618\pm0.005	0.382 \pm 0.001	0.028 \pm 0.000	0.400 \pm 0.000	1.531 \pm 0.015	0.618 \pm 0.001
	192	0.233 \pm 0.002	0.042 \pm 0.003	0.328 \pm 0.047	1.304 \pm 0.145	0.514 \pm 0.068	0.265\pm0.071	0.028 \pm 0.003	0.323 \pm 0.047	1.283 \pm 0.150	0.509\pm0.068
	336	0.297 \pm 0.009	0.048 \pm 0.007	0.348 \pm 0.005	1.363 \pm 0.011	0.545 \pm 0.008	0.284\pm0.003	0.026 \pm 0.001	0.337 \pm 0.002	1.323 \pm 0.016	0.533\pm0.002
	720	0.382\pm0.006	0.041 \pm 0.003	0.401 \pm 0.005	1.552 \pm 0.034	0.618\pm0.005	0.382 \pm 0.001	0.028 \pm 0.000	0.400 \pm 0.000	1.531 \pm 0.015	0.618 \pm 0.001
ECL	96	0.138\pm0.000	0.034 \pm 0.000	0.237\pm0.000	2.442 \pm 0.003	0.372\pm0.000	0.138 \pm 0.000	0.025 \pm 0.000	0.237 \pm 0.001	2.412\pm0.003	0.372 \pm 0.000
	192	0.155 \pm 0.000	0.034 \pm 0.000	0.252 \pm 0.001	2.679 \pm 0.026	0.393 \pm 0.000	0.154\pm0.000	0.025 \pm 0.000	0.251 \pm 0.000	2.652 \pm 0.033	0.392\pm0.000
	336	0.169 \pm 0.000	0.036 \pm 0.000	0.266 \pm 0.001	2.707 \pm 0.030	0.411 \pm 0.001	0.169\pm0.001	0.021 \pm 0.000	0.266 \pm 0.001	2.665 \pm 0.023	0.411\pm0.001
	720	0.206 \pm 0.000	0.042 \pm 0.001	0.297 \pm 0.001	2.915 \pm 0.033	0.454 \pm 0.000	0.206\pm0.000	0.028 \pm 0.003	0.296 \pm 0.000	2.818 \pm 0.063	0.454\pm0.000
AVG	96	0.167 \pm 0.023	0.036 \pm 0.003	0.263 \pm 0.020	2.686 \pm 0.150	0.407 \pm 0.027	0.167\pm0.022	0.025 \pm 0.002	0.262 \pm 0.020	2.637 \pm 0.130	0.407\pm0.027
	192	0.155 \pm 0.023	0.034 \pm 0.003	0.252 \pm 0.020	2.679 \pm 0.150	0.407 \pm 0.027	0.167\pm0.022	0.025 \pm 0.002	0.262 \pm 0.020	2.637 \pm 0.130	0.407\pm0.027

Table 24: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, ILI, Traffx, and Weather datasets and GPT4TS [43]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/DAMO-DI-ML/NeurIPS2023-One-Fits-All>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 2.27%, TAM: 32.13%, MAE: 2.43%, MAPE: 1.56%, and RMSE: 1.14%. The maximum improvement of AliO over the baseline is MSE: 11.54%, TAM: 62.06%, MAE: 10.98%, MAPE: 8.16%, and RMSE: 5.93%. ECL, ETTh1, ETTh2, ETTm1, and ETThm2 are in Tab. 23.

Models	GPT4TS						AliO		
	Method	Baseline			GPT4TS			MAE \downarrow	MAPE \downarrow
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow		
ILI	24	1.965 \pm 0.046	0.137 \pm 0.010	0.862 \pm 0.009	3.994 \pm 0.129	1.402 \pm 0.016	1.897\pm0.036	0.115\pm0.007	0.839\pm0.007
	36	1.914 \pm 0.090	0.104 \pm 0.026	0.913 \pm 0.037	3.408 \pm 0.334	1.383 \pm 0.033	1.693\pm0.044	0.090\pm0.007	0.812\pm0.020
	48	1.851 \pm 0.096	0.112 \pm 0.014	0.915 \pm 0.032	3.073\pm0.103	1.360 \pm 0.036	1.722\pm0.041	0.091\pm0.008	0.852\pm0.006
	60	1.861 \pm 0.056	0.114 \pm 0.011	0.927 \pm 0.031	3.225\pm0.188	1.364 \pm 0.020	1.707\pm0.032	0.097\pm0.005	0.880\pm0.011
	AVG	1.898 \pm 0.041	0.117 \pm 0.011	0.904 \pm 0.023	3.425\pm0.313	1.377 \pm 0.015	1.755\pm0.074	0.098\pm0.009	0.846\pm0.022
	96	0.386 \pm 0.001	0.056 \pm 0.000	0.279 \pm 0.000	2.996 \pm 0.001	0.621 \pm 0.001	0.377\pm0.002	0.039\pm0.000	0.267\pm0.002
Traffic	192	0.404 \pm 0.001	0.058 \pm 0.002	0.286 \pm 0.003	3.081 \pm 0.043	0.636 \pm 0.001	0.399\pm0.001	0.032\pm0.001	0.276\pm0.001
	336	0.411 \pm 0.000	0.061 \pm 0.001	0.290 \pm 0.000	3.106 \pm 0.016	0.641 \pm 0.000	0.406\pm0.002	0.032\pm0.000	0.282\pm0.002
	720	0.444 \pm 0.000	0.063 \pm 0.001	0.304 \pm 0.001	3.212 \pm 0.029	0.667 \pm 0.000	0.438\pm0.000	0.024\pm0.000	0.295\pm0.000
	AVG	0.411 \pm 0.019	0.059 \pm 0.002	0.289 \pm 0.008	3.099 \pm 0.069	0.641 \pm 0.015	0.405\pm0.020	0.032\pm0.005	0.280\pm0.009
	96	0.148 \pm 0.002	0.026 \pm 0.001	0.199 \pm 0.003	12.027 \pm 0.525	0.385 \pm 0.002	0.147\pm0.001	0.018\pm0.000	0.194\pm0.002
	192	0.195 \pm 0.000	0.024 \pm 0.001	0.244 \pm 0.000	14.653 \pm 0.401	0.442 \pm 0.000	0.192\pm0.001	0.017\pm0.000	0.237\pm0.001
Weather	336	0.246 \pm 0.002	0.024 \pm 0.000	0.284 \pm 0.001	15.431 \pm 0.356	0.496 \pm 0.002	0.244\pm0.001	0.013\pm0.000	0.276\pm0.001
	720	0.319 \pm 0.001	0.022 \pm 0.001	0.336 \pm 0.002	14.770\pm0.506	0.565 \pm 0.001	0.316\pm0.001	0.011\pm0.000	0.328\pm0.001
	AVG	0.227 \pm 0.057	0.024 \pm 0.001	0.266 \pm 0.045	14.220 \pm 1.163	0.472 \pm 0.060	0.225\pm0.056	0.015\pm0.002	0.259\pm0.044
	AVG						14.081\pm1.107	0.469\pm0.059	

Table 25: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Solar, traffic, and Weather datasets and CycleNet [27]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/ACAT-SCUT/CycleNet>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 0.52%, TAM: 37.91%, MAE: 0.91%, MAPE: 1.84%, and RMSE: 0.26%. The maximum improvement of AliO over the baseline is MSE: 2.73%, TAM: 74.35%, MAE: 6.79%, MAPE: 13.27%, and RMSE: 1.38%. Solar, Traffic, and Weather are in Tab. 26.

Models	CycleNet						AliO					
	Method	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	
ECL	96	0.141±0.000	0.019±0.000	0.234±0.000	2.305±0.002	0.376±0.000	0.142±0.000	0.019±0.000	0.234±0.000	2.304±0.004	0.376±0.000	
	192	0.156±0.000	0.017±0.002	0.247±0.000	2.450±0.007	0.395±0.000	0.156±0.000	0.015±0.000	0.247±0.000	2.444±0.003	0.394±0.000	
	336	0.173±0.000	0.014±0.000	0.265±0.000	2.439±0.003	0.415±0.000	0.173±0.000	0.010±0.000	0.265±0.000	2.439±0.001	0.415±0.000	
	720	0.211±0.000	0.013±0.000	0.297±0.000	2.583±0.001	0.459±0.000	0.211±0.000	0.010±0.000	0.297±0.000	2.584±0.002	0.459±0.000	
	AVG	0.170±0.023	0.016±0.002	0.261±0.021	2.444±0.088	0.411±0.028	0.170±0.023	0.014±0.003	0.261±0.021	2.443±0.089	0.411±0.028	
ETTh1	96	0.380±0.002	0.054±0.011	0.393±0.002	9.380±0.023	0.616±0.002	0.376±0.000	0.016±0.001	0.387±0.000	9.142±0.027	0.613±0.000	
	192	0.425±0.001	0.043±0.005	0.418±0.001	9.471±0.032	0.652±0.001	0.422±0.000	0.013±0.001	0.414±0.000	9.185±0.033	0.650±0.000	
	336	0.462±0.001	0.041±0.005	0.438±0.001	9.443±0.011	0.680±0.001	0.459±0.001	0.012±0.001	0.434±0.000	9.210±0.029	0.678±0.000	
	720	0.461±0.000	0.038±0.002	0.460±0.000	9.559±0.015	0.679±0.000	0.458±0.001	0.011±0.000	0.454±0.000	9.408±0.029	0.676±0.000	
	AVG	0.432±0.030	0.044±0.005	0.427±0.022	9.463±0.058	0.657±0.023	0.429±0.030	0.013±0.002	0.422±0.022	9.236±0.091	0.654±0.024	
ETTh2	96	0.285±0.001	0.047±0.002	0.335±0.001	1.343±0.005	0.534±0.001	0.283±0.000	0.032±0.000	0.334±0.000	1.324±0.001	0.532±0.000	
	192	0.373±0.002	0.042±0.002	0.392±0.002	1.512±0.011	0.611±0.001	0.371±0.000	0.029±0.001	0.390±0.000	1.504±0.004	0.609±0.000	
	336	0.424±0.004	0.048±0.013	0.435±0.002	1.770±0.012	0.651±0.003	0.418±0.000	0.015±0.000	0.431±0.000	1.735±0.005	0.647±0.000	
	720	0.456±0.003	0.053±0.013	0.459±0.002	2.066±0.009	0.675±0.003	0.449±0.000	0.023±0.005	0.456±0.000	2.049±0.001	0.670±0.000	
	AVG	0.385±0.058	0.047±0.003	0.405±0.042	1.672±0.244	0.618±0.048	0.381±0.056	0.025±0.006	0.402±0.041	1.653±0.243	0.615±0.047	
ETTm1	96	0.326±0.001	0.039±0.003	0.364±0.001	2.208±0.001	0.571±0.001	0.320±0.000	0.017±0.000	0.355±0.000	2.112±0.002	0.566±0.000	
	192	0.366±0.000	0.032±0.003	0.382±0.000	2.263±0.005	0.605±0.000	0.364±0.000	0.013±0.000	0.376±0.000	2.204±0.000	0.603±0.000	
	336	0.396±0.001	0.031±0.003	0.402±0.001	2.316±0.002	0.629±0.000	0.394±0.000	0.012±0.000	0.396±0.000	2.261±0.000	0.627±0.000	
	720	0.457±0.000	0.026±0.001	0.434±0.000	2.476±0.003	0.676±0.000	0.455±0.000	0.016±0.001	0.431±0.000	2.449±0.007	0.675±0.000	
	AVG	0.386±0.043	0.032±0.004	0.395±0.023	2.316±0.089	0.620±0.034	0.383±0.044	0.014±0.002	0.390±0.025	2.256±0.110	0.618±0.035	
ETTm2	96	0.167±0.001	0.033±0.002	0.248±0.001	1.041±0.004	0.408±0.001	0.166±0.000	0.022±0.000	0.247±0.000	1.032±0.000	0.407±0.000	
	192	0.233±0.000	0.029±0.002	0.291±0.000	1.158±0.002	0.482±0.001	0.232±0.000	0.020±0.000	0.290±0.000	1.151±0.000	0.481±0.000	
	336	0.294±0.001	0.025±0.001	0.330±0.000	1.265±0.005	0.542±0.001	0.293±0.000	0.018±0.000	0.330±0.000	1.264±0.000	0.541±0.000	
	720	0.394±0.000	0.022±0.000	0.389±0.000	1.470±0.004	0.628±0.000	0.394±0.000	0.017±0.000	0.389±0.000	1.469±0.000	0.628±0.000	
	AVG	0.272±0.075	0.027±0.004	0.315±0.046	1.233±0.141	0.515±0.072	0.271±0.075	0.019±0.002	0.314±0.047	1.229±0.144	0.514±0.072	

Table 26: Full results of the proposed AliO method on the ECL, ETTh1, ETTh2, ETTm1, ETTm2, Solar, traffic, and Weather datasets and CycleNet [27]. The results are reported in terms of MSE, TAM, MAE, MAPE, and RMSE. The best results are highlighted in **bold**. We use official GitHub code (<https://github.com/ACAT-SCUT/CycleNet>) to train the model with the official configuration. The average improvement of AliO over the baseline is MSE: 0.52%, TAM: 37.91%, MAE: 0.91%, MAPE: 1.84%, and RMSE: 0.26%. The maximum improvement of AliO over the baseline is MSE: 2.73%, TAM: 74.35%, MAE: 6.79%, MAPE: 13.27%, and RMSE: 1.38%. ECL, ETTh1, ETTh2, ETTm1, and ETTm2 are in Tab. 25.

Models	Method	CycleNet						AliO			
		MSE \downarrow	TAM \downarrow	MAE \downarrow	MAPE \downarrow	RMSE \downarrow	MSE \downarrow	TAM \downarrow	MAE \downarrow	RMSE \downarrow	
Solar	96	0.250\pm0.001	0.030 \pm 0.002	0.278 \pm 0.001	1.984 \pm 0.005	0.500\pm0.001	0.250 \pm 0.000	0.026\pm0.000	0.277\pm0.000	1.982\pm0.000	0.500 \pm 0.000
	192	0.289\pm0.000	0.027 \pm 0.000	0.298\pm0.001	2.101\pm0.005	0.538\pm0.000	0.290 \pm 0.000	0.026\pm0.000	0.299 \pm 0.000	2.110 \pm 0.001	0.539 \pm 0.000
	336	0.338 \pm 0.000	0.024\pm0.000	0.322\pm0.000	2.335 \pm 0.001	0.582 \pm 0.000	0.338\pm0.000	0.026 \pm 0.002	0.323 \pm 0.001	2.328\pm0.003	0.581\pm0.000
	720	0.351\pm0.000	0.021 \pm 0.001	0.327\pm0.000	2.478\pm0.005	0.593\pm0.000	0.352 \pm 0.000	0.020\pm0.000	0.327 \pm 0.000	2.480 \pm 0.001	0.593 \pm 0.000
	AVG	0.307\pm0.036	0.026 \pm 0.003	0.306\pm0.018	2.224\pm0.173	0.553\pm0.033	0.308 \pm 0.036	0.024\pm0.002	0.307 \pm 0.018	2.225 \pm 0.172	0.553 \pm 0.033
	96	0.481 \pm 0.000	0.028 \pm 0.003	0.314 \pm 0.001	3.675 \pm 0.005	0.693 \pm 0.000	0.468\pm0.000	0.007\pm0.000	0.293\pm0.001	3.187\pm0.028	0.684\pm0.000
Traffic	192	0.482 \pm 0.001	0.021 \pm 0.000	0.313 \pm 0.000	3.619 \pm 0.004	0.694 \pm 0.000	0.469\pm0.000	0.007\pm0.000	0.295 \pm 0.000	3.181 \pm 0.007	0.685\pm0.000
	336	0.480\pm0.005	0.015 \pm 0.004	0.308 \pm 0.006	3.428 \pm 0.058	0.693\pm0.004	0.481 \pm 0.000	0.006 \pm 0.000	0.301 \pm 0.000	3.185 \pm 0.009	0.694 \pm 0.000
	720	0.507 \pm 0.005	0.022 \pm 0.001	0.324 \pm 0.006	3.490 \pm 0.038	0.712 \pm 0.003	0.506\pm0.005	0.012\pm0.004	0.323 \pm 0.006	3.465\pm0.050	0.711\pm0.004
	AVG	0.487 \pm 0.010	0.021 \pm 0.004	0.315 \pm 0.005	3.553 \pm 0.088	0.698 \pm 0.007	0.481\pm0.014	0.008\pm0.002	0.303 \pm 0.011	3.255\pm0.109	0.693\pm0.010
	96	0.170\pm0.000	0.010 \pm 0.000	0.216\pm0.000	12.814\pm0.055	0.413\pm0.000	0.171 \pm 0.000	0.010\pm0.000	0.217 \pm 0.001	12.942 \pm 0.059	0.413 \pm 0.000
	192	0.223 \pm 0.001	0.013 \pm 0.003	0.260 \pm 0.000	13.923\pm0.100	0.472 \pm 0.001	0.222\pm0.000	0.010 \pm 0.002	0.259\pm0.000	13.935 \pm 0.035	0.472\pm0.000
Weather	336	0.276\pm0.000	0.009 \pm 0.001	0.297\pm0.000	14.299\pm0.037	0.525\pm0.000	0.276 \pm 0.000	0.007\pm0.000	0.297 \pm 0.000	14.302 \pm 0.006	0.525 \pm 0.000
	720	0.350 \pm 0.000	0.009 \pm 0.002	0.345 \pm 0.000	14.876 \pm 0.083	0.591 \pm 0.000	0.350\pm0.000	0.006\pm0.000	0.345\pm0.000	14.851\pm0.003	0.591\pm0.000
	AVG	0.255\pm0.059	0.010 \pm 0.001	0.280\pm0.042	13.978\pm0.674	0.500\pm0.059	0.255 \pm 0.059	0.008\pm0.002	0.280 \pm 0.042	14.007 \pm 0.623	0.500 \pm 0.059

J Pronunciation of a.li.o

To prevent confusion regarding the pronunciation, this section explicitly describes how to pronounce a.li.o.

[a.li.o]

The pronunciation consists of three syllables:

- **a**: Pronounced like the ‘a’ in *father* (ah).
- **li**: Pronounced with a clear ‘L’ sound, as in *Lee* (lee).
- **o**: Pronounced like the ‘o’ in *go* (oh).

Consequently, it is pronounced as “**Ah-Lee-Oh**”, ensuring the ‘L’ is clearly articulated.

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