LANGUAGE MODEL AGENTS SUFFER FROM COMPOSI-TIONAL GENERALIZATION IN WEB AUTOMATION

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Abstract

Language model agents (LMA) recently emerged as a promising paradigm on mutistep decision making tasks, often outperforming humans and other reinforcement learning agents. Despite the promise, their performance on real-world applications that often involve combinations of tasks is still underexplored. In this work, we introduce a new benchmark, called CompWoB - 50 new compositional web automation tasks reflecting more realistic assumptions. We show that while existing prompted LMAs (gpt-3.5-turbo or gpt-4) achieve 94.0% average success rate on base tasks, their performance degrades to 24.9% success rate on compositional tasks. On the other hand, transferred LMAs (finetuned only on base tasks) show less generalization gap, dropping from 85.4% to 54.8%. By balancing data distribution across tasks, we train a new model, HTML-T5++, that surpasses human-level performance (95.2%) on MiniWoB, and achieves the best zero-shot performance on CompWoB (61.5%). While these highlight the promise of small-scale finetuned and transferred models for compositional generalization, their performance further degrades under different instruction compositions changing combinational order. In contrast to the recent remarkable success of LMA, our benchmark and detailed analysis emphasize the necessity of building LMAs that are robust and generalizable to task compositionality for real-world deployment.

1 INTRODUCTION

Based on the exceptional capability of large language models (LLMs) (OpenAI, 2023; Anil et al., 2023; Touvron et al., 2023) in commonsense understanding (Brown et al., 2020; Chowdhery et al., 2022), multi-step reasoning (Wei et al., 2022; Kojima et al., 2022), program synthesis (Chen et al., 2021) and self-improvement (Shinn et al., 2023; Madaan et al., 2023; To et al., 2023), language model agents (LMA) have recently emerged to tackle various decision making problems, such as robotics (Huang et al., 2022a; Ahn et al., 2022), information retrieval (Nakano et al., 2021; Yao et al., 2022b), and external tool use (Wu et al., 2023; Shen et al., 2023; Lu et al., 2023). Especially, in web automation (Shi et al., 2017), LMAs with prompting (Kim et al., 2023; Sun et al., 2023; Zheng et al., 2023) outperform humans and other learning-based agents, such as reinforcement learning (Humphreys et al., 2022) or finetuned language models (Gur et al., 2022; Furuta et al., 2023).

Despite their proficiency in MiniWoB (Shi et al., 2017), a standard web automation benchmark, it is still unclear whether LMAs could deal with challenges in the real world: such as complex observation (Gur et al., 2023), domain generalization (Deng et al., 2023), and ambiguity of instructions (Zhou et al., 2023b). These challenges are exacerbated due to the open-ended nature of real-world tasks, making it infeasible to prepare exemplars and prompts in advance for any unseen task.

In this work, we extensively study the generalization of LMAs to more realistic task compositions. We first design a new controlled test bed, called CompWoB, with 50 compositional tasks by combining a set of base tasks based on their difficulty (Figure 1). Each compositional task is implemented from 2 to 8 base tasks in a single-page or multi-page environment with instructions linked together using simple connectors such as "and then". Only providing the knowledge about base tasks, we investigate the generalization performance of existing SoTA prompted LMAs (Kim et al., 2023; Sun et al., 2023; Zheng et al., 2023) with planning, self-improvement, program synthesis, and structured prompts that are supported by gpt-3.5-turbo and gpt-4. Our findings indicate that their performance drops significantly, from 94.0% success on base tasks to 24.9% success on compositional tasks. In contrast,



Figure 1: We design *CompWoB*, as a novel decision making benchmark for LMAs, by leveraging the high composability of simulated web environments. We first select base tasks from the original MiniWoB (Shi et al., 2017) based on the brute-force task complexity averaged among existing LMAs. While considering the feasibility, we randomly combine them into a single task (e.g. click-checkboxes-transfer+enter-password+click-dialog→ click-checkboxes-transfer_enter-password_click-dialog). The instructions of base tasks are stitched with "and then". LMAs are asked to satisfy the given instructions sequentially (e.g. satisfying the success criteria of task $A \rightarrow B \rightarrow C$). We also implement reverse-order instruction settings, where the instructions are provided upside down (e.g. solve task *B*, and solve task *C*, after solving task *A*). These complex yet controllable strategies make the analysis of LMA's behaviors easy, while maintaining complex and ambiguous aspects of real-world web environments.

small-scale LMAs finetuned only on base tasks and zero-shot-transferred to compositional settings (i.e. transferred LMAs), deal with unknown task compositionality better, achieving 54.8% success rate on average. By rebalancing the data distribution, we also train a new model, HTML-T5++, that achieves human-level performance on MiniWob and performs the best among all the LMAs on compositional tasks. We further show that LMAs struggle to handle complex instruction compositions permuting the order of sub-instructions, where prompted agents are more robust to the difference in the order of compositions compared to transferred agents (6.9% vs 23.8% drop in performance). Finally, we illustrate that instruction length and observation complexity are useful indicators of compositional task performance.

In contrast to the recent notable success of LMAs, our benchmark and detailed analysis highlight building robust and generalizable LMAs to be safely deployed in the real world. In summary, our key contributions are:

- We empirically show that (1) prompted LMAs even with gpt-4 suffer from generalizing to compositional web automation tasks much more than transferred LMAs, and (2) LMAs are highly sensitive to the order of instructions.
- We develop *CompWoB*¹, simulated web environments for LMAs to measure the generalization to the realistic task compositionality and complex instructions.
- We propose a new data mixture strategy for finetuning LMA. HTML-T5++, trained on this strategy, achieves human-level performance on MiniWoB (95.2%) and the best zero-shot transfer to CompWoB (61.5%).

2 RELATED WORKS

Language Model Agents Beyond the common NLP tasks, LLMs could act as autonomous agents (Wang et al., 2023b; Qin et al., 2023a) to solve the given instruction-following tasks, by considering the context in the prompt as states (Ahn et al., 2022; Yao et al., 2022b; Hsieh et al., 2023) and sequentially planning and manipulating external "tools" or "actuators", such as calculators (Parisi et al., 2022), retrievers (Schick et al., 2023; Hao et al., 2023), APIs (Qin et al., 2023b; Tang et al., 2023a), programs (Gao et al., 2023; Wang et al., 2023a; Liang et al., 2023; Song et al., 2023; Cai et al., 2023), robotic commands (Huang et al., 2022a;b; Tang et al., 2023b), computer game (Nottingham et al., 2023; Wang et al., 2023c), or other foundation models (Lu et al., 2023; Hsieh et al., 2023; Wu et al., 2023; Shen et al., 2023; Yang et al., 2023). Those prior works have worked on proposing novel benchmarks (Li et al., 2023; Xu et al., 2023; Patil et al., 2023) and comparing backbone LLMs

¹We will release the code in de-anonymized version.

(e.g. open-sourced v.s. private) (Ruan et al., 2023; Liu et al., 2023b;a). Despite their success, it is still unclear how such LMAs designed for specific tasks can generalize out-of-domain problems, which should be an important perspective since we may not prepare prompts and exemplars for all the possible combinations of problems in the real world. In this work, we measure the compositional generalization and robustness to the complex instructions in web automation.

Web Automation Although prior works have worked on imitation learning and reinforcement learning (Liu et al., 2018; Gur et al., 2019; Jia et al., 2019; Humphreys et al., 2022), web automation has become a popular domain as a benchmark for LMAs (Gur et al., 2022; Kim et al., 2023). In earlier work, finetuned LMAs, based on at most 3-billion parameters, amortize the training costs with the strong prior knowledge on web environments (Gur et al., 2022; Furuta et al., 2023; Shaw et al., 2023), but they often result in sub-optimal performances due to the insufficient data coverage. Recently, by leveraging capable private LLMs (Brown et al., 2020; Ouyang et al., 2022) with self-refinement (Kim et al., 2023), program synthesis (Sun et al., 2023), well-designed structured prompts with instruction-state translation (Zheng et al., 2023), or hierarchical prompts (Sridhar et al., 2023; Ma et al., 2023), prompted LMAs with few-shot exemplars have outperformed finetuned LMAs and shown competitive performance to humans and RL-finetuned agents. In contrast, our work discusses the generalization and robustness of those LMAs in zero-shot web automation with a set of compositional tasks, and resolves the sub-optimality of finetuned LMAs via data-rebalancing.

In addition to MiniWoB (Shi et al., 2017), a representative web simulator, several works have conducted real-world evaluation (Gur et al., 2023) and proposed novel benchmarks reflecting real-world assumptions, such as a simulated e-commerce site (Yao et al., 2022a), sand-boxed real-world websites (Zhou et al., 2023b), an adaptive sim-to-real bridge with unsupervised auto-curricula (Gur et al., 2021), and large-scale web interaction dataset curated by human annotators (Deng et al., 2023). However, real-world web automation may make the analysis challenging because it often faces many obstacles, such as complex HTML observations, domain gaps between websites, and ambiguous instructions. In this work, we design CompWoB while controlling task difficulty and ambiguity of instructions, and investigate what factors may prevent the generalization capability of LMAs in compositional tasks.

Large Language Models for Compositional Tasks Several works have investigated compositional natural language problems with LLMs, such as semantic parsing (Furrer et al., 2021; Shaw et al., 2021; Zhou et al., 2023a), logic grid puzzles (Dziri et al., 2023), mathematical reasoning (Chen et al., 2023), programming (Zelikman et al., 2023), and planning (Brahman et al., 2023), which shows that dynamical selection of exemplars for decomposed sub-problems (Drozdov et al., 2023) or model scaling (Qiu et al., 2022) could help generalization. While those are focused on static tasks, our paper studies compositional generalization in decision making, especially, in web automation where the task may have more explicitly decomposable structures (Gur et al., 2021) than natural language tasks.

3 PRELIMINARIES

Web automation could be described as a deterministic sequential decision making problem, which consists of a state space S, action space A, deterministic transition function $T : S \times A \to S$, a set of instructions G, a set of contextual information (i.e. prompts for LLM) C, and episodic reward function (i.e. success criteria) $r : S \times G \times A \to \{0,1\}$. At each time step t, the language model agent π infers the action conditioned on the prompt, instruction, current state, and previous actions $\pi : S \times \underbrace{A \times \cdots \times A}_{\times t} \times C \times G \to A$, and moves to the next state: $s_{t+1} = T(s_t, a_t)$. When the

agent reaches the terminal state (e.g. Login button is clicked) or the max time step is exceeded, the episode is marked as a success if the instruction g is satisfied (i.e. $r(s_t, g, a_t) = 1$). The state $s_t \in S$ is a raw HTML, and we assume the programmatic action space: function (selector, text). function is either *click*, *move* or *type*, selector is an integer index or XPath that can uniquely specify the element, and text is a text input for *type* function.

Task Compositionality Web automation tasks can be decomposed into a set of primitive base tasks. For instance, (1) clicking several checkboxes, (2) fulfilling the password form, and (3) closing the dialog window. Such a combination could be open-ended. In this work, we assume that the task $\psi \in \Psi$ is characterized by a corresponding subtree of HTML ($S_{\psi} \subset S$) and instructions ($\mathcal{G}_{\psi} \subset \mathcal{G}$), and can be combined each other as long as the task is feasible and executable.

4 LANGUAGE MODEL AGENTS FOR WEB AUTOMATION

We here review the existing LMAs for web automation problems, such as RCI (Section 4.1), Ada-Planner (Section 4.2), Synapse (Section 4.3), and transferred LMAs (Section 4.4). To clarify their algorithmic difference, we further provide the pseudo code for prompted LMAs in Appendix B. Furthermore, we resolve the sub-optimal performance of transferred LMAs by proposing data-rebalanced finetuning (Section 4.5).

4.1 RCI

The agent with Recursive Criticism and Improvement (RCI) prompting (Kim et al., 2023) first generates an open-loop plan to follow a given instruction using few-shot demonstrations. Next, it uses a prompt-based critic to identify the problems in the plan and improves the plan by reflecting on self-criticized outputs, which is referred as an explicit RCI (ERCI) loop. After ERCI, the agent follows the self-improved plan step-by-step. Before executing the action at each time step, the agent grounds the action to the current state (i.e. HTML, open-loop plan, and previous actions) and refines its formatting to be parsable, which increases the feasibility and reduces hallucinations. These final steps are referred to as an implicit RCI (IRCI) loop without the self-criticism.

All of those play complementary roles to achieve proficient performance. While 1 ERCI and 3 IRCI loops are recommended by Kim et al. (2023), we observe that the optimal number of self-improvement iterations may differ across the tasks. See Appendix C.1 for the details.

4.2 ADAPLANNER

In contrast to other prompted LMAs, AdaPlanner (Sun et al., 2023) leverages the capability of program synthesis in LLMs to mitigate the hallucination in a plan. Conditioning on the instruction, the description of permissible actions in the web environments, and few-shot demonstrations, the agent first generates an open-loop plan in a Python function, where each snippet corresponds to the action. Once the agent receives environmental feedback at each step, such as assertion errors in the code, other functional errors, or "ask" action to LLMs, it adaptively re-generates the plan for the remaining steps in a closed-loop manner. It has been reported that LLMs more capable of code generation perform better, such as text-davinci-003 than gpt-3.5-turbo.

4.3 SYNAPSE

Synapse (Zheng et al., 2023) argues that LMAs perform better if well-designed structured prompts are provided, even without self-improvement or program synthesis. The structured prompting is formed by two pre-processing strategies: state filtering and task reformulation. State filtering gradually transforms raw HTML into simple formatted text, such as a Pythonic list or dictionary, in a multi-step manner, which may improve the state understanding of LMAs. Task reformulation translates given instructions or raw HTML into decomposed queries: for instance, translating "select 12/03/2016 as the date and hit submit" into "select the datepicker at step 1, click 'Prev' 7 times at step 2-8 (May is 7 months before December), click the date '12' at step 9, and finally submit at step 10" (translated instruction), or mapping proper noun into corresponding XPath (translated HTML).

While detailed structured prompts have led to strong performances, those should be specialized for each primitive task in MiniWoB by leveraging 7 different types of reformulation. See Appendix C.3 for further details.

Models	Dataset Size	Success Rate
HTML-T5	347K episodes	85.6%
HTML-T5++ (ours)	424K (+77K) 361K (+77K - 63K) 332K (+77K - 92K) 292K (+77K - 132K) 259K (+77K - 165K)	94.1% 94.6% 94.8% 95.2 % 95.0%
RCI (Kim et al. AdaPlanner (Su Human CC-Net (Hump RCI (gpt-4) (Synapse (Zheng	, 2023) in et al., 2023) hreys et al., 2022) (Kim et al., 2023) g et al., 2023)	90.6% 92.9% 93.5% 93.5% 94.0% 98.5 %

Table 1: Average success rate of finetuned LMAs in 56 tasks on MiniWoB. Adding 77K episodes and reducing redundant thousands of episodes, HTML-T5++ achieves competitive performance to prompted LMAs, RL-finetuned agents, and humans, while improving the success rate from 85.6% to 95.2%.

4.4 FINETUNED AND TRANSFERRED LANGUAGE MODEL AGENTS

In addition to the prompted LMAs, LMAs finetuned on base tasks have also been developed (Gur et al., 2022; Furuta et al., 2023; Shaw et al., 2023), which are built on pre-trained language models, such as T5 (Raffel et al., 2020), Flan-T5 (Chung et al., 2022), HTML-T5 (Gur et al., 2023), or Pix2Struct (Lee et al., 2023), with web automation demonstrations. Those LMAs take HTML (or screenshots) and previous actions as inputs and predict the text-format next actions in a closed-loop manner. Since pre-trained language models have a sufficient inductive bias for web environments and instruction-following, finetuned LMAs can data-efficiently achieve competitive performance to the RL-finetuned agents trained from scratch with domain-specific architectures (Humphreys et al., 2022; Liu et al., 2018). Compared to the prompted LMAs relying on private LLM API, it is possible to build on-premise agents based on tractable-size models (at most 3 billion parameters), which may reduce inference time and costs. However, prior works have pointed out that finetuned LMAs struggle to the sub-optimal performance (Zheng et al., 2023) and they require demonstrations on the order of hundreds of thousands while prompted LMAs just need hundreds of episodes (Kim et al., 2023). In this paper, we extensively evaluate such finetuned LMAs in zero-shot transfer settings; LMAs are finetuned only with base task demonstrations and should deal with unseen compositional tasks. We call those transferred LMAs in the later sections.

4.5 DATA-REBALANCING IMPROVES FINETUNED LANGUAGE MODEL AGENTS

Furuta et al. (2023) utilized agent-driven data collection instead of humans to improve the performance of finetuned LMAs further. For each task, 10k demonstrations are collected and filtered based on task success, which resulted in challenging tasks having much less than 10k demonstrations due to the sub-optimal performance of LMA on these tasks. We identify that by fixing the data-imbalance problem, the performance of finetuned LMAs can be significantly improved, achieving super-human performance on MiniWoB. We first run Synapse (Zheng et al., 2023) on MiniWoB and collect 77K additional demonstrations across 16 tasks on top of 347K demonstrations (Furuta et al., 2023) to compensate for the lack of data in specific tasks. We then estimate the "brute-force" task difficulty averaging success rates for representative web automation agents. Based on those proximal measures, we classify 65 base tasks into three categories, such as easy (0.8 - 1.0), medium (0.6 - 0.8), and hard (0.0 - 0.6) (see Appendix D). We then balance the number of episodes based on the task difficulty, where we gradually reduce the ratio of easier tasks to focus more on challenging tasks. For instance, we remove X% episodes from top-k tasks in easy group (see Appendix E for the details).

We finetune HTML-T5-XL (Gur et al., 2023), a pre-trained language model with local and global attention in the encoder and a mixture of long-span denoising, on these rebalanced datasets. Table 1 shows that all the data-rebalance strategies improve the success rate, and reducing 50% episodes from easy tasks (finally 292K episodes in total) is the most effective rebalancing strategy. This suggests that finetuned LMAs can be as capable as prompted LMAs in decision making tasks. We include HTML-T5++ as a baseline in the following sections.

5 DESIGNING COMPWOB TO MEASURE COMPOSITIONAL GENERALIZATION

Even though MiniWoB includes a spectrum of simulated environments, they have still focused on narrow and single-task instances. We need more advanced environments to measure the generalization to the various challenges in real-world web automation, such as complex observation (Deng et al., 2023), instruction (Zhou et al., 2023b), and task compositionality (Gur et al., 2021). We design *CompWoB* (i.e. compositional MiniWoB), as a novel test bed for LMAs, by leveraging the high composability of simulated web environments (Figure 1). In CompWoB, we systematically combine several base tasks (from 2 to 8) in the original MiniWoB, which LMAs can already solve, into a single task (e.g. click-checkboxes-transfer+enter-password+click-dialog) \rightarrow click-checkboxes-transfer_enter-password_click-dialog). This allows us to control the complexity of HTML and instructions, ensuring novel tasks are solvable to some extent. CompWoB includes realistic task compositions, such as combining form filling, popup message, and login page, in a single or across multiple pages.

As mentioned in Section 4.5, we first calculate the average success rates among representative web automation agents as brute-force task complexity, and classify 65 primitive tasks in MiniWoB into 3



Figure 2: Average success rate of LMAs in 50 CompWoB tasks. The light color represents the performance in the original MiniWoB, and the dark color for CompWoB. We use gpt-3.5-turbo as the backbone LLM for prompted LMAs (RCI (Kim et al., 2023), AdaPlanner (Sun et al., 2023), Synapse (Zheng et al., 2023)), and transferred LMAs with 3-billion parameters. Transferred LMA, especially HTML-T5++, achieves the best generalization in compositional tasks, suppressing the performance degradation (from 95.2% to 61.5%). On the contrary, prompted LMAs drop their performance significantly; even the best RCI that uses combined task prompts in the composition just achieves 28.7% success (from 90.6% in base tasks). This indicates, in contrast to the base task performances, prompted LMAs are more vulnerable to, and transferred LMAs can deal with unknown task compositionality better than expected.

categories (easy, medium, hard) based on those scores. The details of classification are described in Appendix D. We randomly select base tasks from easy group, filter those combinations by their feasibility, and make 50 compositional tasks. We divide those into five categories: **two-way** tasks (20), **three-way** tasks (10), **n-way** tasks (5), **transition** tasks (5), and **easy-medium two-way** tasks (10). In n-way tasks, we combine from 4 to 8 tasks sequentially, and in transition tasks, we implement explicit page transition, for instance, transiting from the login form to the email browser. We also sample several tasks from medium group to construct easy-medium two-way tasks. You can find the full list of tasks in Appendix H. We simply stitch the instructions with "*and then*" and put each HTML on the same depth. LMAs should satisfy the given instructions sequentially, such as from task A, B, to C. Moreover, to test whether LMAs can deal with complex and ambiguous instructions, we propose **reverse-order instruction** settings, where the instruction is provided upside down while its task order is semantically the same (e.g. solve task B and C, after solving A). These simple yet controllable strategies make the analysis of LMA's behaviors tractable while reflecting compositional aspects of real-world tasks.

6 RESULTS

Evaluation Methodology We evaluate both transferred and prompted LMAs with base MiniWoB demonstrations on the unseen compositional tasks in a "zero-shot" manner; i.e. we do not provide any demonstrations on the compositional tasks for the training corpus and exemplars to measure the generalization. We test 50 compositional tasks and run 100 episodes per task. We adopt gpt-3.5-turbo as a backbone LLM, unless otherwise mentioned. We assume the optimal exemplar retriever throughout experiments and always provide the pre-defined prompts to LMAs. We borrow hyper-parameters and prompt templates from respective papers with minimal change to respect our zero-shot transfer setting.

RCI We test 4 prompting strategies: (1) zero-shot (without any exemplars), few-shot with (2) first-task exemplars, (3) second-task exemplars, and (4) combination exemplars (i.e. both first and second tasks). For consistency and limited context length, we always consider the first two tasks even if the number of primitive tasks is more than two, and fix the number of self-improvement iterations to 1 explicit RCI and 3 implicit RCI as recommended in the original paper. The exemplars we use are provided by Kim et al. (2023).

AdaPlanner Following the original implementation, we use the exemplars provided by Sun et al. (2023) for the tasks where those base tasks are included, such as enter-text and click-widget (see Appendix C.2). Otherwise, the agents are prompted in a zero-shot manner.

Synapse We test 3 prompting strategies: few-shot with (1) first-task exemplars, (2) second-task exemplars, and (3) best exemplars (i.e. maximum score between (1) and (2)). Because prompts and



Figure 3: Average success rate of language model agents in **reverse-order instruction** settings. We use gpt-3.5-turbo as the backbone LLM for prompted LMAs (RCI, AdaPlanner, Synapse), and transferred LMAs with 3-billion parameters. Notably, most LMAs significantly degrade the success rate when reverse-order instructions are provided. This trend is more remarkable in transferred LMA (from 54.8% to 31.0% on average) than prompted LMA (from 24.9% to 18.0% on average), which suggests that any kind of LMAs are susceptible to the order of compositional instructions. The capability as general language models might be important to parse semantically complex instructions into the correct plan.

modules are quite different among the primitive tasks, we do not merge the prompts and just use proper hyper-parameters corresponding to the given exemplars designed by Zheng et al. (2023).

6.1 LANGUAGE MODEL AGENTS STRUGGLE TO HANDLE TASK COMPOSITIONALITY

Figure 2 shows that, in CompWoB, all the LMAs face performance degradation. Among those, transferred LMAs achieve better success rate (54.8%) than prompted LMAs (24.9%) on average. In particular, HTML-T5++ achieves the best generalization while suppressing the performance drop from 95.2% to 61.5%. In contrast, prompted LMAs degrade their performance drastically; even the best RCI with few-shot combination exemplars (comb) just degrades the success rate to 28.7% from 90.6% in base MiniWoB. These results indicate that LMAs suffer from generalization to task compositionality, and transferred LMAs can relatively deal with that better than prompted LMAs, which is an opposite trend to base MiniWoB performance. Among prompted LMAs, RCI performs better than AdaPlanner and Synapse, which suggests that multiple iterations of self-criticism and improvement might be more robust to out-of-domain decision making from the exemplars than program synthesis with feedback or structured prompting with state translations.

In the failure episodes (Table 2), LMAs often miss necessary steps, common to all the prompted LMAs. Since the instructions get long in compositional settings, LMAs may skip important intermediate steps to satisfy the instructions. In addition, they predict incorrect action types and XPath: for instance, hallucination in XPath (RCI) and mixing up *click* and *type* action (Synapse).

6.2 REVERSE-ORDER INSTRUCTIONS DEGRADE LANGUAGE MODEL AGENTS

As shown in Figure 3, all the LMAs significantly degrade the success rate when reverse-order instructions are provided. This trend is more remarkable in transferred LMAs dropping from 54.8% to 31.0% than prompted LMAs from 24.9% to 18.0% on average, which suggests that any kind of LMAs is susceptible to the order of compositional instructions and that transferred LMAs may not generalize well to diverse instructions beyond the dataset distribution. As opposed to Section 6.1, the performance differences among prompted LMAs are marginal, which implies that existing prompting methods, even with self-improvement, may not handle complex task instructions enough. The stronger capability as general-purpose language models or other prompting methods might be important to parse semantically complex instructions into the executable sequential plan.

RCI (Kim e	et al., 2023)	AdaPlanner (St	ın et al., 2023)	Synapse (Zheng et al., 2023)		
Click button ONE, then click button fUK3 and click Submit	n TWO, and then select whX, 1Nk,	Enter the password "UBKR" into both text fields, and then select KwpUv and click Submit Submit Submit Submit			" into the text field and	
v	×	V	×	 ✓ 	×	
1. click //button[@id="subbtn1"]	1. type //button[@id="subbtn2"]	1. click //*[@id="password"]		1. click //*[text()="yE"]/input		
click //button[@id="subbtn2"]	2. click //*[text()="whX"]/input	2. type UBKR	 type UBKR 	2. click //input[@id="tt"]	 click //input[@id="tt"] 	
click //*[text()="whX"]/input	click //*[text()="1Nk"]/input	click //*[@id="verify"]			2. type yE	
4. click //*[text()="1Nk"]/input	click //*[text()="fUK3"]/input	4. type UBKR	type UBKR	3. type Juan	type Juan	
5. click //*[text()="fUK3"]/input	5. click //*[text()="gSm"]/input	5. click //input[@id="ch0"]	click //input[@id="ch0"]	4. click //*[@id="subbtn"]	click //*[@id="subbtn"]	
6. click //*[@id="subbtn"]	click //*[@id="subbtn"]	6. click //*[@id="subbtn"]	click //*[@id="subbtn"]			

Table 2: Failure examples in CompWoB. The left columns have correct plans and the right columns have failure plans. LMAs often ignore necessary intermediate steps or predict incorrect action types and XPath.



Figure 4: Average success rate of large language models with advanced LLMs (gpt-4 for RCI and Synapse, and text-davinci-003 for AdaPlanner). The lighter color represents the performance in MiniWoB, the medium color does in CompWoB with gpt-3.5-turbo, and the darker color does with gpt-4 or text-davinci-003. The more capable models (gpt-4 as a generalist and text-davinci-003 as a coder) can improve the success rate of prompted LMAs but still struggle to generalize to compositional tasks (e.g. 56.0% by RCI) or to deal with reverse-order instructions (e.g. 43.5% by RCI). This may indicate that we need much better foundation models to realize deployable LMA in the complex real world.

Compared to Section 6.1, LMAs cannot parse reverse-order instructions into plans correctly (Table 3), which is observed with RCI and Synapse but not with AdaPlanner. LMAs still fail to select correct action types (AdaPlanner) or XPath (Synapse), and they also predict unnecessary actions (RCI).

6.3 DO ADVANCED LLMs SOLVE COMPOSITIONAL TASKS?

Figure 4 presents the results when we adopt other advanced LLMs, than gpt-3.5-turbo, as a backbone of each LMA. The more capable models, such as gpt-4 in a generalist aspect and text-davinci-003 in a code generation, can improve the success rate of all the prompted LMAs. However, even gpt-4 is still far from the generalization in compositional tasks (from 28.7% to 56.0% by RCI) or from dealing with reverse-order instructions (from 19.2% to 43.5% by RCI). This indicates that we need much better foundation models to realize deployable LMA in complex real-world decision-making tasks. We provide failure examples in Appendix G.

6.4 WHAT DETERMINES TASK COMPLEXITY IN WEB AUTOMATION?

Figure 5 visualizes the correlation between the success rate averaged across WebGUM, HTML-T5, RCI, AdaPlanner, and Synapse (y-axis) and each statistic of compositional tasks (x-axis), such as synthesized success rate – a product of base task success rates among compositional tasks – the number of instruction tokens, and max depth of HTML subtrees. Synthesized success rate positively correlates with an average success rate (R = 0.691), indicating that compositional task difficulty takes over base task difficulties. In addition, the number of instruction tokens (R = -0.579) and the max depth of HTML subtrees (R = -0.433) show negative correlations. All those are statistically significant in paired t-test with p < 0.01. In contrast, other task statistics, such as synthesized success rate with human performance, the number of HTML tokens, and elements in HTML, just show relatively weaker correlations (see Appendix F for the details). This analysis suggests that HTML with larger depth and long instructions make generalizing compositional tasks challenging. The complexity of HTML is determined by its depth rather than its length or the number of elements. This might come from the hierarchical nature of HTML: in deeper HTML subtrees, the elements near the root tend to be distant from each other after the traversal. Such sparsity may cause confusion during planning.

RCI (Kim	et al., 2023)	AdaPlanner (S	un et al., 2023)	Synapse (Zheng et al., 2023)			
Select rJ and click Submit, after	r clicking on the "yes" button	Select OkRi7, and click Submit, afte	er clicking on the "previous" button	Select 2ld1 and click Submit, after into both text fields	r entering the password "Zy4XI"		
V	×	V	× ×	× ×			
1. click //button[text()="yes"]	1. click //*[text()="rj"]/input	1. click //*[text()="previous"]	1. click //*[text()="previous"]	1. click //*[@type="password"]	1. click //*[text()="2ld1"]/input		
click //*[text()="rj"]/input	click //button[text()="yes"]	2. click //*[text()="OkRi7"]/input	2. type OkRi7	2. type Zy4XI	click //*[@type="password"][1]		
	type rj	click //*[@id="subbtn"]	click //*[@id="subbtn"]	click //*[text()="verify"]	type Zy4XI		
click //*[@id="subbtn"]	click //*[@id="subbtn"]			4. type Zy4XI	click //*[@type="password"][2]		
			1	5. click //*[text()="2ld1"]/input	5. type Zy4XI		
				click //*[@id="subbtn"]	click //*[@id="subbtn"]		

Table 3: Failure examples in CompWoB with **reverse-order** instructions. LMAs often fail to parse the instruction into the correct-order plan, and hallucinate unnecessary actions (e.g. *type*).



Figure 5: 2D-scatter plots between success rate averaged among LMAs (y-axis) and each statistic of compositional task (x-axis), such as success rate synthesized with a product of base task success rate, the number of instruction tokens, and max depth of HTML subtrees. Synthesized success rate positively correlates with an average success rate (R = 0.691, statistically significant in paired t-test with p < 0.01), indicating that base task difficulty may determine compositional task difficulty. In addition, the number of instruction tokens (R = -0.579; p < 0.01) and the max depth of HTML subtrees (R = -0.433; p < 0.01) show negative correlations, which suggests the high complexity of observation and long instructions make the compositional tasks hard to resolve.

7 DISCUSSION

Generalizable Prompting Methods The results of Synapse and RCI in Figure 2 imply that those prompted LMAs have some "over-fitting" trends to the base MiniWoB tasks. While the robustness across the prompts has been investigated in natural language tasks (Wei et al., 2022; Kojima et al., 2022), it is not well understood in the decision making problems. Because we will not be able to prepare the optimal self-improvement iterations or decomposed prompts for all the possible instructions and task compositions, even if using optimal exemplar retrievers, we should care more about the generalization of prompting methods for the agent systems.

Agent-Specialized Large Language Models As shown in Figure 4, the more capable LLMs, such as gpt-4, can improve the performance of LMAs in CompWoB. However, it has not reached the base MiniWoB yet (e.g. from 90.6% to 56.0% in RCI, and from 98.5% to 41.4% in Synapse). Similarly, as described in Section 4.4, transferred LMAs can perform better if the training dataset has a good balance and coverage, but it is far from sufficient compositional generalization or instruction generalization. The current pre-trained LLMs may still not be sufficient to generalize to complex decision making tasks, and then, in addition to prompting methods, the development of agent-specialized LLMs with enhanced reasoning and generalization would be expected.

Parsing Complex Instructions to Executable Plan Section 6.2 highlights that LMAs are fragile when we increase the complexity of instruction even by the most straightforward reverse-order instructions. This may not be preferable for the real-world application since the instructions might not be easy-to-parse and the users should carefully and concisely tell what they would like to do, which hinders the user's experience. It would be an interesting future direction to investigate better planning modules that could parse complex instructions to correct and executable plans.

8 CONCLUSION

The robustness and generalization of LMAs are important aspects for real-world deployment. We extensively examine how much existing LMAs, via transferring and prompting, can deal with a set of compositional web automation environments, CompWoB, that consists of easily-resolvable base primitive tasks. Our evaluation implies the contrary conclusion to the prior works (Table 4); the prompted LMAs are strong solver for primitive web automation tasks but significantly drop their performance in unknown task compositionality. The transferred LMAs often show sub-optimal performance in basic tasks but can deal with compositional problems much better. Our detailed analysis also highlights that LMAs also face catastrophic degradation when they receive complex, even in the simplest reversed-order instructions, and that the challenges in compositional tasks might come from instruction length and the depth of HTML subtree. We hope this inspires the community to build robust and generalizable LMAs to task compositionality toward real-world application.

	Base MiniWoB	CompWoB	Reverse-Order Instructions	Advanced Models
Prompted LMA	94.0 % / 98.5 %	24.9% / 28.7%	18.0% / 19.2%	42.3% / 56.0%
Transferred LMA	85.4% / 95.2%	54.8 % / 61.5 %	31.0 % / 34.3 %	

Table 4: Summary of average / max success rate in web automation.

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APPENDIX

A DETAILS OF LLM API

We used OpenAI API to call LLM inference in our experiments. Table 5 shows the API used for each method. We did most of our experiments from 2023/07 to 2023/09. We use the official implementations and prompts released by the authors ²³⁴. We spent about \$3.6K for the experiments in total.

Methods	API	Cost (input/output; /1K tokens)	Context Length
RCI (Kim et al., 2023)	gpt-3.5-turbo	\$0.0015 / \$0.002	4K tokens
	gpt-4	\$0.03 / \$0.06	8K tokens
AdaPlanner (Sun et al., 2023)	gpt-3.5-turbo	\$0.0015 / \$0.002	4K tokens
	text-davinci-003	\$0.02 / \$0.02	4K tokens
Synapse (Zheng et al., 2023)	gpt-3.5-turbo	\$0.0015 / \$0.002	4K tokens
	gpt-4	\$0.03 / \$0.06	8K tokens

Table 5: List of LLM API used in this paper. We did those experiments from 2023/07 to 2023/09.

B PSEUDO CODE FOR PROMPTED LANGUAGE MODEL AGENTS

Algorithm 1 Prompted Language Model Agents: RCI, AdaPlanner, Synapse

Input: prompt *P*, LMA π , task ψ , environment Env, large language model LLM, number of ERCI N_{ERCI} , number of IRCI N_{IRCI}

1:	$s, g \leftarrow \texttt{Env.reset}(\psi)$	
2:	$s, g \leftarrow \texttt{LLM}(\cdot P_{\texttt{syn}}, s, g)$	▷ Task Reformulation (Synapse)
3:	history $\leftarrow \{\}$	
4:	while Env is not terminated do	
5:	$\{a_1,, a_T\} \leftarrow \pi(\cdot P_\pi, s, g)$	▷ Planning
6:	for i in range($N_{ m ERCI}$) do	
7:	$\texttt{criticism} \leftarrow \texttt{LLM}(\cdot P_{rci}, \{a_1,, a_T\})$	▷ Criticism (RCI)
8:	$\{a_1,,a_T\} \leftarrow \pi(\cdot P_\pi,s,g,\{a_1,,a_T\},\texttt{criticism})$)
9:	end for	
10:	for a in $\{a_1,, a_T\}$ do	
11:	for j in <code>range(N_{IRCI})</code> do	
12:	$a \leftarrow \pi(\cdot P_{\pi}, s, g, \{a,, a_T\}, \texttt{history})$	▷ Improvement (RCI)
13:	end for	
14:	$s, r, info \leftarrow \texttt{Env.step}(\texttt{a})$	
15:	$\{a,,a_T\} \leftarrow \pi(\cdot P_{\pi},s,g,\{a,,a_T\},\texttt{history},\texttt{info}$) Replanning (AdaPlanner)
16:	history \leftarrow history \cup $\{a\}$	
17:	end for	
18:	end while	

²https://github.com/posgnu/rci-agent

³https://github.com/haotiansun14/AdaPlanner

⁴https://github.com/ltzheng/Synapse

C DETAILS OF HYPER-PARAMETERS

C.1 RCI

As we described in Section 4.1, RCI has two important hyper-parameters to control the number of self-improvement iterations. In Explicit RCI (ERCI) loop, LLMs criticize their own generated plans to identify the problem and then improve it, reflecting self-criticism. In Implicit RCI (IRCI) loop, LLMs ground the action to the current state (i.e. HTML) and refine its formatting to be parable without self-criticism, which may reduce hallucinations or tiny errors. We here test how many self-improvement loops RCI requires (IRCI: 1-4, ERCI: 0-2). Table 6 shows that the optimal number of inference loops is different among tasks, while the recommendations are ERCI = 1 and IRCI = 3. These two hyper-parameters might need to be adjusted for each task.

		(ERCI, IRCI)										
Tasks	(0,1)	(0,2)	(0,3)	(0,4)	(1,1)	(1,2)	(1,3)	(1,4)	(2,1)	(2,2)	(2,3)	(2,4)
click-button	1.00	1.00	1.00	1.00	0.92	0.84	0.87	0.88	0.93	0.86	0.87	0.87
click-checkboxes	0.90	0.94	0.87	0.91	0.96	0.94	0.97	1.00	0.89	0.91	0.94	0.99
click-dialog	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
click-link	0.96	0.95	0.98	0.99	0.91	0.91	0.89	0.88	0.95	0.91	0.91	0.87
click-option	0.82	0.77	0.79	0.87	0.41	0.54	0.56	0.52	0.83	0.82	0.73	0.87
click-scroll-list	0.86	0.86	0.84	0.83	0.75	0.81	0.78	0.79	0.76	0.81	0.85	0.74

Table 6: The success rate of RCI with different hyper-parameters. The optimal parameters differ in each task, while the recommended one is (1,3).

C.2 ADAPLANNER

We use the demonstrations of these 13 tasks where they are included in the task composition:

- enter-text
- click-widget
- navigate-tree
- login-user-popup
- email-inbox-forward-nl-turk
- click-checkboxes-large
- click-tab-2-hard
- click-dialog-2
- search-engine
- click-checkboxes-soft
- use-autocomplete
- enter-date
- click-dialog-2

C.3 SYNAPSE

As we explained in Section 4.3, Synapse has several hyper-parameters to construct optimal structured prompts per task to specify whether LLMs translate the instruction or HTML.

Table 7 summarizes the type of reformulation into 7 categories and clarifies which transformed inputs are used for predicting open-loop plans. For instance, Task only requires translated instructions (and few-shot planning exemplars), although Obs takes raw instruction, HTML, and translated HTML as inputs. For the tasks that require temporal abstraction, it also employs state-conditional decomposition, which factorizes demonstrations into a set of exemplars conditioned on the environmental states, and can reduce error accumulation over the time step.

Table 8 provides the detailed values for state-filtering and task reformulation, which is quite different across the tasks. These well-designed structured prompts could be the source of the best performance in base MiniWoB. However, in compositional settings, it is challenging to modify them for any combinations. Instead, we assume the optimal retriever always picks up the exemplars for one of the base tasks, and we compute the maximum score among the results with given prompts.

	Reformulation Strategies									
Inputs	Task	Obs	Obs_Task	Obs_Task_Filter	Raw_Task	None	None_Filter			
Instruction HTML	Translated	Raw Raw+Translated	Translated Raw+Translated	Translated Translated	Raw ×	Raw Raw	Raw Translated			

Table 7:	Summary	of task	reformulation	for	structured	prompting	used	in	Synapse	(Zheng	et	al.,	2023).
Structured	prompts a	re finely	designed per ta	ask.									

Tasks	State Filtering	Exemplar Decomposition	Raw Task Only	Reformulation
book-flight	True	True	False	None
choose-date	False	False	False	Task
choose-list	False	False	True	None
click-button	False	False	False	None
click-button-sequence	False	False	False	None
click-checkboxes	False	False	True	None
click-checkboxes-large	False	False	True	None
click-checkboxes-soft	False	False	False	Obs
click-checkboxes-transfer	False	False	True	None
click-collapsible	False	False	True	None Ob a Ta ala
click-collapsible-2	False	False	Faise	Obs Task
	False	False	True	None
click-dialog	False	False	Falsa	None
click-dialog-2	False	False	Taise	None
click monu	False	False	True	Toole
click option	False	False	True	None
click pie	False	False	True	None
click-scroll-list	False	False	True	None
click-shades	False	False	True	Tack
click-shape	True	False	False	Obs Task
click-tab	False	False	True	None
click-tab-2	True	False	False	Obs Task
click-tab-2-hard	True	False	False	Obs Task
click-test	False	False	False	None
click-test-2	False	False	False	None
click-widget	False	False	True	None
copy-paste	False	False	False	None
copy-paste-2	False	False	False	None
count-shape	True	False	False	Obs Task
email-inbox	False	False	False	Task
email-inbox-forward-nl	False	False	False	Task
email-inbox-forward-nl-turk	False	False	False	Task
email-inbox-nl-turk	False	False	False	Task
enter-date	False	False	True	None
enter-password	False	False	True	None
enter-text	False	False	True	None
enter-text-dynamic	False	False	True	None
enter-time	False	False	True	None
find-word	True	False	False	None
focus-text	False	False	True	None
focus-text-2	False	False	True	None
grid-coordinate	False	False	True	None
guess-number	False	False	False	None
identify-shape	False	False	False	None
login-user	False	False	True	None
login-user-popup	False	False	True	None
multi orderinge	False	False	False	None
multi-orderings	False	False	False	None
navigate-tiee	Faise	False	Faise	None
search-engine	False	False	raise Trave	None
simple algebra	False	False	Folco	None
simple-arithmetic	False	False	False	None
social-media	False	False	False	Obs Task
social-media-all	False	False	True	None
social-media-some	False	False	True	None
terminal	False	True	False	None
text-transform	False	False	False	None
tic-tac-toe	True	False	False	Obs Task
unicode-test	False	False	False	None
use-autocomplete	False	True	False	None
use-spinner	False	False	False	Task
P	1 4150	1 disc	1 4130	rusk

Table 8: Hyperparameters for Synapse (Zheng et al., 2023). Raw Task Only is specified with Task as **Reformation** flag, and **Reformulation** is specified with **Reformat Input** flag in the original imprementation.

D RANKING BASE MINIWOB TASKS

To ensure the solvability of CompWoB to some extent and to identify the data-redundant tasks for finetuned LMAs, we estimate the brute-force task difficulty (Furuta et al., 2021) (Table 9). We compute the average success rate for each task across representative previous web automation agents, such as CC-Net (SL, SL+RL) (Humphreys et al., 2022), WGE (Liu et al., 2018), WebN-T5 (Gur et al., 2022), WebGUM (Furuta et al., 2023), HTML-T5 (Gur et al., 2023), RCI (Kim et al., 2023), AdaPlanner (Sun et al., 2023), Pix2Act (BC, RL) (Shaw et al., 2023), and Synapse (Zheng et al., 2023). Based on those proxy difficulty measures, we classify 65 tasks into three categories (Kim et al., 2023): easy (from 0.8 to 1.0), medium (from 0.6 to 0.8), and hard (from 0.0 to 0.6).

Category	Task	Task Difficulty
	click-button	0.923
	click-button-sequence	0.954
	click-checkboxes	0.936
	click-checkboxes-transfer	0.862
	click-collapsible	0.878
	click-dialog	0.923
	click-link	0.949
	click-option	0.839
	click-tab	0.898
	click-test	1.000
	click-test-2	0.996
	click-widget	0.945
easy (0.8 - 1.0)	email inbox forward nl turk	0.844
	entar password	0.804
	enter-text	0.090
	enter-text-dynamic	0.922
	focus-text	0.999
	focus-text-2	0.990
	grid-coordinate	0.920
	identify-shape	0.918
	login-user	0.881
	login-user-popup	0.818
	multi-layouts	0.832
	navigate-tree	0.825
	unicode-test	0.900
	choose-date-easy	0.740
	click-checkboxes-large	0.784
	click-checkboxes-solt	0.734
	click-collapsible-2	0.693
	click dialog 2	0.742
	click-menu	0.700
	click-pie	0.007
	click-shape	0.664
	click-tab-2	0.736
	click-tab-2-hard	0.651
medium(0.6-0.8)	copy-paste	0.610
	email-inbox	0.778
	email-inbox-nl-turk	0.779
	enter-date	0.714
	multi-orderings	0.793
	read-table	0.660
	search-engine	0.723
	simple-algebra	0.799
	simple-arithmetic	0.782
	social-media text transform	0.733
	use-autocomplete	0.737
	book-flight	0.510
	choose-date	0.331
	choose-date-medium	0.497
	choose-list	0.520
	click-scroll-list	0.401
	click-shades	0.501
	copy-paste-2	0.547
hard $(0.0 - 0.6)$	count-shape	0.536
nara (0.0 - 0.0)	enter-time	0.521
	find-word	0.590
	guess-number	0.363
	social-media-all	0.432
	social-media-some	0.532
	tia taa taa	0.592
	uc-tac-toe	0.598
	use-spinner	0.457

Table 9: Brute-force task complexity and difficulty classification of MiniWoB. We split 65 tasks into the three category based on the task complexity: easy (0.8 - 1.0), medium (0.6 - 0.8), and hard (0.0 - 0.6).

E DETAILS OF MINIWOB DATASET

To resolve the data-imbalance problem, we first run Synapse (Zheng et al., 2023) on MiniWoB and collect 77K additional demonstrations across 16 tasks on top of 347K demonstrations (Furuta et al., 2023) to compensate for the lack of data in specific tasks (Strategy A). We use PaLM 2-L (Anil et al., 2023) as a backbone LLM for Synapse. We then reduce the number of demonstrations for the tasks the agents can solve to focus on more challenging tasks. Based on brute-force task complexity (Appendix D), we consider the following four strategies:

- Removing 50% episodes from top-10 easy tasks (Strategy B; -63K)
- Removing 80% episodes from top-10 easy tasks (Strategy C; -92K)
- Removing 50% episodes from easy tasks (Strategy D; -132K)
- Removing 80% episodes from top-15 easy tasks and removing 50% episodes from other 11 easy tasks (Strategy E; -165K)

Through the empirical evaluations (Section 4.4), we find that **Strategy D** realizes a well-balanced dataset to improve the performance.

Task	Original (347K)	Strat. A (424K)	Strat. B (361K)	Strat. C (332K)	Strat. D (292K)	Strat. E (259K)
book-flight	2.88%	2.49%	2.84%	3.11%	3.54%	4.15%
choose-date	0.11%	1.25%	1.42%	1.55%	1.77%	2.07%
choose-date-easy	0.97%	0.84%	0.95%	1.04%	1.19%	1.39%
choose-date-medium	0.64%	0.55%	0.63%	0.69%	0.79%	0.92%
choose-list	0.54%	1.24%	1.42%	1.55%	1.77%	2.07%
click-button	2.82%	2.44%	1 39%	0.61%	1 73%	0.81%
click-button-sequence	2.88%	2.49%	1 42%	0.62%	1 77%	0.83%
click-checkboxes	2.80%	2 43%	1 36%	0.55%	1.69%	0.73%
click-checkboxes-large	0.57%	2.45%	2.46%	2 10%	3.06%	3 58%
click-checkboxes-soft	2.66%	2.15%	2.40%	2.47%	3 27%	3 83%
click-checkboxes-transfer	2.00%	2.50%	2.05%	2.07%	1 77%	2.07%
click-collapsible	1.71%	2.49%	2.65%	1.85%	1.77%	1.24%
click collapsible 2	0.62%	0.55%	0.63%	0.68%	0.78%	0.01%
click color	0.03%	1 220/	1 40%	1 520/	1 7404	2.04%
alial dialag	2.000	2.40%	2.950	2 110	1.74%	2.04%
click-dialog	2.88%	2.49%	2.83%	5.11%	1.77%	0.85%
click-dialog-2	0.95%	1.30%	1.55%	1.70%	1.95%	2.20%
click-link	2.87%	2.48%	1.42%	0.62%	1.76%	0.83%
click-menu	0.93%	1.24%	1.42%	1.55%	1.77%	2.07%
click-option	2.88%	2.49%	2.84%	3.11%	1.77%	2.07%
click-pie	1.07%	2.32%	2.65%	2.90%	3.30%	3.86%
click-scroll-list	0.00%	1.01%	1.16%	1.26%	1.44%	1.69%
click-shades	0.00%	1.25%	1.42%	1.55%	1.77%	2.07%
click-shape	1.76%	1.80%	2.05%	2.24%	2.56%	2.99%
click-tab	2.88%	2.49%	2.84%	3.10%	1.77%	2.07%
click-tab-2	0.53%	0.46%	0.52%	0.57%	0.65%	0.76%
click-tab-2-hard	0.45%	1.67%	1.91%	2.09%	2.38%	2.78%
click-test	2.88%	2.49%	1.42%	0.62%	1.77%	0.83%
click-test-2	2.88%	2.49%	1.42%	0.62%	1.77%	0.83%
click-widget	2.87%	2.48%	1.41%	0.62%	1.76%	0.82%
count-shape	1.69%	1.10%	1.26%	1.37%	1.56%	1.83%
email-inbox	1.49%	1.29%	1.47%	1.60%	1.83%	2.14%
email-inbox-forward-nl	2.88%	2.49%	2.84%	3.11%	1.77%	2.07%
email-inbox-forward-nl-turk	1.41%	1.22%	1.39%	1.52%	0.86%	1.01%
email-inbox-nl-turk	1.25%	1.08%	1.24%	1.35%	1.54%	1.80%
enter-date	2.88%	2.49%	2.85%	3.11%	3.54%	4.15%
enter-password	2.88%	2.49%	2.84%	3.10%	1.77%	2.07%
enter-text	2.88%	2.49%	2.85%	3.11%	1.77%	0.83%
enter-text-dynamic	2.88%	2.49%	1 42%	0.62%	1 77%	0.83%
enter-time	0.00%	1.08%	1.23%	1.35%	1.54%	1.80%
focus-text	2 88%	2 49%	1 42%	0.62%	1 77%	0.83%
focus-text-2	2.88%	2 49%	1 42%	0.62%	1 77%	0.83%
grid-coordinate	2.00%	2.49%	2 38%	2.60%	1.41%	0.55%
guess-number	0.20%	1 25%	1.42%	1.55%	1.77%	2.07%
identify_shape	2.60%	2 24%	2.56%	2 80%	1.60%	0.75%
login user	2.00%	2.2470	2.50%	2.00%	1 720/	2.03%
login-user nonun	2.8270	2.4470	2.1970	2.03%	1.73%	2.03%
nogin-user-popup	2.82%	2.44%	2.10%	5.04% 2.110/	1./3%	2.03%
muni-nayouts	2.00%	2.49%	2.63%	5.11%	1.77%	2.07%
muni-ordenings	2.88%	2.49%	2.85%	3.11%	5.54%	4.15%
navigate-tree	2.84%	2.46%	2.81%	3.07%	1.73%	2.02%
searcn-engine	2.56%	2.21%	2.52%	2.76%	3.14%	3.08%
social-media	0.76&	0.66%	0.75%	0.82%	0.93%	1.09%
social-media-all	0.03%	0.02%	0.03%	0.03%	0.03%	0.04%
social-media-some	0.09&	0.08%	0.09%	0.10%	0.11%	0.13%
uc-tac-toe	1.14%	1.43%	1.63%	1.78%	2.03%	2.37%
use-autocomplete	1.00%	0.86%	0.99%	1.08%	1.23%	1.44%
use-spinner	0.15%	1.19%	1.36%	1.48%	1.69%	1.98%

Table 10: Task ratio in rebalanced dataset for HTML-T5++.



F TASK COMPLEXITY ANALYSIS IN WEB AUTOMATION

Figure 6: 2D-scatter plots between success rate averaged among LMAs (y-axis) and each statistic of compositional task (x-axis), such as success rate synthesized with a product of base task success rate, the number of instruction tokens, max depth of HTML subtrees, success rate synthesized with a product of base task human performances, the number of elements in HTML, and the number of HTML tokens. Synthesized success rate positively correlates with an average success rate (R = 0.691, statistically significant in paired t-test with p < 0.01), indicating that base task difficulty may determine compositional task difficulty. In addition, the number of instruction tokens (R = -0.579; p < 0.01) and the max depth of HTML subtrees (R = -0.433; p < 0.01) show negative correlations, which suggests the high complexity of observation and long instructions make the compositional tasks hard to resolve. In contrast, synthesized success rate from human performance, the number of HTML tokens, and elements in HTML just show relatively weaker correlations.

G FAILURE EXAMPLES WITH ADVANCED LANGUAGE MODELS

We provide several failure episodes with advanced language models such as gpt-4 and text-davinci-003 in Table 11. The left columns have correct plans, and the right columns have failure plans. Compared to gpt-3.5-turbo (Table 2), LMAs based on advanced models may not ignore the necessary intermediate actions. However, they tend to suffer from tiny errors such as capitalization (RCI, AdaPlanner) or attributes in HTML (Synapse).

et al., 2023)	ername "cristin" and the press login	<pre>X 1. click //*[@id="0Qm9EUt"] 2. click //*[@id="username"] 3. type enistin 4. click //*[@id="password"] 5. type M5 6. click //*[@id="subbtn"]</pre>
Synapse (Zheng e	Select 0Qm9EUt, and then enter the us password "M5" into the text fields and	 l. click //*[text()="0Qm9EUt"]/input click //*[@id="username"] type cristin type cristin type M5 type M5 click //*[@id="password"]
un et al., 2023)	click on a "button" widget	<pre>X 1. click //span[text()="augue"] 2. click //*[@data-type="button"]</pre>
AdaPlanner (S	Click on the link "Augue", and then	 1. click //span[text()="Augue"] 2. click //*[@data-type="button"]
st al., 2023)	nen click on the "submit" button	<pre>X 1. click //span[text()="adipiscing"] 2. click //button[text()="Submit"]</pre>
RCI (Kim e	Click on the link "adipiscing", and th	 click //span[text()="adipiscing"] click //button[text()="submit"]

Table 11: Failure examples in CompWoB with advanced models (gpt-4, text-davinci-003).

Task	HTML-T5 (Gur et al., 2023)	HTML-T5++ (Ours)
book-flight	0.99	0.99
choose-date	0.16	1.00
choose-date-easy	1.00	1.00
choose-date-medium	0.56	1.00
choose-list	0.22	1.00
click-button	1.00	1.00
click-button-sequence	1.00	1.00
click-checkboxes	1.00	1.00
click-checkboxes-large	0.90	0.97
click-checkboxes-soft	0.99	1.00
click-checkboxes-transfer	1.00	1.00
click-collapsible	1.00	1.00
click-collapsible-2	0.93	0.96
click-color	1.00	1.00
click-dialog	1.00	1.00
click-dialog-2	0.74	1.00
click-link	0.99	1.00
click-menu	0.37	0.96
click-option	1.00	1.00
click-pie	0.96	0.94
click-scroll-list	0.99	1.00
click-shades	0.00	1.00
click-shape	0.79	0.95
click-tab	1.00	1.00
click-tab-2	0.94	0.98
click-tab-2-hard	0.88	0.96
click-test	1.00	1.00
click-test-2	1.00	1.00
click-widget	1.00	1.00
count-shape	0.67	0.92
email-inbox	1.00	0.98
email-inbox-forward-nl	1.00	1.00
email-inbox-forward-nl-turk	1.00	1.00
email-inbox-nl-turk	0.99	1.00
enter-date	1.00	1.00
enter-password	1.00	1.00
enter-text	1.00	1.00
enter-text-dynamic	1.00	1.00
enter-time	1.00	1.00
focus-text	1.00	1.00
focus-text-2	1.00	1.00
grid-coordinate	1.00	1.00
guess-number	0.13	1.00
identify-shape	1.00	1.00
login-user	1.00	1.00
login-user-popup	1.00	1.00
multi-layouts	1.00	1.00
multi-orderings	1.00	1.00
navigate-tree	0.99	1.00
search-engine	0.93	0.96
social-media	0.99	1.00
social-media-all	0.31	0.31
social-media-some	0.89	0.85
tic-tac-toe	0.57	0.55
use-autocomplete	0.97	0.99
use-spinner	0.07	0.06
Average	0.856	0.952

H PER-TASK PERFORMANCE ON MINIWOB AND COMPWOB

Table 12: Per-task average success rate on 56 tasks from MiniWoB++. We refer to Gur et al. (2023) for the baseline performance.

Task	WebGUM	HTML-T5	TML-TS++	RCI (zero) R	CI (first) RCI	(second) RC	(comb) RCI (ant-4) Svna	ose (first) Svn	anse (second) Svn	nanse (best) Svna	Dse (fant-4) Sv	nanse (stort -4) S	vnapse (b:ant -4)	AdaPlanner Ad	aPlanner (davinci)
				· · · · ·			· /		- A			A - 6 - 36		6 - 36 - X - 4 - 4		()
click-button_click-checkboxes	01710	00/100	0.790	0.5/0	07/10	0.730	0.800	0.880	07810	0.840	0.840	0.980	0.840	0.980	0.060	0.830
click-button_click-checkboxes-transfer	0100	0.600	0.750	0.270	06/10	06/.0	0.810	1.000	0.540	0.740	0.740	0960	0.740	0.960	0.000	016610
click-button_click-dialog	0/8/0	07/70	0.970	0.740	0.8.90	07870	0.940	0001	1.000	0.690	1.000	1.000	0.000	1.000	0.900	0.980
cick-button_cick-ink	01810	0.860	0.860	0.8/0	0.8.90	0.8/0	07.610	0760	0660	0000	0660	1.000	0000	1.000	04610	0/6/0
Lick-button_crick-option	0.00.0	0.040	0.040	09210	0.000	0.570	01/10	0.4.20	07.60	0.6/0	0760	00610	0.000	00610	0.000	0.000
disk button-sequence. disk boxes	0.640	0060	0.900	0.4440	0720	0.620	0.0.0	0.620	01/10	0.000	0.000	0.000	0.000	0.640	0000	0.080
	04670	00001	0.010		00000	07070	00700	0.000	00000	0000	0060	0000	00000	00000	0.000	064-0
circk with for the second s	0000	0600	01010	0.000	0.000	0.00	0.000	0.000	0000	0001	00001	0.000	0.000	0001	0.420	00000
alion time accounting the second se	0.020	0.07.0	1 000	0.000	0000	0.460	0.600	0.640	0000	0001	0000	00000	0000	0.000	0.540	0.400
diore-time-concerned diore-time alignment	0.040	0.000	0.000	0.550	0 5 20	0.800	0.000	0.780	0.370	0000	0370	0.800	0000	0.000	0.080	0.800
click-link entered as	0.130	0.900	1 000	0.090	0.160	0.200	0.060	0.840	0000	0.000	0000	0.000	0000	0.000	0.860	0.920
dick-must meta-	1 000	0.970	1 000	0.380	0130	0.410	0.500	0.880	0000	0.000	0000	1 000	0000	1 000	0.770	0.960
cuercoproductioner exit	0.980	1000	0.960	0000	0000	0000	0000	0.860	0000	0.000	0000	0.000	0000	0.000	0.000	0000
trace options and the second	0000	0.480	0.370	0.550	0.470	0.500	0.7.0	0.800	0000	0.240	00.00	0.560	0.060	0.000	0.620	0.500
aliante protectione de la companya d A la companya de la co	0.370	0.740	0.810	0.000	0000	0.000	0000	0.740	0000	0.000	0000	0.000	0000	0000	0.000	0.000
dick-widdert mithalework	0.430	0.400	0.220	0.000	0.000	0.000	0000	0.240	0000	0.760	0.760	0.000	1 000	1 000	0.000	0.000
enter-assessment of the section	1 000	0.690	0.000	0.000	0.020	0000	0000	0.780	0000	0.000	0000	0.000	0000	0000	0.000	0.000
login-use in aviatic-tree	0.000	0.040	0.140	0.020	0.010	0.000	0000	0.700	0000	0.000	0000	0.000	0000	0.000	0.000	0.000
multi-layouts_login-user	0.00.0	0.000	0.000	0.000	0.000	0.000	0.000	0.100	0.720	0.000	0.720	1.000	0.000	1.000	0.010	0.000
Average (two-way)	0.579	0.712	0.739	0.320	0.375	0.419	0.469	0.715	0.349	0.300	0.469	0.521	0.346	0.641	0.356	0.523
Alth Monte of the seden 1 when we have a set of the set	0110	0.600	OTEO	0.000	0110	0.000	0.000	0100	0000	0.000	0000	0.040	0.000	0000	0110	0000
aliate hatter a supervised of the supervised of	0.110	0700	0.770	0.500	0420	0.000	00000	07170	0000	0000	0000	0.440	0000	04670	04170	00000
aliat abadebases aliat widens aliat button communes	0000	0.500	0.750	0.400	0.660	0.000	04.0	0001	0510	00000	06.00	0.000	0.190	0000	0.590	00000
tick-citeck poxes_citec_wrate-citek-pointoil-sequence	00700	0100	0.000	0.0400	00000	0.000	07000	0.000.1	07000	0000	07070	0.000	00100	0.50.0	00000	0.420
alick-circk/boxes-tailstel_circk-buttory-sequence_cirite-jussword	00000	0100	0.010	00000	0000	0.000	0000	0000	0000	0000	0000	0000	00700	00000	0.000	00000
alich dialass a faith buitas ter tenter plass wat a cuta de la cuta	00000	0001	0000	0000	0000	0000	0000	002.0	0000	0.000	0000	00000	0000	0.000	0.000	0000
stick-table _ tick- buttor-set usive_static - bits word	0.69.0	0070	0001	0.000	00000	0.000	0.400	0.700	0000	0000	0000	0000	0000	0.000	0.000	00000
curve manage under einer eine anster einen wurden die Liter eine Leiner alse einen aussere einen wurden	0.730	0100	0.000	0.240	02.0	0.480	0.610	0.600	0000	0.600	0.600	0,000	0690	0.69.0	0.560	0.000
alot unidee a lot environmente di di lot	00100	0110	0.110	0010	0000	0000	0.200	00700	0000	0000	0000	0000	0000	0.000	0000	0000
cutes werget.cutes-option_cutes analog enter-missioned effek-checkboxes [origin-user-nomin	0110	00000	0.060	0.000	0000	0000	0000	0200	0000	0.000	0000	00000	0000	0000	0000	0000
A real for a real second se						0.000							0.000		0	
Av crage (three-way)	0.252	0.407	0.531	0.142	0.255	0.218	167.0	0.570	6.1SF	0.102	0.250	0.244	861.0	0.396	97170	0.130
click-button-sequence_click-widget_click-link_click-button_click-checkboxes_click-option_click-dialog	0.000	0.230	0.320	0.160	0.020	0.380	0.080	0.720	0000	0.000	0000	0.000	0.000	0.000	0.000	0.000
click-button-sequence_click-widget_click-link_click-button_click-checkboxes_click-option_click-dialog_login-user	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.620	0000	0.000	0000	0.000	0.000	0.000	0.000	0.000
click-link_click-button_click-checkboxes_click-dialog	0.280	0.630	0.810	0.150	0.230	0.320	0.370	0.540	0000	0.310	0.310	0.000	0.600	0.600	0.050	0.600
click-link_click-button_click-checkboxes_click-option_click-dialog	0.180	0.430	0.780	0.200	0.180	0.370	0.360	0.560	0000	0.060	0900	0.000	0.620	0.620	0.020	0.490
click-widget_click-link_click-button_click-checkboxes_click-option_click-diatog	0.000	0.040	0.140	0.140	0.360	0.100	0.300	0.480	0000	0.000	0000	0.000	0000	0.000	0.000	0.000
Average (n-way)	0.092	0.266	0.410	0.130	0.158	0.234	0.222	0.584	0000	0.074	0.074	0.000	0.244	0.244	0.014	0.218
click-checkboxes-transfer_multi-layouts_email-inbox-forward-ml-transition	0.240	0.460	0.650	0.000	00000	0.000	0.000	0.000	0000	0.000	0000	0.000	000'0	0.000	0.220	0.440
click-option_login-user-transition	0660	1.000	0.800	0.000	0.000	0.000	0.000	0.000	0000	0.000	0000	0.000	0.000	0.000	0.000	0.000
click-option_multi-layouts_click-widget_login-user-popup-transition	0.190	0.220	0.130	0.000	0.000	0.000	0.000	0.000	0000	0.000	0000	0.000	0.000	0.000	0.000	0.000
login-user_navigate-tree-transition	0.960	1.000	1.000	0.000	0.000	0.000	0000	0.460	0000	0.000	0000	0.340	0.000	0.340	0.000	0.000
login-user-popup_email-inbox-torward-ni-turk-transition	1.000	0960	0.910	0.000	0.000	0.200	0.000	07170	0000	0.000	0000	0.000	0000	0.000	0.700	0.560
Average (transition)	0.676	0.728	0.698	0.000	0.000	0.040	0.000	0.116	0000	0.000	0000	0.068	0.000	0.068	0.184	0.200
click-button_click-tab-2-hard	0.240	0.550	0.510	0.080	0.120	0.260	0.340	0.580	0.280	0.040	0.280	0960	0.320	0.960	0.260	0.280
click-button-sequence_use-autocomplete	0.410	0.220	0.840	0.200	0.060	0.640	0.160	0.820	0000	0.000	0000	0.420	0000	0.420	0.000	0.000
circk-check boxes-soft_enter-parsword	0.000	068.0	016.0	0.000	0.000	0.00	0000	07.970	0000	0.000	0000	0000	0000	0.000	0.000	0.000
circk-creek boxes-sort_muit-tayouts	00000	0470	0.170	0.000	00000	0.000	0000	07170	0000	0.000	0000	0000	0260	0.26.0	0000	0,000
click datage searched give	026.0	0/60	0.440	0.000	07070	0000	0000	07600	0010	0.000	0010	0.000	0000	0,000	0.160	0010
etter katalogi – Etter er waget etter katalogi – 2. Josin Jase – norma	0330	0440	0.360	0,000	0000	0000	0000	0.060	0000	0,000	0000	0.000	0000	0.000	0000	0000
click wings the checkbo was soft	0.120	0.290	0.460	0.080	0.100	0.060	0.200	0.600	0000	0.000	0000	0.000	0.000	0.000	0.100	0.140
enter-date_login-user	066.0	1.000	0.230	0.000	0.020	0.000	0.060	0.500	0.000	0.000	0.000	0.000	0.000	0.000	0.380	0.380
use-autocomplete_click-dialog	0.000	0.000	0.000	0.000	0.080	0.000	0.080	0.060	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
Average (two-way, easy-medium)	0.521	0.502	0.511	0.046	0.040	0.096	0.088	0.450	0.038	0.034	0.038	0.156	0.114	0.238	0.090	0.090
Average (total)	0.463	0.560	0.615	6.179	0.225	0.258	0.287	0.560	0.178	0.154	0.254	0.295	6220	0.414	0.206	6.239

Table 13: Per-task success rate on CompWoB.

Glebranu, Clebranus,	boxes-transfer boxes-transfer a lisk-checktowsk lisk-option ogin-user-popup ogin-user-popup ee ee ee ee ee ee ee ee ee ee ee ee ee		(1180 0.300 0.300 0.220 0.220 0.000 0.000 0.000 0.1450 0.1450 0.0000 0.0000 0.000 0.000 0.00000 0.0000 0.000000	0.0340 0.029 0.0429 0.0429 0.0239 0.0239 0.0239 0.0239 0.0599 0.0599 0.0599 0.0470 0.0599 0.0470 0.0599 0.0470 0.0599 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.650 0.030 0.030 0.0350 0.0350 0.1130 0.1130 0.1130 0.1130 0.1130 0.220 0.230 0.230 0.230 0.230 0.230 0.230 0.230 0.230 0.0300 0.030 0.030 0.030 0.0300000000	0,130 0,150 0,850 0,359 0,357 0,350 0,360 0,360 0,360 0,360 0,360 0,360 0,360 0,360 0,360 0,370 0,000000	0.310 0.790 0.790 0.270 0.270 0.270 0.276 0.2760 0.2760 0.2760 0.2760 0.280 0.288 0.6580 0.6580 0.6580 0.6580 0.6580 0.6580 0.0000 0.0000 0.0000 0.288 0.270 0.288 0.0270 0.288 0.0270 0.288 0.0270 0.288 0.0270 0.288 0.0270 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0200 0.288 0.0000 0.288 0.0000 0.288 0.0000 0.288 0.00000 0.288 0.0000 0.288 0.0000 0.288 0.0000 0.288 0.0000 0.288 0.0000 0.0000 0.288 0.00000 0.0000 0.0000 0.00000 0.00000 0.000000	0.430 0.790 0.790 0.790 0.7300 0.730 0.7300 0.7300 0.7300 0.7300 0.7300 0.7300 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.7000 0.700000000	0.380 0.380 0.810 0.410 0.416 0.416 0.4280 0.4280 0.4280 0.4280 0.4280 0.4280 0.4280 0.4280 0.4290 0.530 0.530 0.530 0.530 0.530 0.530 0.2300 0.2300 0.2300 0.2000 0.0000 0.0000 0.0000 0.00000000	0.520 0.520 0.5800 0.5800 0.5800 0.5800 0.5800 0.5800 0.9200 0.9200 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.4800 0.23000 0.23000 0.23000 0.23000 0.23000 0.230000000000	0.550 0.170 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.179 0.000 0.000 0.00000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0,850 0,870 0,270 0,270 0,00000000	0,000 0,000000	0.340 0.000 0.000 0.140 0.700 0.700 0.700 0.700 0.288 0.288 0.288 0.288 0.288 0.288 0.297 0.297 0.297 0.290 0.200 0.00000000
Gib Hung, Gib Adinoseinand Gib Adio Adinoseinand Gib Adinoseina Gib Adinoseina Gib Ad	boxes-transfer iki-checkboxes iki-checkboxes iki-opion ogin-user-popup ee ee ee word un offician n n offician n n offician offician n offician n offician offi		0.000 0.0100 0.0100 0.00000 0.00000 0.00000 0.000000	0.0260 0.0260 0.0140 0.0140 0.0730 0.07000 0.07000 0.07000 0.0700000000	0,050 0,040 0,040 0,040 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1130 0,1200 0,1200 0,1000 0,1000 0,1000 0,10000000000	0.150 0.850 0.433 0.270 0.270 0.260 0.339 0.339 0.339 0.330 0.320 0.330 0.320 0.320 0.320 0.320 0.320 0.320 0.320 0.320 0.320 0.0000 0.000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.140 0.790 0.500 0.260 0.260 0.420 0.420 0.420 0.420 0.420 0.430 0.430 0.430 0.430 0.530 0.530 0.530 0.530 0.530 0.530 0.530 0.500 0.500 0.500 0.500 0.500 0.700 0.0000 0.0000 0.00000000	0,230 0,230 0,430 0,430 0,230 0,230 0,230 0,230 0,230 0,230 0,230 0,480 0,480 0,480 0,480 0,480 0,480 0,480 0,480 0,0000 0,000000	0,210 0,440 0,446 0,446 0,446 0,458 0,458 0,2640 0,2640 0,2640 0,2640 0,2640 0,2640 0,2640 0,2640 0,2640 0,2640 0,2000 0,0000 0,0000 0,0000 0,00000000	0,320 0,840 0,860 0,860 0,820 0,820 0,820 0,920 0,920 0,470 0,478 0,473 0,478 0,478 0,478 0,280 0,2920 0,2920 0,200000000	0.1360 0.1370 0.1370 0.1488 0.1488 0.1488 0.1488 0.1488 0.1488 0.000 0.00000 0.00000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0,030 0,030 0,000000	0030 0870 0870 0870 0870 03350 0000 0000 0000 0000 0000 0000 0	0.000 0.970 0.440 0.770 0.770 0.770 0.770 0.770 0.728 0.288 0.2973 0.2073 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2070 0.2000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.00000000
Gib Mang Gib Mag	s and the set of the		0.300 0.230 0.230 0.000 0.000 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.450 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.0000 0.000000	0.000 0.000 0.420 0.420 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.000000	0,010 0,010 0,050 0,110 0,1110 0,1110 0,120 0,230 0,200 0,000	0.430 0.430 0.330 0.330 0.340 0.340 0.340 0.340 0.530 0.550 0.050 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.00000 0.0000 0.00000 0.00000 0.00000 0.000000	0.790 0.270 0.270 0.276 0.420 0.420 0.420 0.420 0.420 0.420 0.420 0.420 0.000 0.000 0.000 0.000 0.000 0.000 0.000	0,1300 0,1300 0,1400 0,1400 0,13200 0,13200000000000000000000000000000000000	0.4810 0.4400 0.4400 0.4400 0.4700 0.4740 0.4900 0.5300 0.5000 0.5000 0.50000000000	0,5840 0,5600 0,2020 0,0020 0,0000 0,0000 0,0000 0,0000 0,0000 0	0,170 0,1790 0,1350 0,1350 0,1350 0,1350 0,1350 0,1350 0,1350 0,1350 0,1350 0,1350 0,000 0,00000 0,00000 0,00000 0,00000 0,00000 0,000000	0.200 0.200 0.850 0.877 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.000000	0200 0870 0870 0.357 0.3570 0.0000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.00000000	0.000 0.1440 0.1440 0.553 0.553 0.553 0.553 0.553 0.553 0.553 0.553 0.553 0.553 0.553 0.52 0.52 0.52 0.52 0.52 0.52 0.52 0.52
Glebnar, Glebnar	lick-hotchoxes lick-option gin-user-popup ee ee ee ee ee ee ee ee ee ee ee ee ee		0.010 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.000000	0.059 0.140 0.720 0.720 0.720 0.759 0.750 0.759 0.7500 0.7500 0.7500 0.750000000000	0,000 0,000 0,1130 0,1130 0,0000 0,000000	0430 0350 0270 0270 02840 03800 03800 03800 03800 03800 03800 03800 03800 03800 00000000	0.500 0.260 0.267 0.260 0.420 0.420 0.420 0.420 0.4280 0.430 0.430 0.430 0.430 0.580 0.000 0.000 0.000 0.000 0.000 0.289	0.430 0.430 0.322 0.322 0.322 0.322 0.322 0.322 0.480 0.480 0.480 0.480 0.480 0.480 0.480 0.0000 0.00000 0.00000 0.0000 0.00000 0.00000 0.00000 0.000000	0.460 0.4160 0.410 0.4280 0.4280 0.2800 0.8200 0.8200 0.8200 0.8200 0.8200 0.00000 0.00000 0.0000 0.00000 0.00000 0.000000	0,550 0,650 0,920 0,920 0,920 0,920 0,920 0,920 0,480 0,480 0,480 0,480 0,480 0,480 0,480 0,2800	0.530 0.790 0.1350 0.1300 0.1350 0.13000 0.130000 0.130000 0.130000 0.130000 0.13000000 0.1300000000000000000000000000000000000	0,000 0,850 0,870 0,870 0,050 0,0000 0,000000	0.870 0.860 0.860 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.000000	0.970 0.770 0.750 0.750 0.200 0.200000000
Che Nature disperts	In contract of the second seco		0.230 0.000 0.000 0.000 0.450 0.450 0.1280 0.000 0.02800 0.02800 0.02800 0.0280000000000	0.1420 0.0239 0.0239 0.0259 0.0259 0.0259 0.0259 0.0259 0.0259 0.0259 0.0200 0.0259 0.0259 0.0259 0.0259 0.0259 0.0259 0.0200 0.0259 0.0259 0.0259 0.0200 0.0259 0.0250 0.0250 0.0250 0.0250 0.0250 0.0250 0.0250 0.0250 0.00000 0.00000 0.00000 0.000000	0,250 0,119 0,1119 0,1119 0,230 0,230 0,730 0,0730 0,07000 0,0700000000	0.230 0.270 0.360 0.360 0.380 0.389 0.539 0.578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.0578 0.00000 0.0000 0.00000 0.00000 0.00000 0.00000 0.000000	0.270 0.270 0.420 0.700 0.780 0.580 0.580 0.580 0.580 0.580 0.580 0.580 0.580 0.000 0.000 0.000 0.000 0.000	0.400 0.400 0.320 0.320 0.800 0.800 0.470 0.800 0.470 0.470 0.470 0.470 0.000 0.000 0.0000 0.0000 0.1400 0.1400 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.1410 0.00000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.000000	0.2410 0.2400 0.2400 0.2600 0.2800 0.2800 0.2800 0.2800 0.2800 0.2800 0.2000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.0000 0.00000 0.00000 0.00000 0.000000	0,0500 0,0210 0,0210 0,0210 0,0210 0,0210 0,0210 0,0210 0,0210 0,0210 0,0200 0,0000 0,0000 0,0000 0,0000 0,0000 0,0000 0,0000 0,0000 0,0000	0.1790 0.1790 0.1350 0.1350 0.1000 0.00000 0.0000 0.00000 0.00000 0.00000 0.000000	0,550 0,0000 0,000000	0850 0750 0750 0750 077500 077500 077500000000	0.440 0.740 0.550 0.550 0.550 0.550 0.550 0.200 0.970 0.500 0.500 0.500 0.000
Gib Hunse segmenc, Gib Achonse, Gi	lick-hotchoxes egit-user-popup egit-user-popup egit-user-popup eco eco eco eco eco eco eco eco		0,000 0,000000	0.0140 0.723 0.723 0.0739 0.0759 0.0759 0.0759 0.0759 0.0759 0.0759 0.0759 0.0759 0.0759 0.0759 0.0109 0.0109 0.0109 0.0109 0.00000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.000000	01130 01230 02280 02280 02280 02280 02280 02280 02580 000000 0000000000	0.270 0.360 0.0000 0.3840 0.3840 0.359 0.2570 0.450 0.450 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.260 0.420 0.000 0.442 0.442 0.442 0.442 0.442 0.442 0.442 0.442 0.442 0.442 0.442 0.000 0.000 0.000 0.000 0.000	0.390 0.200 0.000 0.470 0.470 0.470 0.470 0.470 0.470 0.470 0.470 0.470 0.550 0.550 0.550 0.550 0.550 0.550 0.550 0.550 0.500 0.0000 0.500 0.0000 0.5000 0.0000 0.5000 0.0000 0.0000 0.00000000	0.280 0.280 0.200 0.260 0.280 0.280 0.280 0.280 0.260 0.200 0.0000 0.00000000	0,920 0,920 0,920 0,920 0,920 0,920 0,480 0,480 0,480 0,480 0,480 0,480 0,280 0,9200 0,9200 0,9200 0000000000	0.489 0.00000 0.0000 0.00000 0.00000 0.00000 0.000000	0.870 0.090 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.000000	0.3570 0.000 0.070 0.070 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.000000	0.700 0.550 0.250 0.280 0.290 0.200
Girk bings: circle circle 0.00	lick-option egin-user-popup ee word word word into in		0.000 0.000 0.1400 0.1400 0.1400 0.1400 0.1400 0.1400 0.1400 0.1400 0.1280 0.0200 0.00000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000000	0.000 0.738 0.738 0.738 0.738 0.738 0.738 0.658 0.658 0.658 0.610 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.000000	0,110 0,120 0,580 0,780 0,990 0,900 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000 0,000000	0.360 0.840 0.550 0.550 0.570 0.240 0.240 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.000000	0.280 0.760 0.766 0.780 0.580 0.580 0.580 0.580 0.580 0.580 0.580 0.580 0.580 0.000 0.000 0.000 0.000	0.3220 0.3220 0.477 0.4870 0.477 0.470 0.470 0.470 0.470 0.470 0.470 0.470 0.470 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.4490 0.830 0.830 0.830 0.830 0.830 0.830 0.830 0.830 0.830 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.0201 0.1500 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7800 0.7900 0.2000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.000000 0.00000000	0.1350 0.00000 0.00000 0.00000 0.00000 0.000000	0000 0.577 0.577 0.0700 0.00000 0.00000 0.00000 0.00000 0.000000	0.350 0.070 0.070 0.070 0.070 0.070 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.00000 0.000000	0.559 0.228 0.228 0.220 0.220 0.200 0.0000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.00000000
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Glei king,	ee		0.910 0.1450 0.1450 0.1450 0.1000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.000000 0.00000000	0.0730 0.0730 0.730 0.730 0.050 0.050 0.020 0.020 0.020 0.020 0.020 0.020 0.0160 0.0160 0.0160 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0140 0.0160 0.0200 0.00000000	0.580 0.720 0.720 0.720 0.750 0.050 0.050 0.050 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.000000	0.840 0.530 0.570 0.570 0.240 0.0000 0.00000 0.0000 0.0000 0.00000 0.00000 0.00000 0.000000	0.760 0.430 0.580 0.280 0.280 0.280 0.280 0.280 0.280 0.280 0.000 0.000 0.000 0.000	0.880 0.470 0.470 0.470 0.470 0.530 0.010 0.010 0.0000 0.00000 0.00000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.00000 0.00000000	0.880 0.880 0.580 0.580 0.530 0.530 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.0000 0.0000 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000	0.920 0.780 0.780 0.780 0.780 0.780 0.780 0.800 0.800 0.440 0.440 0.230 0.230 0.220 0.200 0.200 0.200 0.200 0.200 0.200 0.200 0.200 0.200 0.0000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000000	00000 00000 00000 00000 00000 00000 0000	0.677 0.0700 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.000000 0.000000 0.00000000	0.670 0.670 0.640 0.640 0.640 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.000000	0.550 0.550 0.200 0.577 0.597 0.597 0.597 0.590 0.0000 0.00000 0.00000 0.00000 0.000000
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distribution access and a contraction and a cont	nulti-layouts		0.940	0.390	0.260	0.000	0.000	0.000	0.000	0.200	0.000	0.420	0.000	0.000
CIICA-MIAUQ_SEAUCIF-CIIQUE	ine		0.950	0.820	0.550	0.000	0.000	0.000	0.020	0.980	0.000	0.000	0.000	0.000
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Average (two-way, easy-medium) 0.452 0.357 0.483 0.048 0.040 0.096 0.054	r-medium)		0.452	0.357	0.483	0.048	0.040	0.096	0.054	0.450	0.030	0.044	0.030	0.028
Average (10141) 0.291 0.297 0.343 0.157 0.170 0.181 0.192			0.291	0.297	0.343	0.157	0.170	0.181	0.192	0.435	0.098	0.121	0.160	0.189

Table 14: Per-task success rate on CompWoB with reverse-order instructions.

I PROMPTED LANGUAGE MODEL AGENTS WITH ORACLE EXEMPLARS

We here evaluate the performance of RCI with gpt-4 and oracle exemplars on 20 two-way tasks in CompWoB. We provide two demonstrations per task in the prompts. Figure 7 shows that RCI with gpt-4 and oracle exemplars achieves 82.9% success rate, which is the best among the baselines, such as HTML-T5++ (73.9%), RCI with combination exemplars (gpt-3.5-turbo: 46.9%, gpt-4: 71.5%). See Table 13 for other baselines. This ensures that if a prompt includes how to perform on compositional tasks, the performance gets better. However, please also keep in mind that providing exemplars for every compositional problem is infeasible given the huge space of problems and the cost of collecting examples for every one of them.



Figure 7: Average success rate of LMAs in 20 two-way tasks from CompWoB. RCI with gpt-4 achieves the best performance when the oracle exemplars are provided (82.9%) in the prompt.



J TASK COMPLEXITY ANALYSIS WITH LANGUAGE MODEL AGENTS

Figure 8: 2D-scatter plots between the success rate for each LMA (y-axis) and each statistic of compositional task (x-axis), such as the number of instruction tokens, max depth of HTML subtrees, the number of elements in HTML, and the number of HTML tokens. The results imply that while all the language model agents (HTML-T5++, RCI, AdaPlanner, Synapse) show negative correlations between the success rate and instruction tokens with statistical significance, the trends for other statistics may differ among the methods.