

Problem-Solving Guide (PSG): Predicting the Algorithm Tags and Difficulty for Competitive Programming Problems

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Abstract

The recent program development industries have required problem-solving abilities for engineers, especially application developers. However, AI-based education systems to help solve computer algorithm problems have not yet attracted attention, while most big tech companies require the ability to solve algorithm problems including Google, Meta, and Amazon. The most useful guide to solving algorithm problems might be guessing the category (tag) of the facing problems. Therefore, our study addresses the task of predicting the algorithm tag as a useful tool for engineers and developers. Moreover, we also consider predicting the difficulty levels of algorithm problems, which can be used as useful guidance to calculate the required time to solve that problem. In this paper, we present a real-world algorithm problem multi-task dataset, **AMT**, by mainly collecting problem samples from the most famous and large competitive programming website Codeforces. To the best of our knowledge, our proposed dataset is the most large-scale dataset for predicting algorithm tags compared to previous studies. Moreover, our work is the first to address predicting the difficulty levels of algorithm problems. We present a deep learning-based novel method for simultaneously predicting algorithm tags and the difficulty levels of an algorithm problem given.

Keywords: Algorithm Tag Prediction, Problem Difficulty Level Prediction, Education for Computer Algorithm, Competitive Programming Dataset Benchmarks

1. Introduction

To solve a given algorithm problem, in general, the developer guesses the intention of the problem and classifies the algorithm tag of the problem after reading the problem description. Then, the developer writes a source code for solving the algorithm problem. From this perspective, a problem-solving guide (PSG) is a useful tool for learners and engineers who are facing algorithm problems. For example, predicting algorithm tags properly for a given problem description can provide useful direction to understand the problem for the participants. Moreover, the order of problems to solve also does matter because we may not have enough time to solve all problems. Thus, we note that predicting the difficulty level is also informative in deciding the order to solve problems. In this paper, we introduce an AI-based problem-solving guide (PSG) as a useful tool for programmers facing an algorithm problem. Given algorithm problems, our PSG is a multi-task solution

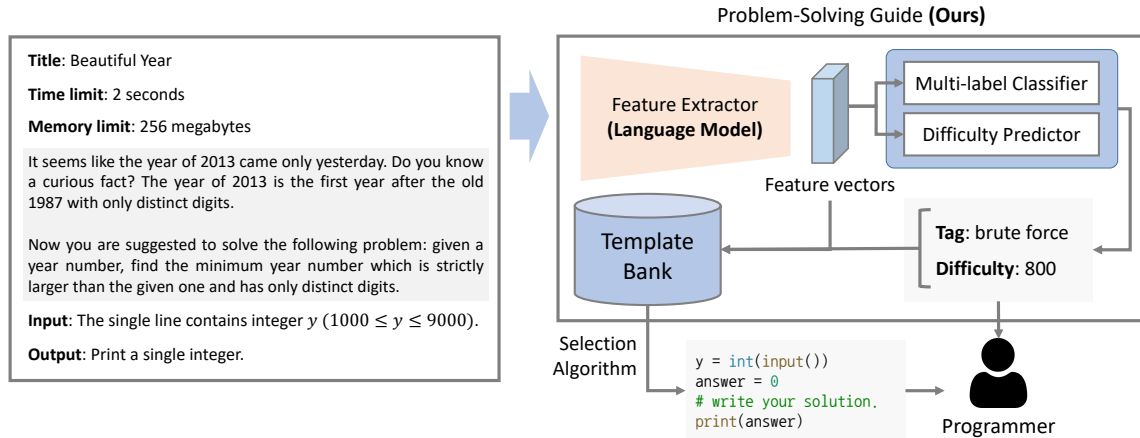


Figure 1: Our proposed method, problem-solving guide (PSG) predicts the tags (categories) and the difficulty (required time) of an algorithm problem simultaneously.

providing simultaneously (1) a predicted algorithm tag, and (2) a predicted difficulty level of the problem. For educational purposes, our proposed method can be used to reduce effectively the time for users to understand and solve various algorithm problems.

Recent work [Athavale et al. \(2019\)](#) has shown that the deep learning-based classifier can be used for predicting the algorithm tags of a problem given. However, they have a limitation in that their method is able to only predict an algorithm tag for a problem and shows poor classification accuracy. For a generalized problem-solving guide, we should design proper architectures that predict the tags and difficulty of the problem properly by understanding the intent of the problem comprehensively. Especially, the algorithm problem set consists of long sentence texts. We note that the deep learning models based on recurrent neural networks [Hochreiter and Schmidhuber \(1997\)](#); [Zaheer et al. \(2020\)](#); [Beltagy et al. \(2020\)](#) are difficult to recognize these long sentences. In this work, we utilize a useful deep-learning architecture to effectively address these long-sequence texts. We adopt transformer-based large language models [Vaswani et al. \(2017\)](#); [Devlin et al. \(2018\)](#); [Clark et al. \(2020\)](#) and show the recent transformer architectures that address long sequences are useful for solving our task [Beltagy et al. \(2020\)](#); [Zaheer et al. \(2020\)](#).

We have also analyzed various programming problems in the broadly used competitive programming platform, Codeforces. On this website, the categories of problems are labeled by algorithm experts, and the difficulty levels are determined by the results of the competition to which the problem belongs except in a few exceptional cases. Predicting the categories of the problem is a well-defined multi-label problem [Liu and Chen \(2015\)](#); [Nam et al. \(2014\)](#); [Liu et al. \(2017\)](#); [Xiao et al. \(2019\)](#); [Katakis et al. \(2008\)](#) and predicting the problem’s difficulty level can be seen as the ordinal classification problem [Pan et al. \(2018\)](#); [Liu et al. \(2018\)](#); [Frank and Hall \(2001\)](#); [Gaudette and Japkowicz \(2009\)](#); [Larichev and Moshkovich \(1994\)](#); [Dembczyński et al. \(2008\)](#). Therefore, we consider this problem a multi-task problem that jointly solves two tasks and also provide a new dataset, **AMT**. We demonstrate that our proposed method shows superior classification performance compared to the previous

Table 1: The data distribution of algorithm tags. This table shows the number of algorithm problems for each tag category in our presented dataset. We consider the most frequent 20 categories.

Top-20 Frequent Categories					
Labels	# of problems	Labels	# of problems	Labels	# of problems
Implementation	2394	Sortings	869	Bitmasks	459
Math	2363	Binary Search	862	Two Pointers	438
Greedy	2302	DFS and Similar	776	Geometry	344
DP	1732	Trees	663	DSU	292
Data Structures	1429	Strings	617	Shortest Paths	231
Brute Force	1370	Number Theory	613	Divide and Conquer	227
Graphs	890	Combinatorics	544		

SOTA work [Athavale et al. \(2019\)](#). To the best of our knowledge, we are the first to adopt the multi-task approach to provide useful applications for real-world developers, which simultaneously predicts the tags and difficulties of an algorithm problem. Moreover, we additionally provide baseline source code templates for the various algorithm tags, which can reduce the time effectively for users to solve the algorithm problems.

2. Background and Related Work

2.1. Predicting Problem Tags

A recent study has proposed a new research area PMP (Programming Word Problems) and presented a dataset for the research purpose of predicting algorithm tags [Athavale et al. \(2019\)](#). In their work, the authors utilize 4,019 problems and more than 10 algorithm tags. They have demonstrated that the CNN-based classifier can achieve near-human performance for the task of predicting the algorithm tags [Athavale et al. \(2019\)](#). However, their adopted architectures do not address the long sequences effectively. The general algorithm problems consist of a lot of words whose size is more than 1,000 in the problem description. However, we have found that the simple CNN architecture with fixed kernel size might not capture the global representations comprehensively. To remedy this issue, we adopt the recent transformer-based architectures [Vaswani et al. \(2017\)](#); [Devlin et al. \(2018\)](#); [Zaheer et al. \(2020\)](#) that are relatively immune to long sequences of the problem description. Moreover, we extend the number of algorithm problems to construct large-scale datasets.

2.2. Multi-Task Solution Using Deep Learning

We consider our task as a multi-task problem that simultaneously addresses (1) multi-label classification and (2) ordinal-class classification. Some related studies have presented joint learning methods for simultaneously training multiple tasks in various research fields [Ruder \(2017\)](#); [Choi et al. \(2023\)](#); [Crawshaw \(2020\)](#); [Yu et al. \(2020\)](#); [Thung and Wee \(2018\)](#). The multi-task learning approach can reduce memory complexity while nearly maintaining the original classification performance of individual single-task models [Choi et al. \(2023\)](#); [Ruder \(2017\)](#); [Lin et al. \(2019\)](#); [Dong et al. \(2015\)](#).

Table 2: The difficulty level distribution of our proposed whole dataset. This table shows the number of algorithm problems according to the difficulty levels. CodeForces provides 28 different types of difficulty levels.

Difficulty	800	900	1000	1100	1200	1300	1400	1500	1600	1700
# of Problems	686	255	306	305	333	325	329	357	397	381
Difficulty	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700
# of Problems	348	371	363	330	362	297	347	306	242	222
Difficulty	2800	2900	3000	3100	3200	3300	3400	3500		
# of Problems	177	165	137	107	105	86	63	112		

3. Proposed Methods

Our method solves the **multi-label classification** problem because each algorithm problem can belong to one or more labels simultaneously. For example, a competitive programming problem requires the idea of *greedy*, *sorting*, and *dynamic programming* simultaneously. Our proposed method also predicts the difficulty of the problems. To the best of our knowledge, we are the first to address the **ordinal-class classification** problem for predicting the degree of difficulty of algorithm problems. We note that predicting the degree of difficulty of algorithm problems is also crucial for developers in that the difficulty level can be interpreted as the required time to solve that algorithm problem.

3.1. Problem Definition

We define a function $F : \mathcal{X} \rightarrow \mathcal{Z}$ as a feature extractor that extracts representations given a text x and maps x into an embedding space \mathcal{Z} . Then, we use a classification head $H : \mathcal{Z} \rightarrow \mathcal{Y}$ on the top of the feature extractor F . Our proposed framework is designed to solve multiple tasks. Specifically, our model solves two kinds of problems (1) multi-label classification and (2) ordinal-class classification simultaneously. Thus, we design deep neural networks for solving these two tasks using two loss functions l_1 and l_2 jointly.

$$\mathbb{E}_{(x,y,d) \in \mathcal{D}_{train}} [l_1(H_1(z), y) + \lambda \cdot l_2(H_2(z), d)]$$

where $z = F(x)$ and l_1 denotes a binary cross-entropy loss for the problem category y . \mathcal{D}_{train} denotes the train data distribution. The second loss l_2 is designed for the ordinal classification task. Thus, we can simply adopt the cross-entropy loss for l_2 . The d denotes a problem difficulty level and the λ is a scale factor for weighting two tasks differently. Our PSG adopts the two-head network architecture. First, we extract a feature representation vector z and forward this vector into two classification heads, multi-label classifier head H_1 and ordinal-class classifier head H_2 . During the training time, the data x and y are picked from the train data distribution \mathcal{D}_{train} . After training time, we test the trained model on the test dataset \mathcal{D}_{test} that is different from \mathcal{D}_{train} in the inference time.

In the multi-label classification tasks, the classification model can classify multiple labels simultaneously, performing binary classification per each label. Thus, we adopt the multi-label classification approach for solving the algorithm tag prediction task in this work. Given a problem description, our model outputs the probability for each possible algorithm tag

label. Thus, we can adopt the binary cross-entropy (BCE) loss function. For the following equation, y_k is set as 1 where the text data x belongs to the k -th class and the value of y_k is 0 in the case that x does not belong to the k -th category (tag). Therefore, we can calculate the full loss value over all possible categories where the number of categories is K for the multi-label classification and $y \in \mathbb{R}^K$ denotes the true label according to x . We have shown that this simple BCE loss is well suitable for our multi-label classification problem where a detection network $\psi(\cdot)$ that informs users of whether a text data belongs to the \mathcal{D}^k that is data distribution of k -th algorithm category (tag), thus, $\psi(x) = 0$ if $x \notin \mathcal{D}^k$.

$$\mathcal{L}^{tag}(\psi(x), y) = -\frac{1}{K} \sum_k^K y_k \cdot \log(\psi(x)) + (1 - y_k) \cdot \log(1 - \psi(x)) \quad (1)$$

3.2. Proposed Datasets and Architectures

To construct our dataset, **AMT**, we have mainly collected algorithm problems from CodeForces. We have excepted a problem if the problem has no tag information. The total number of collected problems is 7,976. First, we consider the top 20 frequent algorithm tags as ground-truth labels, which account for most problems. We represent the number of programming problems for each problem tag of our proposed dataset in Table 1. Secondly, our proposed dataset also contains the difficulty information for each problem. The smaller value denotes the easier problem in Table 2. In our proposed dataset, the difficulty level is calculated based on their own rating system of Codeforces. To implement the multi-task deep learning model, our method adopts BERT-based Devlin et al. (2018); Zaheer et al. (2020); Vaswani et al. (2017) feature extractor and two different classification head networks. With extensive experiments, we have found that the BigBird Zaheer et al. (2020) architecture shows the best performance for solving our multi-task problem. Therefore, we report the performance of BigBird as the main result in the experiment section.

4. Experimental Results

We have extensively experimented with various text classification methods to validate the effectiveness of our proposed dataset. We also construct a smaller version of our AMT dataset, *AMT10*, that only considers the main 10 categories for experiments. A recent work Athavale et al. (2019) has applied various deep learning-based methods for predicting algorithm tags and has demonstrated CNN architectures Kim (2014); Lai et al. (2015) could show improved performance. However, we observe that the recently proposed large-scale transformer architectures Zaheer et al. (2020); Devlin et al. (2018) can show better classification performance compared to the reported classification performance of previous methods as shown in Table 3. With extensive experiments, we have found that the BERT-based architectures can be greatly useful for our task, especially the BigBird can comprehensively process the long embedding tokens and relatively well recognize the implicit feature representations of an algorithm problem. In conclusion, our proposed method for multi-task learning, PSG, results in a competitive classification performance comprehensively. We note that the number of parameters of PSG is smaller by approximately 2 times compared to the parameter size of the combination of two single-task models. This memory efficiency

Table 3: Performance on the test dataset. The symbol \uparrow indicates larger values are better. We have reported the best performance of each method by finding the best learning rate using a grid search. In conclusion, we use the learning rate of $5e-6$ for BigBird models solving each single task. Moreover, we also use the learning rate of $5e-6$ for our proposed multi-task solver PSG. We note that the hyper-parameter λ is crucial to obtain improved classification performance. For the tag prediction, the AUROC and F1-Macro indicate the average value over all the categories. We also report the performance of some baseline methods of the previous work.

Architectures	λ	Rating Prediction \mathcal{T}_1				Tag Prediction \mathcal{T}_2		
		Accuracy \uparrow	CS ($\theta=3$) \uparrow	Pan et al. (2018) \uparrow	CS ($\theta=5$) Pan et al. (2018) \uparrow	MAE \downarrow	AUROC \uparrow	F1-Macro \uparrow
SVM BoW + TF-IDF Athavale et al. (2019)	N/A	N/A	N/A	N/A	N/A	N/A	79.26	40.33
CNN Ensemble TWE Athavale et al. (2019)	N/A	N/A	N/A	N/A	N/A	N/A	58.12	20.14
XGBoost	N/A	N/A	N/A	N/A	N/A	N/A	73.47	43.09
CatBoost	N/A	N/A	N/A	N/A	N/A	N/A	74.39	42.91
LightGBM	N/A	N/A	N/A	N/A	N/A	N/A	74.52	42.94
Gradient Boosting Machine	N/A	N/A	N/A	N/A	N/A	N/A	73.21	40.99
BigBird-based Single Model for \mathcal{T}_1 (Ours)	N/A	11.24		23.71		4.55	N/A	N/A
BigBird-based Single Model for \mathcal{T}_2 (Ours)	N/A	N/A		N/A		N/A	80.70	42.78
Multi-Task PSG (Ours)	1	8.35		19.07		4.74	69.08	25.16
Multi-Task PSG (Ours)	10	10.10		20.41		4.79	79.12	41.08
Multi-Task PSG (Ours)	100	8.76		15.46		7.09	79.59	41.63

comes from the property of the multi-task models that we can extract feature representations by forwarding the input texts into the feature extractor network $F(\cdot)$ only once.

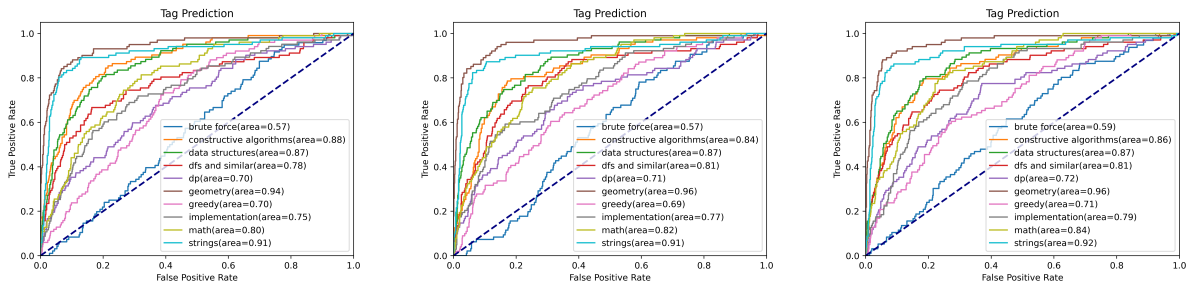


Figure 2: The ROC curves of various models, derived on the test dataset. The first figure represents the ROC curve of our PSG model trained with $\lambda = 10$. The second figure shows the ROC curve of our PSG model trained with $\lambda = 100$. The third figure shows the ROC curve of the single-task BigBird model to solve only the second task \mathcal{T}_2 . Our multi-task learning method can obtain a competitive classification performance for the tag prediction task \mathcal{T}_2 compared to the single-task learning method while maintaining the ability to solve two different tasks.

5. Conclusion

In this work, we present a novel algorithm problem classification dataset, **AMT**, that contains about 8,000 algorithm problems and provides two kinds of annotations (the algorithm tag and difficulty level) for each problem. To validate the effectiveness of the proposed dataset, we also train a variety of text classification models on the dataset and analyze their classification

performance. To solve the multi-task problem effectively, we introduce a novel multi-task approach, PSG, that simultaneously predicts the tag and difficulty level of an algorithm problem given. In the experimental results, we demonstrate our proposed method shows significantly improved classification performance compared to the previously presented SOTA methods. We provide all the source codes, datasets, and trained models publicly available.¹ We hope our proposed dataset and model architectures could contribute to the programming industries for educational purposes.

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